TEC-V MILESTONE 1

By: Michael Dowling & Zealand Brennan



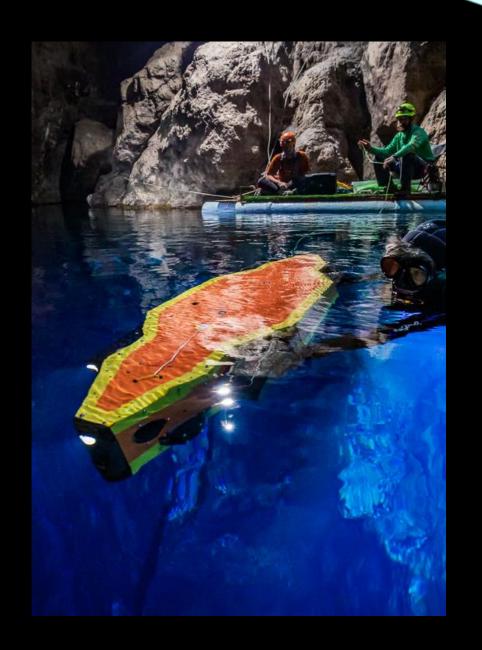
CLIENT

- DR. Wood
 - **Professor** | Ocean Engineering and Marine Sciences
 - Program Chair for Ocean Engineering



MILESTONE 1 OVERVIEW

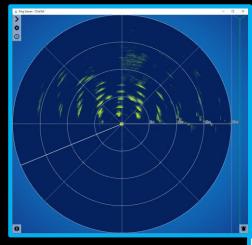
- Sonar Types
- Data Saving
- Scanning Sequence
- Cloud Plotting

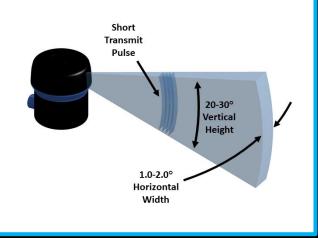


Ping 360

- Reliable imaging
- 360% degree
- 15% Cone
- Detailed Imaging False
- Data Transcription Unknown

SONAR DEVICES

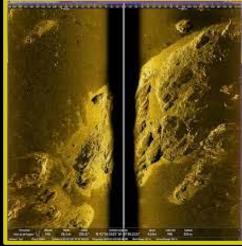




SONAR DEVICES

Omniscan 450 SS

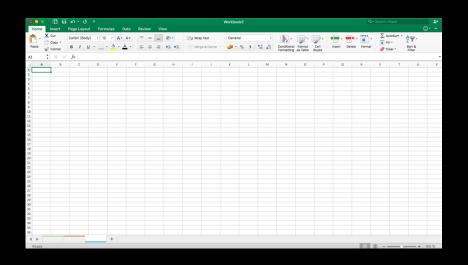
- Reliable imaging
- 5% degree (y movement)
- 70% Angle of scan
- Detailed Imaging True
- Data Transcription Possible





DATA SAVING

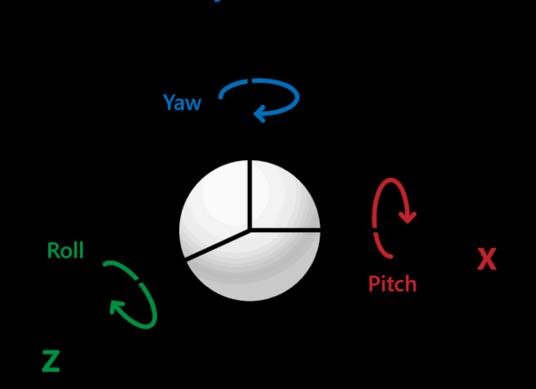
- Sonar data saving options:
 - On-board
 - Topside Receiver
- Format:
 - Excel spreadsheet
- Information Saved:
 - X Y Z of contact point
 - Telemetry data (UAVs XYZ pitch)
 - Time and speed motors are active between points of scan



SCANNING SEQUENCE

Proposal

- Based on the sonar type selected:
 - Command/button through Adru Sub (operating system)
 - Rotate AUV in a specific pattern to scan that module of the cave.



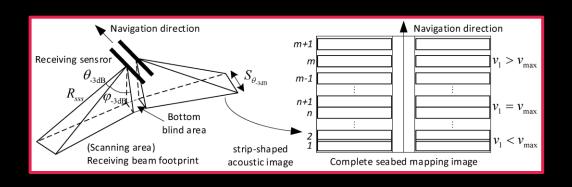
SCANNING SEQUENCE

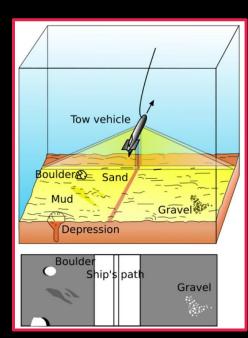
Collect Modules of Cave

 After x Distance Scan and Collect data point

Data Returned

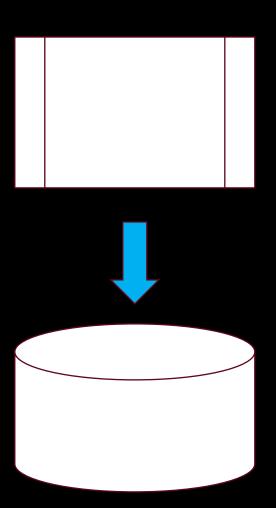
- Side Scan:
 - 3 Dimensional Plane





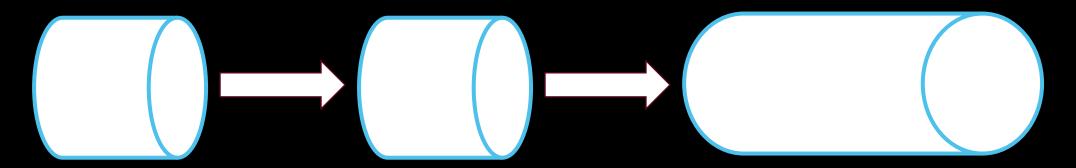
Data Returned

Conform 3D plane to Cylinder



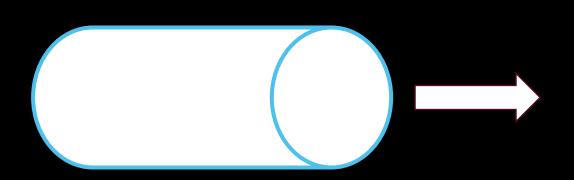
Module Combination

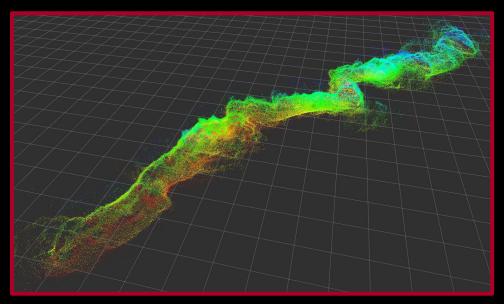
 Using Point Recognition to identify points of contact for connection



Goal

 User Interface to see and interact with the Cloud Plot





MILESTONE 2: TASKS

Create a program to save Required Data to Excel

| Scanning Sequence: | Using Ardu Sub create a sequence that maps close to 100% of a cave segment

| Cloud Plotting | Objective: Get each module to be properly wrapped | Goal: Work on combining sections

WEBPAGE LINK

TEC-V

https://bluecodehydra.github.io/FIT_Project-TEC_V/data.html

QUESTIONS?

