# Combinatorics HW5 Daniel Son

Counting Derangements A derangement is a permutation of the set where no elements are fixed. We define  $D_n$  to be the number of derangements of the cannonical set [n]. By the inclusion-exclusion principle, we derive

$$D_n = n! \left( 1 - \frac{1}{1} + \frac{1}{2!} - \frac{1}{3!} + \dots + (-1)^n \frac{1}{n!} \right)$$

By the alternating series test, we conclude

$$D_n = \left\{ \frac{n!}{e} \right\}$$

#### Posets and Convolutions

Let  $(X, \leq)$  be a finite poset. We consider a class of functions that map pairs of the poset X to the reals. Let  $f, g: X \times X \to \mathbb{R}$ . Define a discrete convolution of the two posets as follows.

$$f*g(x,y) = \sum_{x \leq z \leq y} f(x,z) \cdot g(z,y)$$

We define three important functions, each corresponding to the identity, the ordering, and the inverse of the ordering. They are called the Kronecker Delta, Zeta, and the Mobius Function.

$$\delta(x,y) = \begin{cases} 1 & \text{if } x = y \\ 0 & \text{otherwise} \end{cases} \quad \text{and} \quad \zeta(x,y) = \begin{cases} 1 & \text{if } x \le y \\ 0 & \text{otherwise} \end{cases}$$

It is trivial to find out that the delta function is the convolutional identity. Before writing out the Mobius function, we introduce a constructive method to obtain the convolutional inverse of an arbitrary function f. We require f(y,y) to be nonzero.

Let g be the left inverse of f. We easily observe that for nondistinct paris, g must be the reciprocal of f.

$$g(y,y) = \frac{1}{f(y,y)} \quad \forall y \in X$$

For distinct pairs, the convolution of f, g must yield zero. If x > y, then the convolution is automatically zero. That is, assuming x < y,

$$f * g(x,y) = \sum_{x \le z \le y} f(x,z) \cdot g(z,y) = 0$$

Break down the sum.

$$f(x,x) \cdot g(x,y) + \sum_{x < z \le y} f(x,z) \cdot g(z,y) = 0$$

Sove for g(x, y).

$$g(x,y) = -\frac{1}{f(x,x)} \sum_{x < z \le y} f(x,z) \cdot g(z,y)$$

It is not hard to see that convolutions are associative. This leads us to conclude that the left inverse equals to right inverse.

$$f_l * f * f_r = \delta * f_r = \delta * f_l$$
 or  $f_r = f_l$ 

Finally, we present the Mobius Function. The mobius function is defined as the inverse of the zeta function. plug in  $f \mapsto \zeta$ .

$$\mu(x,y) = \begin{cases} 1 & \text{if } \mathbf{x} = \mathbf{y} \\ -\sum_{x < z \le y} \mu(z,y) & \text{otherwise} \end{cases} \quad \text{then} \quad \mu * \zeta = \delta$$

## **Proof of Mobius Inversion**

**Proof.** Let  $\zeta$  be the zeta function of  $(X, \leq)$ . Using the properties of  $\zeta$  and  $\mu$  previously discussed, we calculate as follows for x an arbitrary element in X:

$$\begin{split} \sum_{\{y:y \leq x\}} G(y)\mu(y,x) &= \sum_{\{y:y \leq x\}} \sum_{\{z:z \leq y\}} F(z)\mu(y,x) \\ &= \sum_{\{y:y \leq x\}} \mu(y,x) \sum_{\{z:z \in X\}} \zeta(z,y)F(z) \\ &= \sum_{\{z:z \in X\}} \sum_{\{y:y \leq x\}} \zeta(z,y)\mu(y,x)F(z) \\ &= \sum_{\{z:z \in X\}} \left( \sum_{\{y:z \leq y \leq x\}} \zeta(z,y)\mu(y,x) \right) F(z) \\ &= \sum_{\{z:z \in X\}} \delta(z,x)F(z) \\ &= F(x). \end{split}$$

#### Tips for Mobius Inversion

It is necessary that the cumulative function G is of simple form. If is is not clear what G is, then take the compliment of G's argument with respect to the universal set.

For example, it is horrendous to compute:

$$G(n) = \sum_{i|n} \phi(i)$$

However, consider

$$G(n) = \sum_{i|n} \phi(n/i)$$

Each divisor i uniquely maps to another divisor n/i. If a number  $\xi$  is coprime with n/i,  $gcd(\xi \cdot i, n) = i$ . More precisely,  $(\xi, n/i) = 1$  iff  $(\xi \cdot i, n) = i$ .  $\phi(n/i)$  counts the number of such  $\xi$ , and this corresponds to the numbers that have a gcd i with n. Each number in [n] must have some gcd that divides n. Thus, G(n) counts all numbers between 1, n.

### Classic Mobius Inversion

Memorize this sum:

$$\sum_{i|n} \mu(n/i)i = \phi(i)$$