#### CHATBOT DAISY

Dialog Analogous Intellectual System

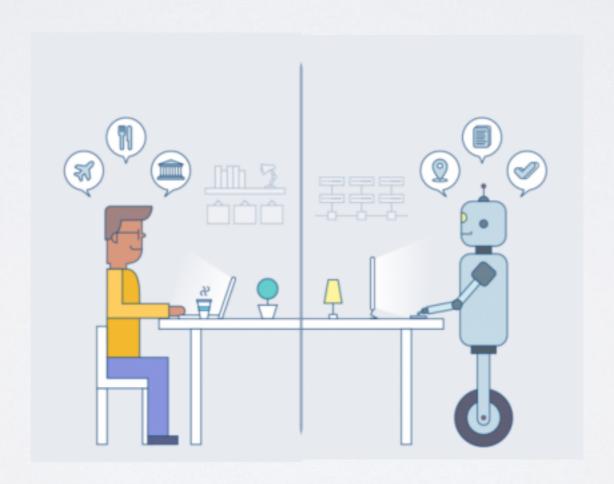
電機四 劉廷緯 B03901170

電機四 溫明浩 B03901179

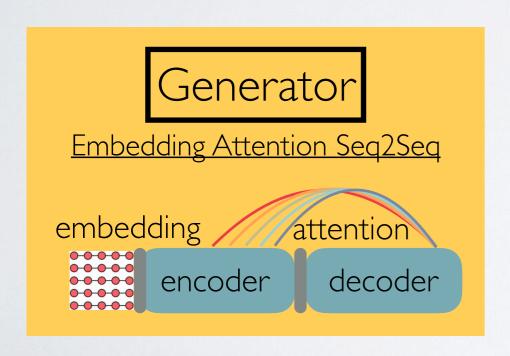
2018.03.07

#### TASK

Improve ChatBot dialog generation quality: to produce more intellectual and meaningful conversations



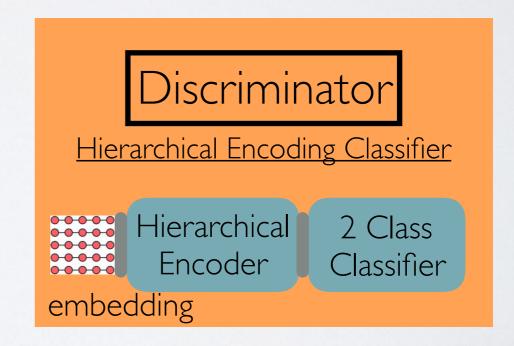
conditional sequence generative adversarial network trained with policy gradient

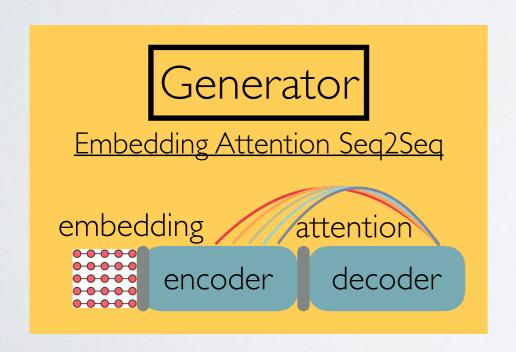


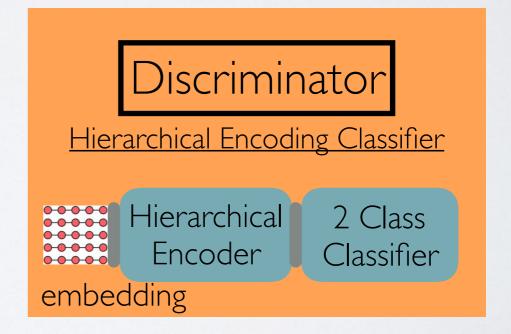
defines the policy that generates a response y given dialogue history x

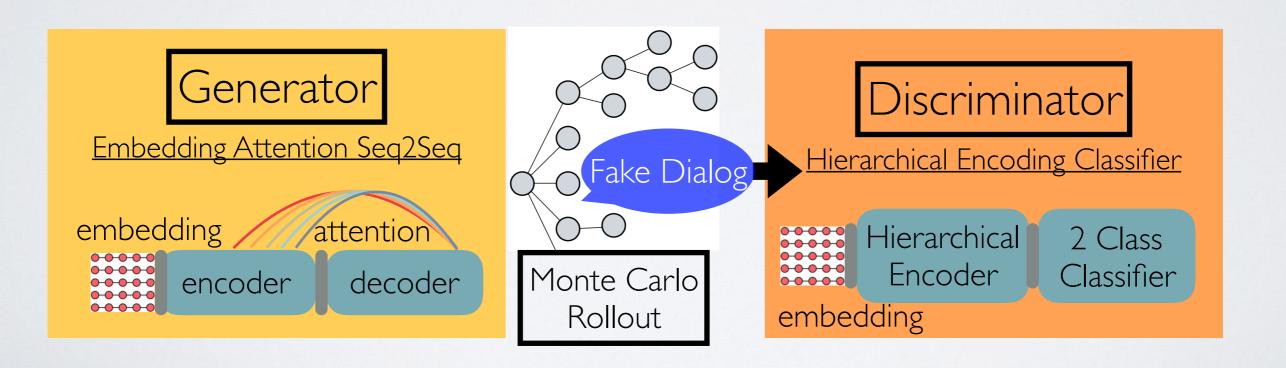
conditional sequence generative adversarial network trained with policy gradient

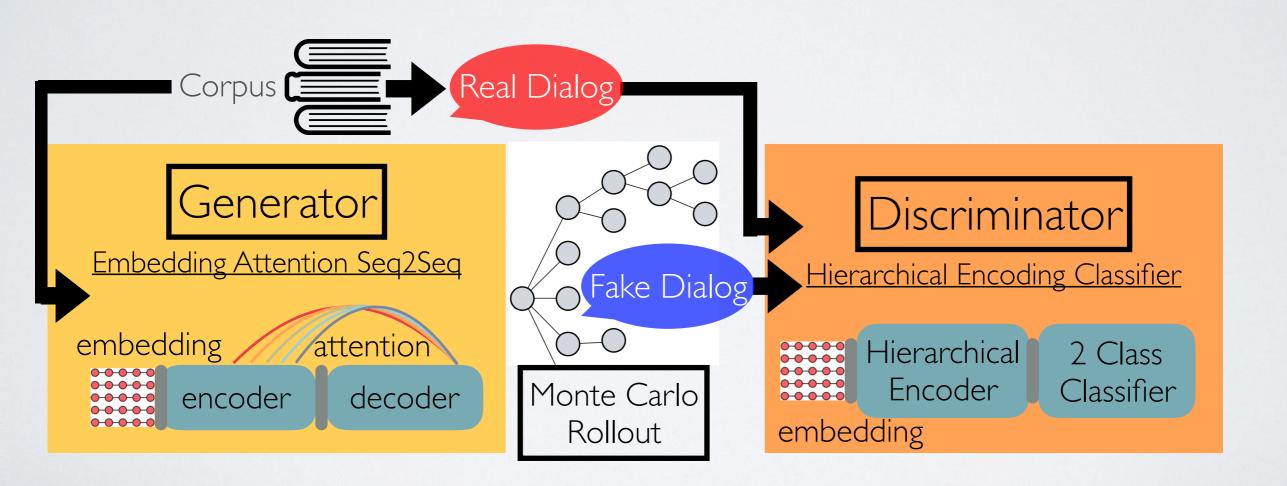
Classifier that takes as input a sequence of dialogue utterances {x,y} and outputs a label indicating whether the input is generated by humans or machines

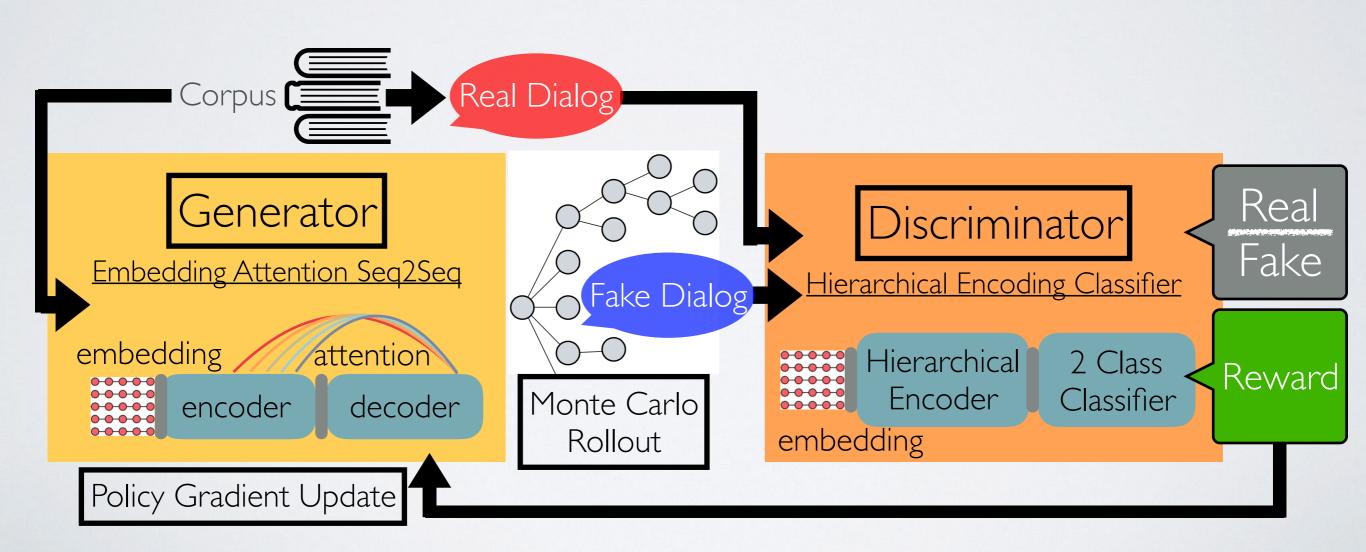












# DETAILS ABOUT OUR FRAMEWORK



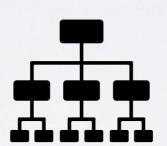
Seq2Seq with Attention



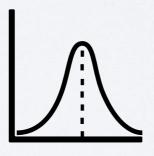
Training Corpus



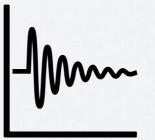
Policy Gradient



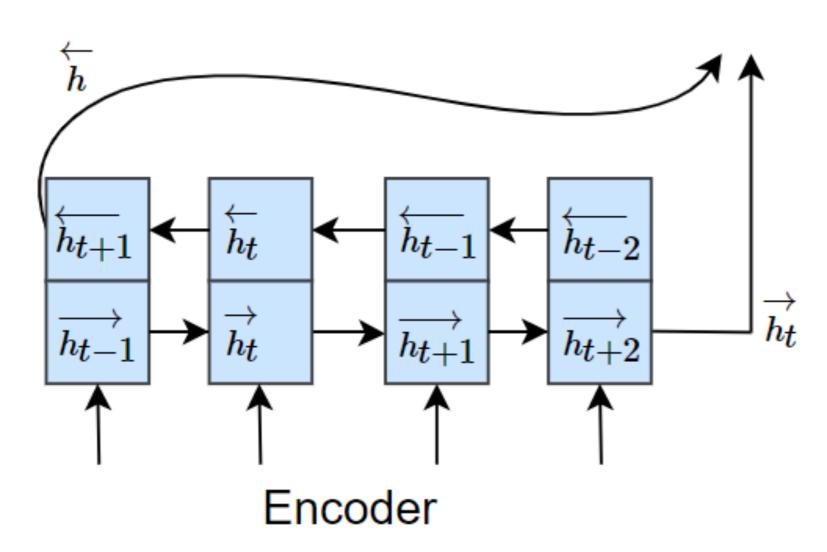
Monte Carlo Rollout



Sampled Softmax



Training Procedure

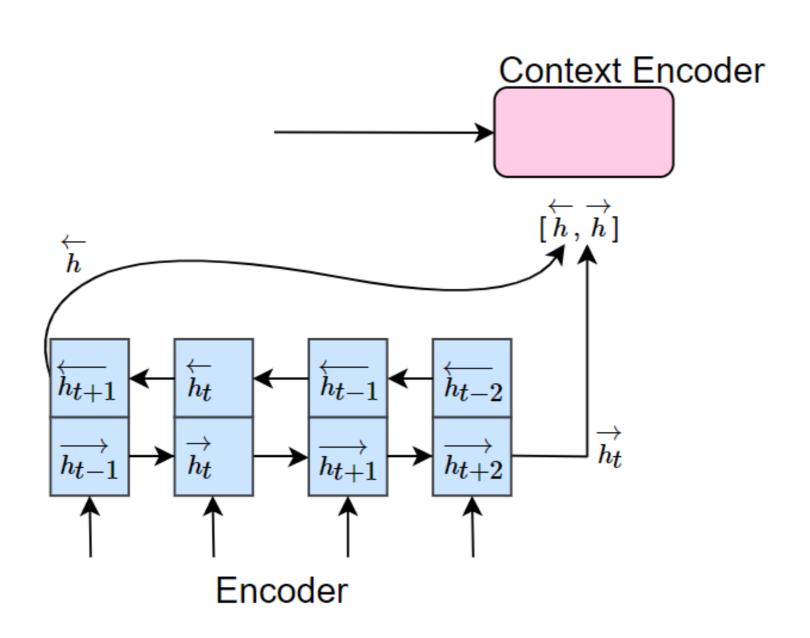


$$\overrightarrow{h_{e,t}} = GRU_{\overrightarrow{h_{e,t-1}}}, Ex_t)$$

$$\overleftarrow{h_{e,t}} = GRU_{\overleftarrow{h_{e,t+1}}}, Ex_t)$$

$$h_{e,t}^o = [\overleftarrow{h_{e,t}}, \overrightarrow{h_{e,t}}]$$

$$h_{c,t} = GRU(h_{c,t-1}, h_{e,t}^o)$$

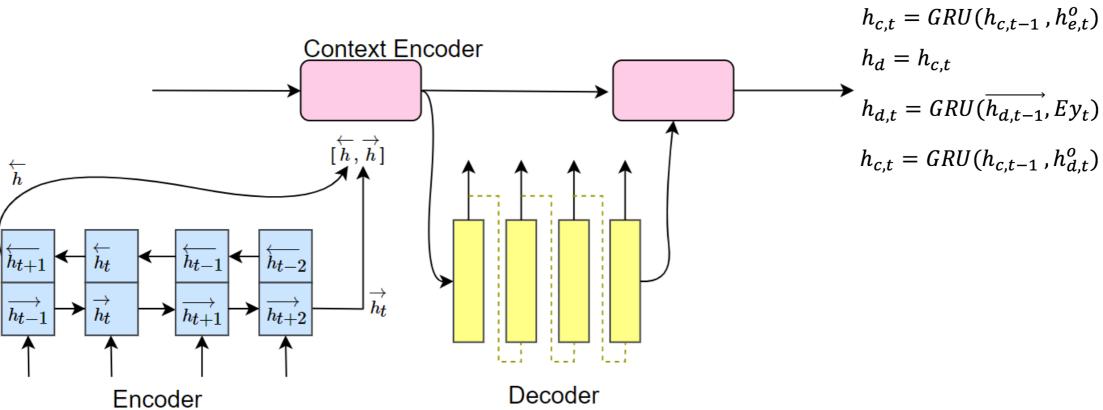


$$\overrightarrow{h_{e,t}} = GRU_{\overrightarrow{\mathbb{H}}}(\overrightarrow{h_{e,t-1}}, Ex_t)$$

$$\overleftarrow{h_{e,t}} = GRU_{\leftarrow}(\overleftarrow{h_{e,t+1}}, Ex_t)$$

$$h_{e,t}^o = [\stackrel{\longleftarrow}{h_{e,t}}, \stackrel{\longrightarrow}{h_{e,t}}]$$

$$h_{c,t} = GRU(h_{c,t-1}\,,h_{e,t}^o)$$



$$\overrightarrow{h_{e,t}} = GRU_{\overrightarrow{e}}(\overrightarrow{h_{e,t-1}}, Ex_t)$$

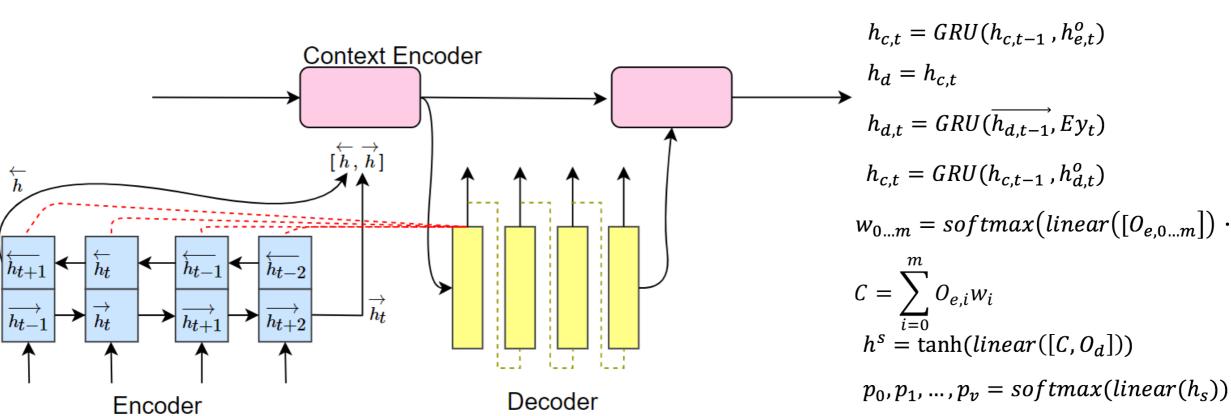
$$\overleftarrow{h_{e,t}} = GRU_{\leftarrow}(\overleftarrow{h_{e,t+1}}, Ex_t)$$

$$h_{e,t}^o = [\stackrel{\longleftarrow}{h_{e,t}}, \stackrel{\longrightarrow}{h_{e,t}}]$$

$$h_{c,t} = GRU(h_{c,t-1}, h_{e,t}^o)$$

$$h_{d,t} = GRU(\overrightarrow{h_{d,t-1}}, Ey_t)$$

$$h_{c,t} = GRU(h_{c,t-1}, h_{d,t}^o)$$



$$\overrightarrow{h_{e,t}} = GRU_{\overrightarrow{b}}(\overrightarrow{h_{e,t-1}}, Ex_t)$$

$$\overleftarrow{h_{e,t}} = GRU_{\overleftarrow{b}}(\overleftarrow{h_{e,t+1}}, Ex_t)$$

$$h_{e,t}^o = [\overleftarrow{h_{e,t}}, \overrightarrow{h_{e,t}}]$$

$$h_{c,t} = GRU(h_{c,t-1}, h_{e,t}^o)$$

$$h_d = h_{c,t}$$

$$h_{d,t} = GRU(\overrightarrow{h_{d,t-1}}, Ey_t)$$

$$h_{c,t} = GRU(h_{c,t-1}, h_{d,t}^o)$$

$$w_{0...m} = softmax(linear([O_{e,0...m}]) \cdot h_t)$$

$$C = \sum_{i=0}^{m} O_{e,i}w_i$$

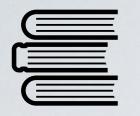
$$h^s = tanh(linear([C, O_d]))$$



#### TRAINING CORPUS

Cornell Movie-Dialogs Corpus dataset

- 220,579 conversational
- 10,292 pairs of movie characters
- 9,035 characters from 617 movies
- Total of 304,713 utterances



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Select dialogs that has len <= 19: 138127 dialog training pairs

# Y

### POLICY GRADIENT

Reward is used to encourage the generator to generate higher quality dialogs

G Max 
$$J(\theta) = \mathbb{E}_{y \sim p(y|x)}(D(\{x,y\})|\theta)$$

maximize the expected reward of generated sequence



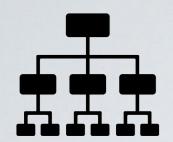
#### POLICY GRADIENT

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$$\nabla J(\theta) \approx [D(\lbrace x, y \rbrace) - b] \nabla \log \pi(y|x)$$
$$= [D(\lbrace x, y \rbrace) - b] \nabla \sum_{t} \log p(y_t|x, y_{1:t-1})$$





Where are you from?



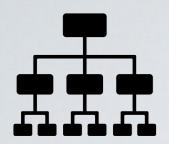
I don't know.



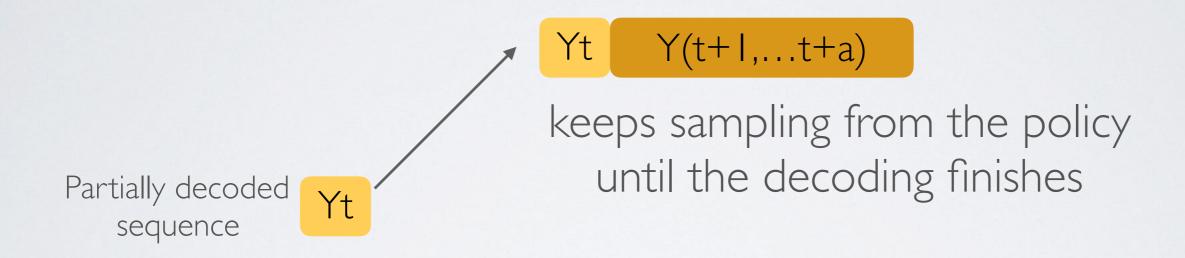
I am from Taiwan.



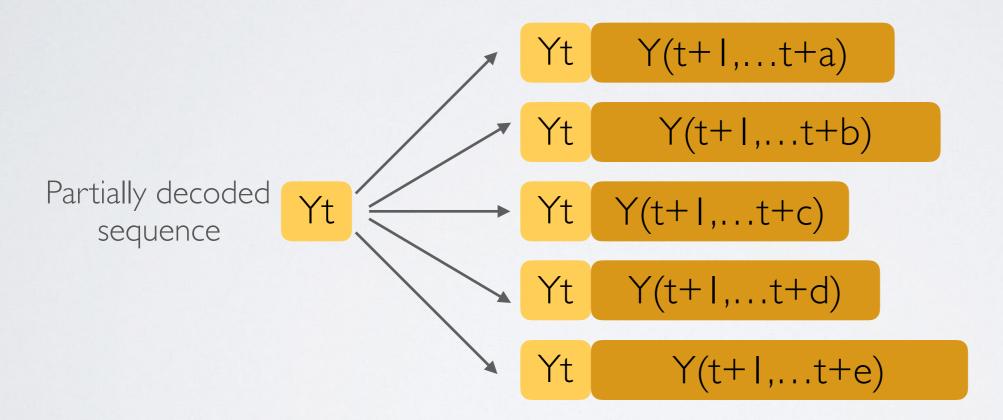
the first token I should receive a neutral reward



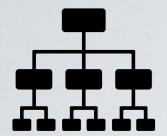
compute intermediate reward by using the Monte Carlo (MC) search



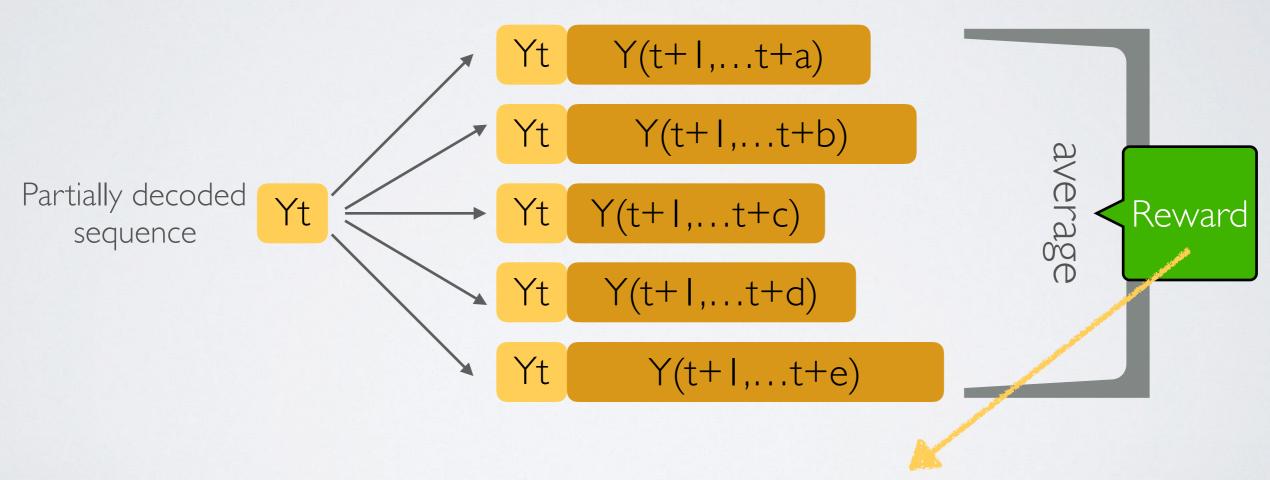
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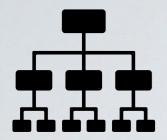
This process is repeated N times (N=5), resulting in N fully generated sequences that starts with Yt.



compute intermediate reward by using the Monte Carlo (MC) search

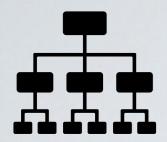


represents the intermediate reward at time step t



compute intermediate reward by using the Monte Carlo (MC) search

$$\nabla J(\theta) \approx [D(\lbrace x, y \rbrace) - b] \, \nabla \log \pi(y|x)$$
$$= [D(\lbrace x, y \rbrace) - b] \, \nabla \sum_{t} \log p(y_t|x, y_{1:t-1})$$



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$$\nabla J(\theta) \approx \sum_{t} [D(\{x,Y_t\}) - b] \nabla \log p(y_t|x,Y_{1:t-1})$$

$$D(\{x,Y_t\}) = \frac{1}{N} \sum_{i=1}^{N} D(\{x,Y_t^i\})$$

## SAMPLED SOFTMAX

Paper: 《 On Using Very Large Target Vocabulary for Neural Machine Translation 》

Regular Softmax

large vocabulary has a high cost at calculating regular softmax, because probability for every word in the vocabulary set has to be calculated.



Sampled Softmax

take in account subset V of your vocabulary to calculate loss.



Pre-train G on real data

```
For training_epochs do:
For D_steps do:
Real data
Fake data
Update
D with real and fake data
End
```

```
For G_steps do:
Real data

Fake data

Monte Carlo Rollout

Compute reward r for fake data using
Policy Gradient: Update
Teacher Forcing: Update
G on real data

Find
```

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```

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Compute reward r for fake data using

Policy Gradient: Update

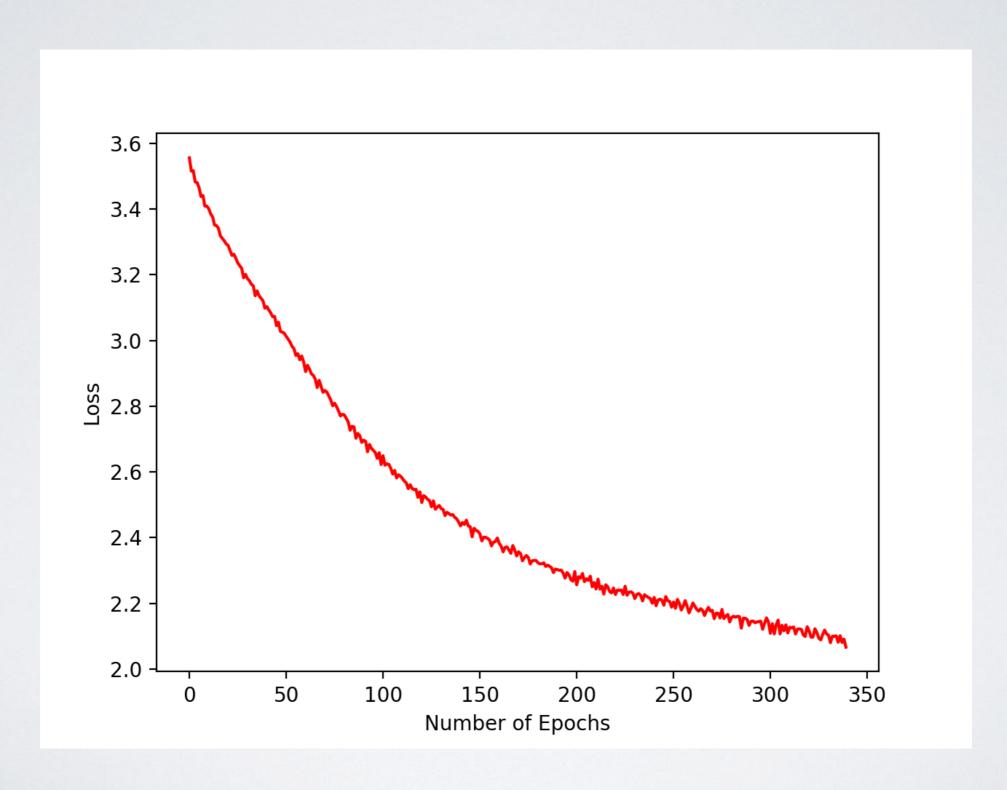
Teacher Forcing: Update

G on fake data

on real data

End
```

#### PRE-TRAIN CURVE



#### BLEU SCORE

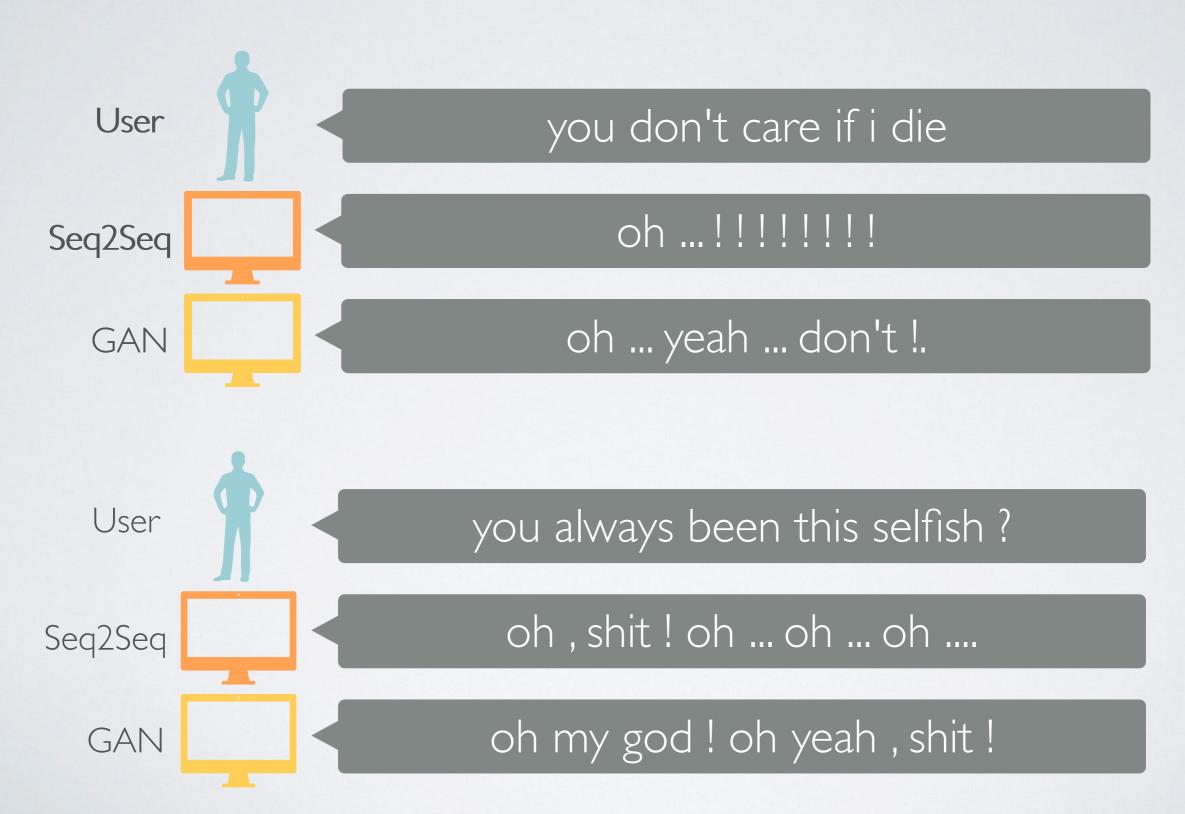


0.395

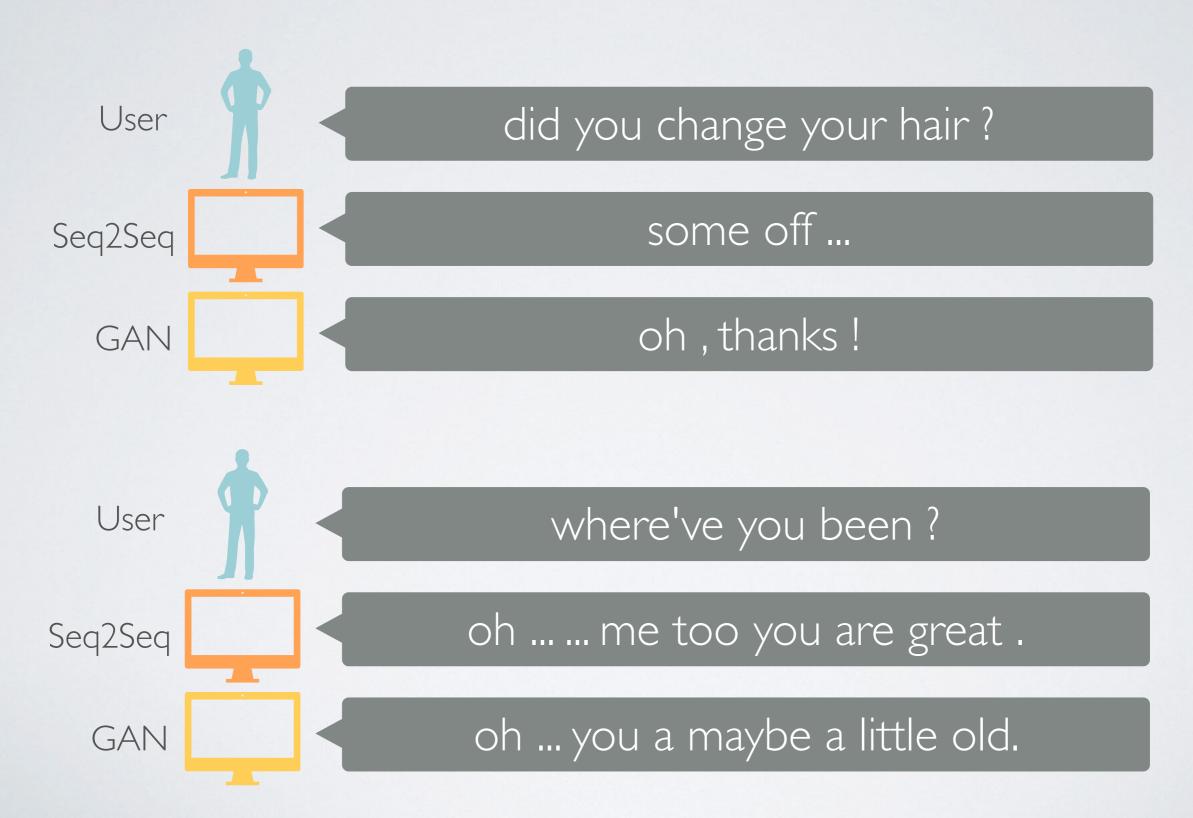


0.352

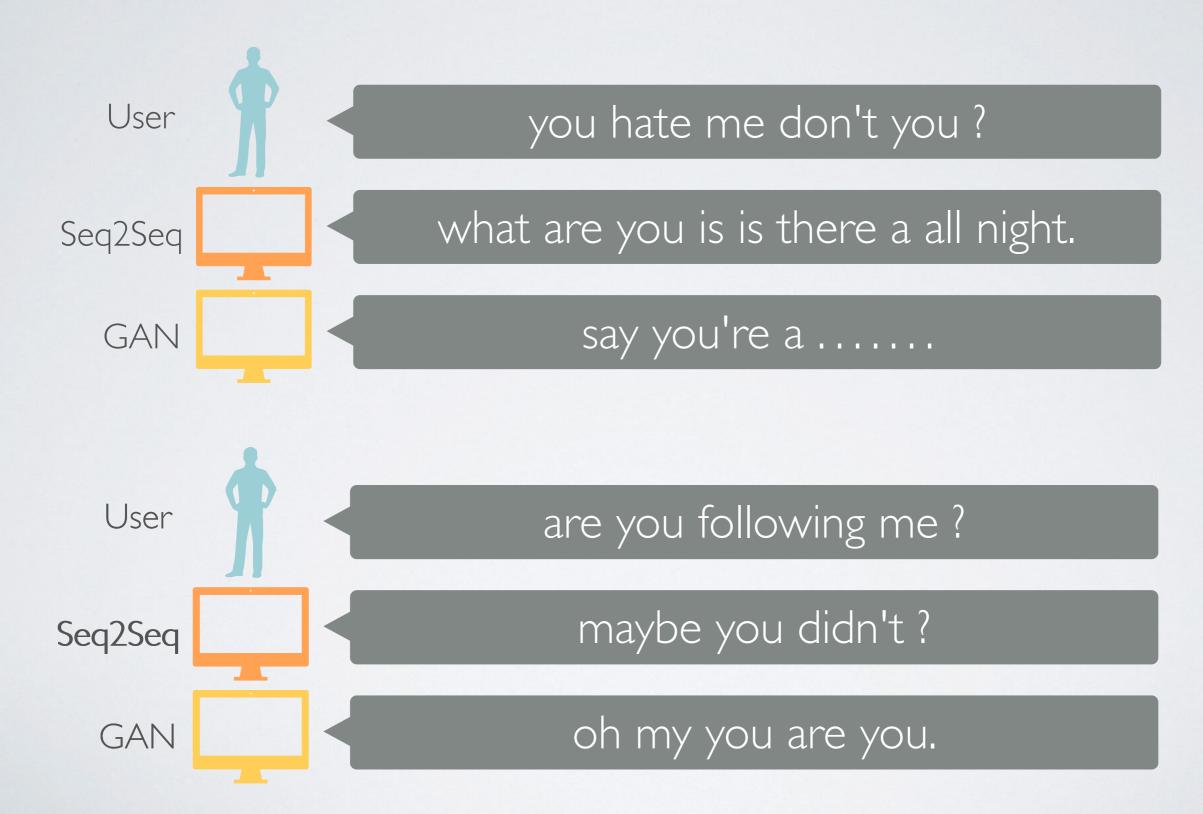
#### CONVERSATION DEMO

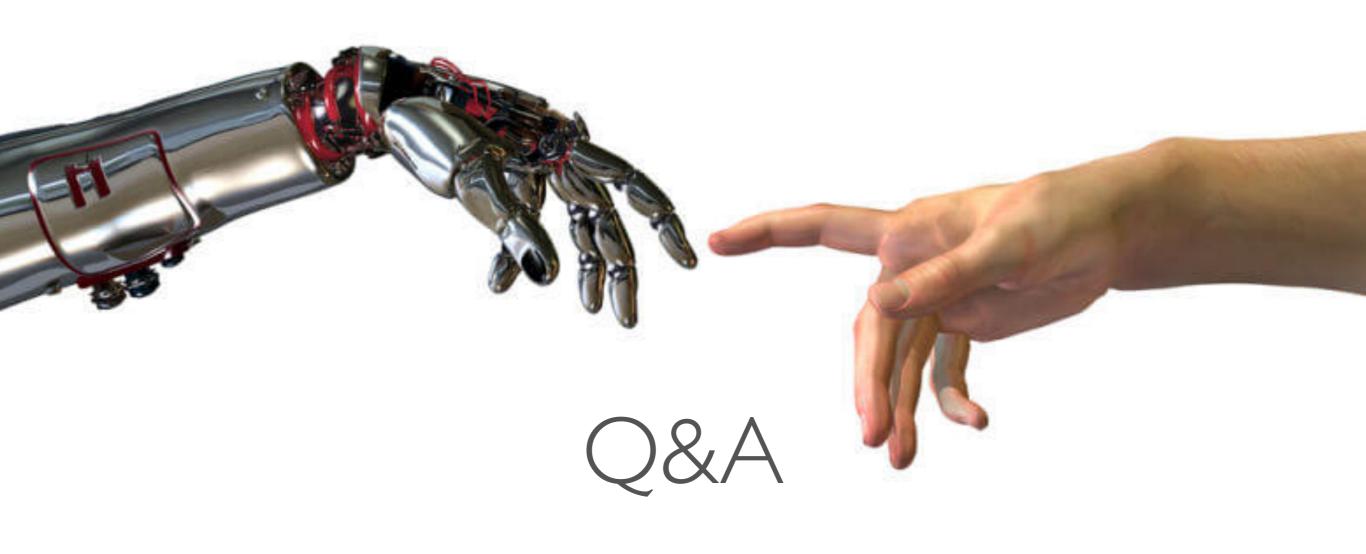


#### CONVERSATION DEMO



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Thank you for your attention!