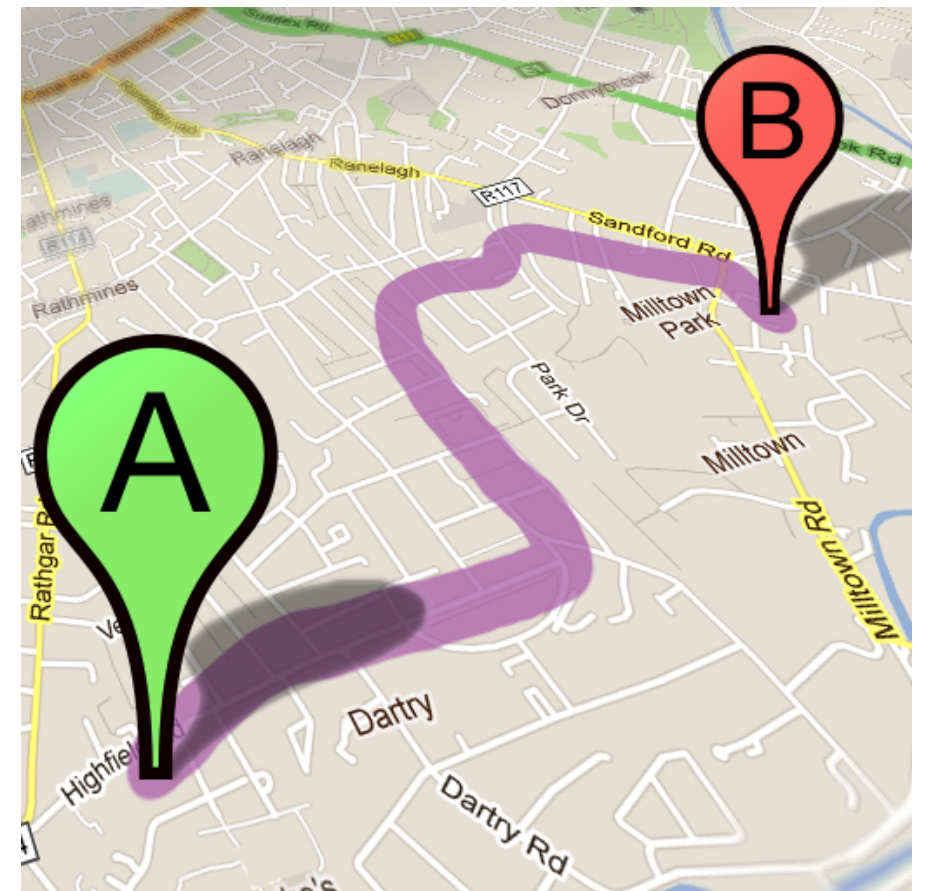


# Data Structures in Java

## Lecture 18: Unweighted Shortest Paths

11/18/2019

Daniel Bauer



Start address e.g., "SFO"

End address e.g., "94526"

seattle

sydney

Get Directions

[Search the map](#)
[Find businesses](#)
[Get directions](#)

- Search Results

My Maps
3.

Merge onto **I-5 N** via the ramp on the **left** to **Vancouver BC**

1.0 mi
4.

Take exit **167** on the **left** toward **Seattle Center**

0.7 mi
5.

Turn **right** at **Fairview Ave N**

400 ft
6.

Turn **left** at **Valley St**

0.2 mi
7.

Turn **right** at **Westlake Ave N**

1.6 mi
8.

Turn **right** at **4th Ave N**

0.3 mi
9.

Turn **right** at **N 34th St**

0.3 mi
10.

Turn **right** at **Stone Way N**

115 ft
11.

Turn **left** at **N Northlake Way**

0.3 mi
12.

Kayak across the **Pacific Ocean**  
Entering Australia (New South Wales)

7,906 mi
13.

Sharp **right** at **Macquarie St**

0.4 mi
14.

Turn **right** at **Albert St**

292 ft
15.

Turn **left** at **Phillip St**

0.1 mi
16.

Turn **right** at **Bridge St**

0.3 mi
17.

Turn **left** at **George St**

0.2 mi
- To:

Sydney NSW Australia

Edit

[Add destination ...](#)

km

miles

These directions are for planning purposes only. You may find that

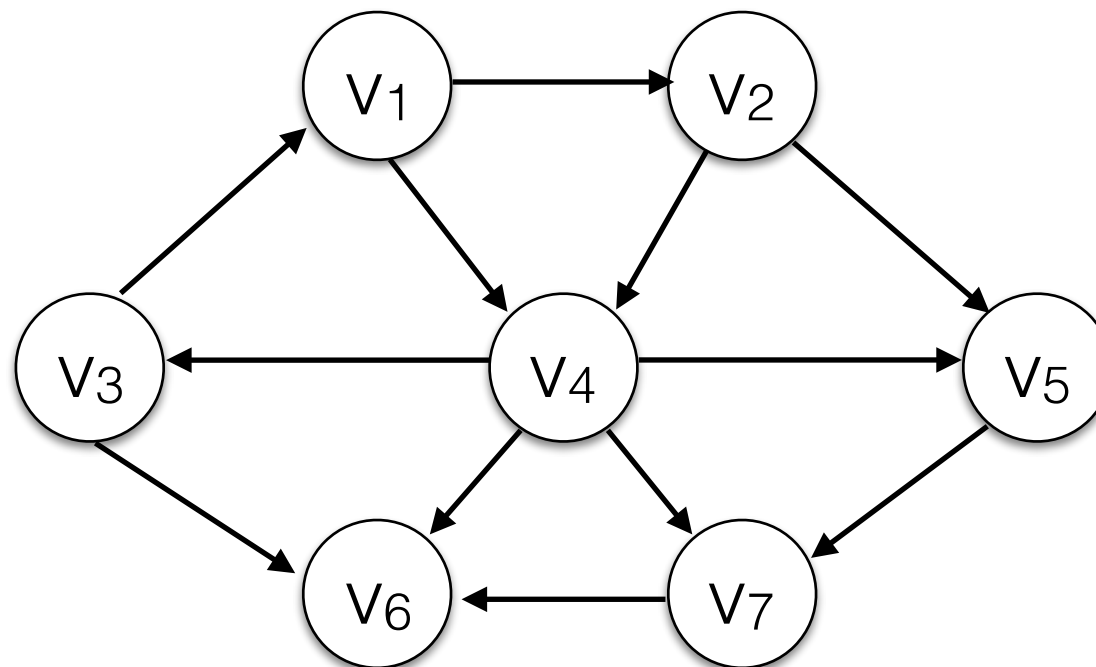


# Graph Traversals

- Different ways of exploring graphs:
  - Topological sort for Directed Acyclic Graphs.
  - Depth First Search (a generalization of pre-order traversal on trees to graphs, uses a Stack)
  - Breadth First Search (uses a Queue)
  - Dijkstra's algorithm to find weighted shortest paths (uses a Priority Queue)

# Finding Shortest Paths

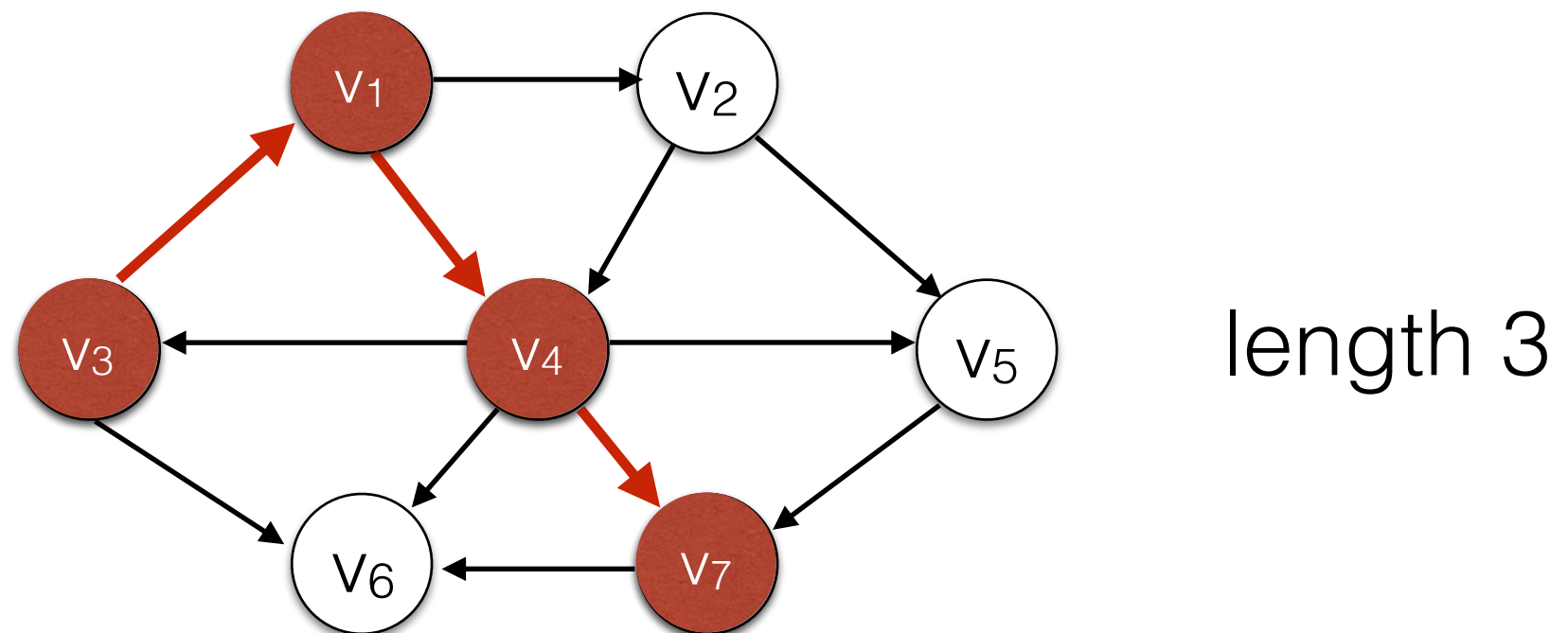
- Goal: Find the shortest path between two vertices  $s$  and  $t$ .



What is the shortest path between  $v_3$  and  $v_7$ ?

# Finding Shortest Paths

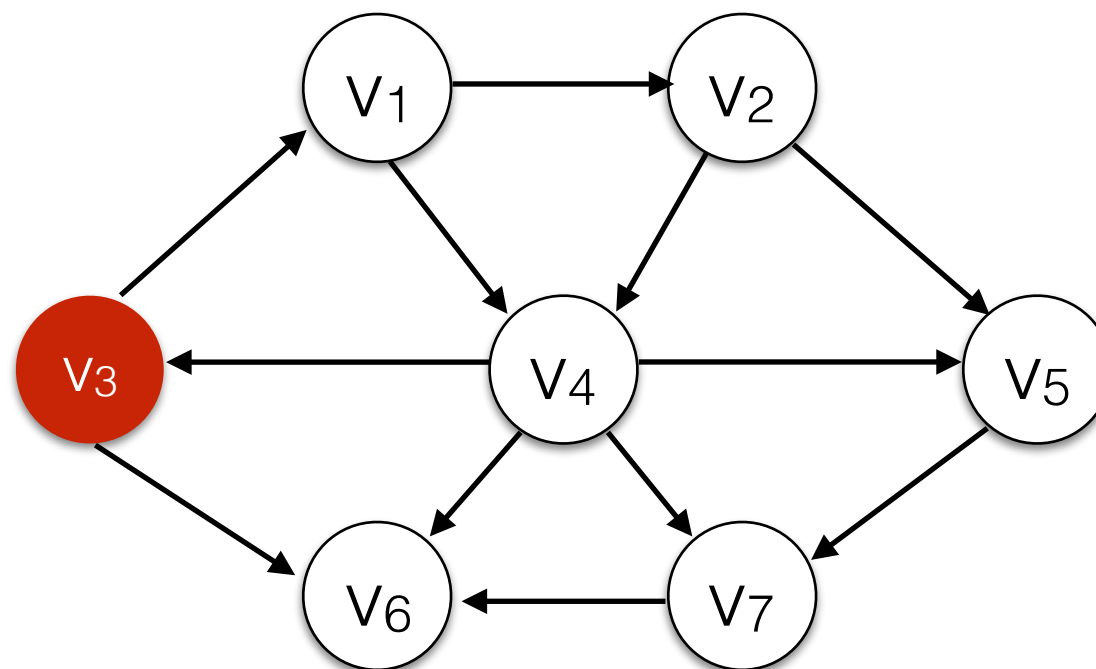
- Goal: Find the shortest path between two vertices  $s$  and  $t$ .



What is the shortest path between  $v_3$  and  $v_7$ ?

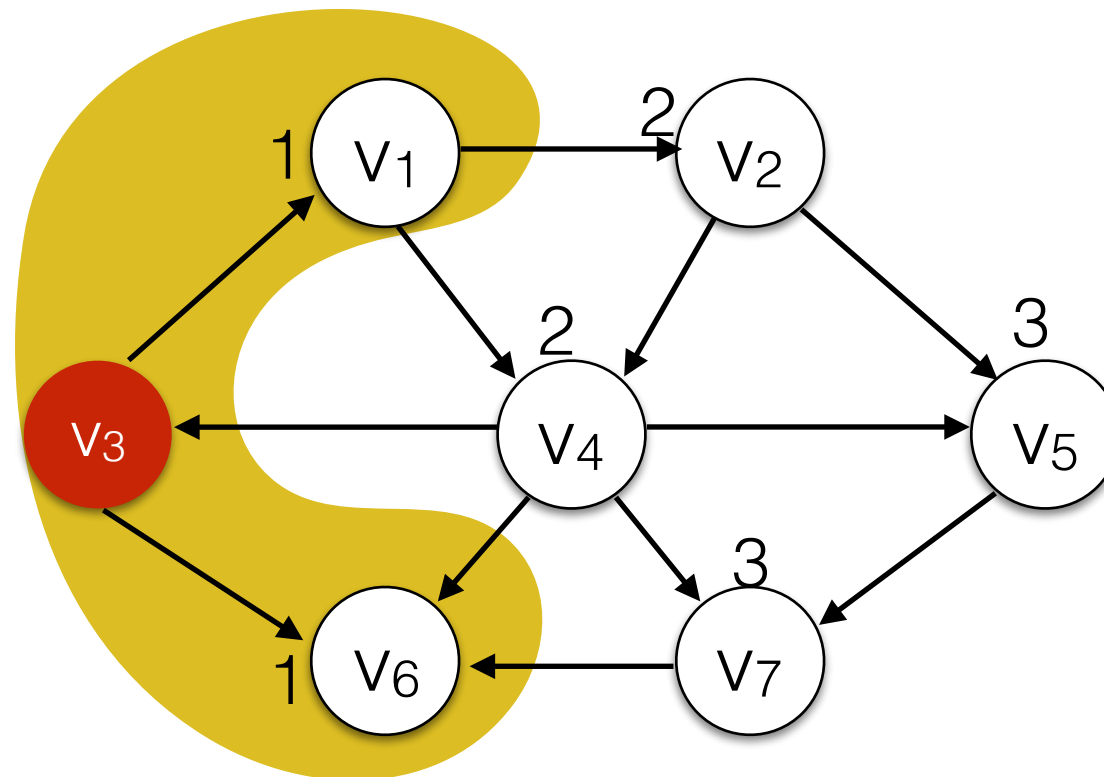
# Finding Shortest Paths

- Goal: Find the shortest path between two vertices  $s$  and  $t$ .
- It turns out that finding the shortest path between  $s$  and ALL other vertices is just as easy. This problem is called **single-source shortest paths**.



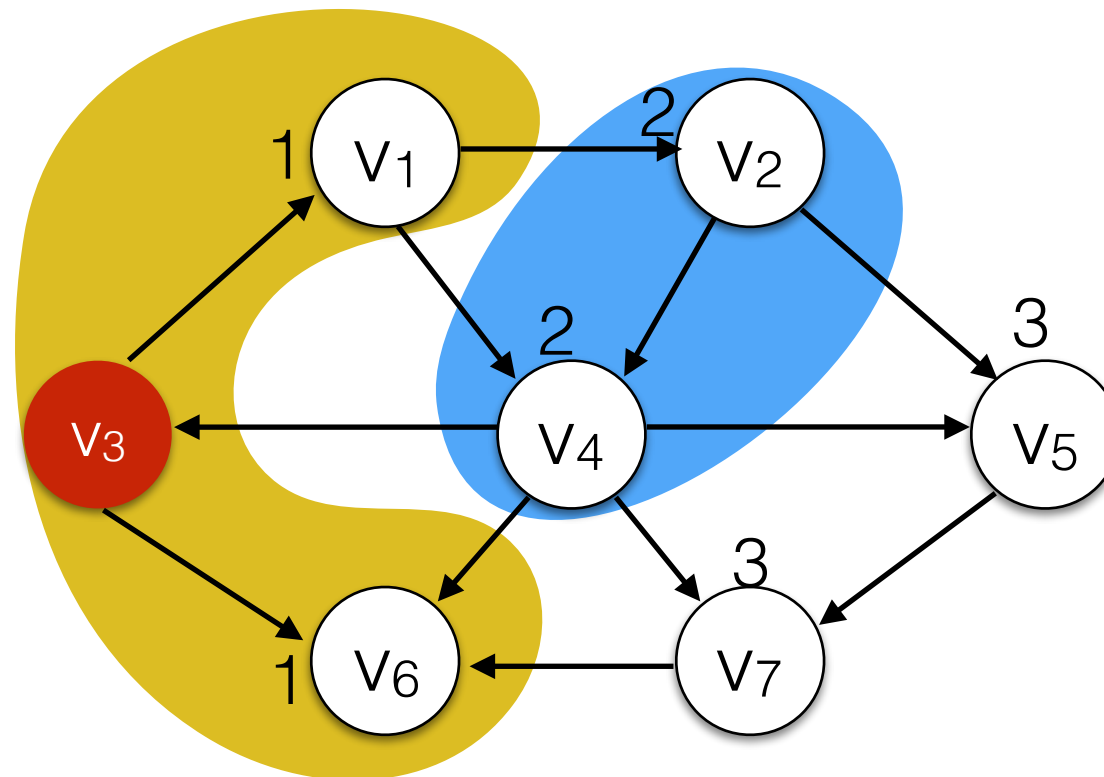
# Finding Shortest Paths

- Goal: Find the shortest path between two vertices  $s$  and  $t$ .
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# Finding Shortest Paths

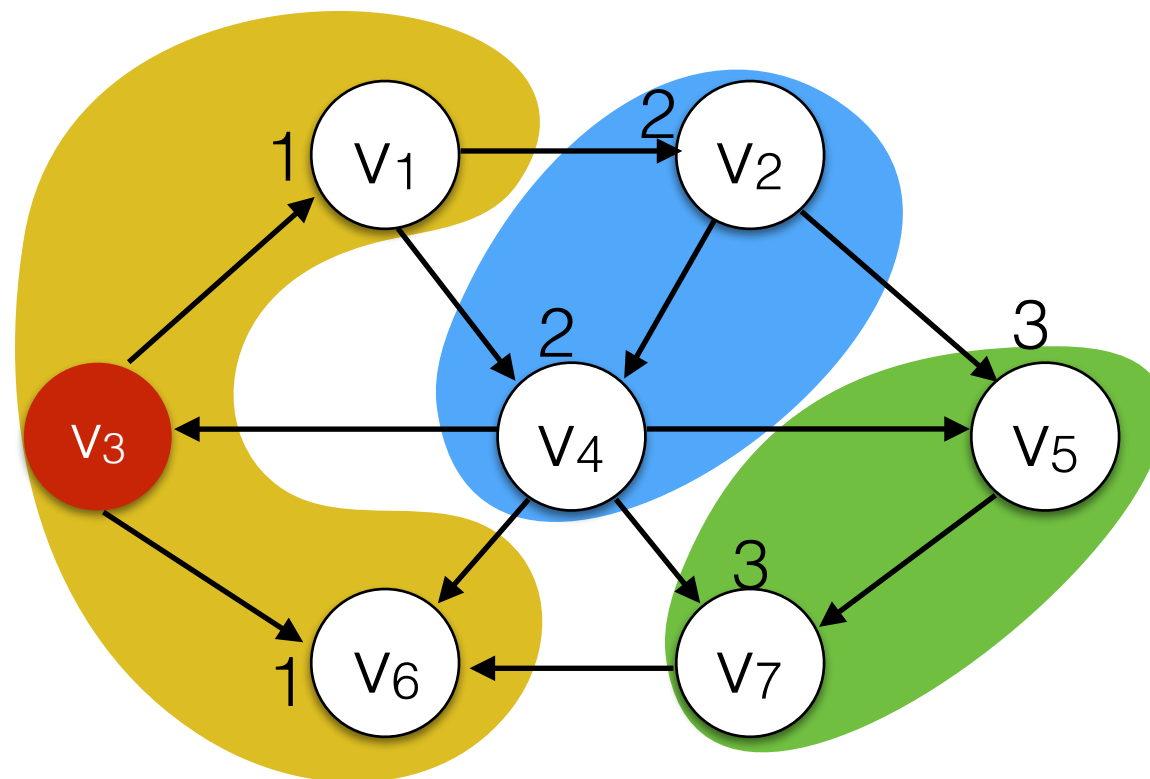
- Goal: Find the shortest path between two vertices  $s$  and  $t$ .
- It turns out that finding the shortest path between  $s$  and ALL other vertices is just as easy. This problem is called **single-source shortest paths**.



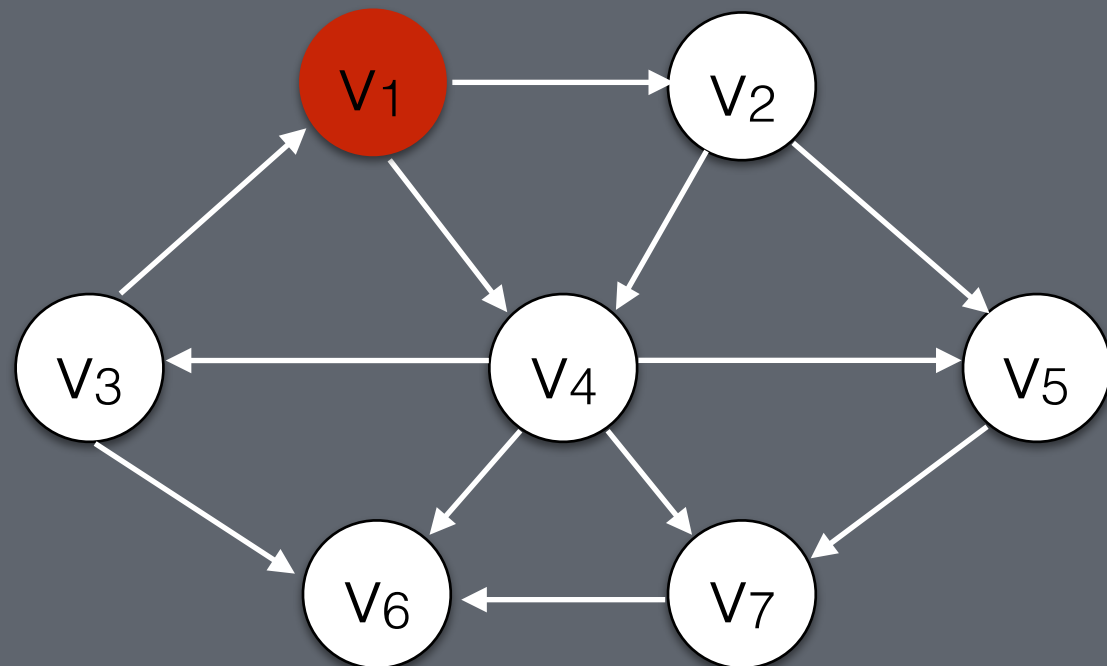


# Finding Shortest Paths

- Goal: Find the shortest path between two vertices  $s$  and  $t$ .
- It turns out that finding the shortest path between  $s$  and ALL other vertices is just as easy. This problem is called **single-source shortest paths**.



# Breadth First Search



Queue: { V<sub>1</sub> }

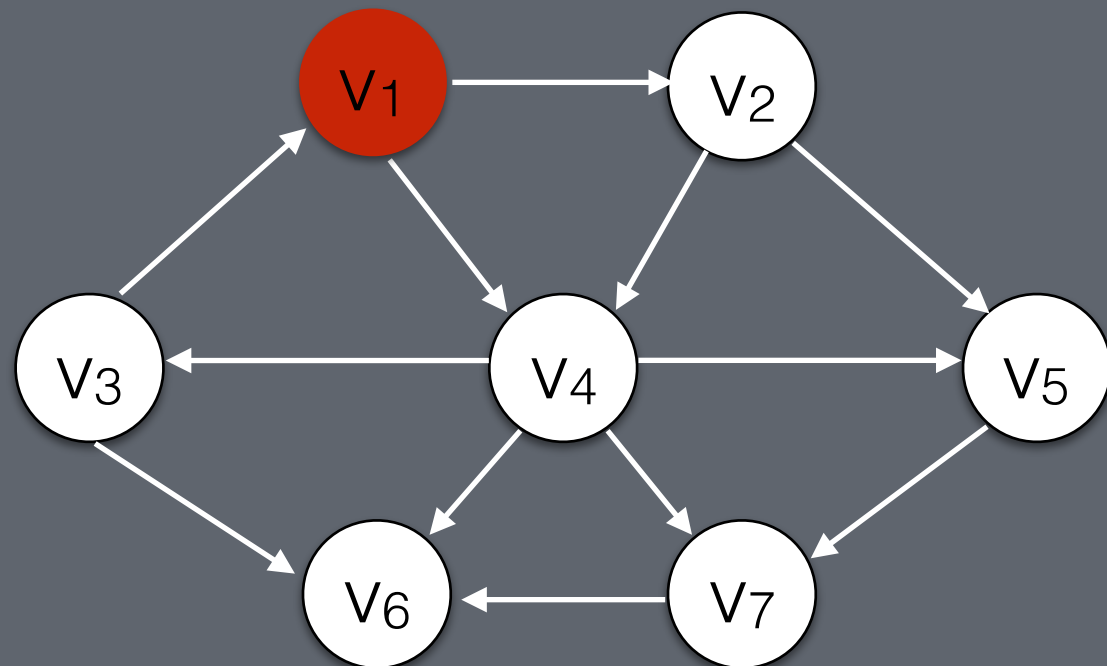
```
Queue q
q.enqueue(start)

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        q.enqueue(v)

        visited.add(v)
```

# Breadth First Search



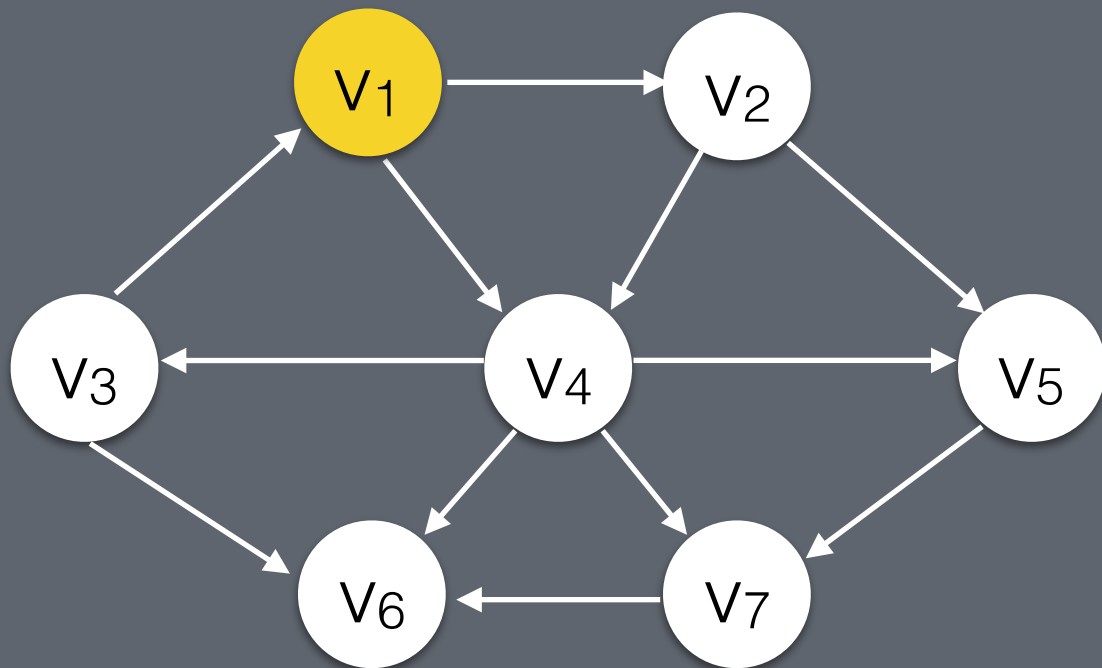
Queue: { V<sub>1</sub> }

```
Queue q
q.enqueue(start)
Set visited

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if (v is not in visited):
            q.enqueue(v)
        visited.add(v)
```

# Breadth First Search



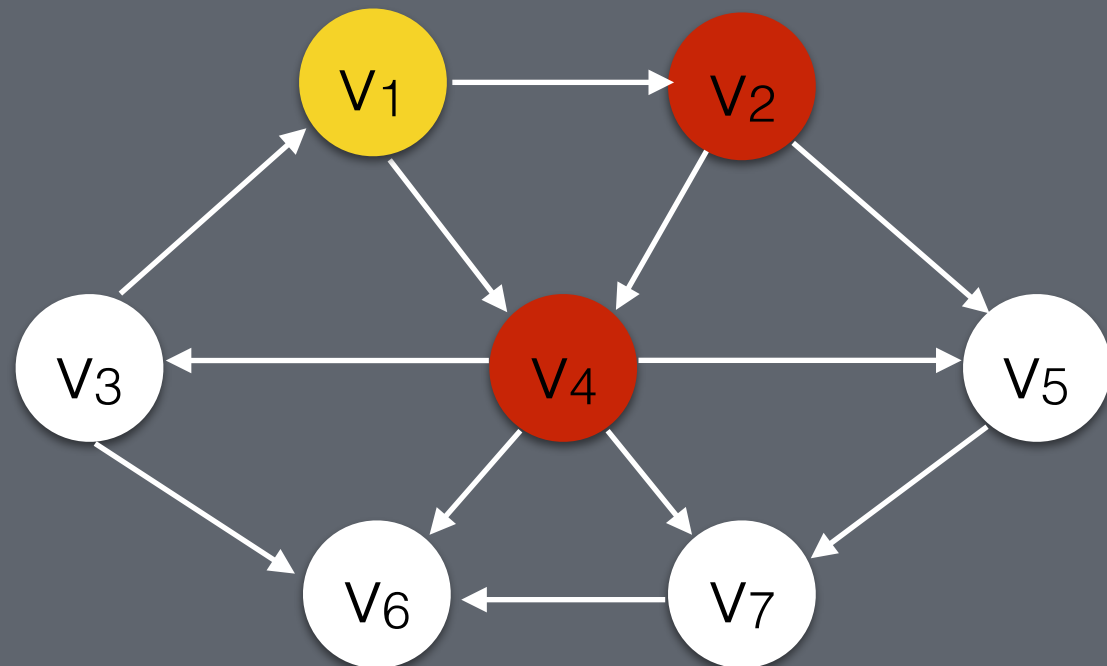
Queue: {}

```
Queue q
q.enqueue(start)
Set visited

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if (v is not in visited):
            q.enqueue(v)
```

# Breadth First Search



Queue: { V<sub>2</sub>, V<sub>4</sub> }

```
Queue q
```

```
q.enqueue(start)
```

```
Set visited
```

```
while (q is not empty):
```

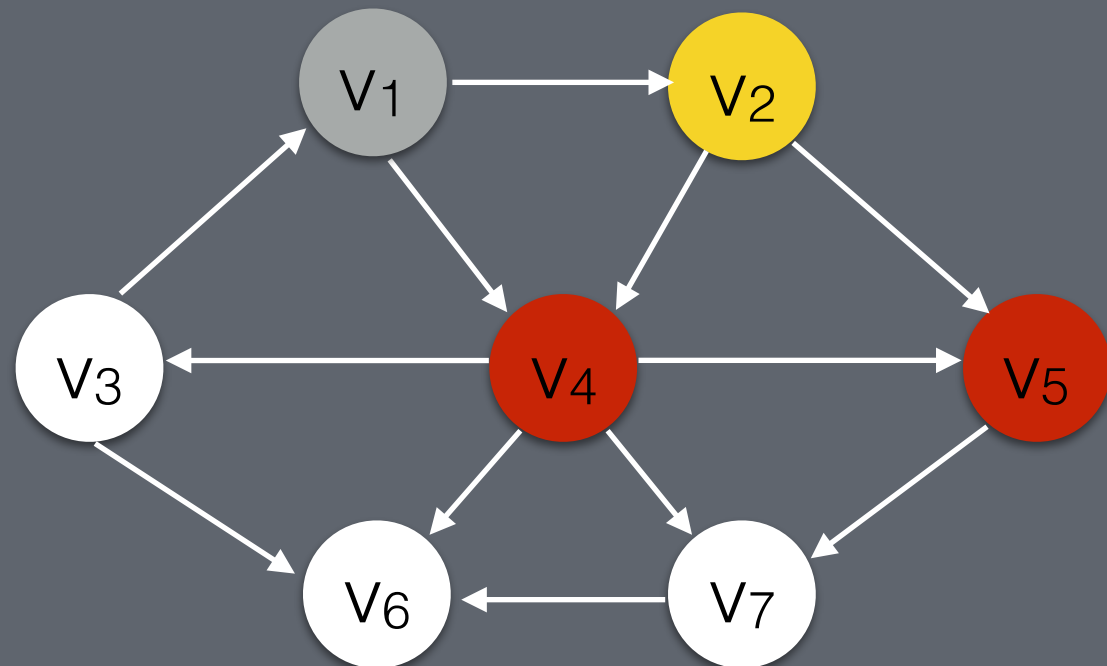
```
    u = q.dequeue()
```

```
    for each v adjacent to u:
```

```
        if (v is not in visited):
```

```
            q.enqueue(v)
```

# Breadth First Search



Queue: { V<sub>4</sub>, V<sub>5</sub> }

```
Queue q
```

```
q.enqueue(start)
```

```
Set visited
```

```
while (q is not empty):
```

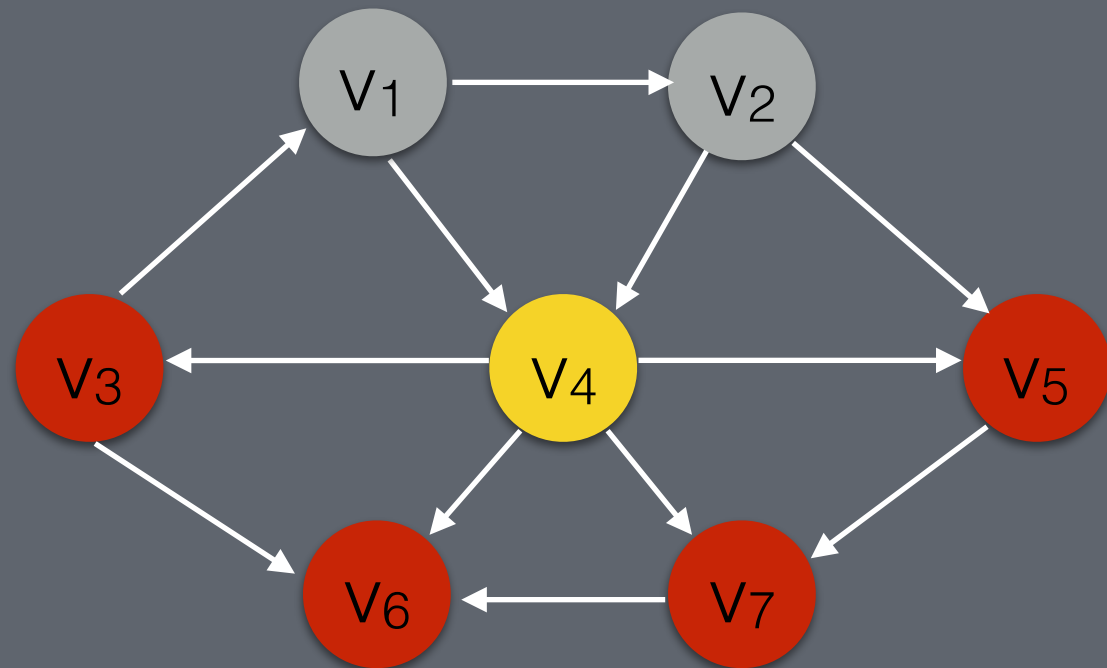
```
    u = q.dequeue()
```

```
    for each v adjacent to u:
```

```
        if (v is not in visited):
```

```
            q.enqueue(v)
```

# Breadth First Search



Queue:  $\{V_5, V_3, V_6, V_7\}$

```
Queue q
```

```
q.enqueue(start)
```

```
Set visited
```

```
while (q is not empty):
```

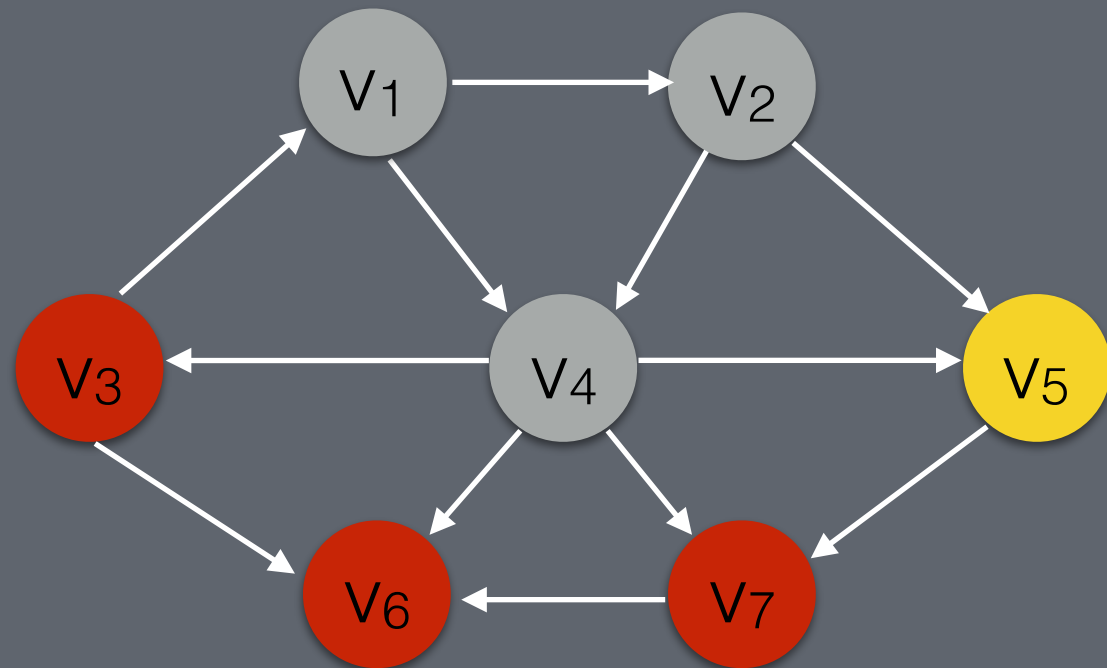
```
    u = q.dequeue()
```

```
    for each v adjacent to u:
```

```
        if (v is not in visited):
```

```
            q.enqueue(v)
```

# Breadth First Search



Queue:  $\{V_3, V_6, V_7\}$

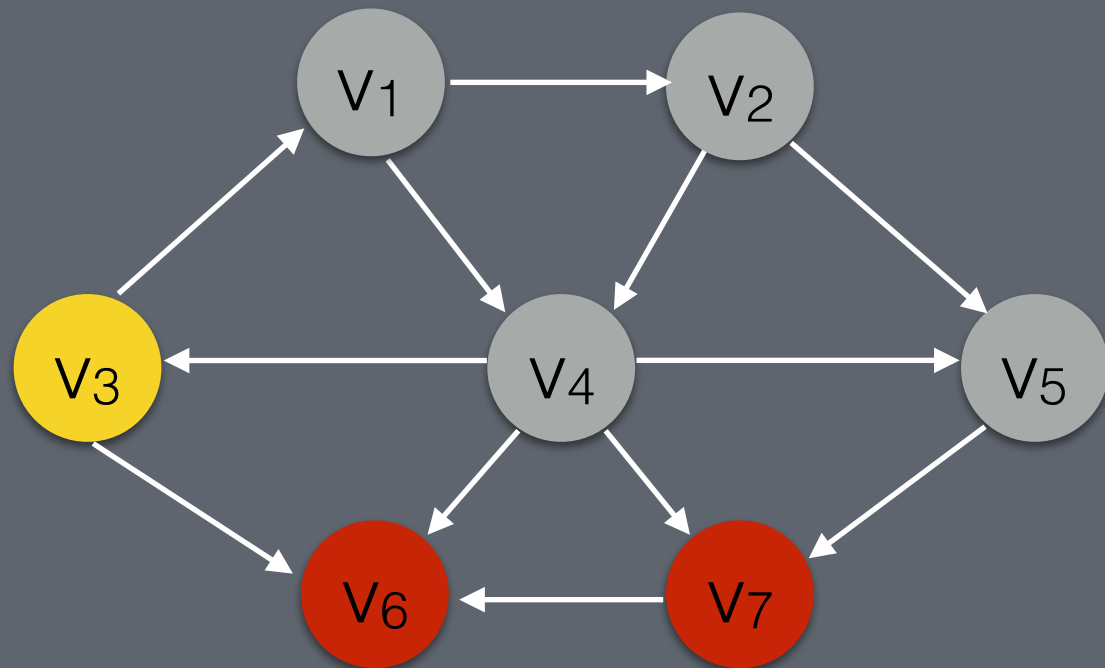
```
Queue q
q.enqueue(start)
Set visited

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if (v is not in visited):
            q.enqueue(v)
```



# Breadth First Search



Queue:  $\{V_6, V_7\}$

```
Queue q
```

```
q.enqueue(start)
```

```
Set visited
```

```
while (q is not empty):
```

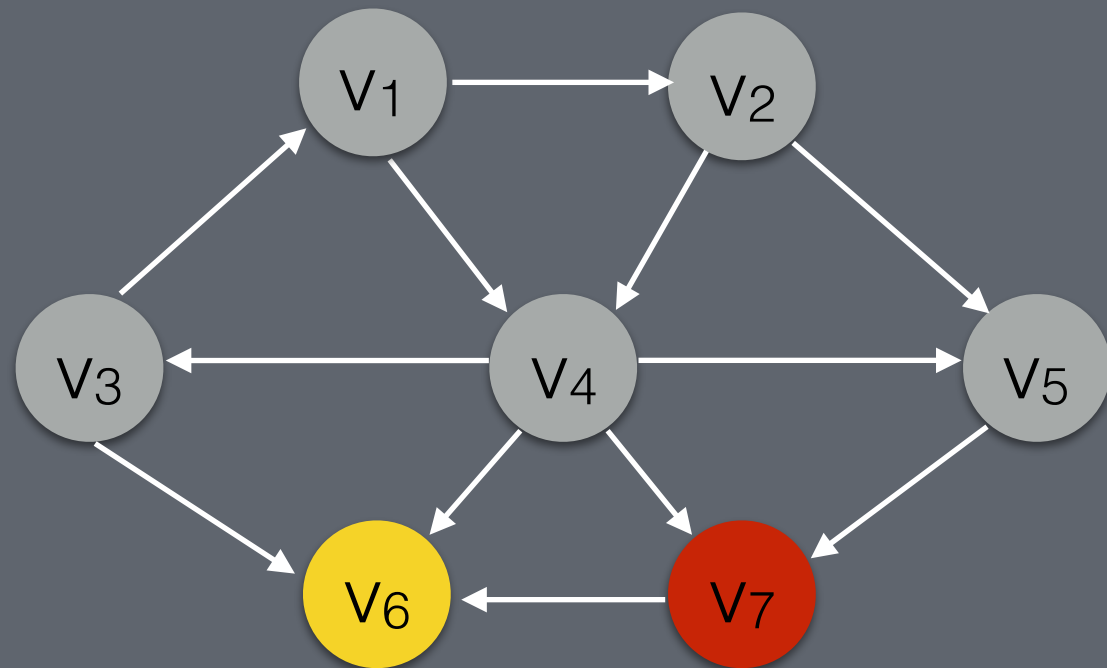
```
    u = q.dequeue()
```

```
    for each v adjacent to u:
```

```
        if (v is not in visited):
```

```
            q.enqueue(v)
```

# Breadth First Search



Queue: {V<sub>7</sub>}

```
Queue q
```

```
q.enqueue(start)
```

```
Set visited
```

```
while (q is not empty):
```

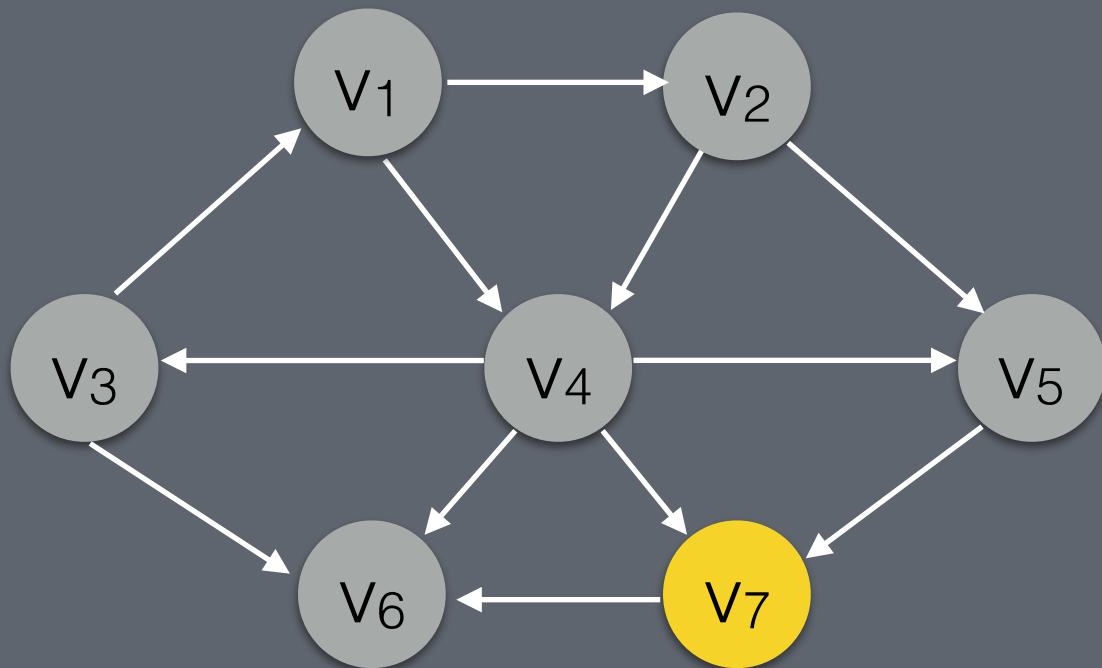
```
    u = q.dequeue()
```

```
    for each v adjacent to u:
```

```
        if (v is not in visited):
```

```
            q.enqueue(v)
```

# Breadth First Search



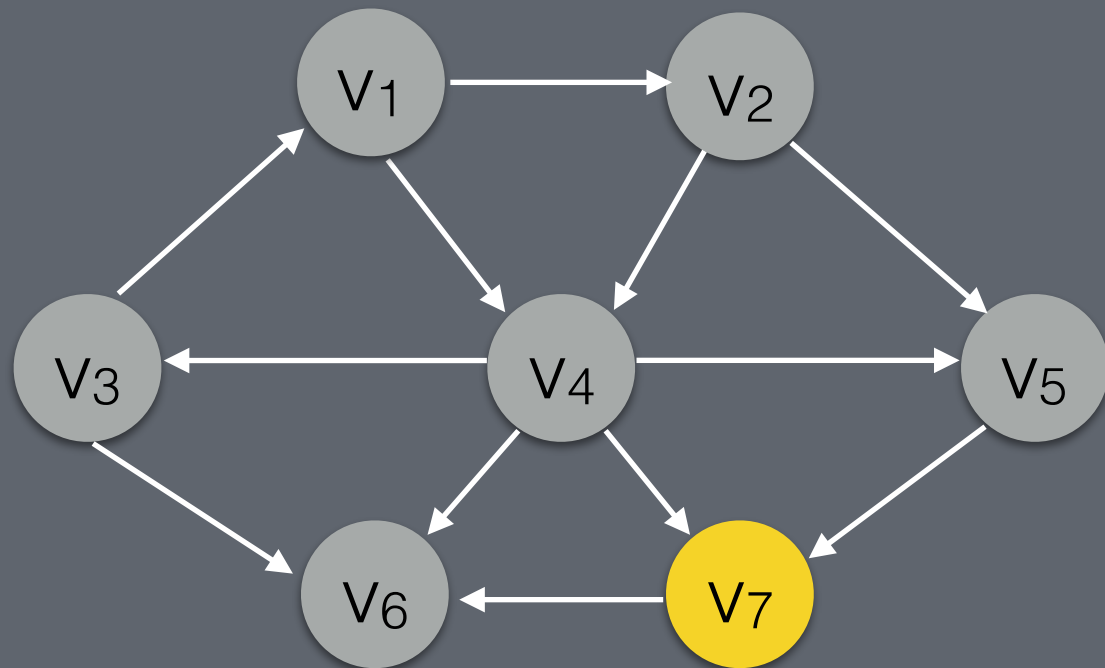
Queue: {}

```
Queue q
q.enqueue(start)
Set visited

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if (v is not in visited):
            q.enqueue(v)
```

# Breadth First Search



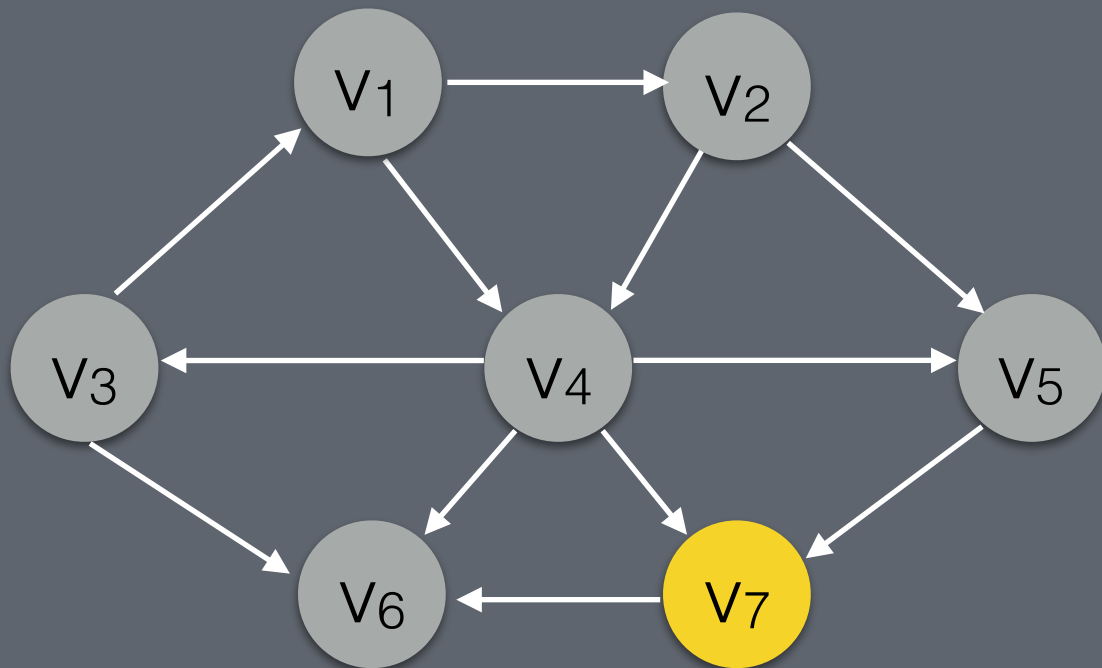
```
Queue q
q.enqueue(start)
Set visited

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if (v is not in visited):
            q.enqueue(v)
```

Running time:  $O(|V|+|E|)$

# Breadth First Search



```
Queue q  
q.enqueue(start)  
Set visited
```

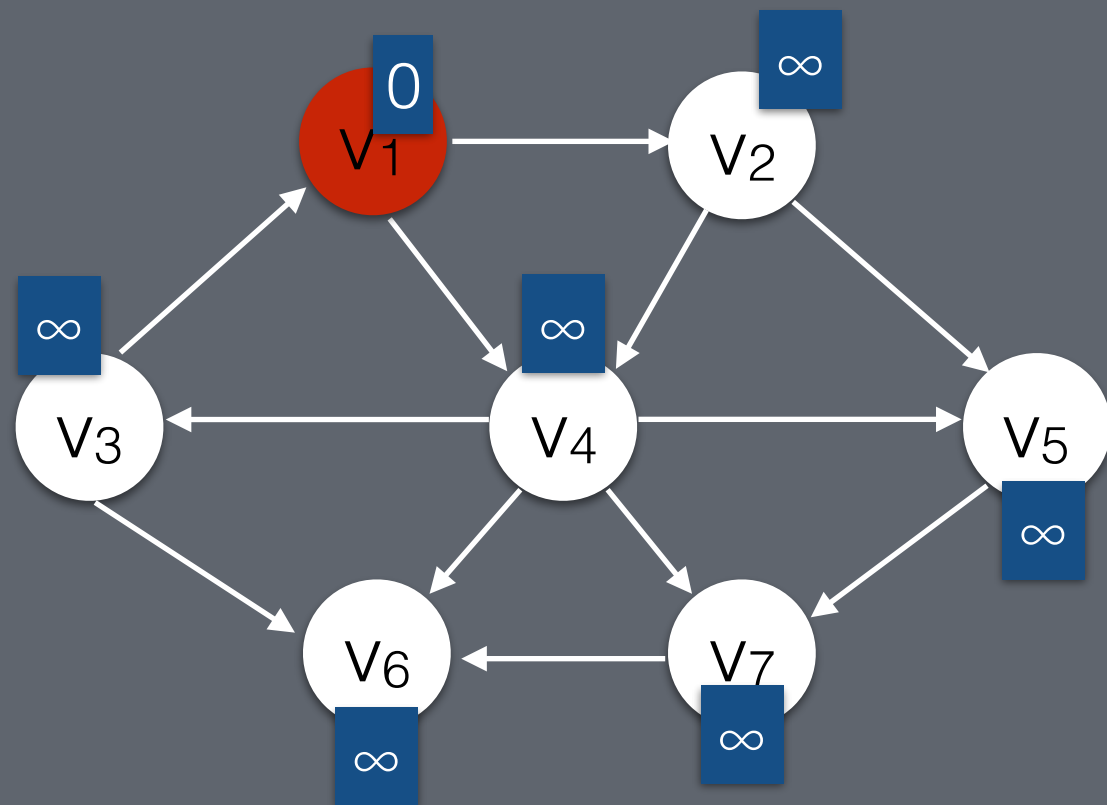
```
while (q is not empty):  
    u = q.dequeue()
```

BFS will traverse the entire graph even without a visited set.

Running time:  $O(|V|+|E|)$

What happens if we use a stack (DFS)?

# Unweighted Shortest Paths

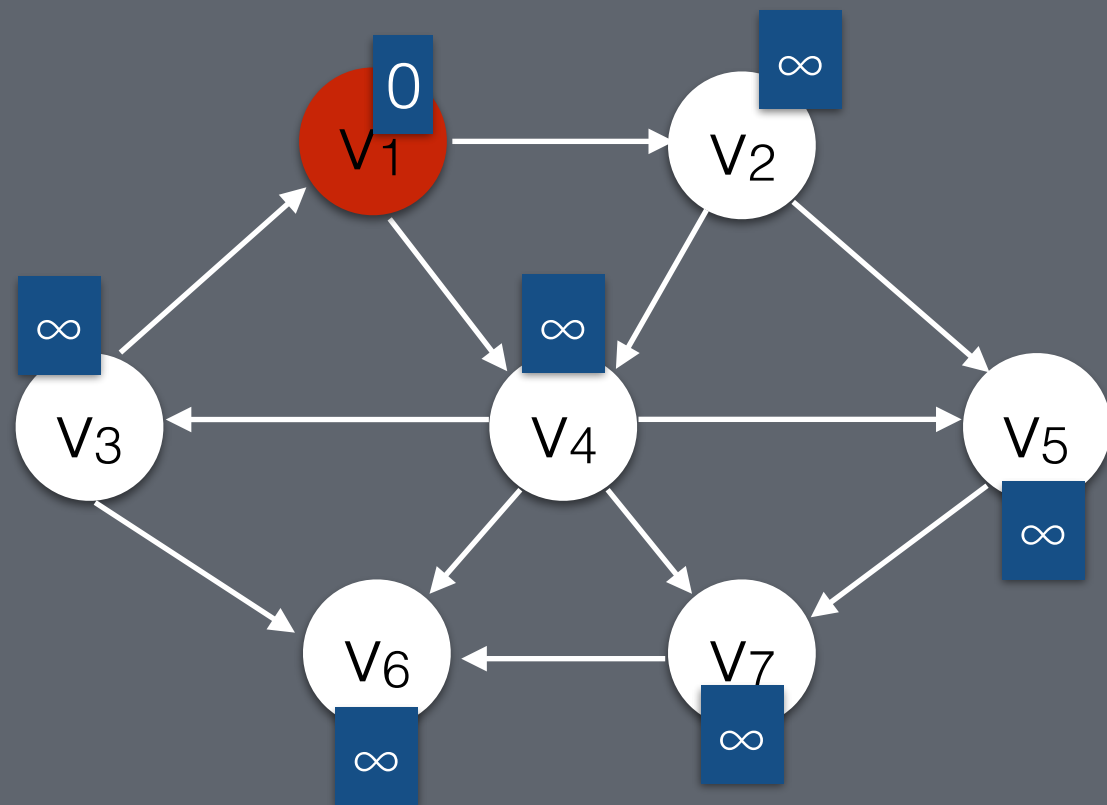


Queue:  $\{V_1\}$

```
for all v:  
    v.cost =  $\infty$   
    v.prev = null
```

```
start.cost = 0
```

# Unweighted Shortest Paths



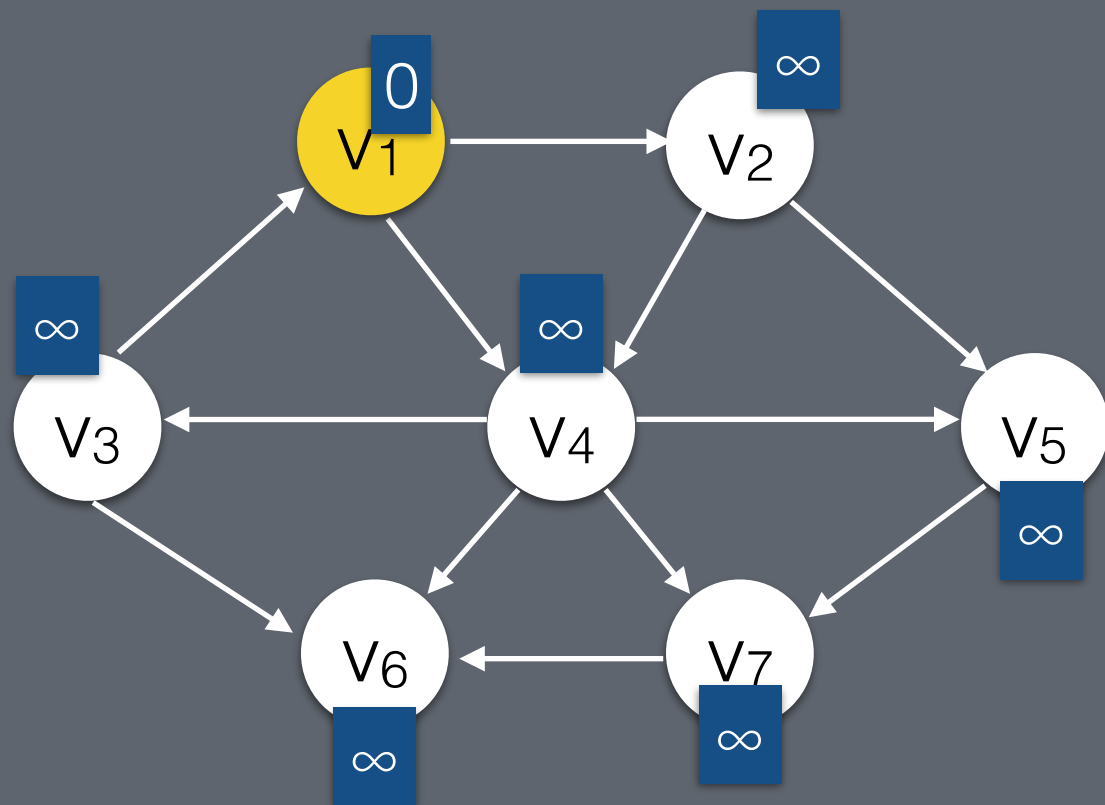
Queue: { V<sub>1</sub> }

```
for all v:  
    v.cost =  $\infty$   
    v.prev = null
```

```
start.cost = 0
```

```
Queue q  
q.enqueue(start)
```

# Unweighted Shortest Paths



Queue: {}

```
for all v:
    v.cost =  $\infty$ 
    v.prev = null

start.cost = 0

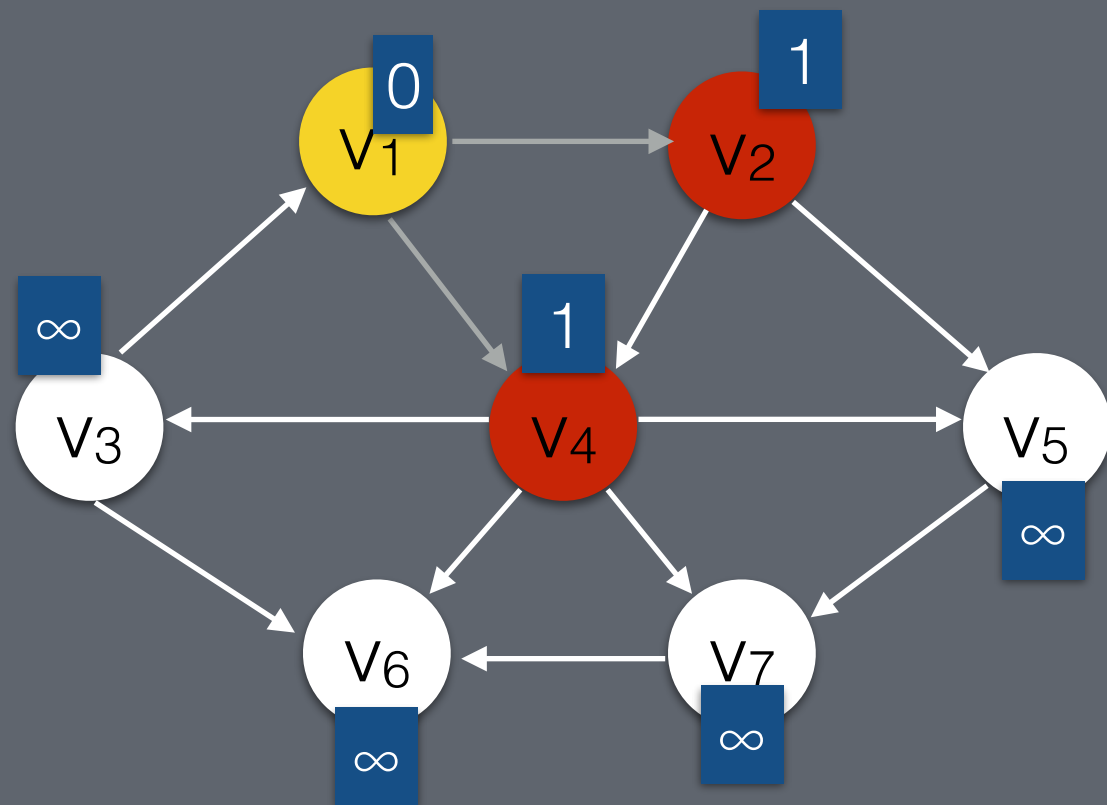
Queue q
q.enqueue(start)

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if v.cost ==  $\infty$ :
            v.cost = u.cost + 1
            v.prev = u
            q.enqueue(v)
```



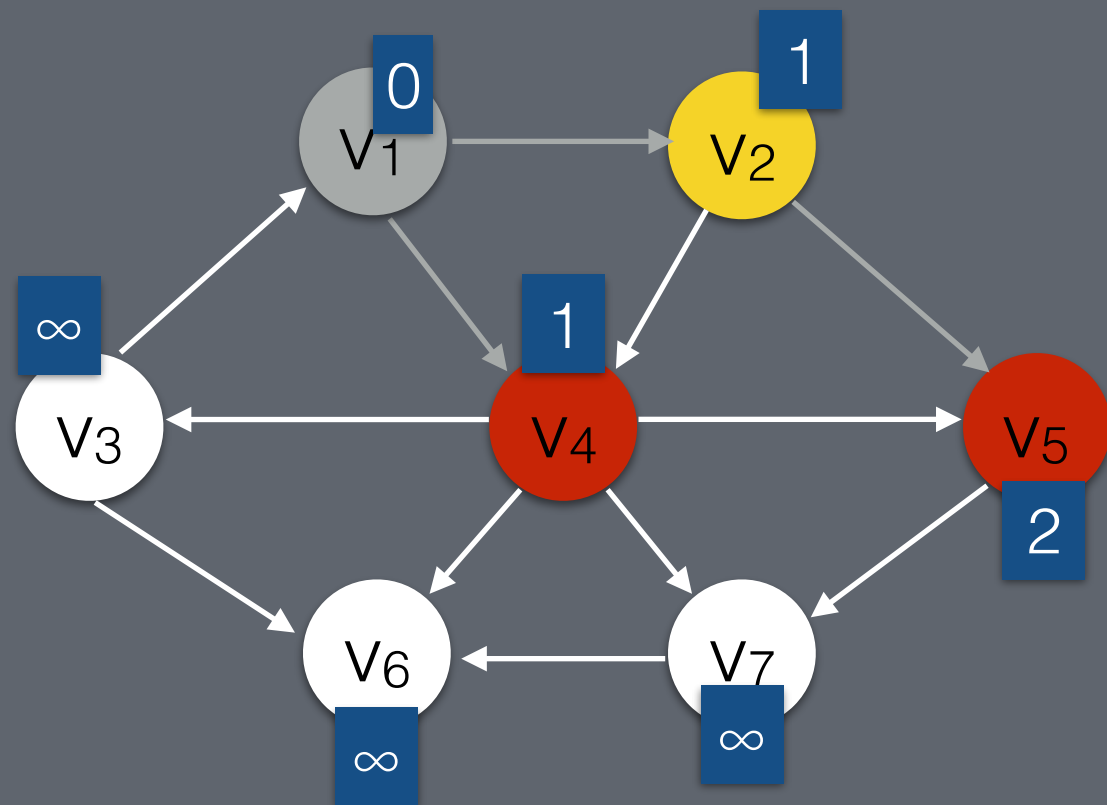
# Unweighted Shortest Paths



Queue: { V<sub>2</sub>, V<sub>4</sub> }

```
for all v:  
    v.cost =  $\infty$   
    v.prev = null  
  
start.cost = 0  
  
Queue q  
q.enqueue(start)  
  
while (q is not empty):  
    u = q.dequeue()  
  
    for each v adjacent to u:  
        if v.cost ==  $\infty$ :  
            v.cost = u.cost + 1  
            v.prev = u  
            q.enqueue(v)
```

# Unweighted Shortest Paths



Queue: { V<sub>4</sub>, V<sub>5</sub> }

```
for all v:
    v.cost = ∞
    v.prev = null

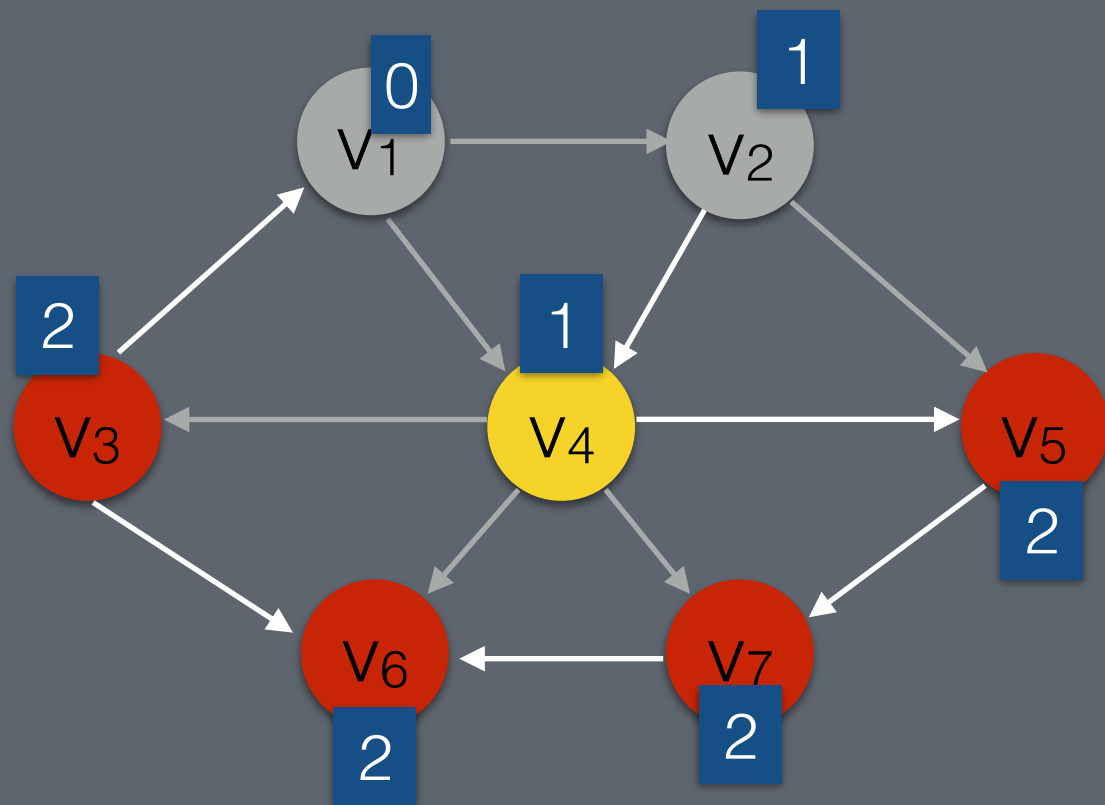
start.cost = 0

Queue q
q.enqueue(start)

while (q is not empty):
    u = q.dequeue()

    for each v adjacent to u:
        if v.cost == ∞:
            v.cost = u.cost + 1
            v.prev = u
            q.enqueue(v)
```

# Unweighted Shortest Paths

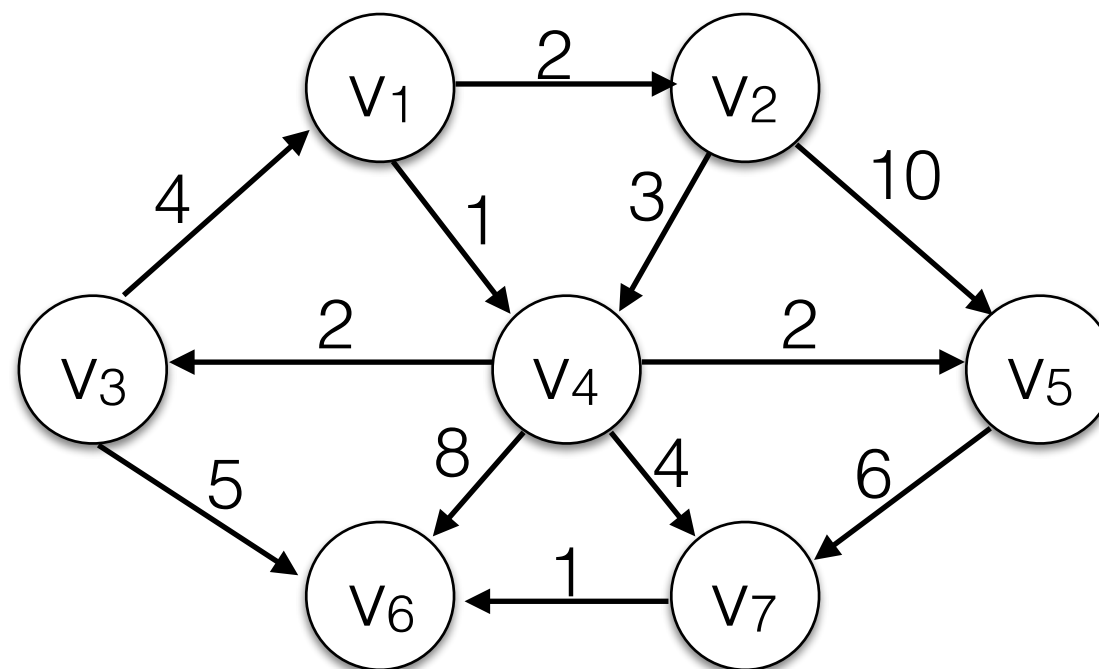


Queue: {V<sub>5</sub>, V<sub>3</sub>, V<sub>6</sub>, V<sub>7</sub>}

```
for all v:  
    v.cost = ∞  
    v.prev = null  
  
start.cost = 0  
  
Queue q  
q.enqueue(start)  
  
while (q is not empty):  
    u = q.dequeue()  
  
    for each v adjacent to u:  
        if v.cost == ∞:  
            v.cost = u.cost + 1  
            v.prev = u  
            q.enqueue(v)
```

# Weighted Shortest Paths

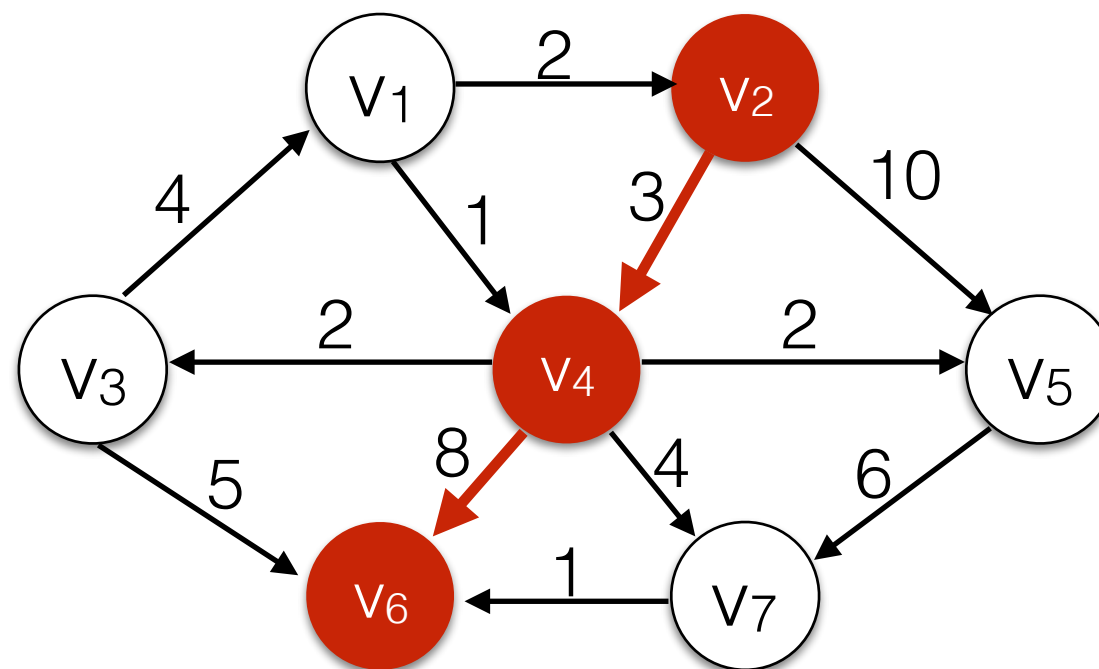
- Goal: Find the shortest path between two vertices  $s$  and  $t$ .



What is the shortest path between  $v_2$  and  $v_6$ ?

# Weighted Shortest Paths

- Goal: Find the shortest path between two vertices  $s$  and  $t$ .
- Normal BFS will find this path.

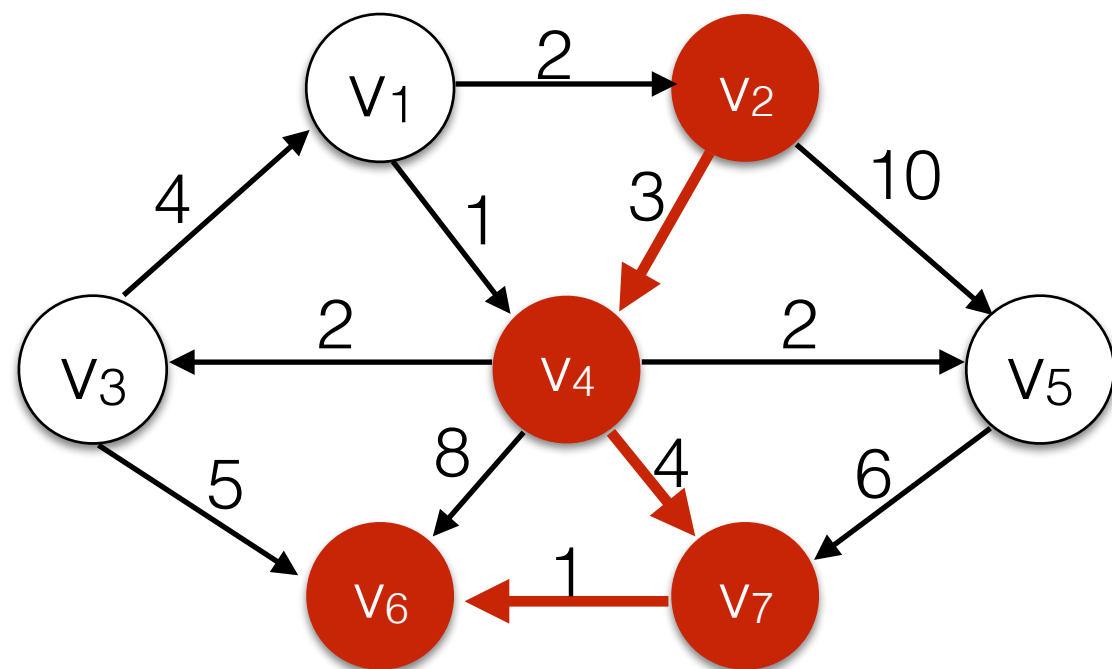


length 2  
cost 11

What is the shortest path between  $v_2$  and  $v_6$ ?

# Weighted Shortest Paths

- Goal: Find the shortest path between two vertices  $s$  and  $t$ .
- This path has a lower cost.



length 3  
cost 8

What is the shortest path between  $v_2$  and  $v_6$ ?