

CS 240: Programming in C

Lecture 26: Hardware Interfacing

Announcements

- The final exam is on 12/13 at 7:00 pm
 - In STEW 183
- Wednesday will be a review lecture
 - Come prepared with questions!
- Homework 13 is due this Wednesday at 9:00 pm!

Announcements

- Course Evaluations
 - Please complete them!
 - Survey closes on 12/8

Interfacing with hardware

- Writing software is fun, but sometimes we want to see how we can interact with the physical world
- Output
 - We can affect external state
- Input
 - We can read external state

Ports

- Computers used to have things like serial and parallel ports
 - Great for (slow) communication, easy to interface
 - Rarely exist now



Source: [shutterstock.com](https://www.shutterstock.com)

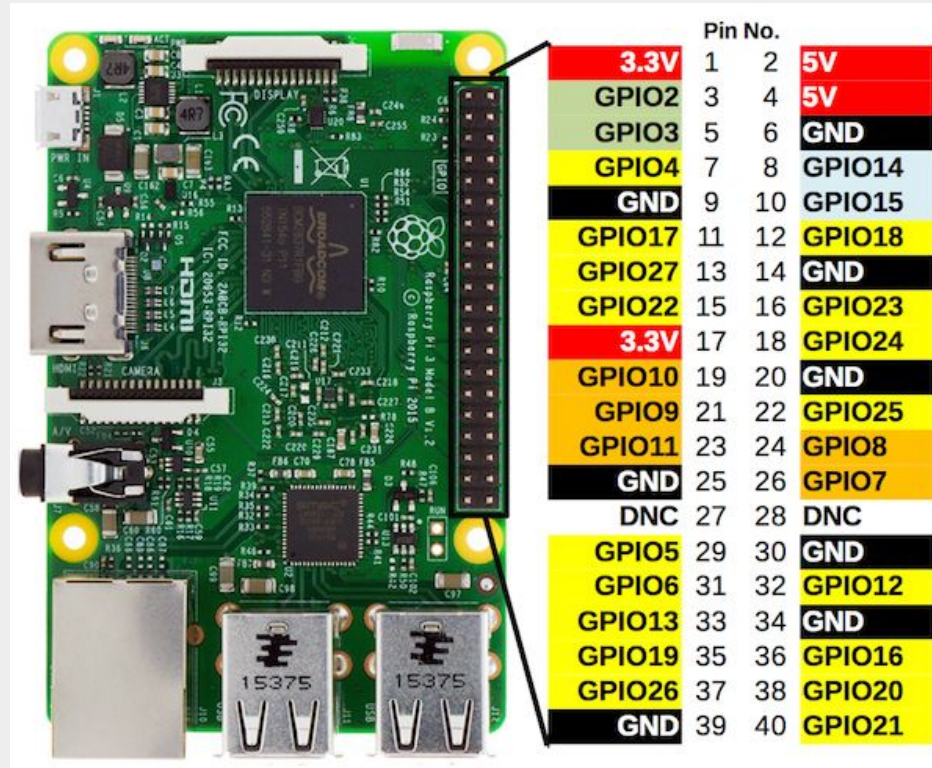
Ports

- Computers used to have things like serial and parallel ports
 - Great for (slow) communication, easy to interface
 - Rarely exist now
- Replaced by more modern ports
 - Ethernet port - need the ethernet protocols
 - USB port - difficult to use; can't directly manipulate signal
- Look in /dev on Linux

Embedded systems

- System on a Chip (SoC)
 - Contains all/most computer components on a single board
 - CPU, memory, storage, ports, etc.
 - Many can run a full-fledged OS (e.g., Raspberry Pi)
- Often with exposed pins
 - General Purpose Input Output (GPIO)
 - Easy to interface

Raspberry Pi GPIO



Source: bigmessowires.com

Raspberry Pi GPIO

- Use pins to form a circuit with LEDs and buttons
 - Or any other components
- 3.3V and 5V power sources
- Ground pins
- GPIO pins can be accessed from a C program

Be careful!

- Incorrectly wiring the GPIO pins can permanently damage the device
- Use appropriate resistors
- Double check your circuit before you connect it to your RPi

Datasheet

- Sometimes called “spec sheet”
- Details technical characteristics of a component
 - Can be hardware or software
- Often includes
 - Functional descriptions
 - Pin diagrams
 - Voltage ratings and specs
 - Power consumption
 - I/O waveforms
 - Timings
 - Physical dimensions
 - etc.

BCM2711

- Raspberry Pi 4B uses a 1.5GHz quad core 64-bit ARM processor (BCM2711)
- Older Pis use BCM2835/6/7

Raspberry Pi GPIO access

- RPI.h
- pins.c
- pins.h
- traffic.c
- button.c

Function select

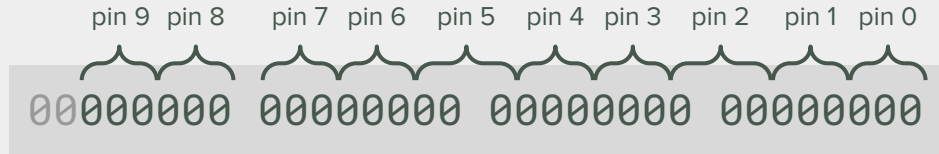
```
#define INP_GPIO(g) *(gpio.addr + ((g)/10)) &= ~(7<<(((g)%10)*3))  
#define OUT_GPIO(g) *(gpio.addr + ((g)/10)) |= (1<<(((g)%10)*3))
```

- g is the pin number
- Each register controls 10 pins
 - 0-9, 10-19, 20-29, 30-39, 40-49, 50-57
- `(gpio.addr + ((g)/10))` gives us the address of the correct register for pin g

Function select

```
#define INP_GPIO(g) *(gpio.addr + ((g)/10)) &= ~(7<<(((g)%10)*3))  
#define OUT_GPIO(g) *(gpio.addr + ((g)/10)) |= (1<<(((g)%10)*3))
```

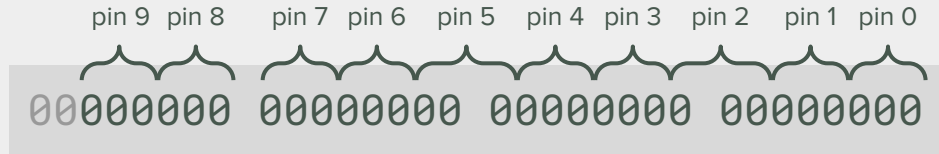
- Say $g = 3$
- $((g)\%10)*3 = 9$
 - gives us the bit offset for that pin



Function select

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#define INP_GPIO(g) *(gpio.addr + ((g)/10)) &= ~(7<<(((g)%10)*3))  
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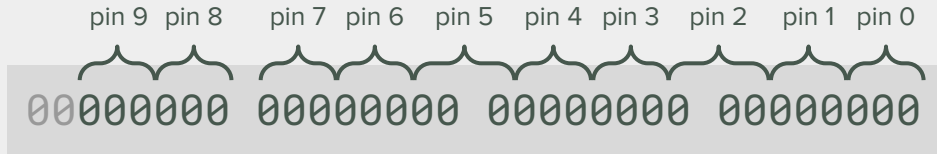
7

00000000 00000000 00000000 00000111

Function select

```
#define INP_GPIO(g) *(gpio.addr + ((g)/10)) &= ~(7<<(((g)%10)*3))  
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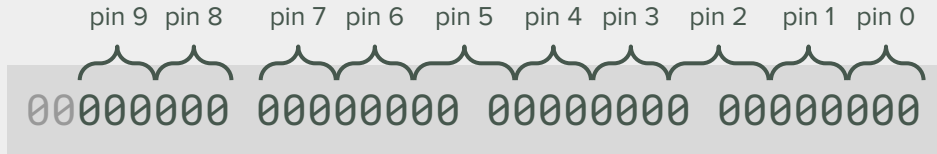
7 << 9

00000000 00000000 00001110 00000000

Function select

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$\sim(7 << 9)$

11111111 11111111 11110001 11111111

GPIO Application

- Realtime Photometric Stereo
- Theory
 - Given 3+ images of a static scene (no camera/scene motion)
 - Each image has a different light source
 - You can solve for per-pixel “surface normals” (direction of surface)
 - With good normals, you can extrude a rough 3D surface

GPIO Application

- Main idea:
 - High-speed camera
 - Array of high-power LEDs sync'd to framerate
 - Use GPU to recover normals quickly

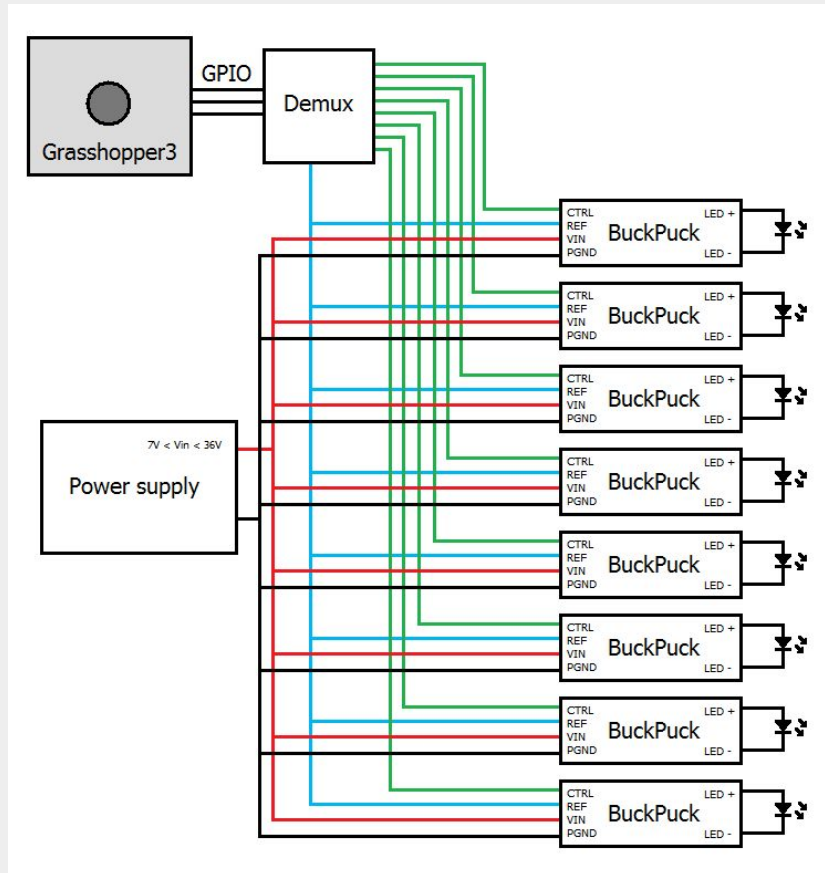


GPIO Application

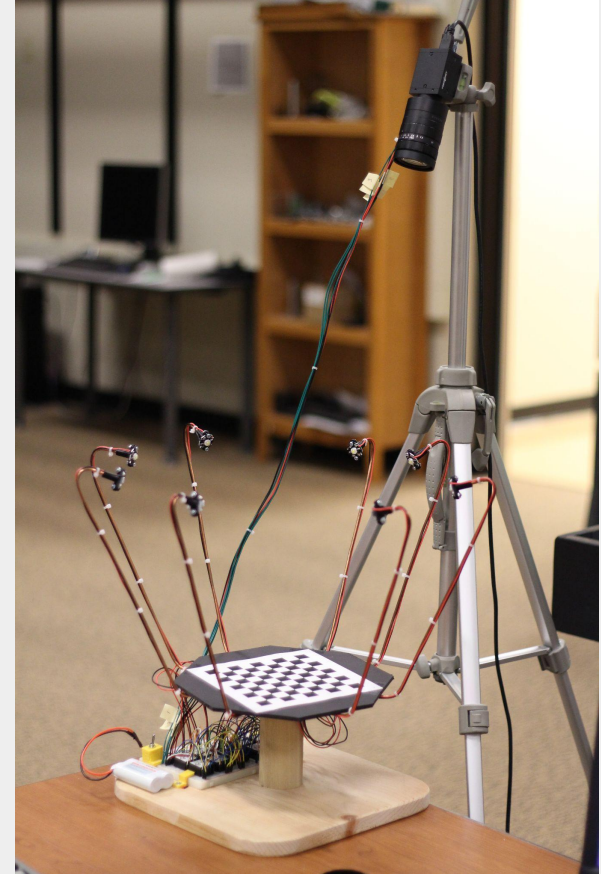
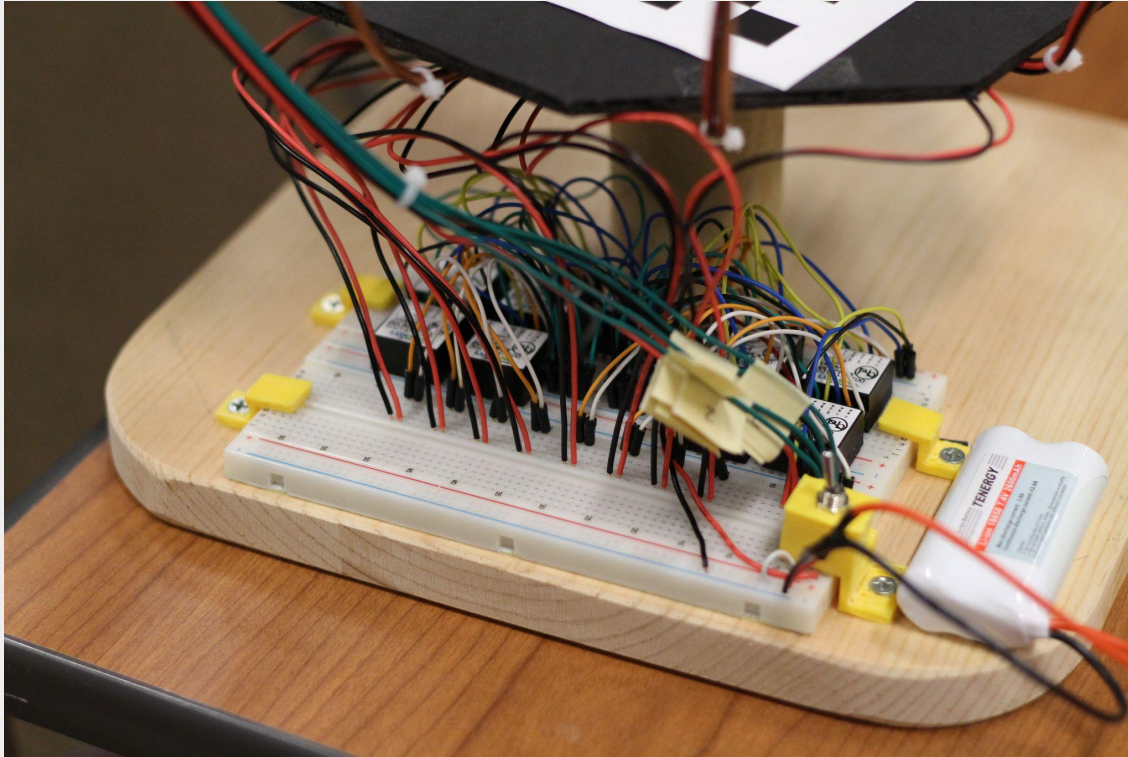
- How? The camera has GPIO pins!



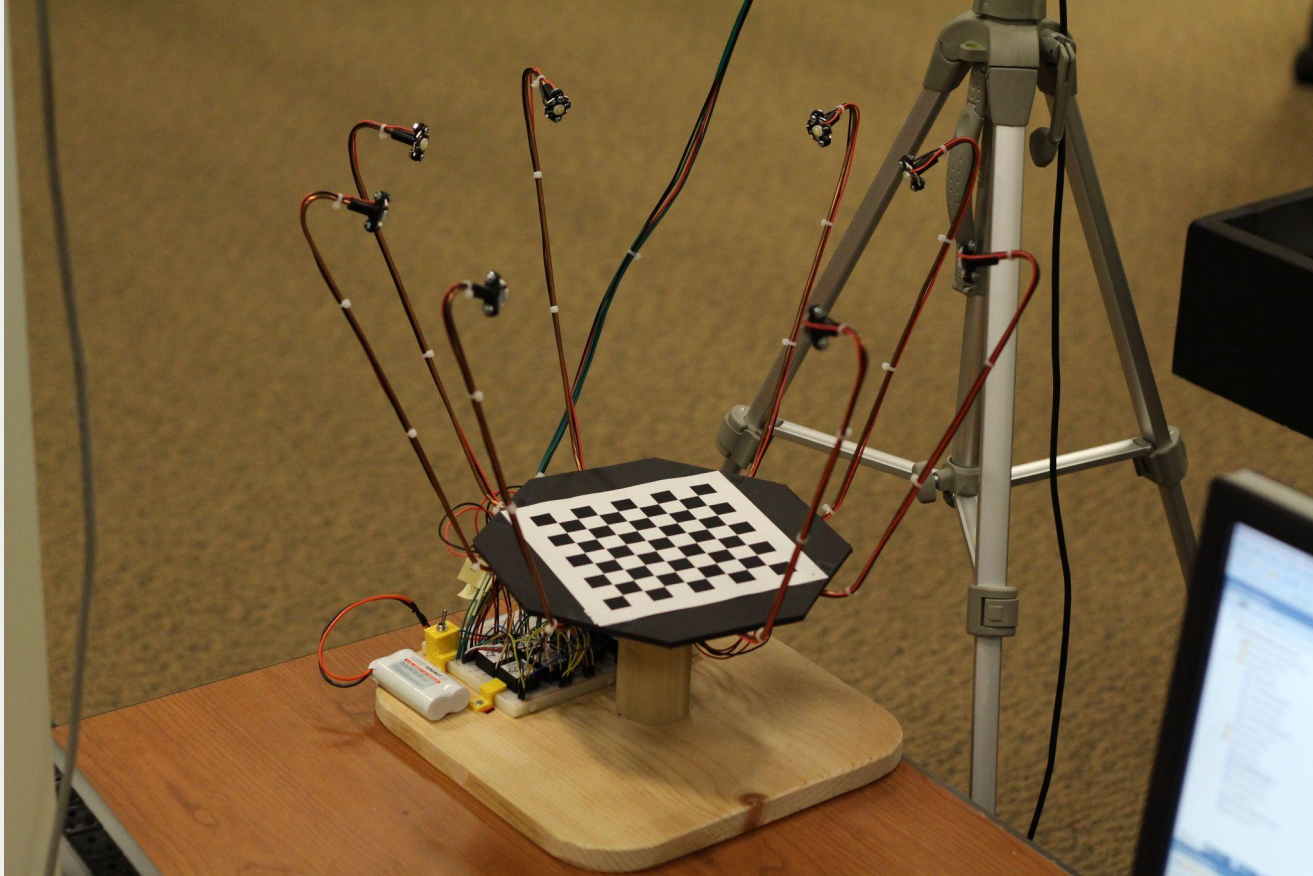
GPIO Application



GPIO Application



GPIO Application



GPIO Application

