

# *MixFishSim*: highly resolved spatiotemporal simulations for exploring mixed fishery dynamics

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## Abstract

Most fisheries exploit a variety of spatially and temporally heterogeneous fish populations using species-unselective gear that can result in unintended, unwanted catch of low quota or protected species. Reducing these unwanted catches is crucial for biological and economic sustainability of ‘mixed fisheries’ and implementation of an ecosystem approach to fishing.

If fisheries are to avoid unwanted catch, a good understanding of spatiotemporal fishery dynamics is required. However, traditional scientific advice is limited by a lack of highly resolved knowledge of population distributions, population movement and how fishers interact with different fish populations. This reflects the fact that data on fish location at high temporal and spatial resolutions is expensive and difficult to collect. Proxies inferred from either scientific surveys or commercial catch data are often used to model distributions, usually with sparse data at limited spatial and temporal resolution.

To understand how data resolution impacts inference on mixed fisheries interactions, we developed a highly resolved spatiotemporal simulation model incorporating: i) delay-difference population dynamics, ii) population movement

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using Gaussian Random Fields to simulate patchy, heterogeneously distributed populations, and iii) fishery dynamics for multiple fleet characteristics based on species targeting under an explore-exploit strategy via a mix of correlated random walk movement (for exploration) and learned behaviour (for exploitation) phases of the fisheries.

We simulated 50 years of fishing and used the results from the fisheries catch to draw inference on the underlying community structures. We compared this inference to a simulated fixed-site sampling design commonly used for fisheries monitoring purposes and the true underlying community structure. We i) used the results to establish the potential and limitations of fishery-dependent data in providing a robust picture of spatiotemporal distributions; and ii) simulated an area closure based on areas defined from the different data sources at a range of temporal and spatial resolutions to assess their effectiveness on reducing catches of a fish population.

Our framework allows users to explore the assumptions in modelling observational data and evaluate the underlying dynamics of such approaches at a fine spatial and temporal scale. We conclude from our simulations that commercial data, while containing bias, provide a useful tool for managing catches in mixed fisheries if applied at the correct spatiotemporal scale.

*Keywords:* Some, keywords, here. Max 6

*2010 MSC:* 00-01, 99-00

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## 1. Introduction

Fishers exploit a variety of fish populations that are heterogeneously distributed in space and time, with varying knowledge of species distributions. In doing so fisheries catch an assemblage of species and may discard over-quota catch when managed by single species quotas and fishers exhaust one or more

6 quota. This may lead to overexploitation of fish populations (Ulrich et al.,  
7 2011; Batsleer et al., 2015). Discarding of fish in excess of quota limits the abil-  
8 ity to maintain fishing mortality within sustainable limits (Alverson et al., 1994;  
9 Crowder et al., 1998; Rijnsdorp et al., 2007) and the ability to manage for the  
10 biological and economic sustainability of fisheries. As such, there is increasing  
11 interest in technical solutions such as gear and spatial closures as measures to  
12 reduce unwanted catch (Kennelly and Broadhurst, 2002; Catchpole and Revill,  
13 2008; Bellido et al., 2011; Cosgrove et al., 2019).

14  
15 Adaptive spatial management strategies have been proposed as a way of  
16 reducing discards (Holmes et al., 2011; Little et al., 2014; Dunn et al., 2014).  
17 Implementation of avoidance measures is, however, restricted by lack of knowl-  
18 edge of fish and fishery spatiotemporal dynamics and understanding of the scale  
19 at which processes become important for management. Understanding the cor-  
20 rect scale for spatial measures is crucial for implementing solutions at a reso-  
21 lution that ensures effective management (Dunn et al., 2016) while minimising  
22 economic impact. For example, the problem can be to identify a scale that  
23 promotes species avoidance for vulnerable or low quota species while allowing  
24 continuance of sustainable fisheries for available quota species.

25  
26 Identifying appropriate spatial scales for fisheries closures has been a chal-  
27 lenge in the past but identified as crucial to its success (Costello et al., 2010;  
28 Dunn et al., 2016). Further, poorly sited closures have led to ineffectual mea-  
29 sures with unintended consequences. For example, increased benthic impact on  
30 previously unexploited areas was observed from the cod closure in the North Sea  
31 with a lack of observed intended effect in reducing cod exploitation (Rijnsdorp  
32 et al., 2001; Dinmore et al., 2003)). More refined spatiotemporal information  
33 has since become available through the combination of logbook and Vessel Mon-  
34 itoring System (VMS) data (Lee et al., 2010; Bastardie et al., 2010; Gerritsen  
35 et al., 2012; Mateo et al., 2016) and more real-time spatial management has  
36 been possible (e.g. Holmes et al., 2011). Such information is, however, derived

37 from an inherently biased sampling programme, targeted fishing, where fishers  
38 establish favoured fishing grounds through an explore-exploit strategy (Bailey  
39 et al., 2018) where they search for areas with high catches and then use experi-  
40 ence to return to areas where they’ve experienced high catch in the past.

41

42 In order to understand the effect of spatiotemporal aggregation of data we  
43 ask two fundamental questions regarding inference derived from observational  
44 data:

- 45 1. How does sampling-derived fisheries data reflects the underlying commu-  
46 nity structure?
- 47 2. How does data aggregation and source impact on spatial fisheries man-  
48 agement measures?

49 To answer these questions we i) develop a simulation model where popula-  
50 tion dynamics are highly-resolved in space and time by use of a Gaussian spatial  
51 process to define suitable habitat. Precise locations being known directly rather  
52 than inferred from sampling or commercial catch, we can use the population  
53 model to validate how inference from fisheries-dependent and fisheries indepen-  
54 dent sampling relates to the real community structure in a way we could not  
55 with real data. We ii) compare, at different spatial and temporal aggregations,  
56 the ‘real population’ distributions to samples from fisheries-dependent and fish-  
57 eries independent catches to test if these are a true reflection of the relative  
58 density of the populations. We then iii) simulate a fishery closure to protect a  
59 species based on different spatial and temporal data aggregations. We use these  
60 evaluations to draw inference on the utility of commercial data in supporting  
61 management decisions.

62

## 63 2. Materials and Methods

64 A simulation model that is modular and discrete-event based was developed.  
65 This approach enables efficient computation by allowing for sub-modules imple-  
66 mented on time-scales appropriate to capture the characteristic of the different  
67 processes (Figure 1). The following sub-modules were included to capture the  
68 full system: 1) Population dynamics, 2) Recruitment dynamics, 3) Population  
69 movement, 4) fishery dynamics.

70  
71 Population dynamics (fishing and natural mortality which are instantaneous  
72 rates, growth of the population biomass) operate on a daily time-step, while  
73 population movement occurs on a weekly time-step. Recruitment takes place  
74 periodically each year for a set time duration specified for each population, while  
75 the fishing module operates on a tow-by-tow basis (i.e. multiple events a day).

76 Population movement is a combination of random (diffusive) movement,  
77 governed by a stochastic process where movement between adjacent cells is  
78 described by a set of probabilities, and directed (advective) movement where  
79 at certain times of year the population moves towards spawning grounds by  
80 increasing the probabilities of moving into the spawning grounds from adjacent  
81 cells. We incorporate characterisation of a number of different fishing fleet dy-  
82 namics exploiting four fish populations with different spatial and population  
83 demographics. The following describes the implementation of each of the sub-  
84 modules.

### 85 2.1. Population dynamics

86 The basic population level processes were simulated using a modified two-  
87 stage Deriso-Schnute delay difference model which models the fish populations in  
88 terms of aggregate biomass of recruits and mature components rather than keep-  
89 ing track of individuals (Deriso, 1980; Schnute, 1985; Dichmont et al., 2003). A  
90 daily time-step was chosen to discretise continuous population processes on a bi-  
91 ologically relevant and computationally tractable timescale. Population biomass

growth and depletion for pre-recruits and recruited fish were modelled separately as a function of previous recruited biomass, intrinsic population growth and recruitment functionally linked to the adult population size. Biomass for each cell  $c$  was incremented each day  $d$  as follows (the full parameter list is detailed in Table 1):

$$\begin{aligned}
B_{c,d+1} = & \\
& (1 + \rho)B_{c,d} \cdot e^{-Z_{c,d}} - \rho \cdot e^{-Z_{c,d}} \quad \times \\
& (B_{c,d-1} \cdot e^{-Z_{c,d-1}} + Wt_{R-1} \cdot \alpha_{d-1} \cdot R_{\tilde{y}(c,y,d-1)}) \quad + \\
& Wt_R \cdot \alpha_d \cdot R_{\tilde{y}(c,y,d)}
\end{aligned} \tag{1}$$

where  $\rho$  is Brody's coefficient, shown to be equal to  $e^{-K}$  when  $K$  is the growth rate from a von Bertalanffy logistic growth model (Schnute, 1985).  $Wt_{R-1}$  is the average weight of fish prior to recruitment, while  $Wt_R$  is the average recruited weight.  $\alpha_d$  represents the proportion of fish recruited during that day for the year, while  $R_{c,\tilde{y}}$  is the annual recruits in cell  $c$  for year  $y$ .

102

Mortality  $Z_{c,d}$  can be decomposed to natural mortality,  $M_{c,d}$ , and fishing mortality,  $F_{c,d}$ , where both  $M_{c,d}$  and  $F_{c,d}$  are instantaneous rates with  $M_{c,d}$  fixed and  $F_{c,d}$  calculated by solving the Baranov catch equation (Hilborn and Walters, 1992) for  $F_{c,d}$ :

$$C_{c,d} = \frac{F_{c,d}}{F_{c,d} + M_{c,d}} * (1 - e^{-(F_{c,d} + M_{c,d})}) \cdot B_{c,d} \tag{2}$$

where  $C_{c,d}$  is the summed catch from the fishing model across all fleets and vessels in cell  $c$  for the population during the day  $d$ , and  $B_{c,d}$  the daily biomass for the population in the cell. Here, catch and fishing mortality are the sum of those across all fleets and vessels, where  $F_{fl,v,c,d,p} = E_{fl,v,c,d} \cdot Q_{fl,p} \cdot D_{c,d,p}$  with  $fl$ ,  $v$  and  $p$  the fleet, vessel and population respectively and  $E$  and  $Q$  fishing effort and catchability of the gear, and  $D$  is the density of the population at the location fished.

114

## 115 2.2. Recruitment dynamics

116 Recruitment is modelled through a function relating the adult biomass to  
 117 recruits at time of recruitment. In *MixFishSim*, it can be modelled either either  
 118 as a stochastic Beverton-Holt stock-recruit form (Beverton and Holt, 1957):

$$\begin{aligned}\bar{R}_{c,d} &= \frac{(\alpha \cdot S_{c,d})}{(\beta + S_{c,d})} \\ R_{c,d} &\sim \log N[(\log(\bar{R}_{c,d}), \sigma^2)]\end{aligned}\tag{3}$$

119 Where  $\alpha$  is the maximum recruitment rate,  $\beta$  the spawning stock biomass (SSB)  
 120 required to produce half the maximum stock size,  $S$  current stock size and  $\sigma^2$   
 121 the variability in the recruitment due to stochastic processes, or a stochastic  
 122 Ricker form (Ricker, 1954):

$$\begin{aligned}\bar{R}_{c,d} &= B_{c,d} \cdot e^{(\alpha - \beta \cdot B_{c,d})} \\ R_{c,d} &\sim \log N[(\log(\bar{R}_{c,d}), \log(\sigma^2))]\end{aligned}\tag{4}$$

123 where  $\alpha$  is the maximum productivity per spawner and  $\beta$  the density dependent  
 124 reduction in productivity as the SSB increases. In our example application the  
 125 Beverton-Holt form of stock recruit relationship was used for all populations  
 126 though either functional form can be chosen.

## 127 2.3. Population movement dynamics

128 To simulate fish population distribution in space and time a Gaussian spatial  
 129 process was employed to model habitat suitability for each of the populations  
 130 on a 2d grid. JM: MENTION IN THE INTRODUCTION

131  
 132 We first defined a Gaussian random field process,  $\{S(c) : c \in \mathbb{R}^2\}$ , where  
 133 for any set of cells  $c_1, \dots, c_n$ , the joint distribution of  $S = \{S(c_1), \dots, S(c_n)\}$   
 134 is multivariate Gaussian with a *Matérn* covariance structure, where the corre-  
 135 lation strength weakens with distance. This enables us to model the spatial  
 136 autocorrelation observed in animal populations where density is more similar  
 137 in nearby locations (Tobler, 1970; F. Dormann et al., 2007) and we change the

parameters to implement different spatial structures for the populations.

139

The habitat for each of the populations was generated with the *RFSimulate* function of the *RandomFields* R package (Schlatter et al., 2015), that simulates a Gaussian Random Field process given a user defined error model and correlation structure. We define a stationary habitat field and combine with a temporally dynamic thermal tolerance field to imitate two key drivers of population dynamics. Each population was initialised at a single location, and subsequently moved according to a probabilistic distribution based on habitat suitability (represented by the normalised values from the GRFs), temperature and distance from current cell:

$$Pr(J|I) = \frac{e^{-\lambda * d_{IJ}} \cdot (Hab_{J,p}^2 \cdot Tol_{J,p,wk})}{\sum_{c=1}^C e^{-\lambda * d} \cdot (Hab_{c,p}^2 \cdot Tol_{c,p,wk})} \quad (5)$$

Where  $d_{IJ}$  is the euclidean distance between cell  $I$  and cell  $J$ ,  $\lambda$  is a given rate of decay,  $Hab_{J,p}^2$  is the squared index of habitat suitability for cell  $J$  and population  $p$ , with  $Tol_{J,p,wk}$  the temperature tolerance for cell  $J$  by population  $p$  in week  $wk$  (see below).

153

During pre-defined weeks of the year the habitat suitability is modified with user-defined spawning habitat locations, resulting in each population having concentrated areas where spawning takes place. In the simulations the populations move towards these cells in the weeks prior to spawning, resulting in directional movement towards the spawning grounds.

JM: WHAT ABOUT INDIVIDUAL INTERACTIONS:w

An advection-diffusion process controls population movement, with a time-varying temperature covariate used to change the interaction between time and suitable habitat on a weekly time-step. Each population  $p$  was assigned a thermal tolerance with mean,  $\mu_p$  and variance,  $\sigma_p^2$  so that each cell and population temperature suitability is defined that:

$$Tol_{c,p,wk} = \frac{1}{\sqrt{(2\pi \cdot \sigma_p^2)}} \cdot \exp\left(-\frac{(T_{c,wk} - \mu_p)^2}{2 \cdot \sigma_p^2}\right) \quad (6)$$



Where  $Tol_{c,p,wk}$  is the tolerance of population  $p$  for cell  $c$  in week  $wk$ ,  $T_{c,wk}$  is the temperature in the cell given the week and  $\mu_p$  and  $\sigma_p^2$  the mean and standard deviation of the population temperature tolerance.

The final process results in a population structure and movement pattern unique to each species, with population movement occurring on a weekly basis. The decision to model population movement on a weekly timescale was to reflect that fish tend to aggregate in species specific locations that have been observed to last around one to two weeks (Poos and Rijnsdorp, 2007b). Therefore this process approximated the demographic shifts in fish populations throughout a year with seasonal spawning patterns (e.g. Figure S5).

## 2.4. Fleet dynamics

The fleet dynamics can be broadly categorised into three components; fleet targeting - that determined the fleet catch efficiency and preference towards a particular species; trip-level decisions, that determined the initial location to be fished at the beginning of a trip; and within-trip decisions, that determined movement from one fishing spot to another within a trip. Together, these elements implemented an explore-exploit type strategy for individual vessels to maximise their catch from an unknown resource distribution Bailey et al. (2018). The decision to use an individual based model for fishing vessels was taken because fishers are heterogeneous in their location choice behaviour due to different objectives, risk preference and targeting preference (Van Putten et al., 2012). Therefore in the simulations fleet dynamics are the productive of individual experiences rather than pre-defined group dynamics.

### 2.4.1. Fleet targeting

Each fleet of  $n$  vessels was characterised by both a general efficiency,  $Q_{fl}$ , and a population specific efficiency,  $Q_{fl,p}$ . Thus, the product of these parameters  $[Q_{fl} \cdot Q_{fl,p}]$  affects the overall catch rates for the fleet and the preferential targeting of one population over another. This, in combination with the param-

194 eter choice for the step-function defined below (as well as some randomness from  
195 the exploratory fishing process) determined the preference of fishing locations  
196 for the fleet. All species prices were kept the same across fleets and seasons.

#### 197 *2.4.2. Trip-level decisions*

198 Several studies (e.g. Hutton et al., 2004; Tidd et al., 2012; Girardin et al.,  
199 2015) have confirmed past activity and past catch rates are strong predictors of  
200 fishing location choice. For this reason, the fleet dynamics sub-model included a  
201 learning component, where a vessel’s initial fishing location in a trip was based  
202 on selecting from previously successful fishing locations. This was achieved by  
203 calculating an expected revenue based on the catches from locations fished in  
204 the preceding trip as well as the same month periods in previous years and the  
205 travel costs from the port to the fishing grounds, and choosing randomly from  
206 the top 75 % of fishing events as defined by the expected profit, that has a  
207 seasonal component.

#### 208 *2.4.3. Within-trip decisions*

209 Fishing locations within a trip are initially determined by a modified ran-  
210 dom walk process. As the simulation progresses the within-trip decision become  
211 gradually more influenced by experience gained from past fishing locations (as  
212 per the initial trip-level location choice), moving location choice towards areas  
213 of higher perceived profit. A random walk was chosen for the exploratory fishing  
214 process as it is the simplest assumption commonly used in ecology to describe  
215 optimal animal search strategy for exploiting homogeneously distributed prey  
216 about which there is uncertain knowledge (Viswanathan et al., 1999). In a ran-  
217 dom walk, movement is a stochastic process through a series of steps. These  
218 steps have a length, and a direction that can either be equal in length or take  
219 some other functional form. The direction of the random walk was also cor-  
220 related (known as ‘persistence’) providing some overall directional movement  
221 (Codling et al., 2008).

222

223 We use a *Lévy flight* which is a particular form of random walk charac-  
 224 terised by a heavy-tailed distribution of step-length. The Lévy flight has re-  
 225 ceived a lot of attention in ecological theory in recent years as having shown to  
 226 have very similar characteristics as those observed by animals in nature, and  
 227 being a near optimum searching strategy for predators pursuing patchily dis-  
 228 tributed prey (Viswanathan et al., 1999; Bartumeus et al., 2005; Sims et al.,  
 229 2008). Bertrand et al. (2007) showed that Peruvian anchovy fishermen have a  
 230 stochastic search pattern similar to that observed with a lévy flight. However,  
 231 it remains a subject of debate (e.g. see Edwards et al., 2011; Reynolds, 2015),  
 232 with the contention that search patterns may be more simply characterised as  
 233 random walks (Sakiyama and Gunji, 2013) with specific patterns related to the  
 234 characteristics of the prey field (Sims et al., 2012).

235  
 236 For our implementation of a random walk directional change is based on  
 237 a negatively correlated circular distribution where a favourable fishing ground  
 238 is likely to be “fished back over” by the vessel returning in the direction it  
 239 came from. The step length (i.e. the distance travelled from the current to the  
 240 next fishing location) is determined by recent fishing success, measured as the  
 241 summed value of fish caught (revenue,  $Rev$ ),

$$Rev = \sum_{p=1}^P L_p \cdot Pr_p \quad (7)$$

242 where  $L_p$  is landings of a population  $p$ , and  $Pr_p$  price of a population. Here,  
 243 when fishing is successful vessels remain in a similar location and continue to  
 244 exploit the local fishing grounds. When unsuccessful, they move some distance  
 245 away from the current fishing location. The movement distance retains some  
 246 degree of stochasticity, that can be controlled separately, but is determined by  
 247 the relationship:

$$StepL = e^{\log(\beta_1) + \log(\beta_2) - (\log(\frac{\beta_1}{\beta_3}))} * Rev \quad (8)$$

248 Where  $\beta_1$ ,  $\beta_2$  and  $\beta_3$  are parameters determining the shape of the step function

249 in its relation to revenue, so that, a step from (x1,y1) to (x2, y2) is defined by:

$$\begin{aligned}
 (x2, y2) = & x1 + StepL \cdot \cos\left(\frac{\pi \cdot Br}{180}\right), \\
 & y1 + StepL \cdot \sin\left(\frac{\pi \cdot Br}{180}\right) \\
 \text{with } & Br_{t-1} < 180, Br_t = 180 + \sim vm[(0, 360), k] \\
 & Br_{t-1} > 180, Br_t = 180 - \sim vm[(0, 360), k]
 \end{aligned} \tag{9}$$

250 where  $k$  the concentration parameter from the von Mises distribution that we  
 251 correlate with the revenue so that  $k = (Rev + 1/RefRev) * max_k$ , where  $max_k$   
 252 is the maximum concentration value,  $k$ , and  $RefRev$  is parametrised as for  $\beta_3$   
 253 in the step length function. A realised example of the step length and turning  
 254 angle relationships to revenue can be seen at Figure S12.

#### 255 2.4.4. Local population depletion

256 Where several fishing vessels exploit the same fish population competition  
 257 is known to play an important role in local distribution of fishing effort (Gillis  
 258 and Peterman, 1998). If several vessels are fishing on the same patch of fish,  
 259 local depletion and interference competition will affect fishing location choice  
 260 of the fleet as a whole (Rijnsdorp, 2000; Poos and Rijnsdorp, 2007a). In order  
 261 to account for this behaviour, the fishing sub-model operates spatially on a  
 262 daily time-step so that for future days the biomass available to the fishery is  
 263 reduced in the areas fished. The cumulative effect is to make heavily fished  
 264 areas less attractive as a future fishing location choice as reduced catch rates  
 265 will be experienced. JM: INTERFERENCE COMPETITION COULD ALSO  
 266 BE REPRESENTED BY A LIMITATION FACTOR

#### 267 2.5. Fisheries independent survey

268 A fisheries-independent survey is simulated where fishing on a regular grid  
 269 begins each year at the same time for a given number of stations (a fixed station  
 270 survey design). Catches of the populations at each station are recorded but not  
 271 removed from the population (catches are assumed to have negligible impact  
 272 on population dynamics). This provides a fishery independent snapshot of the

273 populations at a regular spatial intervals each year, similar to scientific surveys  
274 undertaken by fisheries research agencies.

275

## 276 *2.6. Software: R-package development*

277 The simulation framework is implemented in the statistical software package  
278 R (R Core Team, 2017) and available as an R package from the authors github  
279 site ([www.github.com/pdolder/MixFishSim](https://www.github.com/pdolder/MixFishSim)).

280

## 281 **3. Parameterisation**

### 282 *3.1. Population models*

283 We parametrised the simulation model for four populations with different  
284 demographics; growth rates, natural mortality and recruitment functions (Ta-  
285 ble 4). Habitat preference (Figure S1) and temperature tolerances (Figures S3,  
286 S4) were defined to be unique to each population resulting in differently weekly  
287 distribution patterns (Figures S5-S7). In addition, each of the populations was  
288 assumed to have two defined spawning areas that result in the populations mov-  
289 ing towards these areas in pre-defined weeks (Figure S2) with population-specific  
290 movement rates (Table 4). In such a configuration, the individual habitat pref-  
291 erences and thermal tolerances result in different spatial habitat use for each  
292 population (Figure 2) and consequently different seasonal exploitation patterns  
293 (Fishing mortality in Figure 3).

### 294 *3.2. Fleet parametrisation*

295 The fleets were parametrised to reflect five different characteristic fisheries  
296 with unique exploitation dynamics (Table 5). By setting different catchability  
297 parameters ( $Q_{fl,p}$ ) we create different targeting preferences between the fleets  
298 and hence spatial dynamics. The random walk process implies that within a  
299 fleet different vessels have different spatial distributions based on individual

300 experience. The step function was parametrised dynamically within the simu-  
 301 lations as the maximum revenue obtainable was not known beforehand. This  
 302 was implemented so that vessels take smaller steps when fishing at a location  
 303 that yields landings value in the top 90th percentile of the value experienced in  
 304 that year so far (as defined per fleet in Table 5).

305

306 With increasing probability throughout the simulation, fishing locations were  
 307 chosen based on experience of profitable catches built up in the same month from  
 308 previous years and from the previous trip. 'Profitable' in this context was de-  
 309 fined as the locations where the top 70 % of expected profit would be found  
 310 given revenue from previous trips and cost of movement to the new fishing lo-  
 311 cation. This probability was based on a logistic sigmoid function with a lower  
 312 asymptote of 0 and upper asymptote of 0.95, and a growth rate that ensures  
 313 the upper asymptote (where decisions are mainly based on past knowledge) is  
 314 reached approximately halfway through the simulation.

315

### 316 3.3. *Survey settings*

317 The survey simulation was set up with a fixed gridded station design with  
 318 100 stations fished each year, starting on day 92 and ending on day 112 (5  
 319 stations per day) with same catchability parameters for all populations ( $Q_p =$   
 320 1). This approximates a real world survey design with limited seasonal and  
 321 spatial coverage.

### 322 3.4. *Example research question*

323 To illustrate the capabilities of *MixFishSim*, we investigate the influence of  
 324 the temporal and spatial resolution of different data sources on the reduction in  
 325 catches of a population given spatial closures. To do so, we set up a simulation  
 326 to run for 50 years based on a  $100 \times 100$  square grid (undetermined units), with  
 327 five fleets of 20 vessels each and four fish populations. Fishing takes place four

328 times a day per vessel and five days a week, while population movement is every  
329 week.

330 We allow the simulation to run unrestricted for 30 years, then implement  
331 spatial closed areas for the last 20 years of the simulation based on data (either  
332 derived from the commercial catches, fisheries-independent survey or the 'real  
333 population') used at different spatial and temporal scales.

334  
335 The following steps are undertaken to determine closures:

- 336 1. Extract data source
- 337 2. Aggregate according to desired spatial and temporal resolution
- 338 3. Interpolate across entire area at desired resolution using simple bivariate  
339 kriging using the *interp* function from the R package *akima* (Akima, 2006).  
340 This is intended to represent a naive spatial model of catch rates, without  
341 knowledge of the spatial population dynamics.
- 342 4. Close area covering top 5 % of catch rates

343 In total 28 closure scenarios were run that represent combinations of:

- 344 • **data types:** commercial logbook data, survey data and 'real population',
- 345 • **temporal resolutions:** weekly, monthly and yearly closures,
- 346 • **spatial resolutions:** 1 x 1 grid, 5 x 5 grid, 10 x 10 grid and 20 x 20 grid,
- 347 • **closure basis:** highest 5 % of catch rates for the protected species

348 Survey closures were on an annual basis only, as this was the most temporally  
349 resolved survey data available.

## 350 4. Results

### 351 4.1. Simulation dynamics

It can be seen from a single vessels movements during a trip that the vessel exploits four different fishing grounds, three of them multiple times (Figure S9),

while across several trips fishing grounds that are further apart are fished (Figure S10). These different locations relate to areas where the highest revenue were experienced, as shown by Figure 4, where several trips for the vessel overlaid on the revenue field, i.e.

$$\sum_{c=1}^c \sum_{s=1}^s B_{s,c} \cdot Q_{s,c}$$

352 Vessels from the same fleet (and therefore targeting preference) may exploit  
 353 some shared and some different fishing grounds depending on their own personal  
 354 experience during the explore phase of the fishery (Figure S11). This results  
 355 from the randomness in the correlated random walk step function, with distance  
 356 moved during the exploitation phase and the direction stochastically related to  
 357 the revenue experienced on the fishing ground (Figure S12).

#### 358 *4.2. How does sampling-derived fisheries data reflect the underlying population* 359 *structure?*

360 In order to answer this question we compare different spatial and temporal  
 361 aggregations of the 'real population' distributions to:

- 362 a) **fisheries-independent data:** the inferred population from a fixed-site  
 363 sampling survey design as commonly used for fisheries monitoring pur-  
 364 poses;
- 365 b) **fisheries-dependent data:** the inferred population from our fleet model  
 366 that includes fishery-induced sampling dynamics.

367 Figure 5 shows the aggregated catch composition from each of the data  
 368 sources over a ten-year period (to average seasonal patterns) at different spa-  
 369 tial resolutions. The finer spatial grid for the real population (top left) and  
 370 commercial data (top middle) show visually similar patterns, though there are  
 371 large unsampled areas in the commercial data from a lack of fishing activity  
 372 (particularly in the lower left part of the sampling domain). The survey data at  
 373 this spatial resolution displays very sparse information about the spatial distri-  
 374 butions of the populations. The slightly aggregated data on a 5 x 5 grid shows



375 similar patterns and, while losing some of the spatial detail, there remains good  
 376 consistency between the 'real population' and the commercial data. Survey data  
 377 starts to pick out some of the similar patterns as the other data sources, but  
 378 lacks spatiotemporal coverage. The spatial catch information on a 10 x 10 and  
 379 20 x 20 grid lose a significant amount of information about the spatial resolu-  
 380 tions for all data sources, and some differences between the survey, commercial  
 381 and 'real population' data emerge.

382  
 383 Figure 6 shows the consequences of different temporal aggregations of the  
 384 data over a ten-year period, with weekly (top), monthly (middle) and yearly  
 385 (bottom) catch compositions from across an aggregated 20 x 20 area. By com-  
 386 parison to the 'real population', the monthly aggregation captures the major  
 387 patterns seen in the weekly data, albeit missing more subtle differences. The  
 388 yearly data assumes the same proportion of each population caught at any time  
 389 of the year due to the data aggregation. This assumption introduces 'aggrega-  
 390 tion bias' as the data may only be representative of some point (or no point) in  
 391 time. The commercial data on a weekly basis shows some of the same patterns  
 392 as the 'real population', though the first species (in red) is less well represented  
 393 and some weeks are missing catches from the area. The monthly data shows  
 394 some consistency between the 'real population' and commercial data for species  
 395 2 - 4, though species 1 remains under-represented. On an annual basis, inter-  
 396 estingly the commercial data under represents the first species (in red) while  
 397 the survey over represents species 1. This is likely due to the biases in com-  
 398 mercial sampling, with the fisheries not targeting the areas where species 1 are  
 399 present and the survey sampling areas where species 1 is more abundant than  
 400 on average.

#### 401 *4.3. How does data aggregation and source impact on spatial fisheries manage-* 402 *ment measures?*

403 We implemented a spatial closure using the different data sources and spatial  
 404 and temporal aggregations as outlined in the protocol in Section 3.4. We used

405 this to assess the efficacy of a closure in reducing fishing mortality on species 3,  
406 given availability of data and its use at different resolutions in order to evaluate  
407 the trade-offs in data sources.

408 The trend in fishing mortality for each species show that in most cases the  
409 fishery closure was successful in reducing fishing mortality on the species of in-  
410 terest (species 3; Figure 7), though interestingly the largest reductions in fishing  
411 mortality happened immediately after the closures, following which the fisheries  
412 "adapted" to the closures and fishing mortality increased again somewhat. The  
413 exception to the success was the closures implemented based on the coarsest  
414 spatial (20 x 20) and temporal resolution (yearly) that was ineffective with all  
415 data sources. As expected, closures based on the "known" population distribu-  
416 tion were most effective, with differing degrees of success using the commercial  
417 data. Fishing mortality rates on the other species changed in different propor-  
418 tions, depending on whether the displaced fishing effort moved to areas where  
419 the populations were found in greater or lesser density.

420

421 A regression tree (using the R package REEMtree (Sela and Simonoff, 2012))  
422 highlights that the factor most contributing to differences in fishing mortality  
423 before and after the closure was the population (72 % showing that the closures  
424 were effective for population 3), followed by data resolution (21 %), data type  
425 (7 %) with the least important factor the timescale ( $< 1$  %). In general the finer  
426 the spatial resolution of the data used the greater reduction in fishing mortality  
427 for population 3 after the closures (Figure 8). The notable outliers are the com-  
428 mercial data at the coarsest spatial resolution (20 x 20) at a yearly and weekly  
429 timescale, where closures were nearly as effective as the fine-scale resolution. In  
430 this case the closures were sufficiently large to protect a core area of the habitat  
431 for the population, but this was achieved in a fairly crude manner by closing a  
432 large area - including area where the species was not found (Figure 9) that may  
433 have consequences in terms of restricting the fishery in a much larger area than  
434 necessary.

435

## 436 5. Discussion

437 Our study evaluates the importance of data scaling and considers poten-  
438 tial bias introduced through data aggregation when using fisheries data to infer  
439 spatiotemporal dynamics of fish populations. Understanding how fishers ex-  
440 ploit multiple heterogeneously distributed fish populations with different catch  
441 limits or conservation status requires detailed understanding of the overlap of  
442 resources; this is difficult to achieve using conventional modelling approaches  
443 due to species targeting in fisheries resulting in preferential sampling (Martínez-  
444 Minaya et al., 2018). Often data are aggregated or extrapolated which requires  
445 assumptions about the spatial and temporal scale of processes. Our study ex-  
446 plores the assumptions behind such aggregation and preferential sampling to  
447 identify potential impacts on management advice. With modern management  
448 approaches increasingly employing more nuanced spatiotemporal approaches in  
449 order to maximise productivity while taking account of both the biological and  
450 human processes operating on different time-frames (Dunn et al., 2016), un-  
451 derstanding assumptions behind the data used - increasingly a combination of  
452 logbook and positional information from vessel monitoring systems - is vital to  
453 ensure measures are effective.

### 454 5.1. *Simulation dynamics*

456 We employ a simulation approach to model each of the population and fish-  
457 ery dynamics in a hypothetical 'mixed fishery', allowing us to i) evaluate the  
458 consequences of different aggregation assumptions on our understanding of the  
459 spatiotemporal distribution of the underlying fish populations, and ii) evaluate  
460 the effectiveness of a spatial closure given those assumptions.

462 Our approach is unique in that it captures fine scale population and fish-  
463 ery dynamics and their interaction in a way not usually possible with real data  
464 and thus not usually considered in fisheries simulations. While other simulation

frameworks seek to model individual vessel dynamics based on inferred dynamics from VMS and logbook records (Bastardie et al., 2010), or as a system to identify measures to meet particular management goals (Bailey et al., 2018), our framework allows users to explore the assumptions in modelling observational data and evaluate the underlying dynamics of such approaches at a fine spatial and temporal scale. This offers the advantage that larger scale fishery patterns are emergent properties of the system and results can be compared to those obtained under a statistical modelling framework.

Typically, simulation models that treat fish as individuals are focussed on exploring the inter- and intra- specific interactions among fish populations (e.g. OSMOSE Shin et al. (2004)) in order to understand how they vary over space and time. Our focus was on understanding the strengths and limitations of inference from catch data obtained through commercial fishing activity with fleets exploiting multiple fish populations and realising catch distributions that may differ from the underlying populations. As such, we favoured a minimum realistic model of the fish populations (Plagányi et al., 2014) taking account of environmental but not demographic stochasticity, while incorporating detailed fishing dynamics that take account of different drivers in a mechanistic way.

Demographic stochasticity arises due to individual-level variability in time to reproduction and death. This form of stochasticity is often modelled by drawing random time intervals from a given distribution (Gillespie, 1977). The impact of demographic stochasticity depends on the population size, with the effects expected to decrease with increasing population size (Lande et al., 2010). This contrasts with environmental stochasticity, which affects all population sizes and is present at the population level in our model by variability in recruitment.

We take account of heterogeneity in fleet dynamics due to different preferences and drivers similarly to other approaches (Fulton et al., 2011), but at an individual vessel rather than fleet level. We do not explicitly define fleets as

496 rational profit maximisers at the outset, but consider there are several stages  
497 to development of the fishery; information gathering through search where the  
498 resource location is not known, followed by individual learnt behaviour of prof-  
499 itable locations. This provides a realistic model of how fishing patterns are  
500 established and maintained to exploit an uncertain resource through an explore-  
501 exploit strategy (Mangel and Clark, 1983; Bailey et al., 2018).

502 *5.2. How does sampling-derived fisheries data reflect the underlying population*  
503 *structure?*

504 Our results demonstrate the importance of considering data scale and resolu-  
505 tion when using observational data to support management measures. We find  
506 that understanding of the community composition dynamics will depend on the  
507 level of data aggregation and its important to consider the scale of processes;  
508 including population movement rates, habitat uniformity and fishing targeting  
509 practices if potential biases in data are to be understood and taken into account.

510  
511 Our simulation shows that, despite biases introduced through the fishing  
512 process, the commercially derived data could still inform on the key spatial  
513 patterns in the community structures where the fisheries occurred, which was  
514 spatially limited due to the “hotspots” of commercially valuable species be-  
515 ing fished. Similarly, despite the even spatial coverage the survey was able to  
516 capture some of the same spatial patterns as the ‘real population’, but missed  
517 others due to gaps between survey stations limiting spatial and temporal cov-  
518 erage. This provides a challenge when modelling unsampled areas in inferring  
519 species distribution maps, though these limitations may be overcome by un-  
520 derstanding the relationship between the species and habitat covariates where  
521 these are known at unsampled locations (Robinson et al., 2011).

522

523 *5.3. How does data aggregation and source impact on spatial fisheries manage-*  
524 *ment measures?*

525 From our simulations spatial disaggregation was more important than the  
526 temporal disaggregation of the commercial data. This reflects the fact that there  
527 was greater spatial heterogeneity over the spatial domain than experienced in  
528 individual locations over the course of the year (Figure 2). This indicates that  
529 fixed closures, at the right resolution, when based on commercially derived data  
530 have the potential to reduced fishing mortality. The likely cost of poor spatial  
531 and temporal resolution is associated with reduced effectiveness and potentially  
532 closing fishing opportunities for other fisheries.

533  
534 Two contrasting real world approaches in this respect were the spatial clo-  
535 sures to protect cod in the North Sea. In one example, large scale spatial closures  
536 were implemented with little success due to effort displacement to previously  
537 unfished areas (Dinmore et al., 2003), while in another small scale targeted  
538 spatiotemporal closures were considered to have some effect in reducing cod  
539 mortality without having to disrupt other fisheries significantly (Needle and  
540 Catarino, 2011). These examples emphasise the importance of considering the  
541 right scale and aggregation of data when identifying area closures and the need  
542 to consider changing dynamics in the fisheries in response to such closures.

543  
544 Our study showed that fishing rates on other populations also changed (both  
545 up and down) as a side-effect of closures to protect one species. This indicates  
546 the importance in considering fishing effort reallocation following spatial clo-  
547 sures, and our simulation allows us to consider the spatiotemporal reasons for  
548 these changes.

549 *5.4. Model assumptions and caveats*

550 We model the population and fleet dynamic processes to draw inference on  
551 the importance of data scale and aggregation in understanding and managing  
552 mixed fisheries and their impact on multiple fish populations. In doing so, we

553 have necessarily had to make a number of simplifying assumptions.

554

555 Fish populations in our simulations move in pre-defined timescales and ac-  
556 cording to fixed habitat preferences and temperature gradients (Figures S1, S3).  
557 Our assumptions in parametrising the model (movement rates, temperature tol-  
558 erances) will have a direct impact on our conclusions on the relative importance  
559 of spatial and temporal processes. These assumptions could be explored in a  
560 future study by varying the parameters and assessing the robustness of our con-  
561 clusions. For our example application we have chosen movement rates to reflect  
562 aggregation periods observed in past studies (Poos and Rijnsdorp, 2007b).

563

564 In addition, we have assumed that fishing vessels are not restricted by quota  
565 and therefore discarding of species for which vessels have no quota or that are  
566 unwanted is not taken into account. This is likely to be a significant source of  
567 bias in any inference using commercial data and should also be explored. For  
568 example, MixFishSim could be altered to allow for spatiotemporal appraisal of  
569 the impact of discarding on fisher behaviour and underlying populations via in-  
570 clusion as discarding behaviour, or through move-on rules or cessation of fishing  
571 activity when quota is exhausted.

572

### 573 5.5. Future applications of MixFishSim

574 We consider that the increased availability of high resolution catch and lo-  
575 cational information from commercial fisheries will require it to be a key source  
576 of data for ensuring management is implemented at the right scale in future.  
577 For example, identifying hot-spots for bycatch reduction or identifying spatial  
578 overlaps in mixed fisheries (Dolder et al., 2018; Gardner et al., 2008; Little et al.,  
579 2014; Dedman et al., 2015; Ward et al., 2015). Our simulation model has the  
580 potential to test some of the assumptions behind the modelling approaches in  
581 identifying such hotspots and indeed behind spatiotemporal modelling in gen-  
582 eral (e.g. comparing GAMs, GLMMs, Random Forests and geostatistical mod-

583 els under different data generation processes as exemplified by Stock et al. (2019)).

584

585 Other novel applications of our framework could be; testing different sur-  
586 vey designs given multiple species and data generating assumptions (Xu et al.,  
587 2015); commercial index standardisation methods and approaches and under-  
588 standing of appropriate scales and data aggregations and non-proportionality  
589 in catch rate and abundance (Harley et al., 2001; Maunder and Punt, 2004);  
590 exploring assumptions about the distribution of natural mortality and fishing  
591 mortality throughout the year and importance of capturing in-year dynamics  
592 in estimating stock status (Liu and Heino, 2013); at sea sampling scheme de-  
593 signs to deliver unbiased estimates of population parameters Cotter and Pilling  
594 (2007); Kimura and Somerton (2006); adaptive management (Walters, 2007;  
595 Dunn et al., 2016); testing the ability of commonly employed fleet dynamics  
596 models such as Random Utility Models to capture fine scale dynamics and un-  
597 derstand their importance Girardin et al. (2016); and as a detailed operating  
598 model in a management strategy evaluation Mahévas and Pelletier (2004).

599

## 600 6. Conclusions

601 MixFishSim provides a detailed simulation framework to explore the inter-  
602 action of multiple fisheries exploiting different fish populations. The framework  
603 enables users to evaluate assumptions in modelling commercially derived data  
604 through comparison to the true underlying dynamics at a fine spatial and tem-  
605 poral scale. Understanding these dynamics, the limitations of the data and any  
606 potential biases that may be introduced when making inference on spatiotempo-  
607 ral interactions will enable users to identify weaknesses in modelling approaches  
608 and identify where data collection is needed to strengthen inference.

609

610 Our application shows that inference on community dynamics may change  
611 depending on the scale of data aggregation. There is an important balance in



612 ensuring that the data are sufficiently spatially and temporally disaggregated  
613 that the main features of the data are captured, yet maintaining enough data  
614 coverage that the features can be distinguished. We found in our application  
615 that there was greater spatial heterogeneity than temporal heterogeneity and  
616 that when using aggregated data to define spatial closures coarser temporal reso-  
617 lution (months instead of weeks) could still achieve the same results in reducing  
618 exploitation rates of a vulnerable species at the highest temporal resolution  
619 data. Conversely, reducing the spatial resolution had a negative effect on the  
620 effectiveness of the measures (though importantly, there was still some benefit  
621 even with coarse spatial resolution).

622

623 While any findings are likely to be case specific, our findings emphasise the  
624 need to understand population demographics, habitat use and movement rates  
625 in designing any closure scenario based on observational sampling. This infor-  
626 mation can then be used to set the bounds on data aggregation used in modelling  
627 studies aimed at informing the management measures.

628

629 MixFishSim has numerous potential additional applications as it enables  
630 the user to apply methods to a fisheries system where there is detailed under-  
631 standing of underlying spatiotemporal dynamics. This enables identification of  
632 weaknesses or limitations which would not be possible otherwise. In future, we  
633 recommend use of the framework to test hypothesis that are otherwise unable  
634 to be analysed using real world data due to limitations of data collection. That  
635 way the knowledge gained through simulation can inform the future design of  
636 management measures.

## 637 **Abbreviations**

638 Detail any unusual ones used.

## **639 Acknowledgements**

640 those providing help during the research..

## **641 Funding**

642 This work was supported by the MARES doctoral training program (MARES\_14\_15)  
643 and the Centre for Environment, Fisheries and Aquaculture Science seedcorn  
644 program (DP227AC).

## **645 Appendices**

Table 1: Description of variables for population dynamics sub-module

Variable	Meaning	Units
<b>Population dynamics</b>		
<i>Delay-difference model</i>		
$B_{c,d}$	Biomass in cell $c$ and day $d$	kg
$Z_{c,d}$	Total mortality in cell $c$ for day $d$	-
$R_{c,\bar{y}}$	Annually recruited fish in cell	yr <sup>-1</sup>
$\rho$	Brody's growth coefficient	yr <sup>-1</sup>
$Wt_R$	Weight of a fully recruited fish	kg
$Wt_{R-1}$	Weight of a pre-recruit fish	kg
$\alpha_d$	Proportion of annually recruited fish recruited during day $d$	-
<i>Baranov catch equation</i>		
$C_{c,d}$	Catch from cell $c$ for day $d$	kg
$F_{c,d}$	Instantaneous rate of fishing mortality in cell $c$ on day $d$	-
$M_{c,d}$	Instantaneous rate of natural mortality in cell $c$ on day $d$	-
$B_{c,d}$	Biomass in cell $c$ on day $d$	kg
<b>Recruitment dynamics</b>		
$\tilde{R}_{c,d}$	is the recruitment in cell $c$ for day $d$	$d^{-1}$
$S_{c,d}$	is the stock size in cell $c$ for day $d$	$d^{-1}$
$\alpha$	the maximum recruitment rate	kg
$\beta$	the stock size required to produce half the maximum rate of recruitment	kg

Table 2: Description of variables for population movement sub-module

Variable	Meaning	Units
<b>Population movement dynamics</b>		
<i>Habitat model</i>		
a	b	c
<i>Thermal tolerance</i>		
$T_{c,wk}$	Temperature for cell in week	°C
$\mu_p$	Mean of the thermal tolerance for population	°C
$\sigma_p^2$	Standard deviation of thermal tolerance for the population	°C
<i>Population movement model</i>		
$\lambda$	decay rate for population movement	-
$Hab_{c,p}^2$	Square of habitat suitability for cell $c$ and population $p$	-
$Tol_{c,p,wk}$	Thermal tolerance for population $p$ in cell $c$ at week $wk$	-
$d_{IJ}$	euclidean distance between cell $I$ and cell $J$	-

Table 3: Description of variables for fleet dynamics sub-module

Variable	Meaning	Units
<b>Short-term fleet dynamics</b>		
$Rev$	Revenue from fishing tow	€
$L_p$	Landings of population $p$	kg
$Pr_p$	Average price of population $p$	€ kg <sup>-1</sup>
StepL	Step length for vessel	euclidean distance
Br	Bearing	degrees
$k$	Concentration parameter for Von mises distribution	-
$\beta_1$	shape parameter for step function	-
$\beta_2$	shape parameter for step function	-
$\beta_3$	shape parameter for step function	-

Table 4: Population dynamics and movement parameter setting

Parameter	Pop 1	Pop 2	Pop 3	Pop 4
Habitat quality				
Matérn $\nu$	1/0.015	1/0.05	1/0.01	1/0.005
Matérn $\kappa$	1	2	1	1
Anisotropy	1.5,3,-3,4	1,2,-1,2	2.5,1,-1,2	0.1,2,-1,0.2
Spawning areas (bound box)	40,50,40,50; 80,90,60,70	50,60,30,40; 80,90,90,90	30,34,10,20; 60,70,20,30	50,55,80,85; 30,40,30,40
Spawning multiplier	10	10	10	10
Movement $\lambda$	0.1	0.1	0.1	0.1
Population dynamics				
Starting Biomass	1e5	2e5	1e5	1e4
Beverton-Holt Recruit 'a'	6	27	18	0.3
Beverton-Holt Recruit 'b'	4	4	11	0.5
Beverton-Holt Recruit $\sigma^2$	0.7	0.6	0.7	0.6
Recruit week	13-16	12-16	14-16	16-20
Spawn week	16-18	16-19	16-18	18-20
$K$	0.3	0.3	0.3	0.3
$wt$	1	1	1	1
$wt_{d-1}$	0.1	0.1	0.1	0.1
M (annual)	0.2	0.1	0.2	0.1
Movement dynamics				
$\mu$	12	15	17	14
$\sigma^2$	8	9	7	10

Table 5: Fleet dynamics parameter setting

Parameter	Fleet	Fleet	Fleet	Fleet	Fleet
	1	2	3	4	5
Targeting preferences	pop	pop	-	pop 4	pop
	2/4	1/3			2/3
Price Pop1	100	100	100	100	100
Price Pop2	200	200	200	200	200
Price Pop3	350	350	350	350	350
Price Pop4	600	600	600	600	600
$Q$ Pop1	0.01	0.02	0.02	0.01	0.01
$Q$ Pop2	0.02	0.01	0.02	0.01	0.03
$Q$ Pop3	0.01	0.02	0.02	0.01	0.02
$Q$ Pop4	0.02	0.01	0.02	0.05	0.01
Exploitation dynamics					
step function $\beta_1$	1	2	1	2	3
step function $\beta_2$	10	15	8	12	7
step function $\beta_3$	Q90	Q90	Q85	Q90	Q80
step function $rate$	20	30	25	35	20
Past Knowledge	T	T	T	T	T
Past Year & Month	T	T	T	T	T
Past Trip	T	T	T	T	T
Threshold	0.7	0.7	0.7	0.7	0.7
Fuel Cost	3	2	5	2	1

Table 6: Fishing mortality effects of the closure scenarios. Results show the fishing mortality before the closure (f.before) and after the closure (f.after) and the percentage change in f (f.change). The results are ordered by most effective scenario first, least effective last.)

scenario	metric	pop	f.before	f.after	f.change	timescale	basis	data_type	resolution
9	F	spp_3	1.08	0.29	-73.47	weekly	high_pop	real_pop	1.00
10	F	spp_3	1.08	0.29	-72.94	monthly	high_pop	real_pop	1.00
11	F	spp_3	1.08	0.35	-68.04	yearly	high_pop	real_pop	1.00
45	F	spp_3	1.08	0.58	-46.70	yearly	high_pop	commercial	20.00
1	F	spp_3	1.08	0.58	-46.21	weekly	high_pop	commercial	1.00
23	F	spp_3	1.08	0.59	-45.27	weekly	high_pop	real_pop	5.00
2	F	spp_3	1.08	0.59	-45.06	monthly	high_pop	commercial	1.00
7	F	spp_3	1.08	0.60	-44.48	yearly	high_pop	survey	1.00
24	F	spp_3	1.08	0.61	-43.20	monthly	high_pop	real_pop	5.00
3	F	spp_3	1.08	0.64	-40.82	yearly	high_pop	commercial	1.00
25	F	spp_3	1.08	0.65	-39.94	yearly	high_pop	real_pop	5.00
17	F	spp_3	1.08	0.67	-38.11	yearly	high_pop	commercial	5.00
15	F	spp_3	1.08	0.71	-34.38	weekly	high_pop	commercial	5.00
43	F	spp_3	1.08	0.71	-34.31	weekly	high_pop	commercial	20.00
16	F	spp_3	1.08	0.73	-32.58	monthly	high_pop	commercial	5.00
51	F	spp_3	1.08	0.78	-27.92	weekly	high_pop	real_pop	20.00
37	F	spp_3	1.08	0.78	-27.76	weekly	high_pop	real_pop	10.00
39	F	spp_3	1.08	0.79	-26.98	yearly	high_pop	real_pop	10.00
38	F	spp_3	1.08	0.81	-25.47	monthly	high_pop	real_pop	10.00
21	F	spp_3	1.08	0.81	-25.21	yearly	high_pop	survey	5.00
35	F	spp_3	1.08	0.81	-25.05	yearly	high_pop	survey	10.00
44	F	spp_3	1.08	0.87	-19.91	monthly	high_pop	commercial	20.00
52	F	spp_3	1.08	0.88	-18.39	monthly	high_pop	real_pop	20.00
30	F	spp_3	1.08	0.96	-11.06	monthly	high_pop	commercial	10.00
29	F	spp_3	1.08	0.98	-9.80	weekly	high_pop	commercial	10.00
31	F	spp_3	1.08	1.03	-4.36	yearly	high_pop	commercial	10.00
53	F	spp_3	1.08	1.06	-1.64	yearly	high_pop	real_pop	20.00
49	F	spp_3	1.08	1.07	-1.01	yearly	high_pop	survey	20.00



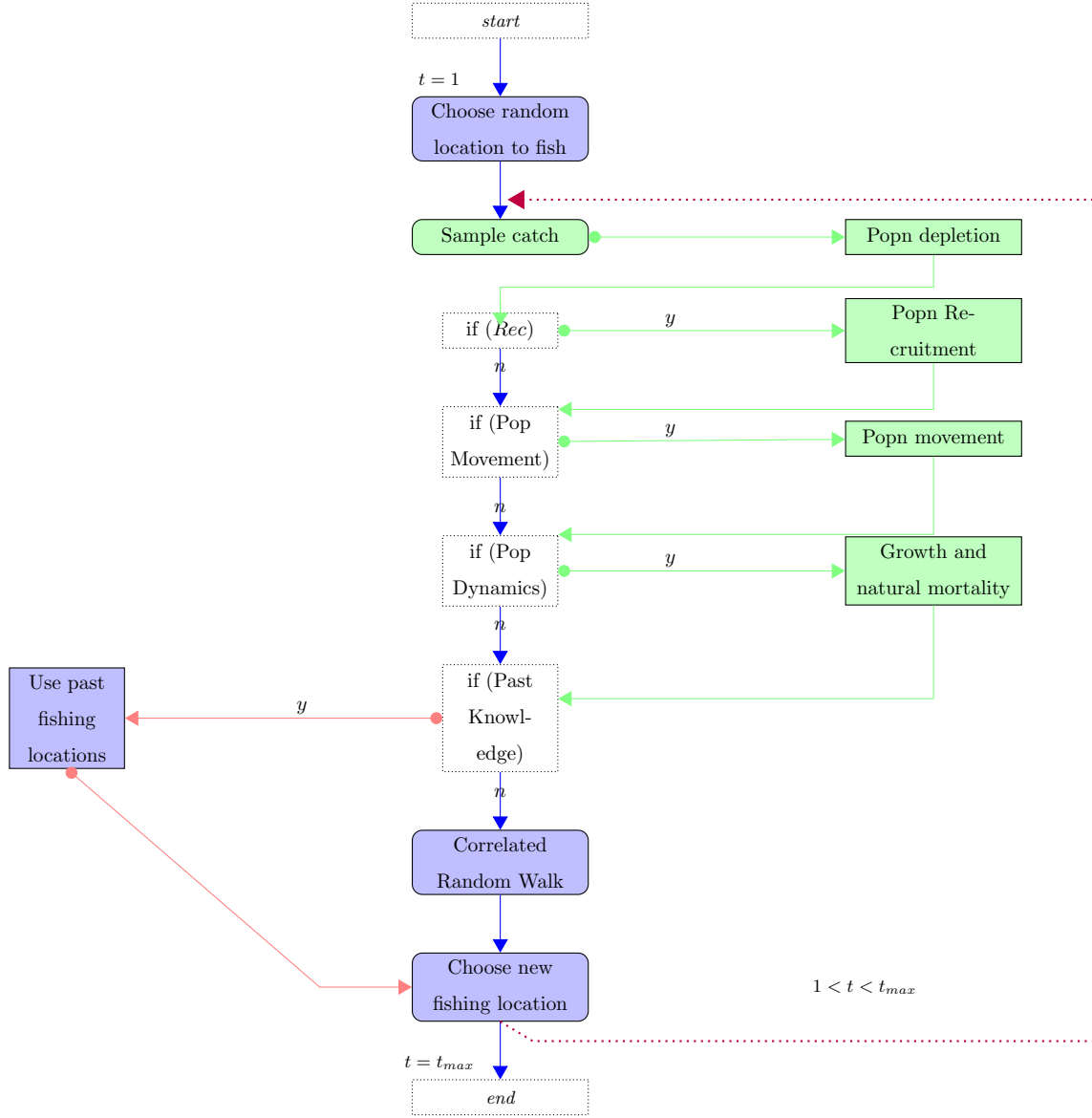


Figure 1: Schematic overview of the simulation model. Blue boxes indicate fleet dynamics processes, the green boxes population dynamics processes while the white boxes are the time steps at which processes occur;  $t = \text{tow}$ ,  $t_{max}$  is the total number of tows; (Rec), (Pop Movement), (Pop Dynamics) logic gates for recruitment periods, population movement and population dynamics for each of the populations, (Past Knowledge) a switch whether to use a random (exploratory) or past knowledge (exploitation) fishing strategy.

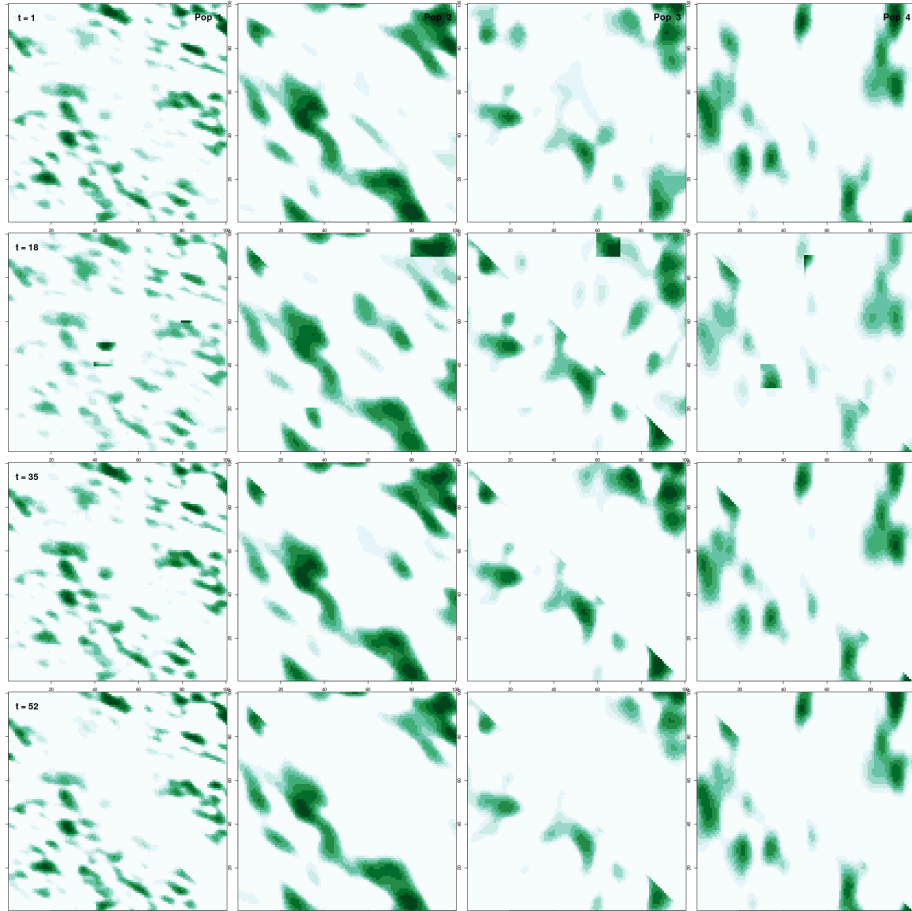


Figure 2: Simulated spatial dynamics - the four populations abundance ( $\log+1$ ) at four time steps.

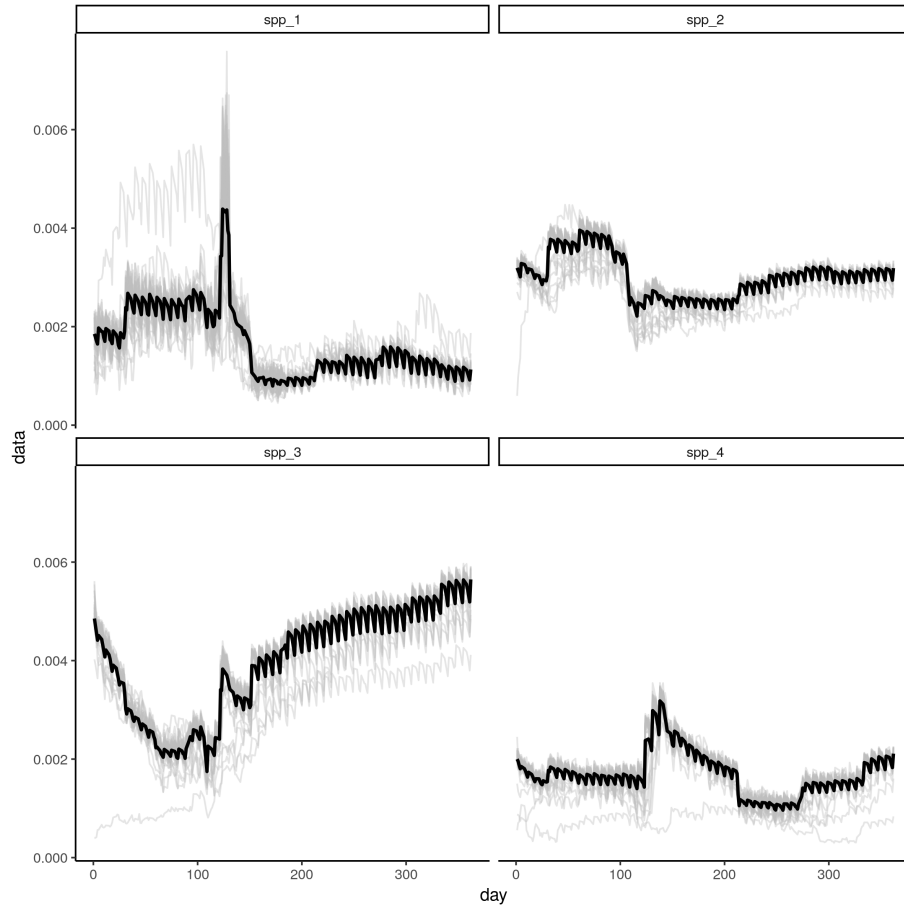


Figure 3: Fishing mortality dynamics - the daily fishing mortalities showing weekly and seasonal patterns in exploitation. Individual years and the light grey lines, the mean of all years the thick black line

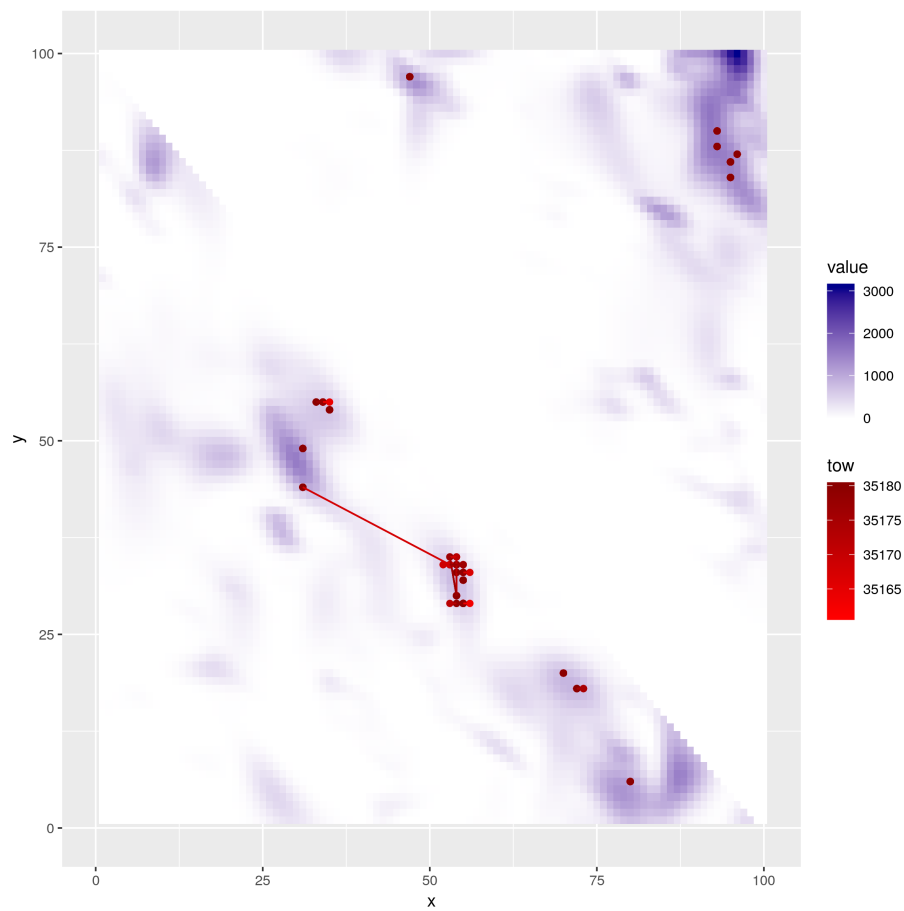


Figure 4: movement of a fleet over a single trip reference overlaid on the value field (i.e. sum of the population abundance  $\times$  catchability  $\times$  value

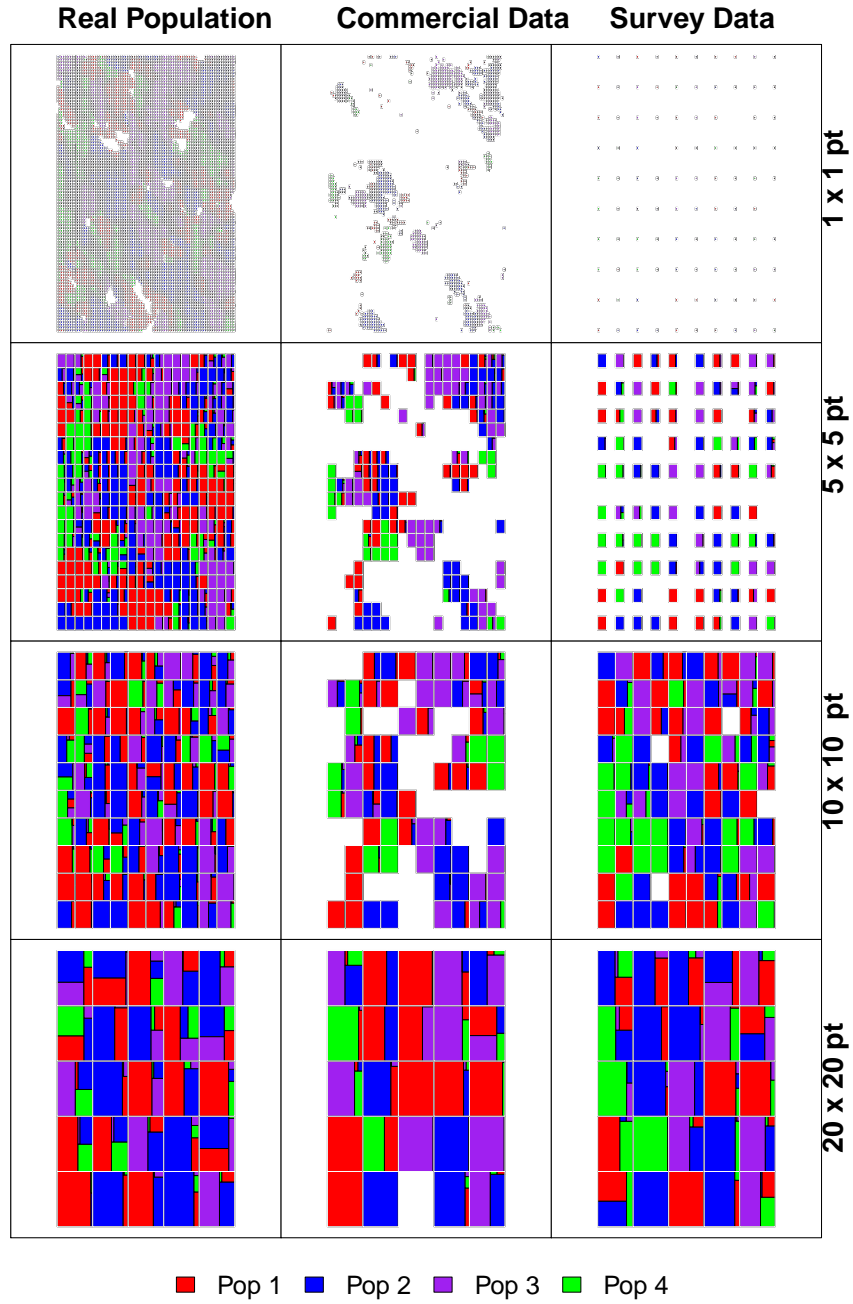


Figure 5: Data aggregation at different spatial resolutions over a ten year period

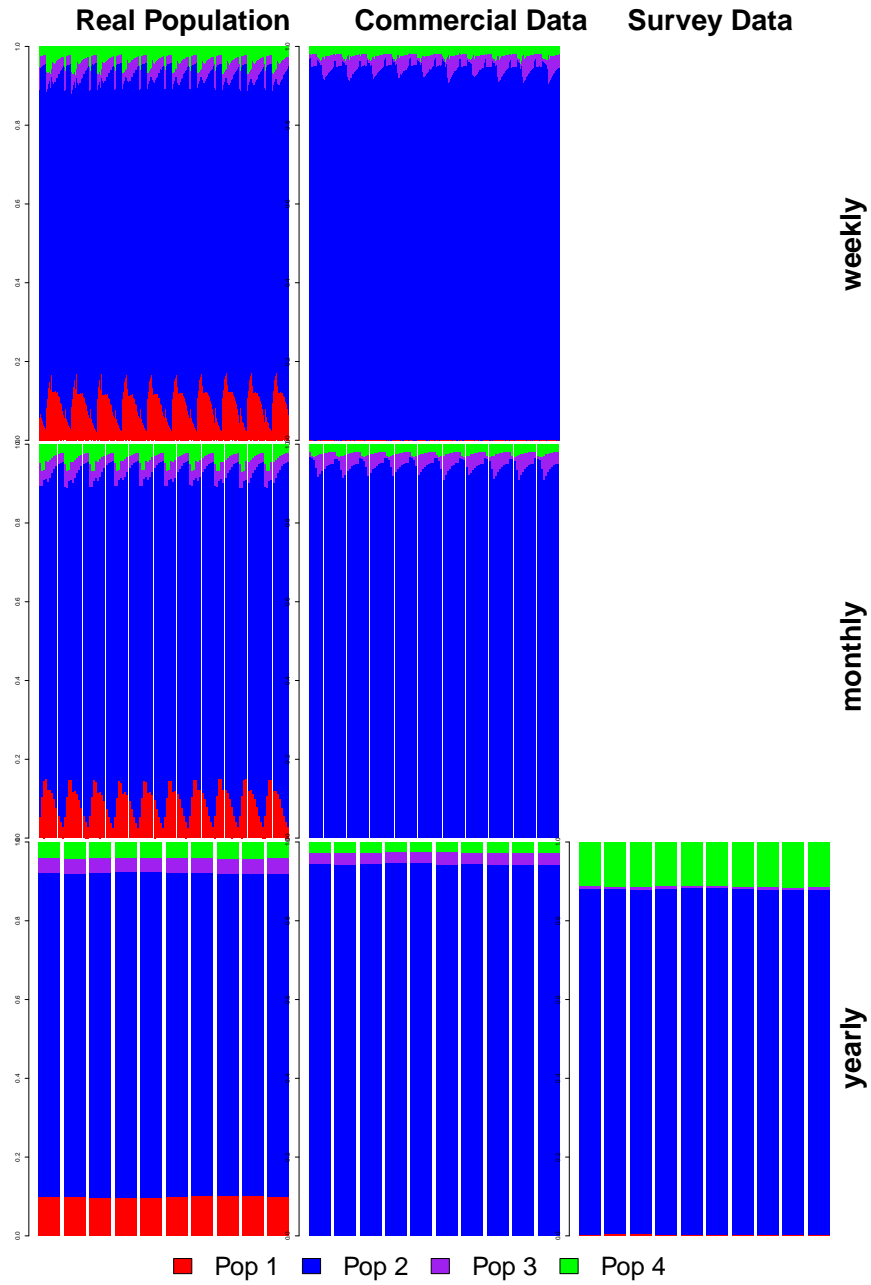


Figure 6: Data aggregation at different temporal resolutions over a ten-year period

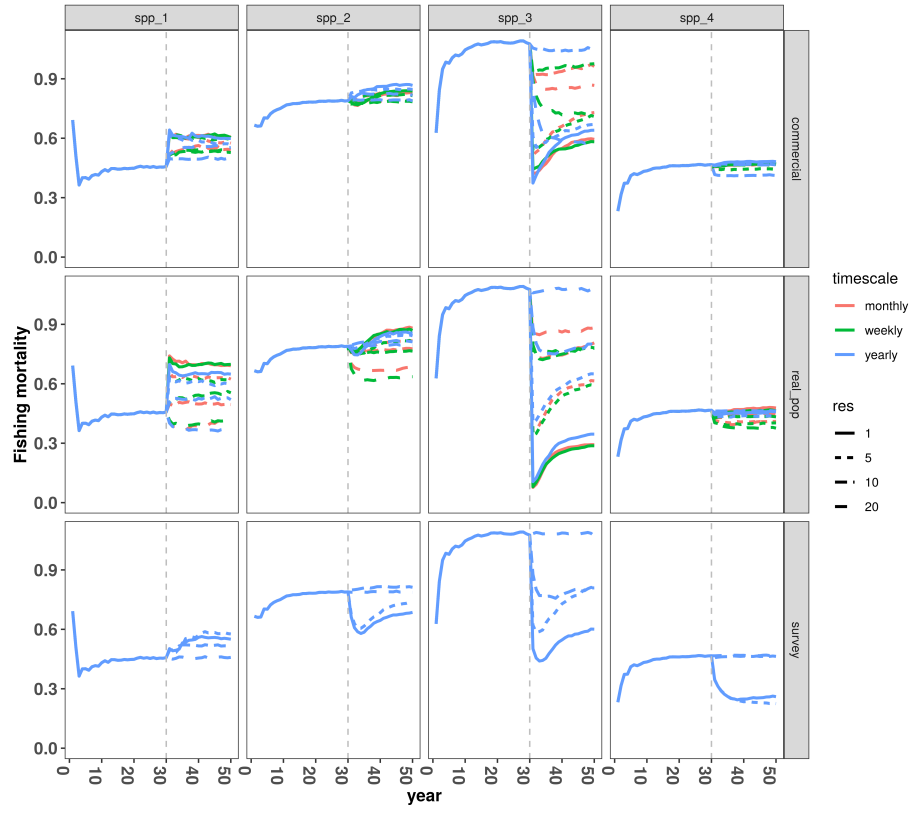


Figure 7: Comparison of closure scenarios effect on fishing mortality trends. Line colour denotes the timescale, while linestyle denotes the spatial resolution.

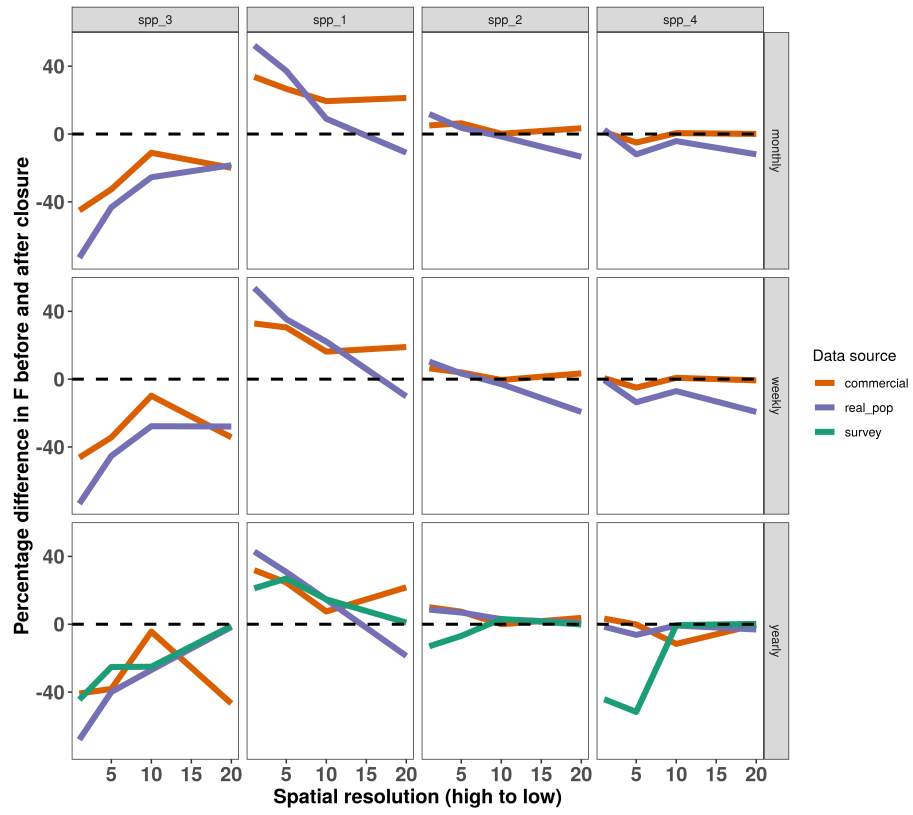


Figure 8: Comparison of closure scenario effectiveness based on different spatial and temporal resolutions.





Figure 9: Closure fishing locations based on annual closures with a coarse spatial resolution. Closure location can be seen in red in relation to a) before the closure fishing locations, b) after the closure fishing locations, c) species 3 habitat distribution

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