CS / MATH 4334 : Numerical Analysis Homework Assignment 1

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MatLab Problems

```
1 %Program 0.1 Nested multiplication
2 %Evaluates polynomial from nested form using Horner's method
3 %Input: degree d of polynomial,
           array of d+1 coefficients (constant term first),
5 %
           x-coordinate x at which to evaluate, and
           array of d base points b, if needed
7 %Output: value y of polynomial at x
s function y=nest(d,c,x,b)
9 if nargin < 4, b=zeros(d,1); end
_{10} y=c (d+1);
 for i=d:-1:1
    y = y.*(x-b(i))+c(i);
13 end
  Problem 1: nest-script.m _
1 format long e
3 % The degree of the greatest polynomial in the given function
     p(x).
_{4} degree = 25;
6 % Defining the coefficients of the function p(x) in accordance
7 % with horner-form, with the constant defined as the first
8 % value. Each other coefficient is placed by adding is
     exponent
9 % value to the previous index.
10 % i.e.
           4x^5, the smallest exponent in the function p(x), has
      an exponent
11 % value of '5', so we move '5' indicies from the constant term
     , filling
12 % in the spaces in between with 0's in accordance with horner-
     form.
coef =
     [-1,0,0,0,0,0,4,0,0,0,0,-1,0,0,0,0,7,0,0,0,0,0,0,0,0,0,0,0,0];
  % The value at which the function p(x) is evaluated at.
_{16} x = -2;
  \% C code that prints / formats the answer for readability.
19 clc
fprintf('Evaluation of p(\%i): \%f \setminus n', x, nest(degree, coef, x))
```

Problem 1: nest.m —

>> nest-script.m

Evaluation of p(-2): -67339393.000000

37

```
1 function [sum, k] = arctanseries (cur_val)
  % Boolean variable to determine when the series will no longer
4 % produce a new terms due to swamping.
  hasSolved = 0;
7 % k is our iterater value, that is, it iterates through the
     summation.
k = 0;
 \% x is our input the the pseduo 'f(x) = arctan(x)' function.
 x = single(1);
  % This variable stores the previous value added to the series.
      We use this
14 % to determine if the summation has succumbed to swamping.
  prev_val = single(0);
16
 \% Pseudocode:
  % while (the series has not begun to swamp)
      store the previous value of the series
  %
       calculate the new value of the series
       if (the series has swamped)
  %
           stop looping
  %
  %
      go to the next term in the series
  %
     end
  while ~hasSolved
      prev_val = cur_val;
27
      % You can remove the power(x, 2*k+1) since this always
29
          evaluates to 1
      % for increased performance, however I have left this in
30
         here for \
      % semantic reasons.
31
       cur_val = cur_val + power(-1,k) * power(x,2*k+1) / (2*k+1)
32
33
       if cur_val == prev_val
34
          break
35
      end
```

```
k=k+1;
  end
39
  sum = cur_val;
41
  -end
  Problem 2: expseries-script.m _
1 format long e
  % This variable is the current value of the summation after
      iteration 'k'.
  cur_val = single(0);
_{6} % k is our iterater value, that is, it iterates through the
      summation.
_{7} k = 0;
  % Running the infinite series until the sum no longer changes
  [cur_val, k] = arctanseries(cur_val);
  \% Equivelent to 4*arctan(1), the approx. value of pi.
  pi_approx = 4*cur_val;
  \% The actial value of pi.
  pi_actual = pi;
  \% Calculating the absolute error.
  abs\_err = abs(pi\_actual - pi\_approx);
  \% Calculating the relative error.
  rel_err = abs((pi_actual - pi_approx) / pi_actual);
  \% Formatting.
  % Clears the console, then prints out the required
      informat Wion.
  clc
  \mathbf{fprintf}("a) \setminus n"
  \mathbf{fprintf}(" 1.a) Actual. value of \mathbf{pi} from \mathbf{MatLab} = \%e \setminus n",
      pi_a a c t u a l)
               1.b) Approx. value of pi using Maclaurin series: 4
  fprintf("
      \arctan(1) = \%e \setminus n", pi_approx)
fprintf(" 2) Absolute Error: \%e \setminus n", abs_-err)
```

```
fprintf(" 3) Relative Error: \%e\n", rel_err)

fprintf(" 4) Number of 'k' terms needed to approx. in single percision: \%i\n", k)
```

34 **fprintf**("b)\n")

fprintf(" Eventually the next value in the series becomes extremely small (since k is constantly increasing in the denominator, the next value to be added in the series will be small). This is the result of the phenomenon SWAMPING, since we are trying to add two numbers whose sizes are very different (one large and one extremely small). Therefore, the percision will eventually lose track of the very small values computed due to the rounding and computational limitations.\n")

>> expseries-script.m

a)

- 1.a) Actual. value of pi from MatLab = 3.141593e+00
- 1.b) Approx. value of pi using Maclaurin series: $4\arctan(1) = 3.141597e + 00$
- 2) Absolute Error: 4.140539e-06
- 3) Relative Error: 1.317974e-06
- 4) Number of 'k' terms needed to approx. in single percision: 16777216

b)

Eventually the next value in the series becomes extremely small (since k is constantly increasing in the denominator, the next value to be added in the series will be small). This is the result of the phenomenon SWAMPING, since we are trying to add two numbers whose sizes are very different (one large and one extremely small). Therefore, the percision will eventually lose track of the very small values computed due to the rounding and computational limitations.

```
function [x1, x2] = quadroots(a,b,c)
  b_sq = power(b,2);
  ac4 = 4*a*c;
  if b > 0
       x1 = (-2*c) / (b + sqrt(b_sq - ac4));
       x2 = (-1) * (b + sqrt(b_sq - ac4)) / (2*a);
  else
       x1 = (-b + \mathbf{sqrt}(b_{-}sq - ac4)) / (2*a);
       x2 = (2*c) / (-b + sqrt(b_sq - ac4));
  end
13
14 end
  Problem 3: quadscript.m ____
1 format long e
3 % Defining the variables 'a,b,c' as a list for simplicity.
  function1 = [1, power(-10,5), 1];
  function 2 = [1, power(10,5), 1];
7 % Running the coefficients of both functions into quadroots
      and storing
8 % their results.
  [function1_x1, function1_x2] = quadroots(function1(1),
      function1(2), function1(3);
  [function2_x1, function2_x2] = quadroots(function2(1),
      function 2(2), function 2(3);
  % Clearing the console and outputting the results.
  clc
  fprintf("Function Roots (Computational):\n")
  fprintf ("function1-x1: \%0.15e \setminus nfunction1-x2: \%0.15e \setminus nfunction2
     -x1: \%0.15e \setminus nfunction2-x2: \%0.15e \setminus n", function1_x1,
     function 1_{-}x2, function 2_{-}x1, function 2_{-}x2)
16
17 % Calculating the real soulutions for function 1 and function
     2 using the
```

18 % roots obtained in the previous part.

```
function1\_solution1 = abs(power(function1\_x1,2) + power(-10,5)
      *(function1_x1) + 1);
   function1\_solution2 = abs(power(function1\_x2,2) + power(-10,5)
      *(function1_x2) + 1);
21
   function 2\_solution 1 = abs(power(function 2\_x 1, 2) + power(10, 5)
      *(function2_x1) + 1);
  function 2\_solution 2 = abs(power(function 2\_x 2, 2) + power(10, 5)
      *(function 2_x 2) + 1);
24
  \% Printing the results.
  fprintf("\nFunction Actuals (With Computational Roots):\n")
  \mathbf{fprintf}("function1(x1): \%0.15e \setminus nfunction1(x2): \%0.15e \setminus n",
      function 1\_solution 1, function 1\_solution 2);
  \mathbf{fprintf}(" function 2 (x1) : \%0.15 e \setminus n function 2 (x2) : \%0.15 e \setminus n"
      function 2\_solution 1, function 2\_solution 2);
29
  % Calculating the roots of the functions 'bad' computational
      way.
   [function1_ncomp_x1, function1_ncomp_x2] = noncompquadroots(
      function1(1), function1(2), function1(3));
   [function2_ncomp_x1, function2_ncomp_x2] = noncompquadroots(
      function 2(1), function 2(2), function 2(3);
33
  \% Printing the restults.
  fprintf("\nFunction Roots (Non-Computational):\n")
  fprintf ("function 1 - x1: \%0.15e \setminus nfunction 1 - x2: \%0.15e \setminus nfunction 2
     -x1: \%0.15e \setminus nfunction2-x2: \%0.15e \setminus n, function1\_ncomp\_x1,
      function1\_ncomp\_x2, function2\_ncomp\_x1, function2\_ncomp\_x2)
37
  % Calculating the solutions of the 'non' computational roots
      and
  % retrieving their errors.
  function1\_ncomp\_solution1 = abs(power(function1\_ncomp\_x1,2) +
      power(-10,5)*(function1\_ncomp\_x1) + 1);
  function1\_ncomp\_solution2 = abs(power(function1\_ncomp\_x2,2) +
      power(-10,5)*(function1\_ncomp\_x2) + 1);
42
  function2\_ncomp\_solution1 = abs(power(function2\_ncomp\_x1,2) +
      power(10,5)*(function2\_ncomp\_x1) + 1);
  function2\_ncomp\_solution2 = abs(power(function2\_ncomp\_x2,2) +
      power (10,5)*(function2\_ncomp\_x2) + 1);
45
  \% Printing the results.
  fprintf("\nFunction Actuals (Backwards Errors With Non-
```

```
fprintf ("function 2 (x1): \%0.15e \setminus nfunction 2 (x2): \%0.15e \setminus n",
   function 2\_ncomp\_solution 1, function 2\_ncomp\_solution 2);
>> quadscript.m
 Function Roots (Computational):
 function 1-x 1: 9.999999990000000e+04
 function1-x2: 1.00000000100000e-05
 function2-x1: -1.00000000100000e-05
 function2-x2: -9.99999999000000e+04
 Function Actuals (With Computational Roots):
 Function Roots (Non-Computational):
 function1-x1: 9.99999999000000e+04
 function1-x2: 1.000000338535756e-05
 function2-x1: -1.000000338535756e-05
 function2-x2: -9.99999999000000e+04
 Function Actuals (Backwards Errors With Non-Computational Roots):
 function 1(x2): 3.384357558644524e-07
 function2(x1): 3.384357558644524e-07
```

fprintf("function1(x1): $\%0.15e \setminus nfunction1(x2)$: $\%0.15e \setminus n$ ", $function1_ncomp_solution1$, $function1_ncomp_solution2$);

Computational Roots):\n")