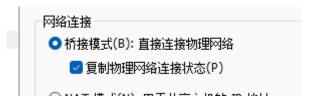
1. Add content in the .bashrc file within the virtual machine to modify the robot's IP address.

22 export MIRO_ROBOT_IP=192.168.0.110

2. Configure the virtual machine's network settings to use "bridged" mode.



3. Steps to launch Gazebo:

Comment out (disable) the robot IP address line previously added in the .bashrc file.

Change the network mode to "NAT"

Open a terminal in the sim directory within the mdk folder