lab1

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1 LAB 1 - Wykrywanie krawędzi metodą Canny'jego

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```
[1]: import torch
import torch.nn as nn
import numpy as np
from PIL import Image, ImageOps
import torchvision.transforms as T
```

```
[2]: def preview(tensor):
    preview = tensor.squeeze(0)
    return T.ToPILImage()(preview)

def save(pil, name):
    return pil.save(f'images/{name}.png', "PNG")
```

1.0.1 Load image

```
[3]: img = original = Image.open("sample.jpg")
img
save(img, "0_original")
```

```
[4]: img = T.ToTensor()(img)
img = img.unsqueeze(0) # == reshape(1, 2, w, h)
```

1.0.2 Convert RGB to grayscale

```
[5]: # 0.299 Red + 0.587 Green + 0.114 Blue.
def rgb_to_grayscale_kernel():
    kernel = torch.tensor([0.299, 0.587, 0.114], dtype=torch.float32)
    return kernel.reshape((1, 3, 1, 1))
```

```
[6]: kernel = rgb_to_grayscale_kernel()
rgb_to_gray_conv = nn.Conv2d(in_channels=3, out_channels=1, kernel_size=1,__
$\to$bias=False)
rgb_to_gray_conv.weight = nn.Parameter(kernel)
```

```
[7]: | img = rgb_to_gray_conv(img)
```

```
[8]: pil = preview(img)
save(pil, "1_gray_scale")
pil
```

[8]:



1.0.3 Apply average pooling

Do wykrywania krawędzi zastosujemy MaxPool ponieważ nie rozmazuje krawędzi tak jak AvgPool. Przy pullingu gdzie kernel size = 2 różnica pomiędzy tymi dwoma jest prawie niezauważalna.

```
[9]: avg_poll_conv = nn.MaxPool2d(kernel_size=2)
print(img.shape)
img = avg_poll_conv(img)

pil = preview(img)
save(pil, "2_resized")
pil
```

torch.Size([1, 1, 360, 540])

[9]:



1.0.4 Apply gaussian blur

img = blur_conv(img)

blur_conv.weight = nn.Parameter(kernel)

```
[10]: def gaussian_kernel(size, sigma=1):
    assert size % 2 == 1, "Kernel size must be an odd number"
    half = int(size) // 2
    x, y = np.mgrid[-half : half + 1, -half : half + 1]
    normal = 1 / (2.0 * np.pi * sigma**2)
    g = np.exp(-((x**2 + y**2) / (2.0 * sigma**2))) * normal
    return torch.tensor(g, dtype=torch.float32).reshape(1, 1, size, size)

[11]: blur_size = 21
    kernel = gaussian_kernel(blur_size)
    blur_conv = nn.Conv2d(
        in_channels=1, out_channels=1, kernel_size=kernel.shape, bias=False
```

```
[12]: pil = preview(img)
save(pil, "3_blured")
pil
```

[12]:



1.0.5 Calculate gradient

```
[13]: def gradient_kernel():
          kernel = torch.tensor(
              Γ
                   [[[[1, 2, 1], [0, 0, 0], [-1, -2, -1]]]],
                   [[[[1, 0, -1], [2, 0, -2], [1, 0, -1]]]],
              ],
              dtype=torch.float32,
          return kernel.reshape(2, 1, 3, 3)
[14]: kernel = gradient_kernel()
      print(kernel)
      gradient_conv = nn.Conv2d(
          in_channels=1, out_channels=2, kernel_size=3, bias=False, #stride=(1, 1, _____)
       \hookrightarrow 1), padding=(0, 0, 0), dilation=(0, 0, 0)
      gradient_conv.weight = nn.Parameter(kernel)
      img = gradient_conv(img)
     tensor([[[[ 1., 2., 1.],
```

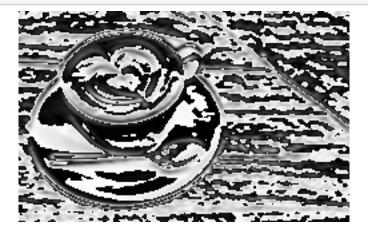
```
[[[ 1., 0., -1.],
[ 2., 0., -2.],
```

[1., 0., -1.]]])

```
[15]: pil = preview(img[:, 0, :, :])
save(pil, "4_sobel_x")
```

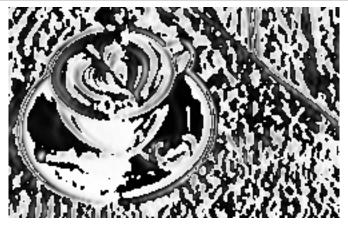
pil

[15]:



```
[16]: pil = preview(img[:, 1, :, :])
save(pil, "5_sobel_y")
pil
```

[16]:



```
[18]: gradient_layer = Gradient()
img = gradient_layer(img)
img.shape
```

```
D = img[0, 1, :, :]
       img = img[0, 0, :, :]
       # return imq
       Z = np.zeros((M, N), dtype=np.float32)
       angle = D * 180.0 / np.pi
       angle[angle < 0] += 180
       for i in range(1, M - 1):
           for j in range(1, N - 1):
                try:
                    q = float("inf")
                    r = float("inf")
                    # angle 0
                    if (0 \le angle[i, j] \le 22.5) or (157.5 \le angle[i, j] \le angle[i, j] \le angle[i, j]
→180):
                        q = img[i, j + 1]
                        r = img[i, j - 1]
                    # angle 45
                    elif 22.5 \le angle[i, j] \le 67.5:
                        q = img[i + 1, j - 1]
                        r = img[i - 1, j + 1]
                    # angle 90
                    elif 67.5 \le angle[i, j] \le 112.5:
                        q = img[i + 1, j]
                        r = img[i - 1, j]
                    # angle 135
                    elif 112.5 <= angle[i, j] < 157.5:</pre>
                        q = img[i - 1, j - 1]
                        r = img[i + 1, j + 1]
                    if (img[i, j] >= q) and (img[i, j] >= r):
                        Z[i, j] = img[i, j]
                    else:
                        Z[i, j] = 0
                except IndexError as e:
                    pass
       return torch.tensor(Z, dtype=torch.float32).reshape(
           1, 1, Z.shape[-2], Z.shape[-1]
       )
```

```
[23]: non_max_suppression_layer = NonMaxSuppression()
img = non_max_suppression_layer(img)

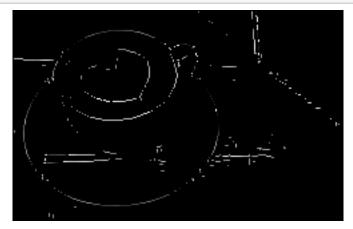
pil = preview(img)
save(pil, "8_non_max_suppresion")
```

```
[24]: TRESHHOLD = 0.5

class ReLU(nn.Module):
    def forward(self, x):
        x[x < TRESHHOLD] = 0.
        return x

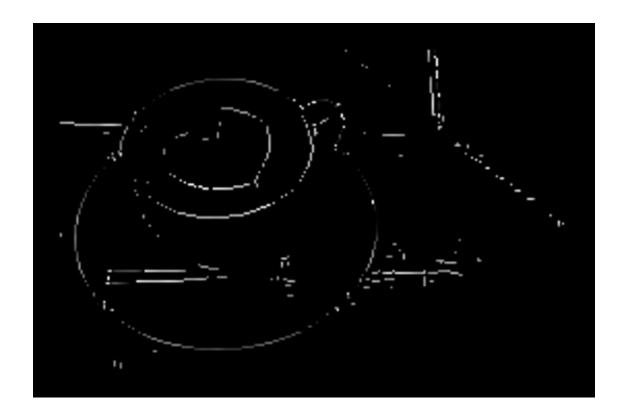
relu = ReLU()
  img = relu(img)
  final = preview(img)
  save(final, "9_relu")
  final</pre>
```

[24]:



```
[25]: expanded = ImageOps.expand(final, border=12, fill="black")
    resized = expanded.resize(original.size)
    save(resized, "10_final_resized")
    resized
```

[25]:



Żeby krawędzie pokrywały się z orginalnym obrazkiem należy dodać marginesy na końcowy obrazek. Aleternatywnie na każdym etapie obróbki trzebaby dbać o poprawny padding, żeby filtry konwolucyjne nie zmieniały wielkości obrazu.

```
[26]: overlayed = original.copy()
  overlayed.paste(resized, (0,0), resized)
  save(overlayed, "11_overlayed")
  overlayed
```

[26]:

