

# MATH 2220 SECTION 203

## HW #8

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**Problem 1** The area of a rectangle with sides  $x$  and  $y$  is  $f(x, y) = xy$ . Its perimeter is  $g(x, y) = 2(x + y)$ . To maximise  $f$  with the constraint  $g(x, y) = p$  we need to solve  $\nabla f(x, y) = \lambda \nabla g(x, y)$ .  $\nabla f(x, y) = (y, x)$ ,  $\nabla g(x, y) = (2, 2)$  so we have  $(y, x) = \lambda(2, 2) \implies x = y = 2\lambda$ . Our constraint gives us  $2(x + y) = 2(4\lambda) = 8\lambda = p$ , so  $x = y = \frac{p}{4}$ , and the area is  $f(\frac{p}{4}, \frac{p}{4}) = (\frac{p}{4})^2$ .

**Problem 2** We want to find  $\vec{x} \in \mathbb{R}^n$  such that the distance between  $\vec{a}$  and  $\vec{x}$  is as small as possible. This distance is  $\|\vec{a} - \vec{x}\|$ . Since the norm is always positive, we can treat this as minimising  $f(\vec{x}) = \|\vec{a} - \vec{x}\|^2 = \sum_{i=1}^n (a_i - x_i)^2$ , under the constraint  $g(\vec{x}) = \vec{c} \cdot \vec{x} = 0$ , reducing our problem to solving  $\nabla f = \lambda \nabla g(\vec{x})$ .  $\nabla f(\vec{x}) = (-2(a_1 - x_1), -2(a_2 - x_2), \dots, -2(a_n - x_n)) = -2((a_1 - x_1), (a_2 - x_2), \dots, (a_n - x_n)) = -2(\vec{a} - \vec{x})$ , and  $\nabla g = \vec{c}$ , so we have  $2(\vec{x} - \vec{a}) = \lambda \vec{c}$ . We can use  $\lambda$  to encompass any multiplicative constants, so this is equivalent to  $\vec{x} - \vec{a} = \lambda \vec{c} \implies \vec{x} = \lambda \vec{c} + \vec{a}$  for some other value of  $\lambda$ .

Using our constraint  $\vec{c} \cdot \vec{x} = 0$ , we get  $\vec{c} \cdot (\lambda \vec{c} + \vec{a}) \implies \lambda \|\vec{c}\|^2 + \vec{c} \cdot \vec{a} = 0 \implies \lambda = -\frac{\vec{c} \cdot \vec{a}}{\|\vec{c}\|^2}$ . Plugging this into our equation for  $\vec{x}$  we get  $\vec{x} = -\frac{\vec{c} \cdot \vec{a}}{\|\vec{c}\|^2} \vec{c} + \vec{a}$ .

### Problem 3

(a) The velocity is  $\vec{v}(t) = \nabla \vec{x} = (-r\omega \sin(\omega t), r\omega \cos(\omega t))$ .  $\vec{x} \cdot \nabla \vec{x} = (r \cos(\omega t))(-r\omega \sin(\omega t)) + (r \sin(\omega t))(r\omega \cos(\omega t)) = r^2\omega(\sin(\omega t) \cos(\omega t) - \sin(\omega t) \cos(\omega t)) = 0$ , so the velocity is orthogonal to the displacement. Because, the displacement is orthogonal to the circle, the velocity is tangent to the circle.

(b) The speed is  $s = \|\vec{v}\| = \|(-r\omega \sin(\omega t), r\omega \cos(\omega t))\| = \sqrt{(-r\omega \sin(\omega t))^2 + (r\omega \cos(\omega t))^2} = \sqrt{r^2\omega^2(\sin^2(\omega t) + \cos^2(\omega t))} = \sqrt{r^2\omega^2} = r\omega$ .

(c) The acceleration is  $\vec{a}(t) = \nabla \vec{v} = (-r\omega^2 \cos(\omega t), -r\omega^2 \sin(\omega t)) = -\omega^2(r \cos(\omega t), r \sin(\omega t)) = -\omega^2 \vec{x}(t)$ . Since it is a negative multiple of the displacement, which is directed away from the origin, the acceleration must be directed towards the origin.

(d)  $\|\vec{a}\| = \sqrt{(-r\omega^2 \cos(\omega t))^2 + (-r\omega^2 \sin(\omega t))^2} = \sqrt{r\omega^4(\cos^2(\omega t) + \sin^2(\omega t))} = \sqrt{r^2\omega^4} = r\omega^2$ .

(e) First, calculate  $(x^2 + y^2)^{\frac{3}{2}} = (r^2(\cos^2(\omega t) + \sin^2(\omega t)))^{\frac{3}{2}} = (r^2)^{\frac{3}{2}} = r^3$ . Then,  $x'' + \frac{x}{(x^2 + y^2)^{\frac{3}{2}}} = -r\omega^2 \cos(\omega t) + \frac{r \cos(\omega t)}{r^3}$ . If  $\omega^2 r^3 = 1 \implies r^3 = \frac{1}{\omega^2}$ , this is equation becomes  $-r\omega^2 \cos(\omega t) + r\omega^2 \cos(\omega t) = 0$ . In exactly the same way but with sin instead of cos, we get  $y'' + \frac{y}{(x^2 + y^2)^{\frac{3}{2}}} = 0$ .

(f)  $x'y - xy' = (-r\omega \sin(\omega t))(r \sin(\omega t)) - (r \cos(\omega t))(r\omega \cos(\omega t)) = -r^2\omega(\sin^2(\omega t) + \cos^2(\omega t)) = -r^2\omega$ .

### Problem 4

(a) Using the definition  $\vec{\omega} = (\vec{x}, \vec{y})$ , we have  $\vec{\omega}'' = (\vec{x}'', \vec{y}'') = \left(\frac{k(\vec{y}-\vec{x})}{m}, -\frac{k(\vec{y}-\vec{x})}{m}\right)$ . Therefore,  $m\vec{\omega}'' = (k(\vec{x}-\vec{y}), -k(\vec{x}-\vec{y}))$ .  $\nabla p(\vec{\omega}) = \frac{k}{2}\nabla \|\vec{x}-\vec{y}\|^2 = \frac{k}{2}\nabla((x_1-y_1)^2 + (x_2-y_2)^2 + (x_3-y_3)^2) = \frac{k}{2}(2(x_1-y_1), 2(x_2-y_2), 2(x_3-y_3), -2(x_1-y_1), -2(x_2-y_2), -2(x_3-y_3)) = (k(\vec{x}-\vec{y}), -k(\vec{x}-\vec{y})) = -m\vec{\omega}''$ .

(b)  $\nabla(p(\vec{\omega}(t))) = \nabla p(\vec{\omega}(t)) \cdot \nabla \vec{\omega}(t) = -m\vec{\omega}'' \cdot \vec{\omega}'$ , as per the equation derived above.

$\nabla \|\vec{\omega}'\|^2 = \nabla(x_1'^2 + x_2'^2 + x_3'^2 + y_1'^2 + y_2'^2 + y_3'^2) = (2x_1'x_1'', 2x_2'x_2'', 2x_3'x_3'', 2y_1'y_1'', 2y_2'y_2'', 2y_3'y_3'') = 2\vec{\omega}' \cdot \vec{\omega}''$

Therefore,  $\nabla \left( \frac{m\|\vec{\omega}'\|^2}{2} + p(\vec{\omega}(t)) \right) = m\vec{\omega}' \cdot \vec{\omega}'' - m\vec{\omega}'' \cdot \vec{\omega}' = 0$ . This quantity therefore does not change with time.

### Problem 5

(a) The linear approximation for  $\vec{x}$  at  $t$  is  $\vec{x}(t+h) \approx L_x(h) = \vec{x}(t) + \vec{x}'(t)h$ , and that of  $\vec{y}$  at  $t$  is  $L_y(h) = \vec{y}(t) + \vec{y}'(t)h$ . Therefore,  $\vec{u}(t+h) \approx (\vec{x}(t) + \vec{x}'(t)h, \vec{y}(t) + \vec{y}'(t)h)$ .

(b) The signed area of the triangle formed by two vectors  $(a, b)$  and  $(c, d)$ , both originating at 0, is  $\frac{bc-ad}{2}$ , as this is the determinant of the matrix  $\begin{bmatrix} \vec{u} & \vec{v} \end{bmatrix}$ . In this case, this is equal to  $\frac{x(y+y'h)-y(x+x'h)}{2} = \frac{h}{2}(xy' - yx')$ .

(c) If  $A$  is the area, the change in area is  $\Delta A = \frac{h}{2}(xy' - yx')$ , and  $\Delta t = h$ . The rate of change of the area is  $\frac{dA}{dt} = \lim_{h \rightarrow 0} \frac{\Delta A}{\Delta t} = \lim_{h \rightarrow 0} \frac{1}{2}(xy' - yx') = \frac{1}{2}(xy' - yx')$ . If we parametrise like in (3) but for an ellipse instead of a circle, we get  $\vec{x}(t) = (ra \cos(\omega t), rb \sin(\omega t))$ . From this, if we push through the algebra as in (3c) we get  $x'y - xy' = -r^2 ab \omega \implies xy' - x'y = r^2 ab \omega$ , which is also constant given fixed  $a, b, r$  and  $\omega$ . That means  $\frac{dA}{dt} = \frac{r^2 ab \omega}{2}$  is constant, which implies that planet that travels for time  $t$  will always sweep out the same area, regardless of where the planet is.

(d) The period is the time taken to sweep out the entire area:  $T = \frac{A}{\frac{dA}{dt}} = \frac{2A}{r^2 ab \omega}$ .

### Problem 6

(a) We know that  $-p\sqrt{x^2 + y^2} \geq 0$ , since  $p < -1$  and  $\sqrt{n} \geq 0 \forall n \in \mathbb{R}$ . Therefore, the equation only makes sense if the right hand side is also nonnegative:  $q - y \geq 0 \implies q \geq y$ . However, for motion to occur, we need this to be positive, so we have  $y < q$ .

(b) As per the equation derived in part (c), this function is the equation for an ellipse.

(c) Rearranging the equation, we get  $p^2(x^2 + y^2) = (q - y)^2 \implies p^2x^2 + (p^2 - 1)y^2 + 2qy = q^2 \implies p^2x^2 + (p^2 - 1)\left(y + \frac{q}{p^2 - 1}\right)^2 - \frac{q^2}{p^2 - 1} = q^2 \implies p^2x^2 + (p^2 - 1)\left(y + \frac{q}{p^2 - 1}\right)^2 = \frac{p^2q^2}{p^2 - 1}$ . To make this into the traditional equation for an ellipse we divide both sides by the right-hand side, giving  $x^2 \frac{p^2 - 1}{q^2} + \left(y + \frac{q}{p^2 - 1}\right)^2 \frac{(p^2 - 1)^2}{p^2q^2} = 1$ . This gives the values of the two axes:  $r_1 = \frac{q}{\sqrt{p^2 - 1}}$  and  $r_2 = \frac{-pq}{p^2 - 1}$ . The minus in the second equation comes from the fact that we want  $r_2 \geq 0$ , but  $p < -1$ , so we need to invert the value to get the unsigned magnitude.

(d) By Kepler's second law, we know that the time taken to "sweep" out the entire ellipse is  $T$ , the period of the orbit. The total area is  $A = \pi r_1 r_2 = \pi \frac{q}{\sqrt{p^2 - 1}} \frac{-pq}{p^2 - 1} = \pi \frac{-pq^2}{(p^2 - 1)^{\frac{3}{2}}}$ . We know that  $\frac{dA}{dt}$  is constant and  $T = A \frac{dA}{dt}$ , so  $T \propto A$ , and therefore  $T^2 \propto A^2$ .  $A^2 = \pi^2 \frac{p^2 q^4}{(p^2 - 1)^3}$