

Scan chain based test setup for the Krypton CPLD board

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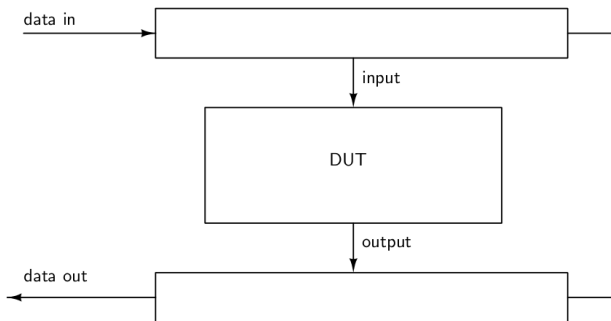
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Objectives

- Familiarize yourself with the Scan Chain environment
- Identify connections used for the Scan Chain system
- Create an input file
- Program the CPLD with a design
- Verify the design using the input file and the scan chain environment
- Analyse the output file
- References

Scan Chain



- Scan chain is a technique used for testing the hardware systems.
- a simple way to set the inputs for the system and observe their outputs.
- It consists of two shift registers and their control signals.

Main blocks

- Has three main parts.
 - Python Script : Gets the command inputs from the user in a text file.
 - Microcontroller(TM4C123GH6PM) : Convert these commands into a set of signals for the Krypton board.
 - Krypton board : Contains both the DUT and the scan chain.
- The PC communicates to the microcontroller through a USB link , with a predefined standard data transfer scheme.
- The microcontroller will translate the commands, and generate corresponding signals through its port pins.

Block Diagram

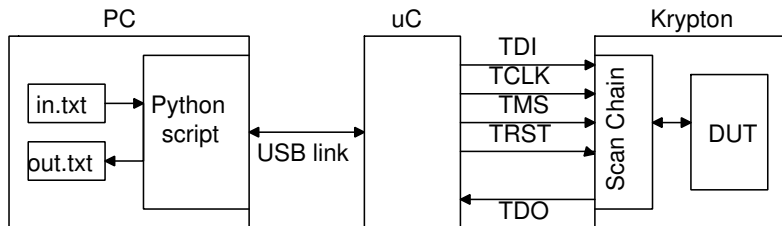


Figure : Tester Architecture

Interface Signals

- The tester hardware contains the scan chain and the controller (TAP controller) that provides necessary control signals to it.
- The interface signals of this top level system would be
 - TDI : The serial test data input to be loaded in the scan chain.
 - TMS : The commands for the TAP (Test Access Port) controller are passed serially through this pin.
 - TCLK : The clock reference forin design for testing all the other communication lines.
 - TRST : Pin to reset the TAP controller at any instant.
 - TDO : The serial data output from the scan chain.

Adding Scan Chain

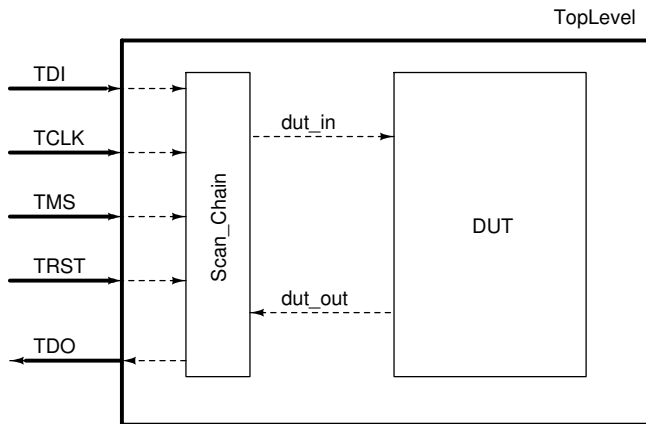


Figure : Top Level entity to be implemented into the Krypton CPLD

Adding Scan Chain(contd.)

- DUT should first be tested in gate level simulation and verified to be working.
- User has to write a top level entity (shown as mySystem) which contains the DUT and Scan Chain module as component
- mySystem should have 5 interface signals, TDI, TMS, TCLK, TRST and TDO.

Scan Chain Specifications

```
entity Scan_Chain is
generic (
  in_pins : integer; -- Number of input pins
  out_pins : integer -- Number of output pins
);
port (
  TDI : in std_logic; -- Test Data In
  TDO : out std_logic; -- Test Data Out
  TMS : in std_logic; -- TAP controller signal
  TCLK : in std_logic; -- Test clock
  TRST : in std_logic; -- Test reset
  dut_in : out std_logic_vector(in_pins-1 downto 0)
  -- Input for the DUT
  dut_out : in std_logic_vector(out_pins-1 downto 0)
  -- Output from the DUT
);
end Scan_Chain;
```

Scan Chain specifications (Contd.)

- Scan chain has two configurable parameters (in pins and out pins) indicating the number of input and output bits to the DUT, which can be generic mapped.
- It also has one output (dut in) and one input (dut out) that should be connected to the DUT
- Internally it contains an FSM (that implements the TAP Controller), one input scan register and one output scan register.

Reference Implementation : 16 bit adder

- DUT should first be tested in gate level simulation and verified to be working.
- User has to write a top level entity (shown as mySystem) which contains the DUT and Scan Chain module as component
- mySystem should have 5 interface signals, TDI, TMS, TCLK, TRST and TDO.

Hardware connections

- Next step is to make physical connections between the host PC, microcontroller board and the Krypton board.
- The microcontroller board is Tiva-C (TM4C123GXL based) from Texas Instruments. Connect it to the PC.
- The following connections between the microcontroller board and the Krypton need to be made

CPLD Pin	Tiva-C Pin	Function
Header 0: 3	J1:PB5	TDO
Header 0: 5	J1:PB0	TDI
Header 0: 7	J1:PB1	TMS
Header 0: 13	J1:PB4	TRST
Header 0: 15	J1:PA5	TCLK
Header 0: 25	J2:GND	GND

Table : Hardware Connections

Hardware connections

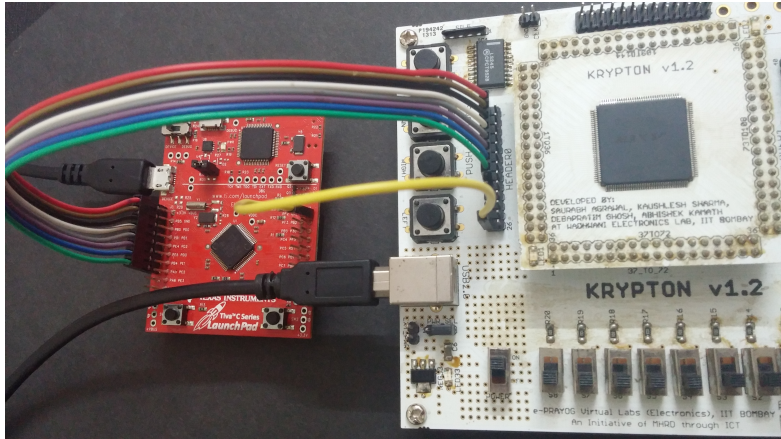


Figure : Hardware Connection between CPLD and Tiva-C using 8-PIN Female Connector

Input file format

- For testing the hardware, the user has to provide input combinations, their expected results and the time duration of execution.
- They should be written as commands in a text file and passed to the python script for test execution.
- These commands are derived from the Serial Vector Format (SVF), usually used in JTAG boundary scan.
- Only two commands are required for the current implementation.

SDR

SDR *<inpins>* TDI(*<input>*) *<outpins>* TDO(*<output>*)
MASK(*<maskbits>*)

- This Serial Data Register instruction is for carrying out a data scan in process.
- in pins & out pins contains the number of input and output bits respectively.
- input & output contains the input combination to be applied and its expected output combination respectively.
- mask bits are used to specify if any of the output bits are not important and could be taken as dont care

Example : SDR 2 TDI(0) 8 TDO(00) MASK(FF)

Note If the scanned output should not be compared, then all the mask bits should be kept as 0.

RUNTEST

RUNTEST <delay >MSEC

- As the previous instruction loads the input and samples the output, this instruction is used to apply the input combination to the DUT and wait for delay seconds.

Example : RUNTEST 60 MSEC

- The input, output and mask bits are to be written as hexadecimal numbers (uppercase for alphabets).
- An example input file is given in the supporting document.

Running the Python script

- First install pyUSB library on the PC by the following steps.
 - open terminal
 - type `sudo apt-get install python-pip`
 - type `sudo pip install pyusb`
- Now run the scan.py script with the following command.

```
python scan.py <inputfile><outputfile>
```

Where <input file > contains all the commands to be executed, and <output file > should be an empty file for storing the results.

References



[Getting Started with the TimeQuest Timing Analyzer]
<https://www.youtube.com/watch?v=bFmTHLZ3DGs> (Last accessed on 27/02/2015)



[SignalTap II Embedded Logic Analyzer Basics]
<https://www.youtube.com/watch?v=vhkzxCEXuaA> (Last accessed on 27/02/2015)



[DE0 Nano user manual]
www.altera.com/literature/ug/DE0_Nano_User_Manual_v1.9.pdf
(Last accessed on 27/02/2015)

Thank you