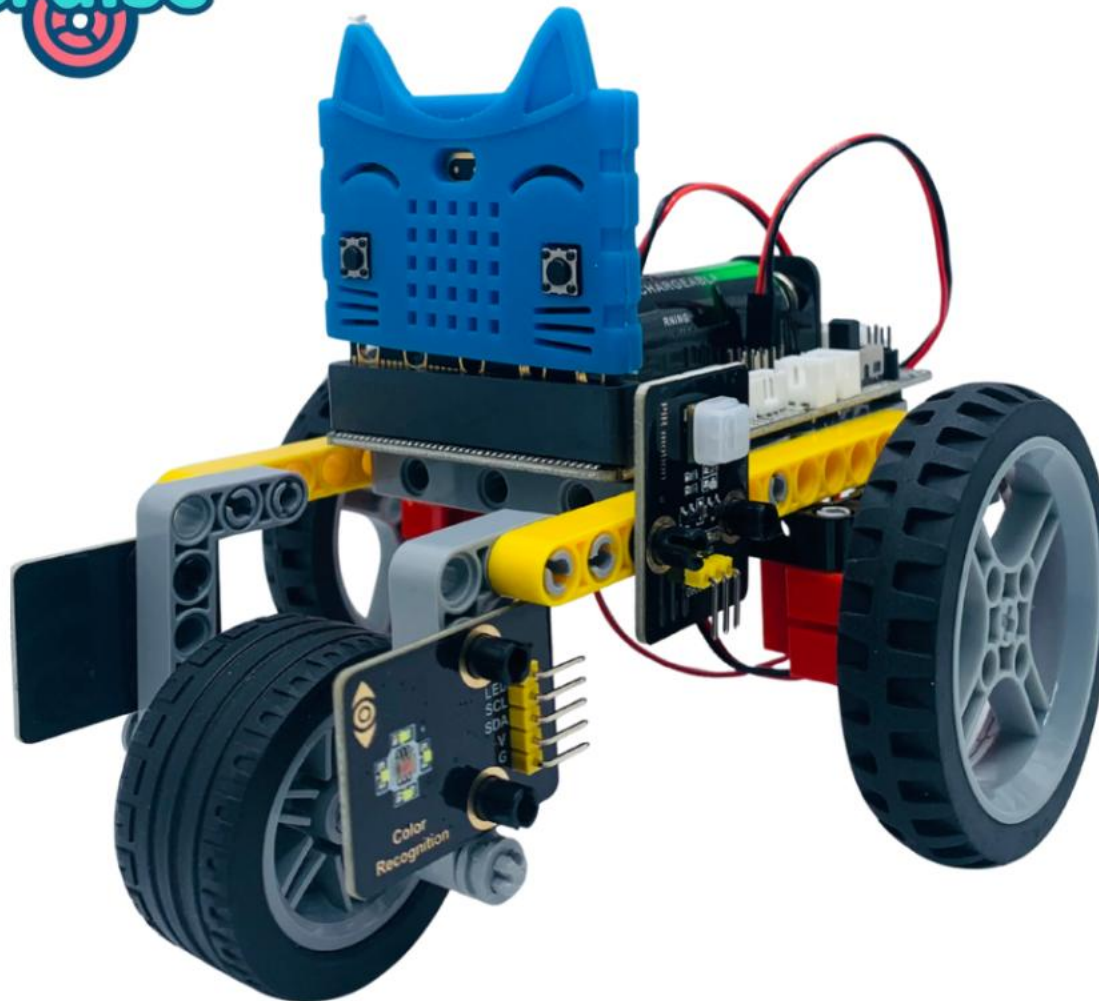
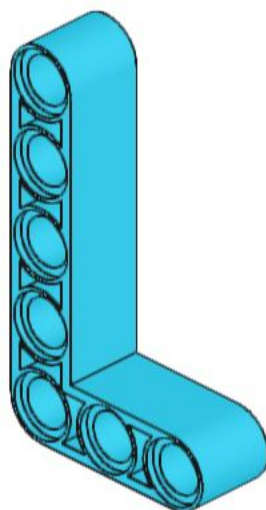
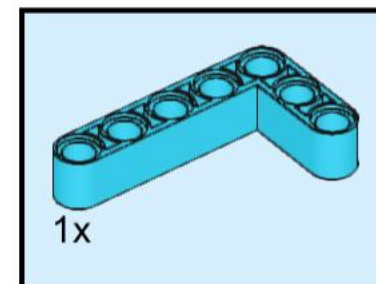




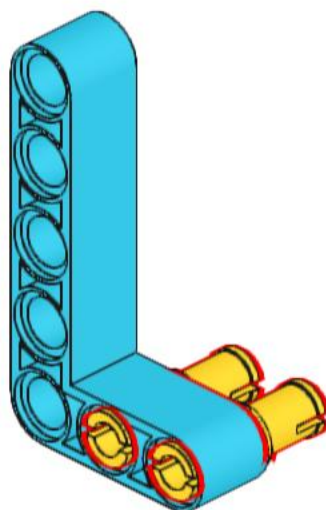
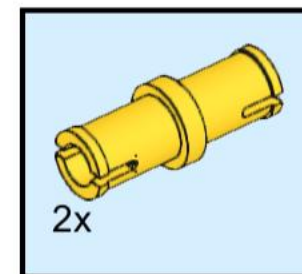
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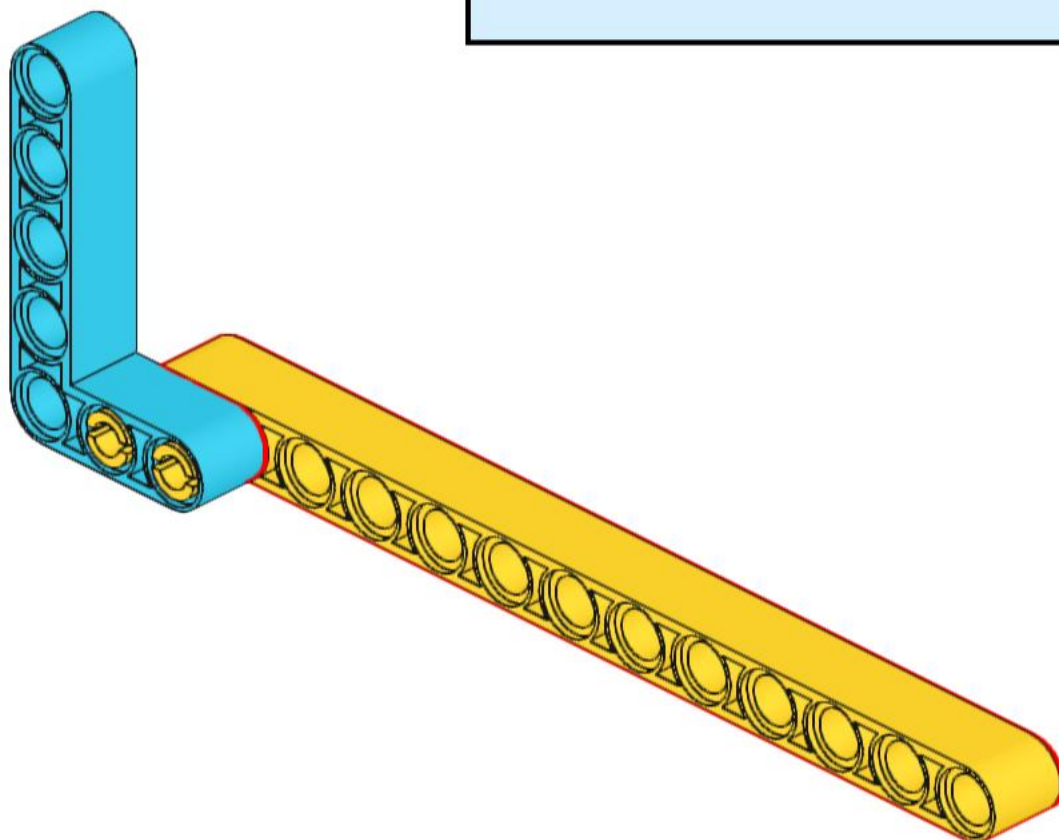
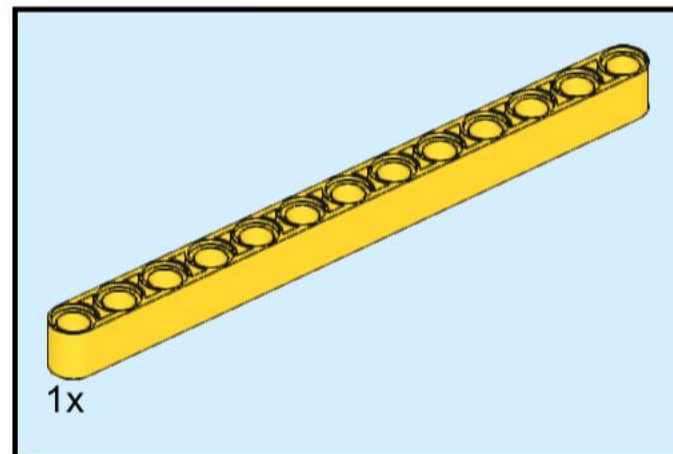
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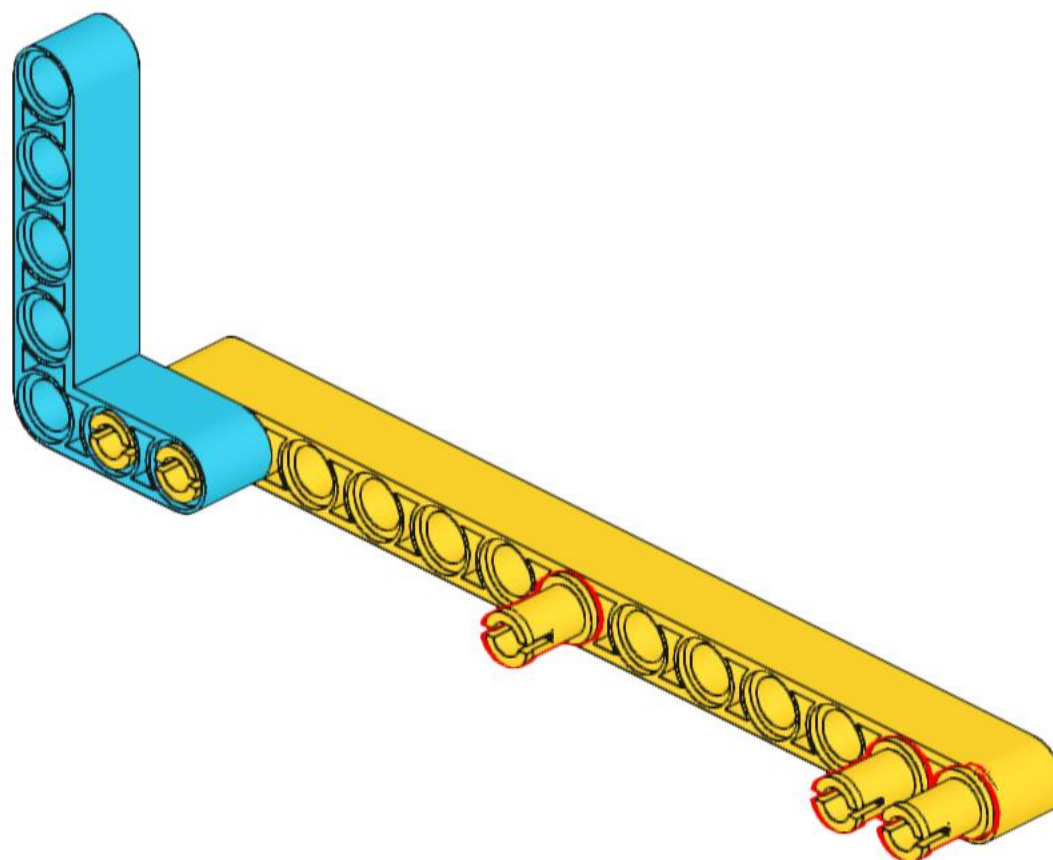
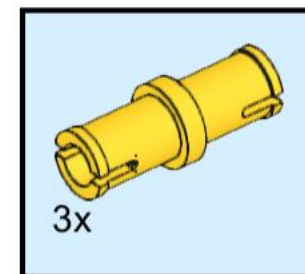
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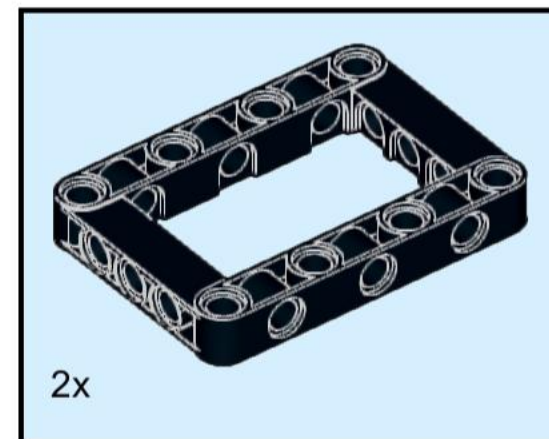
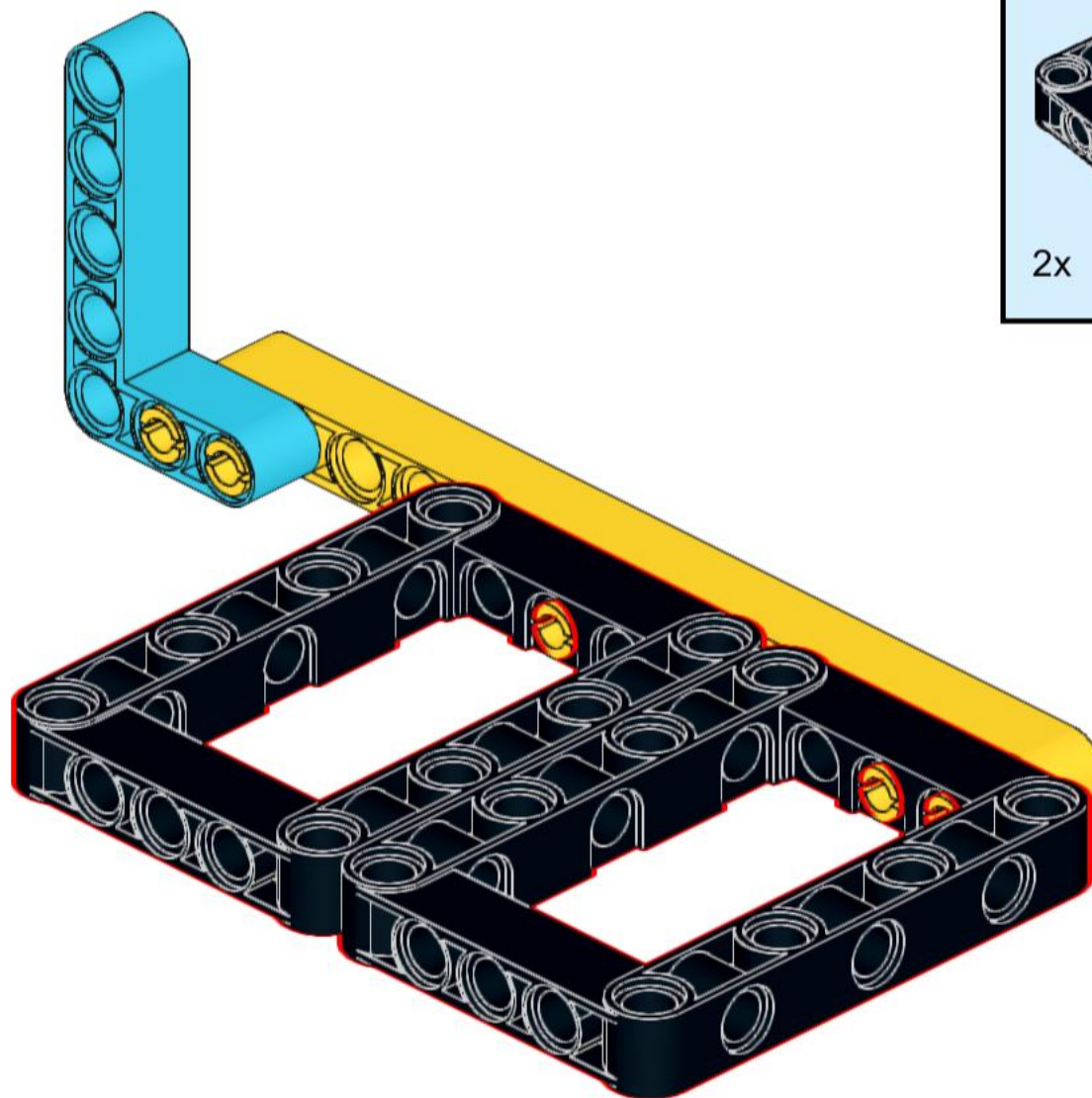
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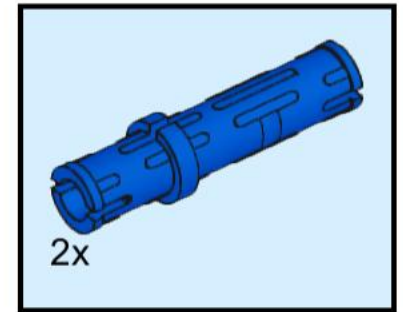
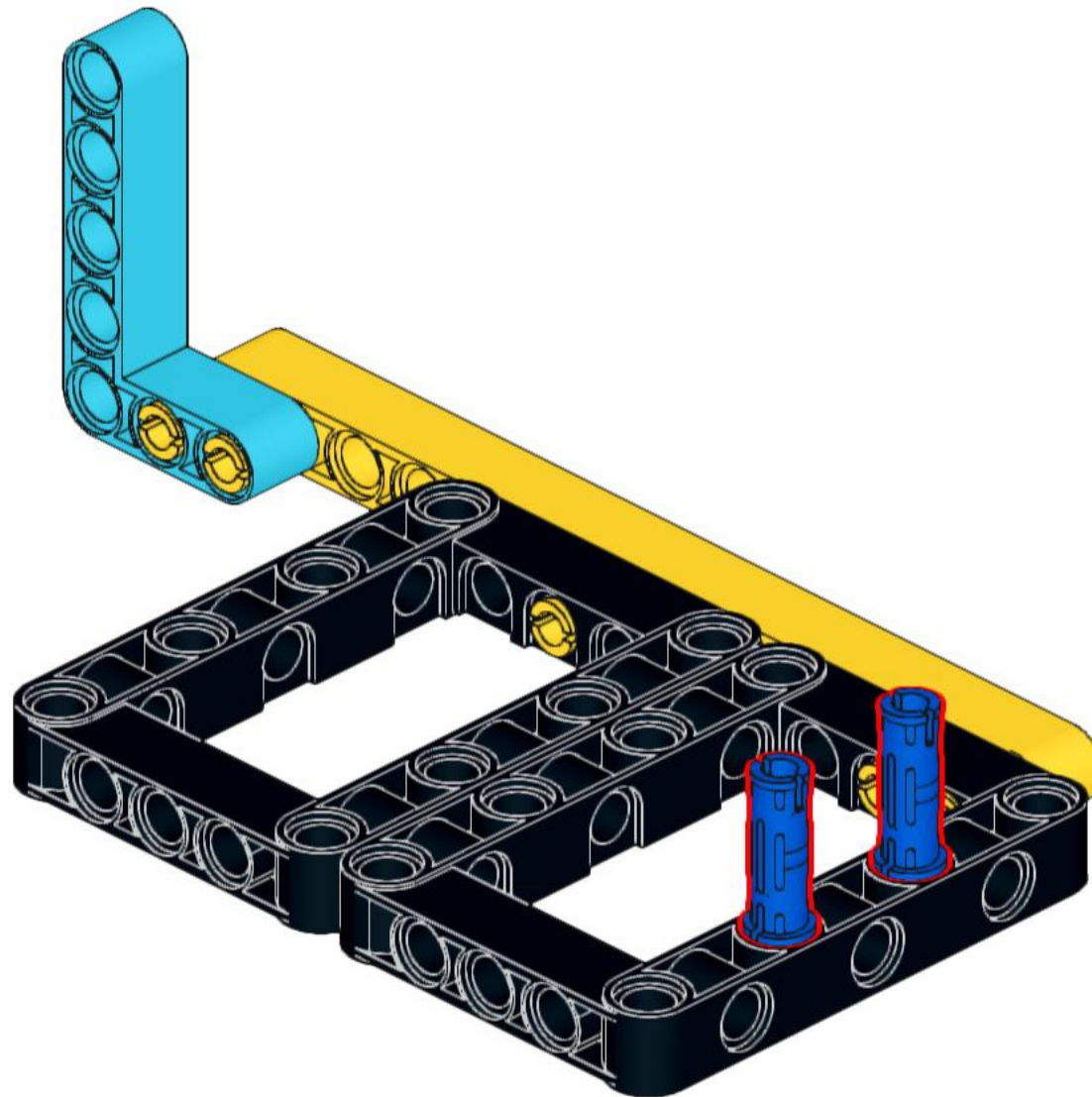
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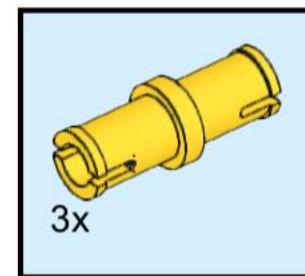
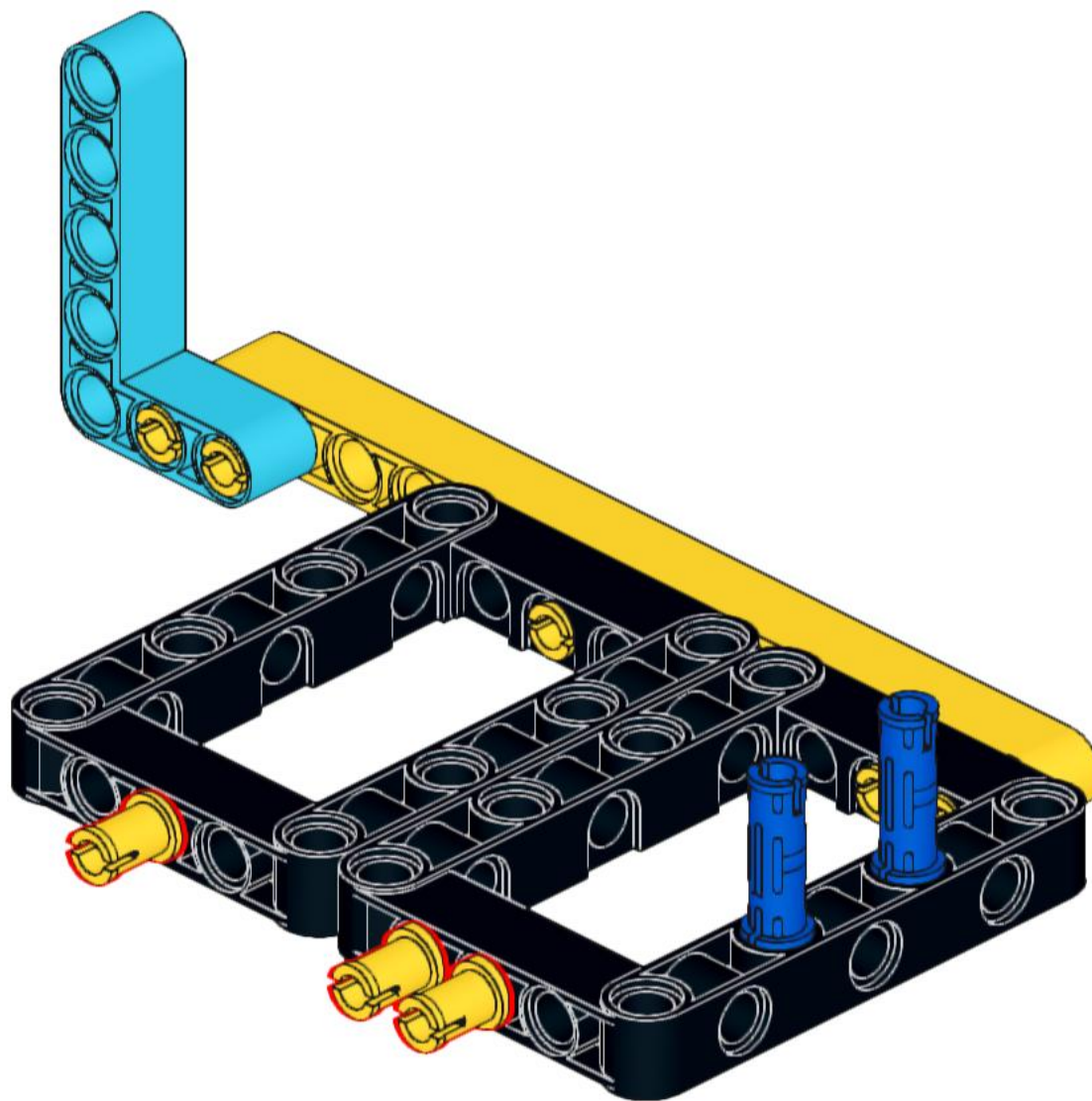
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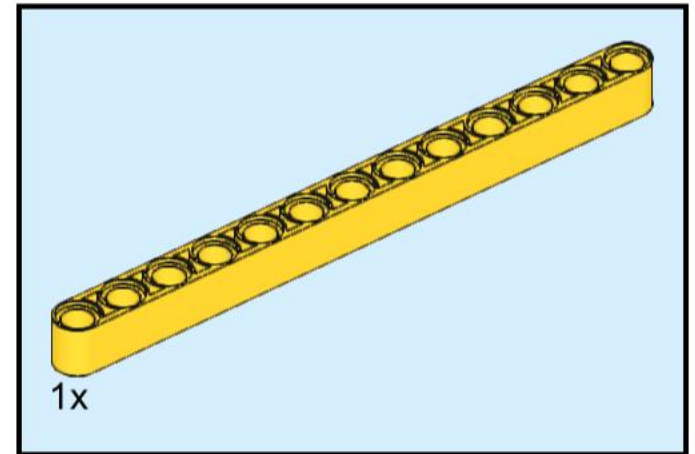
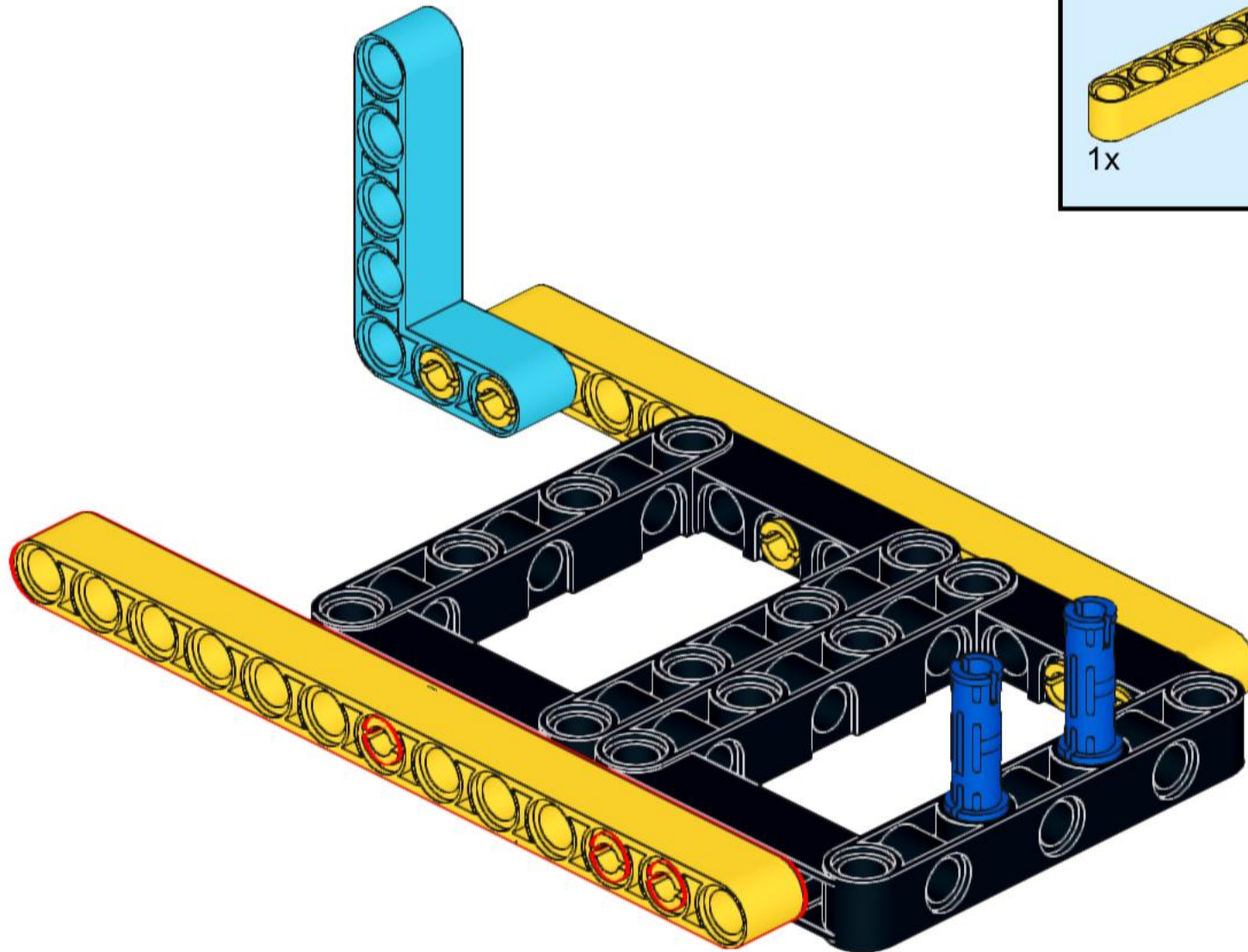
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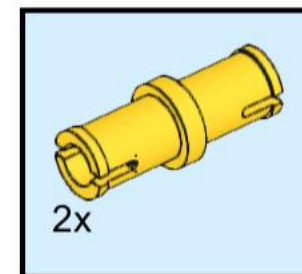
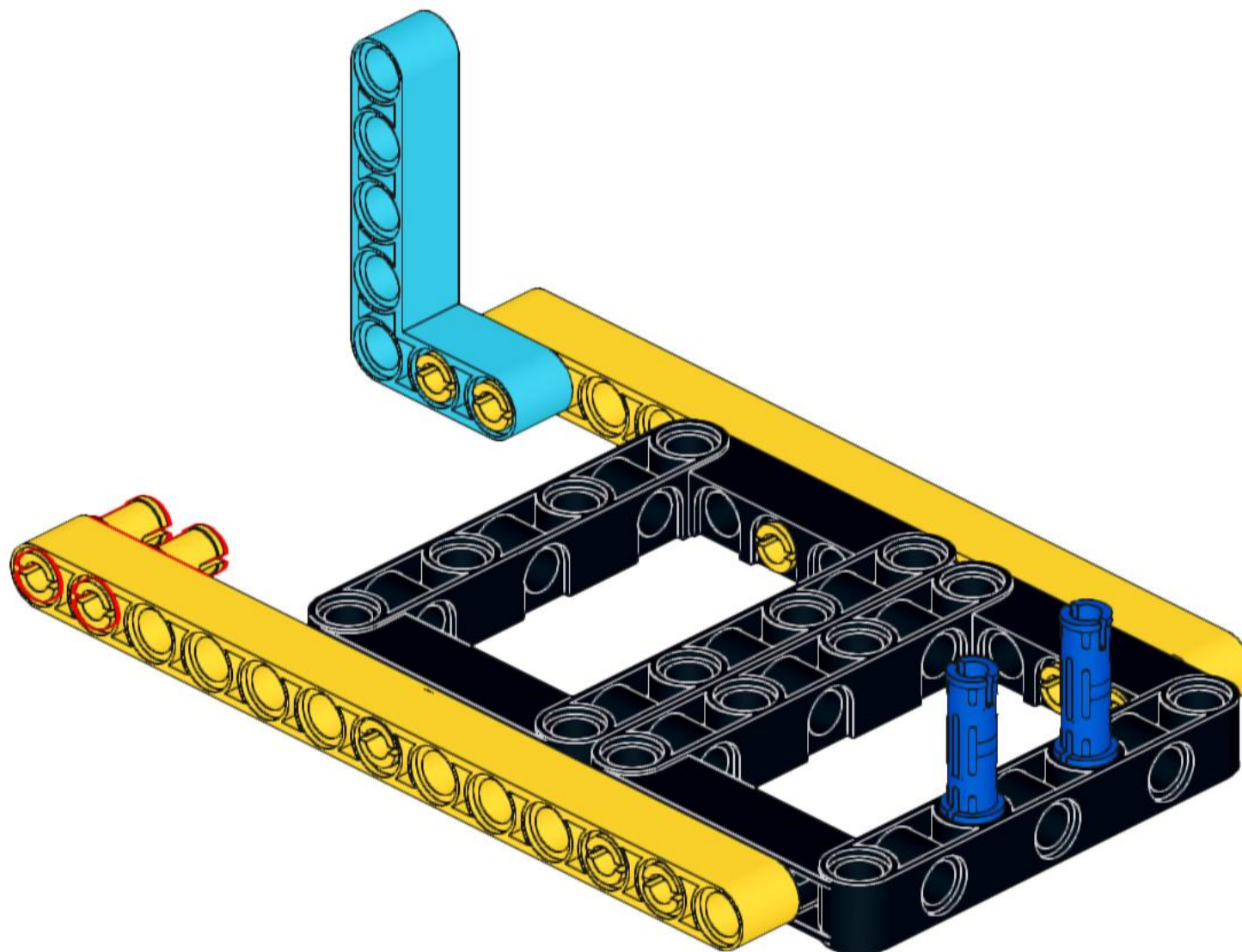
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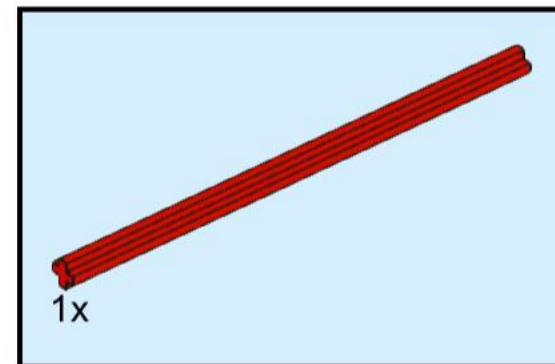
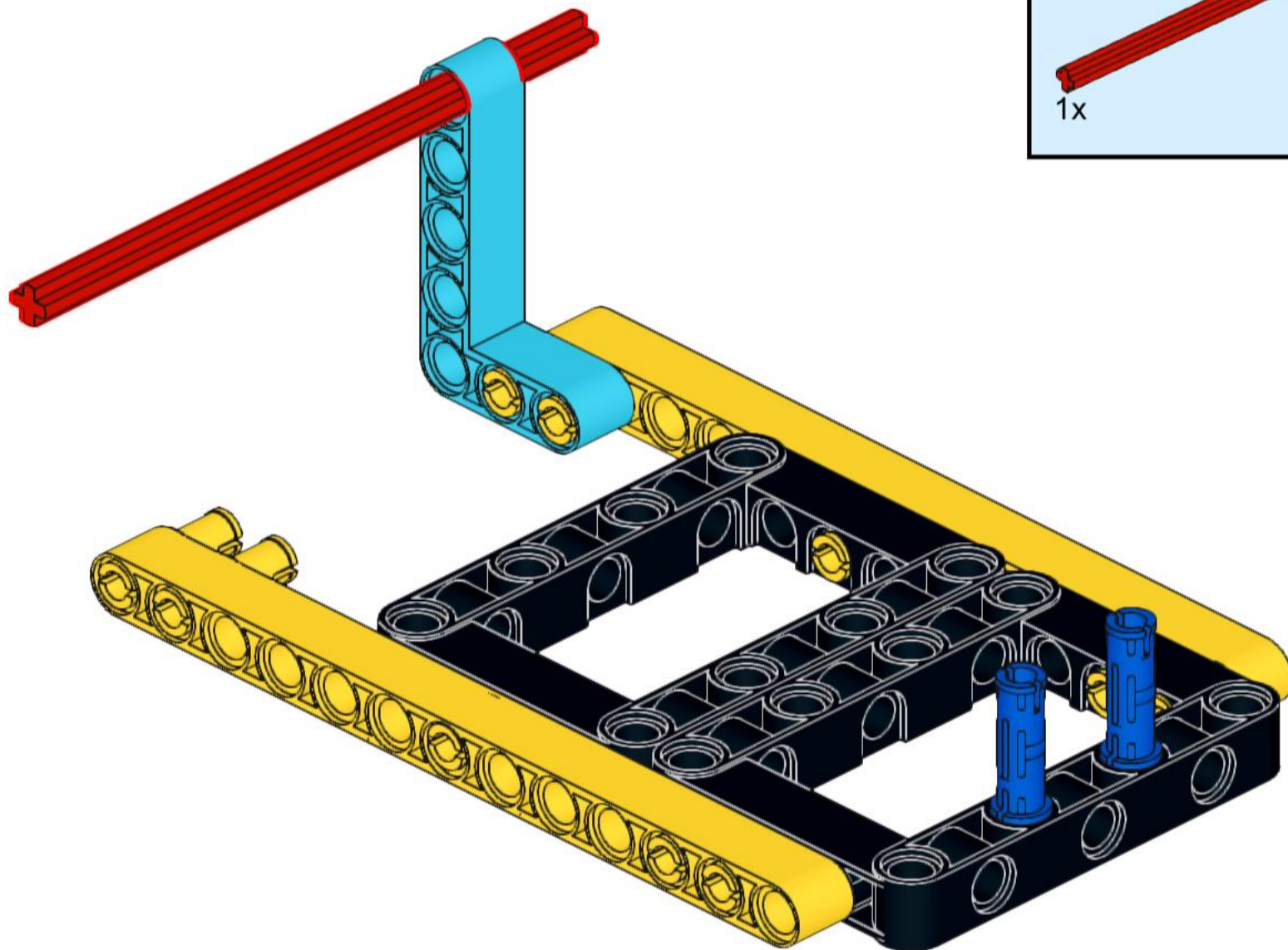
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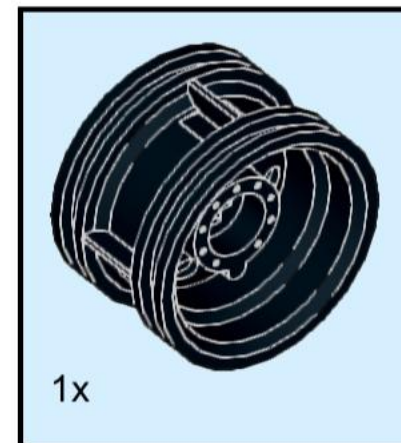
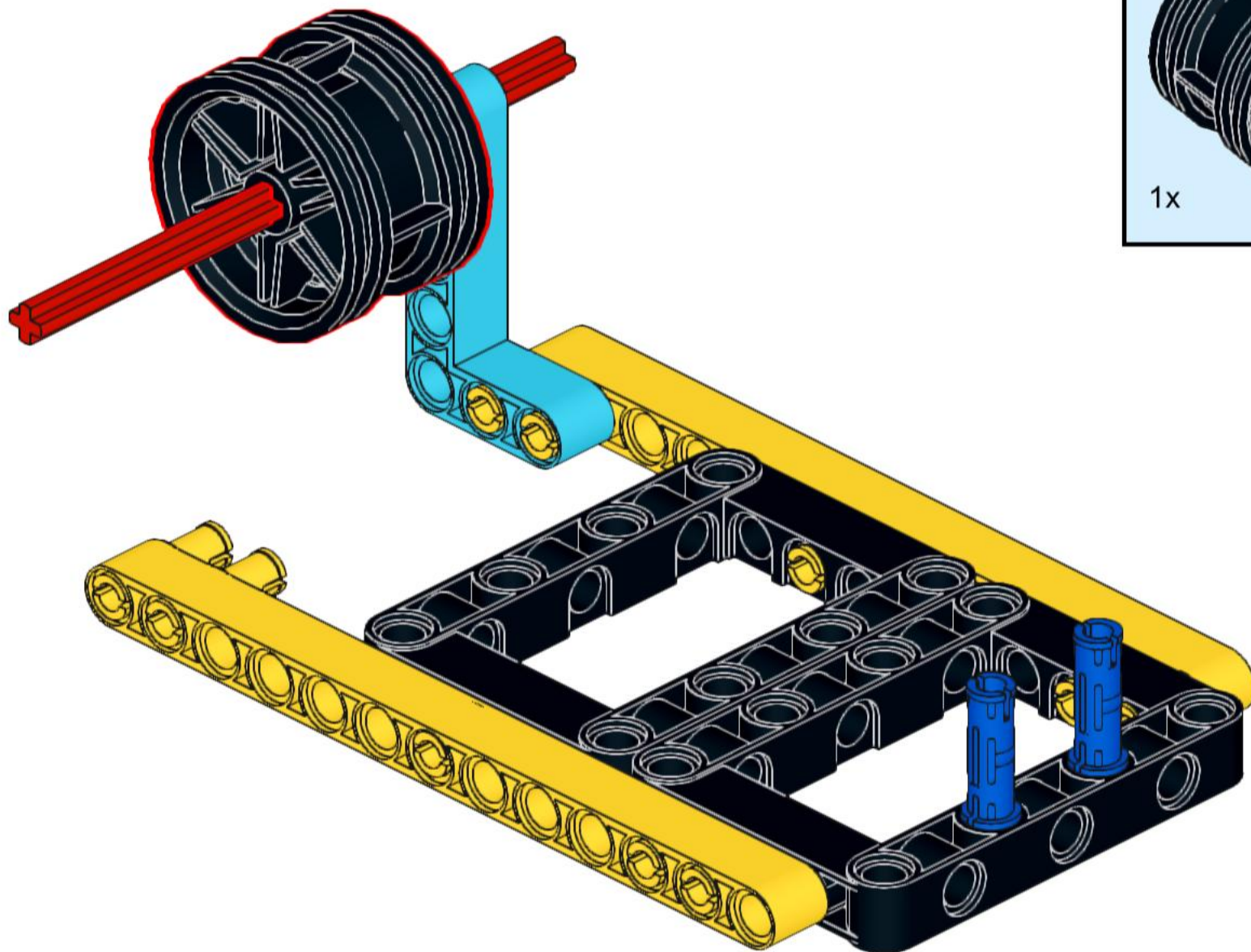
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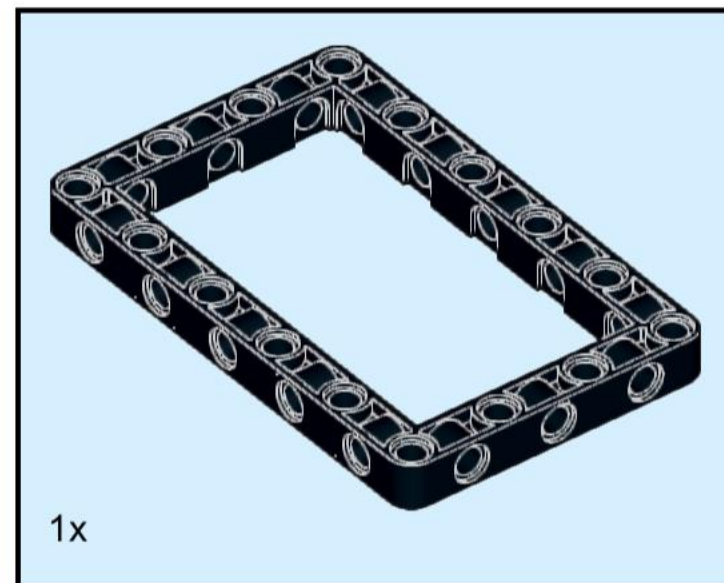
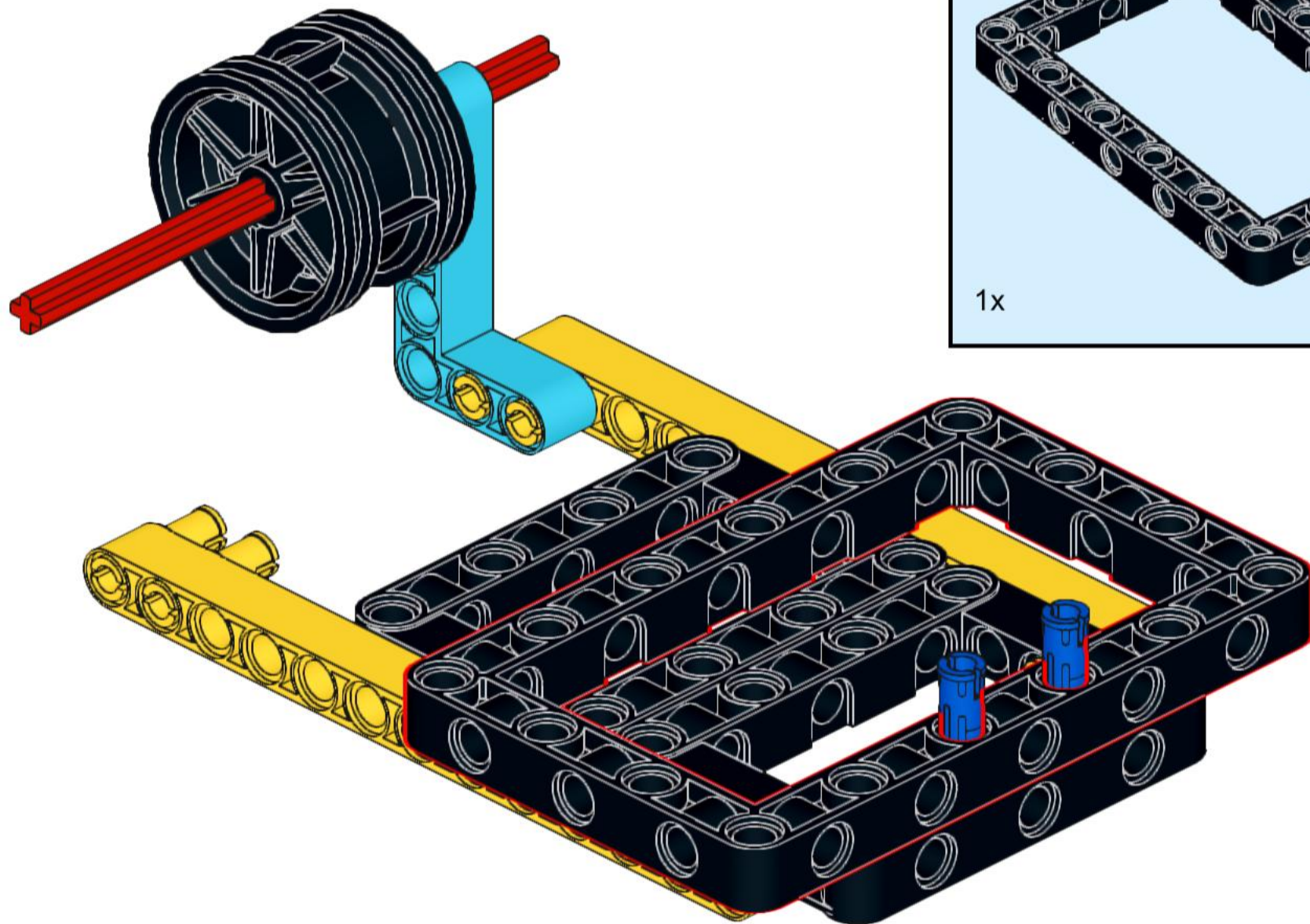
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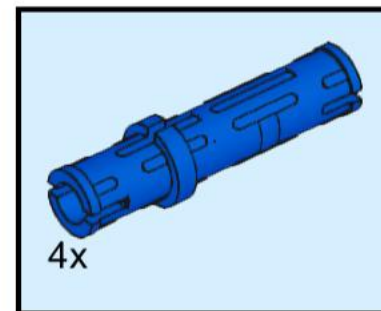
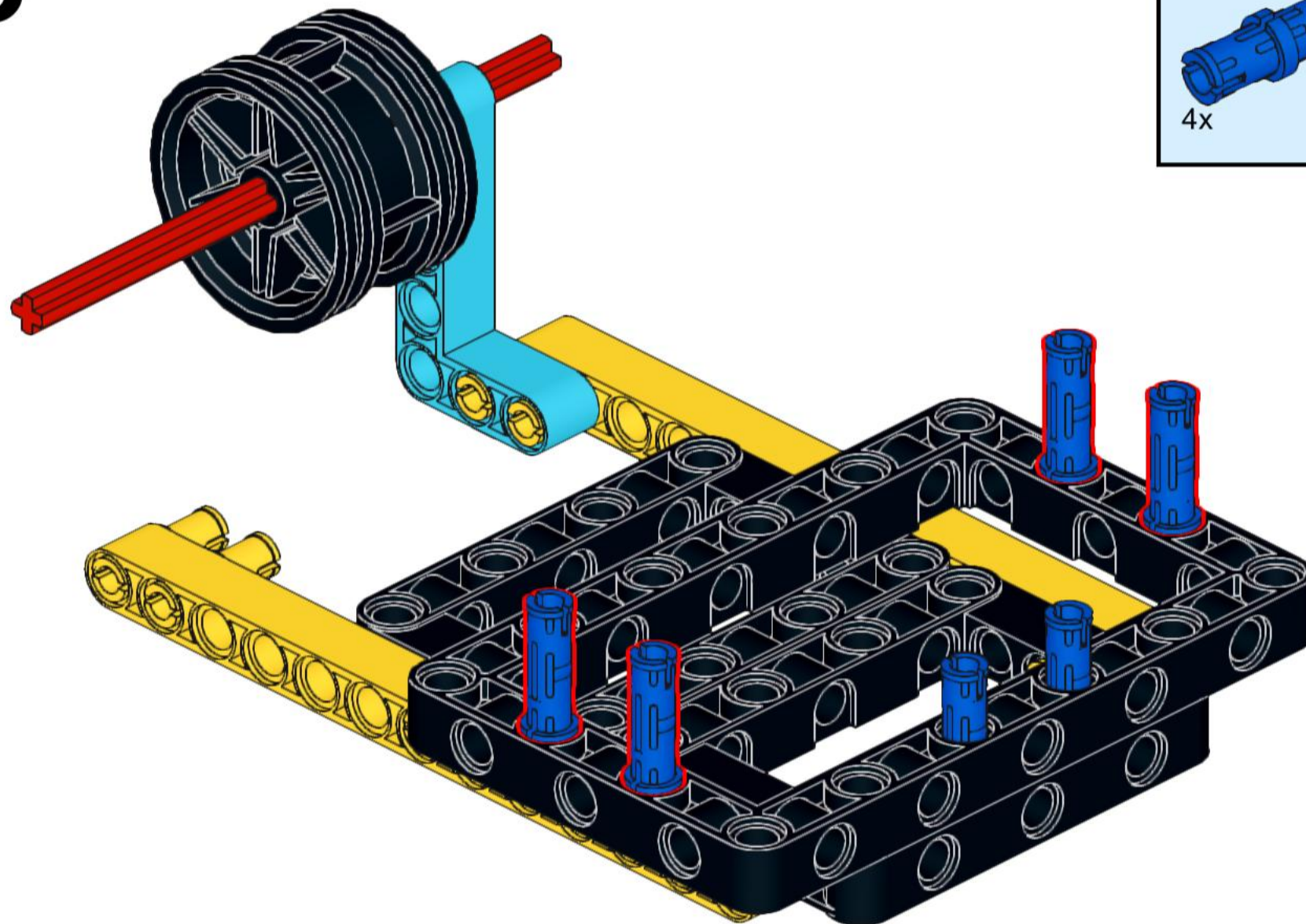
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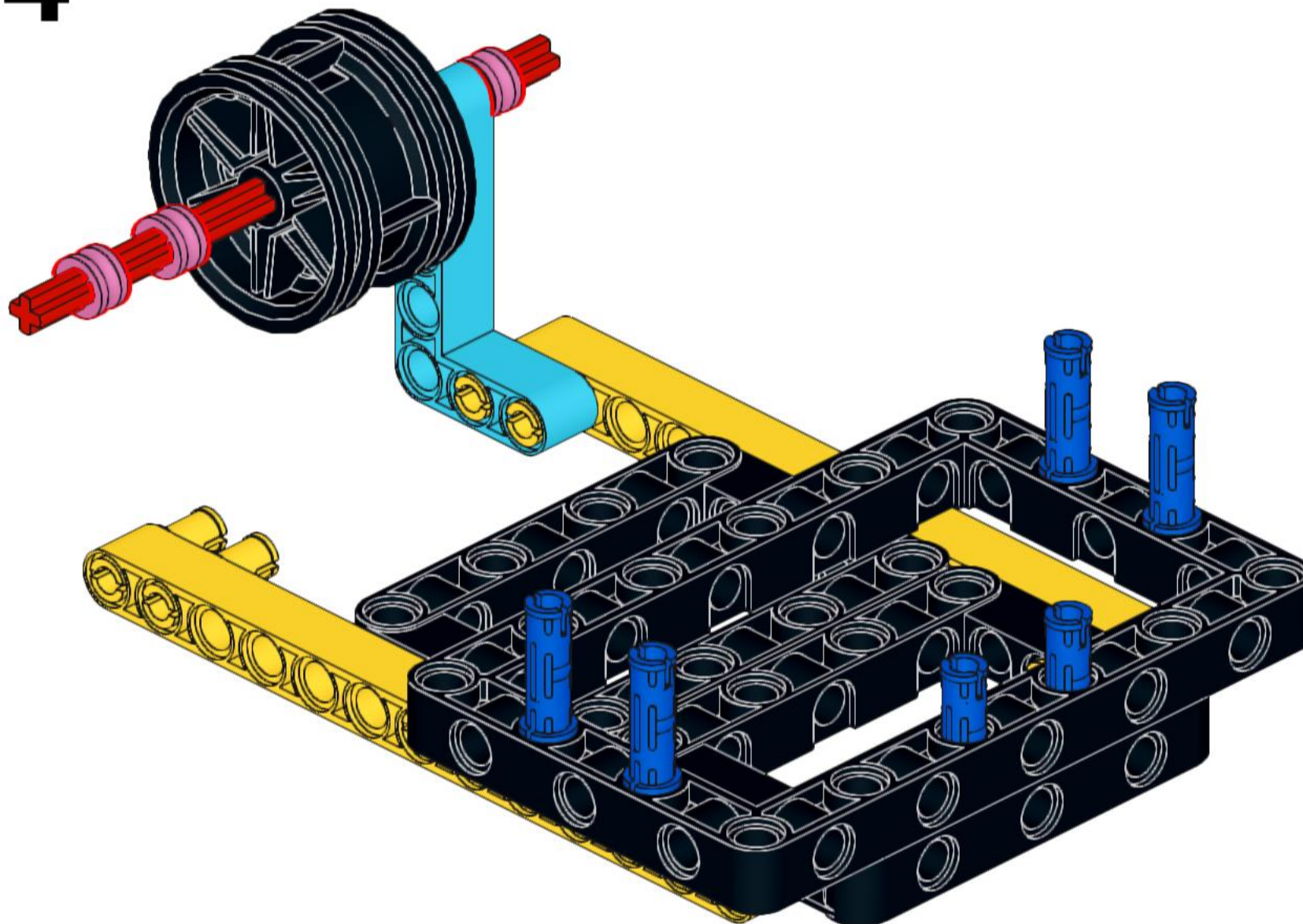
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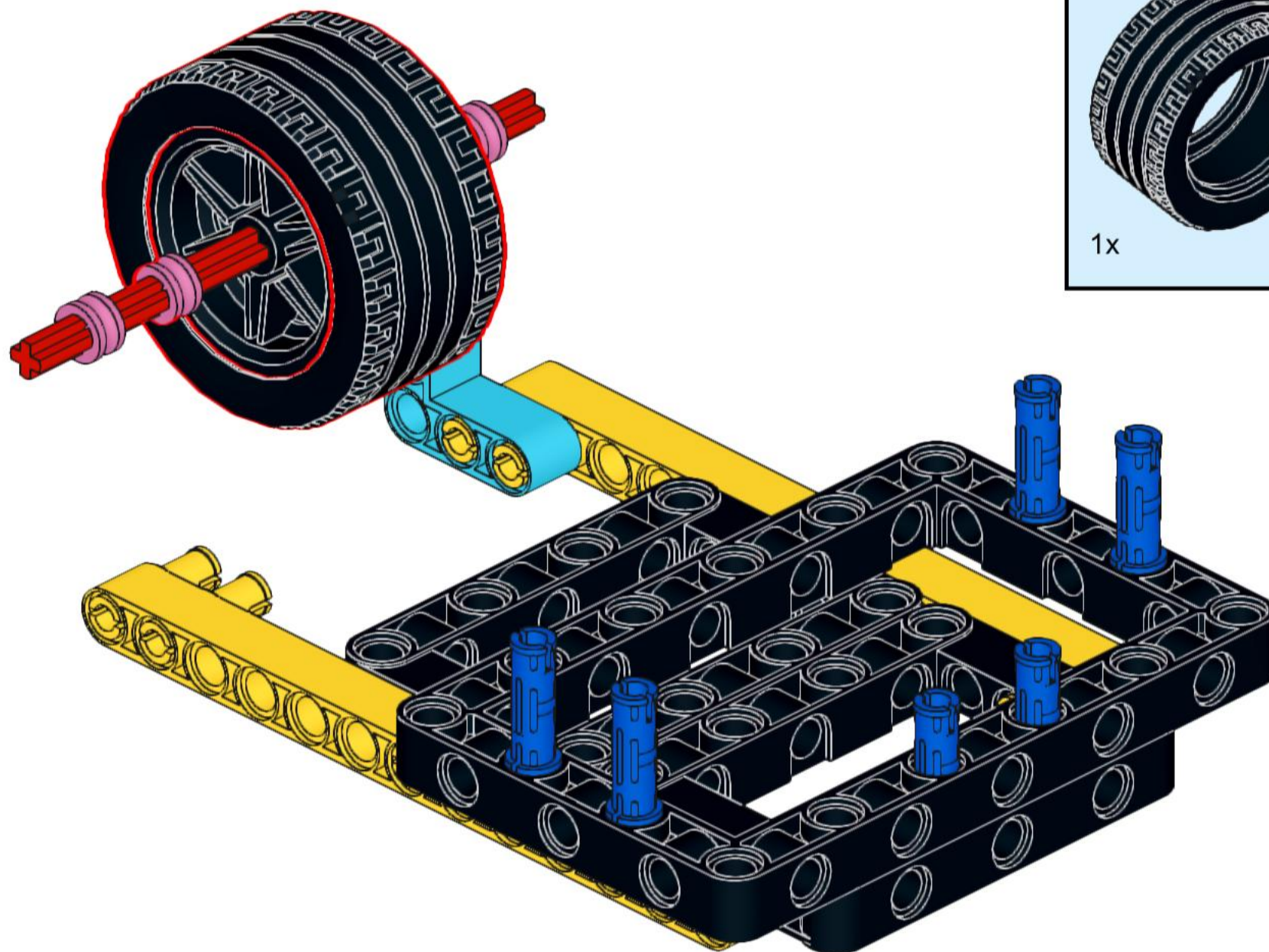
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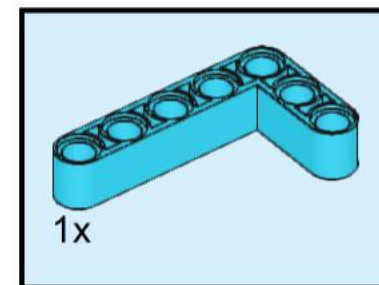
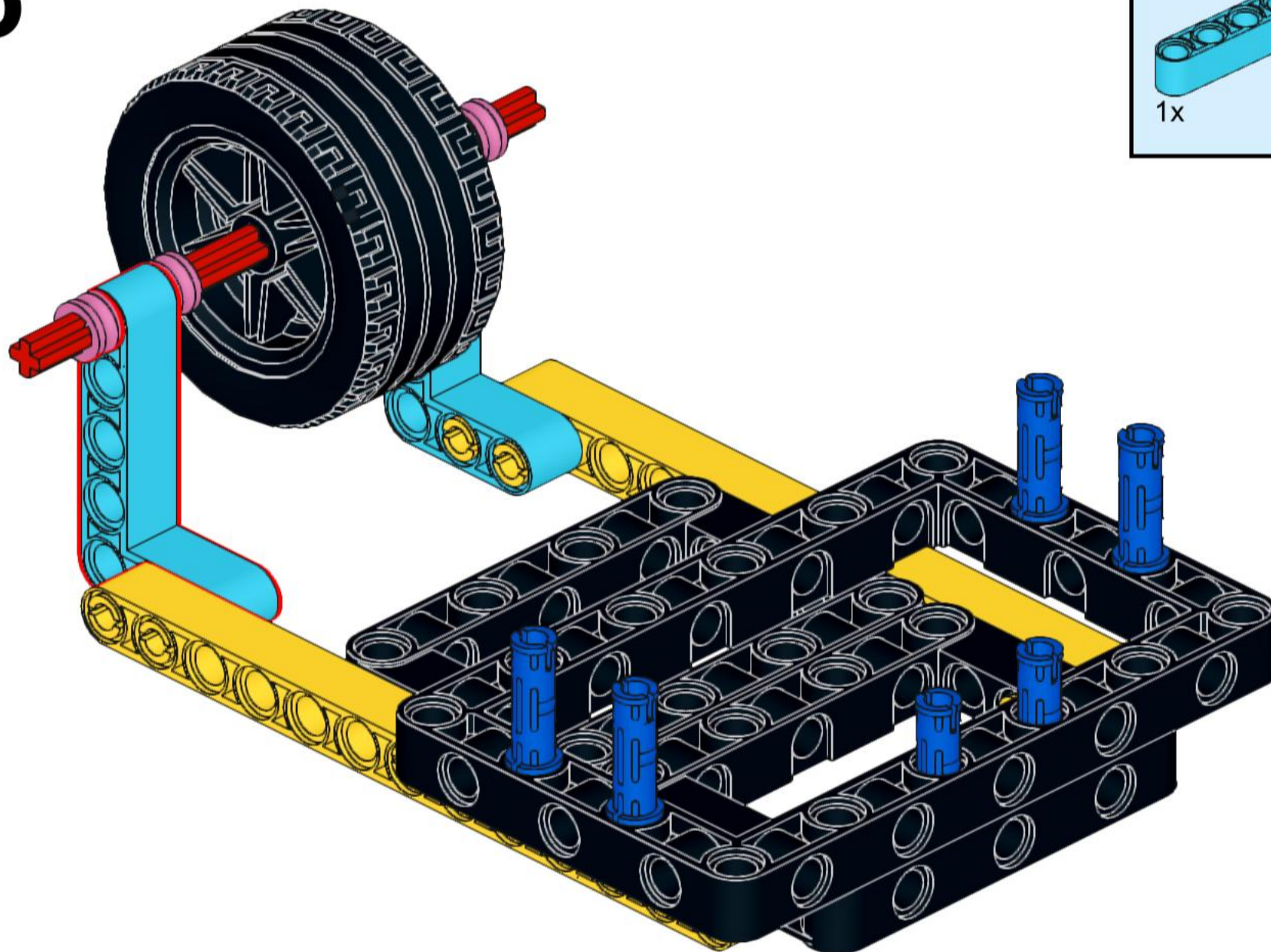
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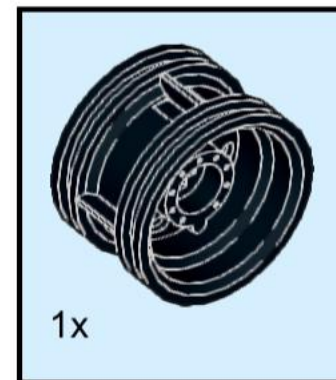
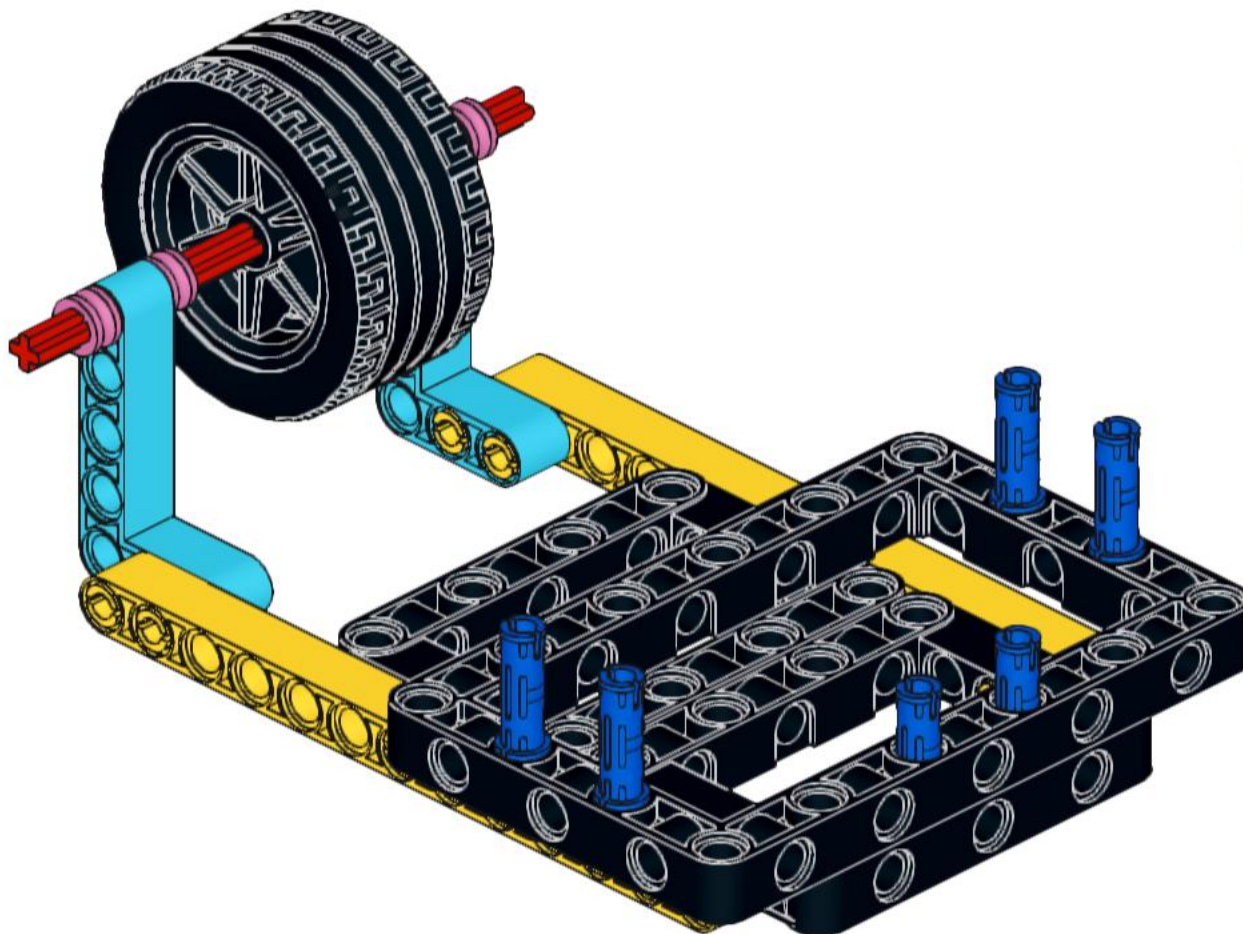
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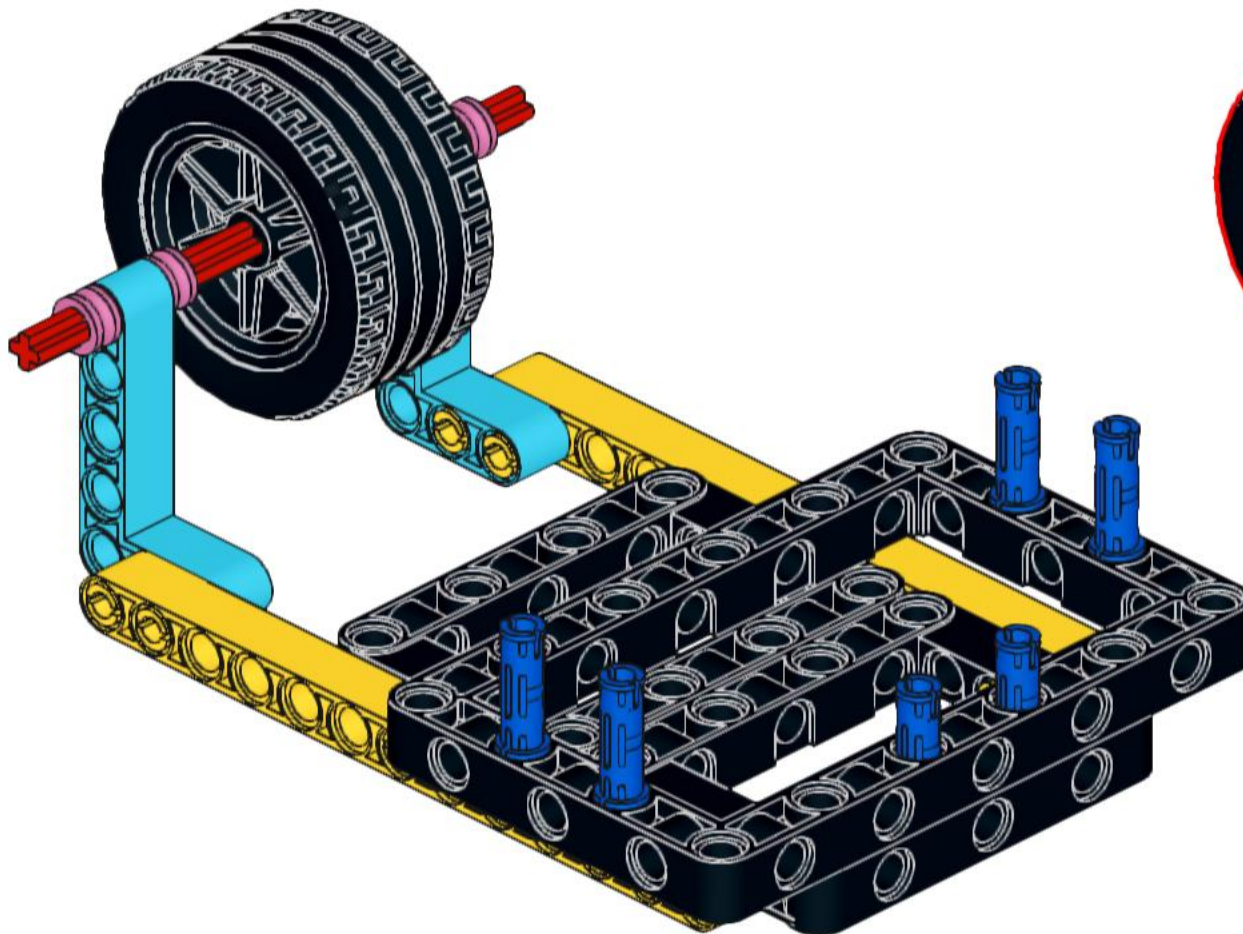
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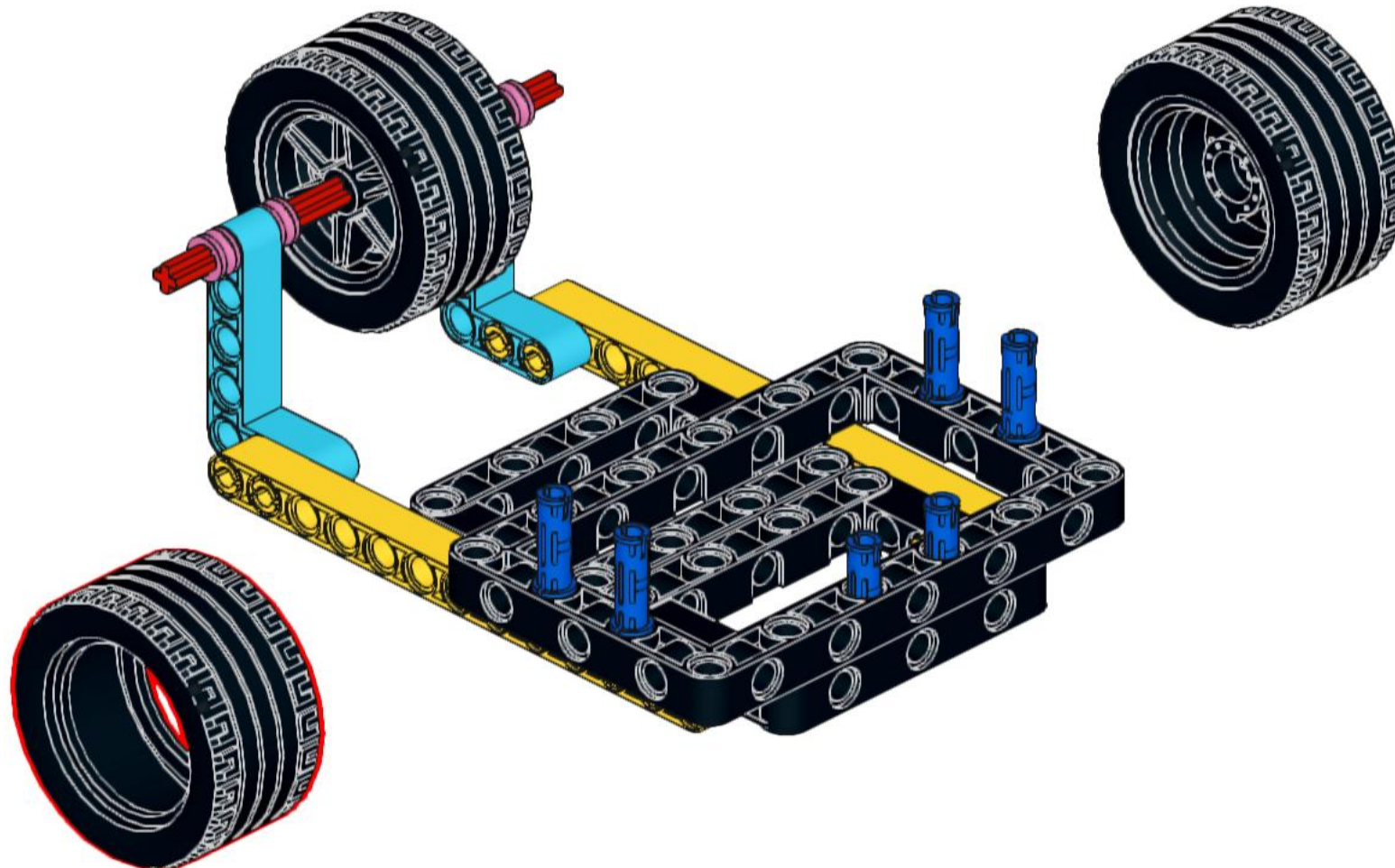
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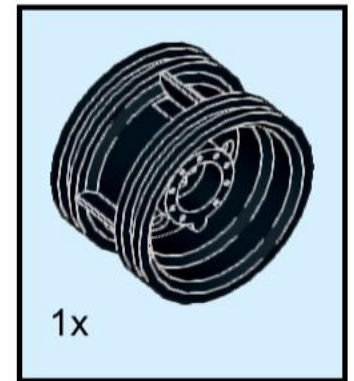
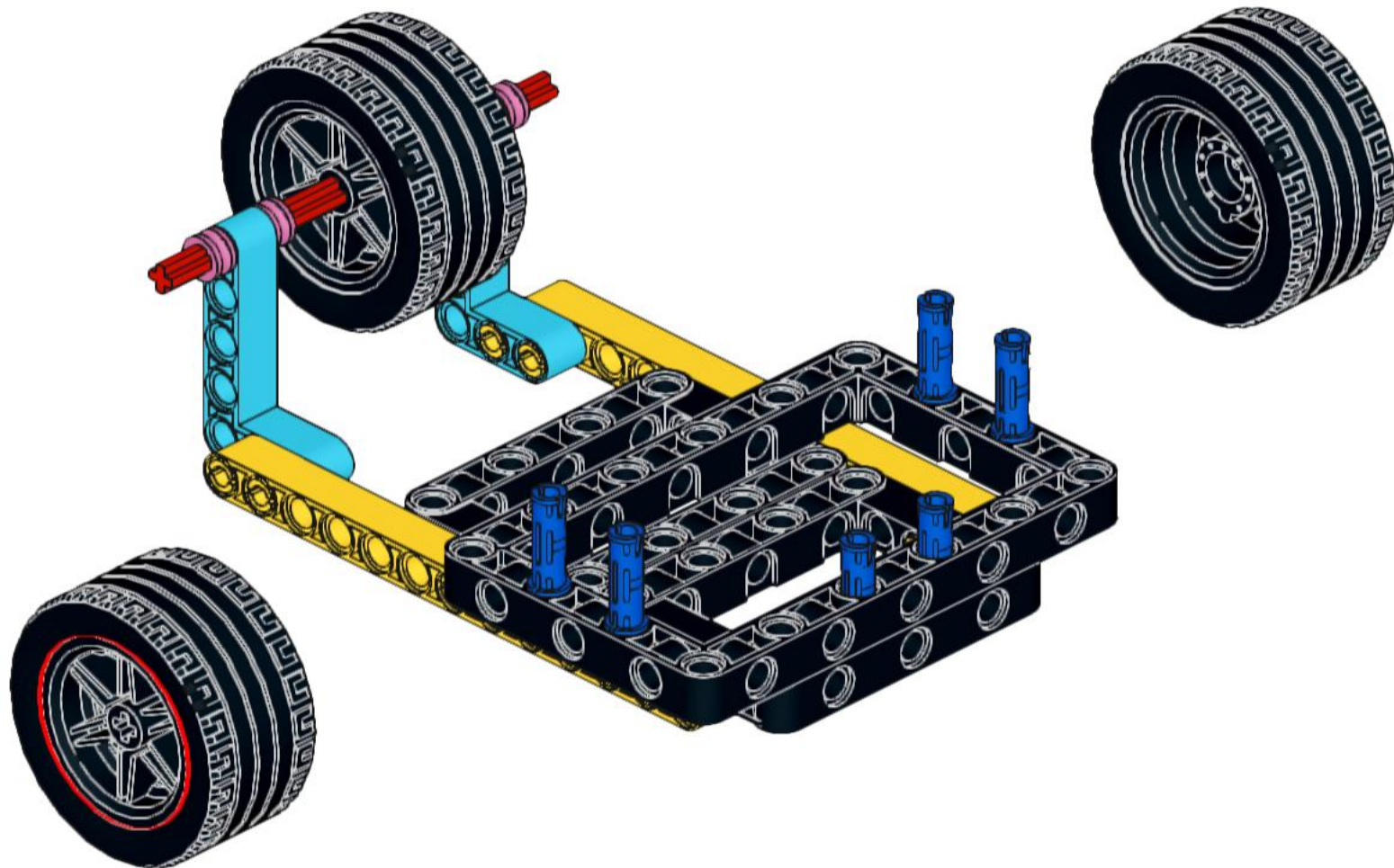
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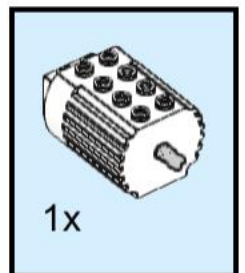
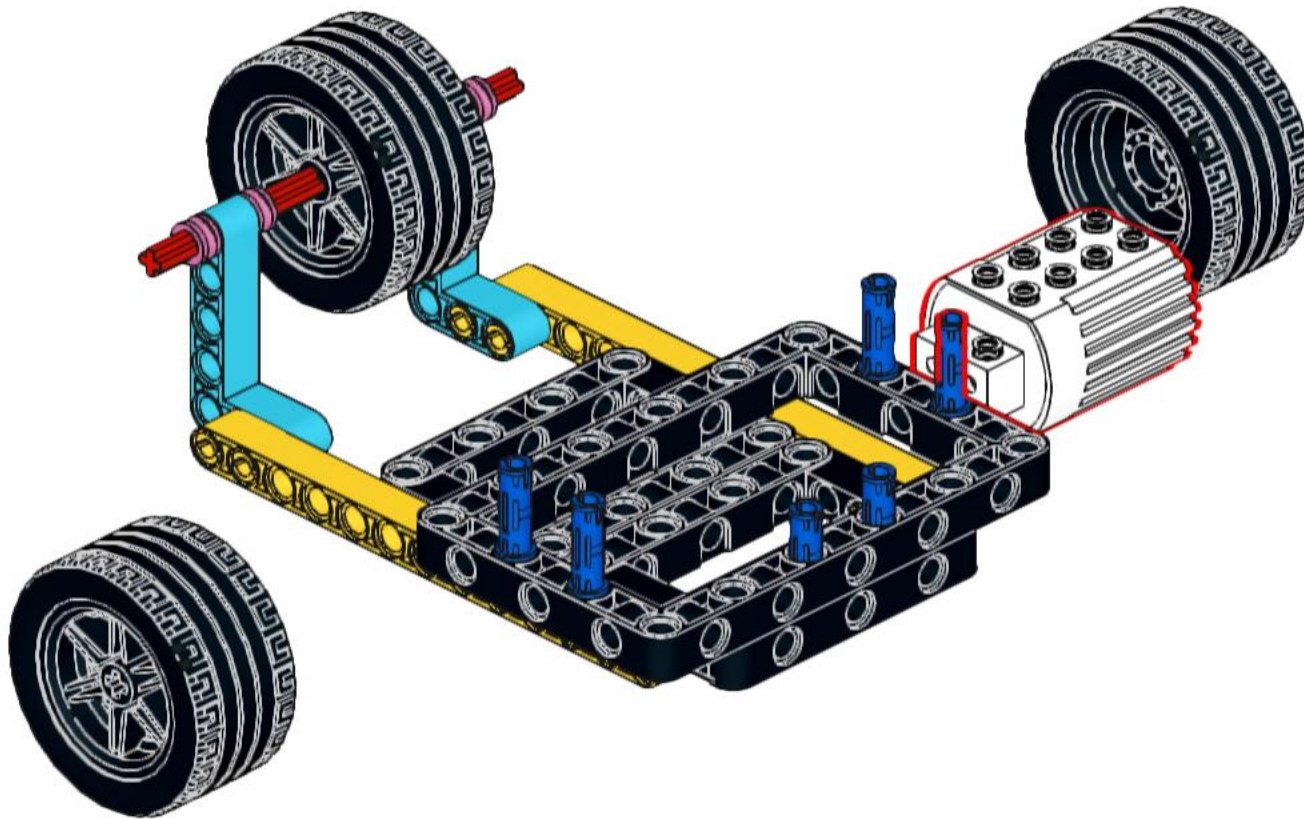
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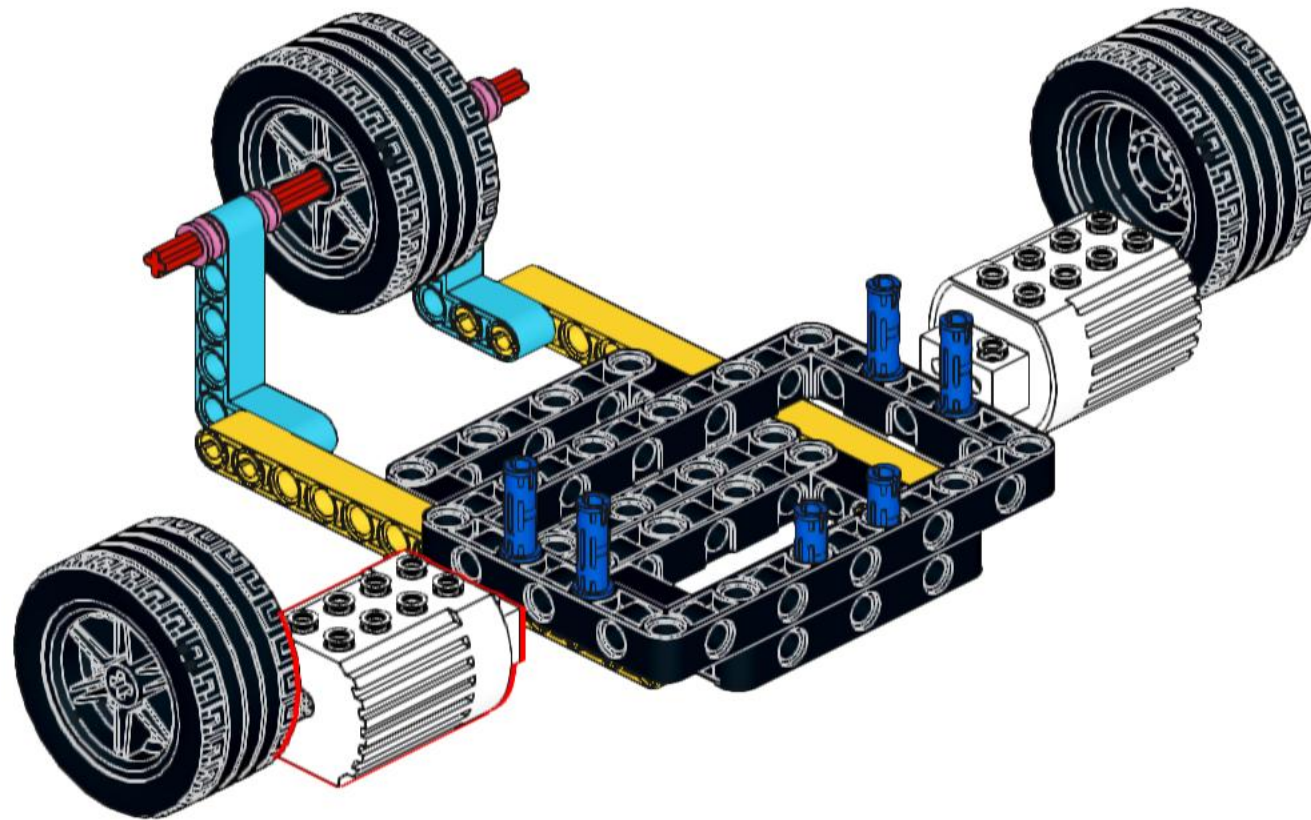
21

Use a servo and wheel set.

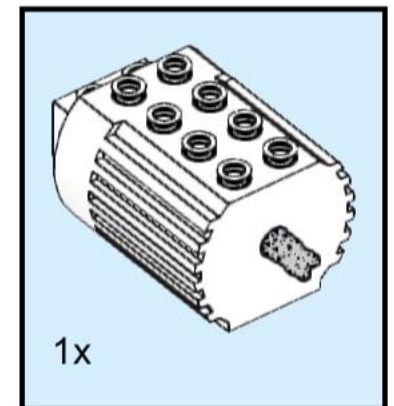
4PCS Red motor + 4PCS Wheel



22



4PCS Red motor + 4PCS Wheel



Attach the micro:bit expansion board to the top of the chassis using connectors.
Connect motors to digital pins (GPIO) and program your micro:bit. *MakeCode is a great way to start learning.

Optional: Connect multiple sensors to create a smart Kitty Cruise!



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