

# Parrot Mambo Swift Playground Command Reference

# Take-off / Landing

takeOff()
land()

#### **Dependencies**:

Maybe you'll put a little wait between takeOff() and land() in order to make the drone hover in the air for a few seconds.

# **Setting the Speed**

Sets the speed for the move command.

droneSpeed = Int

# Moving Along X- and Y-Axis Simple Movement

```
move(direction: MoveDirection. [ down | up | left | right | forward |
backward ], duration: Int)
```

# **Complex Movement**

```
move(pitch: Int, roll: Int, gaz: Int, yaw: Int, duration: Int)
pitch: MoveDirection. [ forward | backward ] (forward > 0, backward <0)
roll: MoveDirection. [ left | right ] (right > 0, left < 0)
gaz: MoveDirection. [ up | down ] (up > 0, down < 0)
yaw: TurnDirection. [ left | right ] (right > 0, left < 0)</pre>
```

# **Conditional Move**

```
move(direction: MoveDirection. [ down | up | left | right | forward |
backward ])
stopMoving()
```

#### Dependencies:

The Mambo has to takeOff() first. At the end it needs to land(). Moves at the speed that is set by the droneSpeed variable.

The conditional move () has to be ended by the stopMoving () command.

# **Turning Along the Z-Axis**

```
turn (direction: TurnDirection. [ left | right ], angle: Int) angle: 0 - 180 (If angle is greater than 180, the Mambo will 180°.)
```

#### Dependencies:

The Mambo has to takeOff() first. At the end it needs to land().

# Flip Along X- and Y-Axis

```
flip(direction: FlipDirection. [ front | back | right | left ])
```

#### Dependencies:

The Mambo has to takeOff() first. At the end it needs to land(). Battery has to be charged at least 20%.

No accessories are mounted.

# **Operating the Grabber**

```
openGrabber()
closeGrabber()
```

#### Dependencies:

The grabber is mounted and connected to the Mambo.

# **Operating the Camera**

```
takePicture()
```

#### **Dependencies**:

The Mambo has to takeOff() first. At the end it needs to land().

# **Events**

#### In the File

Parrot Education.playgroundbook/Content/Sources/motionDetector.swift the return values or the waitNextMotionEvent() are defined as an enum.



# Parrot Mambo Swift Playground Tutorial

# Preface Limiting your creativity / setting rails

It is good to know that Swift Playgrounds sometimes limits you to a subset of the possible solutions to a problem. It can happen that you are able to program syntactically correct answer but the Swift Playground just gives you an error message. For example it would be totally fine to take a picture even if the Mambo hasn't taken off. But you get an error message telling you, that the Mambo needs the takeOff() command first. This is not because of a bad programmer or a bug, but to make you stick to the task and limit distraction.

@@@X-, Y- and Z- Axis @@@Which Mambo Bundle

# **Chapter 1**

#### 1.2 - TakeoffLand

#### 1.2.1 - Basic Version

```
takeOff()
wait(4)
land()
```

# 1.3 - UpDown

#### 1.2.1 - Basic Version

```
takeOff()
move(direction: MoveDirection.up, duration: 1)
wait(1)
move(direction: MoveDirection.down, duration: 2)
land()
```

# 1.4 - LeftRight

## 1.4.1 - Basic Version

```
takeOff()
move(direction: MoveDirection.left, duration: 1)
wait(1)
move(direction: MoveDirection.right, duration: 1)
wait(1)
land()
```

# 1.5 - Challenge: Vertical Square

#### 1.5.1 - Basic Version

```
func verticalSquare() {
    move(direction: MoveDirection.left, duration: 1)
    move(direction: MoveDirection.up, duration: 1)
    move(direction: MoveDirection.right, duration: 1)
    move(direction: MoveDirection.down, duration: 1)
}

takeOff()
verticalSquare()
land()
```

# 1.6 - ForwardBackward

## 1.6.1 - Basic Version

```
takeOff()
```

```
move(direction: MoveDirection.forward, duration: 1)
move(direction: MoveDirection.backward, duration: 1)
land()
```

#### 1.7 - Rotation

#### 1.7.1 - Basic Version

```
takeOff()
turn(direction: TurnDirection.right, angle: 90)
turn(direction: TurnDirection.left, angle: 90)
land()
```

# 1.8 - Challenge

#### 1.8.1 - Basic Version

```
takeOff()
move(direction: MoveDirection.forward, duration: 1)
turn(direction: TurnDirection.right, angle: 90)
land()
```

## 1.8.2 - using a for-loop

```
func horizontalSquare() {
    for n in 1...4 {
        move(direction: MoveDirection.forward, duration: 1)
        turn(direction: TurnDirection.right, angle: 90)
    }
}
takeOff()
horizontalSquare()
land()
```

# 1.9 - SpeedTimeDistance

#### 1.9.1 - Basic Version

```
takeOff()
move(direction: MoveDirection.up, duration: 1)
droneSpeed = 10
move(direction: MoveDirection.forward, duration: 2)
move(direction: MoveDirection.backward, duration: 2)
land()
```

# 1.10 - Flips

#### 1.10.1 - Basic Version

```
takeOff()
```

```
flip(direction: FlipDirection.front)
flip(direction: FlipDirection.back)
flip(direction: FlipDirection.right)
flip(direction: FlipDirection.left)
land()
```

# 2.1 - Complex Moves

#### 2.1.1 - Basic Version

```
takeOff()
move(pitch: 0, roll: 0, gaz: 0, yaw: -20, duration: 2)
land()
```

# 2.2 - Spiral

#### 2.2.1 - Basic Version

```
func twisterUp() {
    //#-editable-code Add commands to your function
   move(pitch: 20, roll: 20, gaz: 10, yaw: 80, duration: 5)
    //#-end-editable-code
}
func twisterDown() {
    //#-editable-code Add commands to your function
   move(pitch: 20, roll: -20, gaz: -10, yaw: 80, duration: 5)
    //#-end-editable-code
}
func verticalTwister() {
    //#-editable-code Add commands to your function
    twisterUp()
    //turn(direction: TurnDirection.right, angle: 180)
    twisterDown()
    //#-end-editable-code
//#-editable-code Tap to enter code
takeOff()
//move(direction: MoveDirection.up, duration: 2)
verticalTwister()
land()
//#-end-editable-code
```

### 2.3 - Conditional Move

#### 2.3.1 - Basic Version

```
takeOff()
droneSpeed = 50
move(direction: MoveDirection.forward)
wait(2)
stopMoving()
move(direction: MoveDirection.backward)
wait(2)
stopMoving()
land()
```

#### 2.4 - Grabber

#### 2.4.1 - Basic Version

```
takeOff()
openGrabber()
wait(2)
closeGrabber()
wait(2)
land()
```

#### 2.5 - Camera

#### 2.5.1 - Basic Version

```
takeOff()
takePicture()
land()
```

# 2.6 - Challenge

#### 2.6.1 - Basic Version

```
func pictureRow() {
    for _ in 1...4 {
        move(direction: MoveDirection.forward, duration: 1)
        //takePicture()
    }
}
func pictureSquare() {
    for _ in 1...4 {
        //takePicture()
        pictureRow()
        move(direction: MoveDirection.right, duration: 1)
        move(direction: MoveDirection.backward, duration: 2)
    }
    move(direction: MoveDirection.right, duration: 2)
}
takeOff()
droneSpeed = 50
move(direction: MoveDirection.up, duration: 1)
```

```
pictureSquare()
land()
```

# 2.7 - Gyroscope

#### 2.7.1 - Basic Version

```
takeOff()
// run forever
while true {
    let event = waitNextMotionEvent()

    switch event {
    case .tiltForward:
        move(direction: MoveDirection.up, duration: 1)
    case .tiltBackward:
        move(direction: MoveDirection.down, duration: 1)
    default:
        break
    }
}
```

# 2.8 - iPad-Remote Control

#### 2.8.1 - Basic Version

```
takeOff()
// run forever
while true {
    let event = waitNextMotionEvent()
    switch event {
    case .tiltForward:
        move(direction: MoveDirection.forward, duration: 1)
    case .tiltBackward:
        move(direction: MoveDirection.backward, duration: 1)
    case .tiltLeft:
        move(direction: MoveDirection.left, duration: 1)
    case .tiltRight:
        move(direction: MoveDirection.right, duration: 1)
    case .shakeUp:
       move(direction: MoveDirection.up, duration: 1)
    case .shakeDown:
        move (direction: MoveDirection.down, duration: 1)
    default:
       break
}
```