ECE250: Signals and Systems

Assignment 4 Max-Marks: 80

Issued on: December 1, 2022 Due by: December 6, 2022 (5:30 pm)

Guidelines for submission

- Submit a hard copy of your solutions in the wooden box kept on the 3rd Floor of Old Academic Block (right side of the lift).
- Write your Name, Roll No. and Group No. (as assigned for your tutorials) on the hard copy of your solutions.
- Do all questions in sequence.
- Use A4 sheets (Plain).
- Staple your sheets properly.
- Please Provide proper mathematical justifications with your answers. No marks will be awarded without a valid justification.
- Institute's plagiarism policy will be strictly followed.
- 1) (CO5) (12 points) A signal $x(t) = 4e^{3t}u(t) + 5e^{4t}u(t)$ is given. Using the concepts of Fourier and Laplace transform answer the following questions:
 - (a) (2 pts) Will the Fourier transform of the given signal converge? Justify.
 - (b) (6 pts) Will the Fourier transform of $x(t)e^{-(2\alpha-\frac{7}{2})t}$ converge for the following values of α ? Justify.
 - i. $\alpha = 2.5$
 - ii. $\alpha = 3.5$
 - iii. $\alpha = 4.5$
 - (c) (4 pts) Compute the Laplace transform X(s) of x(t) and determine the ROC. Sketch the obtained ROC depicting poles and zeros of X(s). Using ROC, comment on the convergence results of Fourier transform in parts-(a) & (b).
- 2) (CO5) (12 points) Compute the Laplace transform, if it exists, for each the following functions. Clarify your reasoning on why the Laplace transform should exist or not in each case:
 - (a) (4 pts) $f_1(t) = t^2 sin(2t)$
 - (b) (4 pts) $f_2(t) = e^{t^2}$
 - (c) (4 pts) $f_3(t) = |2-t|[u(t-1)-u(t-3)]$, where u(t) denotes the unit step function.
- 3) (CO5) (15 points) Find the inverse Laplace transform of the following signals:
 - (a) (5 pts) $F_1(s) = \frac{2+2se^{-2s}+4e^{-4s}}{s^2+4s+3}, Re(s) > -1.$
 - (b) (5 pts) $F_2(s) = \frac{5s+13}{s(s^2+4s+13)}$, Re(s) > 0.
 - (c) (5 pts) $F_3(s) = log\left(\frac{s+4}{s+5}\right)$
- 4) (CO5) (9 points) Using initial value theorem and final value theorem, find $x(0^+)$ and $x(\infty)$ of the following Laplace transforms:

(a) (3 pts)
$$\frac{1}{s^2(s+1)}$$

(b) (3 pts)
$$\frac{(s+1)^2-1}{[(s+1)^2+1]^2}$$

(c) (3 pts)
$$\frac{1 - e^{-sT}}{s}$$

- 5) (CO5) (12 points) Consider four pole-zero configurations as shown in Fig. 1. What should be the possible ROC for each of these configurations if the related time domain function x(t) follows the given criteria?
 - (a) (6 pts) The Fourier transform of $x(t)e^{-t}$ converges.
 - (b) (6 pts) x(t) = 0 for t > 5.

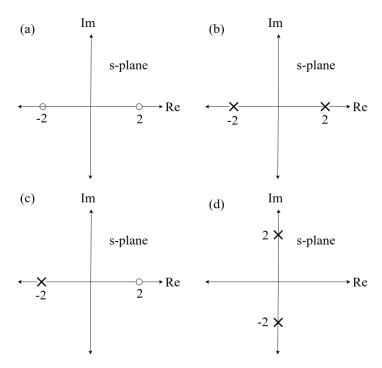


Figure 1: Pole-zero configurations (problem-5).

6) (CO5) (8 points) Consider an LTI system for which the input x(t) and output y(t) satisfy the linear differential equation as defined below:

$$\frac{d^2y(t)}{dt^2} + 3\frac{dy(t)}{dt} + 2y(t) = x(t) \tag{1}$$

- (a) (4 pts) Compute the system function H(s), where H(s) denotes the Laplace transform of system's impulse response. Assume all initial conditions to be zero.
- (b) (4 pts) Evaluate y(t) if the input $x(t) = e^{-t}$.
- 7) (CO5) (8 points) Evaluate y(t) by solving the following differential equation using the Laplace transform:

$$\frac{d^2y(t)}{dt^2} + 4\frac{dy(t)}{dt} = \cos(t-3) + 4t \tag{2}$$

Assume y(3) = 0 and $\frac{dy(3)}{dt} = 7$.

8) (CO5) (4 points) For a system S, as depicted in Fig. 2, input signal x(t) is of the form $x(t) = cos(2\pi f_0 t + \theta)$. Signal x(t) is sampled as $x_p(t)$, using a periodic impulse train p(t). Compute $X_p(j\omega)$, where $X_p(j\omega)$ denotes the Fourier spectrum of sampled signal $x_p(t)$.

$$x(t)$$
 $x_p(t)$ x_p

Figure 2: System S (problem-8).