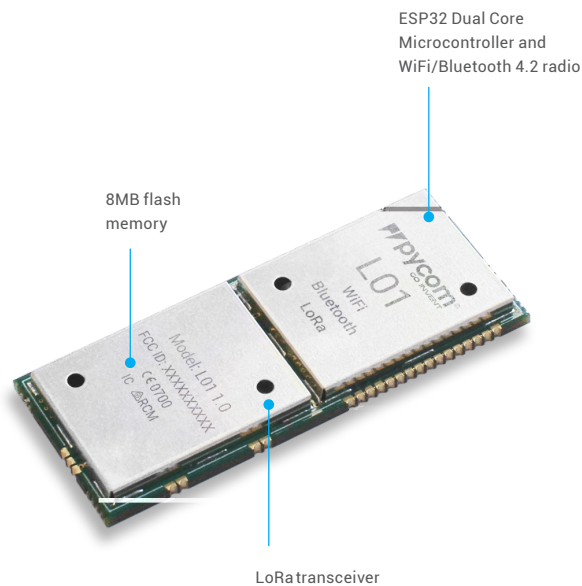


LO1

Datasheet
Version 1.0

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Size
40mm x 16mm x 2.7mm

Operating temperature
-40 to +85 °C

1.0 Overview

With LoRa, Wifi and BLE, the L01 OEM Module is the only triple bearer MicroPython enabled micro controller on the market today – the perfect enterprise grade IoT platform for your connected Things. With the latest Espressif chipset the L01 offers a perfect combination of power, friendliness and flexibility. Create and connect your things everywhere. Fast.

2.0 Features

- Powerful CPU, BLE and state of the art WiFi radio. 1KM Wifi Range
- Can also double up as a Nano LoRa gateway
- MicroPython enabled
- Can be directly surface mount inside your product like a regular component
- Ultra-low power usage: a fraction compared to other connected micro controllers

3.0 Specifications

3.1 CPU

- Xtensa® dual-core 32-bit LX6 microprocessor(s), up to 600 DMIPS
- Hardware floating point acceleration
- Python multi-threading
- An extra ULP-coprocessor that can monitor GPIOs, the ADC channels and control most of the internal peripherals during deep-sleep mode while only consuming ~25uA.

3.2 Memory

- RAM: 520KB + 4MB
- External flash: 8MB

3.3 WiFi

- 802.11b/g/n 16mbps

3.4 Bluetooth

- Low energy and classic

3.5 LoRa

- LoRaWAN 1.0.2 stack - Class A and C devices
- Node range: Up to 40km
- Nano-gateway: Up to 22km (Capacity up to 100 nodes)

3.6 RTC

- Running at 150kHz

3.7 Security

- SSL/TLS support
- WPA Enterprise security

3.8 Hash / encryption

- SHA
- MD5
- DES
- AES

4.0 Block Diagram

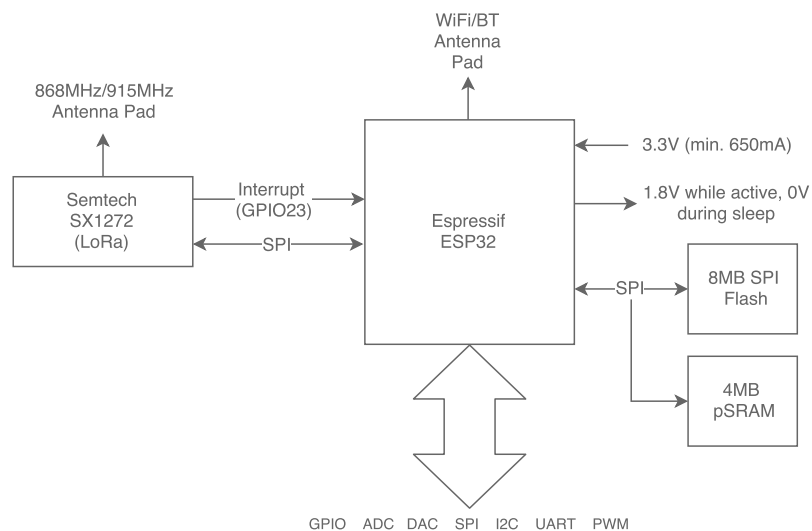


Figure 1 – System block diagram

5.0 Pinout

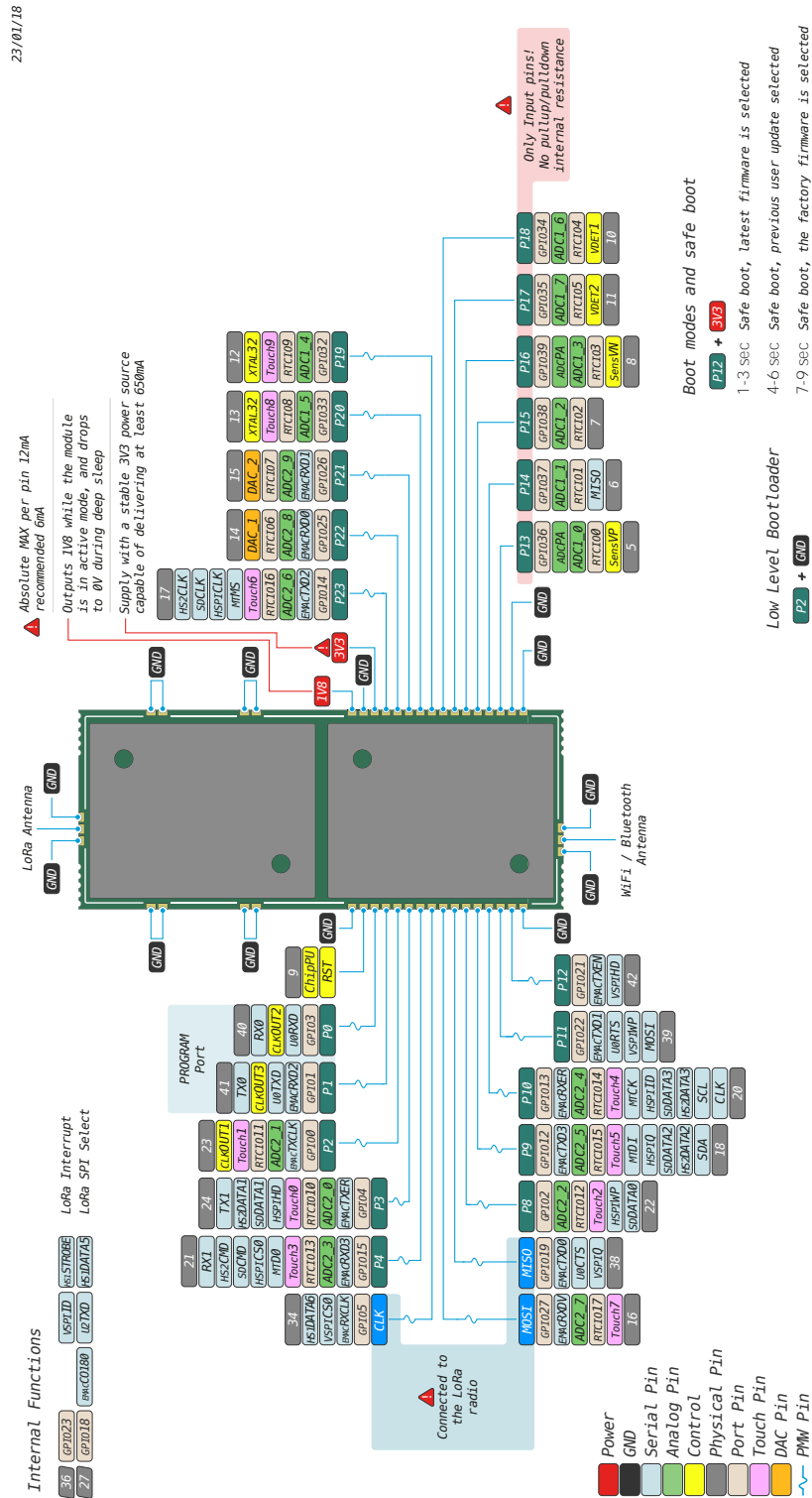


Figure 2 – Module pinout diagram

Note: The ESP32 supports remapping its peripherals to alternative pins. See below for a detailed list.

6.0 Pin Details

Table 1 – Module pinout

| Module Pin | ESP32 GPIO | Pin Name | Default Function | ADC | PWM | RTC† | Notes |
|------------|------------|----------|-----------------------|-----|-----|------|---|
| 1 | – | – | Ground | | | | |
| 2 | – | – | Ground | | | | |
| 3 | – | – | Ground | | | | |
| 4 | – | – | Ground | | | | |
| 5 | – | – | Ground | | | | |
| 6 | – | – | Reset | | | | Active Low |
| 7 | 3 | P0 | RX0 (Programming) | | • | | Used by the bootloader and to program the module |
| 8 | 1 | P1 | TX0 (Programming) | | • | | Used by the bootloader and to program the module |
| 9 | 0 | P2 | | 2* | • | • | If tied to GND during boot the device will enter bootloader mode |
| 10 | 4 | P3 | TX1 | 2* | • | • | |
| 11 | 15 | P4 | RX1 | 2* | • | • | JTAG TDO, SD card CMD |
| 12 | 5 | – | LoRa radio SPI CLK | | • | | Not recommended for external use |
| 13 | 27 | – | LoRa radio SPI MOSI | 2* | • | • | Not recommended for external use |
| 14 | 19 | – | LoRa radio SPI MISO | | • | | Not recommended for external use |
| 15 | 2 | P8 | | 2* | • | • | SD card DAT0 |
| 16 | 12 | P9 | SDA | 2* | • | • | JTAG TDI |
| 17 | 13 | P10 | SCL (I2C) / CLK (SPI) | 2* | • | • | JTAG TCK |
| 18 | 22 | P11 | MOSI | | • | | |
| 19 | 21 | P12 | MISO | | • | | If tied to 3.3V during boot the device enters safe boot mode, JTAG MISO |

6.0 Pin Details

Table 1 – Module pinout

| Module Pin | ESP32 GPIO | Pin Name | Default Function | ADC | PWM | RTC† | Notes |
|------------|------------|----------|------------------|-----|-----|------|--|
| 20 | – | – | Ground | | | | |
| 21 | – | – | Ground | | | | |
| 22 | – | – | WiFi/BT antenna | | | | 50 Ohm impedance required |
| 23 | – | – | Ground | | | | |
| 24 | – | – | Ground | | | | |
| 25 | – | – | Ground | | | | |
| 26 | 36 | P13 | | 1 | | • | Input only |
| 27 | 37 | P14 | | 1 | | • | Input only |
| 28 | 38 | P15 | | 1 | | • | Input only |
| 29 | 39 | P16 | | 1 | | • | Input only |
| 30 | 35 | P17 | | 1 | | • | Input only |
| 31 | 34 | P18 | | 1 | | • | Input only |
| 32 | 32 | P19 | | 1 | • | • | |
| 33 | 33 | P20 | | 1 | • | • | Connected to the on-board RGB LED |
| 34 | 26 | P21 | | 2* | • | • | DAC |
| 35 | 25 | P22 | | 2* | • | • | DAC |
| 36 | 14 | P23 | | 2* | • | • | JTAG TMS, SD card SCLK |
| 37 | – | – | 3.3V input | | | | This supply should be able to source 650mA |
| 38 | – | – | Ground | | | | |
| 39 | – | – | 1.8V Output | | | | Only when the device is active, during deep sleep this drops to 0V |

6.0 Pin Details

Table 1 – Module pinout

| Module Pin | ESP32 GPIO | Pin Name | Default Function | ADC | PWM | RTC† | Notes |
|------------|------------|----------|------------------|-----|-----|------|------------------------|
| 40 | – | – | Ground | | | | |
| 41 | – | – | Ground | | | | |
| 42 | – | – | Ground | | | | |
| 43 | – | – | Ground | | | | |
| 44 | – | – | Ground | | | | |
| 46 | – | – | Ground | | | | |
| – | 36 | | | | | | LoRa radio interrupt |
| – | 35 | | | | | | LoRa radio chip select |

† The pins on the RTC power domain can be used during deep sleep, specifically GPIO pins will maintain their state while in deep sleep.

* ADC2 is currently not supported in the micropython firmware

6.1 Remapping Pins

The ESP32 features comprehensive pin remapping functionality. This allows peripherals to be mapped onto almost any available GPIO pins. The above table merely shows the default assignments. For example, the default mapping has the SPI and I2C clocks overlapping, meaning both cannot be used simultaneously without remapping one to a different pin. For a detailed guide of what peripheral can be assigned to what pins please read “Appendix A – ESP32 Pin Lists” of the ESP32 datasheet.

7.0 ESP32 Peripherals

Table 2 – Peripherals

| Peripheral | Count | Pins |
|------------|-------|--|
| UART | 3 | Remappable to any GPIO. Note: P13–18 can only be mapped to RX or CTS since they are input only. |
| I2C | 2 | Remappable to any GPIO except P13–18 since they are input only and I2C is bi-directional. |
| SPI | 3 | Remappable to any GPIO. Note: P13–18 can only be mapped to MISO since they are input only. |
| CAN* | 1 | Remappable to any GPIO. Note: P13–18 can only be mapped to RX since they are input only. |
| JTAG | 1 | TDO = P4, TDI = P9, TCK = P10, TMS = P24 |
| PWM | 1 | All GPIO except P13–18 which are input only |
| ADC | 18 | Fixed mapping, see Table 1, Only ADC 1 is supported in our micropython firmware. |
| DAC | 2 | Only available on P21 and P22 |
| SD | 1 | DAT0 = P8, SCLK = P23, CMD = P4 |

* Requires an external CAN bus transceiver, we recommend the SN65HVD230 from Texas Instruments.

For a more detailed description of the ESP32 peripherals along with peripherals not currently supported by our firmware, please check the ESP32 datasheet.

7.1 RTC

Our modules by default all use the internal RC oscillator at 150kHz for the RTC. If you require better accuracy/stability you can connect a 32.768 kHz crystal (or TCXO) externally on pins P19 and P20 (or P19 for a TCXO)

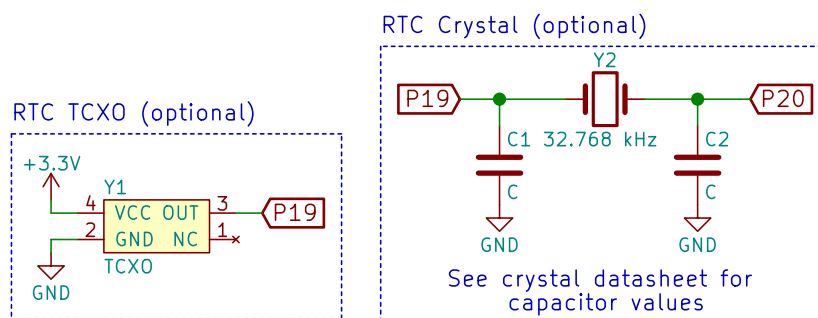


Figure 2 – External RTC crystal circuits

8.0 Programming the device

8.1 UART

By default, the modules run an interactive python REPL on UART0 which is connected to P0 (RX) and P1 (TX) running at 115200 baud. Code can be run via this interactive REPL or you can use our PyMakr plugin for Atom or Visual Studio Code to upload code to the board.

8.2 Wi-Fi

By default, the L01 also acts as a Wi-Fi access point. SSID: lopy-wlan-XXXX
Password: www.pycom.io
Once connected to the L01's Wi-Fi network you can access it in two ways.

8.2.1 Telnet

Running on port 23 is a telnet server. This acts in a very similar way to the UART. It presents you with an interactive REPL and can also be used to upload code via PyMakr.

8.2.2 FTP

The L01 also runs a FTP server that allows you to copy files to and from the device, include an SD card if one is connected. To connect to this FTP server, you need to use plain FTP (un-encrypted) with the following credentials:
User: micro
Password: python

9.0 Boot modes

9.1 Bootloader mode

In order to update the firmware of the L01 device, it needs to be placed into bootloader mode. In order to do this, P2 needs to be connected to ground when the device reboots. Once in bootloader mode you can use the Pycom firmware update tool to update to the latest official firmware. If you are developing your own firmware based on our open-source firmware, a flashing script is provided with the source code.

9.2 Safe boot

The micropython firmware features a safe boot feature that skips the boot.py and main.py scripts and goes straight to the REPL. This is useful if the device is programmed with code that causes the device to crash or become inaccessible. To access this mode, you need to connect P12 to 3.3V and reset the device. Upon entering safe boot mode, the on-board LED will begin to blink orange. Depending on the duration the pin is held at 3.3V, a different firmware will be run.

Table 3 – Boot modes

| 0–3 Seconds | 3–6 Seconds |
|---|--|
| Current firmware without running boot.py or main.py | Previous firmware if the firmware was uploaded via OTA (without running boot.py and main.py) |

10.0 Power

The module requires a single regulated 3V3 power supply. The 1V8 pin is only an output which is enabled whenever the module is in active mode. During deepsleep the 1V8 signal goes low. Do not supply power to the 1V8 pin, and never use this pin as a power supply, only as a control signal.

10.1 Current consumption by power modes/features running at 3.3V

Table 4 – Power consumption by feature

| Mode | Min | Avg. | Max | Units |
|------------------|-----|------|-----|-------|
| Idle (no radios) | – | 33.4 | – | mA |
| LoRa Transmitt† | – | 97.7 | – | mA |
| WiFi AP | – | 107 | – | mA |
| WiFi client | – | 119 | – | mA |
| Bluetooth | – | 104 | – | mA |
| Deep sleep | – | 5.10 | – | µA |

† More details can be found in section 14.2

11.0 Memory Map

11.1 Flash

Table 5 – Flash memory map

| Name | Description | Start address | Size |
|-----------------|---|---------------|----------|
| NVS | Non-volatile RAM area. Used by the NVS API | 0x9000 | 0x7000 |
| Firmware Slot 0 | First firmware slot. Factory firmware is flashed here | 0x10000 | 0x180000 |
| OTA info | Information about the current active firmware | 0x190000 | 0x1000 |
| Firmware Slot 1 | Second firmware slot | 0x1A0000 | 0x180000 |
| File system (1) | 504KB file system on devices with 4MB flash | 0x380000 | 0x7F000 |
| Config | Config area for LoRa, Sigfox and LTE | 0x3FF000 | 0x1000 |
| File system (2) | 4MB file system on devices with 8MB flash | 0x400000 | 0x400000 |

11.2 RAM

Table 6 – RAM memory map

| Name | Description | Size |
|----------------|---|-------|
| On-chip SRAM | Internal RAM memory used by the 2 xtensa CPUs | 520KB |
| Fast RTC RAM | Fast RAM area accessible by the xtensa cores during boot and sleep modes | 8KB |
| Slow RTC RAM | Slow RAM area accessible by the Ultra-Low Power Coprocessor during deep sleep | 8KB |
| External pSRAM | External QSPI RAM memory clocked @ 40MHz | 4MB |

11.3 ROM and eFuses

Table 7 – Miscellaneous memory

| Name | Description | Size |
|-------------|---|-------|
| On-chip ROM | Contains core functions and boot code. | 448KB |
| eFuse | 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including Flash-Encryption and Chip-ID | 1kbit |

12.0 WiFi

12.1 Supported features

- 802.11 b/g/n/e/i
- 802.11 n (2.4 GHz), up to 150 Mbps
- 802.11 e: QoS for wireless multimedia technology
- WMM-PS, UAPSD
- A-MPDU and A-MSDU aggregation
- Block ACK
- Fragmentation and defragmentation
- Automatic Beacon monitoring/scanning
- 802.11i security features: pre-authentication and TSN
- Wi-Fi Protected Access (WPA/WPA2/WPA2-Enterprise/Wi-Fi Protected Setup (WPS)
- Infrastructure BSS Station mode/SoftAP mode
- Wi-Fi Direct (P2P), P2P Discovery, P2P Group Owner mode and P2P Power Management

12.2 Specifications

Table 8 – WiFi specifications

[illegible]

13.0 Bluetooth

13.1 Supported features

- Compliant with Bluetooth v4.2 BR/EDR and BLE specification
- Class-1, class-2 and class-3 transmitter without external power amplifier
- Enhanced power control
- +12 dBm transmitting power
- NZIF receiver with -97 dBm sensitivity
- Adaptive Frequency Hopping (AFH)
- Standard HCI based on SDIO/SPI/UART
- High-speed UART HCI, up to 4 Mbps
- BT 4.2 controller and host stack
- Service Discover Protocol (SDP)
- General Access Profile (GAP)
- Security Manage Protocol (SMP)
- ATT/GATT
- HID
- All GATT-based profile supported
- SPP-like GATT-based profile
- BLE Beacon
- A2DP/AVRCP/SPP, HSP/HFP, RFCOMM
- CVSD and SBC for audio codec
- Bluetooth Piconet and Scatternet

13.2 Specification

13.2.1 Receiver – Basic Data Rate

Table 9 – Receiver (basic data rate) specifications

| Parameter | Min | Typ. | Max | Unit |
|-----------------------------------|-------------------|------|-----|------|
| Sensitivity @0.1% BER | – | –94 | – | dBm |
| Maximum received signal @0.1% BER | 0 | – | – | dBm |
| Co-channel C/I | – | +7 | – | dB |
| Adjacent channel selectivity C/I | F = F0 + 1 MHz | – | –6 | dB |
| | F = F0 – 1 MHz | – | –6 | dB |
| | F = F0 + 2 MHz | – | –25 | dB |
| | F = F0 – 2 MHz | – | –33 | dB |
| | F = F0 + 3 MHz | – | –25 | dB |
| | F = F0 – 3 MHz | – | –45 | dB |
| Out-of-band blocking performance | 30MHz ~ 2000MHz | –10 | – | dBm |
| | 2000MHz ~ 2400MHz | –27 | – | dBm |
| | 2500MHz ~ 3000MHz | –27 | – | dBm |
| | 3000MHz ~ 12.5GHz | –10 | – | dBm |
| Intermodulation | –36 | – | – | dBm |

13.2.2 Receiver – Enhanced Data Rate

Table 10 – Receiver (basic data rate) specifications

| Parameter | Min | Typ. | Max | Unit |
|-----------------------------------|----------------|------|-----|------|
| $\pi/4$ DQPSK | | | | |
| Sensitivity @0.1% BER | – | –90 | – | dBm |
| Maximum received signal @0.1% BER | – | 0 | – | dBm |
| Co-channel C/I | – | 11 | – | dB |
| Adjacent channel selectivity C/I | F = F0 + 1 MHz | – | –7 | dB |
| | F = F0 – 1 MHz | – | –7 | dB |
| | F = F0 + 2 MHz | – | –25 | dB |
| | F = F0 – 2 MHz | – | –35 | dB |
| | F = F0 + 3 MHz | – | –25 | dB |
| | F = F0 – 3 MHz | – | –45 | dB |
| 8DPSK | | | | |
| Sensitivity @0.1% BER | – | –84 | – | dBm |
| Maximum received signal @0.1% BER | – | –5 | – | dBm |
| C/I c-channel | – | 18 | – | dB |
| Adjacent channel selectivity C/I | F = F0 + 1 MHz | – | 2 | dB |
| | F = F0 – 1 MHz | – | 2 | dB |
| | F = F0 + 2 MHz | – | –25 | dB |
| | F = F0 – 2 MHz | – | –25 | dB |
| | F = F0 + 3 MHz | – | –25 | dB |
| | F = F0 – 3 MHz | – | –38 | dB |

13.2.3 Receiver – Bluetooth LE

Table 11 – Receiver (BLE) specifications

| Parameter | | Min | Typ. | Max | Unit |
|------------------------------------|-------------------|-----|------|-----|------|
| Sensitivity @30.8% PER | | – | –97 | – | dBm |
| Maximum received signal @30.8% PER | | 0 | – | – | dBm |
| Co-channel C/I | | – | +10 | – | dB |
| Adjacent channel selectivity C/I | F = F0 + 1MHz | – | –5 | – | dB |
| | F = F0 – 1MHz | – | –5 | – | dB |
| | F = F0 + 2MHz | – | –25 | – | dB |
| | F = F0 – 2MHz | – | –35 | – | dB |
| | F = F0 + 3MHz | – | –35 | – | dB |
| | F = F0 – 3MHz | – | –45 | – | dB |
| Out-of-band blocking performance | 30MHz ~ 2000MHz | –10 | – | – | dB |
| | 2000MHz ~ 2400MHz | –27 | – | – | dBm |
| | 2500MHz ~ 3000MHz | –27 | – | – | dBm |
| | 3000MHz ~ 12.5GHZ | –10 | – | – | dBm |
| Intermodulation | | –36 | – | – | dBm |

13.2.4 Transmitter – Basic Data Rate

Table 12 – Transmitter (basic data rate) specifications

| Parameter | | Min | Typ. | Max | Unit |
|--|-----------------|-------|-------|-----|----------|
| RF transmit power | | – | 0 | – | dBm |
| Gain control step | | – | ±3 | – | dBm |
| RF power control range | | –12 | – | +12 | dBm |
| +20 dB bandwidth | | – | 0.9 | – | MHz |
| Adjacent channel transmit power | F = F0 + 1 MHz | – | –24 | – | dBm |
| | F = F0 – 1 MHz | – | –16.1 | – | dBm |
| | F = F0 + 2 MHz | – | –40.8 | – | dBm |
| | F = F0 – 2 MHz | – | –35.6 | – | dBm |
| | F = F0 + 3 MHz | – | –45.7 | – | dBm |
| | F = F0 – 3 MHz | – | –40.2 | – | dBm |
| | F = F0 + >3 MHz | – | 45.6 | – | dBm |
| | F = F0 – >3 MHz | – | 44.6 | – | dBm |
| Δf1 _{avg} | | – | – | 155 | KHz |
| Δf2 _{max} | | 133.7 | | | KHz |
| Δf2 _{avg} /Δf1 _{avg} | | – | 0.92 | – | – |
| ICFT | | – | –7 | – | KHz |
| Drift rate | | – | 0.7 | – | KHz/50μs |
| Drift (1 slot packet) | | – | 6 | – | KHz |
| Drift (5 slot packet) | | – | 6 | – | KHz |

13.2.5 Transmitter – Enhanced Data Rate

Table 13 – Transmitter (enhanced data rate) specifications

| Parameter | | Min | Typ. | Max | Unit |
|-----------------------------------|----------------------------|-----|-------|-------|------|
| RF transmit power | | – | 0 | – | dBm |
| Gain control step | | – | ±3 | – | dBm |
| RF power control range | | –12 | – | +12 | dBm |
| $\pi/4$ DQPSK max w_0 | | – | –0.72 | – | KHz |
| $\pi/4$ DQPSK max w_i | | – | –6 | – | KHz |
| $\pi/4$ DQPSK max $ w_i + w_0 $ | | – | –7.42 | – | KHz |
| 8DPSK max w_0 | | – | 0.7 | – | KHz |
| 8DPSK max w_i | | – | –9.6 | – | KHz |
| 8DPSK max $ w_i + w_0 $ | | | –10 | | KHz |
| $\pi/4$ DQPSK modulation accuracy | RMS DEVM | – | 4.28 | – | % |
| | 99% DEVM | – | – | 30 | % |
| | Peak DEVM | – | 13.3 | – | % |
| 8 DPSK modulation accuracy | RMS DEVM | – | 5.8 | – | % |
| | 99% DEVM | – | | 20 | % |
| | Peak DEVM | – | 14 | – | % |
| In-band spurious emissions | $F = F_0 + 1\text{MHz}$ | – | –34 | – | dBm |
| | $F = F_0 - 1\text{MHz}$ | – | –40.2 | – | dBm |
| | $F = F_0 + 2\text{MHz}$ | – | –34 | – | dBm |
| | $F = F_0 - 2\text{MHz}$ | – | –36 | – | dBm |
| | $F = F_0 + 3\text{MHz}$ | – | –38 | – | dBm |
| | $F = F_0 - 3\text{MHz}$ | – | –40.3 | – | dBm |
| | $F = F_0 \pm >3\text{MHz}$ | – | – | –41.5 | dBm |
| EDR differential phase coding | | – | 100 | – | % |

13.2.6 Transmitter – Bluetooth LE

Table 14 – Transmitter (BLE) specifications

| Parameter | | Min | Typ. | Max | Unit |
|-----------------------------------|----------------|-----|-------|-----|----------|
| RF transmit power | | – | 0 | – | dBm |
| Gain control step | | – | ±3 | – | dBm |
| RF power control range | | –12 | – | +12 | dBm |
| Adjacent channel transmit power | F = F0 + 1MHz | – | –14.6 | – | dBm |
| | F = F0 – 1MHz | – | –12.7 | – | dBm |
| | F = F0 + 2MHz | – | –44.3 | – | dBm |
| | F = F0 – 2MHz | – | –38.7 | – | dBm |
| | F = F0 + 3MHz | – | –49.2 | – | dBm |
| | F = F0 – 3MHz | – | –44.7 | – | dBm |
| | F = F0 + >3MHz | – | –50 | – | dBm |
| | F = F0 – >3MHz | – | –50 | – | dBm |
| $\Delta f1_{avg}$ | | – | – | 265 | KHz |
| $\Delta f2_{max}$ | | 247 | – | – | KHz |
| $\Delta f2_{avg}/\Delta f1_{avg}$ | | – | –0.92 | – | – |
| ICFT | | – | –10 | – | KHz |
| Drift rate | | – | 0.7 | – | KHz/50µs |
| Drift | | – | 2 | – | KHz |

14.0 LoRa

14.1 Supported features

Table 15 – Supported LoRa features

| Part Number | Frequency Range | LoRa Parameters | | | |
|----------------|-----------------|------------------|---------------|-------------------|------------------|
| | | Spreading factor | Bandwidth | Effective Bitrate | Sensitivity |
| Semtech SX1272 | 860–1020MHz | 6 – 12 | 125 – 500 kHz | 0.24 – 37.5 kpbs | –117 to –137 dBm |

The current micropython firmware supports LoRaWAN 1.0 acting as either a Class A or Class C node.

14.2 Specifications

Table 16 – LoRa modem performance

| Bandwidth (KHz) | Spreading Factor | Nominal Rb (bps) | Sensitivity (dBm) |
|-----------------|------------------|------------------|-------------------|
| 125 | 6 | 9380 | –122 |
| 125 | 12 | 293 | –137 |
| 250 | 6 | 18750 | –119 |
| 250 | 12 | 588 | –134 |
| 500 | 6 | 37500 | –116 |
| 500 | 12 | 1172 | –131 |

14.2 Specifications

Table 17 – LoRa electrical characteristics

| Symbol | Description | Conditions | Min | Typ. | Max | Unit |
|----------|--|---|------|-------|------|------|
| IDDR_L | Supply current in receiver LoRa mode | LNABoost Off, BW=125KHz | – | 9.7 | – | mA |
| | | LNABoost Off, BW=250KHz | – | 10.5 | – | mA |
| | | LNABoost Off, BW=500KHz | – | 12 | – | mA |
| | | LNABoost On, BW=125KHz | – | 10.8 | – | mA |
| | | LNABoost On, BW=250KHz | – | 11.6 | – | mA |
| | | LNABoost On, BW=500KHz | – | 13 | – | mA |
| IDDT_L | Supply current in transmitter mode | RFOP = 13dBm | – | 28 | – | mA |
| | | RFOP = 7dBm | – | 18 | – | mA |
| IDDT_H_L | Supply current in transmitter mode with an external impedance transformer | Using PA_BOOST pin RFOP = 17 dBm | – | 90 | – | mA |
| BI_L | Blocking Immunity, FRF=868MHz CW interferer | Offset = ± 1 MHz | – | 82.5 | – | dB |
| | | Offset = ± 2 MHz | – | 86.5 | – | dB |
| | | Offset = ± 10 MHz | – | 89 | – | dB |
| IIP3_L | 3rd order input intercept point, highest LNA gain, FRF=868MHz, CW interferer | F1 = FRF + 1MHz F2 = FRF + 1.995MHz | – | –12.5 | – | dBm |
| IIP2_L | 2nd order input intercept point, highest LNA gain, FRF=868MHz, CW interferer | F1 = FRF + 20MHz F2 = FRF + 20MHz + Δf | – | 57 | – | dBm |
| BR_L | Bit rate, Long–Range Mode | From SF6, CR=4/5, BW=500 kHz to SF12, CR=4/8, BW = 125kHz | 0.24 | – | 37.5 | kbps |

14.2 Specifications

Table 17 – LoRa electrical characteristics

| Symbol | Description | Conditions | Min | Typ. | Max | Unit |
|----------|---|------------|-----|------|-----|------|
| RFS_L125 | RF sensitivity, Long-Range Mode, highest LNA gain, LNA boost, 125kHz bandwidth using split Rx/Tx path | SF = 6 | – | –121 | – | dBm |
| | | SF = 7 | – | –124 | – | dBm |
| | | SF = 8 | – | –127 | – | dBm |
| | | SF = 9 | – | –130 | – | dBm |
| | | SF = 10 | – | –133 | – | dBm |
| | | SF = 11 | – | –135 | – | dBm |
| | | SF = 12 | – | –137 | – | dBm |
| RFS_L250 | RF sensitivity, Long-Range Mode, highest LNA gain, LNA boost, 250kHz bandwidth using split Rx/Tx path | SF = 6 | – | –118 | – | dBm |
| | | SF = 7 | – | –122 | – | dBm |
| | | SF = 8 | – | –125 | – | dBm |
| | | SF = 9 | – | –128 | – | dBm |
| | | SF = 10 | – | –130 | – | dBm |
| | | SF = 11 | – | –132 | – | dBm |
| | | SF = 12 | – | –135 | – | dBm |
| RFS_L500 | RF sensitivity, Long-Range Mode, highest LNA gain, LNA boost, 500kHz bandwidth using split Rx/Tx path | SF = 6 | – | –111 | – | dBm |
| | | SF = 7 | – | –116 | – | dBm |
| | | SF = 8 | – | –119 | – | dBm |
| | | SF = 9 | – | –122 | – | dBm |
| | | SF = 10 | – | –125 | – | dBm |
| | | SF = 11 | – | –128 | – | dBm |
| | | SF = 12 | – | –129 | – | dBm |

14.2 Specifications

Table 17 – LoRa electrical characteristics

| Symbol | Description | Conditions | Min | Typ. | Max | Unit |
|---------|---|---|------|------|-----|------|
| CCR_LCW | | SF = 7 | – | 5 | – | dB |
| | | SF = 8 | – | 9.5 | – | dB |
| | | SF = 9 | – | 12 | – | dB |
| | | SF = 10 | – | 14.4 | – | dB |
| | | SF = 11 | – | 17 | – | dB |
| | | SF = 12 | – | 19.5 | – | dB |
| CCR_LL | Co-channel rejection | Interferer is a LoRa signal using the same BW and SF. Pw = sensitivity + 3dB | – | –6 | – | dB |
| ACR_LCW | Adjacent channel rejection FRF = 868 MHz | Interferer is 1.5*BW_L from the wanted signal centre frequency 1% PER, Single CW tone = Sensitivity + 3dB | | | | |
| | | SF = 7 | – | 60 | – | dB |
| | | SF = 12 | – | 72 | – | dB |
| IMR_LCW | Image rejection after calibration | 1% PER, Single CW tone = sensitivity + 3dB | – | 66 | – | dB |
| FERR_L | Maximum tolerated frequency offset between transmitter and receiver, no sensitivity degradation | BW_L = 125kHz | –30 | – | 30 | kHz |
| | | BW_L = 250kHz | –60 | – | 60 | kHz |
| | | BW_L = 500kHz | –120 | – | 120 | kHz |

14.2 Specifications

Table 18 – LoRa power consumption

| Symbol | Description | Conditions | Min | Typ. | Max | Unit |
|---------|---|----------------------------|-----|------|-----|------|
| IDDSL | Supply current in sleep mode | | – | 0.1 | 1 | μA |
| IDDIDLE | Supply current in idle mode | RC oscillator enabled | – | 1.5 | – | μA |
| IDDST | Supply current in standby mode | Crystal oscillator enabled | – | 1.4 | 1.6 | mA |
| IDDFS | Supply current in synthesizer mode | FSRx | – | 4.5 | – | mA |
| IDDR | Supply current in receive mode | LnaBoost Off | – | 10.5 | – | mA |
| | | LnaBoost On | – | 11.2 | – | mA |
| IDDT | Supply current in transmit mode with impedance matching | RFOP=+ 20 dBm on PA_BOOST | – | 125 | – | mA |
| | | RFOP=+ 17 dBm on PA_BOOST | – | 90 | – | mA |
| | | RFOP=+ 13 dBm on RFO pin | – | 28 | – | mA |
| | | RFOP=+ 7 dBm on RFO pin | – | 18 | – | mA |

15.0 6LoWPAN

Pycom is currently working on adding 6LoWPAN support to this module and plan to release a new firmware with this functionality in Q2 2018.

16.0 Electrical Characteristics

16.1 Absolute maximum ratings

Table 19 – Absolute maximum ratings

| Parameter | Symbol | Min | Typ. | Max | Unit |
|----------------------------|-----------|-----|------|-----|------|
| Supply Input Voltage | V_{IN} | 3.5 | – | 5.5 | V |
| Supply Output Current | I_{OUT} | – | – | 1.2 | A |
| Supply Output Voltage | V_{3V3} | – | 3.3 | – | V |
| Storage Temperature | T_{STR} | – | – | – | °C |
| Operating Temperature | T_{OPR} | –40 | – | 85 | °C |
| Moisture Sensitivity Level | MSL | – | 1 | – | – |

16.2 Input/Output characteristics

Table 20 – Input/Output characteristics

| Parameter | Symbol | Min | Typ. | Max | Unit |
|---------------------------|--------------|-----------------------|------|-----------------------|------|
| Input low voltage | V_{IL} | –0.3 | – | $0.25 \times V_{3V3}$ | V |
| Input high voltage | V_{IH} | $0.75 \times V_{3V3}$ | – | $V_{3V3} + 0.3$ | V |
| Max Input sink current | I_{SINK} | – | 6 | 12 | mA |
| Input leakage current | I_{IL} | – | – | 50 | nA |
| Input pin capacitance | C_{pin} | – | – | 2 | pF |
| Output low voltage | V_{OL} | $0.1 \times V_{3V3}$ | – | – | V |
| Output high voltage | V_{OH} | $0.8 \times V_{3V3}$ | – | – | V |
| Max Output source current | I_{SOURCE} | – | 6 | 12 | mA |

17.0 Minimum Recommended Circuit

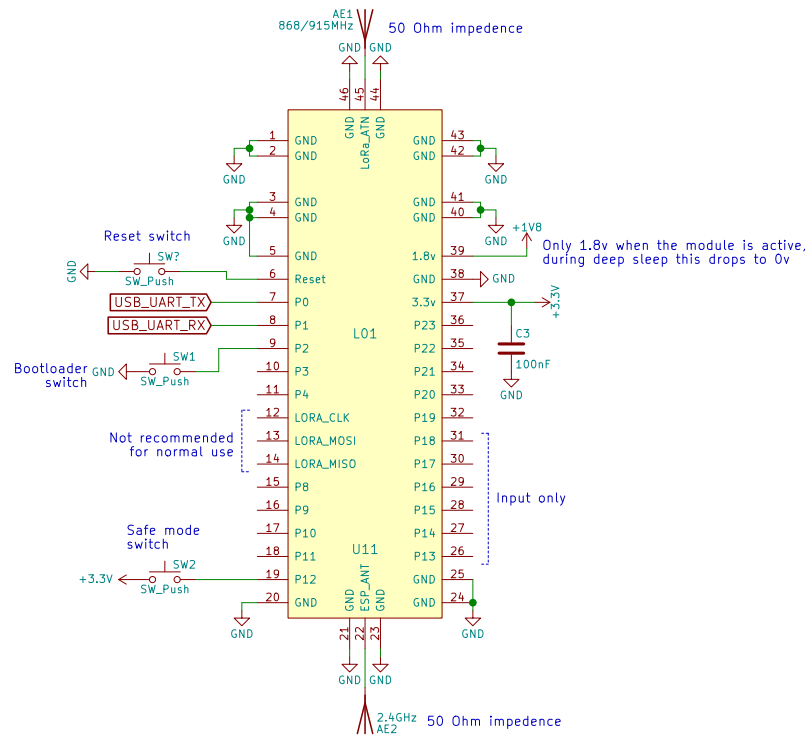


Figure 4 – Minimum required circuit

20.0 Design Considerations

20.1 Antenna Impedance

Our OEM modules are intended to be used with a 50-ohm antenna. They are also required to be connected to the antenna by a 50-ohm grounded co-planar waveguide (as shown in the reference design below with the yellow lines) or a microstrip.

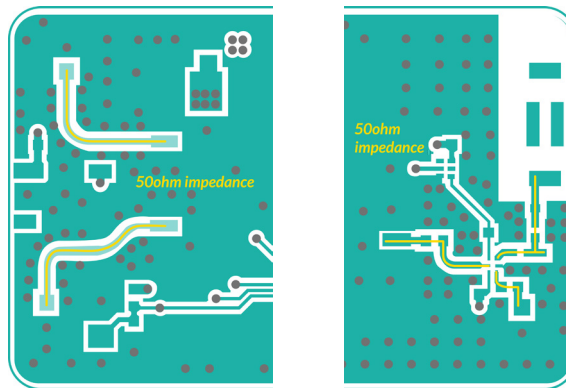


Figure 7 – 50-ohm impedance antenna connections

20.2 Deep sleep power

When selecting a voltage regulator for your application ensure that it has a low power mode, and that this is enabled when the device enters deep sleep. We also recommend cutting off power to all non-essential components such as LEDs, logic gates, sensors etc. when the device is in deep sleep. This can be done using the circuit shown right:

This circuit uses the 1.8V output of the module to cut off supply to non-essential circuitry. The 1.8V output is only active when the module is running, when it goes to deep sleep it drops to 0V. The non-essential circuitry is then powered from the "ACTIVE_POWER" bus.

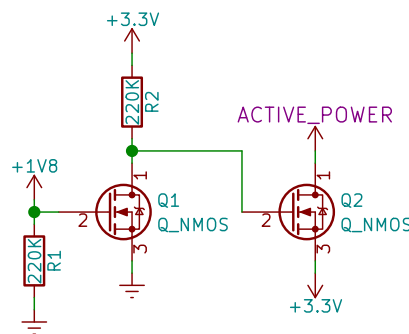


Figure 8 – Power switch for deep sleep mode

20.3 Reference layout

Below you will find the designs for our universal reference board that fits all of our OEM modules. The design files can be downloaded from our website.

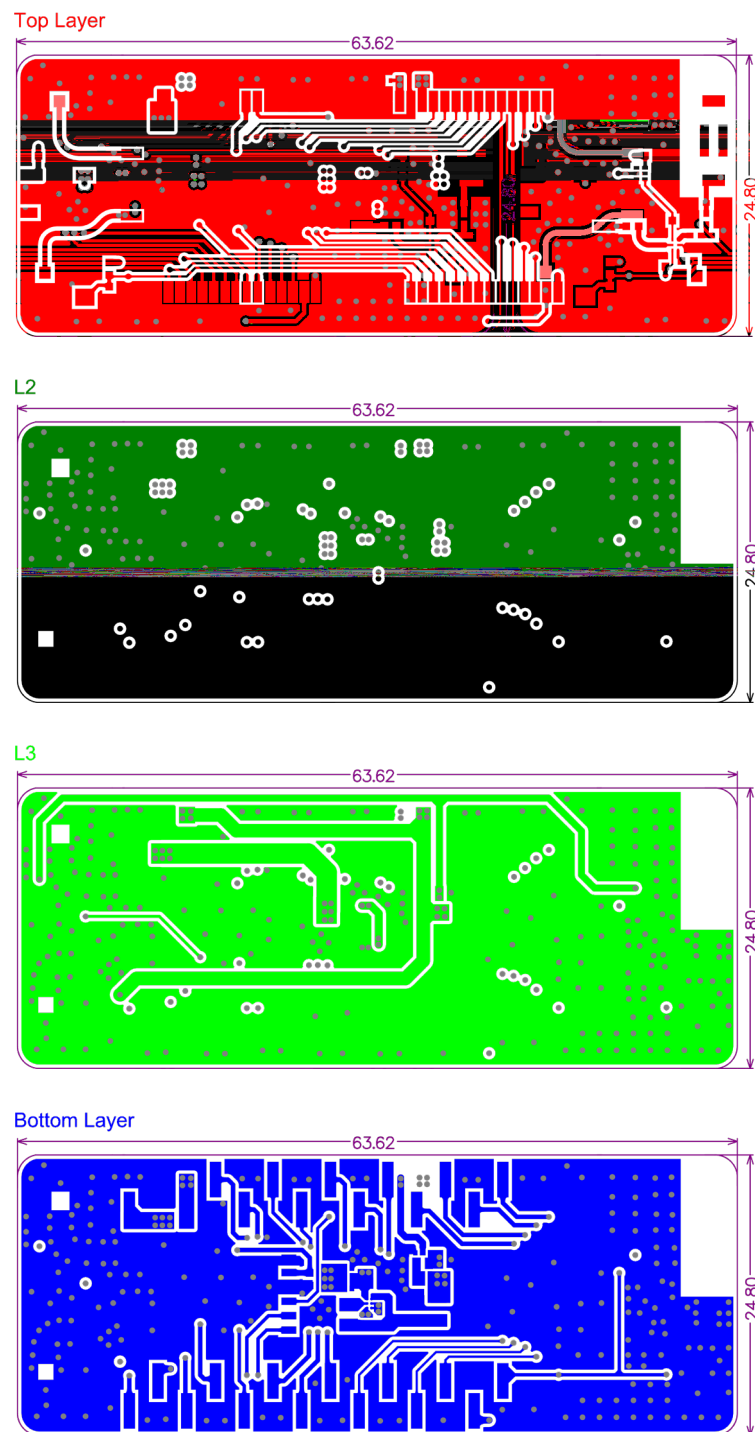


Figure 9 – PCB layers for reference design – Units: mm

21.0 Soldering Profile

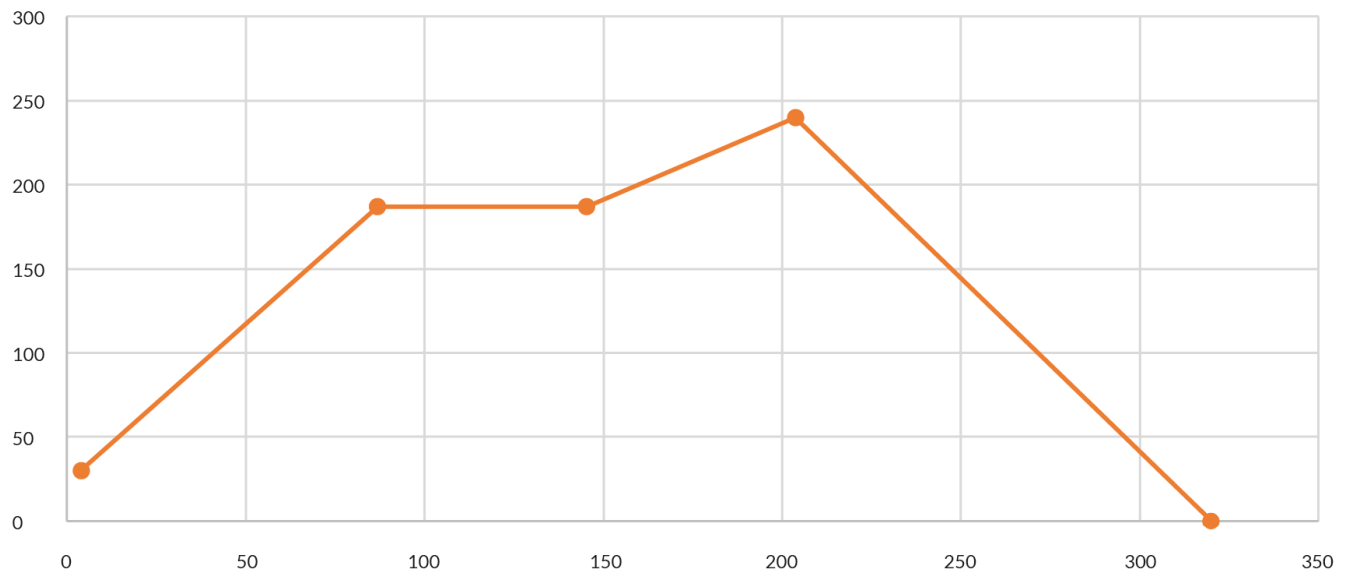


Figure 10 – Reflow soldering temperature profile

Table 21– Soldering profile temperatures

| Stage | Duration/Rate | Temperature |
|--------------|---------------|-----------------|
| Ramp to soak | 2°C/s | Ambient – 185°C |
| Soak | 60s | 185°C |
| Ramp to peak | 1°C/s | 240°C |
| Reflow | 45s | >225°C |
| Cool down | 2°C/s | |

The above profile is based on Alpha CVP-390 solder paste, which has been successfully tested with our devices.

22.0 Ordering Information

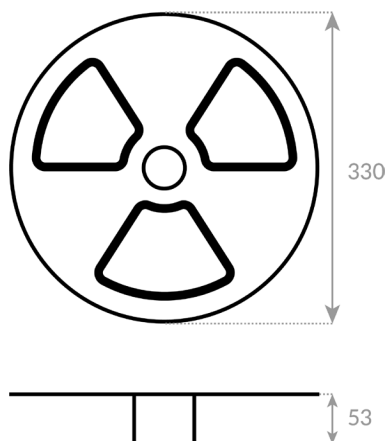
Table 22 – Ordering information

| Product EAN | Description |
|---------------|-------------------------------|
| 0700461341567 | L01 – OEM version of LoPy 1.0 |
| 0700461908869 | Reel of 250 L01 OEM modules |
| 0700461908937 | Reel of 500 L01 OEM modules |

23.0 Packaging

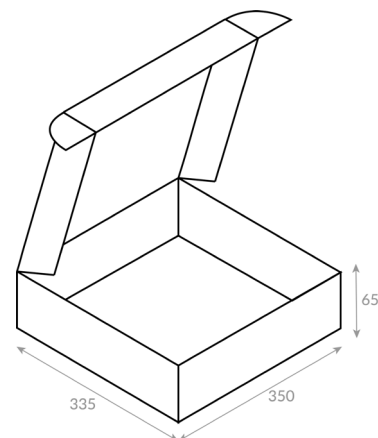
23.1 Reel

Figure 11 – Mechanical drawing of reel – Units: mm



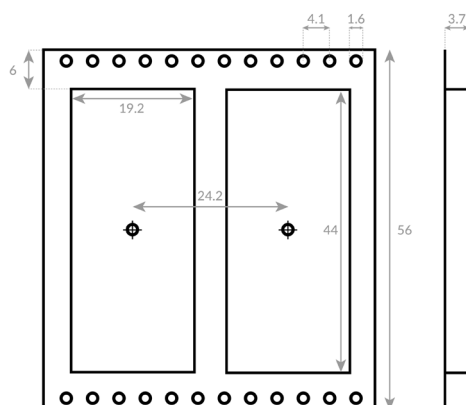
23.3 Box

Figure 13 – Mechanical drawing of reel box – Units: mm



23.2 Tape

Figure 12 – Mechanical drawing of reel tape – Units: mm



24.0 Certification

FCC 2AJMTLOPY1R
IC 2263-LOPY01R
CE 0700

Copies of the certificates can be found on our website.

25.0 Regulator Information

25.1 EU Regulatory Conformance

Hereby, Pycom Ltd declares that this device is in compliance with the essential requirements and other relevant provisions of Directive 1999/5/EC

25.2 Federal Communication Commission Interference Statement

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

1. This device may not cause harmful interference.
2. This device must accept any interference received, including interference that may cause undesired operation.

CAUTION: Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

25.2.1 RF Warning Statement

To comply with FCC RF exposure compliance requirements, the antennas used for this transmitter must be installed to provide a separation distance of at least 20 cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter.

25.2.2 OEM integrator conditions

This device is intended only for OEM integrators under the following conditions:

1. The antenna must be installed such that 20 cm is maintained between the antenna and users, and
2. The transmitter module may not be co-located with any other transmitter or antenna.

As long as the two conditions above are met, further transmitter test will not be required. However, the OEM integrator is still responsible for testing their end-product for any additional compliance requirements required with this module installed. To ensure compliance with all non-transmitter functions the host manufacturer is responsible for ensuring compliance with the module(s) installed and fully operational. For example, if a host was previously authorized as an unintentional radiator under the Declaration of Conformity procedure without a transmitter certified module and a module is added, the host manufacturer is responsible for ensuring that the after the module is installed and operational the host continues to be compliant with the Part 15B unintentional radiator requirements.

The module is limited to OEM installation ONLY. The module is limited to installation in mobile or fixed application. We hereby acknowledge our responsibility to provide guidance to the host manufacturer in the event that they require assistance for ensuring compliance with the Part 15 Subpart B requirements.

IMPORTANT NOTE: In the event that these conditions cannot be met (for example certain laptop configurations or co-location with another transmitter), then the FCC authorization is no longer considered valid and the FCC ID cannot be used on the final product. In these circumstances, the OEM integrator will be responsible for re-evaluating the end product (including the transmitter) and obtaining a separate FCC authorization.

25.2.3 End Product Labelling

This transmitter module is authorized only for use in device where the antenna may be installed such that 20 cm may be maintained between the antenna and users. The final end product must be labelled in a visible area with the following: "Contains FCC ID: 2AJMTLOPY1R". The grantee's FCC ID can be used only when all FCC compliance requirements are met.

The following FCC part 15.19 statement has to also be available on the label:

This device complies with Part 15 of FCC rules. Operation is subject to the following two conditions:

1. this device may not cause harmful interference and
2. this device must accept any interference received, including interference that may cause undesired operation.

25.2.4 Manual Information to the End User

The OEM integrator has to be aware not to provide information to the end user regarding how to install or remove this RF module in the user's manual of the end product which integrates this module.

In the user manual of the end product, the end user has to be informed that the equipment complies with FCC radio-frequency exposure guidelines set forth for an uncontrolled environment.

The end user has to also be informed that any changes or modifications not expressly approved by the manufacturer could void the user's authority to operate this equipment.

The end user manual shall include all required regulatory information/warning as show in this manual.

The maximum operating ambient temperature of the equipment declared by the manufacturer is $-40\sim+85^{\circ}\text{C}$

Receiver category 3

26.0 Revision History

Table 23 – Document revision history

| Version 1.0 | Initial Release |
|-------------|-----------------|
|-------------|-----------------|