

When you convert your iOS code to NEON, usually it's inside loops that can be written in parallel code. Also you have to keep in mind that the more load/store operations you have, the slower your code will be.

Assumptions

This guide is about inline *NEON intrinsics*, which should work on both 32bit and 64bit architectures. Vectors are always supposed to be of length 4, but you can generally just remove the letter *q* in the instruction name to use 2-vectors.

Syntax

Float

Arithmetic

• add: vaddq_f32 or vaddq_f64

```
float32x4_t v1 = { 1.0, 2.0, 3.0, 4.0 }, v2 = { 1.0, 1.0, 1.0, 1.0 };
float32x4_t sum = vaddq_f32(v1, v2);
// => sum = { 2.0, 3.0, 4.0, 5.0 }
```

• multiply: vmulq f32 or vmulq f64

```
float32x4_t v1 = { 1.0, 2.0, 3.0, 4.0 }, v2 = { 1.0, 1.0, 1.0, 1.0 };
float32x4_t prod = vmulq_f32(v1, v2);
// => prod = { 1.0, 2.0, 3.0, 4.0 }
```

• multiply and accumulate: vmlaq_f32

```
float32x4_t v1 = { 1.0, 2.0, 3.0, 4.0 }, v2 = { 2.0, 2.0, 2.0, 2.0 }, v3 = { 3.0, 3.0, 3.0, 3.0 };
```

```
float32x4_t acc = vmlaq_f32(v3, v1, v2); // S = A + B * C // => acc = { 5.0, 7.0, 9.0, 11.0 }
```

• multiply by a scalar: vmulq_n_f32 or vmulq_n_f64

```
float32x4_t v = { 1.0, 2.0, 3.0, 4.0 };
float32_t s = 3.0;
float32x4_t prod = vmulq_n_f32(ary1, s);
// => prod = { 3.0, 6.0, 9.0, 12.0 }
```

• multiply by a scalar and accumulate: vmlaq n f32 or vmlaq n f64

```
float32x4_t v1 = { 1.0, 2.0, 3.0, 4.0 }, v2 = { 1.0, 1.0, 1.0, 1.0 };
float32_t s = 3.0;
float32x4_t acc = vmlaq_n_f32(v1, v2, s);
// => acc = { 4.0, 5.0, 6.0, 7.0 }
```

• invert (needed for division): vrecpeq f32 or vrecpeq f64

```
float32x4_t v = { 1.0, 2.0, 3.0, 4.0 };
float32x4_t reciprocal = vrecpeq_f32(v);
// => reciprocal = { 0.998046875, 0.499023438, 0.333007813, 0.249511719 }
```

• invert (more accurately): use a Newton-Raphson iteration to refine the estimate

```
float32x4_t v = { 1.0, 2.0, 3.0, 4.0 };
float32x4_t reciprocal = vrecpeq_f32(v);
float32x4_t inverse = vmulq_f32(vrecpsq_f32(v, reciprocal), reciprocal);
// => inverse = { 0.999996185, 0.499998093, 0.333333015, 0.249999046 }
```

Load

load vector: vld1q_f32 or vld1q_f64

```
float values[5] = { 1.0, 2.0, 3.0, 4.0, 5.0 };
float32x4_t v = vld1q_f32(values);
// => v = { 1.0, 2.0, 3.0, 4.0 }
```

load same value for all lanes: vld1q_dup_f32 or vld1q_dup_f64

```
float val = 3.0;
float32x4_t v = vld1q_dup_f32(&val);
// => v = { 3.0, 3.0, 3.0, 3.0 }
```

• set all lanes to a hardcoded value: vmovq_n_f16 or vmovq_n_f32 or vmovq_n_f64

```
float32x4_t v = vmovq_n_f32(1.5);
// => v = { 1.5, 1.5, 1.5, 1.5 }
```

Store

• store vector: vst1q_f32 or vst1q_f64

```
float32x4_t v = { 1.0, 2.0, 3.0, 4.0 };
float values[5] = new float[5];
vst1q_f32(values, v);
// => values = { 1.0, 2.0, 3.0, 4.0, #undef }
```

• store lane of array of vectors: vst4q_lane_f16 or vst4q_lane_f32 or vst4q_lane_f64 (change to vst1... / vst2... / vst3... for other array lengths);

```
float32x4_t v0 = { 1.0, 2.0, 3.0, 4.0 }, v1 = { 5.0, 6.0, 7.0, 8.0 }, v2 = { 9.0, 10.0, 11.0, 12.0 }, v3 =
float32x4x4_t u = { v0, v1, v2, v3 };
float buff[4];
vst4q_lane_f32(buff, u, 0);
// => buff = { 1.0, 5.0, 9.0, 13.0 }
```

Arrays

• access to values: val[n]

```
float32x4_t v0 = { 1.0, 2.0, 3.0, 4.0 }, v1 = { 5.0, 6.0, 7.0, 8.0 }, v2 = { 9.0, 10.0, 11.0, 12.0 }, v3 = float32x4x4_t ary = { v0, v1, v2, v3 }; float32x4_t v = ary.val[2]; // => v = { 9.0, 10.0, 11.0, 12.0 }
```

Conditionals

• ternary operator: use vector comparison (for example voltq f32 for less than comparison)

```
float32x4_t v1 = { 1.0, 0.0, 1.0, 0.0 }, v2 = { 0.0, 1.0, 0.0 };
float32x4_t mask = vcltq_f32(v1, v2); // v1 < v2
float32x4_t ones = vmovq_n_f32(1.0), twos = vmovq_n_f32(2.0);
float32x4_t v3 = vbslq_f32(mask, ones, twos); // will select first if mask 0, second if mask 1
// => v3 = { 2.0, 1.0, 2.0, 2.0 }
```

Links

- summary of NEON intrinsics
- ARM NEON intrinsics reference

Contributing

Change README.md and send a pull request.

Author

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