

HO CHI MINH CITY UNIVERSITY OF TECHNOLOGY FACULTY OF TRANSPORTATION ENGINEERING

Department Automotive and Engine

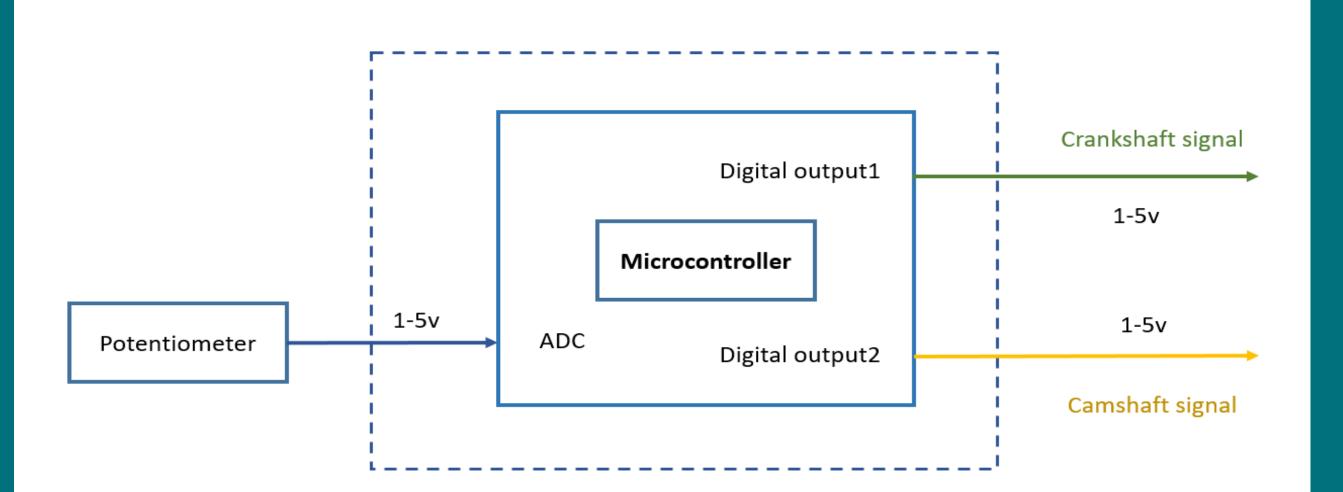
Project: DESIGN OF M.EXPANDER CRANKSHAFT AND CAMSHAFT POSITION SENSOR SIMULATOR

Instructor: Dr. Tran Dang Long

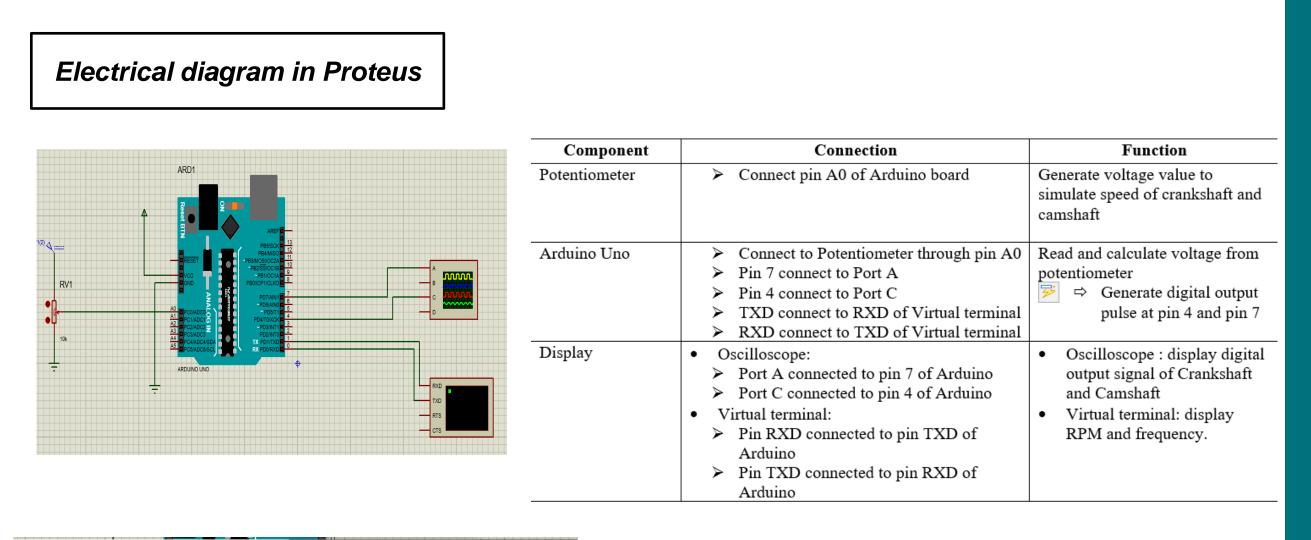
Student's name: Trần Đoàn Đăng Khôi - 1752303

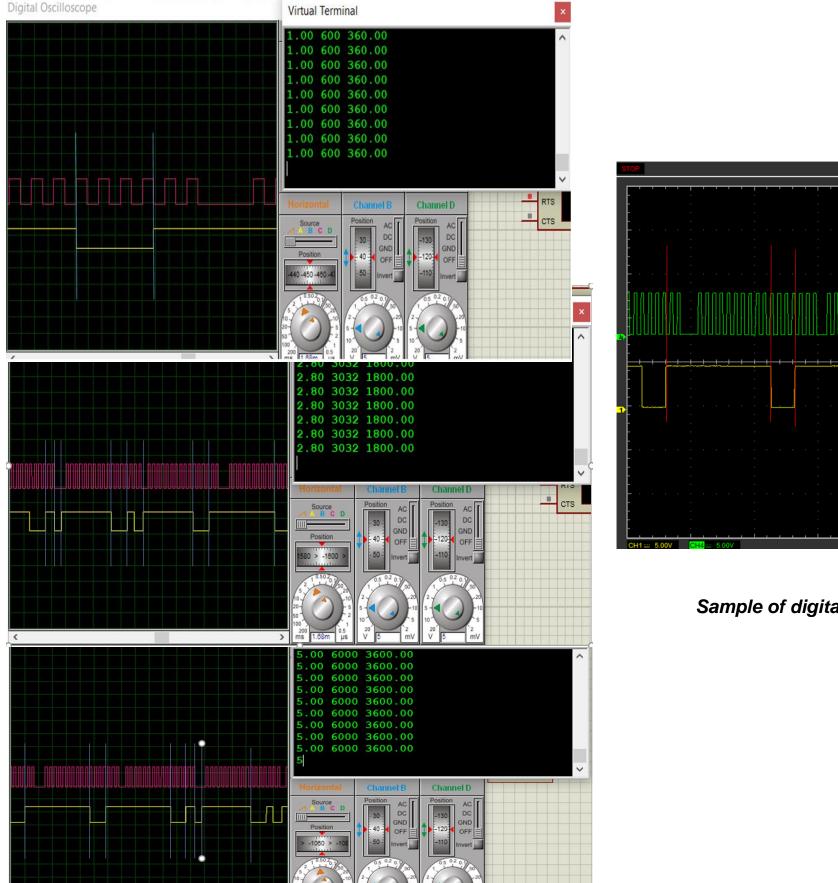
I. INTRODUCTION 1.1 Working principle - The crank angle sensor monitors rotation of crankshaft sensing ring (36 teeth including 3 missing teeth) installed on the crankshaft and converts to voltage (pulse signal) that is output to engine-ECU. Engine-ECU uses crank angle sensor's output pulse to detect crank angle. - The camshaft position sensor monitors rotation of the camshaft position sensing ring (6 teeth) and converts to voltage (pulse signal) that is output to engine-ECU. Upon receiving this output voltage, the engine-ECU effects feedback control to optimize the phase of the camshaft. Engine-ECU uses a combination of the camshaft position sensor output pulse signal and crank angle sensor output pulse signal to identify cylinders in the compression process. This information will help to fine tune spark timing and Angle position Camshaft position sensor Crankshaft position Camshaft position sensing ring 1.2 Mitsubishi Expander crankshaft and camshaft signal simulator Microcontroller Crankshaft signal Angle position Speed Camshaft signal

II. GENERAL LAYOUT DESIGN



IV. SIMULATION AND RESULT





Digital output of crankshaft and camshaft in different speed

Sample of digital output signal of M.EXPANDER

III. TECHNICAL DESIGN Electrical scheme Timing diagram of timer 0 Arduino f_ADC Pin 4 ✓ Read A0 channel and calculate RPM Pin A0 Potentiometer ✓ Calculate RPS (round per second) ✓ Calculate frequency of CKP ✓ Calculate interrupt frequency ✓ Calculate TOP value (ICR1) and update Microcontroller Frequency diagram Timing diagram of timer 1 T INTERRUPT Microcontroller CKP_array[3] CKP_array[67] mber of revolu Missing tooth 35th and tooth 36th Digital Output 1 Calculate RPM CMP_array[102]...[130] [138]...[141] CMP array[0]...[22] Digital Output 2 T_cam2 T_cam1 1______ Algorithm of main program Algorithm of Timer 0 Start TIMERO INTERUPT SERVICE ROUTINE Setup Timer/Counter1, GPIO f ADC = 1 TIMERO INTERUPT SERVICE ROUTINE ISR(TIMER0 COMPA VECT) f ADC = 0 ++_count_ADC Read A0 channel Calculate ne(RPM) Calculate crankshaft and ++ count ADC camshaft position TIMER1 INTERUPT SERVICE ROUTINE **FALSE** Calculate F ne (RPS) TRUE Calculate F tooth (Frequency of CKP) Calculate F INTERRUPT desired count ADC = 0 $f_ADC = 1$ Calculate TOP value (ICR1) and update ICR1 Return 1 > 0 END Algorithm of Timer 1 ISR(Timer1_OVF_vect) f CKP array = CKP array[CKP count] ++ CKP_count CKP_count ==72 True CKP_count = 0 TIMER1 INTERUPT SERVICE ROUTINE digitalWrite(4, f CKP array) f CMP array = CMP array[CMP count]

V. DISCUSSION AND CONCLUSION

++ CMP count

CMP_count ==144

CMP_count = 0

digitalWrite(7, f CKP array)

True

DISCUSSION

From observation between simulated signal and actual signal of Crankshaft and Camshaft. For any change of speed, we completely generate digital output of crankshaft and camshaft without any deviation, 100% accuracy

CONCLUSION

Through simulating the signal of crankshaft and camshaft position sensor, we have better understanding of how the sensor works and basic usage of Proteus and Arduino software

Thanks to these programs, it helps to satisfy the following conditions:

Simulate speed of crankshaft and camshaft
Calculate desired frequency
Generate two digital output signal for crankshaft and
camshaft