## In [2]:

```
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import numpy as np
list1 = [3, 2, 8] #a
list2 = [2, 0, 1] \#b
list3 = [-2, 1, 5] \#c
vector1 = np.array(list1)
vector2 = np.array(list2)
vector3 = np.array(list3)
#lidur a
innfeldi = np.dot(vector1, vector2)
Bb = np.dot(matrix2, vector2)
innfeldi c Bb = np.dot(vector3, Bb)
c = np.linalg.norm(vector3)
utkoma = innfeldi - innfeldi c Bb / (3 * c)
#lidur b
AT = matrix1.T
B odru = np.dot(matrix2, matrix2)
summa = AT + B odru
seinni_svigi = vector1 - 2*vector2
nidurstada = np.dot(summa, seinni svigi)
final = 2 * nidurstada
#lidur c
determinant = np.linalg.det(matrix1)
inverse = np.linalg.inv(matrix1)
#lidur d
x = np.linalg.solve(matrix1, vector2)
```

## In [ ]: