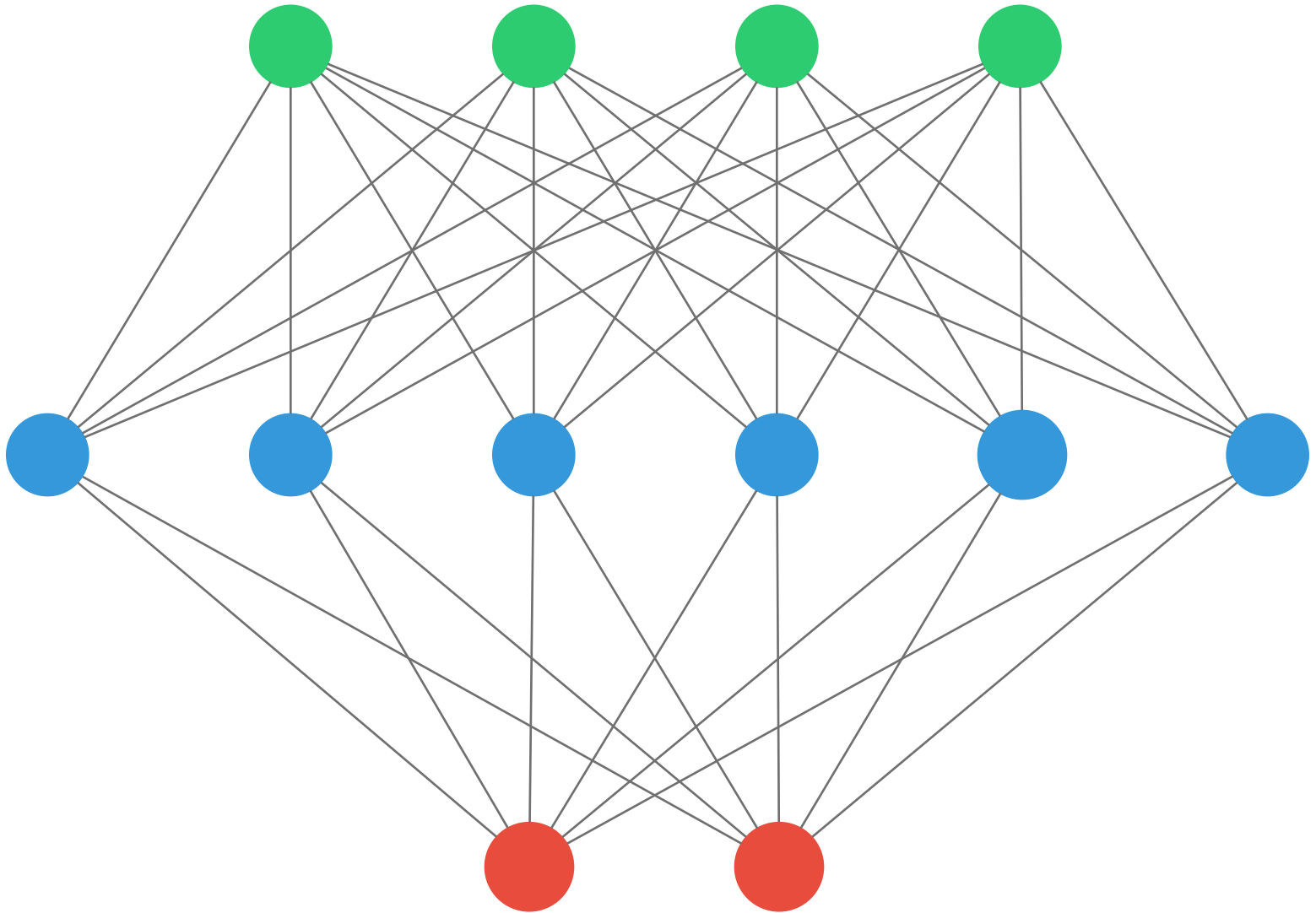


Robot Arm

Input Layer



Output Layer