This folder contains GPS data (time and position) for the camera. This data was collected from a stationary GPS device next to the camera and is separate from boat data in “main\_boat\_position”. It’s intended to make the boat gps data and camera visual data comparable in time.

GPS pings only came in about every 5 seconds, so the “estimated\_time” column uses the average camera FPS to estimate the actual time by interpolating. The resolution is 1 second.