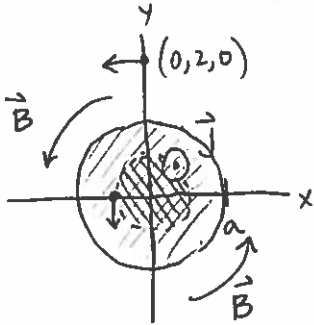


1. (25 pts) According to Ampere's Law, the magnetic \mathbf{H} field generated by a cylindrically symmetric current distribution along the z -axis points in the azimuthal ($\hat{\phi}$) direction, and its magnitude varies with distance r from the z -axis in terms of the $+\hat{z}$ -directed current I_{encl} passing through a circular contour centered on the z -axis:

$$H_{\phi}(r) = \frac{I_{\text{encl}}}{2\pi r} = \frac{B_{\phi}}{\mu}$$

- a) PART ONE: Consider a volumetric current density $\mathbf{J} = 3\hat{z}$ A/m² embedded in free space which is symmetric around the z -axis and uniformly distributed across a cross sectional area of radius $a = 1$ m.



- i. (3 pts) In terms of cartesian coordinate unit directions, what is \mathbf{B} at $(x, y, z) = (0, 2, 2)$?

$r = 2$ (distance along \hat{z} is irrelevant in cylindrical coords)

$$I_{\text{encl}} = \int_0^2 \mathbf{J} \cdot d\mathbf{s} = \int_0^2 3 ds = 3 \int_0^2 ds = 3(\pi a^2) = I_{\text{total}}$$

$$\vec{B} = -\hat{x} \mu_0 H_{\phi} = -\hat{x} \mu_0 \frac{3\pi a^2}{2\pi(2)} = -\hat{x} \frac{3}{4} \mu_0 a^2 \text{ [Wb/m}^2\text{]}$$

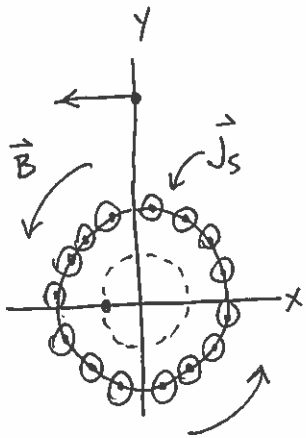
- ii. (3 pts) In terms of cartesian coordinate unit directions, what is \mathbf{B} at $(x, y, z) = (-\frac{1}{2}, 0, 0)$?

$$r = \frac{1}{2}$$

$$I_{\text{encl}} = \int_0^{\frac{1}{2}} \mathbf{J} \cdot d\mathbf{s} = 3(\pi(\frac{1}{2})^2) = \frac{3}{4}\pi$$

$$\vec{B} = -\hat{y} \mu_0 H_{\phi} = -\hat{y} \mu_0 \frac{\frac{3}{4}\pi}{2\pi(\frac{1}{2})} = -\hat{y} \frac{3}{4} \mu_0$$

- b) PART TWO: Now consider that the same total current I (in A) is instead carried as a surface current on a hollow cylindrical shell having the same radius $a = 1$ m as the thick wire described in PART ONE above.



- i. (5 pts) What is the current density on this cylindrical surface?

total current $I = 3(\pi a^2) \text{ [A]}$ is spread around the circumference of the shell $= 2\pi a$.

$$\text{so } \vec{J}_s = \hat{z} \frac{3\pi a^2}{2\pi a} = \hat{z} \frac{3}{2} a \text{ [A/m]}$$

- ii. (5 pts) How would your answers in PART ONE above change for this new current configuration?

Outside the shell, I_{encl} is the same.

so NO CHANGE in $\vec{B}(0, 2, 2)$

Inside the shell, $I_{\text{encl}} = 0$.

so $\vec{B}(-\frac{1}{2}, 0, 0) = 0$ Field components cancel by symmetry

2. (30 pts) Short answer questions, each is independent of the others.

- a) (5 pts) A surface current density $\vec{J} = f(t)\hat{z}$ on the $y = 0$ plane generates a TEM wave that propagates into free space on both sides. The following expression is NOT the wave equation for the plane wave just described:

$$\nabla^2 \vec{E} = \frac{\partial^2 E_x}{\partial y^2} + \frac{\partial^2 E_x}{\partial z^2} = \frac{\partial^2 E_x}{\partial t^2}$$

Identify and explain the errors in this wave equation and write the correct expression below.

Source @ $y=0 \Rightarrow \hat{r}_p = \pm \hat{y}$ so \vec{E} only depends on y . $\frac{\partial}{\partial z} \rightarrow \emptyset$
 \vec{J} along $\hat{z} \Rightarrow \vec{E}$ along \hat{z} so $\vec{E} = E_z(y, t)$. not E_x .

$$\nabla^2 \vec{E} = \frac{\partial^2 E_z}{\partial y^2} = \frac{\partial^2 E_z}{\partial t^2}$$

- b) (5 pts) Which statement best explains the boundary condition between two perfect dielectric media having different magnetic permeabilities μ_1 and μ_2 ?

- ☒ i. All components of the \vec{B} and \vec{H} fields are continuous across the boundary.
- ☒ ii. The normal and the tangential components of the \vec{B} field are continuous across the boundary.
- ☒ iii. The normal and the tangential components of the \vec{H} field are continuous across the boundary.
- ☒ iv. The normal component of \vec{B} and the tangential components of \vec{H} are continuous across the boundary.
- ☒ v. Only the normal component of \vec{B} is continuous across the boundary.
- ☒ vi. None of the above.

no free charges to carry current at the boundary: $\vec{J}_s = 0$

boundary condition equations:

$$\hat{n} \cdot (\vec{B}^+ - \vec{B}^-) = 0 \quad \text{so } B_n^+ = B_n^-$$

normal \vec{B} continuous

$$\hat{n} \times (\vec{H}^+ - \vec{H}^-) = \vec{J}_s = 0$$

tangential \vec{H} continuous.

since $\vec{H} = \vec{B}/\mu$, normal \vec{H} and tangential \vec{B} will be discontinuous since $\mu^+ \neq \mu^-$

- c) (5 pts) A shorted co-axial cable of length l , inner conductor radius a , outer conductor radius b , is filled with a material having permittivity ϵ and permeability μ . A total current I flows along the inner conductor and returns through the outer conductor. The inductance L exhibits which of the following behaviors? Choose all that apply.

i. L increases as b increases

ii. L increases as l increases

iii. L increases as μ increases

iv. L increases as I increases

v. none of the above

$$L = \frac{\Phi}{I} = \mu l \frac{\ln(b/a)}{2\pi}$$

i, ii, iii

- d) (5 pts) If $\mathbf{J} = 2 \sin(z) \hat{z}$ A/m², then the charge density at the origin is

i. constant

ii. increasing

iii. decreasing

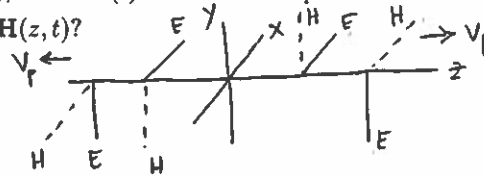
$$-\frac{\partial \rho}{\partial t} = \nabla \cdot \mathbf{J} = \frac{\partial J_z}{\partial z} = 2 \cos(z)$$

$$\text{at } z=0 \quad \frac{\partial \rho}{\partial t} = -2$$

iii

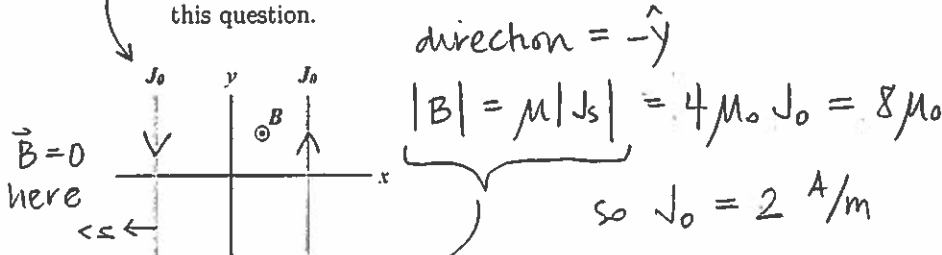
- e) (5 pts) A TEM wave propagating in free space is known to have the following electric field waveform: $\mathbf{E}(z, t) = u(t \pm \frac{z}{c}) \hat{x} - u(t \pm \frac{z}{c}) \hat{y}$, where $u(t)$ is the unit step function. What is the waveform of the associated magnetic field $\mathbf{H}(z, t)$?

$$\frac{|\mathbf{E}|}{|\mathbf{H}|} = \eta_0 \quad \hat{e} \times \hat{h} = \hat{v}_p$$



$$\vec{H}(z, t) = \frac{1}{\eta_0} u(t \mp \frac{z}{c}) (\pm \hat{y}) + \frac{1}{\eta_0} u(t \mp \frac{z}{c}) (\pm \hat{x})$$

- f) (5 pts) A pair of infinite current sheets are positioned on the $x = -2$ m plane and $x = +2$ m plane and carry equal and opposite current density of constant magnitude J_0 . The region between the sheets is filled with a perfect dielectric material having permittivity $9\epsilon_0$ and permeability $4\mu_0$. The magnetic field in the region between the current sheets is known to be $\mathbf{B} = 8\mu_0 \hat{z}$ Wb/m². What is the magnitude and direction of the surface current on the $x = -2$ m plane? You are not required to derive the field strength of a single current sheet using Ampere's Law to answer this question.



direction = $-\hat{y}$

$$|B| = \mu |J_s| = 4\mu_0 J_0 = 8\mu_0$$

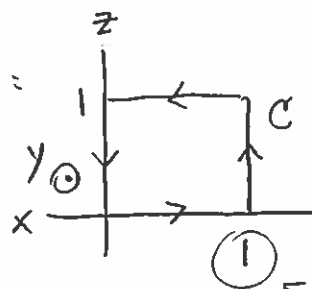
$$\text{so } J_0 = 2 \text{ A/m}$$

$$|\vec{H}| = \frac{|J_s|}{2} \text{ due to one sheet.}$$

$$\text{or } \hat{n} \times (\vec{H}^+ - \vec{H}^-) = \vec{J}_s = -\hat{x} \times (0 - \frac{B}{\mu} \hat{z}) = -\hat{y} J_0$$

$$-\hat{y} \frac{B}{\mu} = -\hat{y} J_0 \Rightarrow J_0 = 2 \text{ A/m}$$

3. Conducting wire shown as:



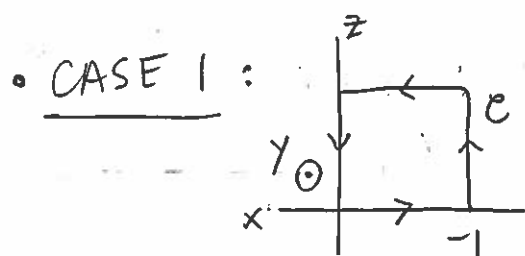
TYPO! Was supposed to be -1

Embedded in

$$\vec{B} = 5y \cos(\omega t) \hat{x} + 5x \sin(\omega t) \hat{y} + 10e^{-t} \hat{z} \quad \text{Wb/m}^2$$

The position of the loop and orientation of \vec{ds} (RH rule w/ \vec{C}) is critical to answers for parts (a)-(c).

Full credit was given to the following answers:



here, $\vec{ds} = +\hat{y} dx dz$

only B_y component contributes to magnetic flux through the loop

- a) At $t=0$, $B_y = 5x \sin(\omega t)$ is negative ($-1 < x < 0$) and increasing in magnitude $\frac{d|\sin(\omega t)|}{dt} > 0$

Induced current will counteract this change in flux by generating \vec{B}' with a positive B_y component.

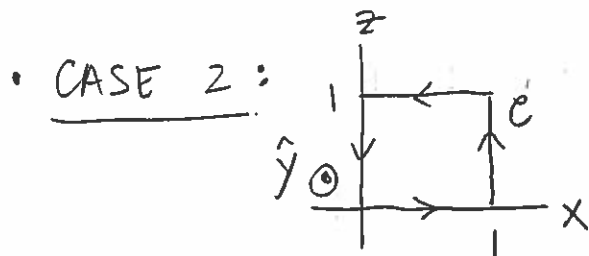
This current must flow along $\vec{C} \Rightarrow$ TRUE.

(Therefore, I expect derived $\mathcal{E} > 0$ below)

$$\begin{aligned} b) \quad \Phi(t) &= \int \vec{B} \cdot \vec{ds} = \int_{-1}^1 \int_0^1 B_y \hat{y} \cdot \hat{y} dx dz && \hat{y} \cdot \hat{y} = +1 \\ &= \int_0^1 dz \int_{-1}^1 5x \sin(\omega t) dx \\ &= (1)(5 \sin(\omega t)) \left[\frac{1}{2} x^2 \right]_{-1}^0 \\ &= -\frac{5}{2} \sin(\omega t) \quad [\text{Wb}] \end{aligned}$$

$$c) \mathcal{E} = -\frac{d\Phi}{dt} = -\frac{d}{dt}\left(-\frac{5}{2}\sin(\omega t)\right) = \frac{5}{2}\omega\cos(\omega t) \text{ [V]}$$

(indeed $\mathcal{E} > 0$ at $t=0$)



NOTE: by moving \hat{x} , coordinate system is now left-handed, so this solution is physically wrong.

a) loop $\vec{ds} = +\hat{y}dx dz$ as before.

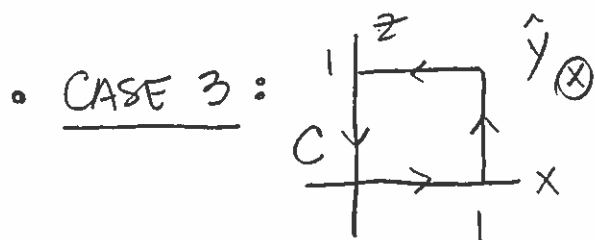
but now B_y is positive and increasing at $t=0$.

\Rightarrow current will flow opposite to C to induce $B_y < 0$ (Lenz law)

$$b) \Phi(t) = \int_0^1 \int_0^1 B_y \hat{y} \cdot \hat{y} dx dz = \int_0^1 dz \int_0^1 5x \sin(\omega t) dx$$

$$= +\frac{5}{2}\sin(\omega t) \text{ [wb]}$$

$$c) \mathcal{E} = -\frac{d\Phi}{dt} = -\frac{5}{2}\omega\cos(\omega t) \text{ [V]} \quad (\mathcal{E} < 0 \text{ at } t=0 \text{ is consistent w/ a})$$



For RH coordinate system, reverse \hat{x} and \hat{y} .

a) now $\vec{ds} = -\hat{y}dx dz$. B_y is still positive & increasing at $t=0$, so current must generate negative B_y . \Rightarrow along $C \Rightarrow$ TRUE

$$b) \Phi(t) = \int_0^1 \int_0^1 B_y \hat{y} \cdot (-\hat{y}) dx dz$$

$$= -\frac{5}{2}\sin(\omega t) \text{ [wb]}$$

$$c) \mathcal{E} = +\frac{5}{2}\omega\cos(\omega t) \text{ [V]}$$

d) Regardless of coordinate system, consider changing material around loop to $\mu = 1.5\mu_0$.

Assuming \vec{B} is the same as above, $\Phi(t)$ stays the same, and $-\frac{d\Phi}{dt} = \mathcal{E}$ also stays the same.

So current direction stays the same.

Induced current magnitude $I = \mathcal{E}/R$ stays the same.

NOTE! I is driven by an electric field in the loop frame:

$\mathcal{E} = \oint \vec{E} \cdot d\vec{\ell}$, generates \vec{B}_{induced} that will change magnitude in the magnetic material.

e) One test for \vec{B} validity is whether it satisfies Maxwell eqn

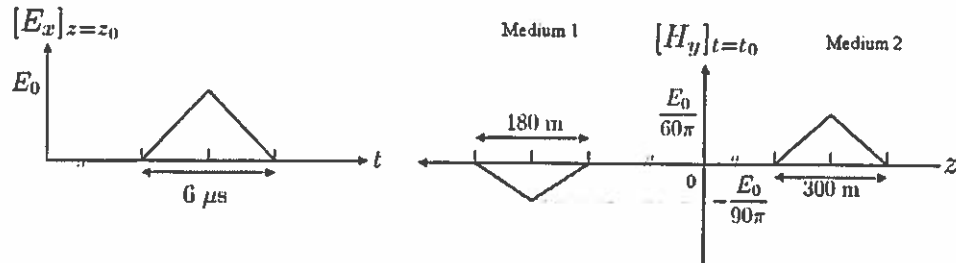
$$\nabla \cdot \vec{B} = \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = 0. \text{ This field does.}$$

It is also realistic to have temporal variation that is co-sinusoidal in one direction and decaying in another — fields from different sources superpose.

However, this field strength $\rightarrow \infty$ for increasing distances from origin. This is not physically realistic unless the expression for B is only valid locally.

4. (25 pts) An infinite plane current sheet of uniform density $\mathbf{J}_s = -J_s(t)\hat{x}$ A/m is sandwiched on the $z = 0$ plane between two perfect dielectric media, having material parameters ϵ_1 and μ_1 in Region 1 (on the $-\hat{z}$ side) and ϵ_2 and μ_2 in Region 2 (on the $+\hat{z}$ side). $J_s(t)$ is a triangular pulse which begins at $t = 0$ and lasts a duration of $6 \mu\text{s}$.

The figure below depicts the associated wavefield $E_x(z_0, t)$ at some location $z = z_0 > 0$ and the associated wavefield $H_y(z, t_0)$ at some time $t = t_0 > 0$.



Based on the information in the figures, answer the following questions:

- a) (4 pts) What are the intrinsic impedances η_1 and η_2 in medium 1 and medium 2, respectively?

$$\frac{|E|}{|H|} = \eta \quad \text{by inspection:} \quad |H_1| = \frac{|E_0|}{90\pi} \quad \text{so} \quad \eta_1 = 90\pi \, \Omega$$

$$|H_2| = \frac{|E_0|}{60\pi} \quad \text{so} \quad \eta_2 = 60\pi \, \Omega$$

- b) (6 pts) What are the propagation velocities v_{p1} and v_{p2} in medium 1 and medium 2, respectively?

Pulse duration of $6 \mu\text{s}$ spans Δz where $v_p = \Delta z / 6 \mu\text{s}$.

$$\text{so} \quad v_{p1} = \frac{180 \text{ m}}{6 \mu\text{s}} = 30 \text{ m}/\mu\text{s}$$

$$v_{p2} = \frac{300 \text{ m}}{6 \mu\text{s}} = 50 \text{ m}/\mu\text{s}$$

- c) (3 pts) If the maximum magnitude of $J_s(t)$ is 4 A/m, what is E_0 ?

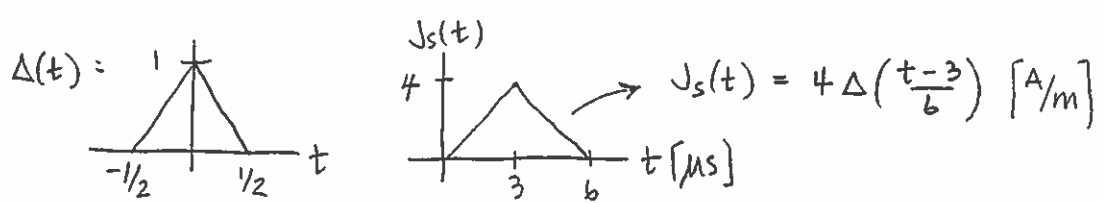
$$|E_0| = \frac{\eta}{2} |J_0| \left[\frac{\text{V}}{\text{m}} \right]$$

$$= \begin{cases} \frac{\eta_1(4)}{2} = 180\pi \left[\frac{\text{V}}{\text{m}} \right] & z < 0 \\ \frac{\eta_2(4)}{2} = 120\pi \left[\frac{\text{V}}{\text{m}} \right] & z > 0 \end{cases}$$

Can also relate $|J_s|$ to $|H|$ via boundary condition eqn:

$$\left(\vec{J}_s = \hat{n} \times (\mathbf{H}^+ - \mathbf{H}^-) \right)_{\text{max}} = 4 = \frac{E_0}{60\pi} + \frac{E_0}{90\pi} \Rightarrow E_0 = 144\pi$$

but this approach assumes $E_0(z > 0) = E_0(z < 0)$, which is not true (Full credit given regardless)



- d) (7 pts) Write the general expression for the propagating electric field $E(z, t)$ in terms of an appropriately scaled and shifted triangular pulse function $\Delta(t)$. You should express your answer in terms of E_0 , v_{p1} , etc., rather than using the numerical values you found above.

$$\vec{E}(z, t) = \begin{cases} \frac{J_0 \eta_1}{2} \Delta\left(\frac{t + z/v_{p1} - 3}{6}\right) (+\hat{x}) \text{ [V/m]} & z < 0 \\ \frac{J_0 \eta_2}{2} \Delta\left(\frac{t - z/v_{p2} - 3}{6}\right) (+\hat{x}) \text{ [V/m]} & z > 0 \end{cases}$$

- e) (5 pts) Is it possible to determine the material parameters μ_1 and ϵ_1 from the information given? If so, how? If not, what other information is needed?

YES. $\eta_1 = \sqrt{\frac{\mu_1}{\epsilon_1}} \quad v_{p1} = \frac{1}{\sqrt{\mu_1 \epsilon_1}}$

so $\epsilon_1 = \frac{1}{\eta_1 v_{p1}}$

$\mu_1 = \frac{\eta_1}{v_{p1}}$