CHAPTER 13:

Kernel Machines





Kernel Machines: Motivation

- Discriminant-based: No need to estimate densities first
- Define the discriminant in terms of support vectors
- The use of kernel functions, application-specific measures of similarity
- No need to represent instances as vectors
- Convex optimization problems with a unique solution

Optimal Separating Hyperpla



$$\mathcal{X} = \left\{ \mathbf{x}^t, \mathbf{r}^t \right\}_t \text{ where } \mathbf{r}^t = \begin{cases} +1 & \text{if } \mathbf{x}^t \in C_1 \\ -1 & \text{if } \mathbf{x}^t \in C_2 \end{cases}$$

find w and w_0 such that

$$\mathbf{w}^{\mathsf{T}}\mathbf{x}^{t} + \mathbf{w}_{0} \ge +1 \text{ for } \mathbf{r}^{t} = +1$$

$$\mathbf{w}^{\mathsf{T}}\mathbf{x}^{t} + \mathbf{w}_{0} \leq +1 \text{ for } \mathbf{r}^{t} = -1$$

which can be rewritten as

$$r^t (\mathbf{w}^T \mathbf{x}^t + \mathbf{w}_0) \ge +1$$

(Cortes and Vapnik, 1995; Vapnik, 1995)

Margin



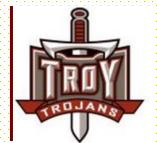
Distance from the discriminant to the closest instances on either side

Distance of x to the hyperplane is $\frac{\left|\mathbf{w}^{T}\mathbf{x}^{t} + \mathbf{w}_{0}\right|}{\left\|\mathbf{w}\right\|}$

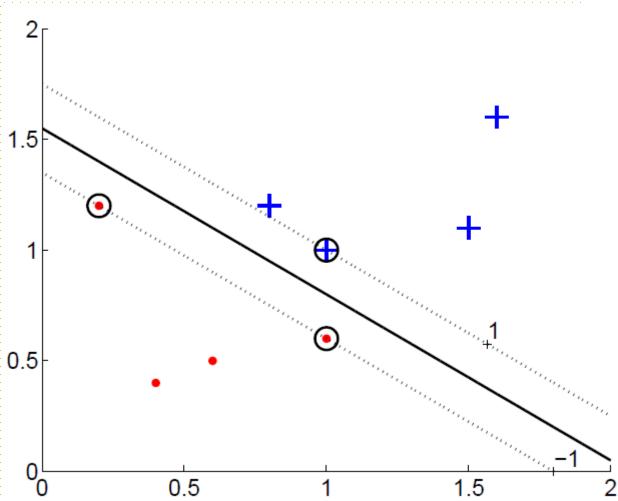
We require
$$\frac{r^t \left(\mathbf{w}^T \mathbf{x}^t + \mathbf{w}_0\right)}{\|\mathbf{w}\|} \ge \rho, \forall t$$

For a unique sol'n, fix $\rho ||\mathbf{w}|| = 1$, and to max margin

$$\min \frac{1}{2} \|\mathbf{w}\|^2 \text{ subject to } r^t (\mathbf{w}^T \mathbf{x}^t + \mathbf{w}_0) \ge +1, \forall t$$



Margin



Dual Formulation and solution 1/2



$$\min \frac{1}{2} \|\mathbf{w}\|^{2} \text{ subject to } r^{t} (\mathbf{w}^{T} \mathbf{x}^{t} + \mathbf{w}_{0}) \ge +1, \forall t$$

$$L_{p} = \frac{1}{2} \|\mathbf{w}\|^{2} - \sum_{t=1}^{N} \alpha^{t} [r^{t} (\mathbf{w}^{T} \mathbf{x}^{t} + \mathbf{w}_{0}) -1]$$

$$= \frac{1}{2} \|\mathbf{w}\|^{2} - \sum_{t=1}^{N} \alpha^{t} r^{t} (\mathbf{w}^{T} \mathbf{x}^{t} + \mathbf{w}_{0}) + \sum_{t=1}^{N} \alpha^{t}$$

$$\frac{\partial L_{p}}{\partial \mathbf{w}} = 0 \Rightarrow \mathbf{w} = \sum_{t=1}^{N} \alpha^{t} \mathbf{r}^{t} \mathbf{x}^{t}$$
$$\frac{\partial L_{p}}{\partial \mathbf{w}_{0}} = 0 \Rightarrow \sum_{t=1}^{N} \alpha^{t} \mathbf{r}^{t} = 0$$

Dual Formulation and solution 2/2



$$L_{d} = \frac{1}{2} (\mathbf{w}^{T} \mathbf{w}) - \mathbf{w}^{T} \sum_{t} \alpha^{t} r^{t} \mathbf{x}^{t} - w_{0} \sum_{t} \alpha^{t} r^{t} + \sum_{t} \alpha^{t}$$

$$= -\frac{1}{2} (\mathbf{w}^{T} \mathbf{w}) + \sum_{t} \alpha^{t}$$

$$= -\frac{1}{2} \sum_{t} \sum_{s} \alpha^{t} \alpha^{s} r^{t} r^{s} (\mathbf{x}^{t})^{T} \mathbf{x}^{s} + \sum_{t} \alpha^{t}$$
subject to $\sum_{t} \alpha^{t} r^{t} = 0$ and $\alpha^{t} \geq 0$, $\forall t$

Most α^t are 0 and only a small number have $\alpha^t > 0$; they are the support vectors

Need for soft margin



- Hard margin issues
 - works if the data is linearly separable
 - Sensitive to outliers

- Soft margin promotes more flexible model
 - Flexibility is controlled by parameter C (Details in next slide)

Soft margin Hyperplane



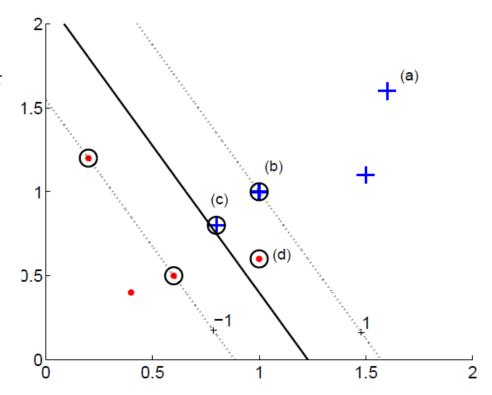
Not linearly separable

$$r^{t}\left(\mathbf{w}^{T}\mathbf{x}^{t}+\mathbf{w}_{0}\right)\geq 1-\xi^{t}$$
1.5

Soft error

$$\sum_{t} \xi^{t}$$

New primal is

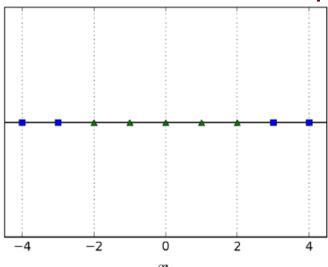


$$L_{p} = \frac{1}{2} \|\mathbf{w}\|^{2} + C \sum_{t} \xi^{t} - \sum_{t} \alpha^{t} \left[r^{t} \left(\mathbf{w}^{T} x^{t} + \mathbf{w}_{0} \right) - 1 + \xi^{t} \right] - \sum_{t} \mu^{t} \xi^{t}$$

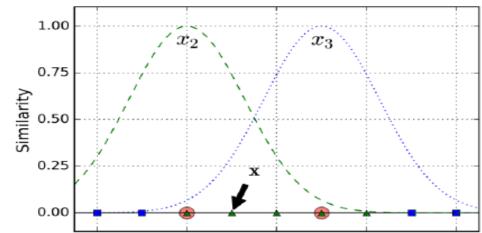
Nonlinear SVM

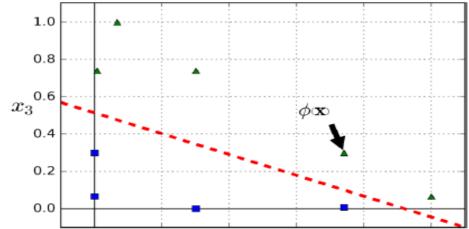
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Not linearly separable



• Similarity function: $\phi y(\mathbf{x}, \ell) = \exp(-y ||\mathbf{x} - \ell||^2)$





Non linear SVM



- When examples are not truly separable.
 - Map attributes to higher dimension
 - ϕ : X-> ϕ (X), going d-dimension to D-dimension
 - Then perform SVM
 - Problem: Computation cost of dot operation
 - X_i.X_i requires O(d²)
 - $\phi(X_i)$. $\phi(X_i)$ requires $O(D^2)$

Kernel Function



- $K(X,Y) = \phi(X_i). \phi(X_i)$
 - Idea is to compute RHS without expanding individual functions.

• Example:

$$K(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^{T} \mathbf{y} + 1)^{2}$$

$$= (x_{1}y_{1} + x_{2}y_{2} + 1)^{2}$$

$$= 1 + 2x_{1}y_{1} + 2x_{2}y_{2} + 2x_{1}x_{2}y_{1}y_{2} + x_{1}^{2}y_{1}^{2} + x_{2}^{2}y_{2}^{2} = \phi(\mathbf{X}). \ \phi(\mathbf{Y})$$

$$\phi(\mathbf{x}) = \begin{bmatrix} 1, \sqrt{2}x_{1}, \sqrt{2}x_{2}, \sqrt{2}x_{1}x_{2}, x_{1}^{2}, x_{2}^{2} \end{bmatrix}^{T}$$





Preprocess input **x** by basis functions

$$z = \varphi(x)$$
 $g(z) = w^T z$ $g(x) = w^T \varphi(x)$

The SVM solution

$$\mathbf{w} = \sum_{t} \alpha^{t} r^{t} \mathbf{z}^{t} = \sum_{t} \alpha^{t} r^{t} \boldsymbol{\varphi}(\mathbf{x}^{t})$$

$$g(\mathbf{x}) = \mathbf{w}^{T} \boldsymbol{\varphi}(\mathbf{x}) = \sum_{t} \alpha^{t} r^{t} \boldsymbol{\varphi}(\mathbf{x}^{t})^{T} \boldsymbol{\varphi}(\mathbf{x})$$

$$g(\mathbf{x}) = \sum_{t} \alpha^{t} r^{t} \mathcal{K}(\mathbf{x}^{t}, \mathbf{x})$$





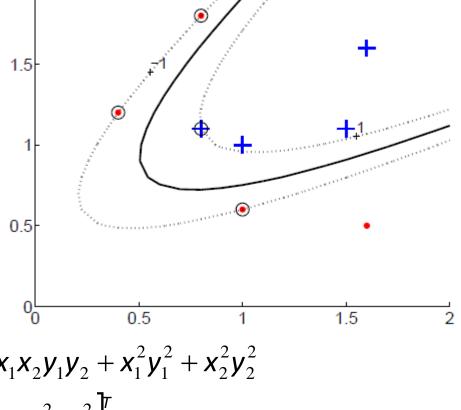
Polynomials of degree q:

$$K(\mathbf{x}^t, \mathbf{x}) = (\mathbf{x}^T \mathbf{x}^t + 1)^q$$

$$K(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^{\mathsf{T}} \mathbf{y} + 1)^{2}$$
$$= (\mathbf{x}_{1} \mathbf{y}_{1} + \mathbf{x}_{2} \mathbf{y}_{2} + 1)^{2}$$

$$= 1 + 2x_1y_1 + 2x_2y_2 + 2x_1x_2y_1y_2 + x_1^2y_1^2 + x_2^2y_2^2$$

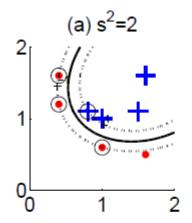
$$\phi(\mathbf{x}) = \left[1, \sqrt{2}x_1, \sqrt{2}x_2, \sqrt{2}x_1x_2, x_1^2, x_2^2\right]^T$$

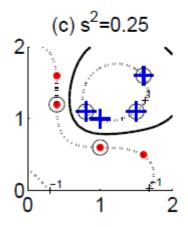


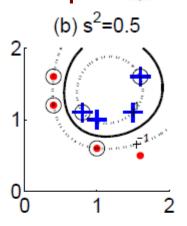
Vectorial Kernels: Popular Kernals 2,

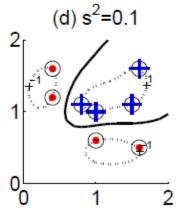


$$K(\mathbf{x}^t, \mathbf{x}) = \exp \left[-\frac{\|\mathbf{x}^t - \mathbf{x}\|^2}{2s^2} \right]$$











Defining kernels

Kernel "engineering"

Defining good measures of similarity

 Depending on representation of data, there are String kernels, graph kernels, image kernels, etc...

Examples: common words between two documents



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Replacing a single kernel with multiple kernel

Fixed kernel combination
$$K(\mathbf{x}, \mathbf{y}) = \begin{cases} cK(\mathbf{x}, \mathbf{y}) \\ K_1(\mathbf{x}, \mathbf{y}) + K_2(\mathbf{x}, \mathbf{y}) \\ K_1(\mathbf{x}, \mathbf{y})K_2(\mathbf{x}, \mathbf{y}) \end{cases}$$

Adaptive kernel combination $K(\mathbf{x}, \mathbf{y}) = \sum_{i=1}^{m} \eta_i K_i(\mathbf{x}, \mathbf{y})$ $L_d = \sum_t \alpha^t - \frac{1}{2} \sum_t \sum_s \alpha^t \alpha^s r^t r^s \sum_i \eta_i K_i(\mathbf{x}^t, \mathbf{x}^s)$ $g(\mathbf{x}) = \sum_t \alpha^t r^t \sum_i \eta_i K_i(\mathbf{x}^t, \mathbf{x})$

Localized kernel combination $g(\mathbf{x}) = \sum_{t} \alpha^{t} r^{t} \sum_{i} \eta_{i}(\mathbf{x} \mid \theta) \kappa_{i}(\mathbf{x}^{t}, \mathbf{x})$