

ICML 2020 Publishing Release

This Final Contribution Agreement ("Agreement") regarding the submission and publication of written material ("Articles") is made and entered into as of Sep 23, 2020 ("Effective Date") by and between Daniela Rus and the International Conference on Machine Learning (ICML), located at 10010 North Torrey Pines Road , La Jolla, CA 92037.

EventTitles: Prediction-Guided Multi-Objective Reinforcement Learning for Continuous Robot Control,
A Natural Lottery Ticket Winner: Reinforcement Learning with Ordinary Neural Circuits

Date: Jul 15, Jul 15, 2020

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Speaker:

Name (Print): Daniela Rus

By Checking this box and typing my name in the box below, I am agreeing to electronically sign this contract:

☒ Accept ☐ Decline

Signature:

Date: Sep 23, 2020

Name (Print): David Blei

Signature: 

International Conference on Machine Learning

Date: Sep 23, 2020

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EventTitle: Prediction-Guided Multi-Objective Reinforcement Learning for Continuous Robot Control

Date: Jul 15, 2020

I, Jie Xu, agree that:

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Speaker:

Name (Print): Jie Xu

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Signature:

Date: Sep 23, 2020

Name (Print): David Blei

Signature: 

International Conference on Machine Learning

Date: Sep 23, 2020

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EventTitle: Prediction-Guided Multi-Objective Reinforcement Learning for Continuous Robot Control

Date: Jul 15, 2020

I, Yunsheng Tian, agree that:

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Speaker:

Name (Print): Yunsheng Tian

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Signature:

Date: Sep 23, 2020

Name (Print): David Blei

Signature: 

International Conference on Machine Learning

Date: Sep 23, 2020

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This Final Contribution Agreement ("Agreement") regarding the submission and publication of written material ("Articles") is made and entered into as of Sep 23, 2020 ("Effective Date") by and between Shinjiro Sueda and the International Conference on Machine Learning (ICML), located at 10010 North Torrey Pines Road , La Jolla, CA 92037.

EventTitle: Prediction-Guided Multi-Objective Reinforcement Learning for Continuous Robot Control

Date: Jul 15, 2020

I, Shinjiro Sueda, agree that:

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Speaker:

Name (Print): Shinjiro Sueda

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☒ Accept ☐ Decline

Signature:

Date: Sep 23, 2020

Name (Print): David Blei

Signature: 

International Conference on Machine Learning

Date: Sep 23, 2020

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EventTitles: Efficient Continuous Pareto Exploration in Multi-Task Learning, Prediction-Guided Multi-Objective Reinforcement Learning for Continuous Robot Control

Date: Jul 16, Jul 15, 2020

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Speaker:

Name (Print): Pingchuan Ma

By Checking this box and typing my name in the box below, I am agreeing to electronically sign this contract:

☒ Accept ☐ Decline

Signature:

Date: Sep 23, 2020

Name (Print): David Blei

Signature: 

International Conference on Machine Learning

Date: Sep 23, 2020