Some Problems that can be solved using graphs

1. Suppose you run a day care for an office building and there are seven children A, B, C, D, E, F. we need to assign a locker where each child's parent can put the child's food. The children come and leave so they are not all there at the same time. You have 1 hour time slots starting7:00 a.m. to 9:00 am. A star in the table means a child is present at that time. What is the minimum 9:00 anumber of lockers necessary? Show how you would assign the lockers

	A	В	С	D	E	F
7:00	*	-	*	-	*	
8:00	-	*	*	-	-	-
9:00	-	-	-	*	*	*

2. We want to schedule a training programs with following training modules for employees:

A,B,C,D,E,F,G,H

Following pairs of training modules have no common employee:

A-B,B-C,A-D,A-E,B-E,E-F,A-F,B-F,D-F, A-G,A-H,B-H,C-H How many minimum training slots are needed?

3. Map coloring:

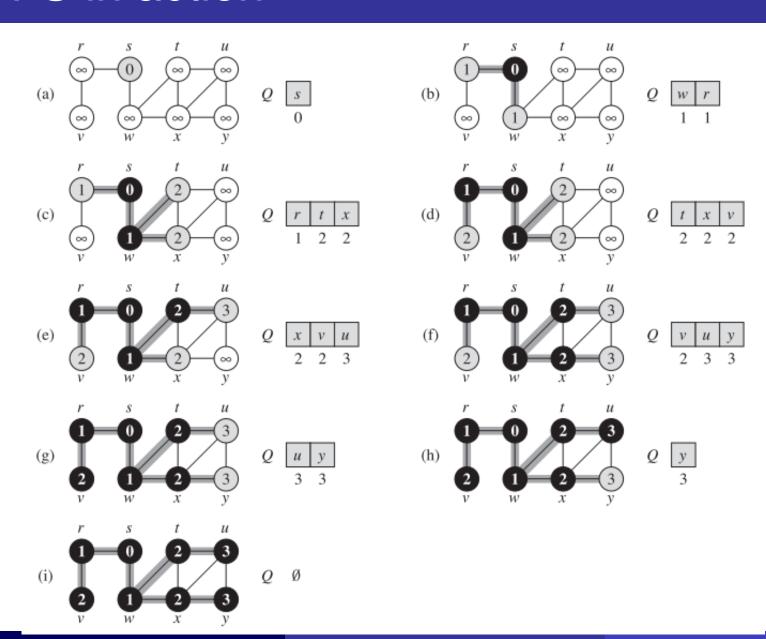
Color the states so that no two adjacent states have same color. What is the minimum number of colors to be used?



Graph Algorithms: Breadth First Search

```
BFS(V, E, s)
for each u \in V - \{s\}
     do d[u] \leftarrow \infty
                                    Complexity = O(|V| + |E|)
d[s] \leftarrow 0
Q \leftarrow \emptyset
ENQUEUE(Q, s)
while Q \neq \emptyset
     do u \leftarrow \text{DEQUEUE}(Q)
         for each v \in Adj[u]
               do if d[v] = \infty
                      then d[v] \leftarrow d[u] + 1
                             ENQUEUE(Q, v)
```

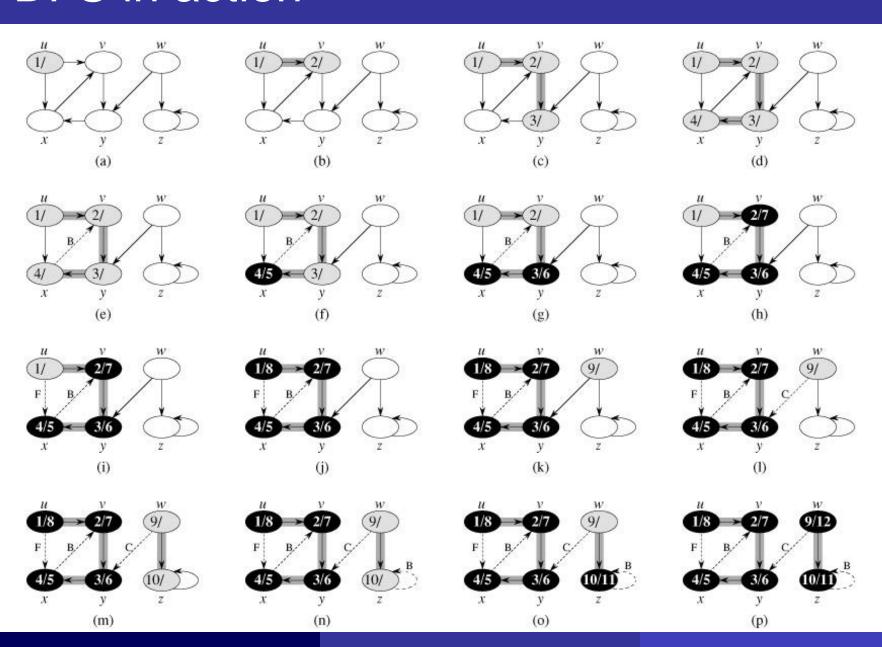
BFS in action



Graph Algorithms: Depth First Search

```
DFS(V, E)
for each u \in V
     do color[u] \leftarrow WHITE
time \leftarrow 0
for each u \in V
                                              Complexity
     do if color[u] = WHITE
                                              = (|V| + |E|)
           then DFS-VISIT(u)
DFS-VISIT(u)
color[u] \leftarrow GRAY \qquad \triangleright discover u
time \leftarrow time + 1
d[u] \leftarrow time
for each v \in Adj[u] \triangleright explore (u, v)
     do if color[v] = WHITE
           then DFS-VISIT(v)
color[u] \leftarrow BLACK
time \leftarrow time + 1
f[u] \leftarrow time
                              \triangleright finish u
```

DFS in action



Graph Algorithms: Kruskal's MST

G = (V, E) is a connected, undirected, weighted graph. $w : E \to \mathbf{R}$.

- Starts with each vertex being its own component.
- Repeatedly merges two components into one by choosing the light edge that connects them (i.e., the light edge crossing the cut between them).
- Scans the set of edges in monotonically increasing order by weight.
- Uses a disjoint-set data structure to determine whether an edge connects vertices in different components.

Graph Algorithms: Kruskal's MST (pseudoC)

```
MST-KRUSKAL(G, w)
   A = \emptyset
   for each vertex v \in G.V
       MAKE-SET(v)
                                                                         MAKE-SET(x)
   sort the edges of G.E into nondecreasing order by weight w
                                                                            x \cdot p = x
   for each edge (u, v) \in G.E, taken in nondecreasing order by weight
                                                                         2 \quad x.rank = 0
       if FIND-SET(u) \neq FIND-SET(v)
           A = A \cup \{(u, v)\}
                                                                         UNION(x, y)
           Union(u, v)
                                                                            LINK(FIND-SET(x), FIND-SET(y))
   return A
                                                                         Link(x, y)
                                                                            if x.rank > y.rank
                                                                                y.p = x
 Time complexity = O(m \log n)
                                                                         3 else x.p = y
 |v| = n, |E| = m
                                                                                if x.rank == v.rank
                                                                                     y.rank = y.rank + 1
                                                                         FIND-SET(x)
                                                                         1 if x \neq x.p
                                                                                x.p = \text{FIND-SET}(x.p)
                                                                         3 return x.p
```

See Chapter 21 in the book for Union and Find-Set operations

Graph Algorithms: Prim's MST

- Builds one tree, so A is always a tree.
- Starts from an arbitrary "root" r.
- At each step, find a light edge crossing cut $(V_A, V V_A)$, where V_A = vertices that A is incident on. Add this edge to A.

Graph Algorithms: Prim's MST (pseudoC)

```
PRIM(G, w, r)
             Q = \emptyset
             for each u \in G.V
                 u.key = \infty
                 u.\pi = NIL
                 INSERT(Q, u)
             DECREASE-KEY(Q, r, 0) // r.key = 0
             while Q \neq \emptyset
                 u = \text{EXTRACT-MIN}(Q)
                 for each v \in G.Adj[u]
                      if v \in Q and w(u, v) < v.key
                          \nu.\pi = u
                          DECREASE-KEY(Q, v, w(u, v))
Time Complexity (using binary Min-Heap):
                       O(|E|\log|V| + |V|\log|V|)
```

Single Source Shortest Path

```
INIT-SINGLE-SOURCE (V, s)
for each v \in V
     do d[v] \leftarrow \infty
         \pi[v] \leftarrow \text{NIL}
d[s] \leftarrow 0
   Relax(u, v, w)
   if d[v] > d[u] + w(u, v)
      then d[v] \leftarrow d[u] + w(u, v)
             \pi[v] \leftarrow u
```

Single Source Shortest Path: Bellman-Ford

Core: The first for loop relaxes all edges |V| - 1 times

```
Bellman-Ford(V, E, w, s)
INIT-SINGLE-SOURCE (V, s)
for i \leftarrow 1 to |V| - 1
    do for each edge (u, v) \in E
           do RELAX(u, v, w)
for each edge (u, v) \in E
    do if d[v] > d[u] + w(u, v)
         then return FALSE
return TRUE
```

Time: $\Theta(VE)$.

Single Source Shortest Path: Dijkstra

Not applicable to graph with –ve weights

```
DIJKSTRA(V, E, w, s)

INIT-SINGLE-SOURCE(V, s)
S \leftarrow \emptyset
Q \leftarrow V \triangleright i.e., insert all vertices into Q
while Q \neq \emptyset
do u \leftarrow \text{Extract-Min}(Q)
S \leftarrow S \cup \{u\}
for each vertex v \in Adj[u]
do Relax(u, v, w)
```

Dynamic Programming: Rod cutting

You are given a rod of length $n \ge 0$ (n in inches)

A rod of length i inches will be sold for p_i dollars

Cutting is free (simplifying assumption)

Problem: given a table of prices p_i determine the maximum revenue r_n obtainable by cutting up the rod and selling the pieces.

Length i	1	2	3	4	5	6	7	8	9	10
Price p_i	1	5	8	9	10	17	17	20	24	30

Dynamic Programming: Rod cutting

In ALL cases we have the recursion

$$r_n = \max(p_n, r_1 + r_{n-1}, r_2 + r_{n-2}, ..., r_{n-1} + r_1)$$

Without Dynamic Programming

CUT-ROD
$$(p, n)$$

1 if $n == 0$

2 return 0

3 $q = -\infty$

4 for $i = 1$ to n

5 $q = \max(q, p[i] + \text{CUT-ROD}(p, n - i))$

6 return q

1 0 0

The number of nodes for a tree corresponding to a rod of size n is:

$$T(0)=1$$
, $T(n)=1+\sum_{j=0}^{n-1}T(j)=2^n$, $n \ge 1$.

Dynamic Programming; Rod Cutting

With Dynamic Programming

```
MEMOIZED-CUT-ROD(p, n)
   let r[0..n] be a new array
  for i = 0 to n
       r[i] = -\infty
   return MEMOIZED-CUT-ROD-AUX(p, n, r)
MEMOIZED-CUT-ROD-AUX(p, n, r)
   if r[n] \geq 0
       return r[n]
   if n == 0
       q = 0
   else q = -\infty
6
       for i = 1 to n
            q = \max(q, p[i] + \text{MEMOIZED-CUT-ROD-AUX}(p, n - i, r))
   r[n] = q
   return q
```

Dynamic Programming: Matrix Multiplication

```
MATRIX-CHAIN (p)
LOOKUP-CHAIN(m, p, i, j)
                                          1 \quad n = p.length - 1
                                          2 let m[1...n, 1...n] be a new table
   if m[i,j] < \infty
                                          3 for i = 1 to n
       return m[i, j]
                                                  for j = i to n
   if i == j
                                                      m[i,j] = \infty
       m[i,j] = 0
                                             return LOOKUP-CHAIN(m, p, 1,
   else for k = i to j - 1
            q = \text{LOOKUP-CHAIN}(m, p, i, k)
                 + LOOKUP-CHAIN(m, p, k + 1, j) + p_{i-1}p_kp_j
            if q < m[i, j]
                m[i,j] = q
   return m[i, j]
```

	1	5	3	8	5	6
	0	15.750	1.8%	9.375	11.83	5.6
		0	3.6%	*33%	3.13	10.50
<i>n</i>)	45		0	30	2.500	5.37
,,		3		0	1.00	3.50
			A.	1 ₃₀ 0	0	5.00
				3		0
				1	40	
		2	3	8	5	6

3

3

3

3

5

5

matrix		A_2	-		A_5	A_6
dimension	30×35	35×15	15 × 5	5 × 10	10 × 20	20 × 25

S warming sold	$m[2,2] + m[3,5] + p_1 p_2 p_5$	=	$0 + 2500 + 35 \cdot 15 \cdot 20$	=	13,000,
$m[2,5] = \min$	$\begin{cases} m[2,2] + m[3,5] + p_1 p_2 p_5 \\ m[2,3] + m[4,5] + p_1 p_3 p_5 \\ m[2,4] + m[5,5] + p_1 p_4 p_5 \end{cases}$	=	$2625 + 1000 + 35 \cdot 5 \cdot 20$	=	7125,
	$m[2,4] + m[5,5] + p_1 p_4 p_5$	=	$4375 + 0 + 35 \cdot 10 \cdot 20$	=	11,375
= 712	5.				

Matrix Multiplication: Bottom up, iterative

```
MATRIX-CHAIN-ORDER (p)
     n \leftarrow length[p] - 1
     for i \leftarrow 1 to n
           do m[i,i] \leftarrow 0
     for l \leftarrow 2 to n > l is the chain length.
           do for i \leftarrow 1 to n-l+1
                    do j \leftarrow i + l - 1
                        m[i, j] \leftarrow \infty
 8
                        for k \leftarrow i to j-1
 9
                              do q \leftarrow m[i, k] + m[k + 1, j] + p_{i-1}p_kp_j
                                  if q < m[i, j]
10
11
                                    then m[i, j] \leftarrow q
12
                                           s[i, j] \leftarrow k
13
     return m and s
```

Dynamic Programming: LCS

```
LCS-LENGTH(X, Y)
    m = X.length
 2 n = Y.length
    let b[1..m, 1..n] and c[0..m, 0..n] be new tables
    for i = 1 to m
         c[i,0] = 0
    for j = 0 to n
         c[0,j] = 0
    for i = 1 to m
 9
         for j = 1 to n
             if x_i == y_i
10
                  c[i, j] = c[i - 1, j - 1] + 1
11
                  b[i, j] = "\\\"
12
             elseif c[i - 1, j] \ge c[i, j - 1]
13
                  c[i, j] = c[i - 1, j]
14
15
                  b[i,j] = "\uparrow"
             else c[i, j] = c[i, j-1]
16
                  b[i,j] = "\leftarrow"
17
18
     return c and b
```

```
PRINT-LCS(b, X, i, j)

1 if i == 0 or j == 0

return

3 if b[i, j] == \text{``\cdot'}

PRINT-LCS(b, X, i - 1, j - 1)

print x_i

elseif b[i, j] == \text{``\cdot'}

PRINT-LCS(b, X, i - 1, j - 1)

else PRINT-LCS(b, X, i - 1, j)

else PRINT-LCS(b, X, i - 1, j)
```

Approximation Algorithm: Subset Sum

Algorithm 1: Exact-Subset-Sum(S, t)

```
1 n \leftarrow |S|

2 L_0 \leftarrow \langle 0 \rangle

3 for i = 1 to n do

4 L_i \leftarrow MergeLists(L_{i-1}, L_{i-1} + x_i)

5 remove from L_i every element greater than t

6 return the largest element in L_n
```

Approximation Algorithm

The solution returned is within a factor of $1 + \epsilon$ of the optimal solution.

The running time is polynomial in both n and $1/\epsilon$

Algorithm 2: $TRIM(L, \delta)$

Algorithm 3: Approx-Subset-Sum (S, t, ϵ)

7 return the largest element in L_n

```
\begin{array}{l} 1 \quad n \longleftarrow |S| \\ 2 \quad L_0 \longleftarrow \langle 0 \rangle \\ 3 \quad \text{for i} = 1 \text{ to n do} \\ 4 \quad \left[ \begin{array}{c} L_i \longleftarrow MergeLists(L_{i-1}, L_{i-1} + x_i) \\ L_i \longleftarrow Trim(L_i, \epsilon/2n) \\ \end{array} \right] \\ 6 \quad \left[ \begin{array}{c} \text{remove from } L_i \text{ every element greater than } t; \end{array} \right] \end{array}
```

Approximation Algorithm: Setcover

```
GREEDY-SET-COVER(X, \mathcal{F})

1 U \leftarrow X

2 \mathcal{C} \leftarrow \emptyset

3 while U \neq \emptyset

4 do select an S \in \mathcal{F} that maximizes |S \cap U|

5 U \leftarrow U - S

6 \mathcal{C} \leftarrow \mathcal{C} \cup \{S\}

7 return \mathcal{C}
```

Note: TSP is also covered in the class, in addition we discussed, P,NP, NP complete and NP hard, cook Levin theorem, and idea of reduction