7 a)

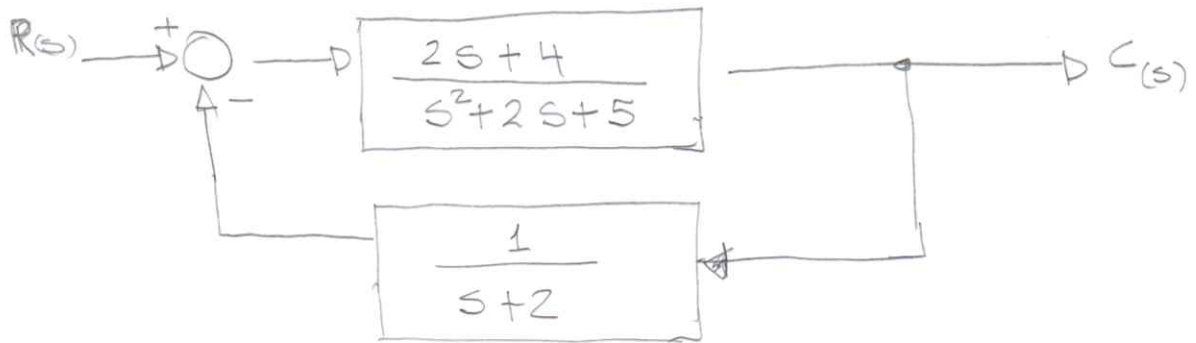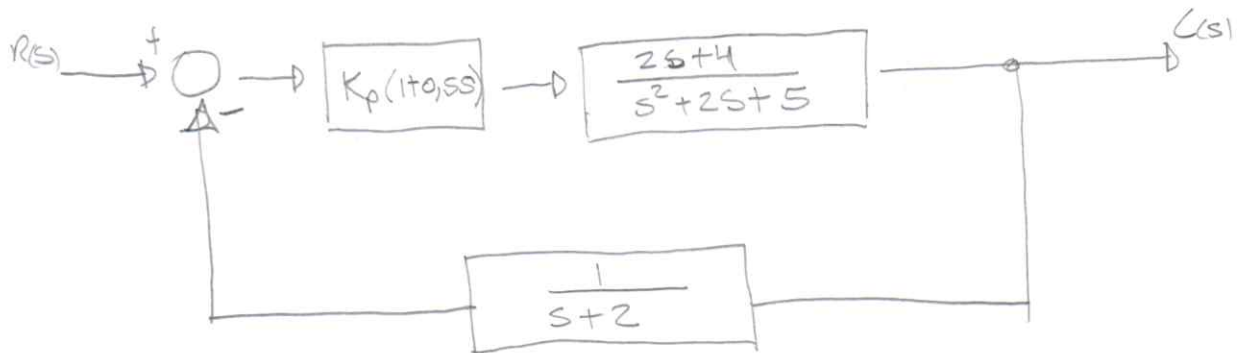○ Redesign the system including a P. D controller with the expression:

$$G_c = K_p (1 + 0,5s)$$

Proporcional term ↗   ↖ Derivative term

b)