

LINEAR ALGEBRA

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Exercises Of Chapter 1-4

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§1. Vector Spaces

1.1. Introduction

1. Only the pairs in (b) and (c) are parallel

(a) $x = (3, 1, 2)$ and $y = (6, 4, 2)$

$\nexists 0 \neq t \in \mathbb{R}$ s.t. $y = tx$

(b) $(9, -3, -21) = 3(-3, 1, 7)$

(c) $(5, -6, 7) = -1(-5, 6, -7)$

(d) $x = (2, 0, -5)$ and $y = (5, 0, -2)$

$\nexists 0 \neq t \in \mathbb{R}$ s.t. $y = tx$

2. (a) $x = (3, -2, 4) + t(-8, 9, -3)$

(b) $x = (2, 4, 0) + t(-5, -10, 0)$

(c) $x = (3, 7, 2) + t(0, 0, -10)$

(d) $x = (-2, -1, 5) + t(5, 10, 2)$

3. (a) $x = (2, -5, -1) + s(-2, 9, 7) + t(-5, 12, 2)$

(b) $x = (-8, 2, 0) + s(9, 1, 0) + t(14, -7, 0)$

(c) $x = (3, -6, 7) + s(-5, 6, -11) + t(2, -3, -9)$

(d) $x = (1, 1, 1) + s(4, 4, 4) + t(-7, 3, 1)$

1.1.

$$4. x = (a_1, a_2, \dots, a_n) \in \mathbb{R}^n, i = 1, 2, \dots, n$$

$$0 = (0, 0, \dots, 0) \in \mathbb{R}^n \text{ s.t. } x + 0 = x, \forall x \in \mathbb{R}^n$$

$$5. x = (a_1, a_2) \Rightarrow tx = t(a_1, a_2) = (ta_1, ta_2)$$

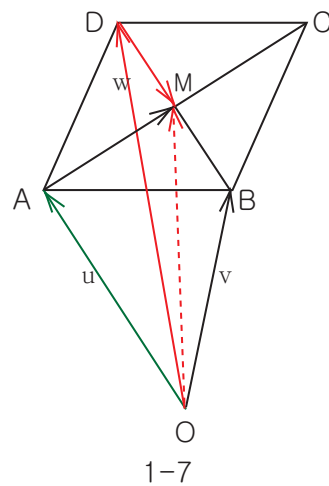
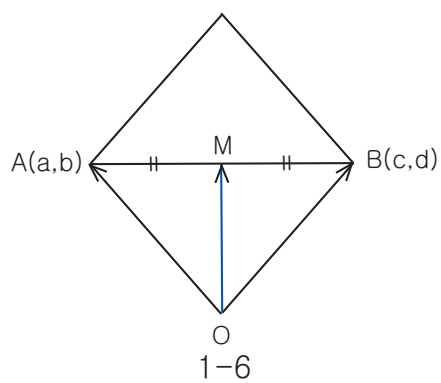
$$6. A + B = (a + c, b + d), M = \left(\frac{a+c}{2}, \frac{b+d}{2}\right)$$

7.

$$C = (v - u) + (w - u) + u = v + w - u$$

$$\overrightarrow{OD} + \frac{1}{2}\overrightarrow{DB} = \overrightarrow{OA} + \frac{1}{2}\overrightarrow{AC}$$

$$i.e. w + \frac{1}{2}(v - w) = \frac{1}{2}(v + w) = u + \frac{1}{2}(v + w - u - u)$$



1.2. Vector Spaces

1.

(a) T

(b) F (If $\exists 0'$ s.t. $x + 0' = x, \forall x \in V$, then $0' = 0 + 0' = 0' + 0 = 0, \therefore 0' = 0$)(c) F (If $x = 0, a \neq b$, then $a \cdot 0 = b \cdot 0$ but $a \neq b$)(d) F (If $a = 0, x \neq y$, then $a \cdot x = 0 = a \cdot y$ but $x \neq y$)

(e) T

(f) F (An $m \times n$ matrix has m rows and n columns)

(g) F

(h) F (If $f(x) = ax + b, g(x) = -ax + b$, then $\deg f = \deg g = 1, \deg(f + g) = 0$)

(i) T (p.10 Example4)

(j) T

(k) T (p.9 Example3)

$$2. \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$3. M_{13} = 3, M_{21} = 4, M_{22} = 5$$

4.

$$(a) \begin{pmatrix} 6 & 3 & 2 \\ -4 & 3 & 9 \end{pmatrix}$$

1.2.

(b) $\begin{pmatrix} 1 & -1 \\ 3 & -5 \\ 3 & 8 \end{pmatrix}$

(c) $\begin{pmatrix} 8 & 20 & -12 \\ 4 & 0 & 28 \end{pmatrix}$

(d) $\begin{pmatrix} 30 & -20 \\ -15 & 10 \\ -5 & 40 \end{pmatrix}$

(e) $2x^4 + x^3 + 2x^2 - 2x + 10$

(f) $-x^3 + 7x^2 + 16$

(g) $10x^7 - 30x^4 + 40x^2 - 15x$

(h) $3x^5 - 6x^3 + 12x + 6$

5.

$$U = \begin{pmatrix} 8 & 3 & 1 \\ 3 & 0 & 0 \\ 3 & 0 & 0 \end{pmatrix}, D = \begin{pmatrix} 9 & 1 & 4 \\ 3 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix}, T = \begin{pmatrix} 17 & 4 & 5 \\ 6 & 0 & 0 \\ 4 & 1 & 0 \end{pmatrix}$$

(*) The total number of crossings

	Fall	Spring	Winter
Brook trout	17	4	5
Rainbow trout	6	0	0
Brown trout	4	1	0

6.

$$M = \begin{pmatrix} 4 & 2 & 1 & 3 \\ 5 & 1 & 1 & 4 \\ 3 & 1 & 2 & 6 \end{pmatrix}, 2M - A = \begin{pmatrix} 3 & 1 & 1 & 4 \\ 4 & 0 & 1 & 3 \\ 5 & 2 & 1 & 9 \end{pmatrix}$$

35 suites were sold during the June sale

7. We are going to show that $f(t) = g(t)$ and $(f + g)(t) = h(t)$, $\forall t \in S = \{0, 1\}$

(i) $f(0) = 1 = g(0), f(1) = 3 = g(1)$

(ii) $(f + g)(0) = 2 = h(0), (f + g)(1) = 6 = h(1)$

\therefore In $\mathcal{F}(S, R)$, $f = g$ and $f + g = h$

8. VS 7, 8

9. (a) Exercise 1(b)

(b) If $\exists y'$ s.t. $x + y' = 0$, then $x + y = 0x + y'$

By the theorem 1.1, $y = y'$

(c) $a \cdot 0 + a \cdot 0 = a(0 + 0) = a \cdot 0 = a \cdot 0 + 0$

By the theorem 1.1, $a \cdot 0 = 0$

10. $V = D(\mathbb{R})$, $\forall s \in \mathbb{R}$

(1) $\forall f, g \in V$, $f + g = g + f$

$(f + g)(s) = f(s) + g(s) = g(s) + f(s) = (g + f)(s)$

$\therefore f + g = g + f$

(2) $\forall f, g, h \in V$, $(f + g) + h = f + (g + h)$

$((f + g) + h)(s) = (f + g)(s) + h(s) = f(s) + g(s) + h(s)$

$= f(s) + (g + h)(s) = (f + (g + h))(s)$

$\therefore (f + g) + h = f + (g + h)$

1.2.

$$(3) \exists 0 \in V \text{ s.t. } f + 0 = f, \forall f \in V$$

$$(f + f')(s) = f(s) + f'(s) = 0(s)$$

$$\therefore f'(s) = 0(s) - f(s) = (0 - f)(s) = (-f)(s)$$

$$\therefore f' = -f$$

$$(5) \forall f \in V, 1 \cdot f = f$$

$$(1 \cdot f)(s) = 1(f(s)) = f(s)$$

$$\therefore 1 \cdot f = f$$

$$(6) \forall a, b \in F, (ab)f = a(bf)$$

$$((ab)f)(s) = (ab)f(s) = a(bf(s)) = a(bf)(s)$$

$$\therefore (ab)f = a(bf)$$

$$(7) \forall a \in F, a(f + g) = af + ag$$

$$a(f + g)(s) = a(f(s) + g(s)) = af(s) + ag(s) = (af + ag)(s)$$

$$\therefore a(f + g) = af + ag$$

$$(8) \forall a, b \in F, (a + b)f = af + bf$$

$$(a + b)f(s) = af(s) + bf(s) = (af + bf)(s)$$

$$\therefore (a + b)f = af + bf$$

$$11. V = \{0\}, \forall a, b \in F$$

12.

$$(1) \forall f, g \in V, t \in \mathbb{R}$$

$$(f + g)(-t) = f(-t) + g(-t) = f(t) + g(t) = (f + g)(t) \therefore f + g \in V$$

- $(g + f)(-t) = (g + f)(t) \therefore g + f \in V$
 $\therefore f + g = g + f$
 (2) $\forall f, g, h \in V, (f + g) + h = f + (g + h)$
 (3) $\exists 0 \in V$ s.t. $f + 0 = f, \forall f \in V$
 (4) $\exists f' \in V$ s.t. $f + f' = 0, \forall f \in V, f' = -f$
 (5) $\forall f \in V, 1f = f$
 (6) $\forall a, b \in F, (ab)f = a(bf)$
 $((ab)f)(-t) = (ab)f(t), \therefore abf \in V$
 (7) $\forall a \in F, \forall f, g \in V, a(f + g) = af + ag$
 (8) $\forall a, b \in F, \forall f \in V, (a + b)f = af + bf$

13. No, (VS 4) fails

(VS 3) $\exists (0, 1) \in V$ s.t. $(a_1, a_2) + (0, 1) = (a_1, a_2), \forall (a_1, a_2) \in V$

(VS 4) If $a_2 = 0$, then $\nexists (b_1, b_2) \in V$ s.t. $(a_1, 0) + (b_1, b_2) = (0, 1)$

14. Yes ($\because \mathbb{R} \subseteq \mathbb{C}$)

15. No ($\because \mathbb{C} \not\subseteq \mathbb{R}$)

$\alpha \in F = \mathbb{C}, \alpha x \notin V = \mathbb{R}^n, \forall x \in V$

16. Yes ($\because \mathbb{Q} \subseteq \mathbb{R}$)

17. No, (VS 5) fails

(VS 5) If $a_2 \neq 0$, then $1(a_1, a_2) = (a_1, 0) \neq (a_1, a_2)$

18. No, (VS 1) fails

(VS 5) If $a_1 \neq b_1$, then it fails to hold (VS 1)

19. No, (VS 8) fails

(VS 8) If $c_1 + c_2 \neq 0$, $c_1 \neq 0$, $c_2 \neq 0$, then it fails to hold (VS 8)

20. (VS 1) $\forall \{a_n\}, \{b_n\} \in V$

$\{a_n\} + \{b_n\} = \{a_1 + b_1, a_2 + b_2, \dots\} = \{b_1 + a_1, b_2 + a_2, \dots\} = \{b_n\} + \{a_n\}$

(VS 2) $(\{a_n\} + \{b_n\}) + \{c_n\} = \{a_n\} + (\{b_n\} + \{c_n\})$

(VS 3) $\exists \{0\}$ s.t. $\{a_n\} + \{0\} = \{a_n\}$

(VS 4) $\exists \{-a_n\}$ s.t. $\{a_n\} + \{-a_n\} = \{a_n\} - \{a_n\} = \{0\}, \forall \{a_n\} \in V$

(VS 5) $\exists \{1\}$ s.t. $\{1\}\{a_n\} = \{a_n\}, \forall \{a_n\} \in V$

(VS 6) $\forall \alpha, \beta \in F, (\alpha\beta)\{a_n\} = \alpha(\beta\{a_n\})$

(VS 7) $\forall \alpha \in F, \forall \{a_n\}, \{b_n\} \in V, \alpha(\{a_n\} + \{b_n\}) = \alpha\{a_n\} + \alpha\{b_n\}$

(VS 8) $\forall \alpha, \beta \in F, (\alpha + \beta)\{a_n\} = \alpha\{a_n\} + \beta\{a_n\}$

22. 2^{mn}

1.3. Subspaces

1. (a) F (p.1 Definition of subspace)
 (b) F ($0 \notin \emptyset$)
 (c) T (V and $\{\emptyset\}$ are subspaces of V)
 (d) F (p.19 Theorem 1.4)
 (e) F
 (f) F (p.18 Example 4)
 (g) F ($(0, 0, 0) \in W$, but $(0, 0, 0) \notin R^2$)

2. (b), (c), (e), (f), (g) are not square matrices
 (a) -5, (d) 12, (h) -6

3. $\forall A, B \in M_{m \times n}(F), a, b \in F (1 \leq i \leq m, 1 \leq j \leq n)$
 $(aA + bB)_{ij}^t = (aA + bB)_{ji} = (aA)_{ji} + (bB)_{ji}$
 $= a(A)_{ji} + b(B)_{ji} = aA_{ij}^t + bB_{ij}^t = (aA^t + bB^t)_{ij}$
 $\therefore (aA + bB)^t = aA^t + bB^t$

4. $(A^t)_{ij}^t = (A^t)_{ji} = A_{ij}$

5. $(A + A^t)^t = A^t + (A^t)^t = A^t + A = A + A^t$
 $\therefore A + A^t$ is symmetric

$$6. \operatorname{tr}(aA + bB) = \sum_{i=1}^n (aA + bB)_{ii} = \sum_{i=1}^n (aA)_{ii} + \sum_{i=1}^n (bB)_{ii} = a \operatorname{tr}(A) + b \operatorname{tr}(B)$$

$$7. A = \begin{pmatrix} a_{11} & & & \\ & a_{22} & O & \\ & O & a_{33} & \\ & & & a_{44} \end{pmatrix} \Rightarrow A^t = A$$

$\therefore A$ is symmetric

8. (a) Yes

(b) No $((0, 0, 0) \notin W_2)$

(c) Yes

(d) Yes

(e) No $((0, 0, 0) \notin W_5)$

(f) No $x + y \notin W_6$, $\forall x, y \in W_6$

9. (1) $W_1 \cap W_3 = \{0\}$ is a subspace of R^3

(2) $W_1 \cap W_4 = W_1$ is a subspace of R^3

(3) $W_3 \cap W_4 = \{(a_1, a_2, a_3) \in R^3 \mid 3a_1 = 11a_2, 3a_3 = 23a_2\}$ is a subspace of R^3

10. (i) W_1 is a subspace of F^n

(ii) W_2 is not a subspace of F^n

($\because (0, 0, 0) \notin W_2$)

11. No (The given set is not closed under addition)

(Example) $\forall f, g \in W$

Let $f(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_0$, $\deg f = n$

$g(x) = b_n x^n + b_{n-1} x^{n-1} + \cdots + b_0$, $\deg g = n$

If $b_n = -a_n$, then $\deg(f + g) = n - 1$

$\therefore f + g \notin W$

$\therefore W$ is not a subspace of V

15. Yes

17. (\Rightarrow) Theorem 1.3

(\Leftarrow) W is a subspace of V

(i) $0 \in W$ ($a = 0 \in F$: field)

(ii) $ax \in W$

(iii) $x + y \in W$

18. (\Rightarrow) Theorem 1.3

(\Leftarrow) W is a subspace of V

(i) $0 \in W$

(ii) $ax \in W$ ($y = 0 \in W$, by (i))

(iii) $x + y \in W$ ($a = 1 \in F$: field)

19. (\Leftarrow) If $W_1 \subseteq W_2$, then $W_1 \cup W_2 = W_2$ is a subspace of V

If $W_2 \subseteq W_1$, then $W_1 \cup W_2 = W_1$ is a subspace of V

$\therefore W_1 \cup W_2$ is a subspace of V

(\Rightarrow) If $\exists a \notin W_1, a \in W_2 \exists b \notin W_2, b \in W_1$,

then $ab \in W_1 \cup W_2$

But if $ab \in W_1$, then $a = (ab)b^{-1} \in W_1$

if $ab \in W_2$, then $b = (ba)a^{-1} \in W_2$

It's a contradiction

$\therefore W_1 \subseteq W_2$ or $W_2 \subseteq W_1$

20. Induction on n

In case of $n = 2$, it's clear

Assume that this holds for $n = k - 1$ ($k > 2$)

By the induction hypothesis,

$$\sum_{i=1}^{k-1} a_i w_i + a_k w_k \in W, \quad w_k \in W, \quad a_k \in F$$

$$\therefore \forall w_i \in W, \quad \sum_{i=1}^n a_i w_i \in W, \quad \text{where } \forall a_i \in F, \quad i = 1, 2, \dots, n$$

21. (i) $\{0\} \rightarrow 0, \therefore \{0\} \in W$

(ii) $\lim\{a_n\} = a, \lim\{b_n\} = b$

$$\lim(\{a_n\} + \{b_n\}) = \lim\{a_n\} + \lim\{b_n\} = a + b$$

$$\therefore \{a_n\} + \{b_n\} \in W$$

$$(iii) \lim c\{a_n\} = c \lim\{a_n\}$$

$$\therefore c\{a_n\} \in W$$

$$\therefore W \text{ is a subspace of } V$$

22.

$$\text{Let } W_1 = \{g \in F(F_1, F_2) \mid g(-t) = g(t), \text{ for each } t \in F_1\}$$

$$W_2 = \{g \in F(F_1, F_2) \mid g(-t) = -g(t), \text{ for each } t \in F_1\}$$

$$(1) \forall g_1, g_2 \in W_1, \forall c \in F$$

$$(i) 0 \in W_1$$

$$(ii) (g_1 + g_2)(-t) = g_1(-t) + g_2(-t) = g_1(t) + g_2(t) = (g_1 + g_2)(t)$$

$$\therefore g_1 + g_2 \in W_1$$

$$(iii) cg_1(-t) = c(g_1(t)) = cg_1(t)$$

$$\therefore cg \in W_1$$

$$\therefore W_1 \text{ is a subspace of } V$$

$$(2) \forall g_1, g_2 \in W_2, \forall c \in F$$

$$(i) 0 \in W_2$$

$$(ii) (g_1 + g_2)(-t) = g_1(-t) + g_2(-t) = -g_1(t) - g_2(t) = -(g_1 + g_2)(t)$$

$$\therefore g_1 + g_2 \in W_2$$

$$(iii) cg_1(-t) = c(-g_1(t)) = -cg_1(t)$$

$$\therefore cg \in W_2$$

$$\therefore W_2 \text{ is a subspace of } V$$

23. (a) $W_1 + W_2 = \{x + y \mid x \in W_1 \text{ and } y \in W_2\}$

(i) $0 = 0 + 0 \in W_1 + W_2$

(ii) $\forall x_1 + y_1, x_2 + y_2 \in W_1 + W_2$

$(x_1 + y_1) + (x_2 + y_2) = (x_1 + x_2) + (y_1 + y_2) \in W_1 + W_2$

(iii) $\forall x_1 + y_1 \in W_1 + W_2, \forall c \in F$

$c(x_1 + y_1) = cx_1 + cy_1 \in W_1 + W_2$

(b) $\forall W$ as a subspace of V s.t. $W_1 \subseteq W, W_2 \subseteq W$

$\forall x \in W_1 \subseteq W, \forall y \in W_2 \subseteq W \Rightarrow x + y \in W_1 + W_2 \subseteq W$

24. $V = F^n$

(i) $W_1 \cap W_2 = \{(0, 0, \dots, 0)\}$

(ii) $W_1 + W_2 \subseteq V$ is clear

$\forall v = (a_1, a_2, \dots, a_n) = (a_1, a_2, \dots, a_{n-1}, 0) + (0, 0, \dots, 0, a_n) \in W_1 + W_2$

$\therefore V = W_1 + W_2$

25. (a) $W_1 \cap W_2 = \{0\}$

(b) $V = \{f(x) \in P(F) \mid f(x) = a_0 + a_1x + \dots\}$

(\therefore) Since $W_1 \subseteq V$ and $W_2 \subseteq V, W_1 + W_2 \subseteq V$ is clear

$\forall f \in V, f = a_0 + a_2x + \dots + a_1x + a_3x^3 + \dots \in W_1 + W_2$

$\therefore V = P(F) = W_1 \oplus W_2$

26. (a) $W_1 \cap W_2 = \{A \in M_{m \times n} \mid A_{ij} = 0 \forall i, j\} = \{0\}$

(b) $W_1 + W_2 \subseteq V$ is clear

$$\begin{aligned} \forall A &= \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & & a_{2n} \\ \vdots & & \ddots & \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix} \in M_{m \times n}, \\ A &= \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & a_{22} & & a_{2n} \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & a_{mn} \end{pmatrix} + \begin{pmatrix} 0 & 0 & \cdots & 0 \\ a_{21} & 0 & & \\ \vdots & & \ddots & \vdots \\ a_{m1} & \cdots & a_{m(n-1)} & 0 \end{pmatrix} \in W_1 + W_2 \\ \therefore V &= P(F) = W_1 \oplus W_2 \end{aligned}$$

27. (a) $W_1 \cap W_2 = \{A \in M_{m \times n} \mid A_{ij} = 0 \ \forall i, j\} = \{0\}$

(b) $W_1 + W_2 \subseteq V$ is clear

$$\begin{aligned} \forall A &= \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & a_{22} & & a_{2n} \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & a_{mn} \end{pmatrix} \in M_{m \times n}, \\ A &= \begin{pmatrix} a_{11} & 0 & \cdots & 0 \\ 0 & a_{22} & & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & & a_{mn} \end{pmatrix} + \begin{pmatrix} 0 & a_{12} & \cdots & a_{1n} \\ 0 & 0 & & a_{2n} \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & a_{(n-1)n} \end{pmatrix} \in W_1 + W_2 \\ \therefore V &= P(F) = W_1 \oplus W_2 \end{aligned}$$

28. (a) $W_1 \cap W_2 = \{0\}$

(b) $W_1 + W_2 \subseteq V$ is clear

$$\forall A \in V, \ A = \left(\frac{A-A^t}{2}\right) + \left(\frac{A+A^t}{2}\right) \in W_1 + W_2$$

$$\therefore V \in W_1 + W_2$$

(cf) $\text{char}(F) \neq 2$

$$\{\tfrac{1}{2}(A - A^t)\}^t = \tfrac{1}{2}(A^t - A) = -\{\tfrac{1}{2}(A - A^t)\} \quad \therefore \tfrac{1}{2}(A - A^t) \in W_1$$

$$\{\tfrac{1}{2}(A - A^t)\}^t = \tfrac{1}{2}(A + A^t) \quad \therefore \tfrac{1}{2}(A + A^t) \in W_2$$

29. W_1 : strictly lower triangular matrices

W_2 : all symmetric matrices

(a) $W_1 \cap W_2 = \{0\}$

(b) Let $A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & & a_{2n} \\ \vdots & & \ddots & \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} \in V$ and $A' = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{12} & a_{22} & & a_{2n} \\ \vdots & & \ddots & \\ a_{1n} & a_{2n} & \cdots & a_{nn} \end{pmatrix} \in W_2$

then $\forall A = (A - A') + A' \in W_1 + W_2$

$$\therefore V \subseteq W_1 + W_2$$

$$\therefore V = W_1 + W_2$$

30.

(\Rightarrow) If $x = x_1 + x_2 = x_3 + x_4$, $x_1, x_3 \in W_1$ and $x_2, x_4 \in W_2$

then $x_1 - x_3 = x_4 - x_2 \in W_1 \cap W_2 = \{0\}$

$$\therefore x_1 = x_3, \quad x_2 = x_4$$

(\Leftarrow) (i) $V = W_1 + W_2$ is clear

(ii) If $w \in W_1 \cap W_2$, then $w = w + 0 = 0 + 0$

$$\therefore w = 0$$

$$\therefore W_1 \cap W_2 = \{0\}$$

$$31. (a) (\Leftarrow) v \in W \Rightarrow v + W = W$$

$\therefore v + W$ is a subspace of V

$$(\Rightarrow) v + w_1, v + w_2 \in W$$

$$v + w_1 + v + w_2 = v + (w_1 + w_2 + v) \in v + W$$

$$\therefore w_1 + w_2 + v \in W$$

$$\therefore v \in W$$

$$(b) v_1 - v_2 \in W \Leftrightarrow v_1 - v_2 + W = W \Leftrightarrow v_1 + W = v_2 + W$$

$$(c) \text{ Since } v_1 - v'_1 \in W \text{ and } v_2 - v'_2 \in W,$$

$$(v_1 - v'_1) + (v_2 - v'_2) = (v_1 + v_2) - (v'_1 + v'_2) \in W$$

$$\therefore (v_1 + v_2) + W = (v'_1 + v'_2) + W$$

$$\therefore (v_1 + W) + (v_2 + W) = (v'_1 + W) + (v'_2 + W)$$

$$\text{Since } a(v_1 - v'_1) \in W, a(v_1 + W) = a(v'_1 + W)$$

$$(d) S = V/W = \{v + W \mid v \in V\} \text{ is a vector space}$$

$$(\text{VS } 1) (v_1 + W) + (v_2 + W) = (v_1 + v_2) + W = (v_2 + v_1) + W = (v_2 + W) + (v_1 + W)$$

$$(\text{VS } 2) \{(v_1 + W) + (v_2 + W)\} + (v_3 + W) = (v_1 + v_2) + W + v_3 + W$$

$$= (v_1 + v_2 + v_3) + W = v_1 + (v_2 + v_3) + W$$

$$= \{v_1 + W\} + \{(v_2 + v_3) + W\}$$

$$= (v_1 + W) + \{(v_2 + W) + (v_3 + W)\}$$

$$(\text{VS } 3) \exists 0 + W \text{ s.t. } (v + W) + (0 + W) = (v + 0) + W = v + W$$

$$(\text{VS } 4) \forall v + W, (1 + W)(v + W) = v + W$$

$$(\text{VS } 5) \exists -v + W \text{ s.t. } (v + W) + (-v + W) = 0 + W$$

$$(\text{VS } 6) \forall a, b \in F, (ab)(v+W) = abv+W = a(bv)+W = a(bv+W) = a(b(v+W))$$

$$(\text{VS } 7) \forall a \in F, a(v_1+W+v_2+W) = av_1+av_2+W = av_1+W+av_2+W = a(v_1+W)+a(v_2+W)$$

$$(\text{VS } 8) (a+b)(v+W) = (a+b)v+W = av+bv+W = a(v+W)+b(v+W)$$

1.4. Linear Combinations and Systems of Linear Equations

1. (a) T ($0v = 0, \forall v \in V$)
 (b) F (p.30 $\text{span}(\emptyset) = \{0\}$)
 (c) T (p.30 Theorem 1.5)
 (d) F (p.27)
 (e) T (p.27)
 (f) F (p.33 2(b))

2. (a) $\{r(1, 1, 0, 0) + s(-3, 0, -2, 1) + (5, 0, 4, 0) \mid r, s \in R\}$
 (b) $(-2, -4, -3)$
 (c) There are no solutions
 (d) $\{r(-8, 3, 1, 0) + (-16, 9, 0, 2) \mid r \in R\}$
 (e) $\{r(0, -3, 1, 0, 0) + s(-3, -2, 0, 1, 0) + (-4, 3, 0, 0, 5) \mid r, s \in R\}$
 (f) $(3, 4, -2)$

3. (a) yes $(-2, 0, 3) = 4(1, 3, 0) + (-3)(2, 4, -1)$
 (b) Yes $(1, 2, -3) = 5(-3, 2, 1) + 8(2, -1, -1)$
 (c) No
 (d) Yes $(2, -1, 0) = \frac{4}{5}(1, 2, -3) + \frac{6}{5}(1, -3, 2)$
 (e) No
 (f) Yes $(-2, 2, 2) = 4(1, 2, -1) + 2(-3, -3, 3)$

4. (a) Yes $(x^3 - 3x + 5) = 3(x^3 + 2x^2 - x + 1) + (-2)(x^3 + 3x^2 - 1)$
 (b) No
 (c) Yes 4, -3
 (d) Yes -2, 5
 (e) No
 (f) No

5. (a) Yes $(2, -1, 1) = 1(1, 0, 2) + (-1)(-1, 1, 1) \in \text{span}(S)$
 (b) No
 (c) No
 (d) Yes 2, -1
 (e) Yes -1, 3, 1
 (f) No
 (g) Yes 3, 4, -2
 (h) No

6. Let $\text{span}\{(1, 1, 0), (1, 0, 1), (0, 1, 1)\} = W$

$$\forall v = (a_1, a_2, a_3) \in F^3,$$

$$v = r(1, 1, 0) + s(1, 0, 1) + t(0, 1, 1) \text{ s.t. } r = \frac{1}{2}(a_1 + a_2 - a_3), \quad s = \frac{1}{2}(a_1 - a_2 + a_3), \quad t =$$

$$\frac{1}{2}(-a_1 + a_2 + a_3) \in W$$

$\therefore V \subseteq W$ Since $W \subseteq F^3$ is clear, $W = F^3$

$$7. \forall v = (a_1, a_2, \dots, a_n) \in F^n$$

$$v = a_1 e_1 + a_2 e_2 + \dots + a_n e_n, \forall a_i \in F, i = 1, \dots, n$$

$$8. \forall f(x) = a_0 + a_1 x + \dots + a_n x^n \in P_n(F)$$

$$f(x) = a_0 \cdot 1 + a_1 \cdot x + \dots + a_n \cdot x^n, \forall a_i \in F, i = 0, 1, \dots, n$$

$$9. \forall A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in M_{2 \times 2}(F)$$

$$A = a_{11} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + a_{12} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + a_{21} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} + a_{22} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$10. \forall A = \begin{pmatrix} a & c \\ c & b \end{pmatrix} \in M_{2 \times 2}(F)$$

$$A = a \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + b \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} + c \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \in \text{span}\{M_1, M_2, M_3\}$$

11. If $x \neq 0$, then $\text{span}(\{x\}) = \{ax \mid a \in F\}$ is the line through the origin in R^3 Otherwise $\text{span}(\{x\}) = \{0\}$ is the origin

12. (\Leftarrow) By the theorem 1.5, $\text{span}(W)$ is a subspace of V

$\therefore W$ is a subspace of V

$$(\Rightarrow) \forall v \in W, v = 1 \cdot v \in \text{span}(W)$$

$$\therefore W \subseteq \text{span}(W)$$

$$\forall v \in \text{span}(W), v = a_1 v_1 + \dots + a_n v_n$$

Since $\forall a_i v_i \in W$, $v = \sum_{i=1}^n \in W$

$\therefore \text{span}(W) \subseteq W$

13. (i) $S_1 \subseteq S_2 \subseteq \text{span}(S_2) \Rightarrow \text{span}(S_1) \subseteq \text{span}(S_2)$

(ii) By (i) $\text{span}(S_1) = V \subseteq \text{span}(S_2) \subseteq V$

$\therefore \text{span}(S_2) = V$

14. $S_1, S_2 \subseteq V$, $S_1 = \{x_1, x_2, \dots, x_m\}$, $S_2 = \{x_{m+1}, x_{m+2}, \dots, x_n\}$

(i) Since $S_1, S_2 \subseteq S_1 \cup S_2$, $\text{span}(S_1), \text{span}(S_2) \subseteq \text{span}(S_1 \cup S_2)$

If $v = \sum_{i=1}^m a_i x_i + \sum_{i=m+1}^n a_i x_i \in \text{span}(S_1) + \text{span}(S_2)$, $\forall a_i \in F$

then $v \in \text{span}(S_1 \cup S_2)$

(ii) If $v = \sum_{i=1}^n a_i x_i \in \text{span}(S_1 \cup S_2)$, $\forall a_i \in F$

then $v = \sum_{i=1}^m a_i x_i + \sum_{i=m+1}^n a_i x_i \in \text{span}(S_1) + \text{span}(S_2)$

15. Since $S_1 \cap S_2 \subseteq S_1 \subseteq \text{span}(S_1)$ and $S_1 \cap S_2 \subseteq S_2 \subseteq \text{span}(S_2)$,

$\text{span}(S_1 \cap S_2) \subseteq \text{span}(S_1) \cap \text{span}(S_2)$

16. $\forall v \in \text{span}(S)$, suppose $v = a_1 v_1 + \dots + a_n v_n = b_1 v_1 + \dots + b_n v_n$

then $(a_1 - b_1)v_1 + \dots + (a_n - b_n)v_n = 0$

$\therefore (a_1 - b_1) = \dots = (a_n - b_n) = 0$

$\therefore a_1 = b_1, \dots, a_n = b_n$

17. W must be a finite set

(i) F is an infinite field

If $\exists 0 \neq w \in W$, then $\{aw \mid a \in F\} \Rightarrow W = \{0\}$

(ii) F is a finite field

If $\beta = \{w_1, \dots, w_n\}$, then $|W| = |F|^{|\beta|}$

$\therefore \dim W < \infty$

1.5. Linear Dependence and Linear Independence

1. (a) If S is a linearly dependent set, then each vector in S is a linear combination of other vector in S .

Ans : F

(Example) $V = R^3$, $S = \{e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1), e_4 = (1, 1, 0)\}$

$\{e_1, e_2, e_3\}$: linearly independent

$\{e_1, e_2, e_4\}$: linearly dependent

(b) Any set containing the zero vector is linearly dependent.

Ans : T ($\because \forall a \in F, 0 = a \cdot 0, a \neq 0$)

(c) The empty set is linearly dependent.

Ans : F (\because linearly dependent set must be non-empty).

(d) Subsets of linearly dependent sets are linearly dependent.

Ans : F (\because theorem 1.6)

(e) Subsets of linearly independent sets are linearly independent.

Ans : T (\because the corollary from theorem 1.6)

(f) If $a_1x_1 + a_2x_2 + \cdots + a_nx_n = 0$ and x_1, x_2, \cdots, x_n are linearly independent, then all the scalars a_i are zero.

Ans : T (\because from the definition).

2. (a), (d), (e), (g), (h), (j) : linearly independent

(b), (c), (f), (i) : linearly dependent

3. In $M_{2 \times 3}(F)$, prove that the set

$$\left\{ \begin{pmatrix} 1 & 1 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 0 \\ 1 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 1 \\ 0 & 1 \end{pmatrix} \right\}$$

is linearly dependent.

$$(\because) a + d = 0, b + d = 0, c + d = 0,$$

$$a + e = 0, b + e = 0, c + e = 0$$

$$\Rightarrow a = -d, b = -d, c = -d, d, e = d$$

\therefore the given set is linearly dependent.

4. In F^n , let e_j denote the vector whose j th coordinate is 1 and whose other coordinates are 0. Prove that $\{e_1, e_2, \dots, e_n\}$ is linearly independent.

$$(\because) (a_1, a_2, \dots, a_n) = a_1 e_1 + a_2 e_2 + \dots + a_n e_n = (0, \dots, 0)$$

$$\therefore a_1 = a_2 = \dots = a_n = 0$$

$\therefore \{e_1, e_2, \dots, e_n\}$ is linearly independent.

5. Show that the set $\{1, x, x^2, \dots, x^n\}$ is linearly independent in $P_n(F)$.

$$(\because) \text{ If } a_0 + a_1 x_1 + a_2 x_2 + \dots + a_n x_n = 0 \cdot 1 + 0 \cdot x_1 + 0 \cdot x_2 + \dots + 0 \cdot x_n,$$

then $\forall a_i = 0, 1 \leq i \leq n$.

6. In $M_{n \times n}(F)$, let E^{ij} denote the matrix whose only nonzero entry is 1 in the i th row and j th column.

Prove that $\{E^{ij} : 1 \leq i \leq m, 1 \leq j \leq n\}$ is linearly independent.

(\therefore) $\forall A \in M_{n \times n}(F)$,

If $A = a_{11}E^{11} + a_{12}E^{12} + \cdots + a_{nn}E^{nn} = 0$

then,

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{pmatrix} = \begin{pmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 0 \end{pmatrix}$$

$\therefore \forall a_{ij} = 0$, where $1 \leq i \leq m, 1 \leq j \leq n$

7. Recall from Example 3 in section 1.3 that the set of diagonal matrices in $M_{2 \times 2}(F)$ is a subspace.

Find a linearly independent set that generates this subspace.

(\therefore) $\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

$\forall \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} = a \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + b \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}, \quad a, b \in F$

8. Let $S = \{(1, 1, 0), (1, 0, 1), (0, 1, 1)\}$ be a subset of the vector space F^3 .

(a) Prove that if $F = R$, then S is linearly independent.

(b) Prove that if F has characteristic 2, then S is linearly independent.

(\therefore) (a) $a(1, 1, 0) + b(1, 0, 1) + c(0, 1, 1) = (0, 0, 0), \quad \forall a, b, c \in F$

then $a + b = 0, a + c = 0, b + c = 0$

$\therefore a = b = c = 0$

(b) If $a = b = c = 1$, then $a(1, 1, 0) + b(1, 0, 1) + c(0, 1, 1) = (2, 2, 2) = (0, 0, 0)$

$\therefore \{(1, 1, 0), (1, 0, 1), (0, 1, 1)\}$ is linearly dependent

9. Let u and v be distinct vectors in a vector space V .

Show that $\{u, v\}$ is linearly dependent if and only if u or v is a multiple of the other.

(\because) $u \neq v, \{u, v\}$: linearly independent

(\Rightarrow) If $au + bv = 0$,

(1) $a \neq 0 \Rightarrow u = \frac{-a}{b}v$

(2) $a = 0 \Rightarrow b \neq 0 \Rightarrow v = \frac{-a}{b}u$

(\Leftarrow) $u = kv \Rightarrow 1u - kv = 0$

10. Give an example of three linearly dependent vectors in R^3 such that none of the three is a multiple of another.

(Example) $\{(-1, 0, -1), (1, -1, 0), (0, 1, 1)\}$

11. Let $S = \{u_1, u_2, \dots, u_n\}$ be a linearly independent subset of a vector space V over the field Z_2 . How many vectors are there in $\text{span}(S)$?

$|\text{span}(S)| = |F|^{|n|}$, when the set is linearly independent.

* what if the given set is not linearly independent?

then the number of vectors in the set is smaller than $|F|^{|n|}$.

(Example) $a_i = \{0, 1\}$,

$$v_1 = (-1, 0, 1), v_2 = (1, -1, 0), v_3 = (0, 1, 1)$$

$$\text{span}(S) = \{(0, 0, 0), (0, 1, 1), (1, 1, 0), (1, 0, 1)\}$$

12. Prove Theorem 1.6 and its corollary.

$$\text{Let } S_1 = \{u_1, \dots, u_n\}, S_2 = \{u_1, \dots, u_n, v\}$$

(i) $a_1u_1 + a_2u_2 + \dots + a_nu_n + a_{n+1}v = 0$, not all $a_i \neq 0$ ($n \geq 1$) then $v =$

$$b_1u_1 + \dots + b_nu_n, \text{ where } b_i = -\frac{a_i}{a_{n+1}} \in F$$

$\therefore S_2$ is linearly independent

(ii) $a_1u_1 + \dots + a_nu_n + 0v = 0 \Rightarrow a_1 = \dots = a_n = 0$

$\therefore S_1$ is linearly independent

13. Let V be a vector space over a field of characteristic not equal to two.

(a) Let u and v be distinct vectors in V .

Prove that $\{u, v\}$ is linearly independent if and only if $\{u + v, u - v\}$ is linearly independent.

(\Rightarrow) Suppose $a(u + v) + b(u - v) = 0$, $a, b \in F$

$$(a + b)u + (a - b)v = 0$$

$$\therefore a = b = 0$$

(\Leftarrow) $\{u + v, u - v\}$ is linearly independent.

$$au + bv = \left(\frac{a+b}{2}\right)(u + v) + \left(\frac{a-b}{2}\right)(u - v) = 0$$

$$\left(\frac{a+b}{2}\right) = 0 \text{ and } \left(\frac{a-b}{2}\right) = 0$$

$$\therefore a = b = 0$$

(b)

$$(\Rightarrow) a(u+v) + b(u+w) + c(v+w) = 0$$

$$\Rightarrow (a+b)u + (a+c)v + (b+c)w = 0$$

$$\therefore a+b = a+c = b+c = 0$$

$$\therefore a = b = c = 0$$

$$(\Leftarrow) au + bv + cw = \left(\frac{a+b}{2}\right)(u+v) + \left(\frac{a+c}{2}\right)(u+w) + \left(\frac{b+c}{2}\right)(v+w)$$

$$\left(\frac{a+b}{2}\right) = \left(\frac{a+c}{2}\right) = \left(\frac{b+c}{2}\right) = 0$$

$$\therefore a = b = c = 0$$

14. (\Leftarrow) By the exercise 1(b), if $S = \{0\}$, then S is linearly dependent

$$\text{If } v = a_1u_1 + \cdots + a_nu_n, \text{ then } a_1u_1 + \cdots + a_nu_n - 1 \cdot v = 0$$

$$\therefore S = \{u_1, \cdots, u_n, v\} \text{ is linearly dependent}$$

$$(\Rightarrow) \text{ If } S \neq \{0\}, \exists a_i \neq 0 \text{ s.t. } a_1u_1 + \cdots + a_nu_n + a_{n+1}v = 0$$

$$\text{Let } a_{n+1} \neq 0$$

$$v = b_1u_1 + \cdots + b_nu_n \in \text{span}(\{u_1, \cdots, u_n\}), \text{ where } b_i = -\frac{a_i}{a_{n+1}} \in F$$

15. (\Leftarrow) By the theorem 1.6

$$(\Rightarrow)$$

$$\text{If } u_1 = 0, \text{ then it's clear}$$

$$\text{So we may assume } u_1 \neq 0$$

Let $k \geq 0$ be the first integer s.t. u_1, \dots, u_k linearly independent and $\{u_1, \dots, u_k, u_{k+1}\}$ linearly dependent

So $a_1u_1 + \dots + a_ku_k + a_{k+1}u_{k+1} = 0$ for some scalar a_1, a_2, \dots, a_{k+1} (not all zero)

If $a_{k+1} = 0$, then $a_1u_1 + \dots + a_ku_k + a_{k+1}u_{k+1} = a_1u_1 + \dots + a_ku_k = 0$

$\therefore a_1 = \dots = a_k = a_{k+1} = 0$

It's a contradiction

Thus $u_{k+1} = b_1u_1 + \dots + b_ku_k \in \text{span}(u_1, \dots, u_k)$, where $b_i = -\frac{a_i}{a_{k+1}}$

16. (\Rightarrow) By the corollary of theorem 1.6

(\Leftarrow) $S \subseteq S$ is linearly independent

17. Let $M^{(1)} = (a_{11}, 0, \dots, 0)^t, M^{(2)} = (a_{12}, a_{22}, 0, \dots, 0)^t, \dots, M^{(n)} = (a_{1n}, a_{2n}, \dots, a_{nn})^t$

$M \in \text{span}\{M^{(1)}, M^{(2)}, \dots, M^{(n)} \mid a_{ii} \neq 0\}$

Suppose $k_1M^{(1)} + \dots + k_nM^{(n)} = 0$

$k_1 = k_2 = \dots = k_n = 0, \forall a_{ii} \neq 0$

$\therefore S$ is linearly independent

18. $f_0(x) = a_0$

$f_1(x) = a_0 + a_1x$

\vdots

$f_n(x) = a_0 + a_1x + \dots + a_nx^n$

$\Rightarrow k_0f_0(x) + k_1f_1(x) + \dots + k_nf_n(x) = 0$

1.5.

$$\Rightarrow k_n a_n = 0$$

$$(k_{n-1} + k_n) a_{n-1} = 0$$

\vdots

$$(k_0 + \cdots + k_n) a_0 = 0$$

$$\therefore \forall k_i = 0$$

19.

$$(a_1 A_1 + \cdots + a_k A_k)^t = (0)^t \Rightarrow a_1 A_1^t + \cdots + a_k A_k^t = 0$$

$$\therefore a_1 = \cdots = a_k = 0$$

$$\therefore \{A_1^t, \cdots, A_k^t\} \text{ is linearly independent}$$

20.

$$ae^{rt} + be^{st} = 0, \quad r \neq s$$

$$\Rightarrow a + be^{(s-r)t} = 0$$

$$\text{Since } e^{(s-r)t} \neq 0, \quad a = b = 0$$

$$\therefore \{e^{rt}, e^{st}\} \text{ is linearly independent}$$

1.6. Bases and Dimension

1. (a) F $(\cdot:)\emptyset$ is a basis for the zero vector space.

* $\text{span}\{\emptyset\} = \{0\}$ and \emptyset is linearly independent.

(b) T $(\cdot:)$ Theorem 1.9 ; If a vector space V is generated by a finite set S , then some subset of S is a basis for V .

(c) F (Counterexample) $\{1, x, x^2, \dots\}$ is a basis for $P(F)$

(d) F $(\cdot:)$ Corollary 2 (c) from Theorem 1.10

Every linearly independent subset of V can be extended to a basis for V .

(e) T $(\cdot:)$ Corollary 1 from Theorem 1.10

Let V be a vector space having a finite basis. Then every basis for V contains the same number of vectors.

(f) F $(\cdot:)$ $\{1, x, x^2, \dots, x^n\}$ is a basis for $P_n(F)$

(g) F $(\cdot:)$ The dimension of $M_{m \times n}(F)$ is $m \times n$

(h) T $(\cdot:)$ Replacement theorem.

(i) F

$(\cdot:)$ Theorem 1.8. Let V be a vector space and $\beta = \{u_1, u_2, \dots, u_n\}$ be a subset of V . Then β is a basis for V if and only if each $v \in V$ can be uniquely expressed as a linear combination of vectors of β .

(Example) $V = R^2$, $S = \{v_1 = (1, 0), v_2 = (0, 1), v_3 = (1, 1)\}$

$(a, b) = av_1 + bv_2 + 0v_3 = 0v_1 + (b - a)v_2 + av_3$

(j) T

Theorem 1.11. Let W be a subspace of a finite-dimensional vector space V . Then W is finite-dimensional and $\dim(W) \leq \dim(V)$. Moreover, if $\dim(W) = \dim(V)$, then $V = W$.

(k) T

(i) The vector space $\{0\}$ has dimension zero and 0 is unique element in V .

So V has exactly one subspace with dimension 0 .

(ii) From the theorem 1.11, $W \leq V$ as a subspace

If $\dim(W) = \dim(V)$, then $V = W$

So V has exactly one subspace with dimension n .

(l) T

(\Rightarrow) If S is linearly independent,

Let W be a space spanned by S .

Then S is a basis for W (the corollary 2 from 1.10)

And $\dim W = n$

$\therefore W = V$

$\therefore S$ is a basis for V

(\Leftarrow) If S is a generating set for V that contains n vectors,

then by the corollary 2 from 1.10, S is linearly independent.

2. (a) $\{(1, 0, -1), (2, 5, 1), (0, -4, 3)\} : \text{a basis for } R^3$

(\therefore) $0 = a \cdot (1, 0, -1) + b \cdot (2, 5, 1) + c \cdot (0, -4, 3) = (a + 2b, 5b - 4c, -a + b + 3c)$

$$\therefore a = b = c = 0$$

(*)

$$\begin{vmatrix} 1 & 0 & -1 \\ 2 & 5 & 1 \\ 0 & -4 & 3 \end{vmatrix} = 27 \neq 0$$

$\therefore \{(1, 0, -1), (2, 5, 1), (0, -4, 3)\}$ is linearly independent.

(b) $\{(2, -4, 1), (0, 3, -1), (6, 0, -1)\}$: a basis for R^3

$$(\because) 0 = a \cdot (2, -4, 1) + b \cdot (0, 3, -1) + c \cdot (6, 0, -1)$$

$$= (2a + 6c, -4a, a - b - c)$$

$$\therefore a = b = c = 0$$

(c) $\{(1, 2, -1), (1, 0, 2), (2, 1, 1)\}$: a basis for R^3

(d) $\{(-1, 3, 1), (2, -4, -3), (-3, 8, 2)\}$: a basis for R^3

(e) $\{(1, -3, -2), (-3, 1, 3), (-2, -10, -2)\}$

$$(\because) 0 = a \cdot (1, -3, -2) + b \cdot (-3, 1, 3) + c \cdot (-2, -10, -2)$$

$$= (a - 3b - 2c, -3a + b - 10c, -2a + 3b - 2c)$$

$$\therefore a = 2b, c = \frac{-1}{2}b$$

$$\therefore \exists (4, 2, 1) \neq (0, 0, 0)$$

(*)

$$\begin{vmatrix} 1 & -3 & -2 \\ -3 & 1 & 3 \\ -2 & 10 & -2 \end{vmatrix} = \begin{vmatrix} 1 & -3 & -2 \\ 0 & -8 & -3 \\ 0 & -16 & -6 \end{vmatrix} = 0$$

$\therefore \{(1, -3, -2), (-3, 1, 3), (-2, -10, -2)\}$ is linearly dependent.

$$3. \text{ (a) } \{-1 - x + 2x^2, 2 + x - 2x^2, 1 - 2x + 4x^2\}$$

$$(\because) 0 = a \cdot (-1 - x + 2x^2) + b \cdot (2 + x - 2x^2) + c \cdot (1 - 2x + 4x^2)$$

$$= (1 + 2a - 2b + 4c)x^2 + (-a + b - 2c)x + (-a + 2b + c)$$

$$\therefore a = -5c, b = -3c$$

$$\therefore \exists(-5, 3, 1) \neq (0, 0, 0)$$

(*)

$$\begin{vmatrix} -1 & -1 & 2 \\ 2 & 1 & -2 \\ 1 & -2 & 4 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ 2 & -1 & 2 \\ 1 & -3 & 6 \end{vmatrix} = 0$$

$\therefore \{-1 - x + 2x^2, 2 + x - 2x^2, 1 - 2x + 4x^2\}$ is linearly dependent.

(b) $\{1 + 2x + x^2, 3 + x^2, x + x^2\}$: a basis for $P^2(R)$

(c) $\{1 - 2x - 2x^2, -2 + 3x - x^2, 1 - x + 6x^2\}$: a basis for $P^2(R)$

(d) $\{-1 + 2x + 4x^2, 3 - 4x - 10x^2, -2 - 5x - 6x^2\}$: a basis for $P^2(R)$

(e) $\{1 + 2x - x^2, 4 - 2x + x^2, -1 + 18x - 9x^2\}$

$$(\because) 0 = a \cdot (-1 - x + 2x^2) + b \cdot (4 - 2x + x^2) + c \cdot (-1 + 18x - 9x^2)$$

$$= (-a + b - 9c)x^2 + (2a - 2b + 18c)x + (a + 4b - c)$$

$$\therefore a = -11c, b = -2c$$

$$\therefore \exists(-11, -2, 1) \neq (0, 0, 0)$$

4. No.

$$|\{x^3 - 2x^2 + 1, 4x^2 - x + 3, 3x - 2\}| = 3 \text{ and } \dim(P_3(R)) = 4$$

The generating set for V contains at least 4 vectors.

5. No.

Any $n + 1$ or more vectors in V are linearly dependent.

Since $\dim(R^3) = 3$, every linearly independent set contains at most 3 vectors.

6.

$$\begin{aligned} & \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\} \\ & \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \right\} \\ & \left\{ \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\} \end{aligned}$$

7.

Select any nonzero vector in the given set, say u_1 , to be a vector in the basis.

Since $u_3 = -4u_1$, the set $\{u_1, u_3\}$ is linearly dependent.

Hence we don't include u_3 .

On the other hand, the set $\{u_1, u_2\}$ is linearly independent. Thus we include u_2 .

And the set $\{u_1, u_2, u_4\}$ is linearly dependent. So we exclude u_4 .

$\therefore \{u_1, u_2, u_5\}$ is a basis for R^3 .

(*)

$$\begin{vmatrix} 2 & -3 & 1 \\ 1 & 4 & -2 \\ 1 & 37 & -17 \end{vmatrix} = \begin{vmatrix} 0 & -11 & 5 \\ 1 & 4 & -2 \\ 0 & 33 & -15 \end{vmatrix} = - \begin{vmatrix} -11 & 5 \\ 33 & -15 \end{vmatrix} = 0$$

$\therefore \{u_1, u_2, u_4\}$ is linearly dependent.

8. $\{u_1, u_3, u_4, u_8\}$ is a basis for W .

$$\begin{aligned} 9. \quad a, b, c, d \in F, (a_1, a_2, a_3, a_4) &= au_1 + bu_2 + cu_3 + du_4 \\ &= (a, a+b, a+b+c, a+b+c+d) \end{aligned}$$

$$\therefore a = a_1, b = a_2 - a_1, c = a_3 - a_2, d = a_4 - a_3$$

$$\therefore (a_1, a_2, a_3, a_4) = a_1u_1 + (a_2 - a_1)u_2 + (a_3 - a_2)u_3 + (a_4 - a_3)u_4$$

10. (a)

$$f_0(x) = \frac{1}{3}(x^2 - 1), \quad f_1(x) = -\frac{1}{2}(x^2 + x - 2), \quad f_2(x) = \frac{1}{6}(x^2 + 3x + 2)$$

$$\therefore g(x) = \sum_{i=0}^2 b_i f_i(x) = -4x^2 - x + 8$$

(b)

$$f_0(x) = \frac{1}{35}(x^2 - 4x + 3), \quad f_1(x) = -\frac{1}{10}(x^2 + x - 12), \quad f_2(x) = \frac{1}{14}(x^2 + 3x - 4)$$

$$\therefore g(x) = \sum_{i=0}^2 b_i f_i(x) = -3x + 12$$

(c)

$$\begin{aligned} f_0(x) &= -\frac{1}{15}(x^3 - 3x^2 - x + 3), \quad f_1(x) = -\frac{1}{8}(x^3 - 2x^2 - 5x + 6), \quad f_2(x) = \\ &= -\frac{1}{12}(x^3 - 7x^2 - 6), \quad f_3(x) = \frac{1}{40}(x^3 + 2x^2 - x - 2) \end{aligned}$$

$$\therefore g(x) = \sum_{i=0}^3 b_i f_i(x) = -x^3 + 2x^2 + 4x - 5$$

(d)

$$f_0(x) = -\frac{1}{12}(x^3 + x^2 - 2x), \quad f_1(x) = \frac{1}{6}(x^3 + 2x^2 - 3x), \quad f_2(x) = -\frac{1}{6}(x^3 + 4x^2 + x -$$

$$6), f_3(x) = \frac{1}{12}(x^3 + 5x^2 + 6x)$$

$$\therefore g(x) = \sum_{i=0}^3 b_i f_i(x) = -3x^3 - 6x^2 + 4x + 15$$

11. (i)

We need to show that $\{u + v, au\}$ is linearly independent

k_1, k_2 are scalars,

$$\text{If } k_1(u + v) + k_2(au) = (k_1 + ak_2)u + (k_1)v = 0$$

Since $\{u, v\}$ is a basis for V ,

$$\therefore k_1 + ak_2 = 0, k_1 = 0 \text{ (} a \text{ is a nonzero scalar)}$$

$$\therefore k_1 = k_2 = 0$$

(ii)

$$\text{If } k_1(au) + k_2(bv) = (ak_1)u + (bk_2)v = 0$$

Since $a \neq 0, b \neq 0$ and $\{u, v\}$ is a basis for V .

$$\therefore k_1 = k_2 = 0$$

$$\therefore \{au, bv\} \text{ is a basis for } V.$$

$$12. k_1(u + v + W) + k_2(v + w) + k_3(w) = 0, k_1, k_2, k_3 \in F$$

$$\Rightarrow k_1u + (k_1 + k_2)v + (k_1 + k_2 + k_3)w = 0$$

$$\Rightarrow k_1 = k_2 = k_3 = 0$$

$$13. \{a(1, 1, 1) | a \in R\} \text{ is a solution set}$$

$$\therefore \{(1, 1, 1)\} \text{ is a basis for the given system}$$

14. $\{(0, 0, 1, 0, 0), (0, 0, 0, 1, 0), (0, 1, 0, 0, 0), (0, 0, 0, 0, 1)\}$: a basis for W_1
 $\{(1, 0, 0, 0, -1), (0, 1, 1, 1, 0)\}$: a basis for W_2
 $\therefore \dim(W_1)=4, \dim(W_2)=2$

(*) The dimension of the solution space $AX = 0$ is equal to $n - \text{rank} A$

(n is the number of rows of A)

(i) $a_1 - a_3 - a_4 = 0$ i.e. $a_1 + 0a_2 - a_3 - a_4 + 0a_5 = 0$ —(*)

$$A = (1, 0, -1, -1, 0)_{1 \times 5}, \quad X = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \end{pmatrix}$$

(*) is equal to $AX = 0$

The dimension of the solution space $AX = 0$ is equal to $n - \text{rank} A = 5 - 1 = 4$

(ii) $a_2 = a_3, a_2 = a_4, a_1 + a_5 = 0$

$$A = \begin{pmatrix} 0 & 1 & -1 & 0 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 & 1 \end{pmatrix}_{3 \times 5}$$

$\therefore \text{rank}(A)=3$

The dimension of the solution space $AX = 0$ is equal to $n - \text{rank} A = 5 - 3 = 2$

15.

(i) $\{(\sum_{i,j=1}^n E_{ij}, \text{ where } i \neq j) \text{ and } (**)\}$: a basis for W .

$$(**) = \{(1, -1, 0, \dots, 0), (0, 1, -1, \dots, 0), \dots, (0, \dots, 1, -1, 0), (0, \dots, 1, -1)\}$$

that is, i th component of the element in $(**)$ is -1

$$(ii) \dim(W) = n^2 - n + (n - 1) = n^2 - 1$$

(\therefore) n^2 : the dim of $M_{n \times n}(F)$, n : the number of vectors consist of diagonal,

$(n - 1)$: the number of vectors consist of $(**)$

* When $\text{char } F = 2$, if $A^t = -A$, then $a_{ij} = -a_{ji}$ and $a_{ii} = -a_{ii}$

$$\therefore a_{ii} = 0$$

(Example)

$W = \{(a_1, a_2, a_3, a_4, a_5) \mid \sum_{i=1}^n a_i = 0\} \leq R^5$ is a subspace of V , $\dim(W) = 4$

$$\beta = \{v_1 = (1, -1, 0, 0, 0), v_2 = (1, 0, -1, 0, 0), v_3 = (1, 0, 0, -1, 0), v_4 = (1, 0, 0, 0, -1)\}$$

$$(\text{or } \beta = \{(1, -1, 0, 0, 0), (0, 1, -1, 0, 0), (0, 0, 1, -1, 0), (0, 0, 0, 1, -1)\})$$

$$\text{From } a_1 + a_2 + a_3 + a_4 + a_5 = 0, a_5 = -(a_1 + a_2 + a_3 + a_4)$$

$$(a_1, a_2, a_3, a_4, a_5) = (a_1, a_2, a_3, a_4, -(a_1 + a_2 + a_3 + a_4))$$

$$= (a_1, 0, 0, 0, -a_1) + (0, a_2, 0, 0, -a_2) + (0, 0, a_3, 0, -a_3) + (0, 0, 0, a_4, -a_4)$$

16.

$\forall A \in W$: the set of all upper triangular $n \times n$ matrices

1.6.

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & a_{22} & \cdots & a_{2n} \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & a_{nn} \end{pmatrix}$$

(i) $\{E_{ij} | E_{ij} = 0, i > j\}$ is a basis for W

(ii) $\dim(W) = 1 + 2 + \cdots + n = \frac{1}{2}n(n+1)$

17.

$\forall A \in W$: the set of all skew-symmetric $n \times n$ matrices

$$\begin{pmatrix} 0 & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & 0 & a_{23} & \cdots & a_{2n} \\ a_{31} & a_{32} & 0 & \cdots & a_{3n} \\ \vdots & & \ddots & & \vdots \\ a_{n1} & a_{n2} & a_{n3} & \cdots & 0 \end{pmatrix}, \quad a_{ij} = -a_{ji}$$

(i) A basis for W

$$\left\{ \left(\begin{array}{cc|c} 0 & 1 & \\ 1 & 0 & \\ \hline & & \end{array} \right), \left(\begin{array}{ccc|c} 0 & 0 & 1 & \\ 0 & 0 & 0 & \\ 1 & 0 & 0 & \\ \hline & & & \end{array} \right), \dots, \left(\begin{array}{c|cc} & & \\ \hline & 0 & 1 \\ & 1 & 0 \end{array} \right) \right\}$$

(ii) $\dim(W) = 1 + 2 + \cdots + (n-1) = \frac{1}{2}n(n-1)$

(iii) In case of $\text{char } F = 2$

if $A^t = -A$, then $a_{ij} \neq -a_{ji}$

(\therefore) if $a_{ii} = -a_{ii} \not\Rightarrow a_{ii} = 0$ in $\text{char}(F) = 2$

18. V consists of all sequences $\{a_n\}$ in F that have only a finite number of nonzero terms a_n

Let $\{e_i\} = \{0, \dots, 0, 1, 0, \dots, 0\}$ *i.e.* the i th term is 1

then $\{e_i \mid i = 1, \dots, n\}$ is a basis for V

19. (\Leftarrow) Suppose each $v \in V$ can be uniquely expressed as a linear combination of vectors of β , then clearly β spans V .

If $0 = a_1u_1 + a_2u_2 + \dots + a_nu_n$

And we also have $0 = 0 \cdot u_1 + 0 \cdot u_2 + \dots + 0 \cdot u_n$

By hypothesis, the representation of zero as a linear combination of the u_i is unique. Hence each $a_i = 0$, and the u_i are linearly independent.

20. (a) Prove that there is a subset of S that is a basis for V . (Be careful not to assume that S is finite.)

If $V = (0) \Rightarrow \emptyset (\subseteq S)$ a basis. So we may assume that $V \neq (0)$

Let $\mathcal{C} = \{B \mid B \subseteq S, B \text{ is linearly independent}\}$

then $\forall B \in \mathcal{C}, |B| \leq n (= \dim V)$

(i) Choose $B' \in \mathcal{C}$ with maximal element

i.e. $B' \in \mathcal{C}$ and $\forall B \in \mathcal{C}, |B| \leq |B'|$

(ii)

Claim $S \subseteq \text{span}(B')$

(\therefore) If not, $S \not\subseteq \text{span}(B')$, then $\exists v \in S, v \notin \text{span}(B')$

By the theorem 1.7(p.39), $B' \cup \{v\}$ is linearly independent

Since $B' \subsetneq B' \cup \{v\} \subseteq S$, this contradicts to the maximality of B'

And $V = \text{span}(S) \subseteq \text{span}(\text{span}(B')) = \text{span}(B')$

$\therefore V = \text{span}(B')$

Therefore B' is a basis for V

(b)

Let $Q \subseteq V$ s.t. $\text{span}(Q) = V$ and $|Q| < n$

From (a), we can find a subset Q' of Q is a basis for V .

This contradicts to the following fact :

If $\beta = \{v_1, v_2, \dots, v_n\}$ is a basis for V , then any set of $n + 1$ vectors in V is linearly dependent

\therefore Any spanning set S for V must contain at least n vectors.

21. (i) Suppose $\dim V = \infty$

$\Rightarrow V$ has an infinite set of linearly independent

(ii) By the Replacement theorem

22. $\dim(W_1 \cap W_2) = \dim(W_1) \Leftrightarrow W_1 \cap W_2 = W_1 \Leftrightarrow W_1 \subseteq W_2$

23. (a) $\dim(W_1) = \dim(W_2)$ if and only if $v \in \text{span}\{v_1, v_2, \dots, v_k\} = W_1$

(b) If $\dim(W_1) \neq \dim(W_2)$, then $\dim(W_1) < \dim(W_2)$

(\therefore) By (a), $v \in W_1$ and $v \notin W_2$

By the exercise 20, $\dim(W_1) \leq k$ and $\dim(W_2) \leq k + 1$

$$\therefore \dim(W_1) \leq \dim(W_2)$$

$$\therefore \dim(W_1) < \dim(W_2)$$

$$24. f(x) = k_n x^n + \cdots + k_1 x + k_0, \quad k_n \neq 0, \forall k_i \in R$$

Let $a_0 f(x) + a_1 f'(x) + \cdots + a_n f^{(n)}(x) = 0$, for some scalars $a_0, \dots, a_n \in R$

$$\text{then } (a_0 k_n) x^n + (a_0 k_{n-1} + a_1 k_n) x^{n-1} + \cdots + (a_0 k_1 + 2! a_1 k_2 + 3! a_2 k_3 + \cdots + n! a_{n-1} k_n) x + \left(\sum_{m=0}^n m! a_m k_m \right) = 0$$

By equating the coefficient of x^k on both sides of this equation for $k = 0, 1, 2, \dots, n$, we obtain $a_0 = a_1 = \cdots = a_n = 0$ (since $\text{char } R = 0$)

It follows from (b) of corollary 2 (p.48) that $\{f(x), f'(x), \dots, f^{(n)}(x)\}$ is a basis for $P_n(R)$.

$$\therefore \forall g(x) \in P_n(R), \exists c_0, \dots, c_n \in R \text{ s.t. } g(x) = c_0 f(x) + c_1 f'(x) + \cdots + c_n f^{(n)}(x)$$

$$25. Z = \{(v, w) \mid v \in V \text{ and } w \in W\} = V \times W$$

$$\dim(Z) = \dim(V) \times \dim(W) = mn$$

$\beta = \{v_1, \dots, v_m\}$ a basis for V

$\gamma = \{w_1, \dots, w_n\}$ a basis for W

then $\alpha = \{(v_1, 0), \dots, (v_m, 0), \dots, (0, w_1), \dots, (0, w_n)\}$ a basis for $V \times W$

26. $W = \{f \in P_n(R) \mid f(a) = 0\}$ is a subspace of $V = P_n(R)$

i.e. $\forall f \in W$ forms $(x - a)(a_{n-1}x^{n-1} + \cdots + a_1x + a_0)$

$\therefore \dim(W) = n$

27.

$$\dim(W_1 \cap P_n(F)) = \begin{cases} \frac{n}{2} & \text{if } n : \text{even} \\ \frac{n+1}{2} & \text{if } n : \text{odd} \end{cases}, \quad \dim(W_2 \cap P_n(F)) = \begin{cases} \frac{n}{2} + 1 & \text{if } n : \text{even} \\ \frac{n+1}{2} & \text{if } n : \text{odd} \end{cases}$$

28.

$$\dim V = 2n$$

$\beta = \{v_1, v_2, \dots, v_n\}$ a basis for V over \mathbb{C} , $\dim V = n$

$\beta' = \{v_1, v_2, \dots, v_n, v_1i, v_2i, \dots, v_ni\}$ a basis for V over \mathbb{R}

$$a_1v_1 + \cdots + a_nv_n + b_1v_1i + \cdots + b_nv_ni = 0$$

$$\Rightarrow (a_1 + ib_1)v_1 + \cdots + (a_n + ib_n)v_n = 0$$

29.

Let $\beta = \{u_1, \dots, u_k, v_1, \dots, v_m, w_1, \dots, w_p\}$ (i) β spans $W_1 + W_2$

$$\forall v \in W_1 + W_2, v = \left(\sum_{i=1}^k a_i u_i + \sum_{i=1}^m b_i v_i\right) + \left(\sum_{i=1}^k c_i u_i + \sum_{i=1}^p d_i w_i\right) \in \text{span}(\beta), w_1 \in$$

$W_1, w_2 \in W_2$ (ii) β is linearly independent

$$\text{Suppose that } a_1u_1 + \cdots + a_ku_k + b_1v_1 + \cdots + b_mv_m + c_1w_1 + \cdots + c_pw_p = 0 \text{ --- } (*)$$

, where $a_1, \dots, a_k, b_1, \dots, b_m, c_1, \dots, c_p \in F$

$$\text{Let } v = \sum_{i=1}^k a_i u_i + \sum_{i=1}^m b_i v_i = - \sum_{i=1}^p c_i w_i \in W_1 \cap W_2$$

Since $\{u_1, \dots, u_k\}$ is a basis for $W_1 \cap W_2$, $\exists d_i \in F$ s.t. $v = \sum_{i=1}^k d_i u_i$

$$\therefore \sum_{i=1}^k d_i u_i + \sum_{i=1}^p c_i w_i = 0 \Rightarrow c_1 = c_2 = \dots = c_p = 0$$

By (*), $a_1 = \dots = a_k = b_1 = \dots = b_m = 0$

$\therefore \beta$ is linearly independent

$\therefore \beta$ is a basis for $W_1 + W_2$

$$\therefore \dim(W_1 + W_2) = \dim(W_1) + \dim(W_2) - \dim(W_1 \cap W_2)$$

$$(b) \dim(W_1 + W_2) = 0 \Leftrightarrow W_1 \cap W_2 = \emptyset$$

30.

(i) W_1 and W_2 are subspaces of V

$$\forall A = \begin{pmatrix} a & b \\ c & a \end{pmatrix}, B = \begin{pmatrix} d & e \\ f & d \end{pmatrix} \in W_1, \alpha \in F$$

$$\alpha A + B = \begin{pmatrix} \alpha a + d & \alpha b + e \\ \alpha c + f & \alpha a + d \end{pmatrix} \in W_1$$

$$\forall A = \begin{pmatrix} 0 & a \\ -a & b \end{pmatrix}, B = \begin{pmatrix} 0 & c \\ -c & d \end{pmatrix} \in W_2, \alpha \in F$$

$$\alpha A + B = \begin{pmatrix} 0 & \alpha a + c \\ -\alpha a - c & b + d \end{pmatrix} \in W_2$$

(ii) $\dim(W_1) = 3, \dim(W_2) = 2, \dim(W_1 \cap W_2) = 1$ and $\dim(W_1 + W_2) = 4$

31. (a)

(\because) $W_1 \cap W_2$ is a subspace of W_1 ,

By the theorem 1.11, $\dim(W_1 \cap W_2) \leq \dim(W_1) \leq n$

$$\therefore \dim(W_1 \cap W_2) \leq n$$

(b)

$$\dim(W_1 + W_2) = \dim(W_1) + \dim(W_2) - \dim(W_1 \cap W_2) \leq m + n - \dim(W_1 \cap W_2)$$

$$\therefore \dim(W_1 + W_2) \leq m + n$$

32.

$$(a) \dim(W_1 \cap W_2) = \dim(W_2)$$

$$W_1 = \{(a_1, a_2, 0) | a_1, a_2 \in F\}, \dim(W_1)=2$$

$$W_2 = \{(a_1, 0, 0) | a_1 \in F\}, \dim(W_2)=1$$

$$(b) \dim(W_1 \cap W_2)=0$$

$$W_1 = \{(a_1, 0, 0) | a_1 \in F\}, \dim(W_1)=1$$

$$W_2 = \{(0, a_2, a_3) | a_2, a_3 \in F\}, \dim(W_2)=2$$

$$(c) W_1 = \{(a_1, 0, a_3) | a_1, a_3 \in F\}, \dim(W_1)=2$$

$$W_2 = \{(a_1, a_2, 0) | a_1, a_2 \in F\}, \dim(W_2)=2$$

$$33. V = W_1 \oplus W_2 \Leftrightarrow \beta_1 \cap \beta_2 = \emptyset, \beta_1 \cup \beta_2 : \text{a basis for } V$$

 (\Rightarrow)

$$(i) \text{ Suppose that } a_1u_1 + a_2u_2 + \cdots + b_1w_1 + b_2w_2 + \cdots = 0 \text{ } a_i, b_j \in F$$

$$\text{Then } a_1u_1 + a_2u_2 + \cdots = -(b_1w_1 + b_2w_2 + \cdots) \in W_1 \cap W_2 = \{0\}$$

$$\therefore \forall a_i = b_j = 0$$

$$\therefore \beta_1 \cup \beta_2 \text{ is linearly independent}$$

$$\text{Let } v = u + w \in W_1 + W_2$$

$$\text{Since } \beta_1, \beta_2 \text{ spans } W_1, W_2, \text{ respectively}$$

$$\exists a_i, b_j \in F \text{ s.t. } v = a_1u_1 + a_2u_2 + \cdots + b_1w_1 + b_2w_2 + \cdots$$

$$\therefore \beta_1 \cup \beta_2 \text{ spans } V$$

$$(ii) \text{ If } \exists 0 \neq u \in \beta_1 \cap \beta_2, \text{ then } W_1 \cap W_2 \neq \{0\}$$

$$\therefore \beta_1 \cap \beta_2 = \emptyset$$

$$(\Leftarrow)$$

$$(i) \text{ Since } \beta_1 \cup \beta_2 \text{ spans } V, v \in \text{span}(\beta_1 \cup \beta_2)$$

$$\therefore v = a_1u_1 + a_2u_2 + \cdots + b_1w_1 + b_2w_2 + \cdots \in W_1 + W_2$$

$$\therefore V = W_1 + W_2$$

$$(ii) \text{ Since } \beta_1 \cap \beta_2 = \emptyset, W_1 \cap W_2 = \{0\}$$

$$\therefore V = W_1 \oplus W_2$$

34. (a)

Let $\beta_1 = \{u_1, u_2, \dots, u_k\}$ be a basis for W_1

and we can extend it to a basis for V , say β

Let $\beta = \{u_1, u_2, \dots, u_k, u_{k+1}, \dots, u_n\}$ and $\beta_2 = \{u_{k+1}, u_{k+2}, \dots, u_n\}$

By the exercise 33, $V = W_1 \oplus W_2$

(b)

$$V = W_1 \oplus W_2, W_1 = \{(a, 0) | a \in R\}, W_2 = \{(0, b) | b \in R\}$$

$$V = W_1 \oplus W_{2'}, W_1 = \{(a, 0) | a \in R\}, W_{2'} = \{(-a, b) | a, b \in R\}$$

35.

(a) $\beta' = \{u_{k+1} + W, u_{k+2} + W, \dots, u_n + W\}$ is a basis for V/W . (p.23)

$$(i) \forall \alpha \in V/W = \{v + W | v \in V\}$$

$$\alpha = (a_1u_1 + a_2u_2 + \cdots + a_nu_n) + W$$

$$= (a_1u_1 + W) + (a_2u_2 + W) + \cdots + (a_nu_n + W)$$

$$= a_1(u_1 + W) + \cdots + a_k(u_k + W) + a_{k+1}(u_{k+1} + W) + \cdots + a_n(u_n + W)$$

$$= a_{k+1}(u_{k+1} + W) + a_{k+2}(u_{k+2} + W) + \cdots + a_n(u_n + W)$$

$$\therefore \beta' \text{ spans } V/W$$

$$(ii) \text{ Suppose } a_{k+1}(u_{k+1} + W) + a_{k+2}(u_{k+2} + W) + \cdots + a_n(u_n + W) = W, a_i \in F, i = k+1, \cdots, n$$

$$\text{then } a_{k+1}u_{k+1} + a_{k+2}u_{k+2} + \cdots + a_nu_n = 0$$

$$\text{Since } \{u_{k+1}, \cdots, u_n\} \text{ is linearly independent, } a_{k+1} = \cdots = a_n = 0$$

$$\therefore \beta' \text{ is a basis for } V/W.$$

$$(b) \dim(V) = k + n, \dim(W) = k, \dim(V/W) = n - k$$

$$\therefore \dim(V/W) = \dim(V) - \dim(W)$$

1.7. Maximal Linearly Independent Subsets

1. Label the following statement as true or false.

(a) Every family of sets contains a maximal element. (F)

(\therefore) Let \mathcal{F} be the family of all finite subsets of an infinite set S .

then \mathcal{F} has no maximal element.

(b) Every chain contains a maximal element. (F)

(\therefore) If A : a partial ordered set and every chain ($\neq \emptyset$) of A has an upper bound, then A has a maximal element.

(ex) $\mathbb{Z}, \mathbb{Q}, \mathbb{R}$

(c) If a family of sets has a maximal element, then that maximal element is unique. (F)

(\therefore) Let $S = \{a = x^3 - 2x^2 - 5x - 3, b = 3x^3 - 5x^2 - 4x - 9, c = 2x^3 - 2x^2 + 12x - 6\}$
then $\{a, b\}, \{a, c\}, \{b, c\}$ are maximal linearly independent subsets of S

So maximal element need not be unique.

(d) If a chain of sets has a maximal element, then that maximal element is unique.
(T)

(e) A basis for a vector space is a maximal linearly independent subset of that vector space. (T)

(f) A maximal linearly independent subset of a vector space is a basis for that vector space. (T)

2. Show that the set of convergent sequences is an infinite-dimensional subspace of the vector space of all sequences of real numbers. (See Exercise 21 in Section 1.3.)

(i) By the exercise 21 of section 1.3, W is a subspace of V

(ii) $\{1, 1, \dots\}$ is a basis for W

3. Let V be the set of real numbers regarded as a vector space over the field of rational numbers. Prove that V is infinite-dimensional.

Let V be a finite-dimensional vector space

$$\beta = \{v_1, \dots, v_n\}$$

Since $\pi \in V$, $\pi = \alpha_1 v_1 + \dots + \alpha_n v_n$, $\forall \alpha_i \in \mathbb{Q}$, $i = 1, \dots, n$

But π is a transcendental number in \mathbb{Q}

It's a contradiction

Thus V is infinite dimensional

4. Let W be a subspace of a (not necessarily finite-dimensional) vector space V . Prove that any basis for W is a subset of a basis for V .

(\therefore) Let β_W be a basis for W , then $\beta_W \subseteq V$

(i) By theorem 1.13, $\exists \beta$: a maximal linearly independent subset of V that contains β_W .

(ii) We are going to show that β is a basis for V which contains β_W .

Since β is linearly independent, so it suffices to show that β spans V .

If $v \in V$ and v is not contained in β (i.e. v is not in $\text{span}(\beta)$),

then $\beta \cup \{v\}$ is linearly independent.

This contradicts to the maximality of β .

$\therefore \forall v \in V, v \in \text{span}(\beta) \in V$

$\therefore \text{span}(\beta) = V$.

$\therefore \beta$ is a basis for V which contains β_W .

5.

(\therefore) (\Rightarrow) Let $\beta = \{v_1, v_2, \dots\}$ is a basis for V .

If $v \in V$, then $v \in \text{span}V$

Thus v is a linear combination of the vectors of β (that is v can be expressed by some finite vectors of β and scalars in F)

Suppose that $v = a_1v_1 + a_2v_2 + \dots + a_nv_n$ and $v = b_1v_1 + b_2v_2 + \dots + b_nv_n$

are two such representation of v . Then

$$0 = (a_1 - b_1)v_1 + (a_2 - b_2)v_2 + \dots + (a_n - b_n)v_n$$

Since β is linearly independent, it follows that $a_i = b_i$, where $1 \leq i \leq n$

(\Leftarrow) Suppose each $v \in V$ can be uniquely expressed as a linear combination of vectors of β , then clearly β spans V .

$$\text{If } 0 = a_1u_1 + a_2u_2 + \dots + a_nu_n$$

$$\text{And we also have } 0 = 0 \cdot u_1 + 0 \cdot u_2 + \dots + 0 \cdot u_n$$

By hypothesis, the representation of zero as a linear combination of the u_i is unique. Hence each $a_i = 0$, and the u_i are linearly independent.

6.

(i) Since $S_1 \in \mathcal{F}$, $\mathcal{F} \neq \emptyset$

Let C be a chain in \mathcal{F} and $U = \cup\{A \mid A \in C\}$

Clearly $S_1 \subseteq U \subseteq S_2$

Let $a_1u_1 + \cdots + a_nu_n = 0$ s.t. $\forall u_i \in U$, $\forall a_i \in F$, $i = 1, \dots, n$

Since $u_i \in A$, $\exists A_i \subseteq C$ s.t. $u_i \in A_i$

Since C is a chain, $\exists A_k$ a.t. $\forall A_i \subseteq A_k$

Thus $\forall u_i \in A_k \in F$

$\therefore a_1 = \cdots = a_n = 0$

So U is an upper bound of C

By the maximal principle, F has a maximal element β

i.e. β is a maximal linearly independent subset of V

(ii) $\forall v \in S_2$, if $v \in \beta$, then $v \in \text{span}(\beta)$

If $v \notin \beta$, $\beta \cup \{v\}$ is linearly independent

This contradicts to the maximality of β

$\therefore S_2 \subseteq \text{span}(\beta)$

Then $V = \text{span}(S_2) \subseteq \text{span}(\beta) \subseteq V$

$\therefore \text{span}(\beta) = V$

Therefore β is a basis for V s.t. $S_1 \subseteq \beta \subseteq S_2$

7. Let $\mathbb{S} = \{A \subseteq \beta \mid A \cap S = \emptyset, A \cup S \text{ is linearly independent} \}$

$\mathbb{S} \neq \emptyset$ ($\because A = \emptyset$)

Let C be a nonempty chain in \mathbb{S} and $B = \cup\{A \mid A \in C\}$

If $\exists x \in B \cap S$, then $x \in B$ and $x \in S$

Since $A \subseteq B$, $x \in A$ for some $A \in C$

thus $x \in A \cap S = \emptyset$

It's a contradiction, so $B \cap S = \emptyset$

If $a_1u_1 + \cdots + a_mu_m + b_1v_1 + \cdots + b_nv_n = 0$, $\forall a_i, b_j \in F$, $u_i \in B, v_j \in S$

Since $B = \cup\{A \mid A \in C\}$, $\exists A_1, \cdots, A_m \in C$ s.t. $\forall u_i \in A_i$

So we may assume that $u_1, \cdots, u_m \in A_m$

then $u_1, \cdots, u_m, v_1, \cdots, v_n \in A_m \cup S$ is linearly independent

$\therefore \forall a_i = 0, \forall b_j = 0$

$\therefore B \cup S$ is linearly independent

i.e. B is an upper bound of C

By the maximal principle, \mathcal{S} has a maximal element, say S_1

Clearly $S_1 \subseteq \beta$, $S_1 \cap S = \emptyset$, $S_1 \cup S$ is linearly independent

So we only need to show that either $\{S_1 \cup S \text{ is a maximal linearly independent subset of } V \text{ or } V\}$ or $\{\beta \subseteq \text{span}(S_1 \cup S)\}$

$\forall v \in \beta$, If $v \in S_1 \cup S$, then $v \in \text{span}(S_1 \cup S)$ If $v \notin S_1 \cup S$, then $S_1 \cup S \cup \{v\}$ is linearly independent

It's a contradiction, $\therefore \beta \subseteq \text{span}(S_1 \cup S)$

Therefore $S_1 \cup S$ is a basis for V

§2. Linear Transformations and Matrices

2.1. Linear Transformations, Null Spaces, and Ranges

1. (a) T

(b) F (\therefore) If $\forall x, y \in V$ and $c \in F$, $T(x + y) = T(x) + T(y)$ and $T(cx) = cT(x)$, then T is a linear transformation

(c) F (\therefore) T is linear and one-to-one if and only if

(d) T (\therefore) $T(0_V) = T(0_V + 0_V) = T(0_V) + T(0_V) \therefore T(0_V) = 0_W$

(e) F (\therefore) p.70 Theorem 2.3

(f) F (\therefore) T is linear and one to one, then

(g) T (\therefore) p.73 Corollary to Theorem 2.6

(h) F (\therefore) p.72 Theorem 2.6

2.

$$(1) T((a_1, a_2, a_3) + (b_1, b_2, b_3)) = T(a_1 + b_1, a_2 + b_2, a_3 + b_3)$$

$$= ((a_1 + b_1) - (a_2 + b_2), 2(a_3 + b_3))$$

$$= (a_1 - a_2, 2a_3) + (b_1 - b_2, 2b_3)$$

$$= T(a_1, a_2, a_3) + T(b_1, b_2, b_3)$$

$$T(c(a_1, a_2, a_3)) = T(ca_1, ca_2, ca_3) = (ca_1 - ca_2, 2ca_3) = c(a_1 - a_2, 2a_3) = cT(a_1, a_2, a_3)$$

Thus, T is linear.

$$(2) N(T) = \text{span}\{(1, 1, 0)\}$$

$$R(T) = \text{span}\{(1, 0), (0, 1)\}$$

$$(3) \text{ Dim}(V) = \text{nullity}(T) + \text{rank}(T) = 1 + 2$$

$$(4) T \text{ is not one-to-one } (\because N(T) \neq \{0\} = \{(0, 0, 0)\})$$

$$T \text{ is onto } (\because 2 = \text{rank}(T) = \text{dim}(W) = 2)$$

3.

$$(1) T \text{ is linear.}$$

$$(2) N(T) = \text{span}\{(0, 0)\}$$

$$R(T) = \text{span}\{(1, 0, 0), (0, 0, 1)\}$$

$$(3) \text{ Dim}(V) = \text{nullity}(T) + \text{rank}(T) = 0 + 2$$

$$(4) T \text{ is one-to-one } (\because N(T) = \{0\})$$

$$T \text{ is not onto } (\because 2 = \text{rank}(T) \neq \text{dim}(W) = 3)$$

4.

$$(1) T \text{ is linear.}$$

$$(2) N(T) = \text{span} \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right\},$$

$$R(T) = \text{span} \left\{ \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix} \right\}$$

$$(3) \text{ Dim}(V) = \text{nullity}(T) + \text{rank}(T) = 4 + 2$$

$$(4) T \text{ is not one-to-one } (\because N(T) \neq \{0\})$$

$$T \text{ is not onto } (\because 2 = \text{rank}(T) \neq \text{dim}(W) = 4)$$

$$5. (1) T \text{ is linear.}$$

$$(2) \ N(T) = \text{span}\{0\}$$

$$R(T) = \text{span}\{1, x, x^2\}$$

$$(3) \ \text{Dim}(V) = \text{nullity}(T) + \text{rank}(T) = 0 + 3$$

$$(4) \ T \text{ is one-to-one } (\because N(T) = \{0\})$$

$$T \text{ is not onto } (\because \text{rank}(T) \neq \text{dim}(W))$$

6. (1) T is linear.

$$(2) \ N(T) = \{A \mid T(A) = \text{tr}(A) = 0\} = \text{span}\{E_{ij}, E'_{ij}\},$$

where E_{ij} denote the matrix whose ij -entry is 1 and zero elsewhere

and E'_{ij} denote the matrix of a_{11} component is 1, a_{jj} component is -1 and others are all zero. ($2 \leq j \leq n$)

$$(*) \ \beta = \{E_{ij} \mid i \neq j\} \cup \{E_{11} - E_{ii} \mid 2 \leq j \leq n\}$$

$$R(T) = \{T(A) \mid A \in \text{Mat}_{n \times n}\} = \text{span}\{1\}$$

$$(3) \ n^2 = \text{Dim}(V) = \text{nullity}(T) + \text{rank}(T) = (n^2 - 1) + 1$$

$$* \ \dim N(T) = n^2 - 1 \text{ (p.56 exercise 15, sec 1.6)}$$

$$(4) \ T \text{ is not one-to-one but onto } (\because \text{rank}(T) = \text{dim}(W))$$

7.

$$(1) \ \text{If } T \text{ is linear, then } T(0) = 0$$

$$T(0) = T(0 + 0) = T(0) + T(0)$$

$$\therefore T(0) = 0$$

(2)

If T is linear, $T(cx + y) = T(cx) + T(y) = cT(x) + T(y)$

Suppose $T(cx + y) = cT(x) + T(y)$, then

$$c = 1, \quad T(x + y) = T(x) + T(y)$$

$$j = 0, \quad T(cx) = cT(x)$$

$$(3) \quad 0 = T(0) = T(x - x) = T(x) + T(-x)$$

$$\Rightarrow T(-x) = -T(x) \quad \forall x$$

$$\text{So } T(x - y) = T(x) + T(-y) = T(x) - T(y)$$

$$(4)$$

$$(\Rightarrow) \text{ If } T \text{ is linear, then } T\left(\sum_{i=1}^n a_i x_i\right) = \sum_{i=1}^n T(a_i x_i) = \sum_{i=1}^n a_i T(x_i)$$

$$(\Leftarrow) \text{ clear}$$

8. (a)

$$(i) \quad T_\theta((a_1, a_2) + (b_1, b_2)) = T_\theta(a_1 + b_1, a_2 + b_2)$$

$$= ((a_1 + b_1) \cos \theta - (a_2 + b_2) \sin \theta, (a_1 + b_1) \sin \theta + (a_2 + b_2) \cos \theta)$$

$$= (a_1 \cos \theta - a_2 \sin \theta, a_1 \sin \theta + a_2 \cos \theta) + (b_1 \cos \theta - b_2 \sin \theta, b_1 \sin \theta + b_2 \cos \theta)$$

$$= T_\theta(a_1, a_2) + T_\theta(b_1, b_2)$$

$$(ii) \quad T_\theta c((a_1, a_2)) = T_\theta(ca_1, ca_2) = (ca_1 \cos \theta - ca_2 \sin \theta, ca_1 \sin \theta + ca_2 \cos \theta)$$

$$= c(a_1 \cos \theta - a_2 \sin \theta, a_1 \sin \theta + a_2 \cos \theta) = cT_\theta(a_1, a_2)$$

(b)

$$(i) \quad T((a_1, a_2) + (b_1, b_2)) = T(a_1 + b_1, a_2 + b_2) = (a_1 + b_1, -a_2 - b_2) = (a_1 - a_2) +$$

$$(b_1 - b_2) = T(a_1 + a_2) + T(b_1 + b_2)$$

$$(ii) \quad T(c(a_1, a_2)) = (ca_1, -ca_2) = c(a_1, -a_2) = cT(a_1, a_2)$$

9. (a)

$$T((a_1 + a_2) + (b_1 + b_2)) = (1, a_2 + b_2)$$

$$T(a_1 + a_2) + T(b_1, b_2) = (2, a_2 + b_2)$$

(b)

$$T(c(a_1, a_2)) = (ca_1, c^2a_2^2) \quad cT(a_1, a_2) = (ca_1, ca_1^2)$$

(c)

$$T((a_1 + a_2) + (b_1 + b_2)) = (\sin(a_1 + b_1), 0)$$

$$T(a_1 + a_2) + T(b_1, b_2) = (\sin a_1 + \sin b_1, 0)$$

(d)

$$T((a_1 + a_2) + (b_1 + b_2)) = (|a_1 + b_1|, a_2 + b_2)$$

$$T(a_1 + a_2) + T(b_1, b_2) = (|a_1| + |b_1|, a_2 + b_2)$$

(e)

$$T((a_1 + a_2) + (b_1 + b_2)) = (a_1 + b_1 + 1, a_2 + b_2)$$

$$T(a_1 + a_2) + T(b_1, b_2) = (a_1 + b_1 + 2, a_2 + b_2)$$

10.

$$(a) \quad T(2, 3) = -1T(1, 0) + 3T(1, 1) = (5, 11)$$

(b) T is one-to-one

$$T(x, y) = xT(1, 0) + yT(0, 1) = xT(1, 0) + y(T(1, 1) - T(0, 1)) = x(1, 4) + y((2, 5) -$$

$$(1, 4)) = (x + y, 4x + y) = (0, 0)$$

$$\therefore (x, y) = (0, 0)$$

11. $T(8, 11) = 2T(1, 1) + 3T(2, 3) = (5, -3, 16)$

12. No $(T(2, 0, 6) \neq -2T(1, 0, 3))$

13.

$S = \{v_1, v_2, \dots, v_k\}$ s.t $T(v_i) = w_i, i = 1, 2, \dots, k$

Suppose $\sum_{i=1}^k a_i v_i = 0$ for some scalars $a_i \in F$,

then we need to show that all $a_i = 0$

$$T\left(\sum_{i=1}^k a_i v_i\right) = \sum_{i=1}^k a_i T(v_i) = a_i \sum_{i=1}^k w_i = T(0) = 0$$

Since w_i 's are linearly independent, so $a_i = 0$

$\therefore S$ is linearly independent.

14. (a)

$(\Rightarrow) \{v_1, v_2, \dots, v_n\}$ is linearly independent subset of V

If $\sum a_i T(v_i) = 0$, then

$$T\left(\sum a_i v_i\right) = 0 \text{ and } \sum a_i v_i \in N(T) = \{0\}$$

$$\therefore \forall a_i = 0$$

$\therefore \{T(v_1), \dots, T(v_n)\}$ is linearly independent subset of W

(\Leftarrow) Let $w_1 = \sum a_i T(v_i), \forall a_i, b_i \in F$

If $w_1 = w_2$, then $\sum (a_i - b_i) T(v_i) = 0$

Since $T(v_i)$'s are linearly independent, $\forall a_i = b_i$

$$\therefore \sum a_i v_i = \sum b_i v_i$$

$\therefore T$ is one-to-one

(b)

(\Rightarrow) By (a), $T(S)$ is linearly independent

(\Leftarrow) Let $T(S) = \{T(v_1), \dots, T(v_n)\}$ " linearly independent

If $\sum a_i v_i = 0$, then $\sum a_i T(v_i) = T(0) = 0$

$$\therefore \forall a_i = 0$$

$\therefore S = \{v_1, \dots, v_n\}$ is linearly independent

(c)

By (b), $T(\beta)$ is linearly independent

By the theorem 2.2, $R(T) = \text{span}(T(\beta))$

Since T is onto, $\text{span}(T(\beta)) = W$

$\therefore T(\beta)$ is a basis for W

15. (a)

$$(i) T(f(x) + g(x)) = \int_0^x (f(t) + g(t)) dt = \int_0^x f(t) dt + \int_0^x g(t) dt = T(f(x)) + T(g(x))$$

$$(ii) T(cf(x)) = \int_0^x cf(t) dt = c \int_0^x f(t) dt = cT(f(x))$$

$$(b) \text{ If } T(f(x)) = T(g(x)), \text{ then } \int_0^x f(t) dt = \int_0^x g(t) dt$$

$$i.e. \int_0^x (f(t) - g(t)) dt = 0$$

$$\therefore f(x) = g(x)$$

(c) $\{x, x^2, \dots\}$ is a basis for $R(T)$

Since $\text{span} R(T) \neq P(R)$, T is not onto

16. (a)

Let $f(x) = ax + b$, $g(x) = ax + d$, $b \neq d$ (i.e. $f(x) \neq g(x)$)

But $T(f(x)) = T(g(x))$

(b) $\beta = \{1, x, x^2, \dots\}$ is a standard basis for $P(R)$

It suffices to show that $\beta \subseteq R(T) = \text{span}(T(\beta))$

$\forall x^n \in \beta$, $x^n = T(\frac{1}{n+1}x^n) \in R(T)$

17. (a) By the theorem 2.3, $\dim R(T) \leq \dim V$

By the assumption, $\dim V < W$

$\therefore \dim R(T) < W$

$\therefore T$ can't be onto

(b) If T is one-to-one i.e. $\text{nullity}(T) = 0$, then $\dim V = \text{rank}(T) > \dim W$

It's a contradiction to $\dim R(T) \leq \dim W$

18. Let $\forall (a, b) \in R^2$, $T(a, b) = (0, a)$

Then $N(T) = \{(0, b) | b \in R\}$, $R(T) = \{(0, a) | a \in R\}$

$\therefore N(T) = R(T)$

19. $\forall (a, b) \in R^2$, Let $T(a, b) = (0, a)$ and $U(a, b) = (0, 2a)$

Then $T \neq U$, $N(T) = \{(0, b) | b \in R\}$, $N(U) = \{(0, b) | b \in R\}$

$R(T) = \{(0, a) | a \in R\}$, $R(U) = \{(0, 2a) | a \in R\}$

20.

(a) Let $w_1, w_2 \in T(v_1)$, $a \in F$ then $\exists v_1, v_2 \in V_1$ s.t. $w_i = T(v_i)$, $i = 1, 2$ So $aw_1 + w_2 = aT(v_1) + T(v_2) = T(av_1 + v_2) \in T(v_1)$ $\therefore T(v_1)$ is a subspace of W (b) Let $K = \{x \in V | T(x) \in W_1\}$, $a \in F$ Let $x_1, x_2 \in K$ s.t. $T(x_1) = w_1, T(x_2) = w_2 \in W_1$ $T(ax_1 + x_2) = aT(x_1) + T(x_2) = aw_1 + w_2 \in W_1$ $ax_1 + x_2 \in K$, $a \in F$ $\therefore \{x \in V | T(x) \in W_1\}$ is a subspace of V

21. (a)

(i) $T(c(a_1, a_2, \dots) + (b_1, b_2)) = T(ca_1 + b_1, ca_2 + b_2, \dots) = (ca_2 + b_2, ca_3 + b_3, \dots) = c(a_2, a_3, \dots) + (b_2, b_3, \dots) = cT(a_1, a_2, \dots) + T(b_1, b_2, \dots)$ (ii) $U(c(a_1, a_2, \dots) + (b_1, b_2)) = U(ca_1 + b_1, ca_2 + b_2, \dots) = (0, ca_1 + b_1, ca_2 + b_2, \dots) = (0, ca_1, ca_2, \dots) + (0, b_1, b_2, \dots) = cU(a_1, a_2, \dots) + U(b_1, b_2, \dots)$

(b)

(i) T is not one-to-one $0 \neq (1, 0, 0, \dots) \in N(T)$ (ii) T is onto $R(T) = \{(a_2, a_3, \dots) | \forall a_i \in F\} = \text{span}\{e_1, e_2, \dots\} = V$

(c)

(i) If $U(a_1, a_2, \dots) = (0, a_1, a_2, \dots) = (0, 0, \dots)$, then $\forall a_i = 0$

$$\therefore N(U) = \{0\}$$

(ii) U is not onto

$$R(U) = \{(0, a_1, a_2, \dots) | \forall a_i \in F\} \neq V$$

22.

(i) $T : R^3 \rightarrow R$ is linearLet $\beta = \{e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)\}$ a standard basis for R^3

$$\text{Put } T(e_1) = a, T(e_2) = b, T(e_3) = c$$

then $\forall (x, y, z) \in R^3$,

$$T(x, y, z) = T(xe_1 + ye_2 + ze_3) = xT(e_1) + yT(e_2) + zT(e_3) = ax + by + cz$$

(ii) $T : F^n \rightarrow F$ is linearLet $\beta = \{e_1, e_2, \dots, e_n\}$ a standard basis for F^n

$$\text{Put } T(e_1) = a_1, T(e_2) = a_2, \dots, T(e_n) = a_n$$

$$\text{then } T(x_1, x_2, \dots, x_n) = a_1x_1 + \dots + a_nx_n$$

(iii) $T : F^n \rightarrow F^m$

$$\text{For } \forall j \ (1 \leq j \leq m), \ T(e_j) = \sum_{i=1}^m a_{ij}w_i$$

$$\begin{aligned} T(x_1, x_2, \dots, x_n) &= T\left(\sum_{j=1}^n x_j e_j\right) = \sum_{j=1}^n x_j T(e_j) = \sum_{j=1}^n x_j \left(\sum_{i=1}^m a_{ij} w_i\right) = \sum_{j=1}^n \sum_{i=1}^m a_{ij} x_j w_i = \\ &= \sum_{i=1}^m \left(\sum_{j=1}^n a_{ij} x_j\right) w_i = \left(\sum_{j=1}^n a_{1j} x_j, \sum_{j=1}^n a_{2j} x_j, \dots, \sum_{j=1}^n a_{mj} x_j\right) \end{aligned}$$

23. $T : R^3 \rightarrow R$ linear transformation

By the exercise 22, $\exists a, b, c \in R$ s.t. $T(x, y, z) = ax + by + cz$

$$N(T) = \{(x, y, z) \in R^3 \mid T(x, y, z) = 0\}$$

$$= \{(x, y, z) \in R^3 \mid ax + by + cz = 0\}$$

$$= R^3 \text{ (where } a = b = c = 0\text{)}$$

a plane through 0 (where $a^2 + b^2 + c^2 \neq 0$)

24.

(a) The projection on the y -axis along the x -axis

$$T(a, b) = (0, b), \quad \forall (a, b) \in R^2, \quad A = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

(b)

$$T(a, b) = (a - b, a - b), \quad \forall (a, b) \in R^2$$

$$(a, b) \mapsto (0, 0) \text{ if } a = b$$

$$(a - b, a - b) \text{ otherwise}$$

25.

(a) Let $W_1 = \{(a, b, 0) \mid a, b \in R\}$, $W_2 = \{(0, 0, c) \mid c \in R\}$

Then $R^3 = W_1 \oplus W_2$

$\forall x = (a, b, c) \in R^3$ s.t. $x_1 = (a, b, 0) \in W_1$ and $x_2 = (0, 0, c) \in W_2$

$$T(x) = x_1$$

$\therefore T$ is the projection on the W_1 along the W_2 , $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$$(b) \ T(a, b, c) = (0, 0, c)$$

$$(c) \ \text{Let } W_1 = \{(a, b, 0) | a, b \in R\}, \ W_2 = L = \{(a, 0, a) | a \in R\}$$

$$\text{then } R^3 = W_1 + W_2$$

$$\text{For all } x = (a, b, c) \in R^3 \text{ s.t. } x = x_1 + x_2, \ x_1 = (a - c, b, 0) \in W_1, \ x_2 = (c, 0, c) \in W_2$$

$$T(a, b, c) = (a - c, b, 0) \in W_1$$

$$\therefore T : R^3 \rightarrow R^3 \text{ is the projection on } W_1 \text{ along the } W_2, \ A = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

26.

$$\forall x \in V \text{ s.t. } x = x_1 + x_2, x_1 \in W_1, x_2 \in W_2 \text{ and } T(x) = x_1$$

$$(1) \ T \text{ is linear}$$

$$\forall x, y \in V \text{ s.t. } x = x_1 + x_2, y = y_1 + y_2, x_1, y_1 \in W_1, x_2, y_2 \in W_2$$

$$T(x + y) = T((x_1 + y_1) + (x_2 + y_2)) = x_1 + y_1 = T(x) + T(y)$$

$$T(cx) = T(cx_1 + cx_2) = cx_1 = T(x)$$

$$(2) \ W_1 = \{x \in V \mid T(x) = x\}$$

$$(\subseteq) \ \text{If } x_1 \in W, \text{ then } T(x_1) = x_1$$

$$\therefore x_1 \in \{x \in V \mid T(x) = x\}$$

$$(\supseteq) \ \text{If } x \in V \text{ s.t. } T(x) = x \text{ and we have } T(x) = x_1$$

$$(\therefore) \ x = x_1 \in W_1$$

$$(b)$$

$$(1) W_1 = R(T)$$

2.1.

$$(\supseteq) \forall T(x) \in R(T), T(x) = x_1 \in W_1 \therefore R(T) \subseteq W_1$$

$$(\subseteq) \forall x_1 \in W_1, x_1 = T(x_1) \in R(T) \therefore W_1 \subseteq R(T)$$

$$(2) W_2 = N(T)$$

$$\forall x_2 \in W_2, T(x_2) = 0 \therefore x_2 \in N(T)$$

$$\therefore W_2 \subseteq N(T)$$

$$(\subseteq) \forall x \in N(T), T(x) = x_1 = 0 \therefore x = x_1 + x_2 = 0 + x_2 = x_2 \in W_2$$

$$(\supseteq) \therefore N(T) \subseteq W_2$$

(c) Describe if $W_1 = V$

$$T(x) = x, \forall x \in W_1 = V$$

$\therefore T$ is the identity transformation(I_V)

(d) Describe if $W_1 = 0$

$$T(x) = x \Leftrightarrow x = 0 \text{ (or } (0) = W_1 = R(T) \text{) } \therefore T \text{ is the zero transformation}(T_0)$$

27.

Claim : $\forall W \leq V, \exists W' \leq V$ as subspace, $T = W + W'$ and $T : V \rightarrow V, T(V) = W$

(a) From the exercise 34 in Section 1.6(p.58),

If W is any subspace of a finite dimensional vector space,

$$\exists W' \text{ s.t } V = W \oplus W'$$

$$\text{so } \forall x \in V, \exists! x_1 \in W, x_2 \in W' \text{ s.t } x = x_1 + x_2$$

Define $T : V \rightarrow V, T(x) = x_1$ is a desired linear transformation

Then T is a projection on W along W'

* Say $\dim V = n \geq 2$

$\{v_1, v_2, \dots, v_m\}$: a basis for W

$\{v_1, v_2, \dots, v_m, v_{m+1}, \dots, v_n\}$: a basis for V

Let $W' = \text{span}\{v_{m+1}, \dots, v_n\}$ and $W'' = \text{span}\{v_{m+1} - v_1, v_{m+2} - v_3, \dots, v_n - v_5\}$

then $V = W \oplus W' = W \oplus W''$

Clearly $W' \neq W''$

(\therefore) If $W' = W''$, then $v_{m+1}, v_{m+1} - v_1 \in W''$

$\therefore v_1 \in W \cap W' = (0)$

It's a contradiction

(b) Example

(example 1) the projection on W along W'_1

$$\{(a, b)\} = (0, b - \frac{1}{3}a) + (a, \frac{1}{3}a)$$

(example 2) the projection on W along W'_2

$$(a, b) = (0, b) + (a, 0)$$

28.

(1) $\{0\}$ is T -invariant

$\forall x \in \{0\}, T(x) = 0 \in \{0\}$ ($\therefore T$ is linear)

(2) V is T -invariant ($T(V) \subseteq V$)

$\forall x \in V, T(x) \in V$ ($\therefore T : V \rightarrow V$)

(3) $R(T)$ is T -invariant ($T(T(V)) \subseteq T(V)$)

$$\forall, T(x) \in R(T),$$

$$T(T(x)) \in T(V) \subseteq R(T)$$

(4) $N(T)$ is T -invariant

$\forall x \in N(T), T(x) = 0 \in N(T)$ ($\because N(T) \leq V$ as subspace, so $N(T)$ has zero)

29.

If $T(W) \subseteq W, \forall x, y \in W$, and $c \in F$

$T_W(x + y) = T(x + y) = T(x) + T(y) = T_W(x) + T_W(y)$ (W is T -invariant and T is linear)

$$T_W(cx) = T(cx) = cT(x) = cT_W(x)$$

$\therefore T_W$ is linear

30. $\forall x \in V, T(x) = x_1$ s.t $x = x_1 + x_2, x_1 \in W, x_2 \in W'$

(1) W is T -invariant

$$\forall x_1 \in W, T(x_1) = x_1 \in W \therefore T(W) \subseteq W$$

(2) $T_W = I_W$

$$T_W : W \rightarrow W, \forall x_1 \in W, T_W(x_1) = x_1$$

$$I_W : W \rightarrow W, \forall x_1 \in W, I_W(x_1) = x_1$$

$$\therefore \forall x_1 \in W, T_W(x_1) = I_W(x_1)$$

$$\therefore T_W = I_W$$

31. $V = R(T) \oplus W, W$ is T -invariant

(a)

$$T(W) \subseteq T(V) \cap W = (0) \Rightarrow T(W) = 0$$

$$\therefore T(W) \subseteq N(T) \text{ (b)}$$

$$\text{Since } V = R(T) \oplus W,$$

$$\text{so } \dim V = \dim R(T) + \dim W \leq \text{rank}(T) + \text{nullity}(T) = \dim V$$

$$\text{Since } \dim V < \infty, \dim W = \text{nullity}(T)$$

(c) (Example 1) Exercise 21, left shift

(Example 2) $\beta = \{v_1, v_2, \dots\}$ for V

$$T : V \rightarrow V, T(v_i) = 0 \text{ if } i \text{ is odd}$$

$$\frac{i}{2} \text{ if } i \text{ is even}$$

$$\text{Then } R(T) = V, N(T) = \text{span}(\{v_1, v_3, v_5, \dots\}), W = (0)$$

$$\therefore V = R(T) \oplus W$$

(Example 3) $\dim V = \aleph_0$, $\{v_1, v_2, v_3, v_4, v_5, v_6, \dots\}$: a basis for V $\{v_1, v_2, v_3, v_5, v_6, v_7, v_9, v_{10}, \dots\}$: a basis for $R(T)$ $\{v_3, v_4, v_7, v_8, v_{11}, v_{12}, v_{15}, v_{16}, \dots\}$: a basis for $N(T)$

$$W = \text{span}\{v_4, v_8, v_{12}, \dots\}$$

$$\text{i.e. } V = R(T) \oplus W, W \subsetneq N(T)$$

32.

$$(1) N(T_W) = N(T) \cap W$$

$$(\subseteq) N(T_W) = \{x_1 \in W \mid T_W(x_1) = 0\}$$

$$\forall x_1 \in N(T_W), x_1 \in W$$

$$T_W(x_1) = T(x_1) = 0 \text{ i.e. } x_1 \in N(T)$$

$$\therefore N(T_W) \subseteq N(T) \cap W$$

$$(\supseteq) \text{ If } x_1 \in N(T) \cap W, \text{ then } x_1 \in W \text{ and } T_W(x_1) = T(x_1) = 0 (\because x_1 \in N(T))$$

$$\therefore N(T) \cap W \subseteq N(T_W)$$

$$(2) R(T_W) = T(W), R(T_W) = \{T_W(x_1) \mid x_1 \in W\}$$

$$(\subseteq) \forall x_1 \in W, T_W(x_1) = T(x_1) \in T(W)$$

$$(\supseteq) \forall x_1 \in W, T(x_1) = T_W(x_1) \in R(T_W)$$

33. Prove theorem 2.2 in case β is infinite

$$\text{Claim : } R(T) = \text{span}(T(\beta)) = \text{span}\{T(v_1), T(v_2), \dots\}$$

$$(\supseteq) \text{ Clearly } T(v_i) \in R(T) \text{ for each } i.$$

Since $R(T) \leq V$ as subspace,

$$R(T) \supseteq \text{span}\{T(v_1), T(v_2), \dots\} = \text{span}(T(\beta))$$

$$(\subseteq) \text{ Suppose that } w \in R(T), \text{ then } w = T(v) \text{ for some } v \in V$$

Since β is a basis for V ,

each $v \in V$ can be uniquely expressed as a linear combination of vectors of β

It means there exist a finite number of vectors v_1, v_2, \dots, v_n in β and scalars

$$a_1, a_2, \dots, a_n \text{ in } F \text{ s.t. } v = \sum_{i=1}^n a_i v_i$$

$$\text{Since } T \text{ is linear, } w = T(v) = \sum_{i=1}^n a_i T(v_i) \in \text{span} T(\beta)$$

$$\therefore R(T) \subseteq \text{span}(T(\beta))$$

34. Generalization of theorem 2.6

Claim : $\forall f : \beta \rightarrow W, \exists! T(x) = f(x), \forall x_i \in \beta$

Let $f : \beta \rightarrow W$ s.t $f(x_i) = w_i$ where $\beta = \{x_i | i \in I\}$

Note that $\forall v \in V, v = a_i v_i$ in a unique way where $a_i \in F, x_i \in \beta$

Define $T : V \rightarrow W$ by $T(v) = \sum_i a_i f(x_i)$

(i) T is well-defined and unique

(ii) T is linear

(iii) $T(x) = f(x), \forall x \in \beta$

(*) Well-definess

(Example 1) $V = R^2, T : R^2 \rightarrow R$ by $v = a_1 v_1 + a_2 v_2 \mapsto (a_1 + a_2)$

$\beta = \{v_1 = (1, 1), v_2 = (1, -1)\}$

$\forall v = (a, b) = (\frac{a+b}{2}, \frac{a-b}{2}) + (\frac{a-b}{2}, -\frac{a-b}{2}) = \frac{a+b}{2}v_1 + \frac{a-b}{2}v_2$

Then actually $T : (a, b) \mapsto a$

(Example 2) $V = R^2, T : R^2 \rightarrow R$ by $v = a_1 v_1 + a_2 v_2 + a_3 v_3 \mapsto (a_1 + a_2 + a_3)$

$\beta = \{v_1 = (1, 1), v_2 = (1, -1), v_3 = (0, 1)\}$

$\forall v = (a, b) = \frac{a+b}{2}v_1 + \frac{a-b}{2}v_2 + 0 \cdot v_3 \mapsto a$ and $v = (a, b) = av_1 + 0 \cdot v_2 + (b-a)v_3 \mapsto b$

$\therefore T$ is not well-defined

35.

(a) Suppose $V = R(T) + N(T)$

Claim : $R(T) \cap N(T) = \{0\}$

(\supseteq) Since $R(T), N(T) \leq V$ as subspaces,

So $R(T)$ and $N(T)$ have $\{0\}$

$\therefore R(T) \cap N(T) \supseteq \{0\}$

(\subseteq) If $v \in R(T) \cap N(T)$,

then $\exists x \in V$ s.t $T(x) = v$ and $T(v) = 0$

$v = T(x) = T^2(x) = T(v) = 0$

(\because T is a projection on $R(T)$ along $N(T)$, then $T^2 = T$)

$\therefore R(T) \cap N(T) = \{0\}$

(b) Suppose $R(T) \cap N(T) = \{0\}$

We are going to show that $V = R(T) + N(T)$

Let $\dim V = n$, $\text{rank}(T) = m$, $\text{null}(T) = k$ and $n = m + k$,

and let $\beta_1 = \{w_1, w_2, \dots, w_m\}$ a basis for $R(T)$

$\beta_2 = \{u_1, u_2, \dots, u_k\}$ a basis for $N(T)$

Claim : $\beta = \beta_1 + \beta_2 = \{w_1, w_2, \dots, w_m, u_1, u_2, \dots, u_k\}$ is linearly independent

If $a_1w_1 + \dots + a_mw_m + b_1u_1 + \dots + b_ku_k = 0$, ($\forall a_i, b_j \in F$)

then $a_1w_1 + \dots + a_mw_m = -(b_1u_1 + \dots + b_ku_k) \in R(T) \cap N(T) = \{0\}$

$\therefore a_1 = \dots = a_m = b_1 = \dots = b_k = 0$

Since $\dim V = n$, β is a basis for V ,

$\forall v \in V$, $v = c_1w_1 + \dots + c_mw_m + d_1u_1 + \dots + d_ku_k = 0$, ($\forall c_i, d_j \in F$)

let $w = c_1w_1 + \dots + c_mw_m$ and $u = d_1u_1 + \dots + d_ku_k$

then $v = w + u \in R(T) + N(T)$

$$\therefore V = R(T) \oplus N(T)$$

36.

(a) We are going to show that if V is infinite-dimensional, then V doesn't hold the result of Exercise 35(a)

From Exercise 21, $\forall v = (a_1, a_2, \dots) \in V$, $T : V \rightarrow V$ is left shift

$$\text{then } N(T) = \{(a_1, 0, 0, \dots) \mid a_1 \in F\}$$

$$R(T) = \{(a_2, a_3, a_4, \dots) \mid \forall a_i \in F, i = 2, 3, \dots\}$$

$$\therefore \forall v \in V, v = (a_1, a_2, a_3, \dots) = (a_1, a_2, a_3, \dots) + (0, 0, 0, \dots) \in R(T) + N(T)$$

$$\therefore V = R(T) + N(T)$$

$$\text{But } R(T) \cap N(T) = \{(a, 0, 0, \dots) \mid a \in F\} \neq \{0\}$$

$$\therefore V \neq R(T) \oplus N(T)$$

(b) Find $T_1 : V \rightarrow V$ s.t $R(T_1) \cap N(T_1) = \{0\}$ but $V \neq R(T_1) \oplus N(T_1)$

$$\forall v \in V, T_1(v) = T(a_1, a_2, \dots) = (0, a_1, a_2, \dots)$$

$$\text{then } N(T_1) = \{0\}$$

$$R(T_1) = \{(0, a_1, a_2, \dots) \mid a_i \in F\}$$

$$\therefore R(T_1) \cap N(T_1) = \{0\}, \text{ but}$$

for $0 \neq a \in F$, $\exists v = (a, 0, 0, \dots)$ is not in $R(T_1) + N(T_1)$

$$\therefore R(T_1) + N(T_1) \subsetneq V$$

$$\therefore V \neq R(T_1) \oplus N(T_1)$$

37. We are going to show that $T(\alpha x) = \alpha T(x)$, $\alpha \in Q$

$$\forall x, y \in V, T(x + y) = T(x) + T(y)$$

$$\text{Let } \alpha = \frac{b}{a}, a, b \in Z, a \neq 0$$

$$T(\alpha x) = T\left(\frac{b}{a}x\right) = T\left(\frac{b}{a}a \cdot \frac{x}{a}\right) = \frac{b}{a} \cdot aT\left(\frac{x}{a}\right) = \frac{b}{a} \cdot T\left(a\frac{x}{a}\right) = \frac{b}{a}T(x)$$

$\therefore T$ is linear

38.

$$\forall x, y \in \mathbb{C} \text{ s.t } x = a + bi, y = c + di, \forall a, b, c, d \in \mathbb{R}, \alpha \in \mathbb{C}$$

$$T(x + y) = T((a + c) + (b + d)i) = (a + c) - (b + d)i = (a - bi) + (b - di) = T(x) + T(y)$$

$$\text{In case } \alpha = i, T(\alpha x) = T(-b + ai) = -b - ai$$

$$\text{but } \alpha T(x) = i(a - bi) = b - ai$$

$$\therefore T(\alpha x) \neq \alpha T(x)$$

$\therefore T$ is not linear

39.

Claim : $\exists T: \mathbb{R} \rightarrow \mathbb{R}$ is an additive function that is not linear

let V be the set of real numbers regarded as a vector space over the field of rational numbers.

Since every vector space has a basis (p.61), so V has a basis β

For fixed $x, y \in \beta$ s.t $x \neq y$

Define $f: \beta \rightarrow V$ by $f(x) = y, f(y) = x$ and $f(z) = z$ otherwise

By Exercise 34, $\exists! T: V \rightarrow V$: linear transformation over \mathbb{Q} s.t $T(u) = f(u), \forall u \in \beta$

Then T is additive (from exercise 37) but T is not linear over \mathbb{R}

(\because) In case $\alpha = \frac{y}{x}$,

$$T(\alpha x) = T\left(\frac{y}{x}x\right) = T(y) = f(y) = x$$

$$\alpha T(x) = \frac{y}{x} T(x) = \frac{y}{x} f(x) = \frac{y}{x} y = \frac{y^2}{x}$$

$$\therefore T(\alpha x) \neq \alpha T(x) \quad (\because x \neq y)$$

$\therefore T$ is not linear

40. $\eta: V \rightarrow V/W$, $\eta(v) = v + W$ ($v + W = 0$ in $V/W \Leftrightarrow v \in W$)

(a) Prove η is linear and $N(\eta) = W$

$$\forall v_1, v_2 \in V, c \in F$$

$$(1) \quad \eta(cv_1 + v_2) = (cv_1 + v_2) + W = cv_1 + W + v_2 + W = c(v_1 + W) + (v_2 + W) = c\eta(v_1) + \eta(v_2)$$

$$(2) \quad \forall v + W \in V/W, \exists v \in V$$

$$(3) \quad N(\eta) = W$$

$$(\because) (\supseteq) \text{ If } w \in W, \text{ then } \eta(w) = w + W = 0 + W$$

$$\therefore w \in N(\eta)$$

$$(\subseteq) \text{ If } v \in N(\eta), \text{ then } \eta(v) = 0 + W = w + W \text{ for some } w \in W$$

$$\therefore v \in W$$

(b) Suppose V is finite-dimensional ($\ker \eta = W$, $R(\eta) = V/W$)

$$\dim N(\eta) = \dim(W), \text{ Rank}(\eta) = \dim(V/W) = \dim V - \dim W \quad (\text{p.58 Sec1.6 Exercise35})$$

$$\dim V = \dim N(\eta) + \text{Rank}(\eta) = \dim(W) + \dim(V/W)$$

(c) same

2.2. The matrix representation of a linear transformation

1. $\beta = \{v_1, v_2, \dots, v_n\}$, $\gamma = \{w_1, w_2, \dots, w_m\}$ bases for V and W , respectively

(a) T (p.82 Theorem 2.7(a))

(b) T (p.73 The corollary to Theorem 2.6 and p.80)

(p.80) Let $T:V \rightarrow W$ is linear. Then for each j , $1 \leq j \leq n$, there exist unique scalars $a_{ij}, b_{ij} \in F$, $1 \leq i \leq m$ s.t

$$T(v_j) = \sum_{i=1}^m a_{ij} w_i, \quad U(v_j) = \sum_{i=1}^m b_{ij} w_i \text{ for } 1 \leq j \leq n$$

Suppose $[T]_{\beta}^{\gamma} = (a_{ij})_{m \times n}$, $[U]_{\beta}^{\gamma} = (b_{ij})_{m \times n}$

If $[T]_{\beta}^{\gamma} = [U]_{\beta}^{\gamma}$, then $T(v_j) = \sum_{i=1}^m a_{ij} w_i = \sum_{i=1}^m b_{ij} w_i = U(v_j)$ for all $a_{ij}, b_{ij} \in F, \forall v_j \in \beta$.

Hence $T=U$

(c) F ($[T]_{\beta}^{\gamma}$ is an $n \times m$ matrix)

(d) T (p.83 Theorem 2.8 (a))

(e) T ($0 \in \mathcal{L}(V, W)$) and Theorem 2.7 (a))

(f) F (p.104 $\mathcal{L}(V, W) \cong M_{m \times n}(F)$, $\mathcal{L}(W, V) \cong M_{n \times m}(F)$)

(cf) ($\mathcal{L}(V, W) \cong \mathcal{L}(W, V)$) but ($\mathcal{L}(V, W) \neq \mathcal{L}(W, V)$)

2. Compute $[T]_{\beta}^{\gamma}$

(a) $T(1,0)=(2,3,1)=2w_1 + 3w_2 + 1w_3$, $T(0,1)=(-1,4,0) = -1w_1 + 4w_2 + 0w_3$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} 2 & -1 \\ 3 & 4 \\ 1 & 0 \end{pmatrix}$$

$$(b) \quad T(1,0,0)=(2,1), \quad T(0,1,0)=(3,0), \quad T(0,0,1) = (-1,1)$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} 2 & 3 & -1 \\ 1 & 0 & 1 \end{pmatrix}$$

$$(c) \quad [T]_{\beta}^{\gamma} = (1, 0, -3)$$

$$(d) \quad [T]_{\beta}^{\gamma} = \begin{pmatrix} 0 & 2 & 1 \\ -1 & 4 & 5 \\ 1 & 0 & 1 \end{pmatrix}$$

$$(e) \quad [T]_{\beta}^{\gamma} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ 1 & 0 & \cdots & 0 \\ \vdots & \vdots & \cdots & \vdots \\ 1 & 0 & \cdots & 0 \end{pmatrix}$$

$$(f) \quad [T]_{\beta}^{\gamma} = \begin{pmatrix} 0 & 0 & \cdots & 0 & 1 \\ 0 & 0 & \cdots & 1 & 0 \\ \vdots & \vdots & \cdots & \vdots & \\ 0 & 1 & \cdots & 0 & 0 \\ 1 & 0 & \cdots & 0 & 0 \end{pmatrix}$$

$$(g) \quad [T]_{\beta}^{\gamma} = (1, 0, \cdots, 0, 1)$$

3.

$$(a) \quad T(1,0)=(1,1,2)=-\frac{1}{3}(1,1,0) + 0(0,1,1) + \frac{2}{3}(2,2,3)$$

$$T(0,1)=(-1,0,1)=-1(1,1,0) + 1(0,1,1) + 0(2,2,3)$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} -\frac{1}{3} & -1 \\ 0 & 1 \\ \frac{2}{3} & 0 \end{pmatrix}$$

$$(b) \quad T(1,2)=(-1,1,4)=-\frac{7}{3}(1,1,0) + 2(0,1,1) + \frac{2}{3}(2,2,3)$$

$$T(2,3)=(-1,2,7)=-\frac{11}{3}(1,1,0) + 3(0,1,1) + \frac{4}{3}(2,2,3)$$

$$[T]_{\alpha}^{\gamma} = \begin{pmatrix} -\frac{7}{3} & -\frac{11}{3} \\ 2 & 3 \\ \frac{2}{3} & \frac{4}{3} \end{pmatrix}$$

$$4. \beta = \{e_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, e_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, e_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}\}, \gamma = \{1, x, x^2\}$$

$$T\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = 1 + 0x + 0x^2, T\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = 1 + 0x + 1x^2,$$

$$T\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = 0 + 0x + 0x^2, T\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = 0 + 2x + 0x^2$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$5. \alpha = \{e_1, e_2, e_3, e_4\}, \beta = \{1, x, x^2\}, \gamma = \{1\}$$

(a)

$$T\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = 1e_1 + 0e_2 + 0e_3 + 0e_4,$$

$$T\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = 0e_1 + 0e_2 + 1e_3 + 0e_4,$$

$$T\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = 0e_1 + 1e_2 + 0e_3 + 0e_4,$$

$$T\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = 0e_1 + 0e_2 + 0e_3 + 1e_4$$

$$[T]_{\gamma} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$(b) T(1) = \begin{pmatrix} 0 & 2 \\ 0 & 0 \end{pmatrix} = 0e_1 + 2e_2 + 0e_3 + 0e_4,$$

$$T(x) = \begin{pmatrix} 1 & 2 \\ 0 & 0 \end{pmatrix} = 1e_1 + 2e_2 + 0e_3 + 0e_4,$$

$$T(x^2) = \begin{pmatrix} 0 & 2 \\ 0 & 2 \end{pmatrix} = 0e_1 + 2e_2 + 0e_3 + 2e_4,$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} 0 & 1 & 0 \\ 2 & 2 & 2 \\ 0 & 0 & 0 \\ 2 & 2 & 2 \end{pmatrix}$$

$$(c) \quad T(e_1)=1, \quad T(e_2)=0, \quad T(e_3)=0, \quad T(e_4)=1$$

$$[T]_{\alpha}^{\gamma} = (1, 0, 0, 1)$$

$$(d) \quad T(1)=1, \quad T(x)=2, \quad T(x^2)=4, \quad T(f(x))=f(2)$$

$$[T]_{\beta}^{\gamma} = (1, 2, 4)$$

$$(e) \quad A=1e_1 + (-2)e_2 + 0e_3 + 4e_4$$

$$[A]_{\alpha} = (1, -2, 0, 4)^T$$

$$(f) \quad f(x) = 3 \cdot 1 + (-6)x + 1x^2$$

$$[f(x)]_{\beta} = (3, -6, 1)^T$$

$$(g) \quad \gamma = \{1\}$$

$$[a]_{\gamma} = a$$

6. Theorem 2.7 (b)

$\mathcal{L}(V, W)$ is a vector space over F

(a) $T_0 \in \mathcal{L}(V, W)$, T_0 : the zero transformation

(b) $aT + U \in \mathcal{L}(V, W)$, $\forall T, U \in \mathcal{L}(V, W), \forall a \in F$

7. Theorem 2.8 (b)

Let $\beta = \{v_1, v_2, \dots, v_n\}$ and $\gamma = \{w_1, w_2, \dots, w_m\}$ bases for V and W , respectively

and let $[T]_\beta^\gamma = (a_{ij})_{m \times n}$, $a_{ij} \in F$

then $(aT)v_j = aT(v_j) = a \sum_{i=1}^m a_{ij}w_i = \sum_{i=1}^m a(a_{ij}w_i) = \sum_{i=1}^m (aa_{ij})w_i, \forall i$

So $[aT]_\beta^\gamma = (aa_{ij})_{m \times n} = a(a_{ij})_{m \times n} = a[T]_\beta^\gamma$

8. $\beta = \{v_1, \dots, v_n\}$: a basis for V

$\forall x, y \in V$ s.t $x = \sum_{i=1}^n a_i v_i, y = \sum_{i=1}^n b_i v_i \in V, a_i, b_i, c \in F$

$T(x) = [x]_\beta = (a_1, \dots, a_n)^t$

and $cx + y = \sum_{i=1}^n (ca_i + b_i)v_i$, then

$T(cx + y) = [cx + y]_\beta = (ca_1 + b_1, \dots, ca_n + b_n)^t = (ca_1, \dots, ca_n)^t + (b_1, \dots, b_n)^t =$

$c(a_1, \dots, a_n)^t + (b_1, \dots, b_n)^t = c[x]_\beta + [y]_\beta = cT(x) + T(y)$

$\therefore T$ is linear

(Indeed T is an isomorphism)

9.

$\forall x = a + bi, y = c + di \in \mathcal{C}, \alpha, a, b, c, d \in \mathcal{R}$

(a) $T(\alpha x + y) = T((\alpha a + c) + (\alpha b + d)i) = (\alpha a + c) - (\alpha b + d)i = (\alpha a - \alpha bi) + (c - di) =$

$\alpha(a - bi) + (c - d)i = \alpha T(a + bi) + T(c + di) = \alpha T(x) + T(y)$

$\therefore T$ is linear

(b) $T(1) = 1 = 1 \cdot 1 + 0 \cdot i$ and $T(i) = -i = 0 \cdot 1 + (-1) \cdot i$

$$A=[T]_{\beta} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

10. Compute $[T]_{\beta}$

$$T(v_1) = v_1 + v_0 = v_1 = 1 \cdot v_1 + 0 \cdot v_2 + \cdots + 0 \cdot v_n$$

$$T(v_2) = v_2 + v_1 = v_1 + v_2 = 1 \cdot v_1 + 1 \cdot v_2 + \cdots + 0 \cdot v_n$$

$$T(v_3) = v_3 + v_2 = v_2 + v_3 = 0 \cdot v_1 + 1 \cdot v_2 + 1 \cdot v_3 + \cdots + 0 \cdot v_n$$

\vdots

$$T(v_n) = v_n + v_{n-1} = v_{n-1} + v_n = 0 \cdot v_1 + 0 \cdot v_2 + \cdots + 1 \cdot v_{n-1} + 1 \cdot v_n$$

$$\therefore [T]_{\beta} = \begin{pmatrix} 1 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & 0 \\ 0 & 0 & 0 & \cdots & 1 & 1 \\ 0 & 0 & 0 & \cdots & 0 & 1 \end{pmatrix}$$

11.

We choose a basis $\{w_1, \dots, w_k\}$ of W and extend it to a basis of V ($\{w_1, \dots, w_k, v_1, \dots, v_s\}$)

Let $\dim V = n$ and $n = k + s$

$$T_W(w_1) = T(w_1) = a_{11}w_1 + \cdots + a_{1k}w_k + 0 \cdot v_1 + \cdots + 0 \cdot v_s$$

$$T_W(w_2) = T(w_2) = a_{21}w_1 + \cdots + a_{2k}w_k + 0 \cdot v_1 + \cdots + 0 \cdot v_s$$

\vdots

$$T_W(w_k) = T(w_k) = a_{k1}w_1 + \cdots + a_{kk}w_k + 0 \cdot v_1 + \cdots + 0 \cdot v_s$$

$$T(v_1) = b_{11}w_1 + \cdots + b_{1k}w_k + c_{11}v_1 + \cdots + c_{1s}v_s$$

$$T(v_2) = b_{21}w_1 + \cdots + b_{2k}w_k + c_{21}v_1 + \cdots + c_{2s}v_s$$

$$\vdots$$

$$T(v_s) = b_{s1}w_1 + \cdots + b_{sk}w_k + c_{s1}v_1 + \cdots + c_{ss}v_s$$

The matrix of T is the transpose of the matrix of coefficients in the above system of equations

$$\therefore [T]_{\beta} = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1k} & b_{11} & b_{12} & \cdots & b_{1s} \\ a_{21} & a_{22} & \cdots & a_{2k} & b_{21} & b_{22} & \cdots & b_{2s} \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ a_{k1} & a_{k2} & \cdots & a_{kk} & b_{k1} & b_{k2} & \cdots & b_{ks} \\ 0 & 0 & \cdots & 0 & c_{11} & c_{12} & \cdots & c_{1s} \\ 0 & 0 & \cdots & 0 & c_{21} & c_{22} & \cdots & c_{2s} \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 0 & c_{s1} & c_{s2} & \cdots & c_{ss} \end{pmatrix}$$

12. $T : V \rightarrow V$: the projection on W along W'

Let $\beta_1 = \{v_1, \dots, v_k\}$, $\gamma_1 = \{v_{k+1}, \dots, v_n\}$ bases for W and W' , respectively

Since $V = W \oplus W'$, $\beta = \beta_1 \cup \gamma_1$ is an ordered basis for V

Claim : $[T]_{\beta}$ is a diagonal matrix

Since $\beta = \{v_1, \dots, v_k, v_{k+1}, \dots, v_n\}$, $\forall x \in V, x = \sum_{i=1}^n a_i v_i, a_i \in F$

So $T(x) = \sum_{i=1}^n a_i T v_i$

$T(v_1) = v_1 = 1 \cdot v_1 + 0 \cdot v_2 + \cdots + 0 \cdot v_n$ ($\because v_1 \in W$)

$$\vdots$$

$T(v_k) = v_k = 0 \cdot v_1 + 0 \cdot v_2 + \cdots + 1 \cdot v_k + \cdots + 0 \cdot v_n$ ($\because v_k \in W$)

$T(v_{k+1}) = 0 = 0 \cdot v_1 + 0 \cdot v_2 + \cdots + 0 \cdot v_n$ ($\because v_{k+1} \in W'$)

$$\vdots$$

$T(v_n) = 0 = 0 \cdot v_1 + 0 \cdot v_2 + \cdots + 0 \cdot v_n$ ($\because v_n \in W'$)

$$\therefore [T]_{\beta} = \begin{pmatrix} 1 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & & \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & & \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & 0 & 0 & \cdots & 0 \end{pmatrix}_{n \times n} \leftarrow k - th$$

$\therefore [T]$ is a diagonal matrix

13. $\beta = \{v_1, v_2, \dots\}$: a basis for V

Claim: If $aT + bU = 0$, then $a = b = 0$, $a, b \in F$

Let $aT(v) + bU(v) = (aT + bU)(v) = 0(v) = 0$

$\Rightarrow aT(v) = -bU(v) \in R(T) \cap R(U) = 0$

$\Rightarrow (aT)(v) = 0, (bU)(v) = 0, \forall v \in V$

$\Rightarrow aT = 0, bU = 0$

$\Rightarrow^* a = 0, b = 0$ ($\because T, U \neq 0$)

[(*)

$a \in F, T \in \mathcal{L}(V, W)$

If $aT = 0 \Rightarrow$ either $a = 0$ or $T = 0$

(\because) Assume $a \neq 0 \Rightarrow \exists a^{-1} \in F$

$\Rightarrow T = 1 \cdot T = (a^{-1}a)T = a^{-1}(aT) = a^{-1}0 = 0$

or

Assume that $T \neq 0 \Rightarrow$

$\exists v \in F$ s.t. $T(v) \neq 0$

$$\Rightarrow a(T(v)) = (aT)(v) = T_0(v) = 0$$

$$\Rightarrow a = 0$$

$$(\because) aw = 0 \Rightarrow a = 0 \text{ or } w = 0 \rfloor$$

14.

Claim: If $(a_1T_1 + a_2T_2 + \cdots + a_nT_n)(x) = 0(x)$, then $a_1 = a_2 = \cdots = a_n = 0, a_i \in F$

Let $f(x) = k_0 + k_1x + k_2x^2 + \cdots + k_nx^n \in P(R)$

$$(a_1T_1 + a_2T_2 + \cdots + a_nT_n)(f(x)) = a_1T_1(f(x)) + a_2T_2(f(x)) + \cdots + a_nT_n(f(x)) = a_1f'(x) + a_2f''(x) + \cdots + a_nf^{(n)}(x) = 0$$

By Exercise 24. Sec1.6(p.56), we obtain $a_1 = a_2 = \cdots = a_n = 0$

$\therefore \{T_1, T_2, \cdots, T_n\}$ is a linearly independent subset of $\mathcal{L}(V)$, $\forall n \in Z^+$.

$$15. S^0 = \{T \in \mathcal{L}(V, W) \mid T(x) = 0, \forall x \in S\}$$

(a) S^0 is a subspace of $\mathcal{L}(V, W)$

$$(1) \forall x \in V, T_0 \in \mathcal{L}(V, W) \text{ s.t } T(x) = 0$$

$$\therefore \forall x \in S, T_0(x) = 0$$

$$\therefore T_0 \in S^0$$

$$(2) \text{ If } T_1, T_2 \in S^0, \alpha \in F, \forall x \in S$$

$$(\alpha T_1 + T_2)(x) = \alpha T_1(x) + T_2(x) = \alpha \cdot 0 + 0 = 0$$

$$\therefore \forall x \in S, (\alpha T_1 + T_2)(x) = 0$$

$$\therefore \alpha T_1 + T_2 \in S^0$$

$$(b) S_1^0 = \{T \in \mathcal{L}(V, W) \mid T(x) = 0, \forall x \in S_1\}$$

and $S_2^0 = \{T \in \mathcal{L}(V, W) \mid T(x) = 0, \forall x \in S_2\}$

If $T \in S_2^0$, then $\forall x \in S_2, T(x) = 0$

Since $S_1 \subseteq S_2, \forall x \in S_1, T(x) = 0$

$\therefore T \in S_1^0$

$\therefore S_2^0 \subseteq S_1^0$

(c) $(V_1 + V_2)^0 = V_1^0 \cap V_2^0$

(\subseteq) Since $V_1, V_2 \subseteq V_1 + V_2$ and (b)

$(V_1 + V_2)^0 \subseteq V_1^0$ and $(V_1 + V_2)^0 \subseteq V_2^0$

$\therefore (V_1 + V_2)^0 \subseteq V_1^0 \cap V_2^0$

(\supseteq) $\forall T \in V_1^0 \cap V_2^0$

Claim: $T \in (V_1 + V_2)^0$ (i.e. $\forall x \in V_1 + V_2, T(x) = 0$ s.t $x = x_1 + x_2, x_1 \in V_1, x_2 \in V_2$)

$T(x) = T(x_1 + x_2) = T(x_1) + T(x_2) = 0 + 0 = 0$ ($\because T$ is linear and $T \in V_1^0 \cap V_2^0$.)

$\therefore T \in (V_1 + V_2)^0$

16.

Let $\beta = \{v_1, \dots, v_n\}$ and $\gamma = \{w_1, \dots, w_n\}$: bases for V and W , respectively

Claim : $[T]_\beta$ is a diagonal matrix

Define $T(v_i) = w_i$ for $i = 1, 2, \dots, n$,

then $[T]_\beta^\gamma = I_n$

$\therefore [T]_\beta^\gamma$ is a diagonal matrix

2.3. Composition of Linear Transformations and Matrix Multiplication

1.

(a) F ($[UT]_\alpha^\gamma = [U]_\beta^\gamma [T]_\alpha^\beta$) (p.88 Theorem 2.11)

(b) T (p.91 Theorem 2.14)

(c) F ($[U(w)]_\gamma = [U]_\beta^\gamma [w]_\beta$ for all $w \in W$)

(d) T (Since $I_V(v_j) = v_j, 1 \leq i, j \leq n$ $[I_V]_\alpha = I_n$)

(e) F

In case $T: V \rightarrow V$, $[T^2]_\alpha = [T \cdot T]_\alpha = [T]_\alpha [T]_\alpha = ([T]_\alpha)^2$

(f) F

If $I \neq A = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{3}{2} & -\frac{1}{2} \end{pmatrix}$, then $A^2 = I$

(cf) $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

(g) F

($T: F^n \rightarrow F^m \Leftrightarrow T = L_A$ for some $A \in M_{m \times n}(F)$)

(h) F

If $A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, then $A^2 = 0$ even though $A \neq 0$

The cancelation property for multiplication in fields is not valid for matrices.

(i) T (p.93 Theorem 2.15(c))

(j) T (p.89 Definition)

2.

(a)

$$(1) A(2B+3C) = \begin{pmatrix} 20 & -9 & 18 \\ 5 & 10 & 8 \end{pmatrix}$$

$$(2) (AB)D = \begin{pmatrix} 29 & -26 \end{pmatrix}$$

$$(3) A(BD) = \begin{pmatrix} 29 & -26 \end{pmatrix}$$

(b)

$$(1) A^t = \begin{pmatrix} 2 & -3 & 4 \\ 5 & 1 & 2 \end{pmatrix}$$

$$(2) A^t B = \begin{pmatrix} 23 & 19 & 0 \\ 26 & -1 & 10 \end{pmatrix}$$

$$(3) BC^t = \begin{pmatrix} 12 \\ 16 \\ 19 \end{pmatrix}$$

$$(4) CB = \begin{pmatrix} 27 & 7 & 9 \end{pmatrix}$$

$$(5) CA = \begin{pmatrix} 20 & 26 \end{pmatrix}$$

3.

(a)

$$(1) [U]_{\beta}^{\gamma}$$

$$U(1) = U(1 + 0 \cdot x + 0 \cdot x^2) = (1, 0, 1)$$

$$U(x) = U(0 + 1 \cdot x + 0 \cdot x^2) = (1, 0, -1)$$

$$U(x^2) = U(0 + 0 \cdot x + 1 \cdot x^2) = (0, 1, 0)$$

$$\therefore [U]_{\beta}^{\gamma} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{pmatrix}$$

$$(2) [T]_{\beta}$$

$$T(1) = T(0 \cdot (3 + x) + 2 \cdot 1) = 2 = 2 \cdot 1 + 0 \cdot x + 0 \cdot x^2$$

$$T(x) = T(1 \cdot (3 + x) + 2 \cdot x) = 3x + 3 = 3 \cdot 1 + 3 \cdot x + 0 \cdot x^2$$

$$T(x^2) = T(2x \cdot (3 + x) + 2 \cdot x^2) = 4x^2 + 6x = 0 \cdot 1 + 6 \cdot x + 4 \cdot x^2$$

$$(3) [UT]_{\beta}^{\gamma} = [U]_{\beta}^{\gamma}[T]_{\beta}$$

$$(UT)(1) = U(T(1)) = U(2 \cdot 1 + 0 \cdot x + 0 \cdot x^2) = (2, 0, 2)$$

$$(UT)(x) = U(T(x)) = U(3 \cdot 1 + 3 \cdot x + 0 \cdot x^2) = (6, 0, 0)$$

$$(UT)(x^2) = U(T(x^2)) = U(0 \cdot 1 + 6 \cdot x + 4 \cdot x^2) = (6, 4, -6)$$

$$\therefore [UT]_{\beta}^{\gamma} = \begin{pmatrix} 2 & 6 & 6 \\ 0 & 0 & 4 \\ 2 & 0 & -6 \end{pmatrix}$$

$$\text{And } [U]_{\beta}^{\gamma}[T]_{\beta} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 3 & 0 \\ 0 & 3 & 6 \\ 0 & 0 & 4 \end{pmatrix} = \begin{pmatrix} 2 & 6 & 6 \\ 0 & 0 & 4 \\ 2 & 0 & -6 \end{pmatrix}$$

$$\therefore [UT]_{\beta}^{\gamma} = [U]_{\beta}^{\gamma}[T]_{\beta}$$

(b)

$$(1) [h(x)]_{\beta} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix}$$

$$(2) [U(h(x))]_{\gamma} = (1 \quad 1 \quad 5)$$

$$(3) [U(h(x))]_{\gamma} = [U]_{\beta}^{\gamma}[h(x)]_{\beta} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{pmatrix} \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} = (1 \quad 1 \quad 5)$$

4.

$$(a) [T(A)]_{\alpha} = [T]_{\alpha}[A]_{\alpha} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 4 \\ -1 \\ 6 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 4 \\ 6 \end{pmatrix}$$

$$(b) [T(f(x))]_{\alpha} = [T]_{\beta}^{\alpha} [f]_{\beta} = \begin{pmatrix} 0 & 1 & 0 \\ 2 & 2 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 4 \\ -6 \\ 3 \end{pmatrix} = \begin{pmatrix} -6 \\ 2 \\ 0 \\ 6 \end{pmatrix}$$

$$(c) [T(A)]_{\gamma} = [T]_{\alpha}^{\gamma} [A]_{\alpha} = \begin{pmatrix} 1 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \\ 2 \\ 4 \end{pmatrix} = (5)$$

$$(d) [T(f(x))]_{\gamma} = [T]_{\beta}^{\gamma} [f]_{\beta} = \begin{pmatrix} 1 & 2 & 4 \end{pmatrix} \begin{pmatrix} 6 \\ -1 \\ 2 \end{pmatrix} = (12)$$

5. Theorem 2.12

$$(a) (D+E)A=DA+EA$$

$$\begin{aligned} [(D+E)A]_{ij} &= \sum_{k=1}^m (D+E)_{ik} A_{kj} = \sum_{k=1}^m (D_{ik} + E_{ik}) A_{kj} = \sum_{k=1}^m (D_{ik} A_{kj} + E_{ik} A_{kj}) = \\ &= \sum_{k=1}^m D_{ik} A_{kj} + \sum_{k=1}^m E_{ik} A_{kj} = (DA)_{ij} + (EA)_{ij} = [DA+EA]_{ij} \end{aligned}$$

$$(b) a(AB) = (aA)B = A(aB) \text{ for any scalar } a$$

$$\text{We have } [a(AB)]_{ij} = \sum_{k=1}^n a(A_{ik} B_{kj}) = \sum_{k=1}^n (aA_{ik}) B_{kj} = [(aA)B]_{ij}$$

$$\text{and } [(aA)B]_{ij} = \sum_{k=1}^n (aA_{ik}) B_{kj} = \sum_{k=1}^n A_{ik} (aB_{kj}) = [A(aB)]_{ij}$$

$$\therefore a(AB) = (aA)B = A(aB)$$

$$(c) A_{ij} = \sum_{k=1}^n A_{ik} \delta_{kj} = \sum_{k=1}^n A_{ik} (I_n)_{kj} = (A \cdot I_n)_{ij}$$

$$(d) \text{ Let } \dim V = n \text{ and } \beta = \{v_1, \dots, v_n\}$$

$$I_V : V \rightarrow V \text{ s.t. } I_V(v_i) = v_i = 0 \cdot v_1 + \cdots + 0 \cdot v_{i-1} + 1 \cdot v_i + 0 \cdot v_{i+1} + \cdots + v_n$$

$$\therefore [I_V]_\beta = \begin{pmatrix} 1 & \cdots & 0 \\ & \ddots & \\ 0 & \cdots & 1 \end{pmatrix} = I_n$$

Corollary.

$$(1) A\left(\sum_{i=1}^k a_i B_i\right) = \sum_{k=1}^k AB_i$$

$$A\left(\sum_{i=1}^k a_i B_i\right) = A(a_1 B_1 + \cdots + a_k B_k) = A(a_1 B_1 + \cdots + A(a_k B_k)) = a_1 AB_1 + \cdots +$$

$$a_k AB_k = \sum_{i=1}^k a_i AB_i$$

$$(2) \left(\sum_{i=1}^k a_i C_i\right)A = (a_1 C_1 + \cdots + a_k C_k)A = (a_1 C_1)A + \cdots + (a_k C_k)A = \sum_{i=1}^k a_i C_i A$$

6. Theorem 2.13

(b)

$$v_j = \begin{pmatrix} B_{1j} \\ B_{2j} \\ \vdots \\ B_{nj} \end{pmatrix} = \begin{pmatrix} B_{11} & \cdots & B_{1j} & \cdots & B_{1n} \\ B_{21} & \cdots & B_{2j} & \cdots & B_{2n} \\ \vdots & & \vdots & & \vdots \\ B_{n1} & \cdots & B_{nj} & \cdots & B_{nn} \end{pmatrix} \begin{pmatrix} 0 & \cdots & 0 & 1(j-th) & 0 & \cdots & 0 \end{pmatrix}^t$$

$$\therefore v_j = B e_j$$

7. Theorem 2.15

(c) $\forall x \in F^n$

$$(1) L_{A+B}(x) = (A+B)x = Ax + Bx = L_A(x) + L_B(x) = (L_A + L_B)(x)$$

$$\therefore L_{A+B} = L_A + L_B$$

$$(2) L_{aA}(x) = (aA)x = a(Ax) = (aL_A)(x)$$

$$\therefore L_{aA} = aL_A$$

$$(f) \ L_{I_n} = I_{F^n}$$

$$L_{I_n}(x) = I_n x = x \text{ and } I_{F^n}(x) = x \ \forall x \in F^n$$

$$\therefore L_{I_n} = I_{F^n}$$

8.

(a)

$$(1) \ (T(U_1 + U_2))(x) = T((U_1 + U_2)(x)) = T(U_1(x) + U_2(x)) = T(U_1(x)) + T(U_2(x)) = (TU_1)(x) + (TU_2)(x) = (TU_1 + TU_2)(x)$$

$$\therefore T(U_1 + U_2) = TU_1 + TU_2$$

$$(2) \ (U_1 + U_2)T(x) = U_1(T(x)) + U_2(T(x)) = (U_1T)(x) + (U_2T)(x) = (U_1T + U_2T)(x)$$

$$\therefore (U_1 + U_2)T = U_1T + U_2T$$

(b)

$$T(U_1U_2)(x) = T(U_1(U_2(x))) = (TU_1)(U_2(x)) = (TU_1)U_2(x)$$

$$\therefore T(U_1U_2) = (TU_1)U_2 \text{ (c)}$$

$$TI(x) = T(I(x)) = T(x) \therefore TI = T$$

$$IT(x) = I(T(x)) = T(x) \therefore IT = T$$

(d)

$$(1) \ a(U_1U_2)(x) = aU_1(U_2(x)) = (aU_1)(U_2(x)) = ((aU_1)U_2)(x)$$

$$\therefore a(U_1U_2) = (aU_1)U_2$$

$$(2) \ U_1(aU_2)(x) = U_1(aU_2(x)) = aU_1(U_2(x)) = a(U_1U_2)(x)$$

$$\therefore U_1(aU_2) = a(U_1)U_2)$$

More general result

Let V, U, W be vector spaces over K . Suppose the following mappings are linear

$$F : V \rightarrow U, F' : V \rightarrow U \text{ and } G : U \rightarrow W, G' : U \rightarrow W$$

Then for any scalars $k \in K$

$$(1) G(F + F') = GF + GF'$$

$$(2) (G + G')F = GF + G'F$$

$$(3) k(GF) = (kG)F + G(kF)$$

9.

$$(1) \text{ Let } U : F^2 \rightarrow F^2 \text{ s.t } U(a, b) = (a + b, 0), \forall a, b \in F \text{ and}$$

$$T : F^2 \rightarrow F^2 \text{ s.t } T(a, b) = (a, -a), \forall a, b \in F$$

$$\text{then } UT(a, b) = U(a, -a) = (0, 0), \text{ i.e } UT = T_0 \text{ and } TU(a, b) = T(a + b, 0) =$$

$$(a + b, -a - b) \neq (0, 0), \text{ i.e } TU \neq T_0$$

$$(2) A = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, B = \begin{pmatrix} 1 & 0 \\ -1 & 0 \end{pmatrix}$$

$$\text{then } AB = 0 \text{ but } BA \neq 0$$

10.

$$(\supseteq) \text{ Since } A_{ij} = \delta_{ij}A_{ij}, \text{ if } i \neq j, \text{ then } A_{ij} = 0$$

thus A is a diagonal matrix

$$(\subseteq) \text{ Since } A \text{ is a diagonal matrix,}$$

if $i \neq j$, then $A_{ij} = 0$, thus $A_{ij} = \delta_{ij}A_{ij}$

and if $i = j$, then $\delta_{ij} = 1$, therefore $A_{ij} = \delta_{ij}A_{ij}$

11.

$(\subseteq) \forall v \in V, T(V) \in R(T)$, since $T(T(V)) = \{0\}$, $T(V) \in N(T)$

$\therefore R(T) \subseteq N(T)$

$(\supseteq) \forall v \in V, T(V) \subseteq R(T)$,

$\therefore R(T) \subseteq N(T)$

$\therefore T^2(v) \subseteq T(T(v) \subseteq T(N(T)) = 0$

$\therefore T^2 = T_0$

12.

(a) Assume $UT : V \rightarrow Z$ is one-to-one and let $T(V_1) = T(v_2)$ for $v_1, v_2 \in V$

Then $U(T(v_1)) = U(T(v_2))$ i.e $(UT)(v_1) = (UT)(v_2)$

Since UT is one-to-one, $v_1 = v_2$

$\therefore T$ is one-to-one

(Example)

$V = R^2, W = Z = R^3$

$T : V \rightarrow W \quad T(a, b) = (a, b, 0)$

$U : W \rightarrow Z \quad U(a, b, c) = (a, b, 0)$

(b) Assume that $UT : V \rightarrow Z$ is onto and let $z \in Z$

$$\exists v \in V \text{ s.t. } (UT)(v) = z$$

$$\text{Let } w = T(v)$$

$$\text{Then } w \in W \text{ and } U(W) = U(T(v)) = (UT)(v) = z$$

$$\therefore U : W \rightarrow Z \text{ is onto}$$

(Example)

$$V = W = R^3, \quad W = R^2$$

$$T : V \rightarrow W \quad T(a, b, c) = (a, b, 0)$$

$$U : W \rightarrow Z \quad U(a, b, c) = (a, b)$$

UT is one-to-one but U is not

$$(c) (1) \text{ Let } v_1, v_2 \in V \text{ and assume } (UT)(v_1) = (UT)(v_2)$$

$$\text{If } U(T(v_1)) = U(T(v_2)), \text{ then } T(v_1) = T(v_2) (\because U \text{ is one-to-one})$$

$$\text{and } v_1 = v_2 (\because T \text{ is one-to-one})$$

(Example)

$$V = W = R^2, \quad W = R^3$$

$$T : V \rightarrow W \quad T(a, b) = (a, b, 0)$$

$$U : W \rightarrow Z \quad U(a, b, c) = (a, b)$$

$$UT = i_{R^2} \text{ is one-to-one and onto}$$

$$(2) \text{ Let } z \in Z$$

$$\text{Since } U \text{ is onto, } \exists w \in W \text{ s.t. } z = U(w)$$

$$\text{and } T \text{ is onto, } \exists v \in V \text{ s.t. } w = T(v)$$

Thus $z = U(w) = U(T(v)) = (UT)(w)$

\therefore UT is onto

Therefore if U and T are one-to-one and onto, then so is UT.

13.

$$(a) \operatorname{tr}(AB) = \sum_{i=1}^n (AB)_{ii} = \sum_{i=1}^n \sum_{j=1}^n (A)_{ij} (B)_{ji} = \sum_{j=1}^n \left(\sum_{i=1}^n (B)_{ji} (A)_{ij} \right) = \sum_{j=1}^n (BA)_{jj} = \operatorname{tr}(BA)$$

$$(b) \operatorname{tr}(A) = \sum_{i=1}^n (A)_{ii} = \sum_{i=1}^n (A^t)_{ii} = \operatorname{tr}(A^t)$$

14.

$$(a) z = (a_1, a_2, \dots, a_p)^t = \sum_{j=1}^p a_j e_j$$

$$\text{So } Bz = B\left(\sum_{j=1}^p a_j e_j\right) = \sum_{j=1}^p a_j (Be_j) = \sum_{j=1}^p a_j v_j$$

$$(b) (AB)^j = (AB)e_j = A(Be_j) = Av_j = \sum_{k=1}^n b_{kj}(u_k), \quad v_j = (b_{1j}, \dots, b_{nj})^t$$

$$(c) wA = \left(\sum_{i=1}^m a_i e_i\right)A = \sum_{i=1}^m a_i (e_i A) = \sum_{i=1}^m a_i u_i$$

$$(d) (AB)_{(i)} = e_i(AB) = (e_i A)B = u_i B = \sum_{k=1}^n b_{ik}(v_k), \quad u_i = (b_{i1}, \dots, b_{in})$$

15.

$$M = (\gamma_{ij})_{m \times n}, \quad A = (a_{jk})_{n \times p}$$

$$\text{If } A^{(j)} = \sum b_k A^{(k)} \Rightarrow MA^{(j)} = M\left(\sum b_k A^{(k)}\right) = \sum b_k MA^{(k)} = \sum b_k (MA)^{(k)}$$

16.

(a) If $\text{rank}(T) = \text{rank}(T^2)$ *i.e.* $\dim R(T) = \dim R(T^2) \therefore \dim N(T) = \dim N(T^2)$ (i) But $\dim R(T) \leq \dim V < \infty \Rightarrow R(T) = R(T^2)$ ($\nRightarrow T = T^2$)(ii) and $\dim N(T^2) \leq \dim V < \infty \Rightarrow N(T) = N(T^2)$ (\because) If $v \in R(T^2) \Rightarrow v = T^2(z)$ for some $z \in V$ $\Rightarrow v = T(T(z)) \in R(T)$ $\therefore R(T^2) \subseteq R(T)$ (a) If $w \in R(T) \cap N(T)$ $\Rightarrow w = T(v)$ for some $v \in V$ Then $T^2(v) = T(w) = 0$ $\therefore v \in N(T^2) = N(T)$ $\therefore w = T(v) = 0$

(b)

Since $R(T) \supseteq R(T^2) \supseteq \dots$ we have $\dim V \geq \text{rank} T \geq \text{rank} T^2 \geq \dots \geq 0$ So $\exists k(\geq 1), \text{rank}(T^k) = \text{rank}(T^{k+1}) \Rightarrow^* R(T^k) = R(T^{k+1}) = \dots = R(T^{2k})$ $\lceil (*)$ If $w \in R(T^k) \Rightarrow w = T^k(v) = T^{k+1}(v_1)$ and $T^{k+1}(v_1) = T(T^k(v_1)) = T(T^{k+1}(v_2)) = T^{k+2}(v_2)$ \rfloor

$$\text{i.e. } R(T^k) = R(T^{2k})$$

$$\text{Let } u := T^k$$

$$\text{then } u^2 := T^{2k}$$

$$\therefore R(u) = R(u^2)$$

Using the similar way to this, then $V = R(U) \oplus N(U)$

$$\therefore V = R(T^k) \oplus N(T^k)$$

17.

For every $x \in V$, $x = T(x) + (x - T(x))$ and

we are going to show that $V = \{y \mid T(y) = y\} \oplus N(T)$

Since $T^2(x) = T(T(x)) = T(x)$, $T(x) \in \{y \mid T(y) = y\}$

and $T(T(x) - T(x)) = T(x) - T^2(x) = T(x) - T(x) = 0$

$$\therefore x - T(x) \in N(T)$$

$$\therefore V = \{y \mid T(y) = y\} + N(T)$$

and if $\exists x \in \{y \mid T(y) = y\} \cap N(T)$, then $x = 0$

(\because) Since $x \in \{y \mid T(y) = y\}$, $\therefore T(x) = x$

and $x \in N(T)$, $T(x) = 0$

$$\therefore x = 0$$

$$\therefore V = \{y \mid T(y) = y\} \oplus N(T)$$

18.

Let A be an $m \times n$ matrix, B be an $n \times p$ matrix and C be an $p \times q$ matrix

We are going to show that $(AB)C=A(BC)$, for $1 \leq i \leq m, 1 \leq j \leq q$

$$((AB)C)_{ij} = \left(\sum_{k=1}^p (AB)_{ik} C_{kj} \right) = \sum_{k=1}^p \left(\sum_{l=1}^n (A)_{il} B_{lk} \right) C_{kj} = \sum_{l=1}^n A_{il} \left(\sum_{k=1}^p B_{lk} C_{kj} \right) = \sum A_{il} (BC)_{lj} = (A(BC))_{ij}$$

19.

$$\begin{aligned} (B^3)_{kk} > 0 &\Leftrightarrow B_{ki} B_{ij} B_{jk} = 1 \text{ for some } i \neq j \text{ differ from } k \\ &\Leftrightarrow k \text{ belongs to a clique} \end{aligned}$$

20.

$$(a) \text{ Since } B^3 = \begin{pmatrix} 0 & 2 & 0 & 3 \\ 2 & 0 & 1 & 0 \\ 0 & 1 & 0 & 2 \\ 3 & 0 & 2 & 0 \end{pmatrix}, \text{ for all } B_{ii}^3 = 0$$

$\therefore \nexists$ clique

$$(b) \text{ Since } B^3 = \begin{pmatrix} 2 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 \\ 3 & 0 & 2 & 3 \\ 3 & 0 & 3 & 2 \end{pmatrix}$$

$\therefore 1, 3, 4$ belong to clique

21.

For convenience, let $A + A^2 = (b_{ij})_{n \times n}$ and for all $i (1 \leq i \leq n)$,

let $D(i) = \{j | a_{ij} = 1\}$

Choose a k such that $D(k)$ is maximal in the set $\{D(i) | 1 \leq i \leq n\}$

We will show that $b_{kj} = a_{kj} + \sum_{i=1}^n a_{ki} a_{ij} > 0$ for all $j \neq k$

For a fixed $j (\neq k)$, if $a_{kj} = 1$ then $b_{kj} > 0$

2.3.

Now suppose $a_{kj} = 0$, then $a_{jk} = 1$

So $k \in D(j)$

If (for the case $a_{kj} = 0$) $a_{ij} = 0$ for all $i \in D(k)$, then

$a_{ji} = 1$ and hence $D(k) \subseteq D(j)$

But $k \in D(j)$, $k \notin D(k)$

This is a contradiction to the choice of k

Thus $a_{ij} = 1$ for some $i \in D(k)$, and this proves the property $b_{kj} = a_{kj} + \sum_{i=1}^n a_{ki}a_{ij} > 0$

22.

1,2 and 3 dominate all the others in at most two stages, while 1,2, and 3 are dominated by all the others in at most two stages

23.

$$n(n-1)/2$$

2.4. Invertibility and Isomorphisms

1.

(a) F, $([T]_{\alpha}^{\beta})^{-1} = [T^{-1}]_{\beta}^{\alpha}$

(b) T

(c) F

$A \in Mat_{m \times n}(F)$, $L_A : F^n \rightarrow F^m$

$\Rightarrow [L_A]_{\alpha}^{\beta} = A$ in case of α, β are the standard bases

(d) F, $\dim(M_{2 \times 3}(F)) \neq F^5$

(e) $P_n(F) \simeq P_m(F)$ iff $n=m$

(\Leftarrow) clear

(\Rightarrow) $\exists T : P_n(F) \rightarrow P_m(F)$ is isomorphic

Since T is one-to-one and onto,

$\dim(P_n(F)) = \text{rank}(T) + \text{nullity}(T) = \dim(P_m(F))$

$\therefore n + 1 = m + 1$

$\therefore n = m$

(f) F (In case A and B are $n \times n$ matrices, it's true)

(g) T

(h) T (Exercise 8)

(i) T

2. T is invertible iff $[T]_{\beta}^{\gamma}$

$$(a) T : R^2 \rightarrow R^3, T(a_1, a_2) = (a_1 - 2a_2, a_2, 3a_1 + 4a_2)$$

For $\beta = \{(1, 0), (0, 1)\}$ and $\gamma = \{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ bases for R^2, R^3 , respectively

$$T(1, 0) = (1, 0, 3) = 1 \cdot (1, 0, 0) + 0 \cdot (0, 1, 0) + 3 \cdot (0, 0, 1)$$

$$T(0, 1) = (-2, 1, 4) = -2 \cdot (1, 0, 0) + 1 \cdot (0, 1, 0) + 4 \cdot (0, 0, 1)$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} 1 & -2 \\ 0 & 1 \\ 3 & 4 \end{pmatrix} \text{ is not a square matrix}$$

So $[T]_{\beta}^{\gamma}$ is not invertible

$\therefore T$ is not invertible

$$(b) T : R^2 \rightarrow R^3, [T]_{\beta}^{\gamma} \in M_{3 \times 2}(F) \text{ is not a square matrix}$$

$\therefore T$ is not invertible

$$(c) T : R^3 \rightarrow R^3,$$

$$T(1, 0, 0) = (3, 0, 3), T(0, 1, 0) = (0, 1, 4), T(0, 0, 1) = (-2, 0, 0)$$

$$\therefore [T]_{\beta}^{\gamma} = \begin{pmatrix} 3 & 0 & 2 \\ 0 & 1 & 0 \\ 3 & 4 & 0 \end{pmatrix} \text{ is invertible}$$

$\therefore T$ is invertible

$$(cf) \text{ If } T(a_1, a_2, a_3) = (3a_1 - 2a_2, a_2, 3a_1 + 4a_2) = (0, 0, 0,)$$

$$\text{then } (a_1, a_2, a_3) = (0, 0, 0)$$

$$\therefore \ker T = (0)$$

$$(d) T : P_3(R) \rightarrow P_2(R), T(p(x)) = p'(x)$$

$$[T]_{\beta}^{\gamma} \in M_{3 \times 4}(R) \text{ is not a square matrix}$$

$\therefore T$ is not invertible

$$(e) \ T : M_{2 \times 2}(R) \rightarrow P_2(R), T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a + 2bx + (c + d)x^2$$

$[T]_{\beta}^{\gamma} \in M_{3 \times 4}(R)$ is not a square matrix

$\therefore T$ is not invertible

$$(f) \ T : M_{2 \times 2}(R) \rightarrow M_{2 \times 2}(R), T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = T \begin{pmatrix} a+b & a \\ c & c+d \end{pmatrix}$$

$$[T]_{\beta}^{\gamma} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} \text{ is invertible}$$

$\therefore T$ is invertible

$$(cf) \text{ If } T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

then $a = b = c = d = 0$

$$\therefore \ker T = (0)$$

$\therefore T$ is invertible

3.

$$(a) \ F^3 \not\cong P_3(F) \ (\because) \dim F^3 \neq \dim P_3(F)$$

$$(b) \ F^4 \cong P_3(F)$$

$$(c) \ M_{2 \times 2}(R) \cong P_3(R)$$

$$(d) \ V = \{A \in M_{2 \times 2}(R) \mid \operatorname{tr}(A) = 0\} \not\cong R^4$$

$$(\because) \dim V = \left| \left\{ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right\} \right| = 3$$

$$\dim R^4 = \left| \{(1, 0, 0, 0), (0, 1, 0, 0), (0, 0, 1, 0), (0, 0, 0, 1)\} \right| = 4$$

$$\therefore \dim V \neq \dim R^4$$

4.

Let A and B $n \times n$ invertible matrix

Since $\exists A^{-1}$ and B^{-1} , $(AB)(B^{-1}A^{-1}) = I_n = (B^{-1}A^{-1})(AB)$

$\therefore B^{-1}A^{-1}$ is an inverse of AB

$\therefore AB$ is invertible and $(AB)^{-1} = B^{-1}A^{-1}$

5.

Let A is invertible

Since $\exists A^{-1}$ s.t $AA^{-1} = A^{-1}A = I_n$

$(A^{-1})^t A^t = (AA^{-1})^t = (I_n)^t = I_n$

$A^t (A^{-1})^t = (A^{-1}A)^t = (I_n)^t = I_n$

$\therefore (A^{-1})^t$ is an inverse of A^t

$\therefore (A^t)^{-1} = (A^{-1})^t$

6.

If A is invertible and $AB=0$, then $\exists A^{-1}$ s.t $A^{-1}A = AA^{-1} = I_n$

$\therefore B = IB = (A^{-1}A)B = A^{-1}0 = 0$

$\therefore B = 0$

7.

(a) Suppose $A^2 = 0$

Assume A is invertible, then $A^{-1}AA = A^{-1}0 \Rightarrow A = 0$

It's contradict to A is invertible

$\therefore A$ is not invertible

(b) Suppose $AB=0$ for some $0 \neq B \in M_{n \times n}(F)$

Assume A is invertible, then $A^{-1}AB = A^{-1}0 \Rightarrow B = 0$

It's contradict to $B \neq 0$

$\therefore A$ can't be invertible

8. (a) $[T]_{\beta}^{\beta} = [T]_{\beta}$

(b) $A = [L_A]_{\beta}$

$(\Leftrightarrow) A = [L_A]_{\beta} \in M_{m \times n}(F)$, where β the standard basis of F^n

Since L_A is invertible, so A is invertible

(\Rightarrow) Since $A = [L_A]_{\beta} \in M_{m \times n}(F)$ is invertible

$\therefore L_A$ is invertible

9.

Let $A, B \in M_{n \times n}(F)$ s.t AB is invertible

(a) Let $L_A, L_B, L_{AB} : F^n \rightarrow F^n$ be the left multiplication

Then clearly $L_AL_B = L_{AB}$ and L_{AB} is invertible since AB is invertible

$\therefore L_A$ is onto, L_B is one-to-one

By theorem 2.5, L_A and L_B are both invertible

$\therefore A$ and B are invertible

(b) Let $A = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & -1 \end{pmatrix}$, $B = \begin{pmatrix} 1 & 3 \\ -2 & 1 \\ 1 & 0 \end{pmatrix}$ then $AB = \begin{pmatrix} 1 & 3 \\ -1 & 7 \end{pmatrix}$ is invertible
 But A and B are not invertible

(Example) (b)

Let $A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$, $B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$ then $AB = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I$,
 but $BA = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \neq I$

10.

(a) $AB = I_n \Rightarrow A$ and B are invertible by exercise 9

(b) $\exists C \in \text{Mat}_{n \times n}(F)$ s.t. $CA = I_n$, so

$$C = CI_n = C(AB) = (CA)B = I_n B = B$$

that is, $BA = CA = I_n = AB$

$$\therefore B = A^{-1} \text{ or } A = B^{-1}$$

(c) Let V be of finite dimensional vector space and let $T : V \rightarrow V$ s.t. $TR = I_V$

(1) T is invertible

$$T, R : V \rightarrow V \text{ linear s.t. } TR = 1_V$$

Since $TR = 1_V$, T is onto

So T is invertible

Similarly R is one-to-one

and hence R is invertible

$$(2) R = T^{-1}$$

Since T is invertible, $\exists T^{-1} : V \rightarrow V$

$$\Rightarrow T^{-1} = T^{-1}1_V = T^{-1}(TR) = (T^{-1}T)R = IR = R$$

$$\therefore R = T^{-1}$$

$$11. T : P^3(R) \rightarrow M_{2 \times 2}(R) \text{ is linear by } T(f) = \begin{pmatrix} f(1) & f(2) \\ f(3) & f(4) \end{pmatrix}$$

We are going to show that $T(f) = 0 \Rightarrow f = 0$ (the zero polynomial)

$$\text{In this case, } f(1) = 0 (\text{i.e. } f(c_0) = b_0), f(2) = 0, f(3) = 0, f(4) = 0$$

$$\therefore \forall f(c_i) = 0, i = 0, 1, 2, 3$$

$$\therefore f(x) = \sum_{i=0}^3 b_i f_i(x) = \sum_{i=0}^3 f(c_i) f_i(x) = 0$$

$$\therefore f \text{ is the zero polynomial}$$

$$\therefore T \text{ is one-to-one}$$

$$12. \phi_\beta(v_i) = [v_i]_\beta = e_i = (0, \dots, 1, \dots, 0)^t$$

$$[\phi_\beta]_\beta^\gamma = I_n, \text{ when } \gamma \text{ is the standard basis for } F^n$$

$$\therefore \phi_\beta \text{ is an isomorphism}$$

or

$$\phi_\beta : V \rightarrow F^n \text{ is onto}$$

$$\Rightarrow \phi_\beta \text{ is an isomorphism because } \dim V = \dim F^n$$

$$13. \sim \text{ is an equivalence relation on the class of vector space over } F$$

$$(i) \sim \text{ is reflexive}$$

$$\forall V \in \mathcal{C}, V \sim V$$

(\cdot) $I_V : V \rightarrow V$ s.t $I_V = v, \forall v \in V$ is an isomorphism

(ii) \sim is symmetric

If $V \sim W$, then $W \sim V$

(\cdot) If $T : V \rightarrow W$ is isomorphic then $\exists T^{-1} : W \rightarrow V$ is isomorphic

$\therefore W \sim V$

(iii) \sim is transitive

If $V \sim W$ and $W \sim Z$, then $V \sim Z$

(\cdot) Let $T : V \rightarrow W$ and $U : W \rightarrow Z$ are isomorphic, then UT is isomorphic

14.

Let $V = \left\{ \begin{pmatrix} a & a+b \\ 0 & c \end{pmatrix} \mid a, b, c \in F \right\}$

$T : V \rightarrow F^3$ s.t $T \begin{pmatrix} a & a+b \\ 0 & c \end{pmatrix} = (a, b, c)$

For the basis for V , $\{v_1 = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, v_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, v_3 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}\}$

$\exists! T(v_i) = w_i$ is linear, $w_i \in F^3$ $i = 1, 2, 3$

and since $\dim V = \dim F^3$, V is isomorphic to F^3

$\therefore T$ is an isomorphism from V to F^3

15.

T is isomorphic iff $T(\beta)$ is a basis for W

(\Rightarrow) Section 2.1 exercise 14 (c) (p75)

$$(\Leftarrow) T(\beta) = \{T(v_1), T(v_2), \dots, T(v_n)\}$$

$$\forall w \in W$$

$$w = \sum a_i T(v_i) = T(\sum a_i v_i) = T(v), \text{ where } v = \sum a_i v_i \in V$$

$\therefore T$ is onto

$\therefore T$ is invertible since $\dim V = \dim W = n$

$$16. \Phi : M_{n \times n}(F) \rightarrow M_{n \times n}(F)$$

$$c \in M_{m \times n}(F), \exists A = B^{-1}CB \in M_{m \times n}(F) \text{ s.t. } \Phi(A) = C$$

$\therefore \Phi$ is onto

$\therefore \Phi$ is an isomorphism

17. V is finite dimensional and $T : V \rightarrow V$ is isomorphic

let $v_0 \in V$

(a) $T(V_0) \leq W$ as a subspace

$$(i) T(v_1) + T(v_2) = T(v_1 + v_2) \in T(V_0)$$

$$(ii) T(av) = aT(v) \in T(V_0)$$

(b) Since T is an isomorphism, $\text{rank}(T) = \dim W$ and $\text{nullity}(T) = 0$

therefore $\text{nullity}(T|_{V_0}) = 0$

$$\dim(V_0) = \text{rank}(T|_{V_0}) + \text{nullity}(T|_{V_0}) = \dim(T(V_0))$$

,where $T|_{V_0} : V_0 \rightarrow T(V_0) (\subseteq W)$

the restriction

18.

$$A = [T]_{\beta}^{\gamma} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix}$$

$$L_A \pi_{\beta}(p(x)) = \pi_{\gamma} T(p(x)) = \begin{pmatrix} 1 \\ 4 \\ 9 \end{pmatrix}$$

$$L_A \pi_{\beta}(p(x)) = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \\ 9 \end{pmatrix}$$

Since $T(p(x)) = p'(x) = 1 + 4x + 9x^2$

So $L_A \pi_{\beta}(p(x)) = \pi_{\gamma} T(p(x))$

19.

$$(a) A = [T]_{\beta}^{\gamma} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$(b) L_A \pi_{\beta}(M) = A \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ 2 \\ 4 \end{pmatrix}$$

Since $T(M) = M^t = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$

We have $\pi_{\gamma} T(M) = (1 \ 3 \ 2 \ 4)^t$

20.

Let $A = (a_{ij})_{m \times n}$ be an incidence matrix associated with a dominance relation

Then $A + A^2$ has a row[column] in which every entry, except for the orthogonal,

is positive

(\therefore) For convenience, let $A + A^2 = (b_{ij})_{n \times n}$

and for $\forall i$ ($1 \leq i \leq n$), let $D(i) = \{j \mid a_{ij} = 1\}$

Choose a k such that $D(k)$ is maximal in the set $\{D(i) \mid 1 \leq i \leq n\}$

We will show that $b_{kj} = a_{kj} + \sum_{i=1}^n a_{ki}a_{ij} > 0$ for all $j \neq k$

For a fixed $j (\neq k)$, if $a_{kj} = 1$ then $b_{kj} > 0$

Now suppose $a_{kj} = 0$, then $a_{ij} = 1 \Rightarrow k \in D(j)$

If (for the case $a_{kj} = 0$), $a_{ij} = 0$ for all $i \in D(k)$, then

$a_{ij} = 1$ and hence $D(k) \subseteq D(j)$

But $k \in D(j)$, k is not in $D(k)$

This is a contradiction to the choice of k

Thus $a_{ij} = 1$ for some $i \in D(k)$ and

this proves the property $b_{kj} = a_{kj} + \sum_{i=1}^n a_{ki}a_{ij} > 0$

21. $\{T_{ij} \mid 1 \leq i \leq m, 1 \leq j \leq n\}$ is a basis for $\dim \mathcal{L}(V, W)$

(a) Since $\dim \mathcal{L}(V, W) = mn$,

we need to show that the given set is linearly independent

Let $\sum_{i=1}^m \sum_{j=1}^n a_{ij}T_{ij} = 0, a_{ij} \in F$

$\forall k (1 \leq k \leq n),$

$$0 = \left(\sum_{i=1}^m \sum_{j=1}^n a_{ij}T_{ij} \right)(v_k) = \sum_{i=1}^m a_{ik}w_i$$

and $\xi = \{w_1, \dots, w_n\}$ is a basis for W

$$\therefore a_{ik} = 0, \forall i, k$$

$$\therefore \forall a_{ij} = 0$$

\therefore It's linearly independent

(b)

$$\beta = \{v_1, v_2, \dots, v_n\}, \gamma = \{w_1, w_2, \dots, w_n\}$$

$\{T_{ij} \mid 1 \leq i \leq m, 1 \leq j \leq n\}$ a basis for $\mathcal{L}(V, W)$ by (a)

$$\forall k, T_{ij}(v_k) = 0w_1 + \dots + 1w_i + \dots + 0w_n \text{ if } j = k$$

$$= 0w_1 + \dots + 0w_n \text{ otherwise}$$

$$\therefore [T_{ij}]_{\gamma\beta} = M^{ij}$$

(c) Now $\Phi : \mathcal{L}(V, W) \rightarrow M_{m \times n}(F)$ is defined by $\Phi(T_{ij}) = M^{ij}$ for all i, j

Since $\{M^{ij}\} = \Phi(T^{ij})$ is a basis of $M_{m \times n}(F)$

Φ is an isomorphism by the exercise 15(p.108)

22.

(i) T is well-defined and linear(check!)

$$T(f + g) = T(f) + T(g)$$

$$T(\alpha f) = \alpha T(f)$$

(ii) T is one-to-one

Suppose that $f \in \ker(T)$ and let $f(x) = \sum_{i=0}^n b_i f_i(x)$,

where $f_i(x) = \frac{(x-c_0)\dots(x-c_n)}{(c_i-c_0)\dots(c_i-c_n)}$, $b_i = f(c_i)$, $\forall i$

$$\text{Then } 0 = T(f) = (f(c_0), f(c_1), \dots, f(c_n)) = (b_0, b_1, \dots, b_n)$$

Since $\forall b_i = 0$, $f \equiv 0$

(iii) T is onto

$$\forall a = (f(c_0), \dots, f(c_n)) \in F^{n+1}, \exists f \in P_n(F) \text{ s.t. } T(f) = a$$

$$23. T(\sigma) = T(\{a_n\}) = a_0 + a_1x + \dots + a_nx^n, \text{ where } a_m \neq 0, \forall m > n$$

(i) T is well-defined

(ii) If $T(\sigma) = 0$, since x_i' s are linearly independent

$$\therefore \forall a_i = 0$$

$$\therefore \sigma = \{0\}$$

$\therefore T$ is one-to-one

(iii) T is onto

$$\forall f(x) = \sum_{i=0}^n a_i x^i \in P_n(F),$$

$$\exists \sigma = \{a_n\} = \{a_1, \dots, a_n, 0, \dots, 0\} \in V \text{ s.t. } T(\sigma) = f(x)$$

24. (a) \bar{T} is well-defined

$$v + N(T) = v' + N(T)$$

$$\Rightarrow v - v' \in N(T)$$

$$\Rightarrow T(v - v') = 0$$

$$\Rightarrow T(v) - T(v') = 0$$

$$\therefore T(v) = T(v')$$

$$\Rightarrow \bar{T}(v + N(T)) = T(v) = T(v') = \bar{T}(v' + N(T))$$

(b) \bar{T} is linear

$$\bar{T}(\alpha(v + N(T)) + (v' + N(T))) = \bar{T}(\alpha v + v' + N(T)) = T(\alpha v + v') = \alpha T(v) + T(v') =$$

$$\alpha \bar{T}(v + N(T)) + \bar{T}(v' + N(T))$$

(c) \bar{T} is an isomorphism

(i) If $\bar{T}(v + N(T)) = 0$, then $v + N(T) = N(T)$ i.e. $v \in N(T)$

(\therefore) Since $0 = \bar{T}(v + N(T)) = T(v) \therefore v \in N(T)$

$$\bar{T}(v + N(T)) = 0 \Rightarrow 0 = \bar{T}(v + N(T)) = T(V) \Rightarrow v \in N(T)$$

$\therefore \bar{T}$ is one-to-one

(ii) Clearly $\bar{T}(V + N(T)) \subseteq T(V)$

If $v \in T(V)$, then $v = T(u)$ for some $u \in V$

$$\text{and so } v = T(u) = \bar{T}(u + N(T))$$

$$\therefore v \in \bar{T}(V + N(T))$$

$\therefore \bar{T}$ is onto

(d) $T = \bar{T}\eta$

$$T(v) = \bar{T}(v + N(T)) = \bar{T}(\eta(v)) = \bar{T}\eta(v)$$

$$\forall v \in V, \bar{T}\eta(v) = \bar{T}(v + N(T)) = T(v)$$

$$\therefore T = \bar{T}\eta$$

25.

(i) $\Psi : \mathcal{C}(S, F) \rightarrow V$ is well-defined

(ii) Ψ is onto

$$\forall v \in V. v = \sum a_i s_i, s_i \in S$$

Define $f(s_i) = a_i, \forall i$

(then $a_i = 0$ for all but a finite number of i)

2.4.

then $\forall v, \exists f \in C(S, F)$ s.t. $\Psi(f) = \sum f(s_i)s_i = \sum a_i s_i, s_i = V$

(iii) Ψ is one-to-one

$\Psi(f) = 0 \Rightarrow \sum f(s_i)s_i = 0, \forall s_i \in S \Rightarrow f \equiv 0$

2.5. The change of Coordinate Matrix

1.

(a) F $([x'_j]_\beta)$

(b) T (Since $Q = [I_V]_{\beta'}^\beta$, Q is an isomorphism)

(c) T

(d) F $(B = Q^{-1}AQ)$

(e) T $([T]_\gamma = Q^{-1}[T]_\beta Q)$

$$2. Q = [I_V]_{\beta'}^\beta$$

$$(a) I_V(a_1, a_2) = (a_1, a_2) = a_1 e_1 + a_2 e_2$$

$$I_V(b_1, b_2) = (b_1, b_2) = b_1 e_1 + b_2 e_2$$

$$\therefore Q = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}$$

$$(b) Q = \begin{pmatrix} 4 & 1 \\ 2 & 3 \end{pmatrix}$$

$$(c) Q = \begin{pmatrix} 3 & -1 \\ 5 & -2 \end{pmatrix}$$

$$(d) Q = \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix}$$

$$3. Q = [I_V]_{\beta'}^\beta$$

$$(a) I_V(a_2 x^2 + a_1 x + a_0) = a_2 x^2 + a_1 x + a_0$$

$$I_V(b_2 x^2 + b_1 x + b_0) = b_2 x^2 + b_1 x + b_0$$

$$I_V(c_2 x^2 + c_1 x + c_0) = c_2 x^2 + c_1 x + c_0$$

$$\therefore Q = \begin{pmatrix} a_2 & b_2 & c_2 \\ a_1 & b_1 & c_1 \\ a_0 & b_0 & c_0 \end{pmatrix}$$

$$(b) \ Q = \begin{pmatrix} a_0 & b_0 & c_0 \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{pmatrix}$$

$$(c) \ Q = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ -3 & 1 & 1 \end{pmatrix}$$

$$(d) \ Q = \begin{pmatrix} 2 & 1 & 1 \\ 3 & -2 & 1 \\ -1 & 3 & 1 \end{pmatrix}$$

$$(e) \ Q = \begin{pmatrix} 5 & -6 & 3 \\ 0 & 4 & -1 \\ 3 & -1 & 2 \end{pmatrix}$$

$$(f) \ Q = \begin{pmatrix} -2 & 1 & 2 \\ 3 & 4 & 1 \\ -1 & 5 & 2 \end{pmatrix}$$

$$4. \ [T]_{\beta'} = Q^{-1}[T]_{\beta}Q$$

$$Q = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}, \ [T]_{\beta} = \begin{pmatrix} 2 & 1 \\ 1 & -3 \end{pmatrix}$$

$$[T]_{\beta'} = \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & -3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 8 & 13 \\ -5 & -9 \end{pmatrix}$$

$$5. \ [T]_{\beta'} = Q^{-1}[T]_{\beta}Q$$

$$Q = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}, \ [T]_{\beta} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$[T]_{\beta'} = 1/2 \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = 1/2 \begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}$$

$$6. [L_A]_\beta = Q^{-1}AQ$$

$$(a) Q = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}, Q^{-1} = \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix}$$

$$[L_A]_\beta = Q^{-1}AQ = \begin{pmatrix} 2 & -1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 6 & 11 \\ -2 & 4 \end{pmatrix}$$

$$(b) Q = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}, Q^{-1} = 1/2 \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$[L_A]_\beta = Q^{-1}AQ = 1/2 \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix}$$

$$(c) Q = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 2 \end{pmatrix}, Q^{-1} = \begin{pmatrix} 1 & 1 & -1 \\ 1 & -1 & 0 \\ -1 & 0 & 1 \end{pmatrix}$$

$$[L_A]_\beta = Q^{-1}AQ = \begin{pmatrix} 1 & 1 & -1 \\ 1 & -1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & -1 \\ 2 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 2 \end{pmatrix} = \begin{pmatrix} 2 & 2 & 2 \\ -2 & -3 & -4 \\ 1 & 1 & 2 \end{pmatrix}$$

$$(d) Q = \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ -2 & 0 & 1 \end{pmatrix}, Q^{-1} = 6 \begin{pmatrix} 1 & 1 & -2 \\ 3 & -3 & 0 \\ 2 & 2 & 2 \end{pmatrix}$$

$$[L_A]_\beta = Q^{-1}AQ = 6 \begin{pmatrix} 1 & 1 & -2 \\ 3 & -3 & 0 \\ 2 & 2 & 2 \end{pmatrix} \begin{pmatrix} 13 & 1 & 4 \\ 1 & 13 & 4 \\ 4 & 4 & 10 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & -1 & 1 \\ -2 & 0 & 1 \end{pmatrix} = 24 \begin{pmatrix} 6 & 0 & 5 \\ 0 & 18 & 0 \\ 0 & -6 & 31 \end{pmatrix}$$

7. In R^2 , let L be the line $y = mx, m \neq 0$

(a) T is the reflection of R^2 about L

$$\beta' = \left\{ \begin{pmatrix} 1 \\ m \end{pmatrix}, \begin{pmatrix} -m \\ 1 \end{pmatrix} \right\} : \text{an ordered basis for } R^2$$

$$\text{Since } T(1, m)^t = (1, m)^t = 1(1, m)^t + 0(-m, 1)^t$$

$$T(-m, 1)^t = (m, -1)^t = 0(1, m)^t + -1(-m, 1)^t$$

$$\therefore [T]_{\beta'} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Let β be the standard ordered basis for R^2 and Q be the matrix that changes

β' -coordinates into β -coordinates

$$\begin{aligned} \text{Then } Q &= [I_V]_{\beta'}^{\beta} = \begin{pmatrix} 1 & -m \\ m & 1 \end{pmatrix} \text{ and } Q^{-1}[T]_{\beta}Q = [T]_{\beta'} \\ \therefore [T]_{\beta} &= Q[T]_{\beta'}Q^{-1} = \begin{pmatrix} 1 & -m \\ m & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & m \\ -m & 1 \end{pmatrix} 1/(1+m^2) \\ &= 1/(1+m^2) \begin{pmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{pmatrix} \\ \therefore T \begin{pmatrix} x \\ y \end{pmatrix} &= 1/(1+m^2) \begin{pmatrix} 1-m^2 & 2m \\ 2m & m^2-1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 1/(1+m^2) \begin{pmatrix} (1-m^2)x + 2my \\ 2mx + (m^2-1)y \end{pmatrix} \\ (cf) \tan \theta = m &\Rightarrow T = \begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{pmatrix} \end{aligned}$$

(b) T is the projection on L along the line perpendicular to L

$$\beta' = \left\{ \begin{pmatrix} 1 \\ m \end{pmatrix}, \begin{pmatrix} -m \\ 1 \end{pmatrix} \right\}$$

$$\text{Since } T(1, m)^t = (1, m)^t = 1(1, m)^t + 0(-m, 1)^t$$

$$T(-m, 1)^t = (0, 0)^t = 0(1, m)^t + 0(-m, 1)^t$$

$$\therefore [T]_{\beta'} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$[T]_{\beta} = Q[T]_{\beta'}Q^{-1} = \begin{pmatrix} 1 & -m \\ m & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & m \\ -m & 1 \end{pmatrix} 1/(1+m^2) = 1/(1+m^2) \begin{pmatrix} 1 & m \\ m & m^2 \end{pmatrix}$$

$$\therefore T \begin{pmatrix} x \\ y \end{pmatrix} = 1/(1+m^2) \begin{pmatrix} x + my \\ mx + m^2y \end{pmatrix}$$

$$(cf) \tan \theta = m \Rightarrow T = \begin{pmatrix} \cos^2 \theta & \sin \theta \cos \theta \\ \sin \theta \cos \theta & \sin^2 \theta \end{pmatrix}$$

8. Let V and W be finite-dimensional vector spaces,

$T : V \rightarrow W$ be linear

β, β' be ordered bases for V and γ, γ' be ordered bases for W

Then $[T]_{\beta'}^{\gamma'} = P^{-1}[T]_{\beta}^{\gamma}Q$

(\because) $[T]_{\beta'}^{\gamma'} = [I_W \cdot T \cdot I_V]_{\beta'}^{\gamma'} = [I_W]_{\gamma'}^{\gamma'}[T]_{\beta}^{\gamma}[I_V]_{\beta'}^{\beta} = P^{-1}[T]_{\beta}^{\gamma}Q,$

where $P = [I_W]_{\gamma'}^{\gamma}, Q = [I_V]_{\beta'}^{\beta}$

9. (i) $\forall A \in M_{n \times n}(F), A$ is similar to A

(\because) $\exists I$ s.t $A = I^{-1}AI$

(ii) If A is similar to B , then $\exists Q$ s.t $A = Q^{-1}BQ$

$\therefore B = QAQ^{-1} = (Q^{-1})^{-1}A(Q^{-1})$

$\therefore B$ is similar to A

(iii) If A is similar to B and B is similar to C

then $\exists Q, P$ s.t $A = Q^{-1}BQ, B = P^{-1}CP \therefore A = Q^{-1}BQ = Q^{-1}(P^{-1}CP)Q =$

$(PQ)^{-1}C(PQ)$

$\therefore A$ is similar to C

\therefore "is similar to" is an equivalence relation on $M_{n \times n}(F)$

10. Since A is similar to $B, A = Q^{-1}BQ,$

$tr(A) = tr(QQ^{-1}B) = tr(B)$

11.

(a) Let $Q = [I_V]_{\alpha}^{\beta}, R = [I_V]_{\beta}^{\gamma}$

Then $RQ = [I_V]_{\beta}^{\gamma}[I_V]_{\alpha}^{\beta} = [I_V]_{\alpha}^{\gamma}$

$$(b) \quad Q^{-1} = ([I_V]_{\alpha}^{\beta})^{-1} = [I_V^{-1}]_{\beta}^{\alpha} = [I_V]_{\beta}^{\alpha}$$

$\therefore Q^{-1}$ changes β' -coordinates into β -coordinates

12.

β : the standard ordered basis for F^n

$$[L_A]_{\gamma} = [I_{F^n}]_{\beta}^{\gamma} [L_A]_{\beta}^{\beta} [I_{F^n}]_{\gamma}^{\beta}$$

Let $[I_{F^n}]_{\gamma}^{\beta} = Q$, then $[L_A]_{\gamma} = Q^{-1} A Q$

$$13. \quad x'_j = \sum_{i=1}^n Q_{ij} x_i, j = 1, \dots, n$$

(1)

By the theorem 2.6(p.72), there is a unique linear operator $T : V \rightarrow V$ s.t.

$$T(x_j) = x'_j \text{ for all } j = 1, 2, \dots, n$$

$$\text{Clearly } [T]_{\beta'}^{\beta} = Q$$

Since Q is invertible, T is an isomorphism by the theorem 2.8

So $\beta' = T(\beta)$ is a basis for V

(2)

Since $x'_j = \sum_{i=1}^n Q_{ij} x_i (1 \leq j \leq n)$, $[x'_j]_{\beta}$ is the j -th column of Q

$\therefore Q = [I_V]_{\beta'}^{\beta}$ changes β' -coordinates into β -coordinates

14.

If $A, B \in M_{m \times n}(F)$ and $P \in M_{m \times m}(F), Q \in M_{n \times n}(F)$ are invertible and $B = P^{-1} A Q$,

then \exists an n -dimensional vector space V and an m -dimensional vector space W (both over F), ordered bases β and β' for V and γ and γ' for W , and a linear transformation $T : V \rightarrow W$ s.t $A = [T]_{\beta}^{\gamma}$, $B = [T]_{\beta'}^{\gamma'}$
 (\therefore)

Let $V = F^n, W = F^m, T = L_A$

$\beta = \{x_1, x_2, \dots, x_n\}, \gamma = \{y_1, y_2, \dots, y_m\}$: the standard ordered bases for F^n and F^m , respectively

Define $x'_j = \sum Q_{ij}e_j$ for $1 \leq j \leq n$

then the set $\beta' = \{x'_1, \dots, x'_n\}$ is a basis for V

and $Q = [I_{F^n}]_{\beta'}^{\beta}$

Define $w'_j = \sum P_{ij}e_i$ for $1 \leq j \leq m$

then the set $\gamma' = \{w'_1, \dots, w'_m\}$ is a basis for W

and $P = [I_{F^m}]_{\gamma'}^{\gamma}$

Now $[T]_{\beta}^{\gamma} = [L_A]_{\beta}^{\gamma} = A$ and

$$[T]_{\beta'}^{\gamma'} = [I_{F^m}]_{\gamma'}^{\gamma} [T]_{\beta}^{\gamma} [I_{F^n}]_{\beta'}^{\beta} = P^{-1} A Q = B$$

2.6. Dual Spaces

1.

(a) F

(linear transformation from V into its field of scalars F is called a linear functional)

(b) T

$$(f : F \rightarrow F, [f] \in \text{Mat}_{1 \times 1}(F))$$

(c) T

$$\dim V^* = \dim(\mathcal{L}(V, F)) = \dim V \dim F = \dim V$$

$$\therefore V \simeq V^*$$

(d) T

For a vector space V , we can define the dual space of V i.e. $(\mathcal{L}(V, F)) = V^*$

Then V is the dual space of V^* $((V^*)^* = V)$

\therefore Every vector space is the dual of some vector space

(e) (example) $V = \mathbb{R}^2, F = \mathbb{R}$

$$\beta = \{e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}\} :$$

So $V^* = \mathcal{L}(V, \mathbb{R}) : 1 \times 2$ matrices

and $e_1^* = (1, 0), e_2^* = (0, 1)$ i.e. $\beta^* = \{e_1^* = (1, 0), e_2^* = (0, 1)\}$ Now if we define

$$T : V \rightarrow V^* \text{ by } T(e_1) = (1, 1), T(e_2) = (1, -1)$$

Since $\{T(e_1), T(e_2)\} = T(\beta)$ a basis of V^* , then clearly T is an isomorphism

But $T(\beta) = \{T(e_1) = (1, 1) \neq e_1^*, T(e_2) = (1, -1) \neq e_2^*\} \neq \beta^*$

(example 2)

$$V = \mathbb{R}, F = \mathbb{R}, f : V \rightarrow F \text{ i.e. } V^* = F \text{ and } \beta^* = \{1^*\} (\because \beta = \{1\})$$

But $T : R \rightarrow R$ is an isomorphism

$$a \mapsto 2a \quad T(\beta) = \{T(1)\} = \{2id\} \neq \beta^* = \{id\}$$

(f) T

$$T : V \rightarrow W, T^t : W^* \rightarrow V^* \text{ by } T^t(g) = gT$$

$$(T^t)^t : (V^*)^* \rightarrow (W^*)^*$$

(g) T

$$V \simeq W \Leftrightarrow T : V \rightarrow W: \text{ an isomorphism } \Leftrightarrow \exists [T]_{\beta}^{\gamma}: \text{ invertible } \Leftrightarrow$$

$$([T]_{\beta}^{\gamma})^t = ([T^t]_{\beta^*}^{\gamma^*}) : \text{ invertible } \Leftrightarrow T^t : W^* \rightarrow V^* : \text{ an isomorphism } \Leftrightarrow V^* \simeq W^*$$

(h) F

$$f : D_n(\mathbb{R}) \rightarrow \mathbb{R} \text{ by } f(g(x)) = g'(x), \forall g(x) = D_n(\mathbb{R})$$

$$\text{but in case } g(x) = x^2, f(g(x)) = g'(x) = 2x \text{ is not in } \mathbb{R}$$

\therefore It's not a linear functional

2.

$$(a) \quad p(x), g(x) \in P(R), \alpha \in R$$

$$f(\alpha p(x) + g(x)) = 2(\alpha p'(0) + g'(0) + \alpha p''(1) + g''(1)) = 2\alpha p'(0) + \alpha p''(0) + 2g'(0) +$$

$$g''(1) = \alpha f(p(x)) + f(g(x))$$

$\therefore f$ is a linear functional

$$(b) \quad (x_1, y_1), (x_2, y_2) \in R^2, \alpha \in R$$

$$f(\alpha(x_1, y_1) + (x_2, y_2)) = f(\alpha x_1 + x_2, \alpha y_1 + y_2) = 2(\alpha x_1 + x_2) + 4(\alpha y_1 + y_2) =$$

$$\alpha(2x_1 + 4y_1) + (2x_2 + 4y_2) = \alpha f(x_1, y_1) + f(x_2, y_2)$$

$$(c) \ A, B \in M_{2 \times 2}(F), \alpha \in F$$

$$f(\alpha A + B) = \text{tr}(\alpha A + B) = \text{tr}(\alpha A) + \text{tr}(B) = \alpha \text{tr}(A) + \text{tr}(B) = \alpha f(A) + f(B)$$

$$(d)$$

$$f((x_1, y_1, z_1) + (x_2, y_2, z_2)) = f(x_1 + x_2, y_1 + y_2 + z_1 + z_2) = (x_1 + x_2)^2 + (y_1 + y_2)^2 + (z_1 + z_2)^2 \neq (x_1^2 + y_1^2 + z_1^2)^2 + (x_2^2 + y_2^2 + z_2^2)^2 = f(x_1, y_1, z_1) + f(x_2, y_2, z_2)$$

$\therefore f$ is not a linear functional

$$(e)$$

$$f(\alpha A + B) = \alpha A_{11} + B_{11} = \alpha f(A) + f(B)$$

$\therefore f$ is a linear functional

3.

$$(a) \ \beta = \{v_1 = (1, 0, 1), v_2 = (1, 2, 1), v_3 = (0, 0, 1)\}$$

$$\text{since } f_i(v_j) = \delta_{ij}$$

$$1 = f_1(v_1) = f_1(e_1 + e_2) = f_1(e_1) + f_1(e_3)$$

$$0 = f_1(v_2) = f_1(e_1 + 2e_2 + e_3) = f_1(e_1) + 2f_1(e_2) + f_1(e_3)$$

$$0 = f_1(v_3) = f_1(e_3)$$

$$\therefore f_1(e_3) = 0, f_1(e_1) = 1, f_1(e_2) = -1/2$$

$$\therefore f_1(x, y, z) = xf_1(e_1) + yf_1(e_2) + zf_1(e_3) = x - 1/2y$$

$$0 = f_2(v_1) = f_2(e_1) + f_2(e_3)$$

$$1 = f_2(v_2) = f_2(e_1 + 2f_2(e_2) + f_2(e_3))$$

$$0 = f_2(v_3) = f_2(e_3)$$

$$\therefore f_2(e_2) = f_2(e_3) = 0, f_2(e_1) = 0$$

$$\therefore f_2(x, y, z) = 1/2y$$

$$0 = f_3(v_1) = f_3(e_1) + f_3(e_3)$$

$$0 = f_3(v_2) = f_3(e_1 + 2f_3(e_2) + f_3(e_3))$$

$$1 = f_3(v_3) = f_3(e_3)$$

$$\therefore f_3(e_1) = -1, f_3(e_2) = 0, f_3(e_3) = 1$$

$$\therefore f_3(x, y, z) = -x + z$$

$$(b) \beta = \{1, x, x^2\}$$

$$f_1(a + bx + cx^2) = af_1(e_1) + bf_1(e_2) + cf_1(e_3) = a$$

$$f_2(a + bx + cx^2) = af_2(e_1) + bf_2(e_2) + cf_2(e_3) = b$$

$$f_3(a + bx + cx^2) = af_3(e_1) + bf_3(e_2) + cf_3(e_3) = c$$

4. $\{f_1, f_2, f_3\}$ is linearly independent

$$(af_1 + bf_2 + cf_3)(x, y, z) = 0(x, y, z)$$

$$af_1(x, y, z) + bf_2(x, y, z) + cf_3(x, y, z)$$

$$= a(x - 2y) + b(x + y + z) + c(y - 3z)$$

$$= (a + b)x + (-2a + b + c)y + (b - 3c)z = 0, \forall (x, y, z) \in V$$

$$\therefore a = b = c = 0$$

$\therefore \{f_1, f_2, f_3\}$ is linearly independent in V^*

5.

(i) If $V_{col} \rightarrow V_{row}^*$

$$V_{row} \rightarrow V_{col}^*$$

$$\begin{pmatrix} a & b \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = 1 \times 1(\text{scalar})$$

$$V = P_1(\mathbb{R}) = \{a + bx \text{ or } \begin{pmatrix} a \\ b \end{pmatrix}\}$$

$$(\because \text{ In } P_1(\mathbb{R}), 1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, 1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \therefore a + bx \Rightarrow \begin{pmatrix} a \\ b \end{pmatrix})$$

$$f_1(a + bx) = (1, \frac{1}{2}) \begin{pmatrix} a \\ b \end{pmatrix} = a + \frac{1}{2}b$$

$$f_2(a + bx) = (2, 2) \begin{pmatrix} a \\ b \end{pmatrix} = 2a + 2b$$

$$\therefore af_1 + bf_2 = a(1, \frac{1}{2}) + b(2, 2) = (a + 2b, \frac{1}{2}a + 2b) = 0 = (0, 0)$$

$$\therefore a = b = 0$$

7.

$$(a) T^t(f) = g, \text{ where } g(a + bx) = -3a - 4b$$

$$(b) [T^t]_{\gamma^*}^{\beta^*} = \begin{pmatrix} -1 & 1 \\ -2 & 1 \end{pmatrix}$$

$$(c) [T]_{\beta}^{\gamma} = \begin{pmatrix} -1 & -2 \\ 1 & 1 \end{pmatrix}$$

8.

Now let π a plane in \mathbb{R}^3 through the origin

$$\text{Then } \exists 0 \neq (a, b, c) \in \mathbb{R}^3 \Rightarrow \pi = \{(x, y, z) \mid ax + by + cz = 0\}$$

Define $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ by $(x, y, z) \mapsto ax + by + cz$: linear functional

Then $f \in V^*$ and $\ker f = \pi$

9.

$$\beta = \{x_1, x_2, \dots, x_n\}$$

$$\gamma = \{y_1, y_2, \dots, y_n\} : \text{standard bases of } F^n \text{ and } F^m$$

$$10. \{p_0 = 1, p_1 = (x - c_1), \dots, p_n = (x - c_1)(x - c_2) \cdots (x - c_n)\}$$

$$(a) \text{ Define } f_i(p(x)) = p(c_i)$$

$$\text{Suppose that } \sum_{i=0}^n \alpha_i f_i = 0$$

$$\text{then } \sum_{i=0}^n \alpha_i f_i(p_j(x)) = \sum_{i=0}^n \alpha_i (p_j(c_i)) = \alpha_i = 0$$

$$\therefore \alpha_i = 0, \forall i = 0, 1, \dots, n$$

$$\therefore \{f_0, f_1, \dots, f_n\} : \text{linearly independent}$$

$$\text{Since } \dim V = \dim V^* = n + 1,$$

$$\{f_0, f_1, \dots, f_n\} : \text{a basis for } V^*$$

$$(b) (i) \text{ By the corollary of theorem 2.26 and (a),}$$

$$\hat{x}_i(f_j) = f_j(x_i) = \delta_{ij}$$

$$\text{then, } f_j(p_i(x)) = p_i(c_j) = \delta_{ij}$$

$$(ii) \text{ Consider } \exists q_i \text{ s.t. } f_j(q_i(x)) = q_i(c_j) = \delta_{ij}, \forall i = 0, 1, \dots, n,$$

$$\text{Let } R_i(x) = p_i(x) - q_i(x), \text{ then } R_i(c_j) = p_i(c_j) - q_i(c_j) = \delta_{ij} - \delta_{ij} = 0, \forall j = 0, 1, \dots, n$$

$$\therefore R_i(x) = 0$$

$$(\therefore) \dim R_i \leq n \text{ and } R_i(x) \text{ has } n + 1 \text{ roots}$$

$$\therefore q_i = p_i$$

(c) Assume that $\exists h(x) \in P_n(x)$ s.t. $h(c_i) = a_i, \forall i$

Since $\{P_0(x), P_1(x), \dots, P_n(x)\}$ a basis for $P_n(x)$

$$\therefore h(x) = \sum_{i=0}^n b_i P_i(x), (\forall b_i \in F)$$

$$a_j = h(c_j) = \sum_{i=0}^n b_i P_i(c_j) = b_j, \forall j$$

$$\therefore h(x) = \sum_{j=0}^n b_j P_j(x) = \sum_{j=0}^n a_j P_j(x) = q(x)$$

(d) Let c_0, \dots, c_n be distinct scalars in F

The polynomials $p_0(x), \dots, p_n(x)$ defined by

$$p_i(x) = \prod_{\substack{k=0 \\ k \neq i}}^n \frac{x - c_k}{c_i - c_k} \in P_n(F) \quad (1)$$

Since $p_i(c_j) = \delta_{ij}$ and $\{p_0, \dots, p_n\}$ is linearly independent

$\{p_0, \dots, p_n\}$: a basis for $P_n(F)$

$$p(x) = \sum_{i=0}^n a_i p_i(x), (a_i \in F)$$

$$p(c_j) = a_j, \forall j$$

$$\therefore p(x) = \sum_{i=0}^n a_i p_i(x) = p(x) = \sum_{i=0}^n p(c_i) p_i(x)$$

$$(e) \int_a^b p(t) dt = \sum_{i=0}^n p(c_i) d_i, \quad d_i = \int_a^b p_i(t) dt$$

$$(\cdot) p(t) = p(c_0) p_0(t) + \dots + p(c_n) p_n(t)$$

$$\int_a^b p(t) dt = \int_a^b (p(c_0) p_0(t) + \dots + p(c_n) p_n(t)) dt$$

$$= p(c_0) \int_a^b p_0(t) dt + \dots + p(c_n) \int_a^b p_n(t) dt$$

$$= p(c_0) d_0 + \dots + p(c_n) d_n$$

$$= \sum_{i=0}^n p(c_i) d_i$$

Trapezoidal rule - $\int_a^b p(t)dt \approx (b-a)\frac{f(b)+f(a)}{2}$

Simpson's rule - $\int_a^b f(t)dt \approx \frac{(b-a)}{6}(f(a) + 4f(\frac{a+b}{2}) + f(b))$

11.

For $\forall x \in V$, $x \mapsto \psi_2 T(x) = \widehat{T(x)}$

$x \mapsto T^{tt}\psi_1(x) = T^{tt}(\widehat{x}) = \widehat{x}T^t$

To show commuting, $\widehat{T(x)} = \widehat{x}T^t$ in $W^{**} : W^* \rightarrow F$

$\forall g \in W^*$, i.e. $g : W \rightarrow F$ a linear functional

Show $(\widehat{x}T^t)(g) = \widehat{T(x)}(g)$

$\widehat{T(x)}(g) = g(T(x)) = (gT)(x) = \widehat{x}(gT) = \widehat{x}(T^t g) = \widehat{x}T^t(g)$

$\therefore \psi_2 T = T^{tt}\psi_1$

12. $\psi(\beta) = \beta^{**}$

$\beta = \{x_1, x_2, \dots, x_n\}$ a basis for V

$\Rightarrow \beta^* = \{x_1^*, x_2^*, \dots, x_n^*\}$ a basis for V^*

, where $x_i^* : V \rightarrow F$ a linear functional s.t. $f_i(x_j) = \delta_{ij}$

Since V^{**} is the dual space of V^*

$\exists \beta^{**} = \{x_1^{**}, x_2^{**}, \dots, x_n^{**}\}$ a basis for V^{**}

s.t. $x_i^{**} : V^* \rightarrow F$ linear functional s.t. $x_i^{**}(x_j^*) = \delta_{ij}$

Show $x_i^{**} = \widehat{x_i}$, $\forall i$, $\psi(\beta) = \{x_1, x_2, \dots, x_n\}$

$\widehat{x}(x_i^*) = \delta_{ij} = x_i^{**}(x_j^*)$, $\forall i, j$

i.e. $\widehat{x}_i = x_i^{**}$ on a basis β^{**}

$$\Rightarrow \widehat{x}_i = x_i^{**}, \forall i$$

$$\therefore \psi(\beta) = \beta^{**}$$

$$13. S^0 = \{f \in V^* | f(x) = 0, \forall x \in S\}, S \subseteq V$$

(a) S^0 is a subspace of V^*

$$(i) 0(x) = 0, \forall x \in S \quad \therefore 0 \in S^0$$

$$(ii) \forall f, g \in S^0, \alpha \in F \Rightarrow \alpha f + g \in S^0$$

$$(\alpha f + g)(x) = \alpha f(x) + g(x) = \alpha 0 + 0 = 0, \forall x \in S$$

$$\therefore \alpha f + g \in S^0$$

(b)

Let $\{x_1, x_2, \dots, x_m\}$ be a basis of W

If x is not in W , then $\{x_1, x_2, \dots, x_m, x\} = \{x_1, x_2, \dots, x_m\} \cup \{x\}$ is linearly independent

$$\exists \beta = \{x_1, x_2, \dots, x_m, x = x_{m+1}, \dots, x_n\} \text{ a basis of } V$$

$$\Rightarrow \beta^* = \{f_1, f_2, \dots, f_m, f_{m+1}, \dots, f_n\} \text{ a basis of } V^*$$

$$f_{m+1}(W) = 0 \text{ and } f_{m+1}(x) = f_{m+1}(x_{m+1}) = 1$$

$$\therefore f_{m+1} \in W^0, f_{m+1}(x) \neq 0$$

$$(c) (S^0)^0 = \text{span} \psi(S)$$

$$(\Leftarrow) \text{ If } \widehat{v} \in \text{span} \psi(S), \text{ then } \exists x_1, x_2, \dots, x_n \in S, \text{ s.t. } \widehat{v} = a_1 \widehat{x}_1 + a_2 \widehat{x}_2 + \dots + a_n \widehat{x}_n$$

for some $a_1, a_2, \dots, a_n \in F$

Now $\forall f \in S^0$

$$\widehat{v}(f) = \left(\sum_{i=1}^n a_i \widehat{x}_i \right)(f) = \sum_{i=1}^n a_i \widehat{x}_i(f) = a_i f(x_i) = \sum_{i=1}^n a_i 0 = 0$$

So $\widehat{v} \in (S^0)^0$

$$\therefore \text{span}\psi(S) \subseteq (S^0)^0$$

(\Rightarrow)

(Step 1)

First note that for \forall subset S of V

$$S^0 = (\text{span}S)^0$$

[For convenience, let $\text{span}S = W$,

then clearly $S \subseteq W$, so $W^0 \subseteq S^0$

Now let $f \in S^0$ and $x \in W$; then

$$x = a_1 x_1 + a_2 x_2 + \cdots + a_n x_n \text{ for some } x_i \in S, a_i \in F$$

$$\Rightarrow f(x) = a_1 f(x_1) + a_2 f(x_2) + \cdots + a_n f(x_n) = 0$$

$$\therefore f \in W^0$$

$$\therefore S^0 \subseteq W^0 \text{]}$$

(Step 2)

Show if $W \leq V$ as a subspace, then $(W^0)^0 = \psi(W)$

$$[(\subseteq) \text{ For } v \in V, \widehat{v} \in W^0 \Rightarrow \widehat{v}(f) = 0 \text{ for all } f \in W^0$$

$$\Rightarrow f(V) = 0$$

$$\Rightarrow v \in W \text{ by the exercise 13(b)}$$

$$\Rightarrow \widehat{v} \in \psi(W)$$

$$(\supseteq) \text{ If } v \in W, \widehat{v} \in \psi(W)$$

$$\widehat{v}(f) = f(v) = 0 \text{ for all } f \in W^0$$

$$\Rightarrow \widehat{v} \in (W^0)^0$$

This implies that $\psi(W) \subseteq (W^0)^0$

(Step 3)

Clearly $\psi(W) = \text{span}\psi(S)$, where $W = \text{span}(S)$

(\therefore) If $v \in W$

$$v = a_1x_1 + a_2x_2 + \cdots + a_nx_n \quad (\forall a_i \in F, x_i \in S)$$

$$\text{then } \psi(v) = \widehat{v} = a_1\widehat{x}_1 + a_2\widehat{x}_2 + \cdots + a_n\widehat{x}_n = \sum_{i=1}^n A_i\psi_i(x_i) \in \text{span}(\psi(S))$$

$$\therefore \widehat{v} \in \psi(S)$$

$$\widehat{v} \in \text{span}(\psi(S))$$

Now $\psi(S) \subseteq \psi(W)$ and $\psi(W)$ is a subspace of W^{**}

$$\text{span}(\psi(S)) \subseteq \text{span}(\psi(W)) = \psi(W)$$

$$\therefore \psi(W) = \text{span}(\psi(S))$$

$$\text{Finally } (S^0)^0 = (W^0)^0 = \psi(W) = \text{span}(\psi(S))$$

$$(d) \ W_1 = W_2 \Leftrightarrow W_1^0 = W_2^0$$

(\Rightarrow) clear

(\Leftarrow) If $W_1 \neq W_2$, then $x \in W_2, x$ is not in W_1

by (b), $\exists f \in W_1^0, f(x) \neq 0$

i.e. f is not in W_2^0

$$\therefore W_1^0 \neq W_2^0$$

(e)

(\Rightarrow)

$$(W_1 + W_2)^0 \subseteq W_1^0, (W_1 + W_2)^0 \subseteq W_2^0$$

$$\therefore (W_1 + W_2)^0 \subseteq W_1^0 \cap W_2^0$$

(\Leftarrow) clear

14.

Let $\dim W = k$ and $\{x_1, \dots, x_k\}$: a basis for W

Extend it to $\{x_1, \dots, x_k, x_{k+1}, \dots, x_n\}$: a basis for V

Let $\{f_1, \dots, f_n\}$ be the basis for V^*

We are going to show that $\{f_{k+1}, \dots, f_n\}$ is a basis for W^0

If $f \in W^0$ we have $f(x_i) = 0, i \leq k$

$$\therefore f = \sum_{i=k+1}^n f(x_i)f_i$$

$$\therefore \{f_{k+1}, \dots, f_n\} \text{ spans } W^0$$

\therefore Since $\dim W = k$ and $\dim V = n$, then $\dim W^0 = n - k$

15.

(\Rightarrow) Suppose that $\phi \in N(T^t)$

$$\text{i.e. } T^t(\phi) = \phi T = 0$$

If $u \in R(T)$, then $u = T(v)$ for some $v \in V$

$$\text{hence } \phi(u) = \phi(T(v)) = (\phi T)(v) = 0(v) = 0, \forall u \in R(T)$$

$$\therefore \phi \in (R(T))^0$$

(\Leftarrow)

$$\text{If } \sigma \in (R(T))^0, \sigma(R(T)) = 0$$

then, $\forall v \in V, (T^t(\sigma))(v) = (\sigma T)(v) = \sigma(T(v)) = 0(v) = 0$

$$\therefore T^t(\sigma) = 0$$

$$\therefore \sigma \in N(T^t)$$

16.

$$\text{rank}(L_{A^t}) = \text{rank}(L_A)$$

Let $\dim V = n$, $\dim W = m$ and $\text{rank}(T) = r$

by the exercise 14, $\dim(R(T)) + \dim(R(T))^\circ = \dim W$

$$\therefore \dim(R(T))^\circ = m - r$$

by the exercise 15 and the dimension theorem,

$$N(T^t) = (R(T))^\circ, \dim(W^*) = \text{nullity}(T^t) + \text{rank}(T^t)$$

$$\therefore \text{rank}(T^t) = \dim(W^*) - \text{nullity}(T^t) = m - (m - r) = \text{rank}(T) \text{ --- } (*)$$

Since $\text{rank}(T) = \text{rank}(L_A)$ and $\text{rank}(T^t) = \text{rank}(L_{A^t}) \text{ --- } (*)$

$$\text{rank}(L_{A^t}) = \text{rank}(L_A)$$

$$\text{Q. } \text{rank}(T^t) = \text{rank}(L_{A^t})$$

(\therefore) When $T = L_A : F^n \rightarrow F^m$ left multiplication

$$\text{rank}(L_A) = \text{rank}(T) = \text{rank}(T^t) = \text{rank}([T^t]_{\gamma^*}^{\beta^*})$$

$$= \text{rank}([T]_{\beta}^{\gamma})^t = \text{rank} A^t = \text{rank} L_{A^t}$$

17.

$$(\Rightarrow) \forall \in W^\circ$$

Since $T^t f = fT$ and $T(W) \subseteq W$,

$$fT(W) \subseteq f(W) = 0$$

$$\therefore T^t f \in W^\circ$$

$$\therefore T^t(W^\circ) \subseteq W^\circ$$

$\therefore W^\circ$ is T^t -invariant

(\Leftarrow) If $T(W) \not\subseteq W$, $\exists w \in W$ s.t. $T(w) \notin W$

by the exercise 13, $\exists f \in W^\circ$ s.t. $f(T(w)) \neq 0$

$$T^t f(w) = fT(w) \neq 0$$

i.e. $\exists f \in W^\circ$ s.t. $T^t f \notin W^\circ$

$\therefore W$ is T -invariant

18.

$$\Phi : V^* \rightarrow \mathcal{L}(S, F)$$

(Actually $\mathcal{L}(S, F) \equiv \mathcal{L}(V, F)$)

(i) Clearly $\mathcal{L}(S, F)$ is a vector space over F and

(ii) Φ is a linear map

$$[f, g \in \mathcal{L}(S, F),$$

$$\Phi(f + g) = (f + g)|_S = f|_S + g|_S = \Phi(f) + \Phi(g)$$

$$\Phi(\alpha f) = \alpha f|_S = \alpha f_s = \alpha \Phi(f)]$$

(iii) $\forall f \in \ker \Phi, \Phi(f) = f_s = 0$

$$\therefore f \in S^\circ = (\text{span} S)^\circ = V^\circ = \{0\}$$

$$\therefore \ker \Phi = \{0\}$$

$\therefore \Phi$ is one-to-one

(iv) By the exercise 34 in section 2.1

$(\forall f_s : S \rightarrow F, \exists! f : V \rightarrow F \text{ a linear map s.t. } f(x) = f_s(x), \forall x \in S)$

$\forall f_s \in \mathcal{L}(S, F), \exists! f \in V^* \text{ s.t. } \Phi(f) = f_s$

$\therefore \Phi$ is onto

19.

(i) Choose $y \in V, y \notin W$ and let γ : a basis of W

then $\gamma \cup \{y\}$: linearly independent

by (section 1.7 or) Maximal principle,

$\exists \beta$: a basis of V s.t. $\gamma \cup \{y\} \subseteq \beta$

Define a function : $g : \beta \rightarrow F$ s.t. $g(x) = 0 \forall x \in \beta, x \neq y$

$g(y) = 1$

then by the exercise 18, $\exists f \in \mathcal{L}(V, F) = V^* \text{ s.t. } f|_{\beta} = g(\cdot : \gamma \subseteq \beta)$

i.e. f is the function we desired.

20.

(a) $T : V \rightarrow W$: linear map $\Rightarrow T^t : W^* \rightarrow V^*$ given by $T^t(g) = gT, \forall g \in W^*$

(\Rightarrow) Suppose that T is onto

Let $g \in \text{Ker } T^t \Rightarrow T^t(g) = 0 \Rightarrow gT = 0 \text{ in } V^*$

i.e. $gT(v) = (gT)(v) = 0, \forall v \in V$

Since T is onto, $g(w) = gT(v) = 0$

i.e. $g(w) = 0 (\because g \in \text{Ker} T^t), \forall w \in W$

$\therefore g = 0$ in V^*

$\therefore T^t$ is one-to-one

(\Leftarrow) Suppose that T^t is one-to-one

Let $W_1 = R(T)$: the range of T

If $W_1 \neq W \Rightarrow$ by the exercise 19, $\exists 0 \neq g \in W^*, g(W_1) = 0$ (*i.e.* $g \in W^\circ 1$)

$\Rightarrow (gT)(V) = g(T(V)) = g(W_1) = 0$

$\Rightarrow (T^t)g(V) = 0 \Rightarrow T^t g = 0$ in W^*

$\therefore g \in \text{Ker} T^t$

Since T^t is one-to-one, $g = 0$

$\therefore W_1 = W$

$\therefore T$ is onto

(b)

(\Leftarrow) Suppose that T is one-to-one

Let $f \in V^*$

Suppose that T is one-to-one

$W = W_1 \oplus W_2$, where $W_1, W_2 \leq W$ and $W_1 = R(T) \cong V$

So the map $U : W_1 \oplus W_2 \rightarrow V$, $U(w_1 \oplus w_2) = v$, where $w_1 = T(v)$ is a well-defined linear map

$T(v) + w_2 \mapsto v$

Let $g = fU$, then $\exists g \in W^*$ and $T^t(g) = gT = f$

$\lceil (\because) (gT)(v) = g(T(v)) = (fU)(T(v)) = f(U(T(v))) = f(v), \forall v \in V$

$$\therefore gT = f$$

$$\text{i.e. } T^t g = f]$$

$$\therefore T^t \text{ is onto}$$

(\Rightarrow) Suppose that $T^t : W^* \rightarrow V^*$ onto

show T is one-to-one

Assume on the contrary T is not one-to-one

$$\Rightarrow \exists 0 \neq v \in V \text{ s.t. } T(v) = 0$$

$$\exists f \in V^* \text{ s.t. } f(v) = 1 \text{ (by the exercise 18)}$$

Now since T^t is onto

$$\exists g \in W^* \text{ s.t. } f = T^t(g) = gT$$

$$\Rightarrow 1 = f(v) = (gT)(v) = g(T(v)) = g(0) = 0$$

$\therefore T$ must be one-to-one

2.7. Homogeneous Linear Differential Equations with Constant Coefficients

1.

(a) T (p.137 corollary to Theorem 2.32)

(b) T (p.132 Theorem 2.28)

(c) F

(d) F (Any solution is a linear combination of e^{at} and $t^k e^{at}$)

(e) T

(\therefore) If x and y are solutions of $p(D) = 0$,

then $p(D)(\alpha x + \beta y) = \alpha p(D)x + \beta p(D)y = 0 + 0 = 0, \alpha, \beta \in F$

$\therefore \alpha x + \beta y$ is a solution of $p(D) = 0$

(f) F

(\therefore) It's different with the multiplicity of c_i (p.137 and 139, Theorem 2.33 and

2.34) (g) T (p.131)

2.

(a) F

Let $S = \left\{ \frac{a}{1+t^2} \mid a \in R \right\} \Rightarrow S$: 1-dimensional subspace of \mathcal{C}^∞

But there is no homogeneous linear differential equation with constant coefficients

(b) F

Let $\{t, t^2\}$ is the solution of $y'' + ay' + by = 0$

$0 + a + bt = 0 \Rightarrow a = b = 0$

then $y'' + ay' + by = 0$ becomes $y'' = 0$

$$(t^2)'' = 2 = 0$$

$$(\text{cf}) \ y''' = 0 \Rightarrow D^3 = 0 \Rightarrow t = 0$$

$$e^{0t}, te^{0t}, t^2e^{0t} \text{ i.e. } 1, t, t^2$$

$$\exists y''' = 0$$

(c) T

Let x is a solution to the homogeneous linear differential equation with constant coefficients $P(D)y = 0$

$$\text{Since } P(D)x = 0, \ P(D)x' = P(D)(Dx) = P(D)Dx = DP(D)x = D(0) = 0$$

$\therefore x'$ is also a solution to the equation

(d) T

$$\text{Let } p(D)x = 0 \text{ and } q(D)y = 0$$

$$\begin{aligned} p(D)q(D)(x + y) &= p(D)q(D)x + p(D)q(D)y = q(D)(p(D)x) + p(D)(q(D)y) = \\ &= q(D)(0) + p(D)(0) = 0 + 0 = 0 \end{aligned}$$

(e) F

$$\text{Let } p(t) = t^2 + 2t + 1 = 0 \ \therefore p(D) = D^2 + 2D + 1$$

$$q(t) = t^3 - 1 \ \therefore q(D) = D^3 - 1$$

$$\{e^{-t}\} : \text{a basis for the solution space of } p(D)$$

$$\{e^t\} : \text{a basis for the solution space of } q(D)$$

$$p(D)q(D) = D^5 + 2D^4 + D^3 - D^2 - 2D - 1$$

$$p(D)q(D)y = y^{(5)} + 2y^{(4)} + y^{(3)} - y^{(2)} - 2y' - y$$

$$p(D)(e^{-t}) = 0, \quad q(D)(e^t) = 0$$

$$\text{But } p(D)q(D)(e^{-t}e^t) \neq 0$$

3.

(a) Given the differential equation is $y'' + 2y' + y = 0$ and its auxiliary polynomial is $p(t) = t^2 + 2t + 1 = (t + 1)^2$

Hence, e^{-t} and te^{-t} are solutions to the differential equation because $c = -1$ is a zero of $p(t)$

$\therefore \{e^{-t}, -te^{-t}\}$ is a basis for the solution space

So any solution y is to the given differential equation is of the form

$$y(t) = b_1e^{-t} + b_2te^{-t} \text{ for unique } b_1 \text{ and } b_2$$

(b)

Since $y''' = y'$, the auxiliary polynomial is $t^3 - t = 0$

$$\therefore t = 0, -1, 1$$

$$\therefore \{1, e^{-t}, e^t\}$$

$$(c) \quad y^{(4)} - 2y^{(2)} + y = 0,$$

the auxiliary polynomial is $t^4 - 2t^2 + 1 = (t^2 - 1)^2 = (t + 1)^2(t - 1)^2$

$$\therefore t = -1, 1$$

$$\therefore \{e^{-t}, te^{-t}, e^t, te^t\}$$

(d)=(a)

(e)

$$\text{Since } y^{(3)} - y^{(2)} + 3y^{(1)} + 5y = 0,$$

2.7.

the auxiliary polynomial is $t^3 - t^2 + 3t + 5 = (t_1)(t^2 - 2t + 5)0$

$$\therefore t = -1, 1 + 2i, 1 - 2i$$

$$\therefore \{e^{-t}, e^t e^{2it}, e^t e^{-2it}\}$$

$$\therefore \{e^{-t}, e^t \cos 2t, e^t \sin 2t\}$$

4.

(a)

$$p(t) = t^2 - t - 1 = 0$$

$$t = \frac{1+\sqrt{5}}{2}, \frac{1-\sqrt{5}}{2}$$

$$\therefore \{e^{\frac{(1+\sqrt{5})t}{2}}, e^{\frac{(1-\sqrt{5})t}{2}}\}$$

(b)

$$p(t) = t^3 - 3t^2 + 3t - 1 = (t - 1)^3 = 0$$

$$\therefore \{e^t, te^t, t^2 e^t\}$$

(c)

$$p(t) = t^3 + 6t^2 + 8t = t(t^2 + 6t + 8) = 0$$

$$\therefore t = 0, -2, -4$$

$$\therefore \{1, e^{-2t}, e^{-4t}\}$$

5.

$$\forall f, g \in C^\infty, \alpha \in F,$$

$$(\alpha f + g)^{(n)} = \alpha f^{(n)} + g^{(n)} \in C^\infty, \forall n$$

$$\therefore C^\infty \text{ is a subspace of } \mathcal{F}(R, C)$$

6.

(a)

$$\forall f, g \in C^\infty, \alpha \in F,$$

$$D(\alpha f + g) = (\alpha f + g)' = \alpha f' + g' = \alpha D(f) + D(g)$$

$\therefore D : C^\infty \rightarrow C^\infty$ is a linear operator

(b)

$$\forall f, g \in C^\infty, \alpha \in F,$$

$$\text{Define } L = p(D) = a_n D^n + a_{n-1} D^{n-1} + \cdots + a_1 D^1 + a_0 I$$

$$L(\alpha f + g) = a_n (\alpha f + g)^n + a_{n-1} (\alpha f + g)^{n-1} + \cdots + a_0 I$$

$$= a_n (\alpha f^{(n)} + g^{(n)}) + a_{n-1} (\alpha f^{(n-1)} + g^{(n-1)}) + \cdots + a_0 I$$

$$= \alpha (a_n f^{(n)} + a_{n-1} f^{(n-1)} + \cdots + a_1 f' + a_0) + (a_n g^{(n)} + a_{n-1} g^{(n-1)} + \cdots + a_1 g' + a_0)$$

$$= \alpha L(f) + L(g)$$

\therefore Any differential operator is a linear operator on C^∞

(cf) If D : a linear operator,

then DD : a linear operator

\vdots

D^n : a linear operator

$\therefore p(D = D^n + a_{n-1} D^{n-1} + \cdots + a_1 D + a_0 I) : \text{a linear operator}$

7.

We only need to show that $\{\frac{x+y}{2}, \frac{x-y}{2i}\}$ is linearly independent

If $\alpha\frac{(x+y)}{2} + \beta\frac{(x-y)}{2i} = 0$, $(\alpha, \beta \in F)$

then $(\frac{\alpha}{2} + \frac{\beta}{2i})x + (\frac{\alpha}{2} - \frac{\beta}{2i})y = 0$

$\Rightarrow \frac{\alpha}{2} + \frac{\beta}{2i} = 0, \frac{\alpha}{2} - \frac{\beta}{2i} = 0$

$\therefore \alpha = \beta = 0$

$\therefore \{\frac{x+y}{2}, \frac{x-y}{2i}\}$ is a basis

8.

Let $t_1 = a + ib (a, b \in R, b \neq 0)$ is a zero of $p(t)$

then, $e^{(a+ib)t}$ is a solution of $p(D)$

Using exercise 7 in this chapter,

If $\{e^{(a+ib)t}, e^{(a-ib)t}\}$ is a basis, then so is $\{\frac{1}{2}(e^{(a+ib)t} + e^{(a-ib)t}), \frac{1}{2i}(e^{(a+ib)t} - e^{(a-ib)t})\}$

Since $\frac{1}{2}(e^{(a+ib)t} + e^{(a-ib)t}) = e^{at}\cos bt$, $\frac{1}{2i}(e^{(a+ib)t} - e^{(a-ib)t}) = e^{at}\sin bt$

$\therefore \{e^{at}\cos bt, e^{at}\sin bt\}$ is a basis

(cf) Let $p(t) = \alpha(t^2 - 2at + a^2 + b^2)$, $t_1 = a + ib$, $t_2 = a - ib$

then $p(D)y = y'' - 2ay' + (a^2 + b^2)y = 0$, $y_1 = e^{at}\cos bt$, $y_2 = e^{at}\sin bt$

check $p(D)y_1 = 0$, and $p(D)y_2 = 0$

9.

$u \in N(U_i) \Rightarrow U_i(u) = 0$

So $U_1 \cdots U_n(u) = U_1 \cdots U_{i-1} U_{i+1} \cdots U_n U_i(u) = U_1 \cdots U_{i-1} U_{i+1} \cdots U_n(0) = 0$
 $\therefore u \in N(U_1 \cdots U_n)$

10.

Suppose that $b_1 e^{c_1 t} + \cdots + b_n e^{c_n t} = 0$, c_i 's are distinct

Apply the mathematical induction on n ,

If $n = 1$, then $b_1 e^{c_1 t} = 0 \therefore b_1 = 0$

Assume that this assertion is true for $n - 1$

We are going to prove that this is also true for n

$$(D - c_n I)(b_1 e^{c_1 t} + \cdots + b_n e^{c_n t}) = 0$$

$$\Rightarrow b_1 c_1 e^{c_1 t} + \cdots + b_{n-1} c_{n-1} e^{c_{n-1} t} + b_n c_n e^{c_n t} - (b_1 c_n e^{c_1 t} + \cdots + b_{n-1} c_n e^{c_{n-1} t} + b_n c_n e^{c_n t}) =$$

$$0$$

$$\Rightarrow b_1 (c_1 - c_n) e^{c_1 t} + b_2 (c_2 - c_n) e^{c_2 t} + \cdots + b_{n-1} (c_{n-1} - c_n) e^{c_{n-1} t} = 0$$

By the induction hypothesis and $c_i - c_n \neq 0$,

$$\forall i = 1, \dots, n-1, b_i = 0$$

$\therefore \{e^{c_1 t}, \dots, e^{c_n t}\}$ is linearly independent

Since the solution space is n -dimensional, the given set is a basis for the solution space of the differential equation

11.

Suppose that $\sum_{i=1}^k \sum_{j=0}^{n_i-1} c_{ij} t^j e^{c_i t} = 0$

2.7.

Let $P_i(t) = \sum_{j=0}^{n_i-1} c_{ij}t^j$

Then we have $P_1(t)e^{c_1t} + P_2(t)e^{c_2t} + \dots + P_k(t)e^{c_kt} = 0$

Assume that not all c_{ij} are zero, then $\exists P_i \neq 0$

Say, P_k

Divide the equation by e^{c_1t}

$$P_1(t) + P_2(t)e^{(c_2-c_1)t} + \dots + P_k(t)e^{(c_k-c_1)t} = 0 \dots (1)$$

Upon differentiating (1) sufficiently many times we can reduce $P_1(t)$ to 0

$$Q_2(t)e^{(c_2-c_1)t} + \dots + Q_k(t)e^{(c_k-c_1)t} = 0, \text{ and } \deg Q_i = \deg P_i$$

and Q_k does not vanish identically

Continuing this process, $R_k(t)e^{(c_k-c_1)t} = 0$, and $\deg R_k = \deg P_k$

and R_k does not vanish identically

But $R_k(t)e^{(c_k-c_1)t} = 0$ implies $R_k = 0$

It's a contradiction to $P_k \neq 0$

$$\therefore P_k(t) = 0, \forall x \in I$$

\therefore All c_{ij} 's are zero

12.

$$(i) \ g(D)(V) \subseteq N(h(D))$$

$$(ii) \ \dim N(h(D)) = \dim g(D)(V)$$

Suppose $\deg g(t) = k$, $\deg h(t) = m$ ($n = k + m$)

Consider the linear map $g(D_V) : V \rightarrow V$

By the dimension theorem,

$$\begin{aligned}
 \dim V &= \dim R(g(D_V)) + \dim N(g(D_V)) \\
 &= \dim R(g(D_V)) + \dim N(g(D)) \quad (\because N(g(D)) \subseteq V) \\
 &= \dim(g(D)(V)) + \dim N(g(D)) \quad (\because R(g(D_V)) = g(D)(V)) \\
 &= \dim g(D)(V) + k \\
 \therefore \dim g(D)(V) &= n - k = m = \dim N(h(D))
 \end{aligned}$$

13.

(a) Ontoness of $P(D) : C^\infty \rightarrow C^\infty$

Since \mathbb{C} is algebraically closed

$$P(D) = \alpha(D - c_1)(D - c_2) \cdots (D - c_n), \text{ where } \alpha \neq 0, c_1, \dots, c_n \in \mathbb{C}$$

Let $v \in C^\infty$: by lemma 1, $\exists u_1 \in C^\infty$ s.t. $(D - c_1)u_1 = v$

and $\exists u_2 \in C^\infty$ $(D - c_2)u_2 = u_1 \cdots$ continuing this process,

we get $u_1, u_2, \dots, u_n \in C^\infty$ s.t. $(D - c_i)u_i = u_{i-1}$ ($2 \leq i \leq n$)

$$\begin{aligned}
 \text{Put } u &= \frac{1}{\alpha} u_n : P(D)u = \alpha(D - c_1)(D - c_2) \cdots (D - c_{n-1})(D - c_n)(u) \\
 &= (D - c_1)(D - c_2) \cdots (D - c_{n-1})(D - c_n)u_n = v
 \end{aligned}$$

14.

By induction on n , $p(t)$: a polynomial of degree $n(\geq 1)$

A solution $x(t)$ of $p(D)y = 0$ — — — (*)

We may assume w.l.o.g that $p(t)$ monic

For $n = 1$, (*) becomes $y' - ay = 0 \Rightarrow x(t) = ce^{at} (c \in \mathbb{C})$

if $x(t_0) = 0 \Rightarrow ce^{at_0} = 0 \Rightarrow c = 0 \therefore x(t) = 0$

Assume it is true for $n - 1 (n > 1)$ and $\deg p(t) = n$

This case $p(t) = q(t)(t - c)$, $q(t)$ of degree $n - 1$, $c \in \mathbb{C}$

let $z = q(D)x$

then by $(*)$, we have $(D - c)z = (D - c)q(D)x = p(D)x = 0$

$\therefore z$ is a solution to $(D - c)y = 0$

By hypothesis, $x(t_0) = x'(t_0) = \dots = x^{n-2}(t_0) = x^{n-1}(t_0) = 0$ for fixed $t_0 \in \mathbb{R}$

$\Rightarrow \forall t \in \mathbb{R}, z(t) = x^{(n-1)}(t) + a_{n-1}x^{(n-2)}(t) + \dots + a_1x'(t) + a_0x(t) \Rightarrow z(t_0) = 0$

$\Rightarrow z(t_0) = 0 \Rightarrow z'(t_0) = 0 (\because z'(t_0) - cz(t_0) = 0, z'(t_0) = 0)$

$\Rightarrow z(t) = 0, \forall t$

$\Rightarrow q(D)x = z = 0$

15.

$\Phi : V \rightarrow \mathcal{C}^n, \Phi(x) = (x(t_0), x'(t_0), \dots, x^{n-1}(t_0))^T, \forall x \in V$

(a)

(i) Φ is linear

$$\begin{aligned} x, y \in V, \alpha \in F \\ \Phi(x + y) &= \begin{pmatrix} (x + y)(t_0) \\ (x + y)'(t_0) \\ \dots \\ (x + y)^{n-1}(t_0) \end{pmatrix} = \begin{pmatrix} x(t_0) + y(t_0) \\ x'(t_0) + y'(t_0) \\ \dots \\ x^{n-1}(t_0) + y^{n-1}(t_0) \end{pmatrix} = \Phi(x) + \Phi(y) \\ \Phi(\alpha x) &= \begin{pmatrix} (\alpha x)(t_0) \\ (\alpha x)'(t_0) \\ \dots \\ (\alpha x)^{n-1}(t_0) \end{pmatrix} = \alpha \begin{pmatrix} x(t_0) \\ x'(t_0) \\ \dots \\ x^{n-1}(t_0) \end{pmatrix} = \alpha \Phi(x) \end{aligned}$$

$$(ii) \Phi(x) = 0 \Rightarrow x = \{0\}$$

If $x(t_0) = x'(t_0) = \dots = x^{n-1}(t_0) = 0$, then $x = 0$

Since $\dim_{\mathbb{C}} V = \dim_{\mathbb{C}} \mathbb{C}^n = n$, Φ is an isomorphism

(iii) Since $\dim_{\mathbb{C}}^V = \dim_{\mathbb{C}}^{\mathbb{C}^n} = n$, Φ is onto

(b)

Since Φ is an isomorphism,

Let $c = (c_0, c_1, \dots, c_{n-1}) \in \mathbb{C}^n$ s.t $x(t_0) = c_0$ and $x^k(t_0) = c_k$, $k = 1, \dots, n-1$

By (a), $\exists! x \in V$

16.

$$(a) \theta'' + \frac{g}{l}\theta = 0$$

$$t^2 + \frac{g}{l} = 0, t_1 = \sqrt{\frac{g}{l}}i, t_2 = -\sqrt{\frac{g}{l}}i$$

$$\therefore \theta = c_1 \cos \frac{g}{l}t + c_2 \sin \frac{g}{l}t$$

$$(b) \theta(0) = \theta_0 > 0, \theta'(0) = 0$$

$$\theta(0) = c_1 = \theta_0$$

$$\theta'(0) = c_2 \sqrt{\frac{g}{l}} = 0$$

$$\therefore c_2 = 0$$

$$\therefore \theta = \theta_0 \cos \sqrt{\frac{g}{l}}t$$

$$(c) \text{ The period of the system is } \frac{2\pi}{\sqrt{\frac{g}{l}}} = 2\pi \sqrt{\frac{g}{l}}$$

17.

$$y'' + \frac{k}{m}y = 0$$

2.7.

$$y(t) = c_1 \cos \sqrt{\frac{k}{m}}t + ic_2 \sin \sqrt{\frac{k}{m}}t$$

18.

$$(a) \quad my'' + ry' + ky = 0, \quad r > 0$$

Since the auxiliary polynomial is $p(t) = mt^2 + rt + k = 0$,

$$\therefore t_1 = \frac{-r + \sqrt{r^2 - 4km}}{2m}, \quad t_2 = \frac{-r - \sqrt{r^2 - 4km}}{2m}$$

$$\therefore y(t) = c_1 e^{t_1 t} + c_2 e^{t_2 t}$$

(b)

$$y(0) = c_1 + c_2 = 0 \quad \therefore c_1 = -c_2$$

$$y'(0) = c_1 t_1 + c_2 t_2 = v_0$$

$$c_2 = \frac{v_0}{t_2 - t_1}, \quad c_1 = \frac{-v_0}{t_2 - t_1}$$

$$\therefore y(t) = \left(\frac{-v_0}{t_2 - t_1}\right)e^{t_1 t} + \left(\frac{v_0}{t_2 - t_1}\right)e^{t_2 t}, \quad (t_2 - t_1 = \frac{\sqrt{r^2 - 4km}}{m})$$

(c)

$$y(t) = c_1 e^{t_1 t} + c_2 e^{t_2 t} = e^{\frac{-r}{2m}t} (c_1 e^{\frac{\sqrt{r^2 - 4km}}{2m}t} + c_2 e^{-\frac{\sqrt{r^2 - 4km}}{2m}t})$$

$$t \rightarrow \infty \Rightarrow e^{\frac{-r}{2m}t} \rightarrow 0$$

$$\therefore \lim_{t \rightarrow \infty} y(t) = 0$$

19.

$\therefore \mathcal{C}$ is algebraically closed

20.

(a) Theorem 2.27

If $n = 1$, then $x' + a_0x = 0 \Rightarrow x' = -a_0x$

Since x has a derivative x' , x' must have a derivative $x'' = -a_0x'$

Assume that this assertion is true for an $n - 1$ th-order homogeneous linear differential equation with constant coefficients

Then $x^{(n)} = x^{(n-1)}x' = -a_0x^{(n-2)}x = -a_0x^{(n-1)}$

So $x^{(k)}$ exists for every positive integer k

(b)

$y_1 = e^{c+t}$, $y_2 = e^ce^t$ (for $\forall c \in \mathbb{R}$)

(i) Let $x = (e^{c+t} - e^ce^t) \Rightarrow x' = e^{c+t} - e^ce^t = x$

So x is a solution to the equation $y' - y = 0$ with $x(0) = 0$

So by the exercise 14, $x(t) \equiv 0 \forall t$

$\therefore e^{c+t} = e^ce^t$ putting $t = d \in \mathbb{R}$

$$e^{c+d} = e^ce^d$$

(ii) $e^ce^{-c} = e^0 = 1 = e^c \frac{1}{e^c}$

$$e^c(e^{-c} - \frac{1}{e^c}) = 0 \Rightarrow e^c \neq 0$$

$$\therefore e^{-c} = \frac{1}{e^c}$$

Since \mathbb{C} is algebraically closed

(c) Theorem 2.28

Any homogeneous linear differential equation with constant coefficients can be rewritten as $P(D)y = 0$, where $p(t)$ is the auxiliary polynomial associated with the equation.

Therefore the set of all solutions to a homogeneous linear differential equation with constant coefficients coincides with the null space of $P(D)$, where $p(t)$ is the auxiliary polynomial associated with the equation.

(d) Theorem 2.29

$$f(t) = e^{ct} = e^{a+ibt} = e^{at}(\cos bt + i \sin bt) = e^{at} \cos bt + i e^{at} \sin bt$$

$$f'(t) = a e^{at} \cos bt - b e^{at} \sin bt + i a e^{at} \sin bt + i b e^{at} \cos bt$$

$$= (a + ib) e^{at} \cos bt + i(a + ib) e^{at} \sin bt$$

$$= (a + ib) \{e^{at}(\cos bt + i \sin bt)\}$$

$$= c e^{ct}$$

(e)

$$(xy)' = (u_1 u_2 + i(u_1 v_2 + u_2 v_1) - v_1 v_2)'$$

$$= \{(u_1 u_2 - v_1 v_2) + i(u_1 v_2 + u_2 v_1)\}'$$

$$= (u_1' u_2 + u_1 u_2' - v_1' v_2 - v_1 v_2') + i(u_1' v_2 + u_1 v_2' + u_2' v_1 + u_2 v_1')$$

$$= \{u_1' u_2 + i(u_1' v_2 + u_2 v_1') - v_1' v_2\} + \{u_1 u_2' + i(u_1 v_2' + u_2' v_1) - v_1 v_2'\}$$

$$= (u_1' + i v_1')(u_2 + i v_2) + (u_1 + i v_1)(u_2' + i v_2')$$

$$= x'y + xy'$$

(f)

Let $x = u + iv$

$$x' = u' + i v' = 0$$

$$\therefore u' = 0, v' = 0$$

$\therefore u, v$ is a constant function

$\therefore x = u + iv$ is a constant function

§3. Elementary Matrix Operations and Systems of Linear Equations

3.1. Elementary Matrix Operations and Elementary Matrices

1. (a) T

(b) F

(\therefore) $I_3 \rightsquigarrow \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$, by $-2 \times C_1 + C_3 \Rightarrow C_3$

(c) T

(\therefore) $I_n \rightsquigarrow I_n$, by $1 \times C_1 \Rightarrow C_1$

(d) F

(e) T

(\therefore) Theorem 3.2

(f) F

(\therefore) Let $E_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$, $E_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

then, $E_1 + E_2$ is not an elementary matrix

(g) T

(h) F

(i) T

Let $A \rightsquigarrow B = EA$,

then E is invertible and its inverse is also an elementary matrix

3.1.

$$\therefore B \rightsquigarrow A = E^{-1}B$$

2.

$$(i) A \rightsquigarrow B, \text{ by } -2 \times C_1 + C_2 \rightarrow C_2$$

$$(ii) B \rightsquigarrow C, \text{ by } -1 \times R_1 + R_2 \rightarrow R_2$$

$$(iii) C \rightsquigarrow I_3, \text{ by}$$

$$\frac{1}{2} \times R_2 \rightarrow R_2$$

$$R_2 \leftrightarrow R_3$$

$$R_3 + R_2 \rightarrow R_2$$

$$\frac{1}{4} \times R_2 \rightarrow R_2$$

$$-1 \times R_2 + R_3 \rightarrow R_3$$

$$-3 \times R_3 + R_1 \rightarrow R_1$$

3.

$$(a) E = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$I_3 \Rightarrow (R_1 \leftrightarrow R_3) \Rightarrow E \Rightarrow (R_1 \leftrightarrow R_3) \Rightarrow I_3$$

$$\therefore E^{-1} = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$(b) E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$I_3 \Rightarrow (3 \times R_2 \rightarrow R_2) \Rightarrow E \Rightarrow (\frac{1}{3} \times R_2 \rightarrow R_2) \Rightarrow I_3$$

3.1.

$$\therefore E^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{3} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$(c) E = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{pmatrix}$$

$$I_3 \Rightarrow (-2 \times R_1 + R_3 \rightarrow R_3) \Rightarrow E \Rightarrow (2 \times R_1 + R_3 \rightarrow R_3) \Rightarrow I_3$$

$$\therefore E^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix}$$

4.

(i) E is of type 1

$$E = (e_1, \dots, e_j, \dots, e_i, \dots, e_n)$$

$$F = (e_1, \dots, e_j, \dots, e_i, \dots, e_n) = E$$

(ii) E is of type 2

$$E = (e_1, \dots, ae_j, \dots, e_n)$$

$$F = (e_1, \dots, ae_j, \dots, e_n) = E$$

(iii) E is of type 3

$$E = (e_1, \dots, e_i, \dots, e_j + ae_i, \dots, e_n)$$

$$F = (e_1, \dots, e_i + ae_j, \dots, e_j, \dots, e_n) = E^t$$

5.

(\Rightarrow)

(i) E is of type 1

$$E = (e_1, \dots, e_j, \dots, e_i, \dots, e_n)$$

$$E^t = (e_1, \dots, e_j, \dots, e_i, \dots, e_n)$$

(ii) E is of type 2

$$E = (e_1, \dots, ae_j, \dots, e_n)$$

$$E^t = (e_1, \dots, ae_j, \dots, e_n)$$

(iii) E is of type 3

$$E = (e_1, \dots, e_i, \dots, e_j + ae_i, \dots, e_n)$$

$$E^t = (e_1, \dots, e_i + ae_j, \dots, e_j, \dots, e_n)$$

(\Leftarrow) Using the fact $(E^t)^t = E$, then it is clear

6.

(i) if $B = EA$, then $B^t = (EA)^t = A^t E^t$

(ii) if $B = AE$, then $B^t = (AE)^t = E^t A^t$

7.

(1) Elementary column operation

(i) E is of type 1

$$B = (A^{(1)}, \dots, A^{(j)}, \dots, A^{(i)}, \dots, A^{(n)})$$

$$E = (e_1, \dots, e_j, \dots, e_i, \dots, e_n)$$

$$\Rightarrow AE = (Ae_1, \dots, Ae_j, \dots, Ae_i, \dots, Ae_n) = B$$

$$\therefore B = AE$$

(ii) E is of type 2

$$B = (A^{(1)}, \dots, aA^{(j)}, \dots, A^{(n)})$$

$$E = (e_1, \dots, ae_j, \dots, e_n)$$

$$\Rightarrow AE = (Ae_1, \dots, aAe_j, \dots, Ae_n) = B$$

$$\therefore B = AE$$

(iii) E is of type 3

$$B = (A^{(1)}, \dots, A^{(i)}, \dots, A^{(j)} + aA^{(i)}, \dots, A^{(n)})$$

$$E = (e_1, \dots, e_i, \dots, e_j + ae_i, \dots, e_n)$$

$$\Rightarrow AE = (Ae_1, \dots, Ae_i, \dots, Ae_j + aAe_i, \dots, Ae_n) = B$$

$$\therefore B = AE$$

(2) Elementary row operation

(i) E is of type 1

$$B = (A_{(1)}, \dots, A_{(j)}, \dots, A_{(i)}, \dots, A_{(m)})$$

$$E = (e_1, \dots, e_j, \dots, e_i, \dots, e_m)$$

$$\Rightarrow EA = (e_1A, \dots, e_jA, \dots, e_iA, \dots, e_mA) = B$$

$$\therefore B = EA$$

(ii) E is of type 2

$$B = (A_{(1)}, \dots, aA_{(j)}, \dots, A_{(m)})$$

$$E = (e_1, \dots, ae_j, \dots, e_m)$$

$$\Rightarrow EA = (e_1A, \dots, ae_jA, \dots, e_mA) = B$$

$$\therefore B = EA$$

(iii) E is of type 3

$$B = (A_{(1)}, \dots, A_{(i)}, \dots, A_{(j)} + aA_{(i)}, \dots, A_{(m)})$$

$$\begin{aligned}
E &= (e_1, \dots, e_i, \dots, e_j + ae_i, \dots, e_m) \\
\Rightarrow EA &= (e_1A, \dots, e_iA, \dots, e_jA + ae_iA, \dots, e_mA) = B \\
\therefore B &= EA
\end{aligned}$$

8.

(i) E is of type 1

$$\begin{aligned}
E &= (e_1, \dots, e_j, \dots, e_i, \dots, e_n) \\
E^{-1} &= (e_1, \dots, e_j, \dots, e_i, \dots, e_n)
\end{aligned}$$

(ii) E is of type 2

$$\begin{aligned}
E &= (e_1, \dots, ae_j, \dots, e_n) \\
E^{-1} &= (e_1, \dots, \frac{1}{a}e_j, \dots, e_n)
\end{aligned}$$

(iii) E is of type 3

$$\begin{aligned}
E &= (e_1, \dots, e_i, \dots, e_j + ae_i, \dots, e_n) \\
E^{-1} &= (e_1, \dots, e_i, \dots, e_j - ae_i, \dots, e_n)
\end{aligned}$$

If $P \rightsquigarrow Q = EP$, then $P = E^{-1}Q$ Let $E' = E^{-1}$ Since E' is invertible and is an elementary matrix, $Q \rightsquigarrow P = E'Q$ 9. $I_n \Rightarrow E'_3, E''_3, E'''_3, E_2 \Rightarrow E$,where $E'_3 : -1 \times R_i + R_j \Rightarrow R_j$ i.e $E = (e_1, \dots, e_i, \dots, e_j - e_i, \dots, e_n)$ $E''_3 : 1 \times R_j + R_i \Rightarrow R_i$ i.e $E = (e_1, \dots, e_i + (e_j - e_i), \dots, e_j - e_i, \dots, e_n)$

3.1.

$$E_3''' : -1 \times R_i + R_j \Rightarrow R_j \text{ i.e } E = (e_1, \dots, e_j, \dots, -e_i, \dots, e_n)$$

$$E_2 : -1 \times R_j \Rightarrow R_j \text{ i.e } E = (e_1, \dots, e_j, \dots, e_i, \dots, e_n)$$

$\therefore E$ is of type 1

10. a is a nonzero scalar

$$I_n \Rightarrow E_2 \Rightarrow E$$

$$\text{,where } E_2 : \frac{1}{a} \times R_i \rightarrow R_i \text{ i.e } E = (e_1, \dots, \frac{1}{a}e_i, \dots, e_n)$$

$\therefore E$ is of type 2

$$11. I_n \Rightarrow E_3 \Rightarrow E$$

$$\text{,where } E_3 : -a \times R_i + R_j \rightarrow R_j \text{ i.e } E = (e_1, \dots, e_i, \dots, e_j - ae_i, \dots, e_n)$$

$\therefore E$ is of type 3

12.

By induction on $n \geq 1$

If $n = 1$ o.k.

Assume that $n > 1$

If the first column of A is zero, then $A = (O \mid B)$, where $B = ()_{m \times (n-1)}$

So by induction hypothesis, B can be transformed by row operation of type 1 and 3

If the first column of A is not zero, we may assume that $a_{11} \neq 0$

3.1.

$$\text{So } A \rightsquigarrow \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & & & \\ \vdots & & C & \\ 0 & & & \end{pmatrix}, \text{ where } C = ()_{(m-1) \times (n-1)}$$

By induction hypothesis, $C \rightsquigarrow$ U.T.M

$$\therefore A \rightsquigarrow \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ 0 & & & \\ \vdots & & D & \\ 0 & & & \end{pmatrix} : \text{U.T.M}$$

3.2. The Rank of a Matrix and Matrix Inverse

1. (a) F (Theorem 3.5)

(b) F

(\therefore) If $A \in M_{m \times n}(F)$, $B \in M_{n \times n}(F)$ and B is invertible,
then the $\text{rank}(AB) = \text{rank}(A)$

(Example)

$$A = B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \text{ and } \text{rank}(A) = \text{rank}(B) = 1$$

$$AB = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \text{ and } \text{rank}(AB) = 0$$

(c) T

(d) T (p.153, Corollary to the Theorem 3.4)

(e) F (p.153, Corollary to the Theorem 3.4)

(f) T (p.153, Theorem 3.4 and Theorem 3.5)

(g) T (p.161)

(h) T

(\therefore) $\forall A \in M_{m \times n}(F)$, $\text{rank}(A) = \dim R(L_A) \leq n$

(i) T

2.

(a) $A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$, $\text{rank}(A) = 2$

3.2.

$$(b) A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \end{pmatrix}, \text{rank}(A) = 3$$

$$(c) A = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \end{pmatrix}, \text{rank}(A) = 2$$

$$(d) A = \begin{pmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \text{rank}(A) = 1$$

$$(e) A = \begin{pmatrix} 1 & 2 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 & -2 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}, \text{rank}(A) = 3$$

$$(g) A = \begin{pmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \text{rank}(A) = 1$$

3.

$\forall A \in M_{m \times n}(F)$, $\text{rank}(A) = 0$ iff A is the zero matrix

(\Leftarrow) clear

(\Rightarrow) let $A = (e_1, 0, \dots, 0)$, $e_1 \neq 0$

Since $\text{rank}(A) = 0$, e_1 is dependent

$\therefore \exists a \in F$ s.t $e_1 = a0$

It's contradict to $e_1 \neq 0$

4.

$$(a) \begin{pmatrix} 1 & 1 & 1 & 2 \\ 2 & 0 & -1 & 2 \\ 1 & 1 & 1 & 2 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & -\frac{1}{2} & 1 \\ 0 & 1 & \frac{3}{2} & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, 2$$

$$(b) \begin{pmatrix} 2 & 1 \\ -1 & 2 \\ 2 & 1 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 12 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}, 2$$

$$5. (A \mid I_n) \rightsquigarrow (I_n \mid B), B = A^{-1}$$

$$(a) \left(\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 1 & 1 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{cc|cc} 1 & 0 & -1 & 2 \\ 0 & 1 & 1 & -1 \end{array} \right)$$

$$\therefore A^{-1} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}, \text{rank}(A) = 2$$

$$(b) \left(\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 2 & 4 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 0 & 0 & -2 & 1 \end{array} \right)$$

$$\text{rank}(A) = 1, \text{ so } \nexists A^{-1}$$

$$(c) \left(\begin{array}{ccc|ccc} 1 & 2 & 1 & 1 & 0 & 0 \\ 1 & 3 & 4 & 0 & 1 & 0 \\ 2 & 3 & -1 & 0 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & -5 & 3 & -2 & 0 \\ 0 & 1 & 3 & -1 & 1 & 0 \\ 0 & 0 & 0 & -3 & 1 & 1 \end{array} \right)$$

$$\text{rank}(A) = 2, \text{ so } \nexists A^{-1}$$

$$(d) \left(\begin{array}{ccc|ccc} 0 & -2 & 4 & 1 & 0 & 0 \\ 1 & 1 & -1 & 0 & 1 & 0 \\ 2 & 4 & -5 & 0 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1/6 & 15/9 & -1/3 \\ 0 & 1 & 0 & -5/18 & -4/9 & 2/9 \\ 0 & 0 & 1 & 1/9 & -2/9 & 1/9 \end{array} \right)$$

$$\therefore \text{rank}(A) = 3, A^{-1} = \begin{pmatrix} \frac{1}{6} & \frac{15}{9} & -\frac{1}{3} \\ -\frac{5}{18} & -\frac{4}{9} & \frac{2}{9} \\ \frac{1}{9} & -\frac{2}{9} & \frac{1}{9} \end{pmatrix}$$

$$(e) \left(\begin{array}{ccc|ccc} 0 & -2 & 4 & 1 & 0 & 0 \\ 1 & 1 & -1 & 0 & 1 & 0 \\ 2 & 4 & 5 & 0 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 0 & 1/6 & -1/3 & 1/2 \\ 0 & 1 & 0 & 1/2 & 0 & -1/2 \\ 0 & 0 & 1 & 1/6 & 1/3 & 1/2 \end{array} \right)$$

$$\therefore \text{rank}(A) = 3, A^{-1} = \begin{pmatrix} \frac{1}{6} & -\frac{1}{3} & \frac{1}{2} \\ \frac{1}{2} & 0 & -\frac{1}{2} \\ -\frac{1}{6} & \frac{1}{3} & \frac{1}{2} \end{pmatrix}$$

$$(f) \left(\begin{array}{ccc|ccc} 0 & 2 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1/2 & -1/2 & 0 \\ 0 & 0 & 0 & -1/2 & -1/2 & 1 \end{array} \right)$$

$$\therefore \text{rank}(A) = 2, \text{ so } \nexists A^{-1}$$

$$(g) \left(\begin{array}{cccc|cccc} 1 & 2 & 1 & 0 & 1 & 0 & 0 & 0 \\ 2 & 5 & 5 & 1 & 0 & 1 & 0 & 0 \\ -2 & -3 & 0 & 3 & 0 & 0 & 1 & 0 \\ 3 & 4 & -2 & -3 & 0 & 0 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -51 & 15 & 7 & 2 \\ 0 & 1 & 0 & 0 & 31 & -9 & -4 & -7 \\ 0 & 0 & 1 & 0 & -10 & 3 & 1 & 2 \\ 0 & 0 & 0 & 1 & -3 & 1 & 1 & 1 \end{array} \right)$$

$$\therefore \text{rank}(A) = 4, A^{-1} = \begin{pmatrix} -51 & 15 & 7 & 2 \\ 31 & -9 & -4 & -7 \\ -10 & 3 & 1 & 2 \\ -3 & 1 & 1 & 1 \end{pmatrix}$$

$$(h) \left(\begin{array}{cccc|cccc} 1 & 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & -1 & 2 & 0 & 1 & 0 & 0 \\ 2 & 0 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & -1 & 1 & -3 & 0 & 0 & 0 & 1 \end{array} \right) \Rightarrow \left(\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -3/2 & -1/10 & 13/10 & 1/10 \\ 0 & 1 & 0 & 0 & 1/2 & 1/2 & -7/5 & 1/2 \\ 0 & 0 & 1 & 0 & -3 & -1/5 & 16/10 & 1/5 \\ 0 & 0 & 0 & 1 & 1/2 & 1/10 & -3/10 & -1/10 \end{array} \right)$$

$$\therefore \text{rank}(A) = 4, A^{-1} = \begin{pmatrix} -3/2 & -1/10 & 13/10 & 1/10 \\ 1/2 & 1/2 & -7/5 & 1/2 \\ -3 & -1/5 & 16/10 & 1/5 \\ 1/2 & 1/10 & -3/10 & -1/10 \end{pmatrix}$$

6.

$$(a) [T]_{\beta} = \begin{pmatrix} -1 & 2 & 2 \\ 0 & -1 & 4 \\ 0 & 0 & -1 \end{pmatrix}, \text{rank}[T]_{\beta} = 3$$

 $\therefore T$ is invertible

$$([T]_{\beta})^{-1} = \begin{pmatrix} -1 & -2 & 10 \\ 0 & -1 & 4 \\ 0 & 0 & -1 \end{pmatrix}$$

$$\therefore T^{-1}(ax^2 + bx + c) = -ax^2 - (4a + b)x - (10a + 2b + c)$$

$$(b) [T]_{\beta} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}, \text{rank}[T]_{\beta} = 2$$

 $\therefore T$ is not invertible

$$(c) [T]_{\beta} = \begin{pmatrix} 1 & 2 & 1 \\ -1 & 1 & 2 \\ 1 & 0 & 1 \end{pmatrix}, \text{rank}[T]_{\beta} = 3$$

 $\therefore T$ is invertible

3.2.

$$([T]_{\beta})^{-1} = \begin{pmatrix} 1/6 & -1/3 & 1/2 \\ 1/2 & 0 & -1/2 \\ -1/6 & 1/3 & 1/ \end{pmatrix}$$

$$\therefore T^{-1}(a, b, c) = (\frac{1}{6}a - \frac{1}{3}b + \frac{1}{2}c, \frac{1}{2}a - \frac{1}{2}c, -\frac{1}{6}a + \frac{1}{3}b + \frac{1}{2}c)$$

7.

$$A = \begin{pmatrix} 1 & 2 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 2 \end{pmatrix} \rightsquigarrow I_3 = E_6 \cdots E_1 A$$

$$\therefore A = E_1^{-1} \cdots E_6^{-1}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

8.

$$cA = (cI_m)A$$

Since cI_m is invertible

$$\therefore \text{rank}(cA) = \text{rank}((cI_m)A)$$

9.

If B is obtained from a matrix A by an elementary column operation, then there exists an elementary matrix E such that $B = AE$

Since E is invertible and hence $\text{rank}(B) = \text{rank}(A)$

10. If A is the zero matrix, then $r = 0$

$$\text{rank}(A) = \text{rank}(D) = 0$$

Suppose that A is a nonzero matrix

By means of at most one type 1 row operation, at most one type 2 row operation, and at most $(m - 1)$ type 3 row operations

this matrix can be transformed into $(1, 0, \dots, 0)^T$

$$\therefore \text{rank}(A) = \text{rank}(D) = 1$$

11. (By theorem 3.6)

$$B' \rightsquigarrow D' = \begin{pmatrix} I_k & O \\ O & O \end{pmatrix}, \text{rank} B' = k \text{ and}$$

$$B \rightsquigarrow D = \left(\begin{array}{c|cc} 1 & O & \\ \hline O & I_k & O \\ & O & O \end{array} \right) = \begin{pmatrix} I_{k+1} & O \\ O & O \end{pmatrix}$$

$$\therefore \text{rank} B = k + 1 = r$$

$$\therefore \text{rank} B' = r - 1$$

12. By induction on $n \geq 1$

If $n = 1$, it is clear

Assume $n > 1$

If the first column of A is zero, then $A = \begin{pmatrix} O & B \end{pmatrix}$, where $B \in M_{m \times (n-1)}$

So by induction hypothesis, B can be transformed by row operation of type 1 and 3

If the first column of A is not zero,

we may assume that $a_{11} \neq 0$

$$\text{So } A \rightsquigarrow \left(\begin{array}{c|ccc} a_{11} & a_{12} & \cdots & a_{1n} \\ \hline 0 & & & \\ \vdots & & C & \\ 0 & & & \end{array} \right), \text{ where } C \in M_{(m-1) \times (n-1)}$$

By by induction hypothesis, $C \rightsquigarrow U.T.M$

$$\therefore A \rightsquigarrow U.T.M$$

13. (b) and (c)

Since $\text{rank}(A) = \text{rank}(A^t)$, the maximal number of linearly independent columns of A equals to the maximal number of linearly independent columns of A^t ,

i.e. the maximal number of linearly independent rows of A

$$\therefore \text{colrank}(A) = \text{rowrank}(A)$$

(*cf*) Let S the solution space for $AX = 0$, then by the dimension theorem and $\text{rank}(L_A) = \text{colrank}(A)$,

$$\dim S = n - \text{colrank}(A)$$

If $r = \dim(\text{row space of } A)$, then the solution space S has a $(n - r)$ vectors,

$$\text{i.e. } \dim S = n - \text{rowrank}(A)$$

$$\therefore \text{colrank}(A) = \text{rowrank}(A)$$

14. $T, U : V \rightarrow W$

$$(i) \ w \in R(T + U) \Rightarrow \exists v \in V \text{ s.t. } w = (T + U)(v)$$

$$\Rightarrow w = T(v) + U(v) \in R(T) + R(U)$$

$$\begin{aligned}
\text{(ii)} \quad & \text{rank}(T + U) \leq \dim(R(T) + R(U)) \\
& \leq \dim(R(T)) + \dim(R(U)) \\
& = \text{rank}(T) + \text{rank}(U)
\end{aligned}$$

$$\begin{aligned}
\text{(c)} \quad & \text{By (b), } \text{rank}(A + B) = \text{rank}(L_{A+B}) \\
& = \text{rank}(L_A + L_B) \\
& \leq \text{rank}(L_A) + \text{rank}(L_B) \\
& = \text{rank}(A) + \text{rank}(B)
\end{aligned}$$

15.

$$\begin{aligned}
& \text{Let } A = (a_1, a_2, \dots, a_p)_{n \times p} \text{ and } B = (b_1, b_2, \dots, b_q)_{n \times q} \\
& (A \mid B) = (a_1, a_2, \dots, a_p, b_1, b_2, \dots, b_q)_{n \times (p+q)} \\
& M(A \mid B) = (Ma_1, Ma_2, \dots, Ma_p, Mb_1, Mb_2, \dots, Mb_q)_{n \times (p+q)} \\
& (MA \mid MB)
\end{aligned}$$

16. (Theorem 3.4 (b))

$$\text{Let } V = R(L_A) = L_A(F^n)$$

$$\text{Then } V \leq F^m \text{ and } \dim V = \dim L_P(V)$$

because L_P is an isomorphism (by the exercise 17 in section 2.4)

$$\begin{aligned}
& \text{rank}(A) = \dim L_A(V) = \dim V \\
& = \dim L_P(V) \\
& = \dim L_P L_A(F^n)
\end{aligned}$$

$$= \dim L_{PA}(F^n)$$

$$\text{rank}(PA)$$

17.

$$\text{Let } PAQ = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \text{ then}$$

$$A = P^{-1} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} (1 \ 0 \ 0) Q^{-1}$$

18.

Let $A = (a_1, a_2, \dots, a_n)_{m \times n}$ where a_k the k -th column of A and let $A_k = (0, \dots, a_k, \dots, 0)_{m \times n}$

Thus $\forall k, \text{rank}(A_k B) \leq 1$ and $AB = A_1 B + \dots + A_n B$

19.

By the theorem 3.7 $\text{rank}(AB) \leq \text{rank}(A)$ and

by the Sylvester inequality, $\text{rank}(AB) \geq \text{rank}(A)$

$\therefore \text{rank}(AB) = \text{rank}(A) = m$

(cf) the Sylvester inequality

$$\text{rank}(A) + \text{rank}(B) \leq \text{rank}(AB) + n,$$

where n is the number of columns of A and also the number of rows of B

20.

(a)

$A \rightsquigarrow D = EA = ()$: the reduced row echelon form of A

$\Rightarrow \{v_1 = (), v_2 = ()\}$ is a basis of $\text{Null}(L_A)$

Thus $AM = (0)_{5 \times 5}$, where $M = (v_1, v_2, 0, 0, 0)$

(b)

Suppose $B = (b_1, b_2, \dots, b_5)_{5 \times 5}$ s.t. $AB = (0)_{4 \times 5}$

$\Rightarrow b_1, b_2, \dots, b_5 \in N(L_A)$ with $\text{null } L_A = 2$

Thus $\text{rank} B = \text{dimspan}(b_1, b_2, \dots, b_5) \leq \text{dim Null}(L_A) = 2$

21.

$A = (a_{ij})_{m \times n}, \text{rank}(A) = m$

$A \rightsquigarrow D = AQ = (I_m \mid O)_{m \times n}, Q \in M_{n \times n}$: invertible matrix

Let $B = QM$, where $M = \begin{pmatrix} I_m \\ O \end{pmatrix}_{n \times m}$

then $AB = (QM) = (AQ)M = (I_m \mid O) \begin{pmatrix} I_m \\ O \end{pmatrix} = I_m$

22.

$B = (b_{ij})_{n \times m}, \text{rank}(B) = m$

$B \rightsquigarrow D = QB = \begin{pmatrix} I_m \\ O \end{pmatrix}_{n \times m}, Q \in M_{n \times n}$: invertible matrix

Let $A = MQ$, where $M = (I_m \mid O)_{m \times n}$

then $AB = M(QB) = MD = I_m$

3.3. Systems of Linear equations - Theoretical aspects

1.

(a) F

p.170, Example 1 (c)

(b) F

(c) T

Any homogeneous system has at least one solution, namely, the zero vector

(d) F

p.174, Theorem 3.10

(e) F

(f) F

p.172, Theorem 3.9

(g) T

If A is invertible, then $AX = 0$ has no nonzero solutions

(h) T

2. Let K be the solution set of the given system and A is the coefficient matrix of the system

$$(a) A = \begin{pmatrix} 1 & 3 \\ 2 & 6 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 3 \\ 0 & 0 \end{pmatrix}$$

$$\text{rank}(A) = 1, \dim(K) = 2 - 1 = 1$$

$$\left\{ \begin{pmatrix} -3 \\ 1 \end{pmatrix} \right\} : \text{a basis for } K$$

$$(b) \ A = \begin{pmatrix} 1 & 1 & -1 \\ 4 & 1 & -2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\text{rank}(A) = 2, \dim(K) = 3 - 2 = 1$$

Since $(1, 2, 3)^t$ is a solution to $AX = 0$,

$$\left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \right\} : \text{a basis for } K$$

$$(c) \ A = \begin{pmatrix} 1 & 2 & -1 \\ 2 & 1 & 1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\text{rank}(A) = 2, \dim(K) = 3 - 2 = 1$$

Since $(-1, 1, 1)^t$ is a solution to $AX = 0$,

$$\left\{ \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \right\} : \text{a basis for } K$$

$$(d) \ A = \begin{pmatrix} 2 & 1 & -1 \\ 1 & -1 & 1 \\ 1 & 2 & -2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{rank}(A) = 2, \dim(K) = 3 - 2 = 1$$

Since $(0, 1, 1)^t$ is a solution to $AX = 0$,

$$\left\{ \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \right\} : \text{a basis for } K$$

$$(e) \ A = (1, 2, -3, 1) \rightsquigarrow (1, 0, 0, 0)$$

$$\text{rank}(A) = 1, \dim(K) = 4 - 1 = 3$$

$$x_1 = -2x_2 + 3x_3 - 4x_4$$

Note that $\{v_1, v_2, v_3\}$ is linearly independent vectors in K

$$\left\{ \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 3 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\} : \text{a basis for } K$$

$$(f) A = \begin{pmatrix} 1 & 2 \\ 1 & -1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\text{rank}(A) = 2, \dim(K) = 2 - 2 = 0$$

$$\left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\} : \text{a basis for } K$$

(So the given system is inconsistent)

$$(g) A = \begin{pmatrix} 1 & 2 & 1 & 1 \\ 0 & 1 & -1 & 1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\text{rank}(A) = 2, \dim(K) = 4 - 2 = 2$$

$$\left\{ \begin{pmatrix} -3 \\ 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\} : \text{a basis for } K$$

3.

$$(a) A = \left\{ \begin{pmatrix} 5 \\ 0 \end{pmatrix} + t \begin{pmatrix} -3 \\ 1 \end{pmatrix} \mid t \in R \right\}$$

$$(b) A = \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \mid t \in R \right\}$$

$$(c) A = \left\{ \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ 1 \\ 1 \end{pmatrix} \mid t \in R \right\}$$

$$(d) A = \left\{ \begin{pmatrix} 2 \\ 0 \\ -1 \end{pmatrix} + t \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \mid t \in R \right\}$$

$$(e) A = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + r \begin{pmatrix} -2 \\ -1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} 3 \\ 0 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \mid r, s, t \in R \right\}$$

$$(f) A = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$$

$$(g) \ A = \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} + r \begin{pmatrix} -3 \\ 1 \\ 1 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ -1 \\ 0 \\ 1 \end{pmatrix} \mid r, s \in R \right\}$$

4.

(a)

$$(1) \ A^{-1} = \begin{pmatrix} -5 & 3 \\ 2 & -1 \end{pmatrix}$$

$$(2) \ x = A^{-1} \begin{pmatrix} 4 \\ 3 \end{pmatrix} = \begin{pmatrix} -11 \\ 5 \end{pmatrix}$$

(b)

$$(1) \ A^{-1} = \begin{pmatrix} \frac{1}{3} & 0 & \frac{1}{3} \\ \frac{1}{9} & \frac{1}{3} & -\frac{2}{9} \\ -\frac{4}{9} & \frac{2}{3} & -\frac{1}{9} \end{pmatrix}$$

$$(2) \ x = A^{-1} \begin{pmatrix} 5 \\ 1 \\ 4 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ -2 \end{pmatrix}$$

5.

$AX = B$, $A = (a_1, \dots, a_n) \in M_{n \times n}$, a_i is the n th column of A

If a_i is expressed by other column vectors of A , i.e. a_i 's are linearly independent,

then the given system has infinitely many solutions

(Example) $A = (a_1, \dots, a_i, \dots, ka_i, \dots, a_n)$, $a_j = ka_i$, $k \in F$

6.

$$T^{-1}(\{(1, 11)\}) = \left\{ \begin{pmatrix} \frac{11}{2} \\ -\frac{9}{2} \\ 0 \end{pmatrix} + t \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \mid t \in R \right\}$$

7. The systems in parts (b), (c), and (d) have solutions

(a) $\text{rank}(A) = 2, \text{rank}(A|b) = 3$

$$A \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, (A|b) \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

(b) $\text{rank}(A) = \text{rank}(A|b) = 2$

(c) $\text{rank}(A) = \text{rank}(A|b) = 3$

(d) $\text{rank}(A) = \text{rank}(A|b) = 4$

(e) $\text{rank}(A) = 2, \text{rank}(A|b) = 3$

8.

(a) $v \in R(T) \quad T(-2, 3, 0) = (1, 3, 2)$

(b) $v \in R(T) \quad T(1, 1, 0) = (2, 1, 1)$

9.

$$L_A : F^n \rightarrow F^m, \quad A = (a_1, \dots, a_n)$$

Let $x = (x_1, \dots, x_n)^t$ is a solution to $Ax = b$

$$\Leftrightarrow b = Ax = a_1x_1 + \dots + a_nx_n, \quad x_i \in F$$

$$\Leftrightarrow b \in \text{span}(a_1, \dots, a_n) = R(L_A)$$

11.

$$Ap = p \rightsquigarrow p = \begin{pmatrix} 1 \\ 0.75 \\ 1 \end{pmatrix}$$

The farmer, tailor, and carpenter must have incomes in the proportions 4:3:4

3.3.

12.

$$0.60p_1 + 0.30p_2 = p_1$$

$$0.40p_1 - 0.30p_2 = 0$$

$$\therefore p = \begin{pmatrix} 0.75 \\ 1 \end{pmatrix}$$

13.

There must be 7.8 units of the first commodity and 9.5 units of the second

$$x = (I - A^{-1})d = \begin{pmatrix} 7.8 \\ 9.5 \end{pmatrix}$$

3.4. Systems of Linear equations - Computational aspects

1.

- (a) F (a finite row operations)
- (b) T (P.182 Corollary)
- (c) T (P.158 Corollary 1 to Theorem 3.6)
- (d) T (p.187 Theorem 3.14)
- (e) F

The system has a solution if and if only the echelon form of the augmented matrix M does not have a row of the form $(0, \dots, 0, b)$ with $b \neq 0$

(f) T

$$\text{rank}(A) = \text{rank}(A \mid b) \Leftrightarrow (A \mid b) \text{ is consistent}$$

If the system $(A \mid b)$ is consistent and $\text{rank}(A) = r$, then the dimension of the solution set is $n - r$.

(g) T

Since A is row equivalent to A' i.e. $A' = EA$ $\text{rank}(A) = \text{rank}(EA') = \text{rank}(A')$

2.

- (a) $\left\{ \begin{pmatrix} 4 \\ -3 \\ 1 \end{pmatrix} \right\}$
- (b) $\left\{ \begin{pmatrix} 9 \\ 4 \\ 0 \end{pmatrix} + r \begin{pmatrix} -5 \\ -3 \\ 1 \end{pmatrix} \mid r \in R \right\}$

$$\begin{aligned}
\text{(c)} & \left\{ \begin{pmatrix} 2 \\ 3 \\ -2 \\ 1 \end{pmatrix} \right\} \\
\text{(d)} & \left\{ \begin{pmatrix} 13 \\ 22 \\ -\frac{1}{26} \\ \frac{18}{13} \end{pmatrix} + r \begin{pmatrix} 9 \\ -15 \\ 0 \\ 1 \end{pmatrix} \mid r \in R \right\} \\
\text{(e)} & \left\{ \begin{pmatrix} 4 \\ 0 \\ 1 \\ 0 \end{pmatrix} + r \begin{pmatrix} 4 \\ 1 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} 1 \\ 0 \\ 2 \\ 1 \end{pmatrix} \mid r, s \in R \right\} \\
\text{(f)} & \left\{ \begin{pmatrix} -3 \\ 3 \\ 1 \\ 0 \end{pmatrix} + r \begin{pmatrix} 1 \\ -2 \\ 0 \\ 1 \end{pmatrix} \mid r \in R \right\} \\
\text{(g)} & \left\{ \begin{pmatrix} -23 \\ 0 \\ 7 \\ 9 \\ 0 \end{pmatrix} + r \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + s \begin{pmatrix} -23 \\ 0 \\ 6 \\ 9 \\ 1 \end{pmatrix} \mid r, s \in R \right\}
\end{aligned}$$

3.

(a)

(\Leftarrow) If $(A' \mid b')$ has such a row, say k -th row, then

the corresponding k -th equation in the system $A'x = b'$ is

$$0x_1 + 0x_2 + \cdots + 0x_n = c_k, \quad c_k \neq 0;$$

which has no solutions *i.e.* $A'x = b'$ is inconsistent

$$\therefore \text{rank}(A') \neq \text{rank}(A' \mid b')$$

(\Rightarrow) Assume that $(A' \mid b')$ has no such a row, then $b' \in R(L_{A'})$

$$\therefore \text{rank}(A') = \text{rank}(A' \mid b')$$

(b)

If two matrices are row equivalent, they have the same solution set

Since $(A' \mid b')$ is equivalent to $(A \mid b)$, so

$Ax = b$ is consistent

$\Leftrightarrow A'x = b'$ is consistent

$\Leftrightarrow \text{rank}(A') = \text{rank}(A' \mid b')$

By (a), $(A' \mid b')$ has no such a row

(cf) (a) $(\Rightarrow) b' \in R(L_{A'})$ (\because Theorem 3.16(b))

4.

(a)

$$\left(\begin{array}{cccc|c} 1 & 0 & 0 & -1/2 & 4/3 \\ 0 & 1 & 0 & 1/2 & 1/3 \\ 0 & 0 & 1 & -1/2 & 0 \end{array} \right)$$

Since $(A' \mid b')$ contains no row in which the only nonzero entry lies in the last

column, therefore $Ax = b$ is consistent

$$\left\{ \begin{pmatrix} 4/3 \\ 1/3 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 1/2 \\ -1/2 \\ 1/ \\ 1 \end{pmatrix} r \mid r \in R \right\} : \text{the solution set}$$

$$\left\{ \begin{pmatrix} 1/2 \\ -1/2 \\ 1/2 \\ 1 \end{pmatrix} \right\} : \text{a basis for the solution set}$$

(b)

$$\left(\begin{array}{cccc|c} 1 & 1 & 0 & -1/2 & 1 \\ 0 & 0 & 1 & -1/2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

Since $\text{rank}(A') = \text{rank}(A' | b')$, $Ax = b$ is consistent

$$\left\{ \left(\begin{array}{c} 1 \\ 0 \\ 1 \\ 0 \end{array} \right) + \left(\begin{array}{c} -1 \\ 1 \\ 0 \\ 0 \end{array} \right) r + \left(\begin{array}{c} 1/2 \\ 0 \\ 1/2 \\ 1 \end{array} \right) s \mid r, s \in R \right\} : \text{the solution set}$$

$$\left\{ \left(\begin{array}{c} -1 \\ 1 \\ 0 \\ 0 \end{array} \right), \left(\begin{array}{c} 1/2 \\ 0 \\ 1/2 \\ 1 \end{array} \right) \right\} : \text{a basis for the solution set}$$

(c)

$$\left(\begin{array}{cccc|c} 1 & 1 & 0 & -1/2 & 7/4 \\ 0 & 0 & 1 & -1/2 & 1/4 \\ 0 & 0 & 0 & 0 & -3/4 \end{array} \right)$$

Since $\text{rank}(A') \neq \text{rank}(A' | b')$, $Ax = b$ is inconsistent

5.

$$B = \begin{pmatrix} 1 & 0 & 2 & 0 & -2 \\ 0 & 1 & -5 & 0 & -3 \\ 0 & 0 & 0 & 1 & 6 \end{pmatrix}$$

Let $A = (a_1, a_2, \dots, a_5)$ and $B = (b_1, b_2, \dots, b_5)$

Since $b_3 = 2e_1 - 5e_2$, it follows that $a_3 = 2a_1 - 5a_2$

Moreover $b_5 = -2e_1 - 3e_2 + 6e_3$, the same result shows that $a_5 = -2a_1 - 3a_2 + 6a_4$

$$\therefore A = \begin{pmatrix} 1 & 0 & 2 & 1 & 4 \\ -1 & -1 & 3 & -2 & -7 \\ 3 & 1 & 1 & 0 & -9 \end{pmatrix}$$

6.

3.4.

$$B = \begin{pmatrix} 1 & -3 & 0 & 4 & 0 & 5 \\ 0 & 0 & 1 & 3 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Let $A = (a_1, a_2, \dots, a_6)$ and $B = (b_1, b_2, \dots, b_6)$

Since $b_2 = -3e_1$,

$$b_4 = 4e_1 + 3e_2,$$

$$b_6 = 5e_1 + 2e_2 - e_3$$

it follows that $a_2 = -3a_1$,

$$a_4 = 4a_1 + 3a_3,$$

$$\begin{aligned} a_6 &= 5a_1 + 2a_3 - a_5 \\ \therefore A &= \begin{pmatrix} 1 & -3 & -1 & 1 & 0 & 3 \\ -2 & 6 & 1 & -5 & 1 & -9 \\ -1 & 3 & 2 & 2 & -3 & 2 \\ 3 & -9 & -4 & 0 & 2 & 5 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} 7. \quad & \begin{pmatrix} 2 & 1 & -8 & 1 & -3 \\ -3 & 4 & 12 & 37 & -5 \\ 1 & -2 & -4 & -17 & 8 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & -4 & -4 & 0 \\ 0 & 1 & 0 & 7 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \\ & \therefore \{u_1, u_2, u_5\} \text{ is a basis for } W \end{aligned}$$

$$\begin{aligned} 9. \quad & \begin{pmatrix} 0 & -1 & -1 & 1 \\ 1 & 2 & 2 & 3 \\ 2 & 1 & 1 & 9 \\ 1 & -2 & -2 & 4 \\ -1 & 2 & 2 & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

$$\left\{ \begin{pmatrix} 0 & -1 \\ -1 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix}, \begin{pmatrix} 2 & 1 \\ 1 & 9 \end{pmatrix} \right\} : \text{a basis for } W$$

$$\begin{array}{l} \text{(cf)} \\ \begin{pmatrix} 0 & \cdots & -1 \\ -1 & \cdots & 2 \\ -1 & \cdots & 2 \\ 1 & \cdots & -1 \end{pmatrix} \\ \text{(a) (i) } S \subseteq V \end{array}$$

$$\text{(ii) } S : \text{linearly independent } A \rightsquigarrow \begin{pmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\{u_1, u_2, \dots, u_5\}$$

10.

(a) It's a singleton set, so it's linearly independent

(b)

Since $x_1 = 2x_2 - 3x_3 + x_4 - 2x_5$, assign parametric values to x_2, x_3, x_4 and x_5

Let $x_2 = t_1, x_3 = t_2, x_4 = t_3$ and $x_5 = t_4$, then the vectors in V have the form

$$(x_1, x_2, \dots, x_5) = t_1(2, 1, 0, 0, 0) + t_2(-3, 0, 1, 0, 0) + t_3(1, 0, 0, 1, 0) + t_4(-2, 0, 0, 0, 1)$$

Hence

$\beta = \{(2, 1, 0, 0, 0), (-3, 0, 1, 0, 0), (1, 0, 0, 1, 0), (-2, 0, 0, 0, 1)\}$ is a basis for V

The matrix whose columns consist of the vectors in S followed by those β is

$$\begin{pmatrix} 0 & 2 & -3 & 1 & -2 \\ 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

and its reduced row echelon form is $\begin{pmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & -1 & 0 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$

Thus $\{(0, 1, 1, 1, 0), (2, 1, 0, 0, 0), (-3, 0, 1, 0, 0), (-2, 0, 0, 0, 1)\}$ is a basis for V containing S

11.

(a) It's a singleton set, so it's clear

(b)

The matrix whose columns consist of the vectors in S followed by those β is

$$\begin{pmatrix} 1 & 2 & -3 & 1 & -2 \\ 2 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

and its reduced row echelon form is $\begin{pmatrix} 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -2 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$

Thus $\{(1, 2, 1, 0, 0), (2, 1, 0, 0, 0), (1, 0, 0, 1, 0), (-2, 0, 0, 0, 1)\}$ is a basis for V containing S

12.

(a) If $a(0, -1, 0, 1, 1, 0) + b(1, 0, 1, 1, 1, 0) = (0, \dots, 0)$. $a, b \in F$ then $a = b = 0$ $\therefore S$ is linearly independent

(b)

Since $x_1 = x_3 - x_4 + x_5 - 3x_6$ $x_2 = x_3 + x_4 - 2x_5 - 2x_6$

Let $x_3 = t_1, x_4 = t_2, x_5 = t_3$ and $x_6 = t_4$, then the vectors in V have the form

$$(x_1, x_2, \dots, x_6) = t_1(1, 1, 1, 0, 0, 0) + t_2(-1, 1, 0, 1, 0, 0) + t_3(1, -2, 0, 0, 1, 0) + t_4(-3, -2, 0, 0, 0, 1)$$

Hence

 $\beta = \{(2, 1, 0, 0, 0), (-3, 0, 1, 0, 0), (1, 0, 0, 1, 0), (-2, 0, 0, 0, 1)\}$ is a basis for V The matrix whose columns consist of the vectors in S followed by those β is

$$\begin{pmatrix} 0 & 1 & 1 & -1 & 1 & -3 \\ -1 & 0 & 1 & 1 & -2 & -2 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

and its reduced row echelon form is
$$\begin{pmatrix} 1 & 0 & -1 & 0 & -1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Thus $\{(0, -1, 0, 1, 1, 0), (1, 0, 1, 1, 1, 0), (-1, 1, 0, 1, 0, 0), (-3, -2, 0, 0, 0, 1)\}$ is a basis for V containing S

13.

(a) If $a(1, 0, 1, 1, 1, 0) + b(0, 2, 1, 1, 0, 0) = (0, \dots, 0)$. $a, b \in F$

then $a = b = 0$

$\therefore S$ is linearly independent

(b)

The matrix whose columns consist of the vectors in S followed by those β is

$$\begin{pmatrix} 1 & 0 & 1 & -1 & 1 & -3 \\ 0 & 2 & 1 & 1 & -2 & -2 \\ 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

and its reduced row echelon form is
$$\begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Thus $\{(1, 0, 1, 1, 1, 0), (0, 2, 1, 1, 0, 0), (1, 1, 1, 0, 0, 0), (-3, -2, 0, 0, 0, 1)\}$ is a basis for V containing S

15.

Let B is a reduced row echelon form to A , then A is row equivalent to B ,

i.e. $A \sim B$

If C is an another reduced row echelon form to A , then $C \sim A \sim B$

Since row equivalent matrices have the same row space and they are finite dimensional, so must be identical

(cf) If C is an another reduced row echelon form to A , then $C \sim A \sim B$

Since $\exists E$ s.t. $C = EB$ and E is invertible, we have $E^{-1}C = B$,

Comparing with their rank,

the row space C and B are the subspace of each other

So $C = B$

§4. Determinants

4.1. Determinants of Order 2

1. (a) F $\det(A + B) \neq \det(A) + \det(B)$

(b) T (p.200. Theorem 4.1)

(c) F (p.201. Theorem 4.2)

(d) F

The area of the parallelogram determined by u and v equals $O \begin{pmatrix} u \\ v \end{pmatrix} \det \begin{pmatrix} u \\ v \end{pmatrix}$

(e) F (p.203)

2. (a) 30

(b) -17

(c) -8

3. (a) $-10+15i$

(b) $36+41i$

(c) -24

4. (a) 4

(b) 10

(c) 14

(d) 26

5.

Let $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$, then $B = \begin{pmatrix} a_{21} & a_{22} \\ a_{11} & a_{12} \end{pmatrix}$

So $\det(B) = a_{12}a_{21} - a_{11}a_{22} = -(a_{11}a_{22} - a_{12}a_{21}) = -\det(A)$

6.

Let $A = \begin{pmatrix} a & a \\ b & b \end{pmatrix}$, and $B = \begin{pmatrix} b & b \\ a & a \end{pmatrix}$

By the exercise 15, $\det(B) = -\det(A)$

Since $\det(A) = \det(B)$

$\therefore \det(A) = 0$

7.

Let $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$, then $A^t = \begin{pmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{pmatrix}$

$\det(A^t) = a_{11}a_{22} - a_{21}a_{12} = \det(A)$

$\therefore \det(A^t) = \det(A)$

8.

If $A = \begin{pmatrix} a_{11} & a_{12} \\ 0 & a_{22} \end{pmatrix}$, then $\det(A) = a_{11}a_{22}$: the product of the diagonal entries of A

9.

Let $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$ and $B = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}$

$$\begin{aligned}
\text{then } AB &= \begin{pmatrix} a_{11}b_{11} + a_{12}b_{21} & a_{11}b_{12} + a_{12}b_{22} \\ a_{21}b_{11} + a_{22}b_{21} & a_{21}b_{12} + a_{22}b_{22} \end{pmatrix} \\
\det(AB) &= (a_{11}b_{11} + a_{12}b_{21})(a_{21}b_{12} + a_{22}b_{22}) - (a_{11}b_{12} + a_{12}b_{22})(a_{21}b_{11} + a_{22}b_{21}) \\
&= (a_{11}a_{22} - a_{12}a_{21})(b_{11}b_{22} - b_{12}b_{21}) \\
&= \det(A) \det(B)
\end{aligned}$$

10.

$$C = \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix}$$

$$(a) \quad CA = AC = (\det A)I = \begin{pmatrix} a_{11}a_{22} - a_{12}a_{21} & 0 \\ 0 & a_{11}a_{22} - a_{12}a_{21} \end{pmatrix}$$

$$(b) \quad \det(C) = a_{22}a_{11} - a_{12}a_{21} = \det(A)$$

$$(c) \quad \text{The classical adjoint of } A^t = \begin{pmatrix} a_{22} & -a_{21} \\ -a_{12} & a_{11} \end{pmatrix} = C^t$$

$$(d) \quad \text{If } A \text{ is invertible, then } \det(A) \neq 0$$

$$\text{by (a), } A\left\{\left(\frac{1}{\det(A)}\right)C\right\} = \left\{\left(\frac{1}{\det(A)}\right)C\right\}A = I$$

$$\therefore A^{-1} = \left(\frac{1}{\det(A)}\right)C$$

11.

Let $A \in M_{2 \times 2}(F)$ (1) If A has *rank* less than 2, then by the assumption (ii) $\delta(A) = 0$ In this case $\det(A)$ equals to zero

$$\therefore \delta(A) = \det(A)$$

(2) If A has *rank* 2, then A is invertible

hence $A = E_k E_{k-1} \cdots E_1$ for some k

Since $\delta(I) = 1, \delta(E) = \det(E), \forall E$: an elementary matrix

Hence we have $\delta(A) = \delta(E_k E_{k-1} \cdots E_1)$

$$= \delta(E_k) \delta(E_{k-1}) \cdots \delta(E_1)$$

$$= \det(E_k) \det(E_{k-1}) \cdots \det(E_1)$$

$$= \det(E_k E_{k-1} \cdots E_1)$$

$$= \det(A)$$

12.

(\Leftarrow) Let $u = (a_1, a_2)$, then $v = (a_1 \cos \theta - a_2 \sin \theta, a_1 \sin \theta + a_2 \cos \theta)$, $0 < \theta < \pi$

Since $\det \begin{pmatrix} u \\ v \end{pmatrix} = (a_1^2 + a_2^2) \sin \theta$ and $\det \begin{pmatrix} u \\ v \end{pmatrix} > 0$

$\therefore O \begin{pmatrix} u \\ v \end{pmatrix} = 1$ (\Rightarrow) Since $O \begin{pmatrix} u \\ v \end{pmatrix} = 1$, $\sin \theta > 0$

$\therefore 0 < \theta < \pi$

$\therefore \{u, v\}$ forms a right-handed coordinate system

4.2. Determinants of Order n

1.

(a) F

(b) T (Theorem 4.4)

(c) T (Corollary to Theorem 4.4)

(d) T (Theorem 4.5)

(e) F ($\det(B) = k \det(A)$)

(f) F ($\det(B) = \det(A)$)

(g) F (If $A \in M_{n \times n}(F)$ and $\text{rank } A = n \Rightarrow A : \text{invertible} \Rightarrow \det A \neq 0$)

(h) T

2. $k = 3^3$

3. $k = 42$

4. $k = 2$

5. $\det(A) = -12$

6. $\det(A) = -13$

7. $\det(A) = -12$

8. $\det(A) = -13$

9. $\det(A) = 22$

10. $\det(A) = 4 + 2i$

11. $\det(A) = -3$

12. $\det(A) = 154$

13. $\det(A) = -8$

14. $\det(A) = -168$

15. $\det(A) = 0$

16. $\det(A) = 36$

17. $\det(A) = -49$

$$18. \det(A) = 10$$

$$19. \det(A) = -28 - i$$

$$20. \det(A) = 17 - 3i$$

$$21. \det(A) = 95$$

$$22. \det(A) = 100$$

23.

$$\text{Let } A = \begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ & a_{22} & \cdots & a_{2n} \\ & & \ddots & \vdots \\ & & & a_{nn} \end{pmatrix}$$

By expanding along the first column, we have

$$\det A = a_{11} \det \begin{pmatrix} a_{22} & a_{23} & \cdots & a_{2n} \\ & a_{33} & \cdots & a_{3n} \\ & & \ddots & \vdots \\ & & & a_{nn} \end{pmatrix}$$

$$= a_{11} a_{22} \det \begin{pmatrix} a_{33} & a_{34} & \cdots & a_{3n} \\ & a_{44} & \cdots & a_{4n} \\ & & \ddots & \vdots \\ & & & a_{nn} \end{pmatrix}$$

\vdots

$$= a_{11} a_{22} \cdots a_{nn}$$

24.

If A has a row consisting entirely of zeros, then $\det(A) = 0$

Let i - th row of A is the zero row

Since $\det(A) = \sum_{j=1}^n (-1)^{i+j} A_{ij} \det(\tilde{A}_{ij})$ and $\forall A_{ij} = 0, (j = 1, 2, \dots, n)$

$\therefore \det(A) = 0$

25.

Let $A = (a_1, a_2, \dots, a_n)$, a_i : rows of A , $i = 1, 2, \dots, n$

If A' is obtained by multiplying a row of A by a nonzero scalar k ,

then $\det(A') = k \det(A)$

$\det(kA) = \det(ka_1, ka_2, \dots, ka_n)$

$= k \det(a_1, ka_2, \dots, ka_n)$

$= k^2 \det(a_1, a_2, ka_3, \dots, a_n)$

\vdots

$= k^n \det(a_1, a_2, \dots, a_n)$

$= k^n \det(A)$

26.

Since $\det(-A) = \det(-I_n A) = \det(-I_n) \det(A) = (-1)^n \det(A)$

$\therefore \det(-A) = \det(A), n = 2k, k \in N$

27.

Let $A = (a_1, \dots, a_i, \dots, a_j, \dots, a_n)$ and $B = (a_1, \dots, a_j, \dots, a_i, \dots, a_n)$

(a_i : columns of A and $a_i = a_j$)

By the row-interchanging property, we have $\det(B) = -\det(A)$

Since $a_i = a_j$, $\det(B) = \det(A)$

$\therefore \det(A) = 0$

28.

(i) E_1 is of type 1

$$\det(E_1) = -\det(I_n) = -1$$

(ii) E_2 is of type 2

$$\det(E_2) = k \det(I_n) = k$$

(iii) E_3 is of type 1

$$\det(E_3) = \det(I_n) = 1$$

29.

(i) E_1 is of type 1

$$\det(E_1) = \det(E_1^t) = -1$$

(ii) E_2 is of type 2

$$\det(E_2) = \det(E_2^t) = k$$

(iii) E_3 is of type 1

$$\det(E_3) = \det(E_3^t) = 1$$

30.

$$\begin{aligned}
\det(B) &= \det(a_n, a_{n-1}, \dots, a_2, a_1) \\
&= (-1) \det(a_1, a_{n-1}, \dots, a_2, a_n) \\
&= (-1)^2 \det(a_1, a_2, a_{n-2}, \dots, a_3, a_{n-1}, a_n) \\
&\vdots \\
&= (-1)^{[n/2]} \det(a_1, a_2, \dots, a_n) \\
&= (-1)^{[n/2]} \det(A)
\end{aligned}$$

4.3. Properties of Determinants

1.

(a) F (p.223)

(b) T (Theorem 4.7 p. 223)

(c) F

(d) T

(e) F (Theorem 4.8 p. 224)

(f) T

(g) F

(h) F

2.

(a) $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$ and $b = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$

Since $\det(A) = a_{11}a_{22} - a_{12}a_{21} \neq 0$, Cramer's rule applies

Using the notation of theorem 4.9, we have

$$x_1 = \det(M_1) / \det(A) = (b_1a_{22} - a_{12}b_2) / (a_{11}a_{22} - a_{12}a_{21})$$

$$x_2 = \det(M_2) / \det(A) = (b_2a_{11} - a_{21}b_1) / (a_{11}a_{22} - a_{12}a_{21})$$

$$\therefore x = (x_1, x_2)$$

$$= ((b_1a_{22} - a_{12}b_2) / (a_{11}a_{22} - a_{12}a_{21}), (b_2a_{11} - a_{21}b_1) / (a_{11}a_{22} - a_{12}a_{21}))$$

3.

4.3.

$$\begin{aligned}
 A &= \begin{pmatrix} 2 & 1 & -3 \\ 1 & -2 & 1 \\ 3 & 4 & -2 \end{pmatrix}, \quad b = \begin{pmatrix} 5 \\ 10 \\ 0 \end{pmatrix}, \quad \det(A) = -25 \\
 \det(M_1) &= \det \begin{pmatrix} 5 & 1 & -3 \\ 10 & -2 & 1 \\ 0 & 4 & -2 \end{pmatrix}, \quad \det(M_2) = \det \begin{pmatrix} 2 & 5 & -3 \\ 1 & 10 & 1 \\ 3 & 0 & -2 \end{pmatrix}, \quad \det(M_3) = \\
 &\det \begin{pmatrix} 2 & 1 & 5 \\ 1 & -2 & 10 \\ 3 & 4 & 0 \end{pmatrix} \\
 x_1 &= \det(M_1) / \det(A) = -100 / -25 = 4 \\
 x_2 &= \det(M_2) / \det(A) = 75 / -25 = -3 \\
 x_3 &= \det(M_3) / \det(A) = 0 / -25 = 0 \\
 \therefore x &= (4, -3, 0)
 \end{aligned}$$

5. $(4, -3, 0)$

7. $(0, -12, 16)$

8.

Since $\det(A^t) = \det(A)$,

$$\text{from the theorem 4.3, } \det \begin{pmatrix} a_1 \\ \vdots \\ a_{r-1} \\ u + kv \\ a_{r+1} \\ \vdots \\ a_n \end{pmatrix}^t = \det \begin{pmatrix} a_1 \\ \vdots \\ a_{r-1} \\ u \\ a_{r+1} \\ \vdots \\ a_n \end{pmatrix}^t + k \det \begin{pmatrix} a_1 \\ \vdots \\ a_{r-1} \\ v \\ a_{r+1} \\ \vdots \\ a_n \end{pmatrix}^t$$

that is,

$$\begin{aligned} & \det(a_1, \dots, a_{r-1}, u + kv, a_{r+1}, \dots, a_n) \\ &= \det(a_1, \dots, a_{r-1}, u, a_{r+1}, \dots, a_n) + k \det(a_1, \dots, a_{r-1}, v, a_{r+1}, \dots, a_n) \\ & , u, v, a'_i s : \text{column vectors in } F^n \end{aligned}$$

9.

(\Rightarrow) Since the determinant of an upper triangular matrix is the product of its diagonal entries

So A is invertible, $\det(A) \neq 0$

thus its diagonal entries are nonzero

(\Leftarrow) By hypothesis, $\det(A) \neq 0$

By the corollary to the theorem 4.7, A is invertible

10.

$$\det(M^k) = \det(0) = 0$$

$$\det(M^k) = \det(M \cdots M) = \det(M)^k = 0$$

$$\therefore \det(M) = 0$$

11.

(i) n is odd

$$\det(M^t) = (-1)^n \det(M) = -\det(M)$$

$$\text{Since } \det(M^t) = \det(M), \quad \det(M) = -\det(M)$$

$$\therefore \det(M) = 0$$

(ii) n is even

$$\det(M^t) = (-1)^n \det(M) = \det(M)$$

12.

$$\det(QQ^t) = \det(Q) \det(Q^t) = 1$$

$$\text{Since } \det(Q^t) = \det(Q), \quad \det(Q) = \pm 1$$

13.

$$(a) \det(\overline{M}) = \overline{\det(M)}$$

Let $M = A + iB$, then

$$\det(\overline{M}) = \det(A - iB) = \det(A) - i \det(B) = \overline{\det(M)}$$

(b)

$$\text{Since } Q \text{ is unitary, } \det(QQ^*) = \det(I) = 1$$

$$1 = \det(Q) \det(Q^*)$$

$$= \det(Q) \det(Q^*)$$

$$= \det(Q) \det(\overline{Q^t})$$

$$= \det(Q) \overline{\det(Q^t)}$$

$$= \det(Q) \overline{\det(Q)}$$

$$= |\det(Q)|$$

14.

(\Leftarrow) Since $\det(B) \neq 0$, $\text{rank}(B) = n$

Let B' be the reduced row echelon form of B ,

then $\text{rank}(B') = n$

Moreover $B' = I_n$

By the theorem 3.16, b_i 's consist of a basis for F^n , $i = 1, \dots, n$

(\Rightarrow) Since β is a basis, $B = I_n$

$\therefore \det B = 1 \neq 0$

15.

If A, B are similar, then

$\exists Q \in M_{n \times n}(F) : \text{invertible s.t. } A = Q^{-1}BQ$

$\therefore \det(A) = \det(Q^{-1}BQ)$

$= \det(Q^{-1}) \det(B) \det(Q)$

$= \det(Q)^{-1} \det(B) \det(Q)$

$= \det(B)$

16.

Suppose that $\det(A)$ is not invertible

then $\det(A) = 0$

Since $1 = \det(AB) = \det(A) \det(B) = 0$

It's a contradiction

17.

Since n is odd, $\det(-B) = (-1)^n \det(B) = -\det(B)$

Let $AB = -BA$

then $\det(A) \det(B) = \det(-B) \det(A) = -\det(B) \det(A)$

$\therefore 2 \det(B) = 0$

Since $\text{char}(F) \neq 2$, $\det(B) = 0$

$\therefore B$ is not invertible

18.

(i) If A is of type 2, then $\det(A) = k$

Since AB is a matrix obtained by multiple of some row of B by the nonzero scalar k ,

$$\det(AB) = k \det(B) = \det(A) \det(B)$$

(ii) If A is of type 3, then $\det(A) = 1$

Since AB is a matrix obtained by adding a multiple of some row of B to another row,

$$\det(AB) = \det(B) = \det(A) \det(B)$$

19.

Let $A = (a_{ij})$ be an (2×2) lower triangular matrix, then $\det(A) = a_{11}a_{22}$

Proceeding inductively, suppose that this assertion is true for any $(k \times k)$ lower triangular matrix, then

4.3.

$$\det(A) = \begin{vmatrix} a_{11} & 0 & 0 & \\ a_{21} & a_{22} & 0 & 0 \\ \vdots & \ddots & & \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix} = a_{11}A', \text{ where } A' = \begin{vmatrix} a_{22} & 0 & 0 & \\ a_{32} & a_{33} & 0 & 0 \\ \vdots & \ddots & & \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{vmatrix}$$

Since $\det(A') = a_{22}a_{33} \cdots a_{nn}$, so $\det(A) = a_{11}a_{22} \cdots a_{nn}$

20.

Reduce C to upper triangular form with elementary column operations

21.

Reduce C to upper triangular form with elementary row operations

then gain reduce A to upper triangular form with elementary column operations

22.

$$(a) [T]_{\beta}^{\gamma} = \begin{pmatrix} 1 & c_0 & c_0^2 & \cdots & c_0^n \\ 1 & c_1 & c_1^2 & \cdots & c_1^n \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & c_n & c_n^2 & \cdots & c_n^n \end{pmatrix}, f = \begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{pmatrix}$$

(b) By the exercise 22 in section 2.4, T is an isomorphism

so $M = [T]_{\beta}^{\gamma}$ is invertible

Thus $\det(M) \neq 0$

(c)

Proceed the following column operations ;

$$-C_1 \times c_0 + C_2 \Rightarrow C_2$$

$$-C_2 \times c_0 + C_3 \Rightarrow C_3$$

$$\vdots$$

$$-C_n \times c_0 + C_{n+1} \Rightarrow C_{n+1}$$

then we have

$$\begin{aligned}
& \begin{vmatrix} 1 & 0 & 0 & \cdots & 0 \\ 1 & (c_1 - c_0) & c_1(c_1 - c_0) & \cdots & c_1^{n-1}(c_1 - c_0) \\ 1 & (c_2 - c_0) & c_2(c_2 - c_0) & \cdots & c_2^{n-1}(c_2 - c_0) \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & (c_n - c_0) & c_n(c_n - c_0) & \cdots & c_n^{n-1}(c_n - c_0) \end{vmatrix} \\
&= (c_1 - c_0)(c_2 - c_0) \cdots (c_n - c_0) \begin{vmatrix} 1 & c_1 & c_1^2 & \cdots & c_1^{n-1} \\ 1 & c_2 & c_2^2 & \cdots & c_2^{n-1} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & c_n & c_n^2 & \cdots & c_n^{n-1} \end{vmatrix} \\
&= (c_1 - c_0)(c_2 - c_0) \cdots (c_n - c_0) \begin{vmatrix} 1 & 0 & 0 & \cdots & 0 \\ 1 & (c_2 - c_1) & c_2(c_2 - c_1) & \cdots & c_2^{n-2}(c_2 - c_1) \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & (c_n - c_1) & c_n(c_n - c_1) & \cdots & c_n^{n-2}(c_n - c_1) \end{vmatrix} \\
&= (c_1 - c_0) \cdots (c_n - c_0)(c_2 - c_1) \cdots (c_n - c_1) \begin{vmatrix} 1 & c_2 & c_2^2 & \cdots & c_2^{n-2} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & c_n & c_n^2 & \cdots & c_n^{n-2} \end{vmatrix} \\
&= \cdots \\
&= \prod_{0 \leq i < j \leq n} (c_j - c_i)
\end{aligned}$$

23.

a)

So k is the largest number of linearly independent columns of A

thus $\text{rank} A(A) = k$

(b)

Since $\text{rank}(A) = k$, there exists $\{a_1, a_2, \dots, a_k\}$ a linearly independent set of columns of A

So A can be written as

$$\begin{pmatrix} a_{11} & \cdots & a_{1k} & 0 & \cdots & 0 \\ \vdots & & \vdots & \vdots & & \vdots \\ a_{n1} & \cdots & a_{nk} & 0 & \cdots & 0 \end{pmatrix}$$

Since $\dim(\text{row space } A) = \dim(\text{column space of } A)$

Therefore

$$A = \begin{pmatrix} a_{11} & \cdots & a_{1k} & & \\ \vdots & & \vdots & O & \\ a_{k1} & \cdots & a_{kk} & & \\ & O & & O & \end{pmatrix}$$

and $\det(A) \neq 0$

24.

$$A + tI = \begin{pmatrix} t & 0 & 0 & \cdots & 0 & a_0 \\ -1 & t & 0 & \cdots & 0 & a_1 \\ 0 & -1 & t & \cdots & 0 & a_2 \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & t & a_{n+2} \\ 0 & 0 & 0 & \cdots & -1 & t + a_{n-1} \end{pmatrix}$$

Let A be a (2×2) matrix, *i.e.* $n = 2$

by cofactor expansion along the first column,

$$\det(A + tI) = \begin{vmatrix} t & a_0 \\ -1 & t + a_1 \end{vmatrix} = t^2 + a_1t + a_0$$

Assume that this assertion holds for $(n - 1)$,

let $A \in M_{n \times n}(F)$

$$\begin{aligned}
 \det(A+tI) &= t \begin{vmatrix} t & 0 & \cdots & 0 & a_1 \\ -1 & t & \cdots & 0 & a_2 \\ \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & \cdots & t & a_{n-2} \\ 0 & 0 & \cdots & -1 & t+a_{n-1} \end{vmatrix} + \begin{vmatrix} 0 & 1 & 0 & \cdots & 0 & 0 \\ 0 & t & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & 0 \\ 0 & 0 & 0 & \cdots & t & 1 \\ a_0 & a_2 & a_3 & \cdots & a_{n-2} & t+a_{n-1} \end{vmatrix} \\
 &= t(t^{n-1} + a_{n-1}t^{n-2} + \cdots + a_2t + a_1) + a_0 \\
 &= t^n + a_{n-1}t^{n-1} + \cdots + a_2t^2 + a_1t + a_0
 \end{aligned}$$

25.

(a)

$$\begin{aligned}
 |B| &= \sum_{j=0}^n c_{jk} A_{jk} \\
 &= c_{1k} A_{1k} + c_{2k} A_{2k} + \cdots + c_{jk} + \cdots + c_{nk} A_{nk} \\
 &= c_{1k} 0 + c_{2k} 0 + \cdots + c_{jk} 1 + \cdots + c_{nk} 0 \\
 &= c_{jk}
 \end{aligned}$$

(b)

Apply Cramer's rule to $Ax = e_j$

we have $\det(M_i) = a_{ji}$ and $x_i = \det(M_i) / \det(A)$ $i = 1, \dots, n$

$$\text{Since } A \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = e_j, \text{ so } A \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix} = \det(A) e_j$$

(c)

By (b),

$$\begin{aligned}
 AC &= A(c_1, c_2, \dots, c_n) \\
 &= (Ac_1, Ac_2, \dots, Ac_n) \\
 &= (\det(A)e_1, \det(A)e_2, \dots, \det(A)e_n) \\
 &= \det(A)(e_1, e_2, \dots, e_n) \\
 &= \det(A)I
 \end{aligned}$$

(d)

Since $\det(B) = \det(r_1, \dots, e_i, \dots, r_n) = r_{ki}$

so $(r_{1i}, r_{2i}, \dots, r_{ni})A = \det(A)e_i$

$$\begin{aligned}
 \text{Let } CA &= (r_1, r_2, \dots, r_n)A \\
 &= (r_1A, r_2A, \dots, r_nA) \\
 &= (\det(A)e_1, \det(A)e_2, \dots, \det(A)e_n) \\
 &= \det(A)I
 \end{aligned}$$

If $\det(A) \neq 0$,

by (b), $AC = \det(A)I$

by the above proof, $CA = \det(A)I$

$$\therefore A^{-1} = \det(A)^{-1}C$$

(d)

$$A = ()_{n \times n}, \quad \det(\text{adj } A) = (\det A)^{n-1}$$

(proof) $A = 0$ or $\text{rank } A = n$ o.k.

$A \neq 0$, $\text{rank } A \neq n$

$$() \quad AX=0$$

$$= n - \text{rank} A \text{ eqn} - 1$$

$$\text{adj} A \quad AX = 0$$

$$\Rightarrow \text{adj} A$$

$$\Rightarrow \det(\text{adj} A) = 0 = (\det A)^{n-1}$$

In fact,

$$(1) \text{rank} A = n \Rightarrow \text{rank}(\text{adj} A) = n$$

$$(2) \text{rank} A = n - 1 \Rightarrow \text{rank}(\text{adj} A) = 1$$

$$(3) \text{rank} A \leq n - 2 \Rightarrow \text{rank}(\text{adj} A) = 0 \text{ i.e. } \text{adj} A = (0) : \text{zero matrix } (?)$$

$$\text{So } \text{rank} A - \text{rank}(\text{adj} A) \leq n - 2$$

26.

(a)

$$\begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \Rightarrow \begin{pmatrix} A_{22} & -A_{12} \\ -A_{21} & A_{11} \end{pmatrix}$$

(b)

$$\begin{pmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} \Rightarrow \begin{pmatrix} 16 & 0 & 0 \\ 0 & 16 & 0 \\ 0 & 0 & 16 \end{pmatrix}$$

(c)

$$\begin{pmatrix} -4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 5 \end{pmatrix} \Rightarrow \begin{pmatrix} 10 & 0 & 0 \\ 0 & -20 & 0 \\ 0 & 0 & -8 \end{pmatrix}$$

(d)

4.3.

$$\begin{aligned}
 & \begin{pmatrix} 3 & 6 & 7 \\ 0 & 4 & 8 \\ 0 & 0 & 5 \end{pmatrix} \Rightarrow \begin{pmatrix} 20 & -30 & 20 \\ 0 & 15 & -24 \\ 0 & 0 & 12 \end{pmatrix} \\
 (e) \quad & \begin{pmatrix} 1-i & 0 & 0 \\ 4 & 3i & 0 \\ 2i & 1+4i & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} -3i & 0 & 0 \\ 4 & -1+i & 0 \\ 10+16i & -5-3i & 3+3i \end{pmatrix} \\
 (f) \quad & \begin{pmatrix} 6 & 22 & 12 \\ 12 & -2 & 24 \\ 21 & -39 & -27 \end{pmatrix} \\
 (g) \quad & \begin{pmatrix} 18 & 28 & -6 \\ -20 & -21 & 37 \\ 48 & 14 & -16 \end{pmatrix} \\
 (h) \quad & \begin{pmatrix} -i & -8+i & -1+2i \\ 1-5i & 9-6i & -3i \\ -1+i & -6 & -3+i \end{pmatrix}
 \end{aligned}$$

27.

$$A \neq (0), \det(A) = 0$$

$$A = (a_{ij})_{m \times n} = (A^1, \dots, A^n)$$

$$\text{Since } \det(A) = 0, \text{rank}(A) < n$$

$$\exists k (1 \leq k \leq n), A^{(k)} = \sum_{j \neq k} b_j A^{(j)}, A^{(j)} \text{ is the } j\text{th column of } A$$

Without loss of generality, we may assume $k = n$

$$(\tilde{A}_{i(n-1)} = b_1 B_1 + \dots + b_{n-2} B_{n-2} + b_{n-1} B_{n-1})$$

$$\tilde{A}_{i(n-1)} = \sum_{j=1}^{n-2} b_j B_j + b_{n-1} \tilde{A}_{in}, \text{ where } B_j = ()_{(n-1) \times (n-1)} \text{ is the matrix obtained}$$

from \tilde{A}_{in} by replacing the last column with the j th column ($1 \leq k \leq n-2$)

$$\begin{aligned}
\text{Actually } C_{i(n-1)} &= (\det \tilde{A}_{i(n-1)}) = \begin{pmatrix} c_{11} & \cdots & c_{1(n-1)} & c_{1n} \\ c_{11} & \cdots & c_{1(n-1)} & c_{1n} \\ \vdots & \vdots & & \vdots \\ c_{11} & \cdots & c_{1(n-1)} & c_{1n} \end{pmatrix} \\
&= \begin{pmatrix} b_1 c_{1n} & b_2 c_{1n} & \cdots & b_{n-1} c_{1n} & c_{1n} \\ b_1 c_{2n} & b_2 c_{2n} & \cdots & b_{n-1} c_{2n} & c_{2n} \\ \vdots & \vdots & & \vdots & \vdots \\ b_1 c_{nn} & b_2 c_{nn} & \cdots & b_{n-1} c_{nn} & c_{nn} \end{pmatrix} \\
&= (b_1 c^n, \dots, b_{n-1} c^n, c^n) \\
\therefore \det(\text{adj}(A)) &= 0
\end{aligned}$$

28.

$$\begin{aligned}
\text{(a) } T(y+z) &= \det \begin{pmatrix} (y+z)(t) & y_1(t) & \cdots & y_n(t) \\ (y+z)'(t) & y_1'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \cdots & \vdots \\ (y+z)^{(n)}(t) & y_1^{(n)}(t) & \cdots & y_n^{(n)}(t) \end{pmatrix} \\
&= \det \begin{pmatrix} (y)(t) & y_1(t) & \cdots & y_n(t) \\ (y)'(t) & y_1'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \cdots & \vdots \\ (y)^{(n)}(t) & y_1^{(n)}(t) & \cdots & y_n^{(n)}(t) \end{pmatrix} + \det \begin{pmatrix} (z)(t) & y_1(t) & \cdots & y_n(t) \\ (z)'(t) & y_1'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \cdots & \vdots \\ (z)^{(n)}(t) & y_1^{(n)}(t) & \cdots & y_n^{(n)}(t) \end{pmatrix} \\
T(ky)(t) &= \det \begin{pmatrix} k(y)(t) & y_1(t) & \cdots & y_n(t) \\ k(y)'(t) & y_1'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \cdots & \vdots \\ k(y)^{(n)}(t) & y_1^{(n)}(t) & \cdots & y_n^{(n)}(t) \end{pmatrix} \\
&= k \det \begin{pmatrix} (y)(t) & y_1(t) & \cdots & y_n(t) \\ (y)'(t) & y_1'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \cdots & \vdots \\ (y)^{(n)}(t) & y_1^{(n)}(t) & \cdots & y_n^{(n)}(t) \end{pmatrix}
\end{aligned}$$

$$(b) \text{ Let } M(y) = \begin{pmatrix} (y)(t) & y_1(t) & \cdots & y_n(t) \\ (y)'(t) & y_1'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \cdots & \vdots \\ (y)^{(n)}(t) & y_1^{(n)}(t) & \cdots & y_n^{(n)}(t) \end{pmatrix}$$

$$\Leftrightarrow T(y) = 0$$

$$\Leftrightarrow \text{rank} M(y) = m$$

$$\Leftrightarrow \begin{pmatrix} y_1 \\ y_1' \\ \vdots \\ y_1^{(n)} \end{pmatrix} \in \text{span} \left(\begin{pmatrix} y_2 \\ y_2' \\ \vdots \\ y_2^{(n)} \end{pmatrix}, \cdots, \begin{pmatrix} y_n \\ y_n' \\ \vdots \\ y_n^{(n)} \end{pmatrix} \right)$$

$$\Leftrightarrow y(t) \in \text{span}(y_1, y_2, \cdots, y_n)$$

4.4. Summary-Important Facts about Determinants

1. (a) T
 (b) T
 (c) T
 (d) F ($\det(B) = -\det(A)$)
 (e) F ($\det(B) = k \det(A)$)
 (f) T
 (g) T
 (h) F ($\det(A^t) = \det(A)$)
 (i) T
 (j) T
 (k) T
2. (a) 22 (b) -29 (c) $2 - 4i$ (d) $-24 + 6i$
3. (a) -12 (b) -13 (c) -12 (d) -13 (e) 22 (f) $4 + 2i$ (g) -2 (h) 154
4. (a) 36 (b) -100 (c) -49 (d) -10 (e) $-28 - i$ (f) $17 - 3i$ (g) 95
- 5 6. 20 and 21 in 4.3

4.4.

4.5. A characterization of the Determinants

1. (a) F

(b) T

(c) T

(d) F ($\delta(B) = -\delta(A)$)

(e) F ($\delta(I) = 1$)

(f) T (p.238, 239)

2.

Determine all the 1 - *linear* functions $\delta : M_{1 \times 1}(F) \rightarrow F$

Identity function

3. No

Let $A = \begin{pmatrix} a_1 \\ a_2 \\ a_3 + tv \end{pmatrix}$, $v = (b_1, b_2, b_3)$

$$\delta(A) = k \neq k + tv = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + t\delta \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}$$

4. No

Let $A = \begin{pmatrix} a_1 \\ a_2 + kv \\ a_3 \end{pmatrix}$, $v = (b_1, b_2, b_3)$

$$\delta(A) = a_2 \neq a_2 + ka_2 = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + k\delta \begin{pmatrix} a_1 \\ v \\ a_3 \end{pmatrix}$$

5. Yes

$$(i) \delta \begin{pmatrix} a_1 + kv \\ a_2 \\ a_3 \end{pmatrix} = (A_{11} + kb_1)A_{23}A_{32} = A_{11}A_{23}A_{32} + k(b_1A_{23}A_{32}) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} v \\ a_2 \\ a_3 \end{pmatrix}$$

$$(ii) \delta \begin{pmatrix} a_1 \\ a_2 + kv \\ a_3 \end{pmatrix} = A_{11}(A_{23} + kb_3)A_{32} = A_{11}A_{23}A_{32} + k(A_{11}b_3A_{32}) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} a_1 \\ v \\ a_3 \end{pmatrix}$$

$$(iii) \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 + kv \end{pmatrix} = A_{11}A_{23}(A_{32} + kb_2) = A_{11}A_{23}A_{32} + k(A_{11}A_{23}b_2) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}$$

6. No

$$\delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 + kv \end{pmatrix} = A_{11} + A_{23} + (A_{32} + kb_2) \neq (A_{11} + A_{23} + A_{32}) + k(A_{11} + A_{23} + b_2) =$$

$$\delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + k \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}$$

7. Yes

$$(i) \delta \begin{pmatrix} a_1 + kv \\ a_2 \\ a_3 \end{pmatrix} = (A_{11} + kb_1)A_{21}A_{32} = A_{11}A_{21}A_{32} + k(b_1A_{21}A_{32}) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} v \\ a_2 \\ a_3 \end{pmatrix}$$

$$(ii) \delta \begin{pmatrix} a_1 \\ a_2 + kv \\ a_3 \end{pmatrix} = A_{11}(A_{21} + kb_1)A_{32} = A_{11}A_{21}A_{32} + k(A_{11}b_1A_{32}) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} a_1 \\ v \\ a_3 \end{pmatrix}$$

$$(iii) \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 + kv \end{pmatrix} = A_{11}A_{21}(A_{32} + kb_2) = A_{11}A_{21}A_{32} + k(A_{11}A_{21}b_2) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}$$

$$8. \text{ No}$$

$$\delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 + kv \end{pmatrix} = A_{11}(A_{31} + kb_1)(A_{32} + kb_2) \neq A_{11}A_{31}A_{32} + k(A_{11}b_1b_2) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}$$

$$9. \text{ No}$$

$$\delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 + kv \end{pmatrix} = A_{11}^2 A_{22}^2 (A_{33} + kb_3)^2 \neq A_{11}^2 A_{22}^2 A_{33}^2 + k(A_{11}^2 A_{22}^2 b_3^2) = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} +$$

$$k \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}$$

10. Yes

$$\begin{aligned}
\text{(i)} \quad & \delta \begin{pmatrix} a_1 + kv \\ a_2 \\ a_3 \end{pmatrix} = (A_{11} + kb_1)A_{22}A_{33} - (A_{11} + kb_1)A_{21}A_{32} \\
& = A_{11}A_{22}A_{33} - A_{11}A_{21}A_{32} + k(b_1A_{22}A_{33} - b_1A_{21}A_{32}) \\
& = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + k \begin{pmatrix} v \\ a_2 \\ a_3 \end{pmatrix} \\
\text{(ii)} \quad & \delta \begin{pmatrix} a_1 \\ a_2 + kv \\ a_3 \end{pmatrix} = A_{11}(A_{22} + kb_2)A_{33} - A_{11}(A_{21} + kb_1)A_{32} \\
& = A_{11}A_{22}A_{33} - A_{11}A_{21}A_{32} + k(A_{11}b_2A_{33} - A_{11}b_1A_{32}) \\
& = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + k \begin{pmatrix} a_1 \\ v \\ a_3 \end{pmatrix} \\
\text{(iii)} \quad & \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 + kv \end{pmatrix} = A_{11}A_{22}(A_{33} + kb_3) - A_{11}A_{21}(A_{32} + kb_2) \\
& = A_{11}A_{22}A_{33} - A_{11}A_{21}A_{32} + k(A_{11}A_{22}b_3 - A_{11}A_{21}b_2) \\
& = \delta \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + k \begin{pmatrix} a_1 \\ a_2 \\ v \end{pmatrix}
\end{aligned}$$

11.

(i) Corollary 2 to the theorem 4.10(p.241)

Let $M = (a_1, a_2, \dots, a_n)^t$, a'_i s : rows of M Since $\text{rank}(M) < n$,some row of M , say r , is a linear combination of the other rowsThat is, $\exists c_1, \dots, c_{r-1}, c_{r+1}, \dots, c_n \in F$ s.t.

$$a_r = c_1 a_1 + \dots + c_{r-1} a_{r-1} + c_{r+1} a_{r+1} + \dots + c_n a_n$$

If M' is obtained from M by adding $-c_i$ times row i to row r for each $i \neq r$,

then row r of M' consists entirely of zeros, so $\delta(M') = 0$

But by the corollary 1 to the theorem 4.10, $\delta(M') = \delta(M)$

$\therefore \delta(M) = 0$

(i) Corollary 3 to the theorem 4.10

By the theorem 4.10 (a), $\delta(E_1) = -\delta(I)$

By the n -linearity, $\delta(E_2) = k\delta(I)$

By the corollary 1 to the theorem 4.10, $\delta(E_3) = \delta(I)$

12. Theorem 4.11

(i) $A = E_1 \Rightarrow \delta(E_1) = -1$

$\delta(AB) = -\delta(B) = \delta(A)\delta(B)$

(ii) $A = E_2 \Rightarrow \delta(E_2) = k$

$\delta(AB) = k\delta(B) = \delta(A)\delta(B)$

(ii) $A = E_3 \Rightarrow \delta(E_3) = 1$

$\delta(AB) = \delta(B) = \delta(A)\delta(B)$

13.

$\forall A \in M_{2 \times 2}(F)$, $A = (a_1, a_2)$, $v = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$, a_i : columns of A

(i) $\det(a_1, a_2 + kv) = \det(a_1, a_2) + k \det(a_1, v)$

(ii) $\det(a_1 + kv, a_2) = \det(a_1, a_2) + k \det(v, a_2)$

14.

Let $A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}$, a_i : rows of A , $v = (b_1, b_2)$

$$(i) \delta \begin{pmatrix} a_1 + kv \\ a_2 \end{pmatrix} = \delta \begin{pmatrix} A_{11} + kb_1 & A_{12} + kb_2 \\ A_{21} & A_{22} \end{pmatrix} = (A_{11} + kb_1)A_{22}a + (A_{11} + kb_1)A_{21}b + \\ (A_{12} + kb_2)A_{22}c + (A_{12} + kb_2)A_{21}d$$

$$\delta \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + \delta \begin{pmatrix} v \\ a_2 \end{pmatrix} = A_{11}A_{22}a + A_{11}A_{21}b + A_{12}A_{22}c + A_{12}A_{21}d + k(A_{22}b_1a + A_{21}b_1b + \\ A_{22}b_2c + A_{21}b_2d)$$

$$(ii) \delta \begin{pmatrix} a_1 \\ a_2 + kv \end{pmatrix} = \delta \begin{pmatrix} A_{11} & A_{12} \\ A_{21} + kb_1 & A_{22} + kb_2 \end{pmatrix} = A_{11}(A_{22} + kb_2)a + A_{11}(A_{21} + \\ kb_1)b + A_{12}(A_{22} + kb_2)c + A_{12}(A_{21} + kb_1)d$$

$$\delta \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + \delta \begin{pmatrix} a_1 \\ v \end{pmatrix} = A_{11}A_{22}a + A_{11}A_{21}b + A_{12}A_{22}c + A_{12}A_{21}d + k(A_{11}b_2a + A_{11}b_1b + \\ A_{12}b_2c + A_{12}b_1d)$$

15.

(\Leftarrow) Exercise 14

$$(\Rightarrow) \text{ Let } A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \in M_{2 \times 2}(F)$$

$$\delta(A) = \delta \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & 0 \end{pmatrix} + \delta \begin{pmatrix} A_{11} & A_{12} \\ 0 & A_{22} \end{pmatrix} \\ = \delta \begin{pmatrix} A_{11} & 0 \\ A_{21} & 0 \end{pmatrix} + \delta \begin{pmatrix} 0 & A_{12} \\ A_{21} & 0 \end{pmatrix} + \delta \begin{pmatrix} A_{11} & 0 \\ 0 & A_{22} \end{pmatrix} + \delta \begin{pmatrix} 0 & A_{12} \\ 0 & A_{22} \end{pmatrix} \\ = A_{11}A_{21}\delta \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} + A_{12}A_{21}\delta \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + A_{11}A_{22}\delta \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + A_{12}A_{22}\delta \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$$

Since δ is 2-linear function,

$$\delta \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} = \delta \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} = 0, \delta \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1, \delta \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = -1$$

Let $a = 1$, $b = 0$, $c = 0$, $d = -1$

$$\text{then } \delta(A) = A_{11}A_{21} \cdot 0 + A_{12}A_{21} \cdot (-1) + A_{11}A_{22} \cdot 1 + A_{12}A_{22} \cdot 0$$

16.

If $\delta(I) = t$, then

$$\delta(E_1) = -t = t \det(E_1)$$

$$\delta(E_2) = kt = t \det(E_2)$$

$$\delta(E_3) = t = t \det(E_3)$$

$$\therefore \delta(E) = -t \det(E)$$

17.

$$\begin{aligned}
(a\delta_1 + b\delta_2) \begin{pmatrix} a_1 \\ \vdots \\ a_r + kv \\ \vdots \\ a_n \end{pmatrix} &= (a\delta_1) \begin{pmatrix} a_1 \\ \vdots \\ a_r + kv \\ \vdots \\ a_n \end{pmatrix} + (b\delta_2) \begin{pmatrix} a_1 \\ \vdots \\ a_r + kv \\ \vdots \\ a_n \end{pmatrix} \\
&= a \left(\delta_1 \begin{pmatrix} a_1 \\ \vdots \\ a_r \\ \vdots \\ a_n \end{pmatrix} + k\delta_1 \begin{pmatrix} a_1 \\ \vdots \\ v \\ \vdots \\ a_n \end{pmatrix} \right) + b \left(\delta_2 \begin{pmatrix} a_1 \\ \vdots \\ a_r \\ \vdots \\ a_n \end{pmatrix} + k\delta_2 \begin{pmatrix} a_1 \\ \vdots \\ v \\ \vdots \\ a_n \end{pmatrix} \right) \\
&= a\delta_1 \begin{pmatrix} a_1 \\ \vdots \\ a_r \\ \vdots \\ a_n \end{pmatrix} + b\delta_2 \begin{pmatrix} a_1 \\ \vdots \\ a_r \\ \vdots \\ a_n \end{pmatrix} + k(a\delta_1 \begin{pmatrix} a_1 \\ \vdots \\ v \\ \vdots \\ a_n \end{pmatrix} + b\delta_2 \begin{pmatrix} a_1 \\ \vdots \\ v \\ \vdots \\ a_n \end{pmatrix})
\end{aligned}$$

$$= (a\delta_1 + b\delta_2) \begin{pmatrix} a_1 \\ \vdots \\ a_r \\ \vdots \\ a_n \end{pmatrix} + k(a\delta_1 + b\delta_2) \begin{pmatrix} a_1 \\ \vdots \\ v \\ \vdots \\ a_n \end{pmatrix}$$

18. V : the set of all $m \times n$ matrices with entries from a field F is a vector space, and $W \subseteq V$

(i) By the exercise 17,

$$\forall \delta_1, \delta_2, \delta_1 + \delta_2 \in W \text{ and } c\delta_1 \in W$$

(ii) By the example in p.238, $O \in W$

19.

Let $M = (a_1, a_2, \dots, a_n)^t$, a'_i 's : rows of M

Say a_i and a_j are identical rows in M

If M' is obtained from M by interchanging a_i and a_j ,

$$\text{then } \delta(M') = -\delta(M)$$

$$\text{Since } a_i = a_j, \delta(M') = \delta(M)$$

$$\text{therefore } 2\delta(M) = 0$$

$$\text{Since } \text{char}(F) \neq 2, \delta(M) = 0$$

20.

$$\text{In } \mathbb{Z}_2, 2\delta(M) = 0 \not\Rightarrow \delta(M) = 0$$