## Homework 6 solutions

1

(a)

$$x^{2} + y^{2} = 1 \implies f(x, y) = e^{-1}, g(x, y) = e^{-1}.$$

(b)

$$\nabla f = \begin{bmatrix} -2xe^{-x^2-y^2} & -2ye^{-x^2-y^2} \end{bmatrix}, \ \nabla g = \begin{bmatrix} \frac{-2e^{-1}x}{(x^2+y^2)^2} & \frac{-2e^{-1}y}{(x^2+y^2)^2} \end{bmatrix}.$$

(c)

If  $a^2+b^2=1$ , then  $\nabla f(a,b)=\begin{bmatrix} -2ae^{-1} & -2be^{-1} \end{bmatrix}$ , and  $\nabla g=\begin{bmatrix} -2ae^{-1} & -2be^{-1} \end{bmatrix}$ . Since  $\nabla f(a,b)=\nabla g(a,b)$  and f(a,b)=g(a,b), the graphs are tangent.

2

(a)

$$\frac{\partial}{\partial x}(y+x^2)^3 = 6x(y+x^2)^2.$$

(b)

$$\frac{\partial}{\partial x}g(x+x^2) = 2x \cdot g_x(y+x^2).$$

3

(a)

$$f_1 = r^2 \cos 2\theta = r^2 (\cos^2 \theta - \sin^2 \theta) = r^2 (\frac{x^2}{r^2} - \frac{y^2}{r^2}) = x^2 - y^2.$$

$$f_2 = r^{-2} \sin 2\theta = r^{-2} (2 \sin \theta \cos \theta) = 2r^{-2} \frac{y}{r} \frac{x}{r} = \frac{2xy}{(x^2 + y^2)^2}$$

$$f_3 = r^3 \sin 3\theta = r^3 (3 \sin \theta \cos^2 \theta - \sin^3 \theta) = r^3 (3 \frac{y}{r} \frac{x^2}{r^2} - \frac{y^3}{r^3}) = 3x^2 y - y^3$$

(b)

$$f_{1xx} = \frac{\partial}{\partial x} 2x = 2$$
,  $f_{1yy} = \frac{\partial}{\partial y} - 2y = -2$ , so  $f_{1xx} + f_{1yy} = 0$ .

 $f_{2xx} = \frac{\partial}{\partial x} \frac{y^3 - 3x^2y}{(x^2 + y^2)^3} = \frac{12xy(x^2 - y^2)}{(x^2 + y^2)^4}.$   $f_{2yy} = \frac{12xy(y^2 - x^2)}{(x^2 + y^2)^4}$  since f(x, y) = f(y, x). Therefore  $f_{2xx} = -f_{2yy}$ .

$$f_{3xx} = \frac{\partial}{\partial x} 6xy = 6y$$
.  $f_{3yy} = \frac{\partial}{\partial y} (3x^2 - 3y^2) = -6y = -f_{3xx}$ .

4

(a)

For  $f(x,y) = x^4 + y^4$ ,  $\Delta f = f_{xx} + f_{yy} = 12(x^2 + y^2)$ . For  $f(x,y) = (x^2 + y^2)^p$ ,  $f_{1xx} = \frac{\partial}{\partial x} 2px(x^2 + y^2)^{p-1} = 2p(x^2 + y^2)^{p-2}(x(p-1) + (x^2 + y^2))$   $f_{yy} = 2p(x^2 + y^2)^{p-2}(y(p-1) + (x^2 + y^2))$  since f(x,y) = f(y,x)  $\Delta f = f_{xx} + f_{yy} = 2p(x^2 + y^2)^{p-2}(x(p-1) + (x^2 + y^2) + y(p-1) + (x^2 + y^2)) = 2p(x^2 + y^2)^{p-2}((x+y)(p-1) + 2x^2 + 2y^2)$ .

(b)

 $\Delta f = 2a + 2b.$ 

(c)

 $\frac{\partial^2}{\partial x^2}ln(x^2+y^2) = \frac{\partial}{\partial x}\frac{2x}{x^2+y^2} = \frac{2(y^2-x^2)}{x^2+y^2}.$  Since this function is symmetric,  $\frac{\partial^2}{\partial y^2}ln(x^2+y^2) = \frac{2(x^2-y^2)}{x^2+y^2} = -\frac{\partial^2}{\partial x^2}ln(x^2+y^2).$  Therefore  $\Delta ln(x^2+y^2) = 0$ .

The domain of ln(x) is x > 0, so the domain of  $ln(x^2 + y^2)$  is  $x^2 + y^2 > 0$ , that is, either  $x \neq 0$  or  $y \neq 0$ .

5

(a)

 $t_r = \frac{\partial t}{\partial r} = \frac{\partial u}{\partial x} \frac{\mathrm{d}}{\mathrm{d}r} r \cos \theta + \frac{\partial u}{\partial y} \frac{\mathrm{d}}{\mathrm{d}r} r \sin \theta = \frac{\partial u}{\partial x} \cos \theta + \frac{\partial u}{\partial y} \sin \theta. \text{ Similarly, } t_\theta = \frac{\partial t}{\partial \theta} = \frac{\partial u}{\partial x} \frac{\mathrm{d}}{\mathrm{d}\theta} r \cos \theta + \frac{\partial u}{\partial y} \frac{\mathrm{d}}{\mathrm{d}\theta} r \sin \theta = -\frac{\partial u}{\partial x} r \sin \theta + \frac{\partial u}{\partial y} r \sin \theta.$ 

(b)

From (a) we know that  $t_r = u_x \cos\theta + u_y \sin\theta$ . By the product rule, we have  $t_{rr} = u_{xr} \cos\theta + u_{yr} \sin\theta$ , since  $\frac{\partial}{\partial r} \cos\theta = \frac{\partial}{\partial r} \sin\theta = 0$ . We can work out  $u_{xr}$  and  $u_{yr}$  by differentiating  $u_x$  and  $u_y$  with respect to r, as in (a):  $u_{xr} = u_{xx} \cos\theta + u_{xy} \sin\theta$ , and  $u_{yr} = u_{yx} \cos\theta + u_{yy} \sin\theta$ . Thus, we have  $t_{rr} = (u_{xx} \cos\theta + u_{xy} \sin\theta) \cos\theta + (u_{yx} \cos\theta + u_{yy} \sin\theta) \sin\theta$ . Similarly, we can apply the above steps to get  $t_{\theta\theta} = \frac{\partial}{\partial \theta} t_{\theta} = \frac{\partial}{\partial \theta} (u_x (-r\sin\theta) + u_y (r\cos\theta))$ . This comes out to  $u_{x\theta}(-r\sin\theta) + u_x (-r\cos\theta) + u_{y\theta}(r\cos\theta) + u_y (-r\sin\theta)$ , using the product rule. In a similar way we work out  $u_{x\theta}$  and  $u_{y\theta}$  by differentiating:  $u_{x\theta} = u_{xx}(-r\sin\theta) + u_{yx}(r\cos\theta)$  and  $u_{y\theta} = u_{xy}(-r\sin\theta) + u_{yy}(r\cos\theta)$ . We can simplify by applying the change of variables specified in the question:  $x = r\cos\theta$  and  $y = r\sin\theta$ , giving  $t_{\theta\theta} = u_{x\theta}(-y) + u_x(-x) + u_{y\theta}(x) + u_y(-y) = -y(-yu_{xx} + xu_{yx}) + x(-yu_{yx} + xu_{yy}) + -xu_x - yu_y$ . Note that  $rt_r = u_x r\cos\theta + u_y r\sin\theta = xu_x + yu_y$  and  $x^2 + y^2 = r^2$ , so  $t_{\theta\theta} = -rt_r + r^2(u_{xx} + u_{yy})$ . Therefore,  $t_{\theta\theta} = t_{x\theta} + t_{rr} = t_{x\theta} + t_{xr} + t_{x\theta} + t_{x\theta} + t_{x\theta}$ .

6

(a)

$$\overrightarrow{Df} = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} = \begin{bmatrix} e^x \cos y & -e^x \sin y \\ e^x \sin y & e^x \cos y \end{bmatrix}.$$

(b)

 $\det \overrightarrow{Df} = e^x \cos^2 y + e^x \sin^2 y = e^x$ .  $e^x > 0 \ \forall \ x \in \mathbb{R}$ , so  $\det \overrightarrow{Df}$  is nonzero for all (x,y), that is,  $\overrightarrow{Df}^{-1}$  exists everywhere.

(c)

f contains y only as  $\sin y$  and  $\cos y$  and is therefore periodic in y. Therefore, there are infinite examples of such points, such as  $f(1,0) = f(1,\pi) = [e,0]$ .