



**HO CHI MINH UNIVERSITY OF TECHNOLOGY
FACULTY OF TRANSPORTATION ENGINEERING
DEPARTMENT OF AUTOMOTIVE AND ENGINE**

GRADUATION THESIS
**STUDY ON AUTOMOTIVE PUSH-ROD
SUSPENSION SYSTEM**

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INSTRUCTOR:

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DATE:

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- 1 Introduction
- 2 Key problems
- 3 Implementation process
- 4 Result and disscussion
- 5 Conclusion and future work

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- 1** Introduction
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 - 5** Conclusion and future work
- 1.1** Suspension system
 - 1.2** Suspension components
 - 1.3** Technical characteristics
 - 1.4** Thesis objectives & limitations

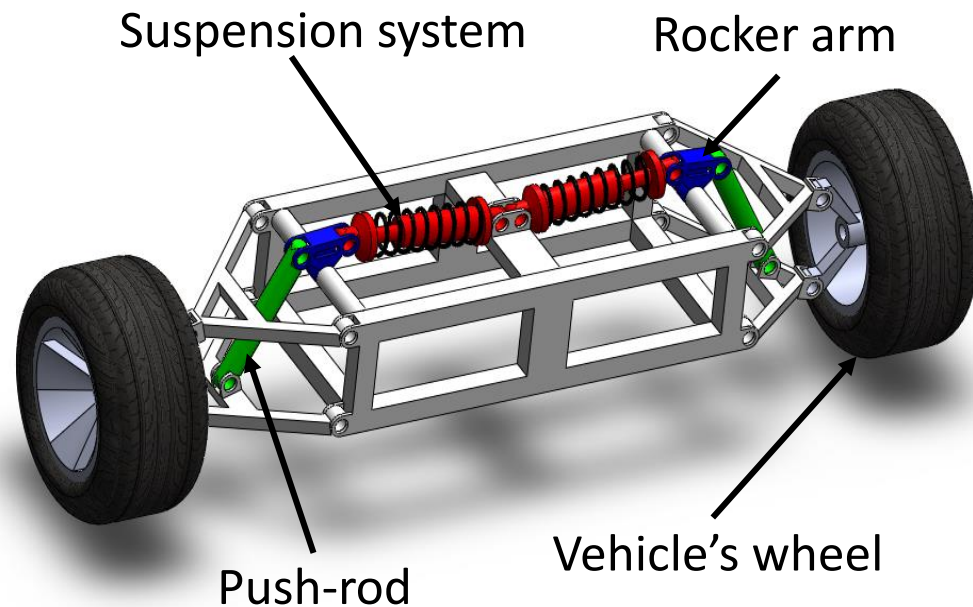


Fig 1: Push-rod suspension system

Suspension system: connects the wheels to vehicle body, allows relative motions.

Primary function of the suspension system:

- Isolating the **roughness** between **road and the vehicle chassis**
- Keep the wheel in **proper position** (wheel alignment)
- **Stable** in **rapid cornering** without body roll
- Keep the tires in **contact** with the road surface
- **Support the weight** of the vehicle

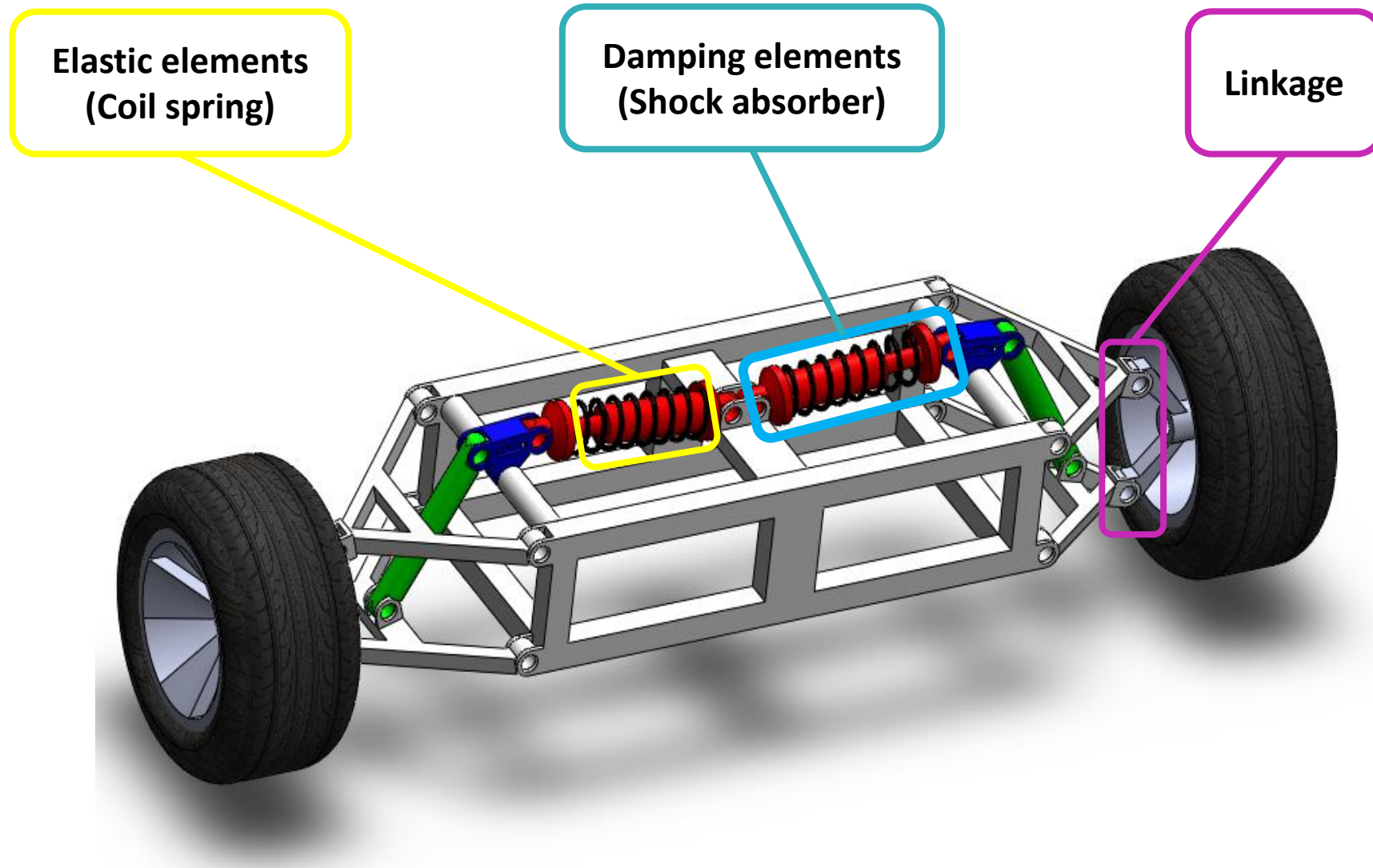


Fig 2: Push-rod suspension system components

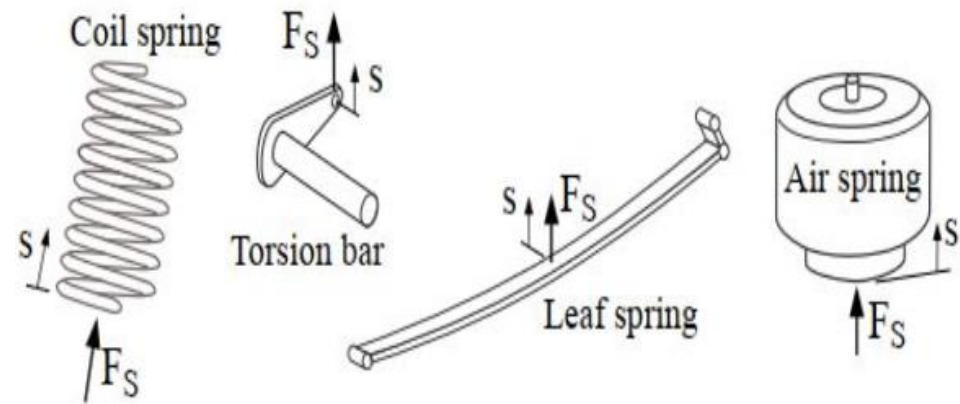


Fig 3: Type of springs

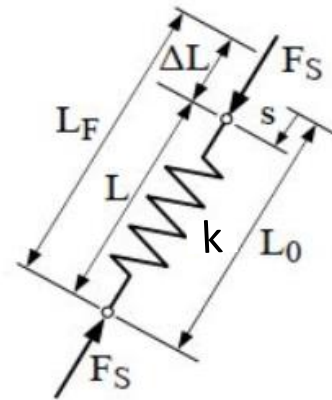


Fig 4: Coil spring parameters

Elastic element:

- Support vehicle weight
- Absorb vibration energy
- $F_k = -k(L_f - L)$

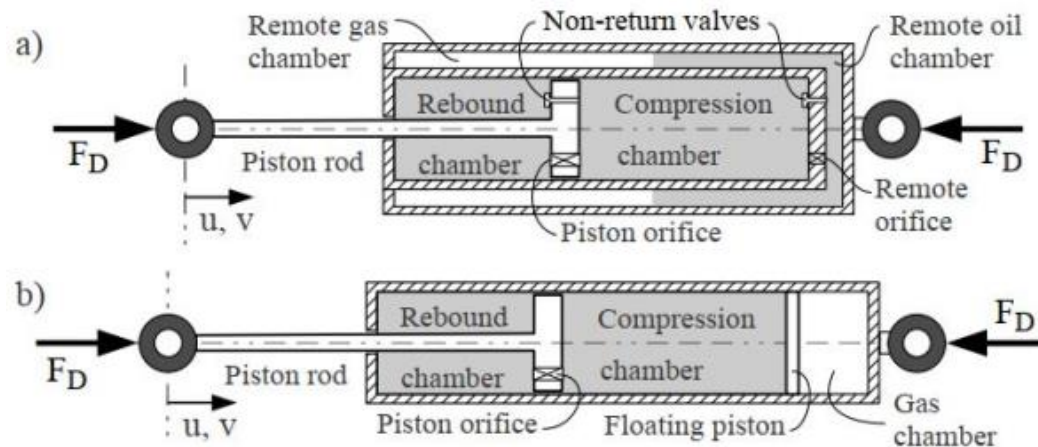


Fig 5: Twin-tube (a) and mono-tube (b) dampers

Damping element:

- Dissipate vibration energy
- $F_c = -c \times v$

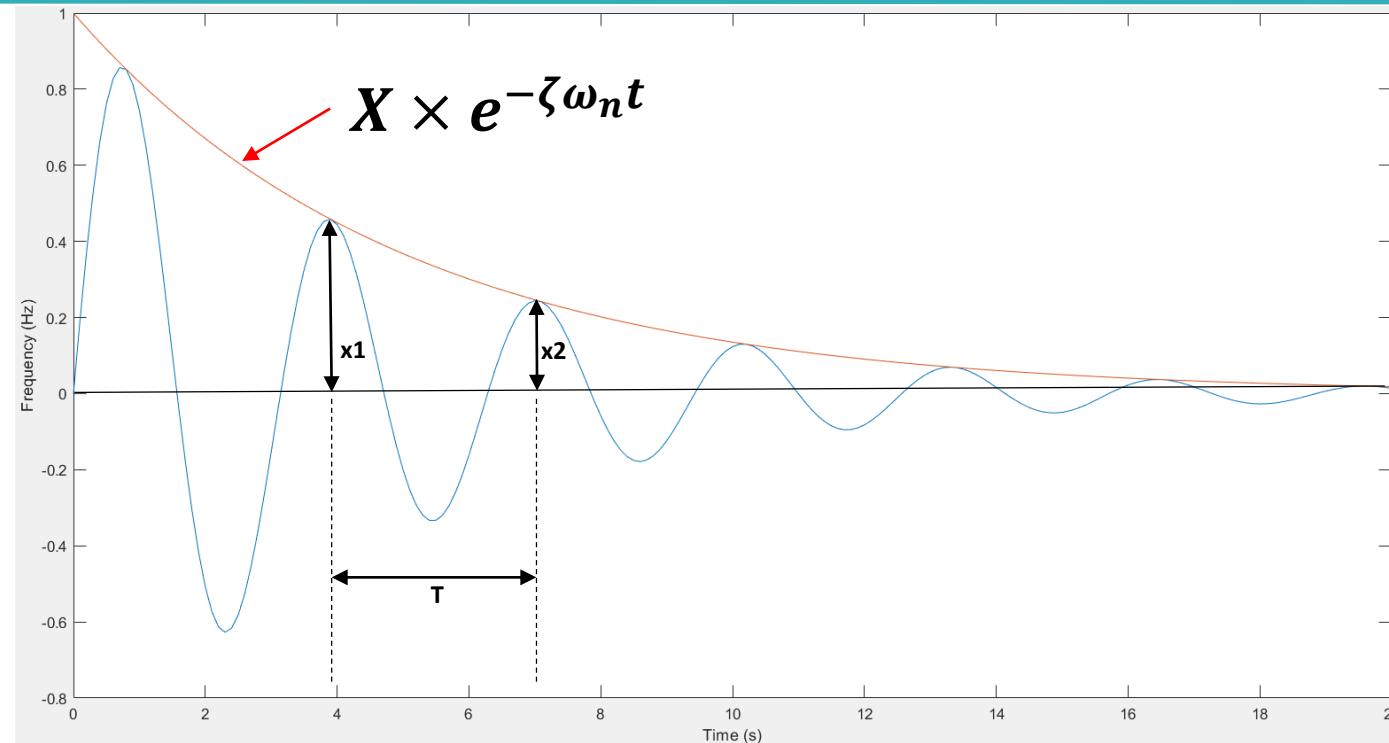


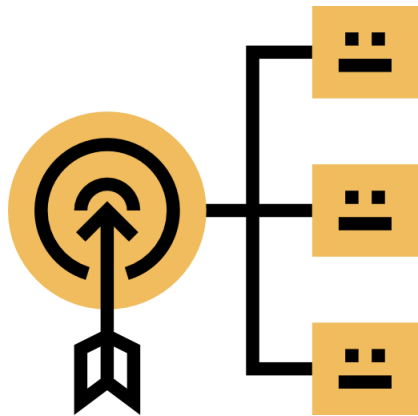
Fig 6: Underdamped characteristics curve

Natural frequency: $f_n = \frac{1}{T}$ — Vehicle body supported by main suspension: **0.2 – 2 Hz**
 The un-sprung mass: **2 – 20 Hz**

Damping ratio: $\zeta = \frac{1}{\sqrt{1 + \left(\frac{2\pi}{\delta}\right)^2}}$ where $\delta = \ln \frac{x_1}{x_2}$

→ $0 < \zeta < 1$ (Underdamped)

Thesis's objectives:



- Relationship between the wheel displacement and the Suspension travel
- The Spring stiffness and the Damping coefficient
- The change in Camber angle and sliding range of the tire

Idea:

Compare with the Conventional suspension system under the same conditions:

- Natural frequency
- Damping ratio

Hypothesis:

- Neglect the tire's stiffness and sliding friction between tire and road
- Use vehicle's mass of the conventional suspension system

Limitations:

- Not evaluate the frequency-weighted acceleration to calculate how intensive vibrations affect human body

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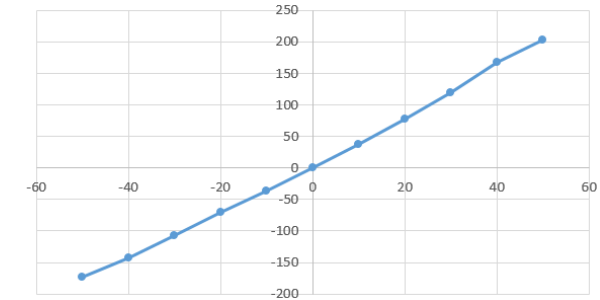
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2.1 Kinematic problem

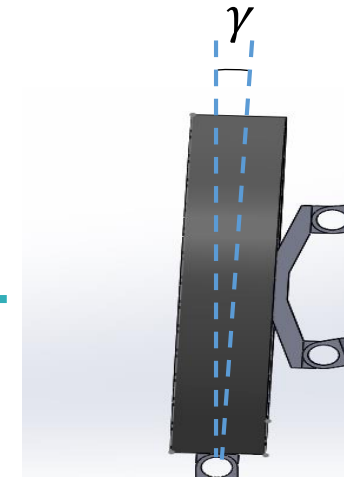
2.2 Dynamic problem

Kinematic
problems

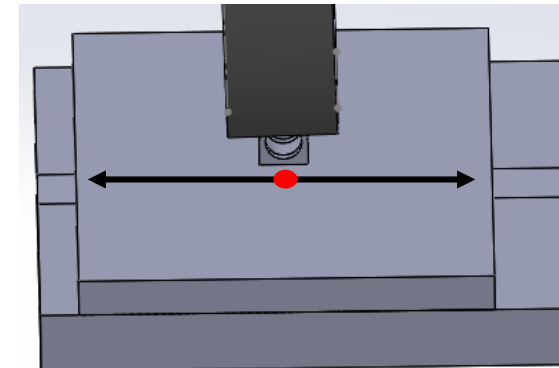
Relationship between **wheel displacement** and **suspension travel**

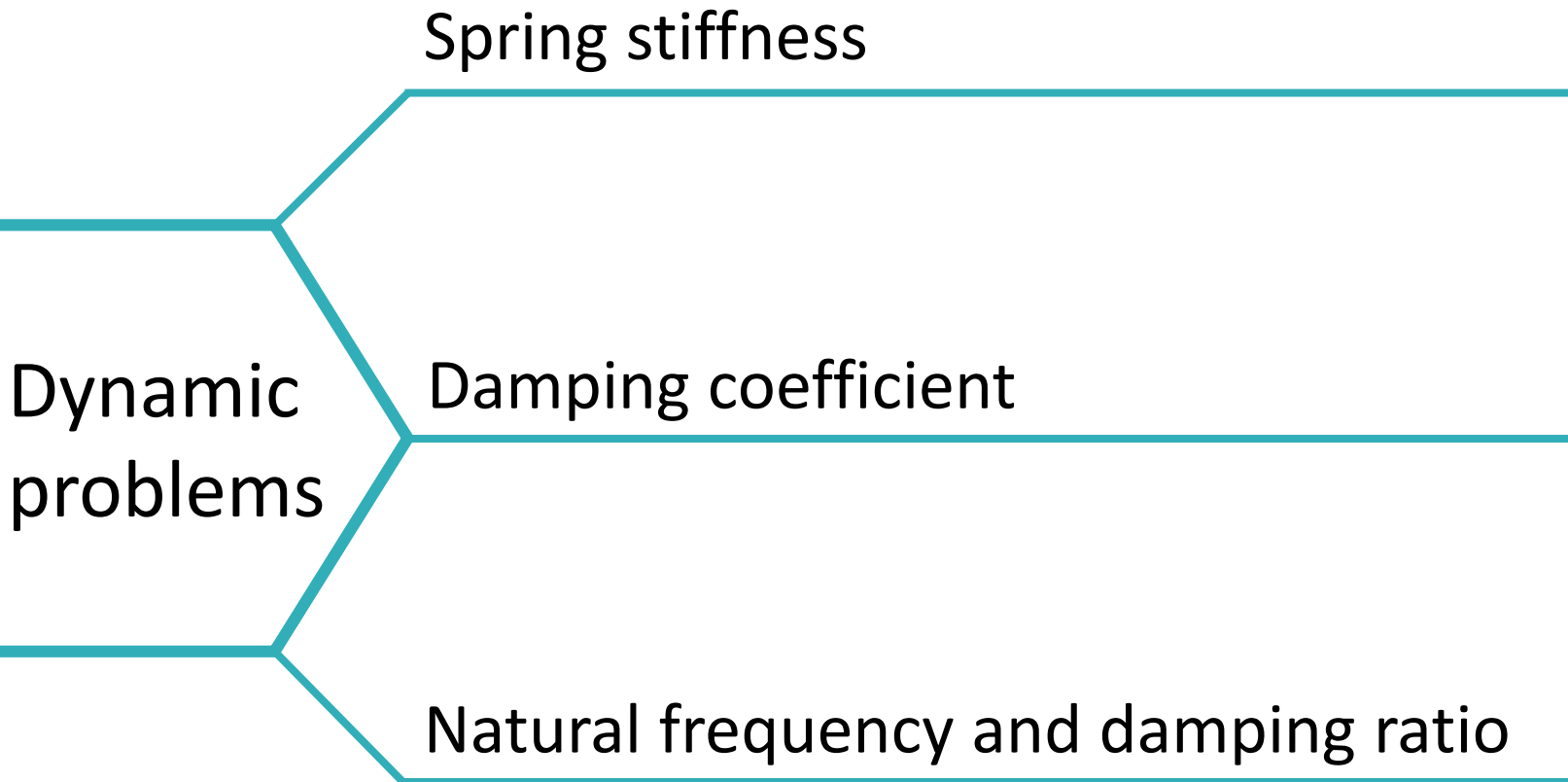


The change in **camber angle**



Sliding range between road and tire





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- 3** **Implementation process**
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- 3.1** Build 3D model on SolidWorks
- 3.2** Simulate on Matlab/Multibody
- 3.3** Road profile simulation
- 3.4** Calculation flow

3. IMPLEMENTATION PROCESS

3.1 Build 3D model on SolidWorks

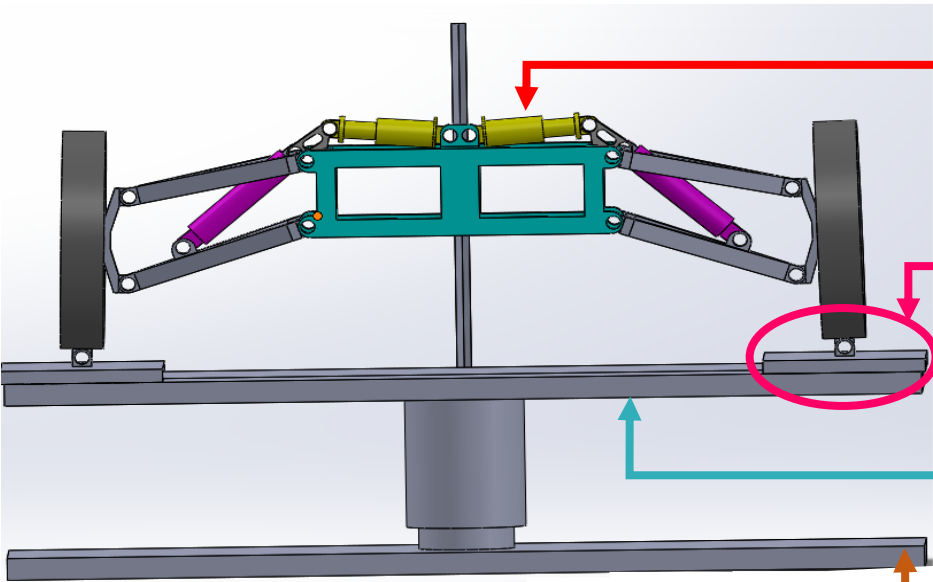


Fig 7: 3D model of Push-rod suspension system

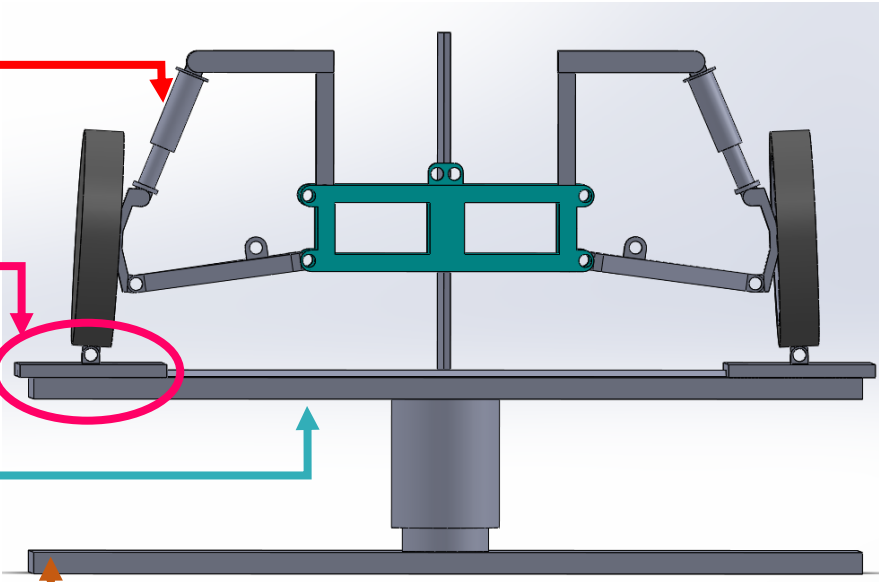


Fig 8: 3D model of Conventional suspension system

Spring and damper

Camber angle and sliding of tire

Translational base

Fix base

Parameters	Unit	Meaning	Value
m_{s_1}	Kg	Sprung weight (1/3 load)	574
m_{s_2}	Kg	Sprung weight (2/3 load)	706
m_{s_3}	Kg	Sprung weight (full load)	840
m_u	Kg	Unsprung weight	80
k_s	N/m	Spring stiffness	28566
c_s	Ns/m	Damping coefficient	2090

Table 1: light truck suspension parameters
(Source: Vibration analysis of a light truck by 3d dynamic vehicle vibration model by Mr. Truong Hoang Tuan, Dr. Tran Huu Nhan and Mr. Tran Quang Lam.)

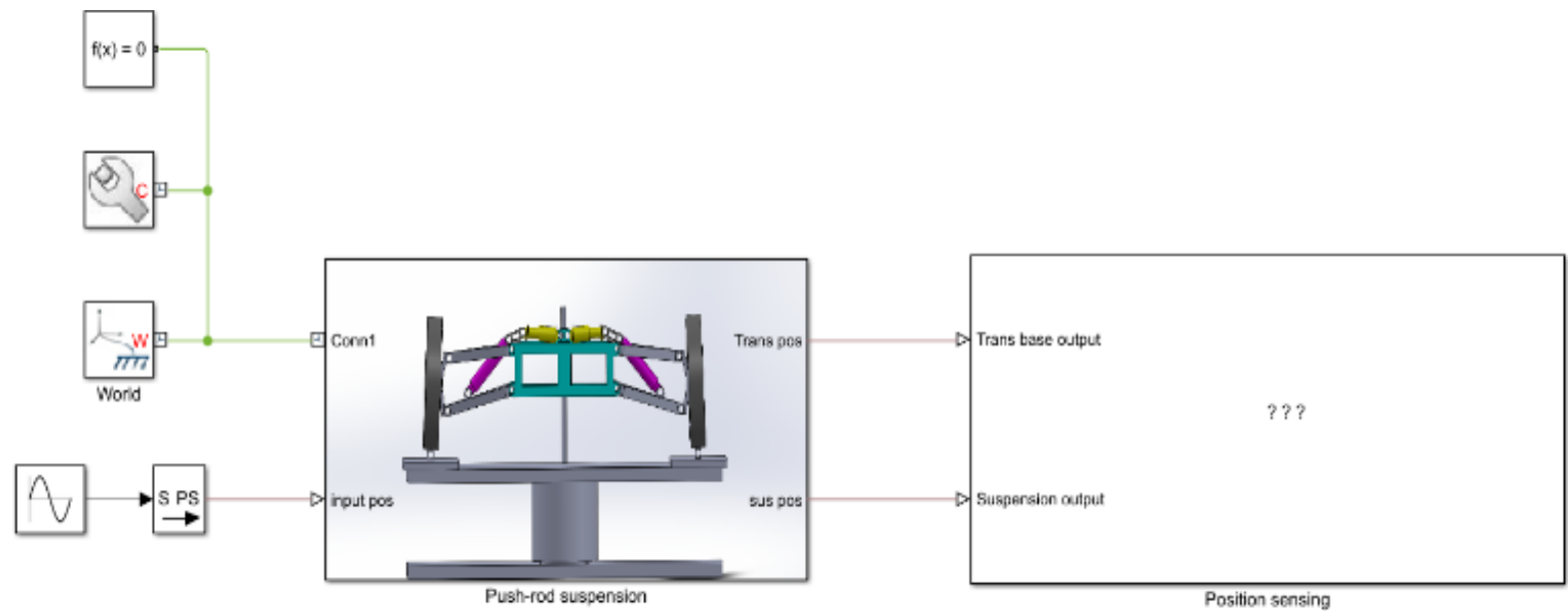


Fig 9: Simulation model in Matlab/ Multibody environment

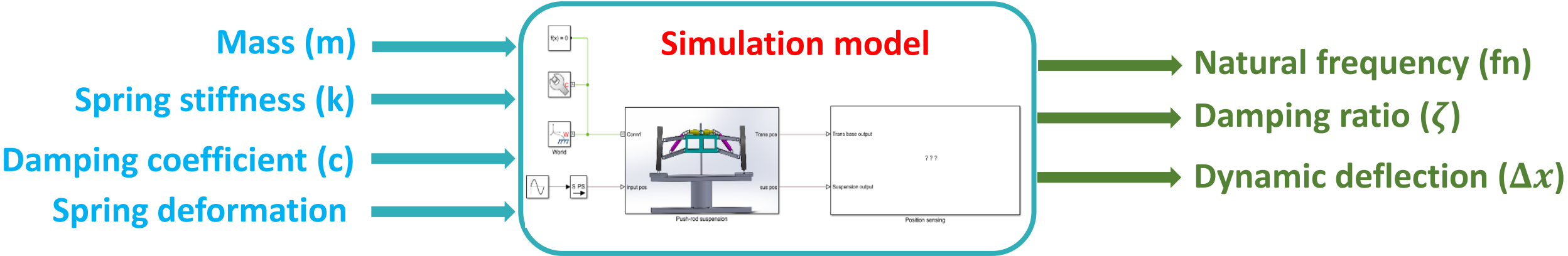


Fig 10: Simulation input and output parameters

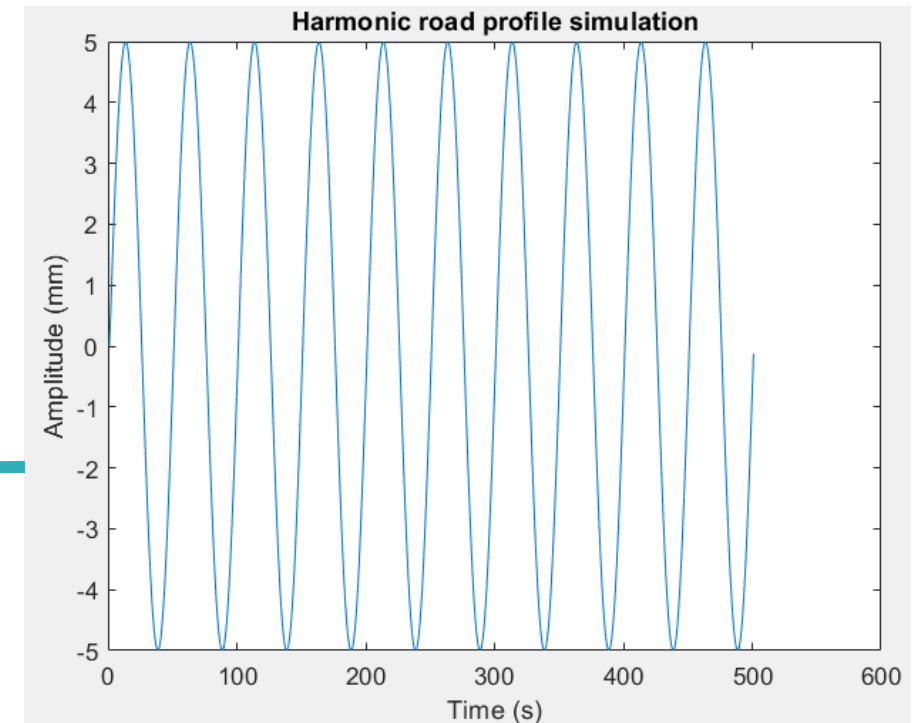
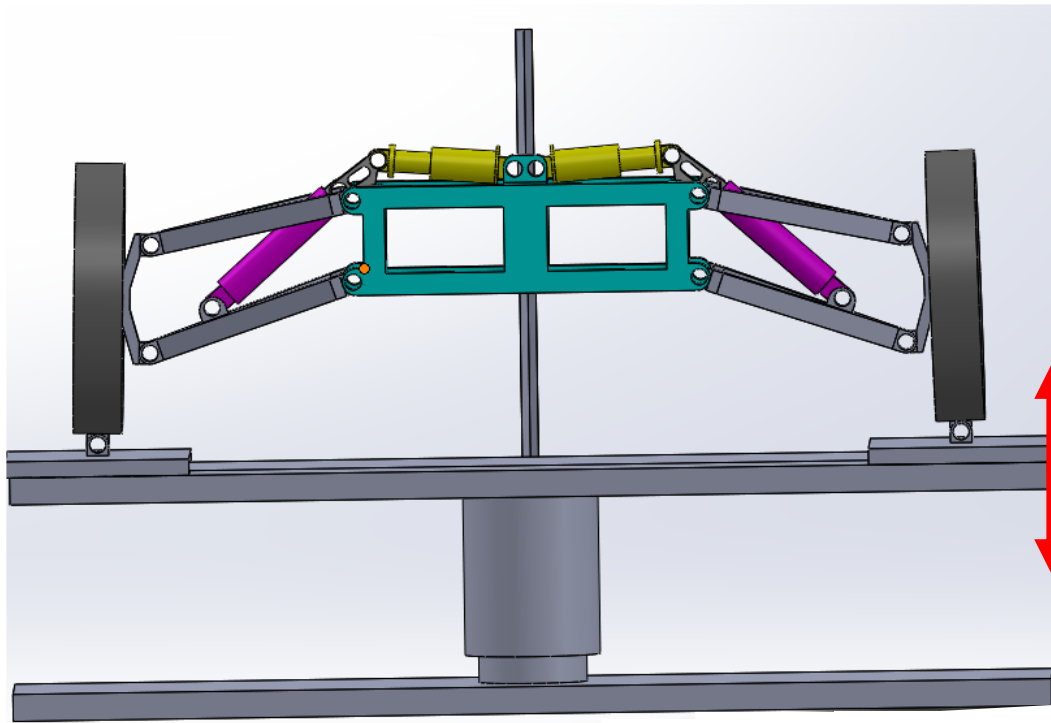


Fig 11: Harmonic road profile simulation on Matlab/ Multibody

Using **harmonic road profile** to find

- Natural frequency of the simulation model
- The Gain response spectrum

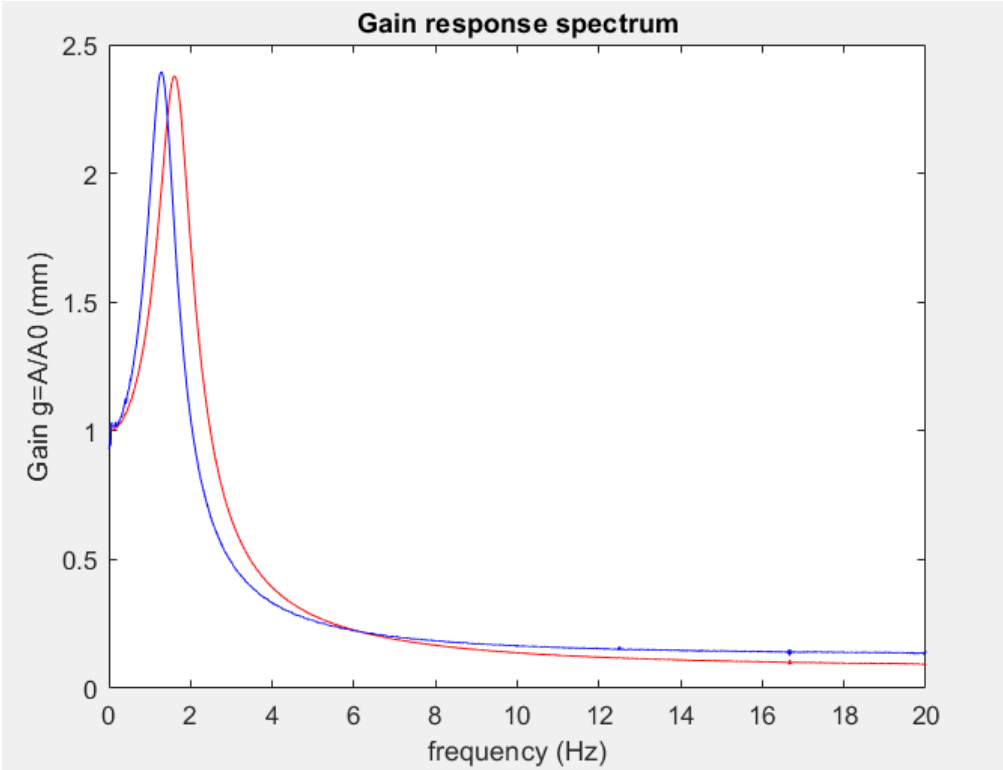
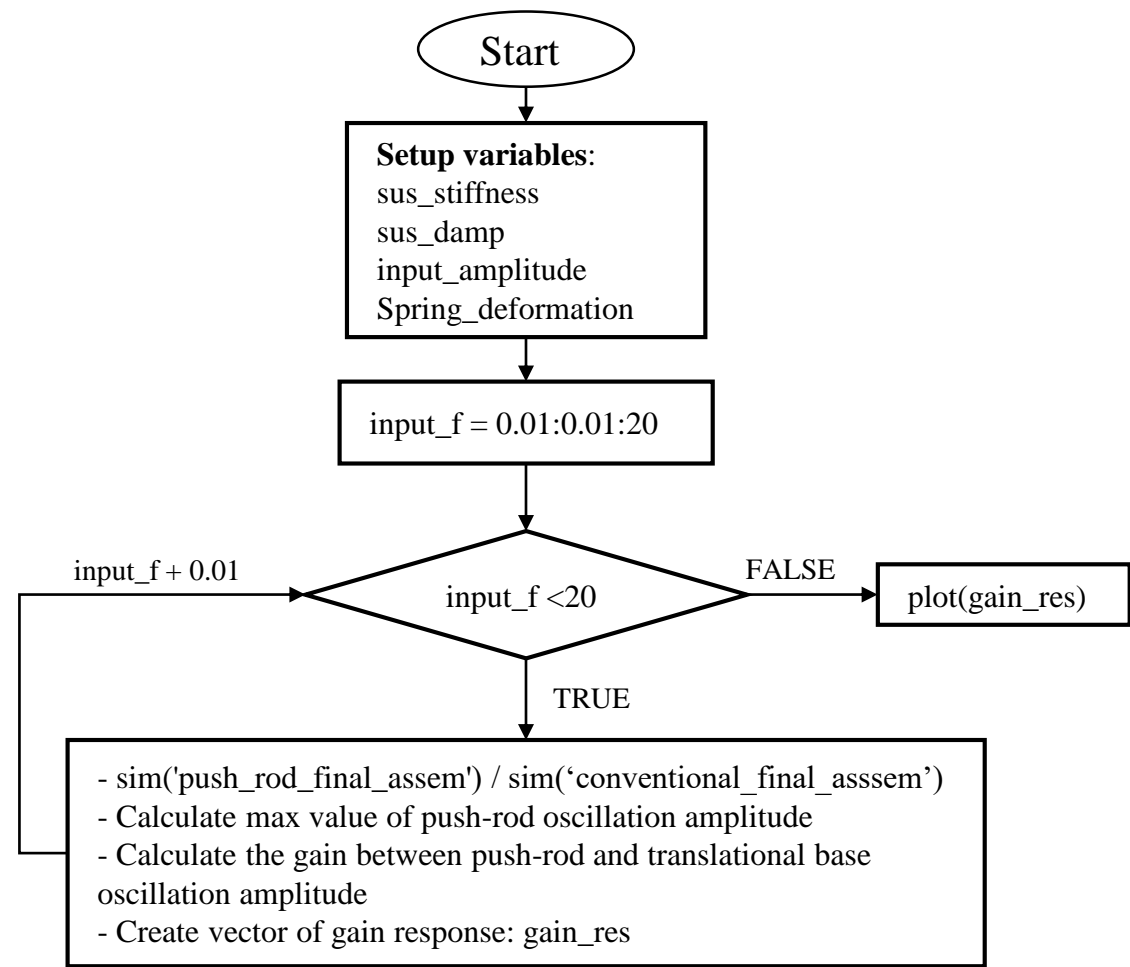


Fig 12: Calculation flowchart of the simulation model

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- 4.1** Relationship between wheel displacement and suspension travel
- 4.2** Change in wheel alignment and sliding gain
- 4.3** Gain response spectrum

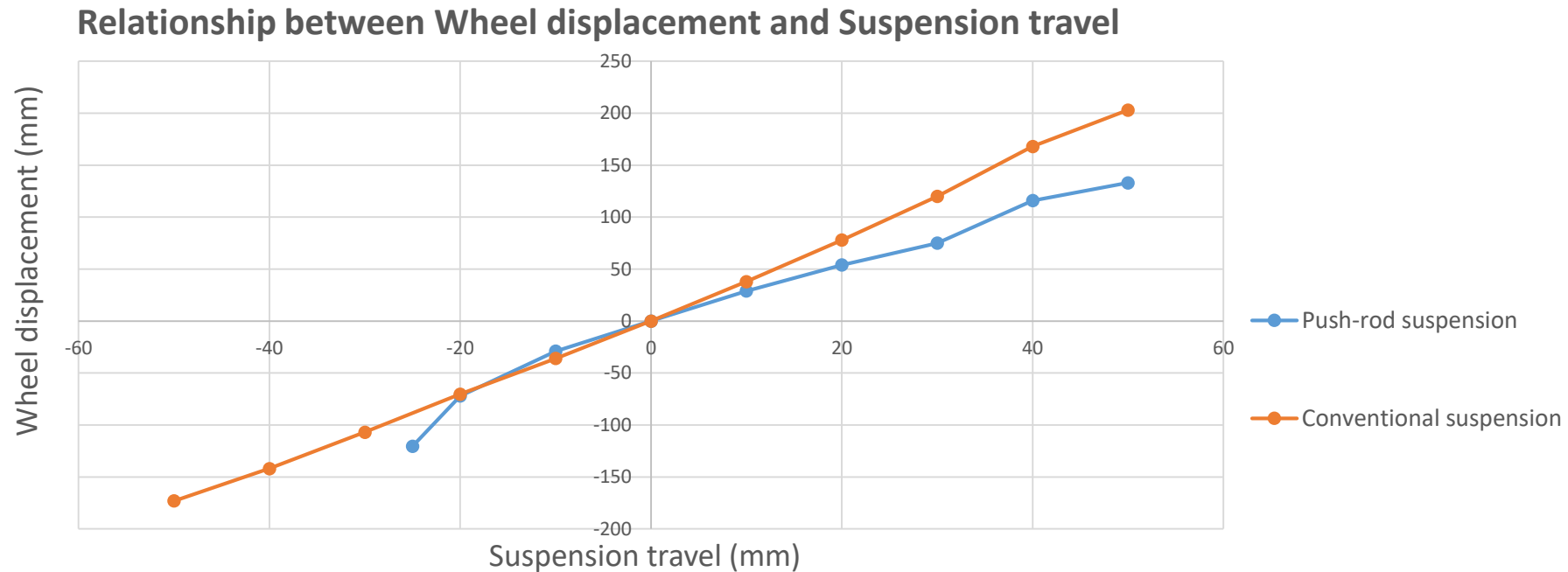


Fig 13: Relationship between wheel displacement and suspension travel curve

- Suspension travel of the Push-rod suspension system is **25 mm shorter** than Conventional suspension
→ **Use shorter suspension system**
- Maximum and minimum wheel displacement of Push-rod suspension is **70mm and 50mm lower** than Conventional suspension respectively
→ **Decrease the dynamic deflection, reduce the movement of vehicle's body**

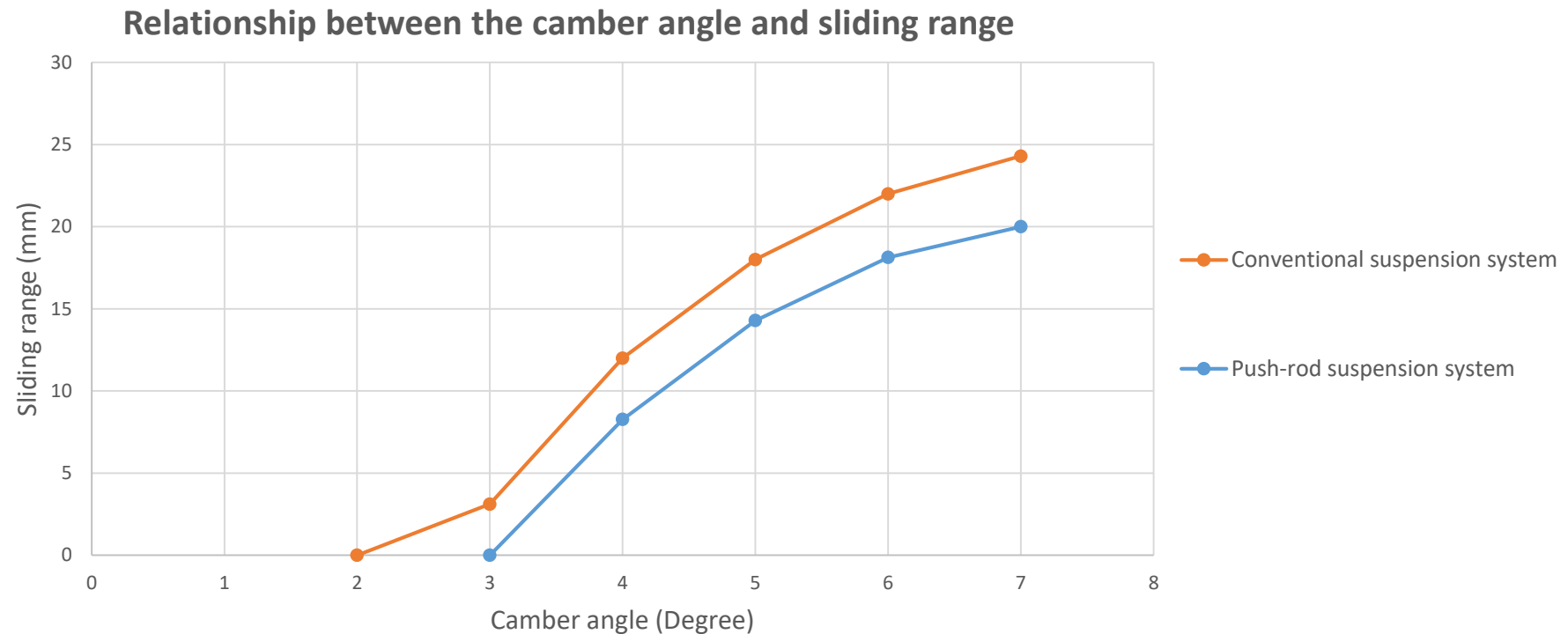


Fig 14: Relationship between change in camber angle and tire's sliding range curve

- Camber angle of both suspension system vary from 2° to 7°
- The sliding rang of the tire of the Push-rod suspension system is always lower when the camber angle change, about **4 mm lower**
 → **Less tire slip compared with the conventional suspension system**

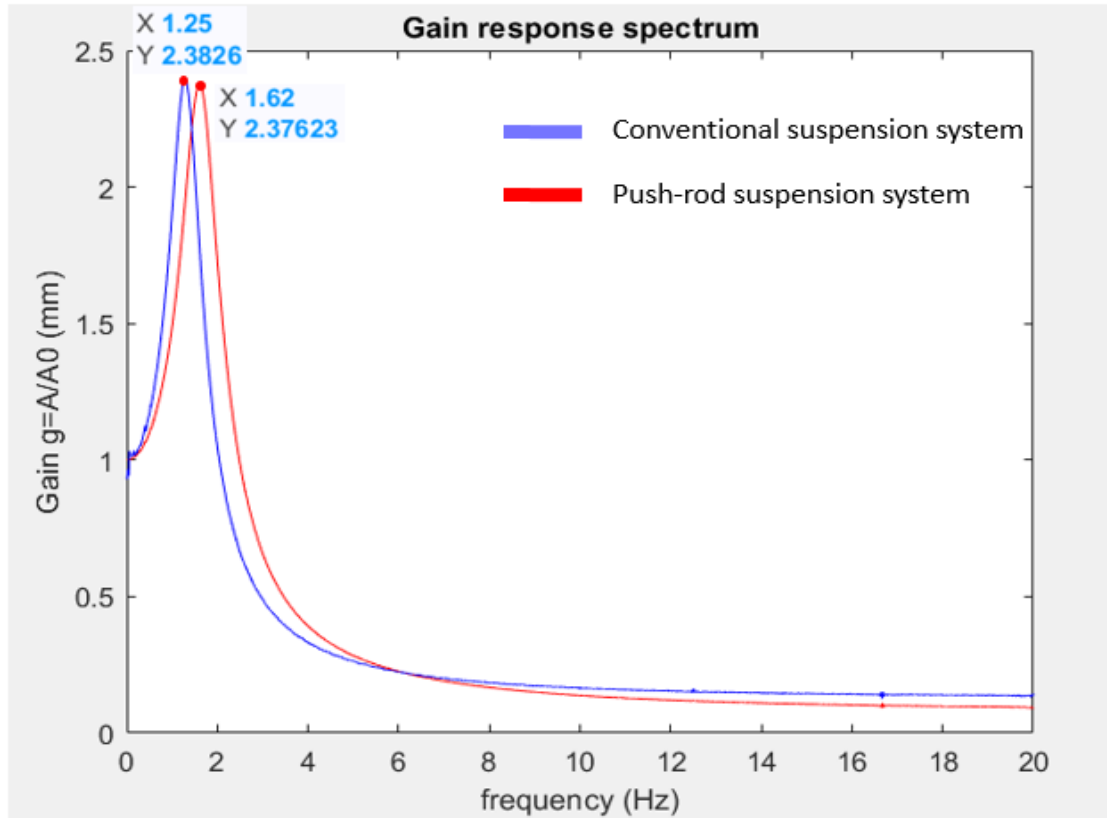


Fig 15: Gain response spectrum of 1/3 load condition

1/3 load: $m = 574 \text{ kg}$

Natural frequency:

- Push-rod: $f_n = 1.62 \text{ Hz}$
- Conventional: $f_n = 1.25 \text{ Hz}$

Damping ratio: $\zeta = 0.259$

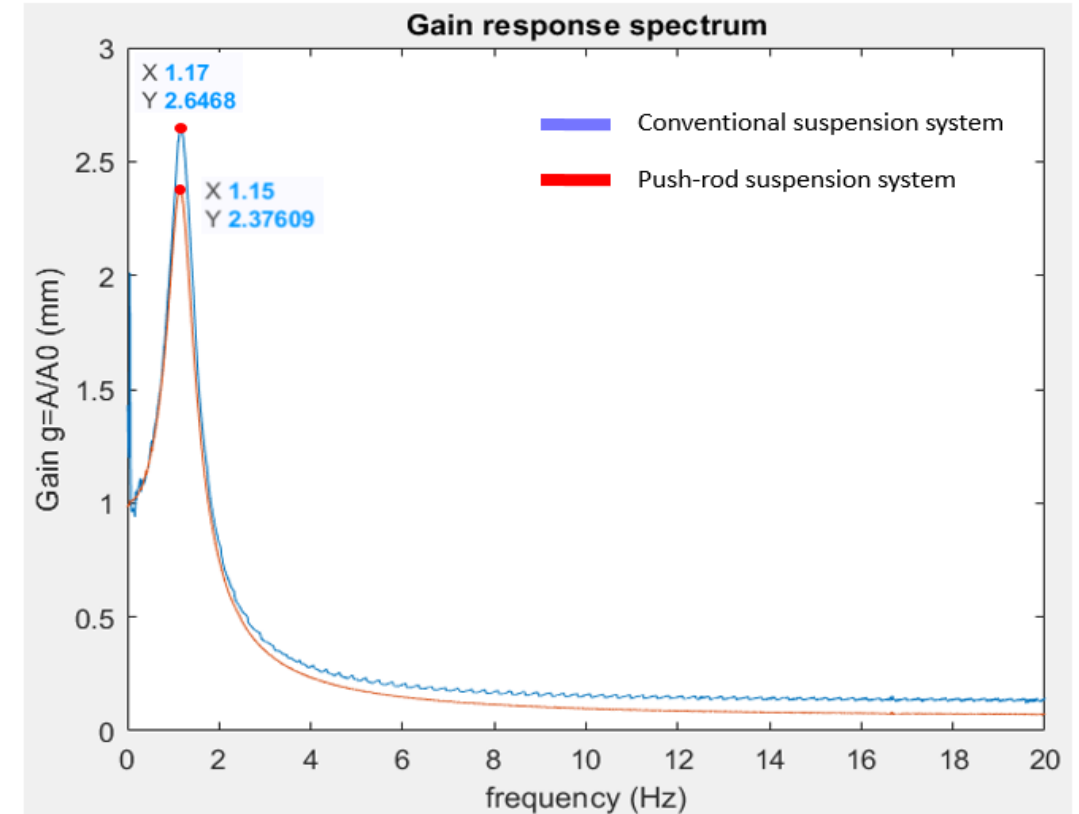


Fig 16: Gain response spectrum of 2/3 load condition

2/3 load: $m = 706 \text{ kg}$

Natural frequency:

- Push-rod: $f_n = 1.15 \text{ Hz}$
- Conventional: $f_n = 1.17 \text{ Hz}$

Damping ratio: $\zeta = 0.249$

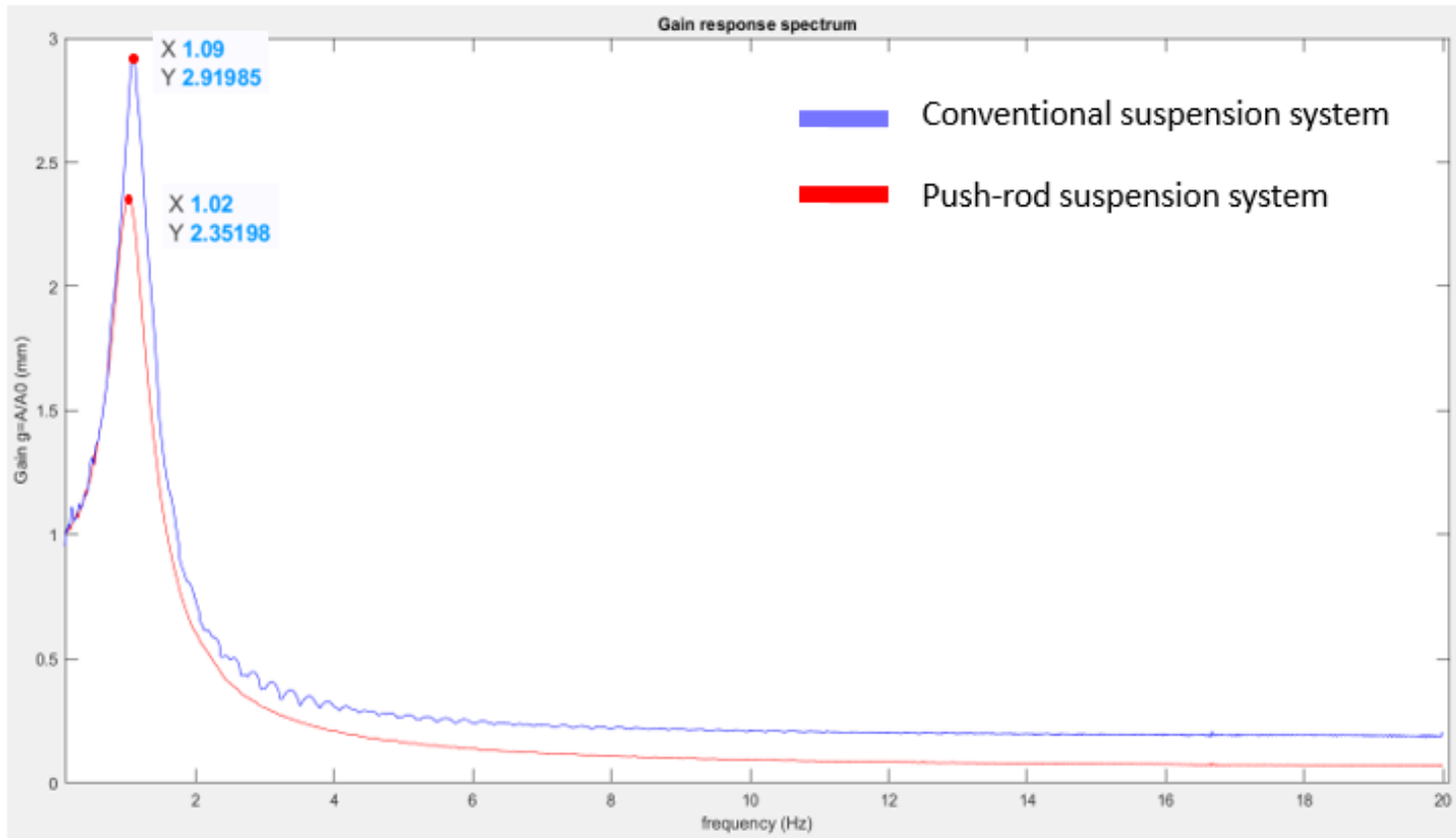


Fig 17: Gain response spectrum of full load condition

Full load: $m = 840 \text{ kg}$

Natural frequency:

- Push-rod: $f_n = 1.09 \text{ Hz}$
- Conventional: $f_n = 1.02 \text{ Hz}$

Damping ratio: $\zeta = 0.274$

	1/3 Load		2/3 load		Full load	
Suspension	Push-rod	Conventional	Push-rod	Conventional	Push-rod	Conventional
Natural frequency	1.62	1.25	1.15	1.17	1.02	1.09
Damping ratio	0.259	0.259	0.249	0.249	0.274	0.274

Table 2: Natural frequency and damping ratio of Push-rod and Conventional suspension system with different load condition

	Push-rod	Conventional	Difference
Spring stiffness (N/m)	36500	28566	1.27 times
Damping coefficient (Ns/m)	3034	2090	1.45 times

Table 3: Spring stiffness and damping coefficient of Push-rod and Conventional suspension system

- When the load **increases from 1/3 to full load** → the Natural frequency **decreases moderately** and the damping ratio **fluctuate from 0.249 to 0.274**
- The Spring stiffness and Damping coefficient of the Push-rod suspension system is **1.27 times** and **1.45 times greater** than Coventional suspension system respectively
→ **Use a spring with higher stiffness**

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- 2 Method and core solution
- 3 Implementation process
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5. CONCLUSION & FUTURE WORK

CONCLUSION

- Push-rod suspension has **more linkage components**
- **Shorter** suspension travel and movement of vehicle's body
- Spring stiffness and damping coefficient is **greater** than conventional suspension system
- Simulation method compared with calculus method:
 - Combination of **vertical and horizontal direction**
 - Use various linkage components in the simulation model
- Advantages of Push-rod suspension:
 - **Better aerodynamic** by optimizing the push-rod design
 - More stable when **heavy cornering**

FUTURE WORKS

- Optimize the design of Push rods and the rocker arms.
- Study the relationship between ride comfort and handling of vehicle. To achieve this, a 3D suspension model is utilized to consider the vehicle rotational motions.
- Evaluate the frequency-weighted acceleration to calculate how intensive vibrations affect human body

References

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Thank You

