# SELFBALANCING ROBOT "STEPPEREK"

Active mode: Position Mode



### Modes

Balance Mode

Position Mode

Quadrant Driving Mode

Ultrasonic Mode

Remote Control

Ref. Position [m]: 0.2

### **Function Buttons**

STOP

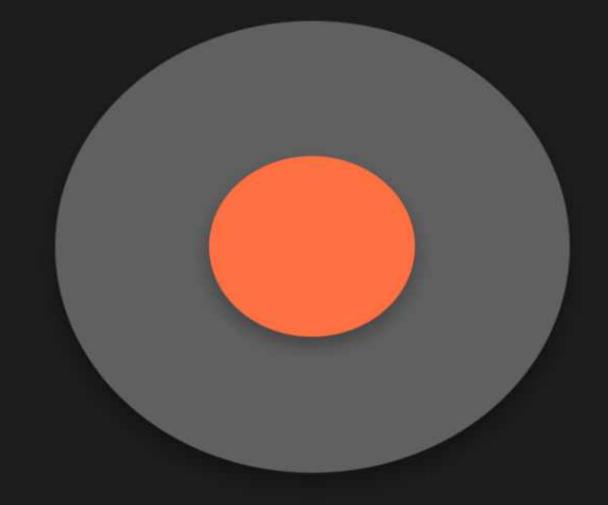
SEND

# SELFBALANCING ROBOT "STEPPEREK"

Active mode: Remote Control

0.12°

Remote Control



#### Modes

Balance Mode

Position Mode

Quadrant Driving Mode

Ultrasonic Mode

Remote Control

#### **Function Buttons**

STOP

SEND

# SELFBALANCING ROBOT "STEPPEREK"

Active mode: Ultrasonic Mode

-0.30°

# Modes

Balance Mode

Position Mode

Quadrant Driving Mode

Ultrasonic Mode

**Remote Control** 

Ref. Position - Ultrasonic [m]: 0.4

# **Function Buttons**

STOP

SEND