

3.1 Introduction

- We take a closer look at the use of the imshow function
- We look at image quality and how that may be affected by various image attributes
- For human vision in general, the preference is for images to be sharp and detailed



3.2 Basics of Image Display

- There are many factors that will affect the display
 - √ ambient lighting,
 - ✓ the monitor type and settings,
 - ✓ the graphics card, and
 - ✓ monitor resolution

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3.2 Basics of Image Display

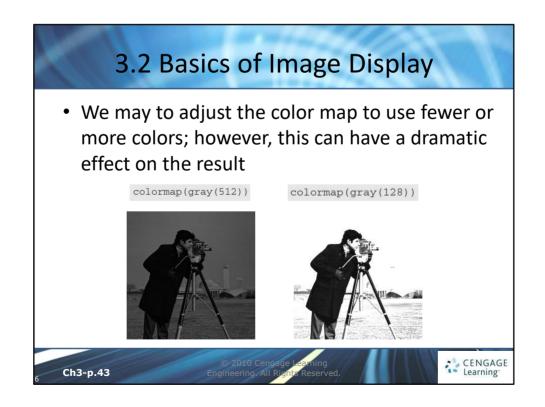
• This function image simply displays a matrix as an image

```
>> c=imread('cameraman.tif');
>> image(c)
```

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3.2 Basics of Image Display use imread to pick up the color map >> [x,map]=imread('trees.tif'); >> image(x),truesize,axis off,colormap(map) ✓ map is <256×3 double> in the workspace

3.2 Basics of Image Display

- True color image will be read (by imread) as a three-dimensional array
 - ✓ In such a case, image will ignore the current color map and assign colors to the display based on the values in the array
 - >> t=imread('twins.tif');
 >> image(t),truesize,axis off



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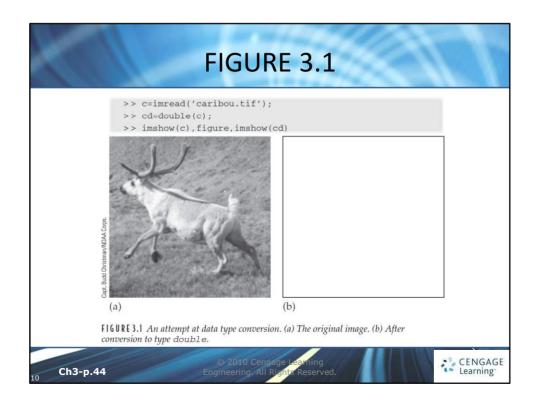
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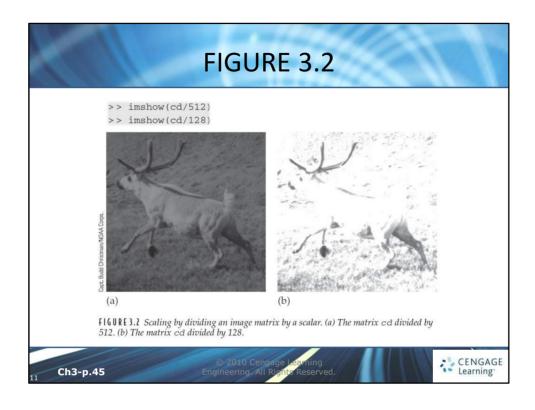
3.3 The imshow Function

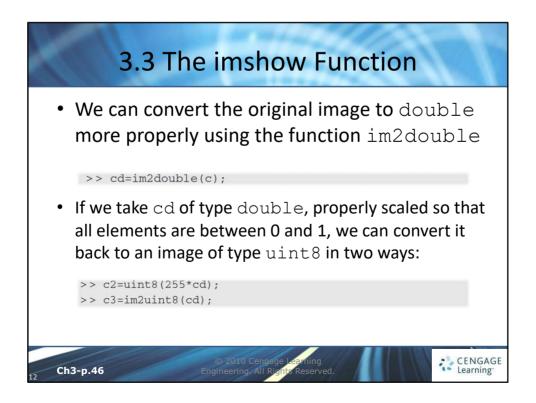
- We have two choices with a matrix of type double:
 - ✓ Convert to type uint8 and then display
 - ✓ Display the matrix directly
- imshow will display a matrix of type double as a grayscale image (matrix elements are between 0 and 1)

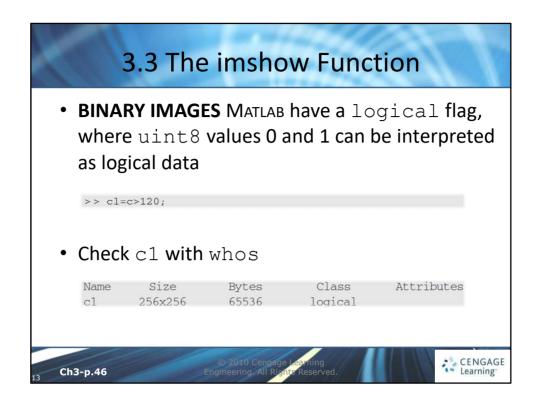
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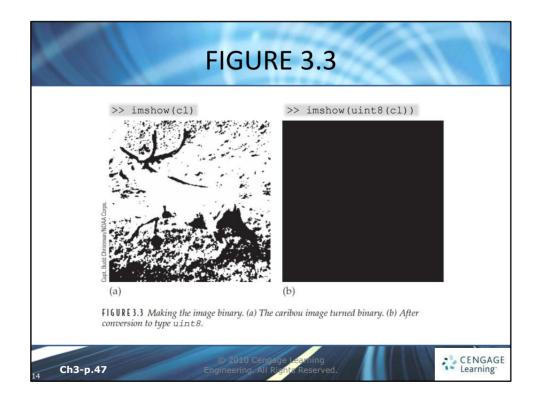
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3.4 Bit Planes

- Grayscale images can be transformed into a sequence of binary images by breaking them up into their bitplanes
- The zeroth bit plane
 - √ the least significant bit plane
- The seventh bit plane
 - √ the most significant bit plane



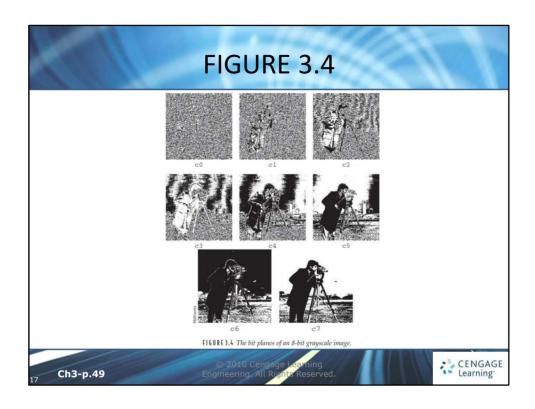
3.4 Bit Planes

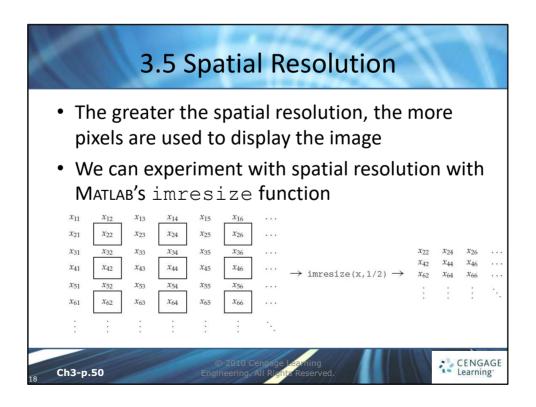
 We start by making it a matrix of type double; this means we can perform arithmetic on the values

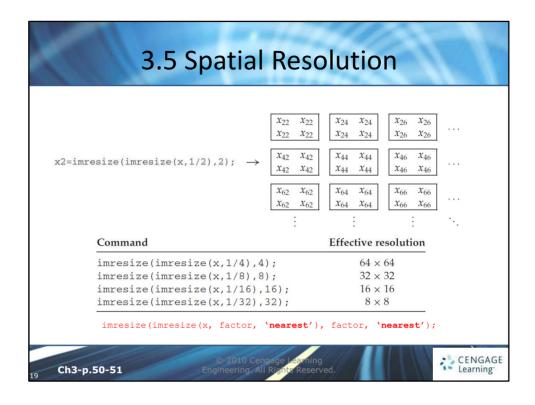
```
>> c=imread('cameraman.tif');
>> cd=double(c);
>> c0=mod(cd,2);
>> c1=mod(floor(cd/2),2);
>> c2=mod(floor(cd/4),2);
>> c3=mod(floor(cd/8),2);
>> c4=mod(floor(cd/16),2);
>> c5=mod(floor(cd/16),2);
>> c6=mod(floor(cd/32),2);
>> c7=mod(floor(cd/128),2);
```

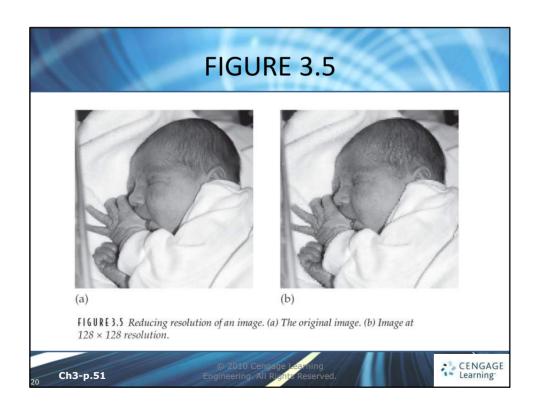
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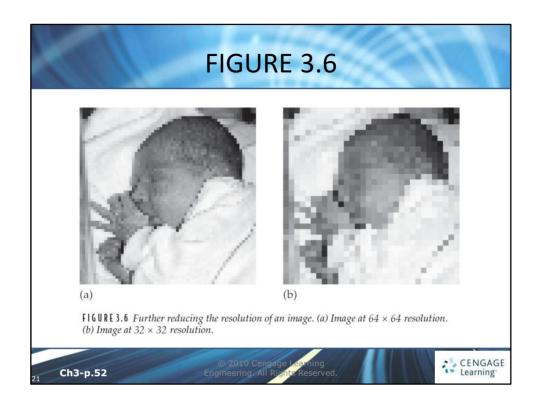
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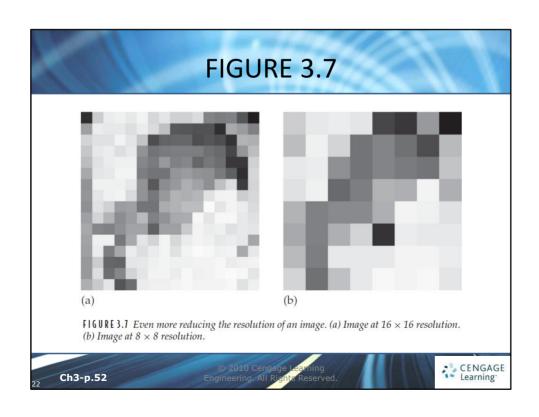


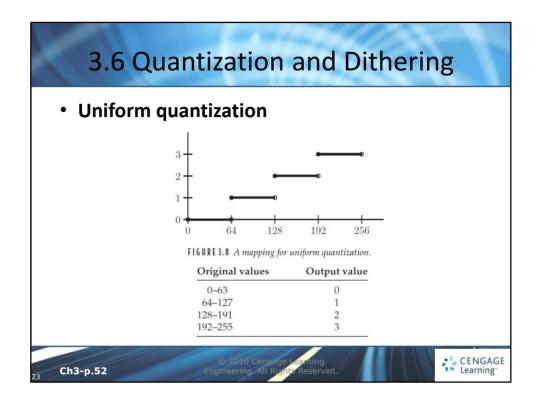












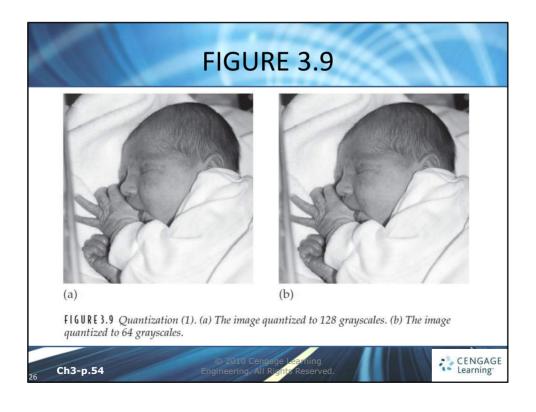
• To perform such a mapping in Matlab, we can perform the following operations, supposing x to be a matrix of type uint8

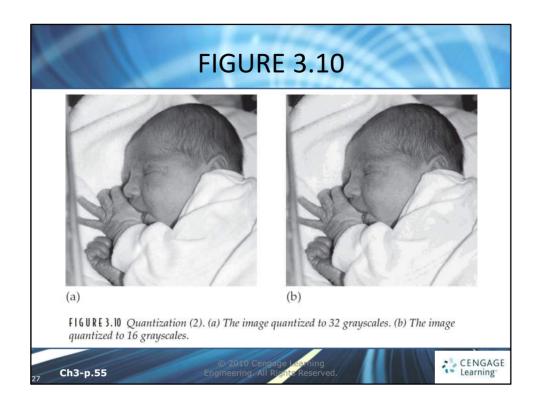
f=floor(double(x)/64);
q=uint8(f*64);

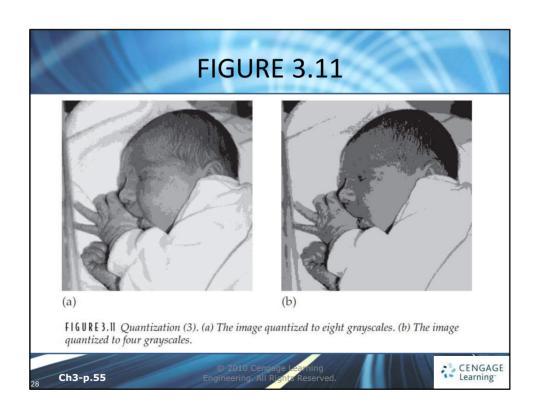
 There is, a more elegant method of reducing the grayscales in an image, and it involves using the grayslice function

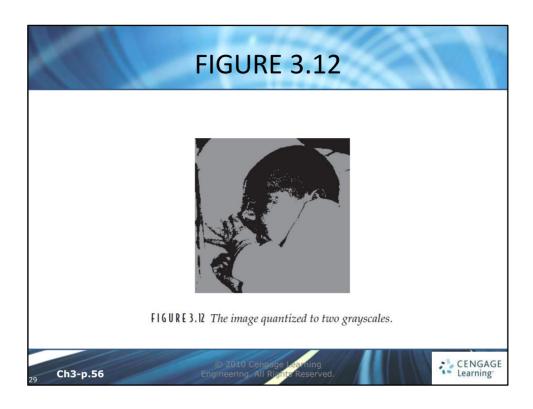


Command	Number of grayscale
<pre>imshow(grayslice(x,128),gray(128))</pre>	128
<pre>imshow(grayslice(x,64),gray(64))</pre>	64
imshow(grayslice(x, 32), gray(32))	32
<pre>imshow(grayslice(x,16),gray(16))</pre>	16
<pre>imshow(grayslice(x,8),gray(8))</pre>	8
imshow(grayslice(x,4),gray(4))	4
<pre>imshow(grayslice(x,2),gray(2))</pre>	2









- DITHERING In general terms, refers to the process of reducing the number of colors in an image
- Representing an image with only two tones is also known as halftoning



• Dithering matrix

$$D = \begin{bmatrix} 0 & 128 \\ 192 & 64 \end{bmatrix} \qquad D_2 = \begin{bmatrix} 0 & 128 & 32 & 160 \\ 192 & 64 & 224 & 96 \\ 48 & 176 & 16 & 144 \\ 240 & 112 & 208 & 80 \end{bmatrix}$$

• D or D_2 is repeated until it is as big as the image matrix, when the two are compared

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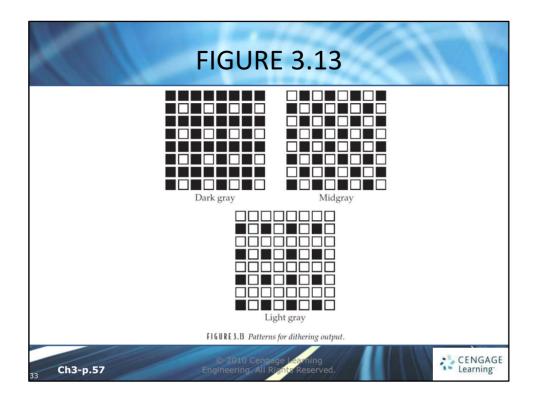
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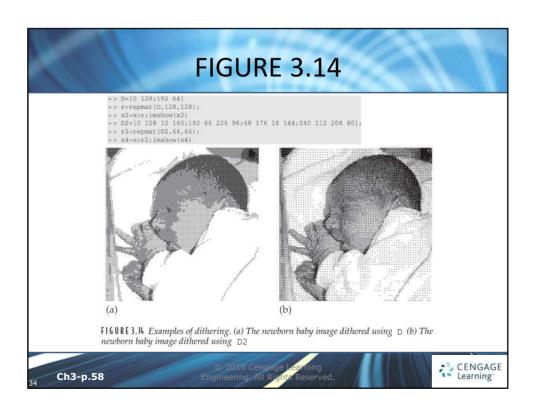
3.6 Quantization and Dithering

• Suppose d(i, j) is the matrix obtain by replicating the dithering matrix, then an output pixel p(i, j) is defined by

$$p(i,j) = \begin{cases} 1 & \text{if } x(i,j) > d(i,j) \\ 0 & \text{if } x(i,j) \le d(i,j) \end{cases}$$







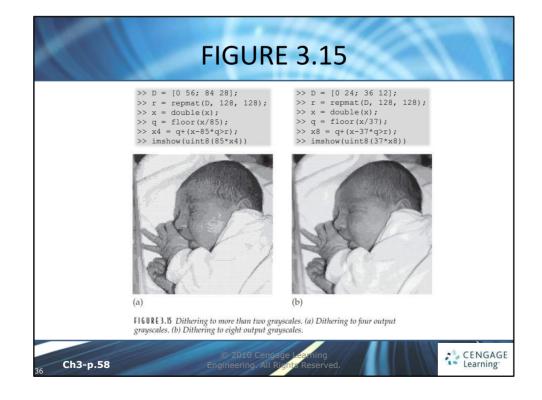
- Dithering can be extended easily to more than two output gray values
- For example, we wish to quantize to four output levels 0, 1, 2, and 3

$$q(i,j) = [x(i,j)/85] \quad \text{(Since 255/3 = 85)}$$

$$p(i,j) = q(i,j) + \begin{cases} 1 & \text{if } x(i,j) - 85q(i,j) > d(i,j) \\ 0 & \text{if } x(i,j) - 85q(i,j) \leq d(i,j) \end{cases}$$

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ERROR DIFFUSION

- √ The image is quantized at two levels
- ✓ For each pixel we take into account the error between its gray value and its quantized value
- ✓ The idea is to spread this error over neighboring pixels

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3.6 Quantization and Dithering

- Floyd and Steinberg method
 - ✓ For each pixel p(i, j) in the image we perform the following sequence of steps:
 - 1. Perform the quantization
 - 2. Calculate the quantization error

$$E = \begin{cases} p(i,j) & \text{if } p(i,j) < 128\\ p(i,j) - 255 & \text{if } p(i,j) >= 128 \end{cases}$$

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