

Deep Neural Network module

Modules

[Partial List of Implemented Layers](#)

[Utilities for New Layers Registration](#)

Classes

class [cv::dnn::BackendNode](#)

Derivatives of this class encapsulates functions of certain backends. [More...](#)

class [cv::dnn::BackendWrapper](#)

Derivatives of this class wraps [cv::Mat](#) for different backends and targets. [More...](#)

class [cv::dnn::Dict](#)

This class implements name-value dictionary, values are instances of [DictValue](#). [More...](#)

struct [cv::dnn::DictValue](#)

This struct stores the scalar value (or array) of one of the following type: double, [cv::String](#) or int64. [More...](#)

class [cv::dnn::Importer](#)

Small interface class for loading trained serialized models of different dnn-frameworks. [More...](#)

class [cv::dnn::Layer](#)

This interface class allows to build new Layers - are building blocks of networks. [More...](#)

class [cv::dnn::LayerParams](#)

This class provides all data needed to initialize layer. [More...](#)

class [cv::dnn::Net](#)

This class allows to create and manipulate comprehensive artificial neural networks. [More...](#)

Typedefs

typedef std::vector< int > [cv::dnn::MatShape](#)

Enumerations

```
enum cv::dnn::Backend {
    cv::dnn::DNN_BACKEND_DEFAULT,
    cv::dnn::DNN_BACKEND_HALIDE
}
```

Enum of computation backends supported by layers. [More...](#)

```
enum cv::dnn::Target {
    cv::dnn::DNN_TARGET_CPU,
    cv::dnn::DNN_TARGET_OPENCL
}
```

Enum of target devices for computations. [More...](#)

Functions

Mat [cv::dnn::blobFromImage](#) (const **Mat** &image, double scaleFactor=1.0, const **Size** &size=**Size**(), const **Scalar** &mean=**Scalar**(), bool swapRB=true, bool crop=true)
Creates 4-dimensional blob from image. Optionally resizes and crops *image* from center, subtract mean values, scales values by scaleFactor, swap Blue and Red channels. [More...](#)

Mat [cv::dnn::blobFromImages](#) (const std::vector< **Mat** > &images, double scaleFactor=1.0, **Size** size=**Size**(), const **Scalar** &mean=**Scalar**(), bool swapRB=true, bool crop=true)
Creates 4-dimensional blob from series of images. Optionally resizes and crops *images* from center, subtract mean values, scales values by scaleFactor, swap Blue and Red channels. [More...](#)

Ptr< Importer > [cv::dnn::createCaffeImporter](#) (const **String** &prototxt, const **String** &caffeModel=**String**())
Creates the importer of [Caffe](#) framework network. [More...](#)

Ptr< Importer > [cv::dnn::createTensorflowImporter](#) (const **String** &model)
Creates the importer of [TensorFlow](#) framework network. [More...](#)

Ptr< Importer > [cv::dnn::createTorchImporter](#) (const **String** &filename, bool isBinary=true)
Creates the importer of [Torch7](#) framework network. [More...](#)

void [cv::dnn::NMSBoxes](#) (const std::vector< **Rect** > &bboxes, const std::vector< float > &scores, const float score_threshold, const float

nms_threshold, std::vector< int > &indices, const float eta=1.f, const int top_k=0)

Performs non maximum suppression given boxes and corresponding scores. [More...](#)

Net `cv::dnn::readNetFromCaffe` (const **String** &prototxt, const **String** &caffeModel=**String**())

Reads a network model stored in Caffe model files. [More...](#)

Net `cv::dnn::readNetFromCaffe` (const char *bufferProto, size_t lenProto, const char *bufferModel=NULL, size_t lenModel=0)

Reads a network model stored in Caffe model in memory. [More...](#)

Net `cv::dnn::readNetFromDarknet` (const **String** &cfgFile, const **String** &darknetModel=**String**())

Reads a network model stored in **Darknet** model files. [More...](#)

Net `cv::dnn::readNetFromTensorflow` (const **String** &model, const **String** &config=**String**())

Reads a network model stored in Tensorflow model file. [More...](#)

Net `cv::dnn::readNetFromTensorflow` (const char *bufferModel, size_t lenModel, const char *bufferConfig=NULL, size_t lenConfig=0)

Reads a network model stored in Tensorflow model in memory. [More...](#)

Net `cv::dnn::readNetFromTorch` (const **String** &model, bool isBinary=true)

Reads a network model stored in Torch model file. [More...](#)

Mat `cv::dnn::readTorchBlob` (const **String** &filename, bool isBinary=true)

Loads blob which was serialized as torch.Tensor object of Torch7 framework. [More...](#)

void `cv::dnn::shrinkCaffeModel` (const **String** &src, const **String** &dst, const std::vector< **String** > &layersTypes=std::vector< **String** >())

Convert all weights of Caffe network to half precision floating point. [More...](#)

Detailed Description

This module contains:

- API for new layers creation, layers are building bricks of neural networks;
- set of built-in most-useful Layers;
- API to construct and modify comprehensive neural networks from layers;
- functionality for loading serialized networks models from differnet frameworks.

Functionality of this module is designed only for forward pass computations (i. e. network testing). A network training is in principle not supported.

Typedef Documentation

§ MatShape

```
typedef std::vector<int> cv::dnn::MatShape
```

Enumeration Type Documentation

§ Backend

```
enum cv::dnn::Backend
```

Enum of computation backends supported by layers.

| Enumerator | |
|---------------------|--|
| DNN_BACKEND_DEFAULT | |
| DNN_BACKEND_HALIDE | |

§ Target

enum `cv::dnn::Target`

Enum of target devices for computations.

Enumerator

| | |
|-------------------|--|
| DNN_TARGET_CPU | |
| DNN_TARGET_OPENCL | |

Function Documentation

§ `blobFromImage()`

```
Mat cv::dnn::blobFromImage ( const Mat &    image,
                              double         scalefactor =
                              1.0,
                              const Size &   size = Size(),
                              const Scalar & mean =
                              Scalar(),
                              bool           swapRB = true,
                              bool           crop = true
                              )
```

Creates 4-dimensional blob from image. Optionally resizes and crops `image` from center, subtract mean values, scales values by `scalefactor`, swap Blue and Red channels.

Parameters

- image** input image (with 1-, 3- or 4-channels).
- size** spatial size for output image
- mean** scalar with mean values which are subtracted from channels. Values are intended to be in (mean-R, mean-G, mean-B) order if `image` has BGR ordering and `swapRB` is true.
- scalefactor** multiplier for `image` values.
- swapRB** flag which indicates that swap first and last channels in 3-channel image is necessary.
- crop** flag which indicates whether image will be cropped after resize or not

if `crop` is true, input image is resized so one side after resize is equal to corresponding dimension in `size` and another one is equal or larger. Then, crop from the center is performed. If `crop` is false, direct resize without cropping and preserving aspect ratio is performed.

Returns

4-dimensional `Mat` with NCHW dimensions order.

§ blobFromImages()

```
Mat cv::dnn::blobFromImages ( const std::vector< Mat > & images,
                               double scalefactor =
                               1.0,
                               Size size = Size(),
                               const Scalar & mean =
                               Scalar(),
                               bool swapRB = true,
                               bool crop = true
                               )
```

Creates 4-dimensional blob from series of images. Optionally resizes and crops images from center, subtract mean values, scales values by scalefactor, swap Blue and Red channels.

Parameters

- images** input images (all with 1-, 3- or 4-channels).
- size** spatial size for output image
- mean** scalar with mean values which are subtracted from channels. Values are intended to be in (mean-R, mean-G, mean-B) order if image has BGR ordering and swapRB is true.
- scalefactor** multiplier for images values.
- swapRB** flag which indicates that swap first and last channels in 3-channel image is necessary.
- crop** flag which indicates whether image will be cropped after resize or not

if crop is true, input image is resized so one side after resize is equal to corresponding dimension in size and another one is equal or larger. Then, crop from the center is performed. If crop is false, direct resize without cropping and preserving aspect ratio is performed.

Returns

4-dimensional **Mat** with NCHW dimensions order.

§ createCaffeImporter()

```
Ptr<Importer> cv::dnn::createCaffeImporter ( const String & prototxt,  
                                             const String & caffeModel = String()  
                                             )
```

Creates the importer of [Caffe](#) framework network.

Deprecated:

Use [readNetFromCaffe](#) instead.

Parameters

prototxt path to the .prototxt file with text description of the network architecture.

caffeModel path to the .caffemodel file with learned network.

Returns

Pointer to the created importer, NULL in failure cases.

§ createTensorflowImporter()

Ptr<Importer> cv::dnn::createTensorflowImporter (const **String** & **model**)

Creates the importer of **TensorFlow** framework network.

Deprecated:

Use **readNetFromTensorflow** instead.

Parameters

model path to the .pb file with binary protobuf description of the network architecture.

Returns

Pointer to the created importer, NULL in failure cases.

§ **createTorchImporter()**

```
Ptr<Importer> cv::dnn::createTorchImporter ( const String & filename,  
                                             bool isBinary = true  
                                             )
```

Creates the importer of [Torch7](#) framework network.

Deprecated:

Use [readNetFromTorch](#) instead.

Parameters

filename path to the file, dumped from Torch by using `torch.save()` function.

isBinary specifies whether the network was serialized in ascii mode or binary.

Returns

Pointer to the created importer, NULL in failure cases.

Warning

Torch7 importer is experimental now, you need explicitly set CMake `opencv_dnn_BUILD_TORCH_IMPORTER` flag to compile its.

Note

Ascii mode of Torch serializer is more preferable, because binary mode extensively use `long` type of C language, which has various bit-length on different systems.

The loading file must contain serialized [nn.Module](#) object with importing network. Try to eliminate a custom objects from serialazing data to avoid importing errors.

List of supported layers (i.e. object instances derived from Torch `nn.Module` class):

- `nn.Sequential`
- `nn.Parallel`
- `nn.Concat`
- `nn.Linear`
- `nn.SpatialConvolution`

- nn.SpatialMaxPooling, nn.SpatialAveragePooling
- nn.ReLU, nn.TanH, nn.Sigmoid
- nn.Reshape
- nn.SoftMax, nn.LogSoftMax

Also some equivalents of these classes from cunn, cudnn, and fbcunn may be successfully imported.

§ NMSBoxes()

```
void cv::dnn::NMSBoxes ( const std::vector< Rect > & bboxes,
                        const std::vector< float > & scores,
                        const float score_threshold,
                        const float nms_threshold,
                        std::vector< int > & indices,
                        const float eta = 1.f,
                        const int top_k = 0
                      )
```

Performs non maximum suppression given boxes and corresponding scores.

Parameters

- | | |
|------------------------|--|
| bboxes | a set of bounding boxes to apply NMS. |
| scores | a set of corresponding confidences. |
| score_threshold | a threshold used to filter boxes by score. |
| nms_threshold | a threshold used in non maximum suppression. |
| indices | the kept indices of bboxes after NMS. |
| eta | a coefficient in adaptive threshold formula: $nms_threshold_{i+1} = eta \cdot nms_threshold_i$. |
| top_k | if >0, keep at most top_k picked indices. |

§ readNetFromCaffe() [1/2]

```
Net cv::dnn::readNetFromCaffe ( const String & prototxt,  
                               const String & caffeModel = String()  
                             )
```

Reads a network model stored in Caffe model files.

This is shortcut consisting from createCaffeImporter and Net::populateNet calls.

§ readNetFromCaffe() [2/2]

```
Net cv::dnn::readNetFromCaffe ( const char * bufferProto,
                                size_t      lenProto,
                                bufferModel =
                                const char * NULL,
                                size_t      lenModel = 0
                                )
```

Reads a network model stored in Caffe model in memory.

This is an overloaded member function, provided for convenience. It differs from the above function only in what argument(s) it accepts.

Parameters

- bufferProto** buffer containing the content of the .prototxt file
- lenProto** length of bufferProto
- bufferModel** buffer containing the content of the .caffemodel file
- lenModel** length of bufferModel

§ readNetFromDarknet()

```
Net cv::dnn::readNetFromDarknet ( const String & cfgFile,  
                                const String & darknetModel = String()  
                                )
```

Reads a network model stored in **Darknet** model files.

Parameters

cfgFile path to the .cfg file with text description of the network architecture.

darknetModel path to the .weights file with learned network.

Returns

Network object that ready to do forward, throw an exception in failure cases.

This is shortcut consisting from DarknetImporter and Net::populateNet calls.

§ readNetFromTensorflow() [1/2]

```
Net cv::dnn::readNetFromTensorflow ( const String & model,  
                                    const String & config = String()  
                                    )
```

Reads a network model stored in Tensorflow model file.

This is shortcut consisting from createTensorflowImporter and Net::populateNet calls.

§ readNetFromTensorflow() [2/2]

```
Net cv::dnn::readNetFromTensorflow ( const char * bufferModel,  
                                     size_t      lenModel,  
                                     bufferConfig =  
                                     const char * NULL,  
                                     size_t      lenConfig = 0  
                                     )
```

Reads a network model stored in Tensorflow model in memory.

This is an overloaded member function, provided for convenience. It differs from the above function only in what argument(s) it accepts.

Parameters

bufferModel buffer containing the content of the pb file
lenModel length of bufferModel
bufferConfig buffer containing the content of the ptxt file
lenConfig length of bufferConfig

§ readNetFromTorch()

```
Net cv::dnn::readNetFromTorch ( const String & model,  
                               bool          isBinary = true  
                               )
```

Reads a network model stored in Torch model file.

This is shortcut consisting from createTorchImporter and Net::populateNet calls.

§ readTorchBlob()

```
Mat cv::dnn::readTorchBlob ( const String & filename,
                             bool           isBinary = true
                             )
```

Loads blob which was serialized as torch.Tensor object of Torch7 framework.

Warning

This function has the same limitations as [createTorchImporter\(\)](#).

§ shrinkCaffeModel()

```
void cv::dnn::shrinkCaffeModel ( const String &          src,
                                 const String &          dst,
                                 const std::vector< String > & layersTypes = std::vector< String >()
                                 )
```

Convert all weights of Caffe network to half precision floating point.

Parameters

- src** Path to origin model from Caffe framework contains single precision floating point weights (usually has .caffemodel extension).
- dst** Path to destination model with updated weights.
- layersTypes** Set of layers types which parameters will be converted. By default, converts only Convolutional and Fully-Connected layers' weights.

Note

Shrunked model has no origin float32 weights so it can't be used in origin Caffe framework anymore. However the structure of data is taken from NVidia's Caffe fork: <https://github.com/NVIDIA/caffe>. So the resulting model may be used there.

