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MENU

Agents



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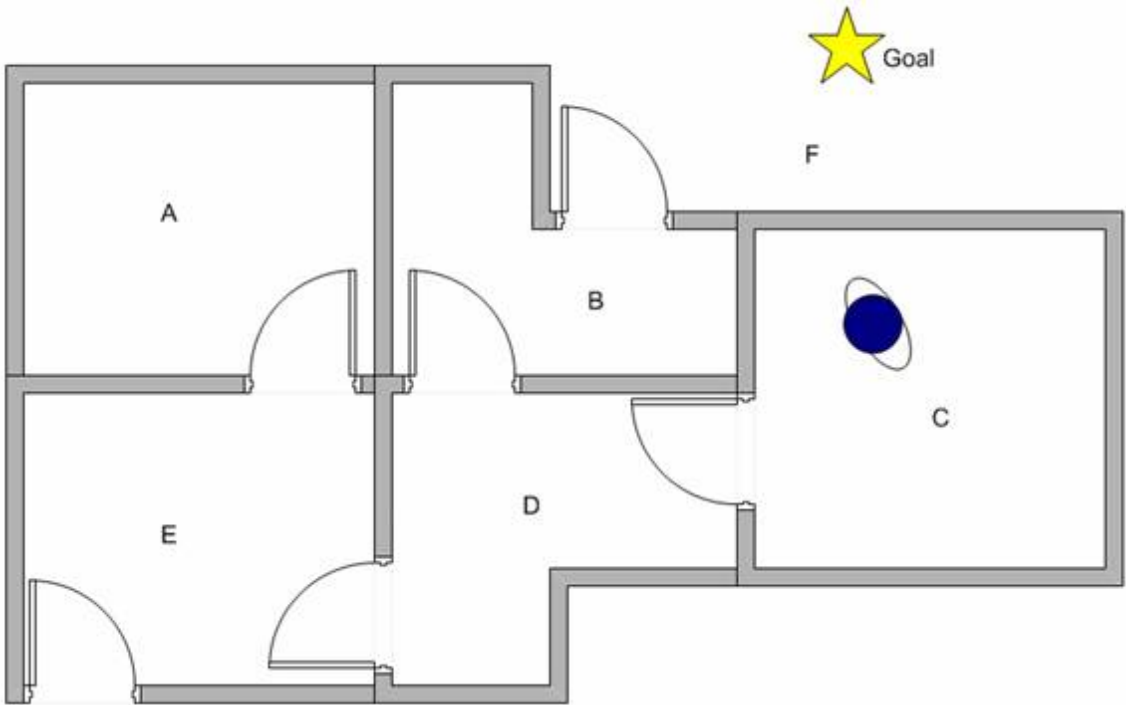
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Agent, States, Action

Ladies and gentlemen, now is the time to introduce our superstar agent?.

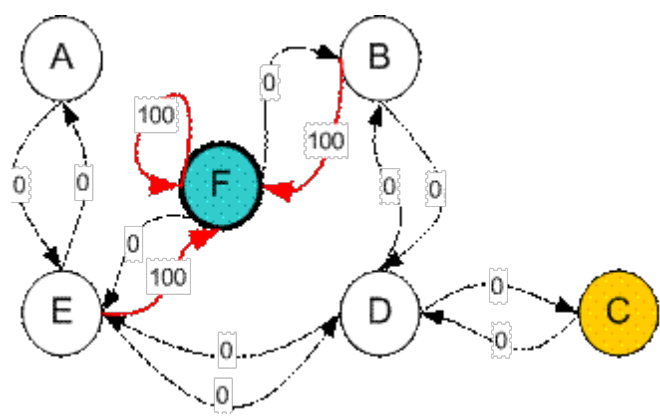
Imagine our agent as a dumb virtual robot that can learn through experience. The agent can pass one room to another but has no knowledge of the environment. It does not know which sequence of doors the agent must pass to go outside the building.

Suppose we want to model some kind of simple evacuation of an agent from any room in the building. Now suppose we have an agent in Room C and we want the agent to learn to reach outside the house (F). (see diagram below)



How to make our agent learn from experience?

Before we discuss about how the agent will learn (using Q learning) in the [next section \(Q-Learning.htm\)](#) , let us discuss about some terminologies of *state* and *action* .



Suppose now the agent is in state C. From state C, the agent can go to state D because the state C is connected to D. From state C, however, the agent cannot directly go to state B because there is no direct door connecting room B and C (thus, no arrow). From state D, the agent can go either to state B or state E or back to state C (look at the arrow out of state D). If the agent is in state E, then three possible actions are to go to state A, or state F or state D. If agent is state B, it can go either to state F or state D. From state A, it can only go back to state E.

We can put the state diagram and the instant reward values into the following reward table, or matrix R .

		Action to go to state					
Agent now in state	A	B	C	D	E	F	
A	-	-	-	0	-		
B	-	-	0	-	100		
C	-	-	0	-	-		
D	-	0	0	-	0	-	
E	0	-	-	0	-	100	
F	-	0	-	-	0	100	

The minus sign in the table says that the row state has no action to go to column state. For example, State A cannot go to state B (because no door connecting room A and B, remember?)

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Preferable reference for this tutorial is

Teknomo, Kardi. 2005. Q-Learning by Examples. <http://people.revoledu.com/kardi/tutorial/ReinforcementLearning/index.html>