## **Errata Sheet**

Last Updated: 9/10/2023

# Chapter 1

• On page 20, in the paragraph preceding Section 1.2.3, the word "statistics" should be replaced with "statistic."

# Chapter 3

• On page 35, in the beginning of Section 3.1.3, all  $\lambda$ 's should be replaced with  $\eta$ .

#### Errata Sheet for Previous Versions

#### Applicable to versions before 2/4/2023

### Chapter 3

• On page 42 and on page 43, the following Python code

```
ax = plt.figure(figsize=(12, 10)).gca(projection='3d')
```

should be rewritten as

```
fig = plt.figure(figsize=(12,10))
ax = fig.add_subplot(projection='3d')
```

The gca() function is now deprecated.

#### Chapter 4

• On page 53, the gradient of the SVM loss near Equation (4.9) should be written as

$$\nabla \ell = \begin{cases} -y\vec{\mathbf{x}} & y\vec{\mathbf{w}} \cdot \vec{\mathbf{x}} < 1\\ 0 & y\vec{\mathbf{w}} \cdot \vec{\mathbf{x}} > 1 \end{cases}$$

• On page 54, in Figure 4.4, the lines of boundary should be labeled  $\vec{\mathbf{w}} \cdot \vec{\mathbf{x}} = -1, 0, +1$  (left to right).

#### Chapter 8

• On page 101, the phrase "an loss" should be written as "a loss."

### Chapter 11

- On page 137, in Definition 11.4.4, Jacobian matrix should be of size  $J(\vec{\mathbf{z}}, \vec{\mathbf{x}}) \in \mathbb{R}^{\ell \times n}$
- On page 137, the equation in Example 11.4.5 should be written as

$$J(\vec{\mathbf{z}}, \vec{\mathbf{x}}) = J(\vec{\mathbf{z}}, \vec{\mathbf{y}}) J(\vec{\mathbf{y}}, \vec{\mathbf{x}}) = diag(\mathbb{1}(\mathbf{A}\vec{\mathbf{x}} > 0))\mathbf{A}$$

## Chapter 15

• On page 197, the equation after (15.3) should be updated as

$$Q_t' = r_t + \gamma \max_b Q(s_{t+1}, b)$$

and similarly in page 198, the equation in the Example 15.3.3 should be updated as

$$Q'_{t} = r_{t} + \gamma \max_{b} Q(s_{t+1}, b) = 1$$

## Chapter 19

• On page 242, the formula in Definition 19.2.5 should be written as

$$\left. \frac{\partial y_j}{\partial x_i} \right|_{\vec{\mathbf{x}}} = \lim_{h \to 0} \frac{f_j(x_1, \dots, x_i + h, \dots, x_n) - f_j(x_1, \dots, x_i, \dots, x_n)}{h}$$