

```

      SUBROUTINE ALGOR(IINCS ,IITER ,KRESL ,KUNLD )
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C
C Hyplas database: Global parameters and common blocks
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C Numerical constants
      DATA R0 /0.0D0/
C*****
C SETS EQUATION RESOLUTION INDEX, KRESL, ACCORDING TO SELECTED ITERATIVE
C ALGORITHM FOR SOLUTION OF THE NON-LINEAR EQUILIBRIUM PROBLEM
C
C REFERENCE: Section 5.4.4
C*****
C
C Set KRESL
C -----
      KRESL=2
      IABSN=IABS(NALGO)
C Initial stiffness method
      IF(IABSN.EQ.1.AND.IINCS.EQ.1.AND.IITER.EQ.1) KRESL=1
C Newton-Raphson tangential stiffness method
      IF(IABSN.EQ.2) KRESL=1
C Modified Newton KT1
      IF(IABSN.EQ.3.AND.IITER.EQ.1) KRESL=1
C Modified Newton KT2
      IF(IABSN.EQ.4.AND.IINCS.EQ.1.AND.IITER.EQ.1) KRESL=1
      IF(IABSN.EQ.4.AND.IITER.EQ.1.AND.KUNLD.EQ.1) KRESL=1
      IF(IABSN.EQ.4.AND.IITER.EQ.2) KRESL=1
C Secant Newton - Initial stiffness
      IF(IABSN.EQ.5.AND.IINCS.EQ.1.AND.IITER.EQ.1) KRESL=1
C Secant Newton - KT1
      IF(IABSN.EQ.6.AND.IITER.EQ.1) KRESL=1
C Secant Newton - KT2
      IF(IABSN.EQ.7.AND.IINCS.EQ.1.AND.IITER.EQ.1) KRESL=1
      IF(IABSN.EQ.7.AND.IITER.EQ.1.AND.KUNLD.EQ.1) KRESL=1
      IF(IABSN.EQ.7.AND.IITER.EQ.2) KRESL=1
C
C Zero prescribed displacements if not first iteration
C -----
      IF(IITER.GT.1)THEN
        NRHS=1
        IF(NALGO.LT.0)NRHS=2
        DO 20 ITOTV = 1,NTOTV
          DO 10 IRHS=1,NRHS
            FIXED(ITOTV,IRHS)=R0
          10 CONTINUE
        20 CONTINUE
      ENDIF
C
      RETURN
      END

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      SUBROUTINE ARCLEN
      1( DFACT ,DLAMD ,DLENG ,DLENM ,DLENP ,
      2  IFNEG ,IINCS ,IITER ,INCCUT ,TFACT )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C Arguments
      LOGICAL INCCUT
C Local logical flags
      LOGICAL ONEROO ,TWOORO
C Local numerical constants
      PARAMETER
      1( R0=0.0D0 ,R1=1.0D0 ,R2=2.0D0 )
C*****
C SOLVE ARC-LENGTH EQUATIONS AND UPDATE LOAD FACTOR AND VECTOR OF
C ITERATIVE DISPLACEMENTS ACCORDINGLY
C
C REFERENCE: Box 4.4, items (iv)-(vi)
C Section 4.4
C*****
      IF(IITER.EQ.1)THEN
C
C For first iteration only
C =====
C evaluate length of tangential solution
      APARM=SCAPRD(DTANG,DTANG,NTOTV)
C
C ...and compute arc-length/load increment factor
      IF(IINCS.EQ.1)THEN
C for the first iteration of the first increment set up the arc-length
C constraint, DLENG, so as to match the user-prescribed initial load
C increment factor, DFACT
      SIGNUM=DBLE(IFNEG)
      DFACT=SIGNUM*DFACT
      DLENG=SQRT(DFACT*DFACT*APARM)
C set up the maximum allowed arc-length according to the specified
C maximum arc-length parameter, DLENP
      DLENM=DLENP*DLENG
      ELSE
C Predictor solution: for the first iteration of other increments
C compute the load increment factor, DFACT, corresponding to the
C arc-length constraint, DLENG, of the current increment
      IF(NARCL.EQ.1)THEN
C Use stiffness determinant sign criterion
      SIGNUM=DBLE(IFNEG)
      ELSEIF(NARCL.EQ.2)THEN
C Use secant path criterion (sign of the internal product between the
C previous converged displacement increment and the current tangential
C solution)
      SCAL=SCAPRD(DINCRO,DTANG,NTOTV)
      IF(SCAL.GT.R0)THEN
        SIGNUM=R1
      ELSE
        SIGNUM=-R1
      ENDIF
      DFACT=SIGNUM*ABS(DLENG/SQRT(APARM))
      ENDIF
C update current total load factor
      DLAMD=DFACT
      TFACT=TFACT+DLAMD
C
      ELSE
C
C For iterations other than the first: Solve the cylindrical arc-length
C constraint equation to update
C the load factor
C =====
C
C Compute the coefficients of the arc-length constraint equation
      APARM=R0
      BPARM=R0
      CPARM=R0
      DO 10 ITOTV=1,NTOTV
C Here, DTANG is the current tangential solution, DINCRO is the last
C incremental displacement (at the end of the previous iteration) and
C DITER is the current iterative displacement resulting from the
C standard load controlled N-R procedure.
      APARM=APARM+DTANG(ITOTV)*DTANG(ITOTV)
      BPARM=BPARM+R2*(DINCRO(ITOTV)+DITER(ITOTV))*DTANG(ITOTV)
      CPARM=CPARM+(DINCRO(ITOTV)+DITER(ITOTV))*
      1 (DINCRO(ITOTV)+DITER(ITOTV))
      10 CONTINUE
      CPARM=CPARM-(DLENG*DLENG)
C Solve the quadratic equation and decide which root to use
      CALL SOLQUA
      1( APARM ,BPARM ,CPARM ,ONEROO ,TWOORO ,
      2  DLAM1 ,DLAM2 )
      IF(TWOORO)THEN
C Two real roots: Choose the solution that renders minimum angle
C (maximum cosine) between the incremental displacements at the end
C of the previous iteration and the current iteration
      COS1=R0
      COS2=R0
      DO 20 ITOTV=1,NTOTV
        COS1=COS1+(DINCRO(ITOTV)+DITER(ITOTV)+DLAM1*DTANG(ITOTV))*
      1 DINCRO(ITOTV)
        COS2=COS2+(DINCRO(ITOTV)+DITER(ITOTV)+DLAM2*DTANG(ITOTV))*
      1 DINCRO(ITOTV)
      20 CONTINUE
      IF(COS1.GT.COS2)THEN
        DLAMD=DLAM1
      ELSE
        DLAMD=DLAM2
      ENDIF
      ELSEIF(ONEROO)THEN
C There is only one root to the equation

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        DLAMD=DLAM1
    ELSE
C There are no real roots: issue warning message and request main
C program to activate increment cutting
        CALL ERRPRT('WE0012')
        INCCUT=.TRUE.
        GOTO 999
    ENDIF
C Update current incremental and total load factors
    DFACT=DFACT+DLAMD
    TFACT=TFACT+DLAMD
C
    ENDIF
C
C For all iterations: compute actual iterative displacement using
C the arc-length expression
C =====
C
    DO 30 ITOTV=1,NTOTV
        DITER(ITOTV)=DITER(ITOTV)+DLAMD*DTANG(ITOTV)
    30 CONTINUE
C
999 CONTINUE
    RETURN
    END

```

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      SUBROUTINE ARRGO2
      1(      A4TH      ,AMATX      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
      1(      NDIM=2      ,NGDIM=4      )
C Arguments
      DIMENSION
      1      A4TH(NDIM,NDIM,NDIM,NDIM)      ,AMATX(NGDIM,NGDIM)
C*****
C RE-ARRANGES A FOURTH ORDER TENSOR, STORED AS A 4-INDEX ARRAY, IN
C MATRIX FORM (2-INDEX ARRAY) USING G-MATRIX COMPONENT ORDERING
C (11,21,12,22). FOR 2-D ONLY.
C
C REFERENCE: Section D.2.1
C*****
C
      AMATX(1,1)=A4TH(1,1,1,1)
      AMATX(1,2)=A4TH(1,1,2,1)
      AMATX(1,3)=A4TH(1,1,1,2)
      AMATX(1,4)=A4TH(1,1,2,2)
C
      AMATX(2,1)=A4TH(2,1,1,1)
      AMATX(2,2)=A4TH(2,1,2,1)
      AMATX(2,3)=A4TH(2,1,1,2)
      AMATX(2,4)=A4TH(2,1,2,2)
C
      AMATX(3,1)=A4TH(1,2,1,1)
      AMATX(3,2)=A4TH(1,2,2,1)
      AMATX(3,3)=A4TH(1,2,1,2)
      AMATX(3,4)=A4TH(1,2,2,2)
C
      AMATX(4,1)=A4TH(2,2,1,1)
      AMATX(4,2)=A4TH(2,2,2,1)
      AMATX(4,3)=A4TH(2,2,1,2)
      AMATX(4,4)=A4TH(2,2,2,2)
C
      RETURN
      END

```

```

SUBROUTINE ATMDFB
1( AMATX ,NTYPE ,QMATX ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER
1( MADIM=5 )
DIMENSION
1 AMATX(MADIM,MADIM) ,QMATX(MADIM,MADIM) ,STRES(*)
DATA
1 R0 ,RP5 ,R1 ,R2 ,R3 /
2 0.0D0,0.5D0,1.0D0,2.0D0,3.0D0/
C*****
C COMPUTE THE ADDITIONAL TANGENT MODULUS "q" REQUIRED BY F-BAR
C ELEMENTS:
C
C 
$$q := \frac{1}{3} a:(I(x) I) - \frac{2}{3} [\text{sigma}](x) I$$

C FOR AXISYMMETRIC CASE, AND
C
C 
$$q := \frac{1}{2} a:(I(x) I) - \frac{1}{2} [\text{sigma}](x) I$$

C FOR PLANE STRAIN.
C
C REFERENCE: Expressions (15.11) and (15.22)
C*****
C
C IF(NTYPE.EQ.2)THEN
C Plane strain
A=RP5
B=-RP5
QMATX(1,1)=A*(AMATX(1,1)+AMATX(1,4))+B*STRES(1)
QMATX(2,1)=A*(AMATX(2,1)+AMATX(2,4))+B*STRES(3)
QMATX(3,1)=A*(AMATX(3,1)+AMATX(3,4))+B*STRES(3)
QMATX(4,1)=A*(AMATX(4,1)+AMATX(4,4))+B*STRES(2)
QMATX(1,2)=R0
QMATX(2,2)=R0
QMATX(3,2)=R0
QMATX(4,2)=R0
QMATX(1,3)=R0
QMATX(2,3)=R0
QMATX(3,3)=R0
QMATX(4,3)=R0
QMATX(1,4)=QMATX(1,1)
QMATX(2,4)=QMATX(2,1)
QMATX(3,4)=QMATX(3,1)
QMATX(4,4)=QMATX(4,1)
ELSEIF(NTYPE.EQ.3)THEN
C Axisymmetric
A=R1/R3
B=-R2/R3
QMATX(1,1)=A*(AMATX(1,1)+AMATX(1,4)+AMATX(1,5))+B*STRES(1)
QMATX(2,1)=A*(AMATX(2,1)+AMATX(2,4)+AMATX(2,5))+B*STRES(3)
QMATX(3,1)=A*(AMATX(3,1)+AMATX(3,4)+AMATX(3,5))+B*STRES(3)
QMATX(4,1)=A*(AMATX(4,1)+AMATX(4,4)+AMATX(4,5))+B*STRES(2)
QMATX(5,1)=A*(AMATX(5,1)+AMATX(5,4)+AMATX(5,5))+B*STRES(4)
QMATX(1,2)=R0
QMATX(2,2)=R0
QMATX(3,2)=R0
QMATX(4,2)=R0
QMATX(5,2)=R0
QMATX(1,3)=R0
QMATX(2,3)=R0
QMATX(3,3)=R0
QMATX(4,3)=R0
QMATX(5,3)=R0
QMATX(1,4)=QMATX(1,1)
QMATX(2,4)=QMATX(2,1)
QMATX(3,4)=QMATX(3,1)
QMATX(4,4)=QMATX(4,1)
QMATX(5,4)=QMATX(5,1)
QMATX(1,5)=QMATX(1,1)
QMATX(2,5)=QMATX(2,1)
QMATX(3,5)=QMATX(3,1)
QMATX(4,5)=QMATX(4,1)
QMATX(5,5)=QMATX(5,1)
ENDIF
C
RETURN
END

```

```

SUBROUTINE BETRIA
1(   BETRL      ,EEN          ,FINCR        ,NTYPE      )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION
1   BETRL(*)           ,EEN(*)               ,FINCR(3,3)
DIMENSION
1   AUXM(2,2)         ,BEN(4)                ,BENMTX(2,2)
2   BETRLM(2,2)
C*****
C COMPUTES THE "ELASTIC TRIAL" LEFT CAUCHY-GREEN STRAIN TENSOR FOR
C HYPERELASTIC-BASED LARGE STRAIN ELASTO-PLASTIC MODELS ACCORDING TO
C THE FORMULA:
C
C
C
C

$$\mathbf{B}_{n+1}^{e \text{ trial}} := \mathbf{F}_{incr}^T \mathbf{B}_n \mathbf{F}_{incr}$$

C WHERE  $\mathbf{B}_n^e$  IS OBTAINED AS:
C
C

$$\mathbf{B}_n^e := \exp[2 \mathbf{E}_n^e]$$

C WITH  $\mathbf{E}_n^e$  DENOTING THE ELASTIC LOGARITHMIC STRAIN AT t .
C REFERENCE: Box 14.3, item (ii)
C*****
    BEN(1)=EEN(1)
    BEN(2)=EEN(2)
    BEN(3)=EEN(3)
    BEN(4)=EEN(4)
C Convert engineering elastic logarithmic strain components into the
C corresponding elastic left Cauchy-Green strain tensor components
    CALL SETBE(BEN,NTYPE)
C Convert left Cauchy-Green strain tensor from vector array to matrix
C form
    BENMTX(1,1)=BEN(1)
    BENMTX(2,1)=BEN(3)
    BENMTX(1,2)=BEN(3)
    BENMTX(2,2)=BEN(2)
C
C In-plane components of the elastic trial left Cauchy-Green tensor
C
    CALL RVZERO(AUXM,4)
    DO 30 I=1,2
      DO 20 J=1,2
        DO 10 K=1,2
          AUXM(I,J)=AUXM(I,J)+FINCR(I,K)*BENMTX(K,J)
10       CONTINUE
20     CONTINUE
30   CONTINUE
    CALL RVZERO(BETRLM,4)
    DO 60 I=1,2
      DO 50 J=1,2
        DO 40 K=1,2
          BETRLM(I,J)=BETRLM(I,J)+AUXM(I,K)*FINCR(J,K)
40       CONTINUE
50     CONTINUE
60   CONTINUE
C
C
C Store  $\mathbf{B}_{n+1}^{e \text{ trial}}$  in array form
C
    BETRL(1)=BETRLM(1,1)
    BETRL(2)=BETRLM(2,2)
    BETRL(3)=BETRLM(1,2)
C out-of-plane component
    IF(NTYPE.EQ.2)THEN
      BETRL(4)=BEN(4)
    ELSEIF(NTYPE.EQ.3)THEN
      BETRL(4)=BEN(4)*FINCR(3,3)**2
    ENDIF
C
    RETURN
END

```

```

      SUBROUTINE CHECK2(MXFRON)
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C
C Hyplas database: Global parameters and common blocks
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C Local array
      DIMENSION
      1 NDFRO(MELEM)
C*****
C PERFORMS FURTHER CHECKS ON THE INPUT DATA
C*****
1010 FORMAT(' Check why node',I4,' never appears')
1020 FORMAT('// Maximum frontwidth encountered =',I5)
      DO 10 IELEM=1,NELEM
        NDFRO(IELEM)=0
      10 CONTINUE
C Check against two identical nodal coordinates
      IREPCO=0
      DO 40 IPOIN=2,NPOIN
        KPOIN=IPOIN-1
        DO 30 JPOIN=1,KPOIN
          DO 20 IDIME=1,NDIME
            IF(COORD(IDIME,IPOIN,1).NE.COORD(IDIME,JPOIN,1))GOTO 30
          20 CONTINUE
          IREPCO=IREPCO+1
        30 CONTINUE
      40 CONTINUE
C... send warning message if there are nodes with identical coordinates
      IF(IREPCO.NE.0)CALL ERRPRT('WD0001')
C Check for invalid node numbers in connectivity list
      DO 70 IELEM=1,NELEM
        IGRUP=IGRPID(IELEM)
        IELIDN=IELTID(IGRUP)
        NNODE=IELPRP(3,IELIDN)
        DO 60 INODE=1,NNODE
          IF(LNODS(IELEM,INODE).LE.0.OR.LNODS(IELEM,INODE).GT.NPOIN)
            1 CALL ERRPRT('ED0038')
        60 CONTINUE
      70 CONTINUE
C Change the sign of the last appearance of each degree of freedom
      DO 90 IELEM=1,NELEM
        IGRUP=IGRPID(IELEM)
        IELIDN=IELTID(IGRUP)
        NNODE=IELPRP(3,IELIDN)
        DO 80 INODE=1,NNODE
          DO 75 IDOFN=2,NDOFN
            LNODS(IELEM,NNODE*(IDOFN-1)+INODE)=
              1 LNODS(IELEM,INODE)+NPOIN*(IDOFN-1)
          75 CONTINUE
        80 CONTINUE
      90 CONTINUE
      DO 150 ITOTV=1,NTOTV
        KSTAR=0
        DO 130 IELEM=1,NELEM
          IGRUP=IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NNODE=IELPRP(3,IELIDN)
          KZERO=0
          DO 120 INODE=1,NNODE
            DO 110 IDOFN=1,NDOFN
              IEVAB=(IDOFN-1)*NNODE+INODE
              IPOIN=IABS(LNODS(IELEM,INODE))
              IF(MASTER(NDOFN*(IPOIN-1)+IDOFN).NE.ITOTV)GOTO 110
              KZERO=KZERO+1
              IF(KSTAR.NE.0)GOTO 100
              KSTAR=IELEM
              NDFRO(IELEM)=NDFRO(IELEM)+1
            100 CONTINUE
            LELEM=IELEM
            LEVAB=IEVAB
          110 CONTINUE
          120 CONTINUE
        130 CONTINUE
        IF(KSTAR.EQ.0)GOTO 150
        IF(LELEM.LT.NELEM)NDFRO(LELEM+1)=NDFRO(LELEM+1)-1
        LNODS(LELEM,LEVAB)=-LNODS(LELEM,LEVAB)
      150 CONTINUE
C Check for any repetition of a node number within an element
      DO 200 IPOIN=1,NPOIN
        KSTAR=0
        DO 170 IELEM=1,NELEM
          IGRUP=IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NNODE=IELPRP(3,IELIDN)
          KZERO=0
          DO 160 INODE=1,NNODE
            IF(IABS(LNODS(IELEM,INODE)).NE.IPOIN)GOTO 160
            KZERO=KZERO+1
            IF(KZERO.GT.1)CALL ERRPRT('ED0039')
            IF(KSTAR.EQ.0)KSTAR=IELEM
          160 CONTINUE
        170 CONTINUE
C Check that coordinates for an unused node have not been specified
      IF(KSTAR.EQ.0)THEN

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```

        WRITE(16,1010)IPOIN
        CALL ERRPRT('ED0040')
    ENDIF
200 CONTINUE
C Calculate the largest frontwidth
    NFRONT=0
    MXFRON=0
    DO 210 IELEM=1,NELEM
        NFRONT=NFRONT+NDFRO(IELEM)
        IF(NFRONT.GT.MXFRON)MXFRON=NFRONT
210 CONTINUE
    WRITE(16,1020)MXFRON
    IF(MXFRON.GT.MFRON)CALL ERRPRT('ED0041')
C Check data for nodes with prescribed displacements
    DO 230 IVFIX=1,NVFIX
        IF(NOFIX(IVFIX).LE.0.OR.NOFIX(IVFIX).GT.NPOIN)THEN
            CALL ERRPRT('ED0042')
        ENDIF
        KVFIX=IVFIX-1
        DO 220 JVFIX=1,KVFIX
            IF(IVFIX.NE.1.AND.NOFIX(IVFIX).EQ.NOFIX(JVFIX))THEN
                CALL ERRPRT('ED0043')
            ENDIF
220 CONTINUE
230 CONTINUE
    RETURN
END

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```

      SUBROUTINE CHKNDE
1(   FOUND      ,NNODE      ,NEDGEL      ,NODCHK      ,NORDEB      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL FOUND
      DIMENSION
1      NODCHK(NNODE)      ,NORDEB(NNODE,NEDGEL)
C*****
C CHECKS WHETHER A GIVEN SET OF LOCAL ELEMENT NODE NUMBERS CORRESPOND TO
C ONE OF THE ELEMENT BOUNDARIES (EDGES IN 2-D AND FACETS IN 3-D). IF IT
C DOES, RETURNS (STORED IN NODCHK) THE LOCAL NODE NUMBERS ORDERED FOR
C NUMERICAL INTEGRATION ON BOUNDARY.
C*****
      FOUND=.FALSE.
C Searches for the element boundary whose nodes coincide with the given
C set
      DO 20 IEDGEL=1,NEDGEL
        DO 10 INODE=1,NNODE
          IF( (NODCHK(INODE).NE.0.AND.NORDEB(INODE,IEDGEL).EQ.0).OR.
1          (NODCHK(INODE).EQ.0.AND.NORDEB(INODE,IEDGEL).NE.0))GOTO 20
        10 CONTINUE
        FOUND=.TRUE.
        GOTO 30
      20 CONTINUE
C
      30 CONTINUE
      IF(FOUND)THEN
C If the given node set corresponds indeed to one of the boundaries of
C the element, stores the node numbers in NODCHK ordered for numerical
C integration on the boundary.
        DO 40 INODE=1,NNODE
          INODEG=NORDEB( INODE,IEDGEL)
          IF( INODEG.NE.0)NODCHK( INODEG)=INODE
        40 CONTINUE
      ENDIF
C
      RETURN
      END

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      SUBROUTINE CONVER
1(   CONVRG   ,DIVERG   ,ITER   ,TOLER   ,TFACT   )
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C
C Hyplas database: Global parameters and common blocks
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C
      LOGICAL CONVRG,DIVERG
      SAVE RATOLD ,REMOLD
      DATA R0 ,R20 ,R100 ,R1000 /
1      0.0D0,20.0D0,100.0D0,1000.0D0/
C*****
C COMPUTE GLOBAL RESIDUAL (OUT-OF-BALANCE) FORCE VECTOR AND ITS RELATIVE
C NORM AND SET EQUILIBRIUM CONVERGENCE FLAG
C
C REFERENCE: Expressions (4.72) and (4.77)
C*****
1000 FORMAT(6X,I3,19X,G14.6,15X,G14.6)
1010 FORMAT(6X,I3,11X,G14.6,6X,G14.6,6X,G14.6)
C Initialize relevant variables
C -----
      CONVRG=.FALSE.
      DIVERG=.FALSE.
      RESID=R0
      RETOT=R0
      REMAX=R0
C Evaluate global nodal internal and external forces
C -----
      CALL RVZERO(STFOR,NTOTV)
      CALL RVZERO(TOFOR,NTOTV)
      DO 30 IELEM=1,NELEM
          IGRUP =IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NNODE =IELPRP(3,IELIDN)
          KEVAB=0
          DO 20 INODE=1,NNODE
              LOCNO=IABS(LNODS(IELEM,INODE))
              DO 10 IDOFN=1,NDOFN
                  KEVAB=KEVAB+1
                  NPOSI=MASTER((LOCNO-1)*NDOFN+IDOFN)
C current internal force
                  STFOR(NPOSI)=STFOR(NPOSI)+ELOAD(KEVAB,IELEM)
C current external force
                  TOFOR(NPOSI)=TOFOR(NPOSI)+TFACT*RLOAD(KEVAB,IELEM)
          10      CONTINUE
          20      CONTINUE
          30      CONTINUE
C Loop over nodal points
C -----
      DO 70 IPOIN=1,NPOIN
          ISVAB=(IPOIN-1)*NDOFN
C Search for node in prescribed displacements
      DO 60 IVFIX=1,NVFIX
          IF(NOFIX(IVFIX).EQ.IPOIN.AND.ANGLE(IVFIX).NE.R0)THEN
C Rotate forces to local nodal coordinate system for prescribed
C displacements at an angle (for 2-D only)
              C=COS(ANGLE(IVFIX))
              S=SIN(ANGLE(IVFIX))
              ISVAB=ISVAB+1
              JSVAB=ISVAB+1
              GASHI= C*STFOR(ISVAB)+S*STFOR(JSVAB)
              GASHJ=-S*STFOR(ISVAB)+C*STFOR(JSVAB)
              STFOR(ISVAB)=GASHI
              STFOR(JSVAB)=GASHJ
              GASHI= C*TOFOR(ISVAB)+S*TOFOR(JSVAB)
              GASHJ=-S*TOFOR(ISVAB)+C*TOFOR(JSVAB)
              TOFOR(ISVAB)=GASHI
              TOFOR(JSVAB)=GASHJ
C Evaluate reactions
              KSVAB=ISVAB-1
              DO 40 IDOFN=1,NDOFN
                  KSVAB=KSVAB+1
                  IF(IFFIX(KSVAB).NE.0)THEN
                      TREAC(IVFIX,IDOFN)=STFOR(KSVAB)-TOFOR(KSVAB)
                      TOFOR(KSVAB)=TOFOR(KSVAB)+TREAC(IVFIX,IDOFN)
                  ELSE
                      TREAC(IVFIX,IDOFN)=R0
                  ENDIF
              40      CONTINUE
C Rotate forces and reactions back to global system
              GASHI= C*STFOR(ISVAB)-S*STFOR(JSVAB)
              GASHJ= S*STFOR(ISVAB)+C*STFOR(JSVAB)
              STFOR(ISVAB)=GASHI
              STFOR(JSVAB)=GASHJ
              GASHI= C*TOFOR(ISVAB)-S*TOFOR(JSVAB)
              GASHJ= S*TOFOR(ISVAB)+C*TOFOR(JSVAB)
              TOFOR(ISVAB)=GASHI
              TOFOR(JSVAB)=GASHJ
              GASHI= C*TREAC(IVFIX,1)-S*TREAC(IVFIX,2)
              GASHJ= S*TREAC(IVFIX,1)+C*TREAC(IVFIX,2)
              TREAC(IVFIX,1)=GASHI
              TREAC(IVFIX,2)=GASHJ
              GOTO 70
          ELSEIF(NOFIX(IVFIX).EQ.IPOIN)THEN

```

```

C Evaluate reactions
      DO 50 IDOFN=1,NDOFN
        ISVAB=ISVAB+1
        IF (IFFIX(ISVAB).NE.0) THEN
          TREAC(IVFIX,IDOFN)=STFOR(ISVAB)-TOFOR(ISVAB)
          TOFOR(ISVAB)=TOFOR(ISVAB)+TREAC(IVFIX,IDOFN)
        ELSE
          TREAC(IVFIX,IDOFN)=R0
        ENDIF
      50 CONTINUE
      GOTO 70
    ENDIF
  60 CONTINUE
  70 CONTINUE
C Evaluate residual and external force norm
C -----
      DO 80 ITOTV=1,NTOTV
        REFOR=TOFOR(ITOTV)-STFOR(ITOTV)
        RESID=RESID+REFOR*REFOR
        RETOT=RETOT+TOFOR(ITOTV)*TOFOR(ITOTV)
C maximum nodal residual
        AGASH=ABS(REFOR)
        IF (AGASH.GT.REMAX) REMAX=AGASH
      80 CONTINUE
C Euclidean norm of residual
      RESID=SQRT(RESID)
C Euclidean norm of external force
      RETOT=SQRT(RETOT)
C compute relative residual norm
      IF (RETOT.EQ.R0) THEN
        RATIO=R0
      ELSE
        RATIO=R100*RESID/RETOT
      ENDIF
      IF (NALGO.GT.0) THEN
        WRITE(16,1000) IITER,RATIO,REMAX
        WRITE(*,1000) IITER,RATIO,REMAX
      ELSE
        WRITE(16,1010) IITER,RATIO,REMAX,TFACT
        WRITE(*,1010) IITER,RATIO,REMAX,TFACT
      ENDIF
C Set convergence/divergence flags
C -----
      IF (RATIO.LE.TOLER.OR.ABS(REMAX).LE.(TOLER/R1000)) CONVRG=.TRUE.
      IF (IITER.NE.1.AND.(RATIO.GT.R20*RATOLD.OR.REMAX.GT.R20*REMOLD))
1 DIVERG=.TRUE.
      RATOLD=RATIO
      REMOLD=REMAX
C Evaluate element residual forces before exit -> store it in ELOAD
C -----
      DO 100 IELEM=1,NELEM
        IGRUP=IGRPID(IELEM)
        IELIDN=IELTID(IGRUP)
        NEVAB=IELPRP(5,IELIDN)
C Current element residual (out-of-balance force) = current element
C external load - current element internal force
        DO 90 IEVAB=1,NEVAB
          ELOAD(IEVAB,IELEM)=TFACT*RLOAD(IEVAB,IELEM)-ELOAD(IEVAB,IELEM)
        90 CONTINUE
      100 CONTINUE
C
      RETURN
      END

```

```

SUBROUTINE CSTEP2
1(  AMATX      ,BETRL      ,DMATX      ,STRES      ,DETF      ,
2  NTYPE      )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER
1(  MADIM=5      ,MSTRE=4      )
EXTERNAL DDLGD2 ,DLGD2
LOGICAL  OUTOFFP
DIMENSION
1  AMATX(MADIM,MADIM)      ,BETRL(MSTRE)
2  DMATX(MSTRE,MSTRE)      ,STRES(MSTRE)
DIMENSION
1  AUXMTX(MADIM,MADIM)      ,BMTX(MADIM,MADIM)
2  DLGAUX(MSTRE,MSTRE)      ,DLGMTX(MADIM,MADIM)
3  DMATX2(MADIM,MADIM)      ,IG(MADIM)
DATA
1  R1      ,R2      /
2  1.0D0,2.0D0 /
DATA
1  IG(1),IG(2),IG(3),IG(4),IG(5) /
2  1      ,3      ,3      ,2      ,4      /
C*****
C COMPUTE THE CONSISTENT SPATIAL TANGENT MODULUS 'a' FOR LARGE STRAIN
C HYPERELASTIC-BASED ELASTOPLASTIC MATERIAL MODELS
C
C REFERENCE: Section 14.5
C*****
IF(NTYPE.EQ.3)THEN
OUTOFFP=.TRUE.
NADIM=5
ELSEIF(NTYPE.EQ.1.OR.NTYPE.EQ.2)THEN
OUTOFFP=.FALSE.
NADIM=4
ELSE
CALL ERRPR('EI0020')
ENDIF
C
C Compute the derivative dE/dB
CALL DISO2
1(  DLGAUX      ,DDLGD2      ,DLGD2      ,OUTOFFP      ,BETRL      )
FACTOR=R1/DETF
DO 20 I=1,MSTRE
DO 10 J=1,MSTRE
DLGAUX(I,J)=FACTOR*DLGAUX(I,J)
10 CONTINUE
20 CONTINUE
C
C Rearrange components of DMATX and dE/dB into the
C ordering (11,21,12,22,33), compatible with the discrete gradient G.
CALL RVZERO(DMATX2,MADIM*MADIM)
CALL RVZERO(DLGMTX,MADIM*MADIM)
DO 40 INEW=1,NADIM
DO 30 JNEW=1,NADIM
IOLD=IG(INEW)
JOLD=IG(JNEW)
DLGMTX(INEW,JNEW)=DLGAUX(IOLD,JOLD)
DMATX2(INEW,JNEW)=DMATX(IOLD,JOLD)
30 CONTINUE
40 CONTINUE
C Compute remaining needed matrix [DELTA_ik BETRL_jl+DELTA_jl BETRL_il]
CALL RVZERO(BMTX,MADIM*MADIM)
BMTX(1,1)=R2*BETRL(1)
BMTX(1,3)=R2*BETRL(3)
BMTX(2,1)=BETRL(3)
BMTX(2,2)=BETRL(1)
BMTX(2,3)=BETRL(2)
BMTX(2,4)=BETRL(3)
BMTX(3,1)=BETRL(3)
BMTX(3,2)=BETRL(1)
BMTX(3,3)=BETRL(2)
BMTX(3,4)=BETRL(3)
BMTX(4,2)=R2*BETRL(3)
BMTX(4,4)=R2*BETRL(2)
IF(OUTOFFP)BMTX(5,5)=R2*BETRL(4)
C Assemble the spatial tangent modulus a
C -----
C compute the product D:L:B
CALL RVZERO(AUXMTX,MADIM*MADIM)
DO 70 I=1,NADIM
DO 60 J=1,NADIM
DO 50 K=1,NADIM
AUXMTX(I,J)=AUXMTX(I,J)+DMATX2(I,K)*DLGMTX(K,J)
50 CONTINUE
60 CONTINUE
70 CONTINUE
CALL RVZERO(AMATX,MADIM*MADIM)
DO 100 I=1,NADIM
DO 90 J=1,NADIM
DO 80 K=1,NADIM
AMATX(I,J)=AMATX(I,J)+AUXMTX(I,K)*BMTX(K,J)
80 CONTINUE
90 CONTINUE
100 CONTINUE
C subtract [SIGMA_il DELTA_jk]
AMATX(1,1)=AMATX(1,1)-STRES(1)
AMATX(1,3)=AMATX(1,3)-STRES(3)
AMATX(2,1)=AMATX(2,1)-STRES(3)
AMATX(2,3)=AMATX(2,3)-STRES(2)
AMATX(3,2)=AMATX(3,2)-STRES(1)
AMATX(3,4)=AMATX(3,4)-STRES(3)
AMATX(4,2)=AMATX(4,2)-STRES(3)
AMATX(4,4)=AMATX(4,4)-STRES(2)
IF(OUTOFFP)AMATX(5,5)=AMATX(5,5)-STRES(4)
RETURN
END

```

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SUBROUTINE CSTOGD
1( AMATX ,B ,IPROPS ,NTYPE ,RPROPS ,
2 STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
LOGICAL OUTOFFP ,REPEAT
PARAMETER
1( MADIM=5 ,MSTRE=4 ,NDIM=2 )
PARAMETER(IPOGDC=2)
DIMENSION
1 AMATX(MADIM,MADIM) ,B(MSTRE) ,IPROPS(*) ,
2 RPROPS(*) ,STRES(MSTRE)
DIMENSION
1 DELTA(3,3) ,DPSTRE(3,3) ,DTAUDB(MSTRE,MSTRE) ,
2 EIGPRJ(MSTRE,NDIM) ,EIGB(NDIM) ,PSTALP(3) ,
3 PSTRES(3) ,PSTRTC(3)
DATA
1 DELTA(1,1) ,DELTA(1,2) ,DELTA(1,3) /
2 1.0D0 ,0.0D0 ,0.0D0 /
3 DELTA(2,1) ,DELTA(2,2) ,DELTA(2,3) /
4 0.0D0 ,1.0D0 ,0.0D0 /
5 DELTA(3,1) ,DELTA(3,2) ,DELTA(3,3) /
6 0.0D0 ,0.0D0 ,1.0D0 /
DATA
1 R1 ,R2 ,R3 ,R6 /
2 1.0D0,2.0D0,3.0D0,6.0D0/
C*****
C COMPUTATION OF THE CONSISTENT SPATIAL TANGENT MODULUS 'a' FOR
C OGDEN TYPE HYPERELASTIC MATERIAL MODEL.
C PLANE STRESS, PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 13.5.2
C*****
C Set Ogden material constants
C =====
C Number of terms in Ogden's strain-energy function
NOGTRM=IPROPS(3)
C Bulk modulus (incompressibility penalty parameter)
BULK=RPROPS(IPOGDC+NOGTRM*2)
C Compute principal stretches
C =====
C Perform spectral decomposition of the left Cauchy-Green tensor B
CALL SPDEC2
1( EIGPRJ ,EIGB ,REPEAT ,B )
C Compute in-plane principal stretches
PSTRTC(1)=SQRT(EIGB(1))
PSTRTC(2)=SQRT(EIGB(2))
C and out-of-plane stretches
IF(NTYPE.EQ.1)THEN
PSTRTC(3)=R1/(PSTRTC(1)*PSTRTC(2))
DETF=R1
ELSEIF(NTYPE.EQ.2)THEN
PSTRTC(3)=R1
DETF=PSTRTC(1)*PSTRTC(2)
ELSEIF(NTYPE.EQ.3)THEN
PSTRTC(3)=SQRT(B(4))
DETF=PSTRTC(1)*PSTRTC(2)*PSTRTC(3)
ENDIF
C Recover principal Kirchhoff stresses (from the given Cauchy stress)
PSTRES(1)=(STRES(1)*EIGPRJ(1,1)+STRES(2)*EIGPRJ(2,1)+
1 R2*STRES(3)*EIGPRJ(3,1))*DETF
PSTRES(2)=(STRES(1)*EIGPRJ(1,2)+STRES(2)*EIGPRJ(2,2)+
1 R2*STRES(3)*EIGPRJ(3,2))*DETF
IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)PSTRES(3)=STRES(4)*DETF
C Compute derivatives of principal Kirchhoff stresses
C =====
CALL RVZERO(DPSTRE,9)
IF(NTYPE.EQ.1) THEN
C Plane stress: Perfectly incompressibility assumed
C -----
NSTRA=2
DO 10 IP=1,NOGTRM
ALPHA=RPROPS(IPOGDC+IP*2-1)
ALPHMU=ALPHA*RPROPS(IPOGDC+IP*2-2)
PSTALP(1)=PSTRTC(1)**ALPHA
PSTALP(2)=PSTRTC(2)**ALPHA
FACTOR=R1/(PSTALP(1)*PSTALP(2))
DO I=1,NSTRA
DO J=1,NSTRA
DPSTRE(I,J)=DPSTRE(I,J)+ALPHMU/(R2*PSTRTC(J)**2)*
1 (PSTALP(J)*DELTA(I,J)+FACTOR)
END DO
END DO
10 CONTINUE
ELSE IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
C Plane strain and axisymmetric: Regularised Ogden model
C -----
C compute principal Kirchhoff stresses derivatives
R1D3=R1/R3
IF(NTYPE.EQ.2)THEN
NSTRA=2
ELSEIF(NTYPE.EQ.3)THEN
NSTRA=3
ENDIF
DO 40 IP=1,NOGTRM
CMU=RPROPS(IPOGDC-1+IP*2-1)
ALPHA=RPROPS(IPOGDC-1+IP*2)
PSTALP(1)=PSTRTC(1)**ALPHA
PSTALP(2)=PSTRTC(2)**ALPHA

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        PSTALP(3)=PSTRTC(3)**ALPHA
        ALPHMU=ALPHA*CMU
        FACTOR=R1D3*(PSTALP(1)+PSTALP(2)+PSTALP(3))
        FACVOL=DETF**(-ALPHA*R1D3)
        DO 30 I=1,NSTRA
            DO 20 J=1,NSTRA
                DPSTRE(I,J)=DPSTRE(I,J)+ALPHMU*FACVOL/(R6*PSTRTC(J)**2)*
                    (FACTOR-PSTALP(I)-PSTALP(J)+R3*PSTALP(I)*
                    DELTA(I,J))
            CONTINUE
        CONTINUE
        DO 60 I=1,NSTRA
            DO 50 J=1,NSTRA
                DPSTRE(I,J)=DPSTRE(I,J)+BULK/(R2*PSTRTC(J)**2)
            CONTINUE
        CONTINUE
    ENDIF
C Compute the derivative of the Kirchhoff stress with respect to B
C (use routine for computation of derivative of general isotropic
C tensor functions of one tensor)
C =====
    IF(NTYPE.EQ.3)THEN
        OUTOFF=.TRUE.
        NADIM=5
    ELSE
        OUTOFF=.FALSE.
        NADIM=4
    ENDIF
    CALL DGISO2
    1( DPSTRE ,DTAUSB ,EIGPRJ ,EIGB ,PSTRES ,
    2 OUTOFF ,REPEAT )
C Assemble the spatial tangent modulus 'a'
C =====
    R2DDET=R2/DETF
C upper triangle and diagonal terms
    AMATX(1,1)=R2DDET*(DTAUSB(1,1)*B(1)+DTAUSB(1,3)*B(3))-STRES(1)
    AMATX(1,2)=R2DDET*(DTAUSB(1,3)*B(1)+DTAUSB(1,2)*B(3))
    AMATX(1,3)=R2DDET*(DTAUSB(1,1)*B(3)+DTAUSB(1,3)*B(2))-STRES(3)
    AMATX(1,4)=R2DDET*(DTAUSB(1,3)*B(3)+DTAUSB(1,2)*B(2))
    AMATX(2,2)=R2DDET*(DTAUSB(3,3)*B(1)+DTAUSB(3,2)*B(3))
    AMATX(2,3)=R2DDET*(DTAUSB(3,1)*B(3)+DTAUSB(3,3)*B(2))-STRES(2)
    AMATX(2,4)=R2DDET*(DTAUSB(3,3)*B(3)+DTAUSB(3,2)*B(2))
    AMATX(3,3)=R2DDET*(DTAUSB(3,1)*B(3)+DTAUSB(3,3)*B(2))
    AMATX(3,4)=R2DDET*(DTAUSB(3,3)*B(3)+DTAUSB(3,2)*B(2))-STRES(3)
    AMATX(4,4)=R2DDET*(DTAUSB(2,3)*B(3)+DTAUSB(2,2)*B(2))-STRES(2)
    IF(NTYPE.EQ.3) THEN
        AMATX(1,5)=R2DDET*DTAUSB(1,4)*B(4)
        AMATX(2,5)=R2DDET*DTAUSB(3,4)*B(4)
        AMATX(3,5)=R2DDET*DTAUSB(3,4)*B(4)
        AMATX(4,5)=R2DDET*DTAUSB(2,4)*B(4)
        AMATX(5,5)=R2DDET*DTAUSB(4,4)*B(4)-STRES(4)
    ENDIF
C lower triangle
    DO 80 J=1,NADIM
        DO 70 I=J+1,NADIM
            AMATX(I,J)=AMATX(J,I)
        CONTINUE
    CONTINUE
70
80
C
    RETURN
END

```

```

SUBROUTINE CSTDPS
1(  AMATX ,DGAM ,EPFLAG ,FINCR ,IPROPS ,
2  LALGVA ,NTYPE ,RPROPS ,RSTAVA ,RSTAVN ,
3  STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER
1(  IPHARD=6 ,IPHVAR=5 ,MADIM=5 ,NDIM=2 ,NGDIM=4 ,
2  NIPROP=3 ,NLALGV=6 ,NRALGV=4 ,NRSTAV=5 ,NSTRE=4 ,
3  NSYST=4 )
C Arguments
LOGICAL
1  EPFLAG ,LALGVA(NLALGV)
DIMENSION
1  AMATX(MADIM,MADIM) ,DGAM(NRALGV) ,FINCR(3,3) ,
2  IPROPS(NIPROP) ,RPROPS(*) ,RSTAVA(NRSTAV) ,
3  RSTAVN(NRSTAV) ,STRES(NSTRE)
C Local arrays and variables
LOGICAL
1  S1ACT ,S2ACT ,S3ACT ,S4ACT
DIMENSION
1  APMATX(NGDIM,NGDIM) ,AUXMTX(NGDIM,NGDIM) ,AUX2ND(NDIM,NDIM) ,
2  AUX4TH(NDIM,NDIM,NDIM,NDIM) ,BEISO(3,3) ,
3  BMATX(NDIM,NDIM,NSYST) ,DELKRO(NDIM,NDIM) ,
4  DEREXP(3,3,3,3) ,DEVPRJ(NGDIM,NGDIM) ,DEVSTR(NGDIM) ,
5  DSOMO(NDIM,NDIM) ,DUMATX(NDIM,NDIM,NDIM,NDIM) ,
6  FE(2,2) ,FEFETR(NGDIM,NGDIM) ,FEISO(2,2) ,
7  FEN(2,2) ,FETISO(2,2) ,FETRL(2,2) ,
8  FOIDS(NGDIM,NGDIM) ,FPILOG(3,3) ,GINV(NSYST,NSYST) ,
9  GMATX(NSYST,NSYST) ,IACSET(NSYST) ,
0  SMOMS0(NDIM,NDIM,NSYST) ,SOID(NGDIM) ,
1  SOM0(NDIM,NDIM,NSYST) ,
2  UMATX(NDIM,NDIM,NDIM,NDIM) ,VECM(NDIM,NSYST) ,
3  VECM0(NDIM,NSYST) ,VECS(NDIM,NSYST) ,VECS0(NDIM,NSYST) ,
4  VMATX(NGDIM,NGDIM)
C... Kroenecker delta
DATA
1  DELKRO(1,1),DELKRO(1,2)/
2  1.0D0 ,0.D0 /
3  DELKRO(2,1),DELKRO(2,2)/
4  0.0D0 ,1.D0 /
C... fourth order (symmetric subspace) identity components stored in
C matrix form using G matrix ordering (11,21,12,22)
DATA
1  FOIDS(1,1),FOIDS(1,2),FOIDS(1,3),FOIDS(1,4)/
2  1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3  FOIDS(2,1),FOIDS(2,2),FOIDS(2,3),FOIDS(2,4)/
4  0.0D0 ,0.5D0 ,0.5D0 ,0.0D0 /
5  FOIDS(3,1),FOIDS(3,2),FOIDS(3,3),FOIDS(3,4)/
6  0.0D0 ,0.5D0 ,0.5D0 ,0.0D0 /
7  FOIDS(4,1),FOIDS(4,2),FOIDS(4,3),FOIDS(4,4)/
8  0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
C... second order identity components in stored in vector form using G
C matrix ordering
DATA
1  SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2  1.0D0 ,0.0D0 ,0.0D0 ,1.D0 /
DATA
1  R0 ,R1 ,R2 ,R3 /
2  0.0D0,1.0D0,2.0D0,3.0D0/
C*****
C COMPUTATION OF THE CONSISTENT SPATIAL TANGENT MODULUS 'a' FOR
C THE PLANAR DOUBBLE SLIP SINGLE CRYSTAL ELASTO-PLASTIC MODEL.
C MODEL VALID FOR PLANE STRAIN ONLY.
C
C REFERENCE: Expression (16.85)
C*****
C Stop program if not plane strain
IF(NTYPE.NE.2)CALL ERRPR('EI0035')
C Retrieve some state and algorithmic variables
C -----
C... current hardening internal variable
HRVAR=RSTAVA(IPHVAR)
C... current elastic deformation gradient
FE(1,1)=RSTAVA(1)
FE(2,1)=RSTAVA(2)
FE(1,2)=RSTAVA(3)
FE(2,2)=RSTAVA(4)
C... current active slip-systems logical flags
S1ACT=LALGVA(3)
S2ACT=LALGVA(4)
S3ACT=LALGVA(5)
S4ACT=LALGVA(6)
C... elastic deformation gradient at the beginning of the current load
C increment
FEN(1,1)=RSTAVN(1)
FEN(2,1)=RSTAVN(2)
FEN(1,2)=RSTAVN(3)
FEN(2,2)=RSTAVN(4)
C Retrieve material properties
C -----
C... neo-Hookean constants
GMODU=RPROPS(2)
BULK=RPROPS(3)
C... initial system orientation
THETA=RPROPS(4)
C... relative angle between systems
BETA=RPROPS(5)
C... number of sampling points on hardening curve
NHARD=IPROPS(3)
C Set some constants
C -----
R1D3=R1/R3
R2D3=R2*R1D3
C Assemble deviatoric projection tensor (use G matrix ordering)
DO 20 I=1,NGDIM
DO 10 J=1,NGDIM
DEVPRJ(I,J)=FOIDS(I,J)-R1D3*SOID(I)*SOID(J)
10 CONTINUE
20 CONTINUE
C Get current Cauchy deviatoric stress and Cauchy hydrostatic pressure
P=R1D3*(STRES(1)+STRES(2)+STRES(4))
C... use G matrix component ordering to store in-plane deviatoric

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C      Cauchy stress components
      DEVSTR(1)=STRES(1)-P
      DEVSTR(2)=STRES(3)
      DEVSTR(3)=STRES(3)
      DEVSTR(4)=STRES(2)-P
C Compute isochoric component of Fe and Be
      DETFE=FE(1,1)*FE(2,2)-FE(1,2)*FE(2,1)
      FACTOR=DETFE**(-R1D3)
      FEISO(1,1)=FACTOR*FE(1,1)
      FEISO(1,2)=FACTOR*FE(1,2)
      FEISO(2,1)=FACTOR*FE(2,1)
      FEISO(2,2)=FACTOR*FE(2,2)
      CALL RVZERO(BEISO,9)
      DO 50 I=1,2
        DO 40 J=1,2
          DO 30 K=1,2
            BEISO(I,J)=BEISO(I,J)+FEISO(I,K)*FEISO(J,K)
30      CONTINUE
40      CONTINUE
50      CONTINUE
      BEISO(3,3)=FACTOR*FACTOR
C Trace of isochoric component of Be
      TRBISO=BEISO(1,1)+BEISO(2,2)+BEISO(3,3)
C
C
C Compute ELASTIC tangent modulus
C =====
C
      GFAC=R2D3*GMODU*TRBISO/DETFE
      BULFAC=BULK/DETFE
      R2P=R2*P
C... assemble tensorially compact part
      DO 70 I=1,NGDIM
        DO 60 J=1,NGDIM
          AMATX(I,J)=BULFAC*SOID(I)*SOID(J)-R2P*FOIDS(I,J)+
1          GFAC*DEVPRJ(I,J)-
2          R2D3*(DEVSTR(I)*SOID(J)+SOID(I)*DEVSTR(J))
60      CONTINUE
70      CONTINUE
C... add non-compact part: delta_ik sigma_jl
      AMATX(1,1)=AMATX(1,1)+STRES(1)
      AMATX(3,1)=AMATX(3,1)+STRES(3)
      AMATX(2,2)=AMATX(2,2)+STRES(1)
      AMATX(4,2)=AMATX(4,2)+STRES(3)
      AMATX(1,3)=AMATX(1,3)+STRES(3)
      AMATX(3,3)=AMATX(3,3)+STRES(2)
      AMATX(2,4)=AMATX(2,4)+STRES(3)
      AMATX(4,4)=AMATX(4,4)+STRES(2)
C
C
      IF(EPFLAG)THEN
C
C Compute and add algorithm-consistent PLASTIC contribution to spatial
C tangent modulus
C =====
C
C Compute individual terms needed to assemble the plastic contribution
C -----
C
C Last elastic trial deformation gradient
      CALL RVZERO(FETRL,4)
      DO 100 I=1,2
        DO 90 J=1,2
          DO 80 K=1,2
            FETRL(I,J)=FETRL(I,J)+FINCR(I,K)*FEN(K,J)
80      CONTINUE
90      CONTINUE
100     CONTINUE
C... isochoric component
      DETFET=FETRL(1,1)*FETRL(2,2)-FETRL(1,2)*FETRL(2,1)
      VOLFAC=DETFET**(-R1D3)
      FETISO(1,1)=VOLFAC*FETRL(1,1)
      FETISO(2,1)=VOLFAC*FETRL(2,1)
      FETISO(1,2)=VOLFAC*FETRL(1,2)
      FETISO(2,2)=VOLFAC*FETRL(2,2)
C Assemble relevant fourth order tensor
      DO 140 I=1,NDIM
        DO 130 J=1,NDIM
          DO 120 K=1,NDIM
            DO 110 L=1,NDIM
              AUX4TH(I,J,K,L)=FEISO(I,L)*FETISO(J,K)
110      CONTINUE
120      CONTINUE
130      CONTINUE
140      CONTINUE
C... rearrange in matrix form with G matrix component ordering
      CALL ARRG02(AUX4TH,FEFETR)
C
C Compute exact exponential map derivative
C -----
C
C retrieve information on current set of active slip-systems and set up
C corresponding initial slip-system vectors
      IACSYS=0
      IF(S1ACT)THEN
C... system 1:
        IACSYS=IACSYS+1
        IACSET(IACSYS)=1
        VECS0(1,1)=COS(THETA)
        VECS0(2,1)=SIN(THETA)
        VECM0(1,1)=-SIN(THETA)
        VECM0(2,1)=COS(THETA)
      ENDIF
      IF(S2ACT)THEN
C... system 2:
        IACSYS=IACSYS+1
        IACSET(IACSYS)=2
        VECS0(1,2)=COS(THETA+BETA)
        VECS0(2,2)=SIN(THETA+BETA)
        VECM0(1,2)=-SIN(THETA+BETA)
        VECM0(2,2)=COS(THETA+BETA)
      ENDIF

```



```

      IF(S3ACT)THEN
        IACSYS=IACSYS+1
        IACSET(IACSYS)=3
C... system 3:
        VECS0(1,3)=-COS(THETA)
        VECS0(2,3)=-SIN(THETA)
        VECM0(1,3)=-SIN(THETA)
        VECM0(2,3)=COS(THETA)
      ENDIF
      IF(S4ACT)THEN
C... system 4:
        IACSYS=IACSYS+1
        IACSET(IACSYS)=4
        VECS0(1,4)=-COS(THETA+BETA)
        VECS0(2,4)=-SIN(THETA+BETA)
        VECM0(1,4)=-SIN(THETA+BETA)
        VECM0(2,4)=COS(THETA+BETA)
      ENDIF
C... number of currently active systems
      NACSYS=IACSYS
C Compute current elastic push forward of the slip-system vectors
C of the active systems
      CALL RVZERO(VECS,NDIM*NSYST)
      CALL RVZERO(VECM,NDIM*NSYST)
      DO 170 I=1,NDIM
        DO 160 J=1,NDIM
          DO 150 II=1,NACSYS
            ISYST=IACSET(II)
            VECS(I,ISYST)=VECS(I,ISYST)+FEISO(I,J)*VECS0(J,ISYST)
            VECM(I,ISYST)=VECM(I,ISYST)+FEISO(I,J)*VECM0(J,ISYST)
          150      CONTINUE
          160      CONTINUE
        170      CONTINUE
C Current slope of Taylor hardening curve
      HSLOPE=DPLFUN(HRVAR,NHARD,RPROPS(IPHARD))
C Compute logarithm of inverse of incremental plastic deformation
C gradient by summing up contributions from each active slip system
      CALL RVZERO(FPILOG,9)
      DO 200 II=1,NACSYS
        ISYST=IACSET(II)
        DO 190 I=1,2
          DO 180 J=1,2
            FPILOG(I,J)=FPILOG(I,J)-
              1      DGAM(ISYST)*VECS0(I,ISYST)*VECM0(J,ISYST)
          180      CONTINUE
          190      CONTINUE
        200      CONTINUE
C... and the corresponding exact derivative of the exponential map
      CALL DEXFPM( DEREXP ,NOCONV ,FPILOG )
C
C Compute jacobian of non-linear system of return mapping equations
C -----
C compute some preliminary matrices
      CALL RVZERO(BMATX,NDIM*NDIM*NSYST)
      DO 300 II=1,NACSYS
        ISYST=IACSET(II)
        DO 220 I=1,2
          DO 210 J=1,2
            SOM0(I,J,ISYST)=VECS0(I,ISYST)*VECM0(J,ISYST)
            SMOMS0(I,J,ISYST)=VECS(I,ISYST)*VECM0(J,ISYST)+
              1      VECM(I,ISYST)*VECS0(J,ISYST)
          210      CONTINUE
          220      CONTINUE
          CALL RVZERO(DSOM0,NDIM*NDIM)
          DO 260 I=1,2
            DO 250 J=1,2
              DO 240 K=1,2
                DO 230 L=1,2
                  DSOM0(I,J)=DSOM0(I,J)+
                    1      DEREXP(I,J,K,L)*SOM0(K,L,ISYST)
                230      CONTINUE
                240      CONTINUE
              250      CONTINUE
            260      CONTINUE
            DO 290 I=1,2
              DO 280 J=1,2
                DO 270 K=1,2
                  BMATX(I,J,ISYST)=BMATX(I,J,ISYST)+
                    1      FETISO(I,K)*DSOM0(K,J)
                270      CONTINUE
                280      CONTINUE
              290      CONTINUE
            300      CONTINUE
C Assemble exact jacobian of non-linear system
            DO 320 II=1,NACSYS
              ISYST=IACSET(II)
              DO 310 JJ=1,NACSYS
                JSYST=IACSET(JJ)
                GMATX(II,JJ)=GMODU*
                  1      SCAPRD(SMOMS0(1,1,ISYST),BMATX(1,1,JSYST),NDIM*NDIM)+
                  2      HSLOPE
              310      CONTINUE
            320      CONTINUE
C Invert jacobian: Note that for the double slip model only one or two
C systems may be active
            IF(NACSYS.EQ.1)THEN
              IF(GMATX(1,1).EQ.R0)CALL ERRPRT('EE0006')
              GINV(1,1)=R1/GMATX(1,1)
            ELSEIF(NACSYS.EQ.2)THEN
              DETG=GMATX(1,1)*GMATX(2,2)-GMATX(1,2)*GMATX(2,1)
              IF(DETG.EQ.R0)CALL ERRPRT('EE0006')
              DETGIN=R1/DETG
              GINV(1,1)=GMATX(2,2)*DETGIN
              GINV(2,2)=GMATX(1,1)*DETGIN
              GINV(1,2)=-GMATX(1,2)*DETGIN
              GINV(2,1)=-GMATX(2,1)*DETGIN
            ENDIF
C Compute U matrix
C -----
      CALL RVZERO(UMATX,NDIM*NDIM*NDIM*NDIM)
      DO 380 I=1,NDIM
        DO 370 J=1,NDIM

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DO 360 K=1,NDIM
DO 350 L=1,NDIM
DO 340 II=1,NACSYS
ISYST=IACSET(II)
DO 330 JJ=1,NACSYS
JSYST=IACSET(JJ)
UMATX(I,J,K,L)=UMATX(I,J,K,L)+SOM0(I,J,ISYST)*
GINV(II,JJ)*SM0MS0(K,L,JSYST)
1
330 CONTINUE
340 CONTINUE
350 CONTINUE
360 CONTINUE
370 CONTINUE
380 CONTINUE
C Compute product [D:U]
CALL RVZERO(DUMATX,NDIM*NDIM*NDIM*NDIM)
DO 440 I=1,NDIM
DO 430 J=1,NDIM
DO 420 K=1,NDIM
DO 410 L=1,NDIM
DO 400 M=1,NDIM
DO 390 N=1,NDIM
DUMATX(I,J,K,L)=DUMATX(I,J,K,L)+
DEREXP(I,J,M,N)*UMATX(M,N,K,L)
1
390 CONTINUE
400 CONTINUE
410 CONTINUE
420 CONTINUE
430 CONTINUE
440 CONTINUE
C... and the contribution to a^p involving the product D:U
CALL RVZERO(AUX4TH,NDIM*NDIM*NDIM*NDIM)
DO 490 I=1,NDIM
DO 480 J=1,NDIM
DO 470 K=1,NDIM
DO 460 L=1,NDIM
DO 450 M=1,NDIM
AUX4TH(I,J,K,L)=AUX4TH(I,J,K,L)+
DUMATX(I,J,K,M)*FEISO(L,M)
1
450 CONTINUE
460 CONTINUE
470 CONTINUE
480 CONTINUE
490 CONTINUE
CALL RVZERO(AUX2ND,NDIM*NDIM)
DO 530 I=1,NDIM
DO 520 J=1,NDIM
DO 510 K=1,NDIM
DO 500 L=1,NDIM
AUX2ND(I,J)=AUX2ND(I,J)+DUMATX(I,J,K,L)*FEISO(K,L)
500 CONTINUE
510 CONTINUE
520 CONTINUE
530 CONTINUE
DO 570 I=1,NDIM
DO 560 J=1,NDIM
DO 550 K=1,NDIM
DO 540 L=1,NDIM
AUX4TH(I,J,K,L)=AUX4TH(I,J,K,L)-
R1D3*AUX2ND(I,J)*DELKRO(K,L)
1
540 CONTINUE
550 CONTINUE
560 CONTINUE
570 CONTINUE
C... rearrange in matrix form
CALL ARRG02(AUX4TH,VMATX)
CALL RVZERO(AUXMTX,NGDIM*NGDIM)
DO 600 I=1,NGDIM
DO 590 J=1,NGDIM
DO 580 K=1,NGDIM
AUXMTX(I,J)=AUXMTX(I,J)+FEFETR(I,K)*VMATX(K,J)
580 CONTINUE
590 CONTINUE
600 CONTINUE
C Compute plastic contribution
CALL RVZERO(APMATX,NGDIM*NGDIM)
AUX=R2*GMODU*GMODU/DETFE
DO 630 I=1,NGDIM
DO 620 J=1,NGDIM
DO 610 K=1,NGDIM
APMATX(I,J)=APMATX(I,J)-AUX*DEVPRJ(I,K)*AUXMTX(K,J)
610 CONTINUE
620 CONTINUE
630 CONTINUE
C Add plastic contribution to spatial tangent modulus
DO 650 I=1,NGDIM
DO 640 J=1,NGDIM
AMATX(I,J)=AMATX(I,J)+APMATX(I,J)
640 CONTINUE
650 CONTINUE
C
ENDIF
C
RETURN
END

```

```

SUBROUTINE CTDAMA
1( DGAMA ,DMATX ,EPFLAG ,IPROPS ,NTYPE ,
2 RPROPS ,RSTAVA ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=6 ,MSTRE=4)
LOGICAL EPFLAG
DIMENSION
1 DMATX(MSTRE,MSTRE),IPROPS(*) ,RPROPS(*) ,
2 RSTAVA(MSTRE+2) ,STRES(MSTRE)
DIMENSION
1 DEVPRJ(MSTRE,MSTRE),FOID(MSTRE,MSTRE) ,S(MSTRE) ,
2 SOID(MSTRE)
DATA
1 FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2 1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3 FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4 0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5 FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6 0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7 FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8 0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
DATA
1 SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2 1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
DATA
1 R0 ,R1 ,R2 ,R3 ,R6 ,SMALL ,TOLDGA/
2 0.0D0,1.0D0,2.0D0,3.0D0,6.0D0,1.D-16,1.D-08/
C*****
C COMPUTATION OF THE CONSISTENT TANGENT MODULUS FOR LEMAITRE'S DUCTILE
C DAMAGE ELASTO-PLASTIC MODEL WITH PIECE-WISE LINEAR ISOTROPIC
C HARDENING.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 12.4.2
C*****
C Stops program if neither plane strain nor axisymmetric state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0052')
C Retrieve current hardening and damage variables
HVAR=RSTAVA(MSTRE+1)
DAMAGE=RSTAVA(MSTRE+2)
OMEGA=R1-DAMAGE
C Retrieve material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
DAMEXP=RPROPS(4)
DAMDEN=RPROPS(5)
NHARD=IPROPS(3)
C Shear and bulk moduli
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R1D3=R1/R3
C Set deviatoric projection tensor
IF(NTYPE.EQ.2)THEN
NSTRE=3
ELSEIF(NTYPE.EQ.3)THEN
NSTRE=4
ENDIF
DO 20 I=1,NSTRE
DO 10 J=1,NSTRE
DEVPRJ(I,J)=FOID(I,J)-SOID(I)*SOID(J)*R1D3
10 CONTINUE
20 CONTINUE
IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent
C =====
R3G=R3*GMODU
R6G=R6*GMODU
R2BULK=R2*BULK
ROO3D2=SQRT(R3/R2)
C Current hydrostatic pressure
P=(STRES(1)+STRES(2)+STRES(4))*R1D3
C Current deviatoric stress components
S(1)=STRES(1)-P
S(2)=STRES(2)-P
S(3)=STRES(3)
S(4)=STRES(4)-P
C Recover last (undamaged) elastic trial von Mises effective stress
SNORM=SQRT(S(1)*S(1)+S(2)*S(2)+R2*S(3)*S(3)+S(4)*S(4))
Q=ROO3D2*SNORM
IF(ABS(OMEGA).LT.SMALL)THEN
C... internal error: singular residual derivatives
CALL ERRPRT('EI0053')
ENDIF
IF(DGAMA.EQ.R0)THEN
C... at DGAMA=0 use numerical perturbation
DGAMA=TOLDGA
ENDIF
QTILTR=(Q+R3G*DGAMA)/OMEGA
C.. and last (undamaged) elastic trial pressure
PTILDE=P/OMEGA
C Get factors required in the assemblage of the elastoplastic tangent
C -----
HSLOPE=DPLFUN(HVAR,NHARD,RPROPS(IPHARD))
SIGMAY=PLFUN(HVAR,NHARD,RPROPS(IPHARD))
Y=-SIGMAY**2/R6G-PTILDE**2/R2BULK
AUX=-Y/DAMDEN
AUXB=(QTILTR-SIGMAY)/R3G
PHIT=QTILTR-SIGMAY
DOMEGA=(R3G+OMEGA*HSLOPE)/PHIT
DY=-HSLOPE*SIGMAY/R3G
DOMDQT=-OMEGA/PHIT
C... residual derivatives
DRES=DOMEGA-HSLOPE/R3G*AUX**DAMEXP-
2 AUXB*DAMEXP*DY/DAMDEN*AUX** (DAMEXP-R1)
DRDPTL=DAMEXP*AUXB*AUX** (DAMEXP-R1)*PTILDE/
1 (DAMDEN*BULK)
DRDQTL=DOMDQT+AUX**DAMEXP/R3G
C Compute some factors
A1=-DRDQTL/DRES
A2=-DRDPTL/DRES
A3=A2*DOMEGA
A4=A1*DOMEGA+DOMDQT

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      AFACT=R2G*SIGMAY*OMEGA/QTILTR
      BFACT=R2G*(A1*HSLOPE*OMEGA+A4*SIGMAY-SIGMAY*OMEGA/QTILTR)
      BFACT=BFACT/(SNORM*SNORM)
      CFACT=BULK*(A2*HSLOPE*OMEGA+A3*SIGMAY)/ROO3D2
      CFACT=CFACT/SNORM
      DFACT=PTILDE*R2G*ROO3D2*A4
      DFACT=DFACT/SNORM
      EFACT=BULK*(OMEGA+PTILDE*A3)
C Assemble elastoplastic tangent modulus
C -----
      DO 40 I=1,NSTRE
      DO 30 J=1,NSTRE
            DMATX(I,J)=AFACT*DEVPRJ(I,J)+BFACT*S(I)*S(J)+
1             CFACT*S(I)*S(I)*S(I)+DFACT*S(I)*S(I)*S(I)+
2             EFACT*S(I)*S(I)*S(I)
30      CONTINUE
40      CONTINUE
      ELSE
C Compute damaged elasticity matrix
C -----
C... upper triangle
      FACTG=OMEGA*R2G
      FACTK=OMEGA*BULK
      DO 60 I=1,NSTRE
      DO 50 J=I,NSTRE
            DMATX(I,J)=FACTG*DEVPRJ(I,J)+FACTK*S(I)*S(I)*S(I)
50      CONTINUE
60      CONTINUE
C... lower triangle
      DO 80 J=1,NSTRE-1
      DO 70 I=J+1,NSTRE
            DMATX(I,J)=DMATX(J,I)
70      CONTINUE
80      CONTINUE
      ENDIF
      RETURN
      END

```

```

SUBROUTINE CTDMELE
1(  DMATX      ,NTYPE      ,RPROPS      ,RSTAVA      ,STRES      )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(MSTRE=4)

C Arguments
DIMENSION
1  DMATX(MSTRE,MSTRE) ,RPROPS(*)      ,RSTAVA(*)      ,
2  STRES(MSTRE)

C Local arrays and variables
LOGICAL
1  REPEAT      ,OUTOFP
DIMENSION
1  DPSTRA(3,3)      ,DPSTRE(3,3)      ,EIGPRJ(MSTRE,2)      ,
2  PDMINU(3,3)      ,PDPLUS(3,3)      ,PSTRA(3)      ,
3  PSTRES(3)      ,STRAIN(MSTRE)      ,VI(3)      ,
4  VIDMIN(3)      ,VIDPLU(3)
DATA
1  VI(1),VI(2),VI(3)/
2  1.D0 ,1.D0 ,1.D0 /
DATA
1  R0 ,R1 ,R2 /
2  0.0D0,1.0D0,2.0D0/

C*****
C COMPUTATION OF THE TANGENT MODULUS (ELASTICITY MATRIX) FOR THE
C ISOTROPICALLY DAMAGED ISOTROPIC ELASTIC MATERIAL MODEL WITH
C MICROCRACK/VOID CLOSURE EFFECTS
C
C REFERENCE: Section 12.6.1
C*****
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPR('EI0056')

C Set material constants
YOUNG=RPROPS(2)
POISS=RPROPS(3)
DAMAGE=RPROPS(4)
HFACT=RPROPS(5)

C Retrieve current (physical) strains
STRAIN(1)=RSTAVA(1)
STRAIN(2)=RSTAVA(2)
STRAIN(3)=RSTAVA(3)/R2
STRAIN(4)=RSTAVA(4)

C Perform spectral decomposition of the strain tensor
CALL SPDEC2(EIGPRJ,PSTRA,REPEAT,STRAIN)
PSTRA(3)=STRAIN(4)

C Compute the principal stresses (internal product between stress
C tensor and individual eigenprojection tensors)
PSTRES(1)=STRES(1)*EIGPRJ(1,1)+STRES(2)*EIGPRJ(2,1)+
1  R2*STRES(3)*EIGPRJ(3,1)
PSTRES(2)=STRES(1)*EIGPRJ(1,2)+STRES(2)*EIGPRJ(2,2)+
1  R2*STRES(3)*EIGPRJ(3,2)
PSTRES(3)=STRES(4)

C Zero relevant arrays
CALL RVZERO(PDPLUS,9)
CALL RVZERO(PDMINU,9)

C Construct current projection matrices
C... positive and negative principal stress projection matrices
IF(PSTRES(1).GE.R0)THEN
PDPLUS(1,1)=R1/(R1-DAMAGE)
PDMINU(1,1)=R0
ELSE
PDPLUS(1,1)=R0
PDMINU(1,1)=R1/(R1-HFACT*DAMAGE)
ENDIF
IF(PSTRES(2).GE.R0)THEN
PDPLUS(2,2)=R1/(R1-DAMAGE)
PDMINU(2,2)=R0
ELSE
PDPLUS(2,2)=R0
PDMINU(2,2)=R1/(R1-HFACT*DAMAGE)
ENDIF
IF(PSTRES(3).GE.R0)THEN
PDPLUS(3,3)=R1/(R1-DAMAGE)
PDMINU(3,3)=R0
ELSE
PDPLUS(3,3)=R0
PDMINU(3,3)=R1/(R1-HFACT*DAMAGE)
ENDIF

C... positive and negative trace operators
TRACE=PSTRES(1)+PSTRES(2)+PSTRES(3)
IF(TRACE.GE.R0)THEN
VIDPLU(1)=R1/(R1-DAMAGE)
VIDPLU(2)=R1/(R1-DAMAGE)
VIDPLU(3)=R1/(R1-DAMAGE)
VIDMIN(1)=R0
VIDMIN(2)=R0
VIDMIN(3)=R0
ELSE
VIDPLU(1)=R0
VIDPLU(2)=R0
VIDPLU(3)=R0
VIDMIN(1)=R1/(R1-HFACT*DAMAGE)
VIDMIN(2)=R1/(R1-HFACT*DAMAGE)
VIDMIN(3)=R1/(R1-HFACT*DAMAGE)
ENDIF

C Inverse elasticity operator that transforms principal stresses into
C principal strains (matrix of derivatives of principal strains with
C respect to principal stresses)
DO 20 I=1,3
DO 10 J=1,3

```

```

      DPSTRA(I,J)=(R1+POISS)/YOUNG*(PDPLUS(I,J)+PDMINU(I,J))-
1      POISS/YOUNG*(VI(I)*(VIDPLU(J)+VIDMIN(J)))
10     CONTINUE
20     CONTINUE
C Compute elasticity operator that transforms principal strains into
C principal stresses (matrix of derivatives of principal stresses with
C respect to principal strains)
      CALL INVT3(DPSTRA,DPSTRE,DET)
C
C Use general routine for isotropic tensor functions of a single tensor
C to compute the tangent operator
C
      IF(NTYPE.EQ.2)THEN
        OUTOFF=.FALSE.
      ELSEIF(NTYPE.EQ.3)THEN
        OUTOFF=.TRUE.
      ENDIF
      CALL DGISO2
1(   DPSTRE      ,DMATX      ,EIGPRJ      ,PSTRA      ,PSTRES      ,
2   OUTOFF      ,REPEAT      )
C
      RETURN
      END

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```

SUBROUTINE CTDPE
1(  DGAM ,DMATX ,EPFLAG ,IPROPS ,LALGVA ,
2  NTYPE ,RPROPS ,RSTAVA ,STRAT )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=7 ,MSTRE=4)
LOGICAL APEX, EPFLAG, LALGVA(3)
DIMENSION
1  DMATX(MSTRE,MSTRE),IPROPS(*) ,RPROPS(*) ,
2  RSTAVA(MSTRE+1) ,STRAT(MSTRE)
DIMENSION
1  EETD(MSTRE) ,FOID(MSTRE,MSTRE) ,SOID(MSTRE) ,
2  UNIDEV(MSTRE)
DATA
1  FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2  1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3  FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4  0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5  FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6  0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7  FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8  0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
DATA
1  SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2  1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
DATA
1  R0 ,R1 ,RP5 ,R2 ,R3 /
2  0.0D0,1.0D0,0.5D0,2.0D0,3.0D0/
C*****
C COMPUTATION OF CONSISTENT TANGENT MODULUS FOR DRUCKER-PRAGER TYPE
C ELASTO-PLASTIC MATERIAL WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW RULE AND
C PIECE-WISE LINEAR ISOTROPIC HARDENING
C
C REFERENCE: Section 8.3.5
C*****
IF(NTYPE.EQ.2)THEN
NSTRE=3
ELSEIF(NTYPE.EQ.3)THEN
NSTRE=4
ELSE
CALL ERRPR('EI0017')
ENDIF
C Retrieve accumulated plastic strain, DGAMA and APEX algorithm flag
EPBAR=RSTAVA(MSTRE+1)
DGAMA=DGAM
APEX=LALGVA(3)
C Set some material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
ETA=RPROPS(4)
XI=RPROPS(5)
ETABAR=RPROPS(6)
NHARD=IPROPS(3)
C and some constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R1D3=R1/R3
ROOT2=SQRT(R2)
C
IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent
C =====
C Hardening slope
HSLOPE=DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
IF(APEX)THEN
C Elastoplastic tangent consistent with apex return
C -----
ALPHA=XI/ETABAR
BETA=XI/ETA
AFACT=BULK*(R1-BULK/(BULK+ALPHA*BETA*HSLOPE))
DO 20 I=1,NSTRE
DO 10 J=1,NSTRE
DMATX(I,J)=AFACT*SOID(I)*SOID(J)
10 CONTINUE
20 CONTINUE
ELSE
C Elastoplastic tangent consistent with smooth cone wall return
C -----
C Elastic trial deviatoric (physical) strain
EEVD3=(STRAT(1)+STRAT(2)+STRAT(4))*R1D3
EETD(1)=STRAT(1)-EEVD3
EETD(2)=STRAT(2)-EEVD3
EETD(3)=STRAT(3)*RP5
EETD(4)=STRAT(4)-EEVD3
ETDNOR=SQRT(EETD(1)*EETD(1)+EETD(2)*EETD(2)+
1 R2*EETD(3)*EETD(3)+EETD(4)*EETD(4))
C Unit deviatoric flow vector
IF(ETDNOR.NE.R0)THEN
EDNINV=R1/ETDNOR
ELSE
EDNINV=R0
ENDIF
DO 30 I=1,NSTRE
UNIDEV(I)=EETD(I)*EDNINV
30 CONTINUE
C Assemble tangent
AUX=R1/(GMODU+BULK*ETA*ETABAR+XI*XI*HSLOPE)
AFACT=R2G*(R1-DGAMA/(ROOT2*ETDNOR))
AFACD3=AFACT*R1D3
BFACT=R2G*(DGAMA/(ROOT2*ETDNOR)-GMODU*AUX)
CFACT=-ROOT2*GMODU*BULK*AUX
DFACT=BULK*(R1-BULK*ETA*ETABAR*AUX)
DO 50 I=1,NSTRE
DO 40 J=1,NSTRE
DMATX(I,J)=AFACT*FOID(I,J)+BFACT*UNIDEV(I)*UNIDEV(J)+
1 CFACT*(ETA*UNIDEV(I)*SOID(J)+
2 ETABAR*SOID(I)*UNIDEV(J))+
3 (DFACT-AFACD3)*SOID(I)*SOID(J)
40 CONTINUE
50 CONTINUE
ENDIF
ELSE

```

```
C Compute elasticity matrix
C =====
      FACTOR=BULK-R2G*R1D3
      DO 70 I=1,NSTRE
        DO 60 J=I,NSTRE
          DMATX(I,J)=R2G*FOID(I,J)+FACTOR*SOID(I)*SOID(J)
60      CONTINUE
70      CONTINUE
      DO 90 J=1,NSTRE-1
        DO 80 I=J+1,NSTRE
          DMATX(I,J)=DMATX(J,I)
80      CONTINUE
90      CONTINUE
      ENDIF
      RETURN
      END
```



```

      SUBROUTINE CTDPPN
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,
2   NTYPE      ,RPROPS      ,RSTAVA      ,STRAT      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER( MSTRE=4 )
C Arguments
      LOGICAL EPFLAG, LALGVA(3)
      DIMENSION
1   RALGVA(3)      ,DMATX(MSTRE,MSTRE),IPROPS(*)      ,
2   RPROPS(*)      ,RSTAVA(MSTRE+1) ,STRAT(MSTRE)
C Local arrays
      DIMENSION
1   D12(3)      ,D21(3)
C*****
C COMPUTATION OF THE CONSISTENT TANGENT MODULUS FOR THE DRUCKER-PRAGER
C ELASTO-PLASTIC MATERIAL WITH PIECE-WISE LINEAR ISOTROPIC HARDENING.
C PLANE STRESS IMPLEMENTATION ONLY.
C
C REFERENCE: Sections 9.2.4-5
C*****
C Stops program if not plane stress
      IF(NTYPE.NE.1)CALL ERRPRT('EI0039')
C Retrieve the elastic trial THICKNESS STRAIN last determined in the
C plane stress enforcement loop of subroutine SUDPPN. The in-plane
C elastic trial components have already been stored in the first
C three components of STRAT before the present routine was called.
      STRAT(4)=RALGVA(3)
C Compute the axisymmetric consistent tangent matrix
      CALL CTDP
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,
2   3      ,RPROPS      ,RSTAVA      ,STRAT      )
C Decompose into submatrices
      D12(1)=DMATX(1,4)
      D12(2)=DMATX(2,4)
      D12(3)=DMATX(3,4)
      D21(1)=DMATX(4,1)
      D21(2)=DMATX(4,2)
      D21(3)=DMATX(4,3)
      D22=DMATX(4,4)
C Assemble plane stress consistent tangent matrix
      DO 20 I=1,3
        DO 10 J=1,3
          DMATX(I,J)=DMATX(I,J)-D12(I)*D21(J)/D22
10      CONTINUE
20 CONTINUE
      RETURN
      END

```

```

      SUBROUTINE CTEL
1(   DMATX      ,NTYPE      ,RPROPS      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(MSTRE=4)
      DIMENSION
1   DMATX(MSTRE,MSTRE),RPROPS(*)
      DIMENSION
1   FOID(MSTRE,MSTRE) ,SOID(MSTRE)
      DATA
1   FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2   1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3   FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4   0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5   FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6   0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7   FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8   0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
      DATA
1   SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2   1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
      DATA
1   R1 ,R2 ,R3 ,R4 /
2   1.0D0,2.0D0,3.0D0,4.0D0/
C*****
C COMPUTATION OF THE TANGENT MODULUS (ELASTICITY MATRIX) FOR THE LINEAR
C ELASTIC MATERIAL MODEL
C
C REFERENCE: Expression (4.44)
C*****
C
C Set shear and bulk modulus
C -----
C
      GMODU=RPROPS(2)
      BULK=RPROPS(3)
C
      R1D3=R1/R3
      R2G=R2*GMODU
      FACTOR=BULK-R2G*R1D3
C
C Compute elasticity matrix
C -----
C
      IF(NTYPE.EQ.1)THEN
C plane stress
      NSTRE=3
      R4GD3=R4*GMODU*R1D3
      FACTOR=(BULK-R2G*R1D3)*(R2G/(BULK+R4GD3))
      ELSEIF(NTYPE.EQ.2)THEN
C plane strain
      NSTRE=3
      FACTOR=BULK-R2G*R1D3
      ELSEIF(NTYPE.EQ.3)THEN
C axisymmetric
      NSTRE=4
      FACTOR=BULK-R2G*R1D3
      ELSE
C stops program if other stress state
      CALL ERRPRT('EI0019')
      ENDIF
C
C Assemble matrix
C
      DO 20 I=1,NSTRE
        DO 10 J=I,NSTRE
          DMATX(I,J)=R2G*FOID(I,J)+FACTOR*SOID(I)*SOID(J)
10      CONTINUE
20    CONTINUE
C lower triangle
      DO 40 J=1,NSTRE-1
        DO 30 I=J+1,NSTRE
          DMATX(I,J)=DMATX(J,I)
30      CONTINUE
40    CONTINUE
C
      RETURN
      END

```

```

      SUBROUTINE CTMC
1(   DMATX ,EPFLAG ,IPROPS ,LALGVA ,NTYPE ,
2   RPROPS ,RSTAVA ,STRAT ,STRES )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=7 ,MDIM=3, MSTRE=4)
C Arguments
      LOGICAL EPFLAG ,LALGVA(5)
      DIMENSION
1   DMATX(MSTRE,MSTRE) ,IPROPS(*) ,RPROPS(*) ,
2   RSTAVA(MSTRE+1) ,STRAT(MSTRE) ,STRES(MSTRE)
C Local arrays and variables
      LOGICAL APEX ,EDGE ,OUTOFF ,RIGHT ,REPEAT
      DIMENSION
1   DPSTRS(MDIM,MDIM) ,EIGPRJ(MSTRE,2) ,FOID(MSTRE,MSTRE) ,
2   PSTRS(MDIM) ,PSTRA(MDIM) ,SOID(MSTRE) ,
3   STRAC(MSTRE)
      DATA
1   FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2   1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3   FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4   0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5   FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6   0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7   FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8   0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
      DATA
1   SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2   1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
      DATA
1   RP5 ,R1 ,R2 ,R3 ,R4 /
2   0.5D0,1.0D0,2.0D0,3.0D0,4.0D0/
C*****
C COMPUTATION OF CONSISTENT TANGENT MODULUS FOR MOHR-COULOMB TYPE
C ELASTO-PLASTIC MATERIAL WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW RULE AND
C PIECE-WISE LINEAR ISOTROPIC HARDENING.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 8.2.5
C*****
C Stops program if neither plane strain nor axisymmetric state
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPR('EI0026')
C Current accumulated plastic strain
      EPBAR=RSTAVA(MSTRE+1)
C Set material properties
      YOUNG=RPROPS(2)
      POISS=RPROPS(3)
      SINPHI=RPROPS(4)
      COSPHI=RPROPS(5)
      SINPSI=RPROPS(6)
      NHARD=IPROPS(3)
C Set needed algorithmic variables
      EDGE=LALGVA(3)
      RIGHT=LALGVA(4)
      APEX=LALGVA(5)
C Set some constants
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
      R2G=R2*GMODU
      R4G=R4*GMODU
      R2BULK=R2*BULK
      R2CPHI=R2*COSPHI
      R4C2PH=R2CPHI*R2CPHI
      R1D3=R1/R3
      R2D3=R2*R1D3
      R2GD3=R2G*R1D3
      R4GD3=R4G*R1D3
      IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent
C -----
C Spectral decomposition of the elastic trial strain
      STRAC(1)=STRAT(1)
      STRAC(2)=STRAT(2)
      STRAC(3)=STRAT(3)*RP5
      CALL SPDEC2(EIGPRJ,PSTRA,REPEAT,STRAC)
      PSTRA(3)=STRAT(4)
C and current total stress
      PSTRS(1)=STRES(1)*EIGPRJ(1,1)+STRES(2)*EIGPRJ(2,1)+
1   R2*STRES(3)*EIGPRJ(3,1)
      PSTRS(2)=STRES(1)*EIGPRJ(1,2)+STRES(2)*EIGPRJ(2,2)+
1   R2*STRES(3)*EIGPRJ(3,2)
      PSTRS(3)=STRES(4)
C Identify directions of maximum and minimum principal trial stresses
      II=1
      JJ=1
      PSTMAX=PSTRA(II)
      PSTMIN=PSTRA(JJ)
      DO 10 I=2,3
        IF(PSTRA(I).GE.PSTMAX)THEN
          II=I
          PSTMAX=PSTRA(II)
        ENDIF
        IF(PSTRA(I).LT.PSTMIN)THEN
          JJ=I
          PSTMIN=PSTRA(JJ)
        ENDIF
      10 CONTINUE
      IF(II.NE.1.AND.JJ.NE.1)MM=1
      IF(II.NE.2.AND.JJ.NE.2)MM=2
      IF(II.NE.3.AND.JJ.NE.3)MM=3
      IF(EDGE)THEN
C Tangent consistent with 2-vector return to edge
      SPHSPS=SINPHI*SINPSI
      CONSTA=R4G*(R1+R1D3*SPHSPS)+R4*BULK*SPHSPS
      IF(RIGHT)THEN
        CONSTB=R2G*(R1+SINPHI+SINPSI-R1D3*SPHSPS)+R4*BULK*SPHSPS
      ELSE
        CONSTB=R2G*(R1-SINPHI-SINPSI-R1D3*SPHSPS)+R4*BULK*SPHSPS
      ENDIF
      FACTA=R4C2PH*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
      DRVAA=-CONSTA-FACTA
      DRVAB=-CONSTB-FACTA
      DRVBA=-CONSTB-FACTA

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DRVBB=-CONSTA-FACTA
AUX1=R2G*(R1+R1D3*SINPSI)+R2BULK*SINPSI
AUX2=(R4GD3-R2BULK)*SINPSI
AUX3=R2G*(R1-R1D3*SINPSI)-R2BULK*SINPSI
R1DDET=R1/(DRVAA*DRVBB-DRVAB*DRVBA)
IF(RIGHT)THEN
C ...returned to right edge
  DPSTRS(II,II)=BULK+R4GD3+AUX1*(-DRVAB+DRVBB+DRVAA-DRVBA)*
    (R2G+(R2BULK+R2GD3)*SINPHI)*R1DDET
  1 DPSTRS(II,MM)=BULK-R2GD3+AUX1*(R2G*(DRVAB-DRVAA)+
    ((-DRVAB+DRVBB+DRVAA-DRVBA)*(R2BULK+R2GD3)+
    1 (DRVBA-DRVBB)*R2G)*SINPHI)*R1DDET
  2 DPSTRS(II,JJ)=BULK-R2GD3+AUX1*(R2G*(DRVBA-DRVBB)+
    ((-DRVAB+DRVBB+DRVAA-DRVBA)*(R2BULK+R2GD3)+
    1 (DRVAB-DRVAA)*R2G)*SINPHI)*R1DDET
  2 DPSTRS(MM,II)=BULK-R2GD3+(AUX2*(DRVAB-DRVBB)+AUX3*(DRVBA-
    DRVAA))*R2G+(R2BULK+R2GD3)*SINPHI)*R1DDET
  1 DPSTRS(MM,MM)=BULK+R4GD3+(AUX2*((R2BULK*(DRVAB-DRVBB)+
    (DRVAB*R2GD3+DRVBB*R4GD3))*SINPHI-DRVAB*R2G)+
    1 AUX3*(DRVAA*R2G+(R2BULK*(DRVBA-DRVAA)-
    2 (DRVAA*R2GD3+DRVBA*R4GD3))*SINPHI))*R1DDET
  3 DPSTRS(MM,JJ)=BULK-R2GD3+(AUX2*((R2BULK*(DRVAB-DRVBB)-
    (DRVBB*R2GD3+DRVAB*R4GD3))*SINPHI+DRVBB*R2G)+
    1 AUX3*((R2BULK*(DRVBA-DRVAA)+(DRVAA*R4GD3+
    2 DRVBA*R2GD3))*SINPHI-DRVBA*R2G))*R1DDET
  3 DPSTRS(JJ,II)=BULK-R2GD3+((AUX2*(DRVBA-DRVAA)+AUX3*(DRVAB-
    DRVBB))*((R2BULK+R2GD3)*SINPHI+R2G))*R1DDET
  1 DPSTRS(JJ,MM)=BULK-R2GD3+(AUX2*((R2BULK*(DRVBA-DRVAA)-
    (DRVBA*R4GD3+DRVAA*R2GD3))*SINPHI)+DRVAA*R2G)+
    1 AUX3*((R2BULK*(DRVAB-DRVBB)+(DRVAB*R2GD3+
    2 DRVBB*R4GD3))*SINPHI-DRVAB*R2G))*R1DDET
    3 DPSTRS(JJ,JJ)=BULK+R4GD3+(AUX2*((R2BULK*(DRVBA-DRVAA)+
    (DRVAA*R4GD3+DRVBA*R2GD3))*SINPHI)-DRVBA*R2G)+
    1 AUX3*((R2BULK*(DRVAB-DRVBB)-(DRVAB*R4GD3+
    2 DRVBB*R2GD3))*SINPHI)+DRVBB*R2G))*R1DDET
    3 ELSE
C ...returned to left edge
  DPSTRS(II,II)=BULK+R4GD3+(AUX1*((R2BULK*(DRVBB-DRVAB)+
    (DRVAB*R4GD3+DRVBB*R2GD3))*SINPHI)+DRVBB*R2G)+
    1 AUX2*((R2BULK*(DRVBA-DRVAA)+(DRVAA*R4GD3+
    2 DRVBA*R2GD3))*SINPHI)+DRVBA*R2G))*R1DDET
    3 DPSTRS(II,MM)=BULK-R2GD3+(AUX1*((R2BULK*(DRVBB-DRVAB)-
    (DRVAB*R2GD3+DRVBB*R4GD3))*SINPHI)-DRVAB*R2G)+
    1 AUX2*((R2BULK*(DRVBA-DRVAA)-(DRVAA*R2GD3+
    2 DRVBA*R4GD3))*SINPHI)-DRVAA*R2G))*R1DDET
    3 DPSTRS(II,JJ)=BULK-R2GD3+((AUX1*(DRVBB-DRVAB)+AUX2*(DRVBA-
    DRVAA))*((R2BULK+R2GD3)*SINPHI)-R2G))*R1DDET
    1 DPSTRS(MM,II)=BULK-R2GD3+(AUX1*((R2BULK*(DRVAA-DRVBA)-
    (DRVAA*R4GD3+DRVBA*R2GD3))*SINPHI)-DRVBA*R2G)+
    1 AUX2*((R2BULK*(DRVAB-DRVBB)-(DRVAB*R4GD3+
    2 DRVBB*R2GD3))*SINPHI)-DRVBB*R2G))*R1DDET
    3 DPSTRS(MM,MM)=BULK+R4GD3+(AUX1*((R2BULK*(DRVAA-DRVBA)+
    (DRVAA*R2GD3+DRVBA*R4GD3))*SINPHI)+DRVAA*R2G)+
    1 AUX2*((R2BULK*(DRVAB-DRVBB)+(DRVAB*R2GD3+
    2 DRVBB*R4GD3))*SINPHI)+DRVAB*R2G))*R1DDET
    3 DPSTRS(MM,JJ)=BULK-R2GD3+((AUX1*(DRVAA-DRVBA)+AUX2*(DRVAB-
    DRVBB))*((R2BULK+R2GD3)*SINPHI)-R2G))*R1DDET
    1 DPSTRS(JJ,II)=BULK-R2GD3+(AUX3*((R2BULK*(DRVAB-DRVBB-DRVAA+
    DRVBA)+(DRVAA-DRVAB)*R4GD3+(DRVBA-DRVBB)*
    1 R2GD3)*SINPHI)+(DRVBA-DRVBB)*R2G))*R1DDET
    2 DPSTRS(JJ,MM)=BULK-R2GD3+(AUX3*((R2BULK*(DRVAB-DRVBB-DRVAA+
    DRVBA)+(DRVAB-DRVAA)*R2GD3+(DRVBB-DRVBA)*
    1 R4GD3)*SINPHI)+(DRVAB-DRVAA)*R2G))*R1DDET
    2 DPSTRS(JJ,JJ)=BULK+R4GD3+(AUX3*(DRVAB-DRVBB-DRVAA+DRVBA)*
    1 (((R2BULK+R2GD3)*SINPHI)-R2G))*R1DDET
    ENDIF
  ELSEIF(APEX)THEN
C Tangent consistent with multi-vector return to apex
  COTPHI=COSPHI/SINPHI
  DSIDEJ=BULK*(R1-(BULK/(BULK+
    1 DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))*COTPHI*COSPHI/
    2 SINPSI)))
  DPSTRS(II,II)=DSIDEJ
  DPSTRS(II,MM)=DSIDEJ
  DPSTRS(II,JJ)=DSIDEJ
  DPSTRS(MM,II)=DSIDEJ
  DPSTRS(MM,MM)=DSIDEJ
  DPSTRS(MM,JJ)=DSIDEJ
  DPSTRS(JJ,II)=DSIDEJ
  DPSTRS(JJ,MM)=DSIDEJ
  DPSTRS(JJ,JJ)=DSIDEJ
  ELSE
C Tangent consistent with 1-vector return to main active plane
  SPHSPS=SINPHI*SINPSI
  CONSTA=R4G*(R1+R1D3*SPHSPS)+R4*BULK*SPHSPS
  DENOM=-CONSTA-R4C2PH*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
  B1=(R2G*(R1+R1D3*SINPSI)+R2BULK*SINPSI)/DENOM
  B2=(R4G*R1D3-R2BULK)*SINPSI/DENOM
  B3=(R2G*(R1-R1D3*SINPSI)-R2BULK*SINPSI)/DENOM
  DPSTRS(II,II)=R2G*(R2D3+B1*(R1+R1D3*SINPHI))+
    1 BULK*(R1+R2*B1*SINPHI)
  DPSTRS(II,MM)=R1D3*(R3*BULK-R2G)*(R1+R2*B1*SINPHI)
  DPSTRS(II,JJ)=R2G*(-R1D3-B1*(R1-R1D3*SINPHI))+
    1 BULK*(R1+R2*B1*SINPHI)
  DPSTRS(MM,II)=R2G*(-R1D3-B2*(R1+R1D3*SINPHI))+
    1 BULK*(R1-R2*B2*SINPHI)
  DPSTRS(MM,MM)=R4G*R1D3*(R1+B2*SINPHI)+BULK*(R1-R2*B2*SINPHI)
  DPSTRS(MM,JJ)=R2G*(-R1D3+B2*(R1-R1D3*SINPHI))+
    1 BULK*(R1-R2*B2*SINPHI)
  DPSTRS(JJ,II)=R2G*(-R1D3-B3*(R1+R1D3*SINPHI))+
    1 BULK*(R1-R2*B3*SINPHI)
  DPSTRS(JJ,MM)=R1D3*(R3*BULK-R2G)*(R1-R2*B3*SINPHI)
  DPSTRS(JJ,JJ)=R2G*(R2D3+B3*(R1-R1D3*SINPHI))+
    1 BULK*(R1-R2*B3*SINPHI)
  ENDIF
C
  IF(NTYPE.EQ.2)THEN
    OUTOFF=.FALSE.
  ELSEIF(NTYPE.EQ.3)THEN
    OUTOFF=.TRUE.
  ENDIF
  CALL DGISO2

```

```

1( DPSTRS      ,DMATX      ,EIGPRJ      ,PSTRA      ,PSTRS      ,
2  OUTOFP      ,REPEAT    )
ELSE
C Compute elasticity matrix
C -----
IF(NTYPE.EQ.2)THEN
  NSTRE=3
ELSEIF(NTYPE.EQ.3)THEN
  NSTRE=4
ENDIF
FACTOR=BULK-R2G*R1D3
DO 50 I=1,NSTRE
  DO 40 J=I,NSTRE
    DMATX(I,J)=R2G*FOID(I,J)+FACTOR*SOID(I)*SOID(J)
40  CONTINUE
50  CONTINUE
    DO 70 J=1,NSTRE-1
      DO 60 I=J+1,NSTRE
        DMATX(I,J)=DMATX(J,I)
60  CONTINUE
70  CONTINUE
ENDIF
RETURN
END

```

```

SUBROUTINE CTTFR
1(  DMATX  ,EPFLAG  ,IPROPS  ,LALGVA  ,NTYPE  ,
2  RPROPS  ,RSTAVA  ,STRAT   ,STRES   )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER (IPHARD=4 ,MDIM=3,  MSTRE=4)
LOGICAL EPFLAG, LALGVA(4), OUTOFF, RIGHT, REPEAT, TWOVEC
DIMENSION
1  DMATX(MSTRE,MSTRE) ,IPROPS(*)      ,RPROPS(*)      ,
2  RSTAVA(MSTRE+1)    ,STRAT(*)      ,STRES(*)      ,
DIMENSION
1  DPSTRS(MDIM,MDIM) ,DPSTRE(MDIM,MDIM) ,EIGPRJ(MSTRE,2) ,
2  FOID(MSTRE,MSTRE) ,PSTRS(MDIM)      ,PSTRA(MDIM)      ,
3  SOID(MSTRE)       ,STRAC(MSTRE)
DATA
1  FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2  1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3  FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4  0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5  FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6  0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7  FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8  0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
DATA
1  SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2  1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
DATA
1  R0 ,RP5 ,R1 ,R2 ,R3 ,R4 /
2  0.0D0,0.5D0,1.0D0,2.0D0,3.0D0,4.0D0/
C*****
C COMPUTATION OF CONSISTENT TANGENT MODULUS FOR TRESCA TYPE
C ELASTO-PLASTIC MATERIAL WITH PIECE-WISE LINEAR ISOTROPIC HARDENING.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 8.1.5
C*****
C Stops program if neither plane strain nor axisymmetric state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPR('EI0028')
C Current accumulated plastic strain
EPBAR=RSTAVA(MSTRE+1)
C Set material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
NHARD=IPROPS(3)
C Set needed algorithmic variables
TWOVEC=LALGVA(3)
RIGHT=LALGVA(4)
C Set some constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R4G=R4*GMODU
R1D3=R1/R3
R2D3=R2*R1D3
IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent
C -----
C Spectral decomposition of the elastic trial strain
STRAC(1)=STRAT(1)
STRAC(2)=STRAT(2)
STRAC(3)=STRAT(3)*RP5
CALL SPDEC2(EIGPRJ,PSTRA,REPEAT,STRAC)
PSTRA(3)=STRAT(4)
C and current total stress
PSTRS(1)=STRES(1)*EIGPRJ(1,1)+STRES(2)*EIGPRJ(2,1)+
1 R2*STRES(3)*EIGPRJ(3,1)
PSTRS(2)=STRES(1)*EIGPRJ(1,2)+STRES(2)*EIGPRJ(2,2)+
1 R2*STRES(3)*EIGPRJ(3,2)
PSTRS(3)=STRES(4)
C Identify directions of maximum and minimum principal trial stresses
II=1
JJ=1
PSTMAX=PSTRA(II)
PSTMIN=PSTRA(JJ)
DO 10 I=2,3
IF(PSTRA(I).GE.PSTMAX)THEN
II=I
PSTMAX=PSTRA(II)
ENDIF
IF(PSTRA(I).LT.PSTMIN)THEN
JJ=I
PSTMIN=PSTRA(JJ)
ENDIF
10 CONTINUE
IF(II.NE.1.AND.JJ.NE.1)MM=1
IF(II.NE.2.AND.JJ.NE.2)MM=2
IF(II.NE.3.AND.JJ.NE.3)MM=3
IF(TWOVEC)THEN
C Tangent consistent with two-vector return algorithm
HSLOPE=DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
DAA=R4G+HSLOPE
DAB=R2G+HSLOPE
DBA=R2G+HSLOPE
DBB=R4G+HSLOPE
DET=DAA*DBB-DAB*DBA
R2GDD=R2G/DET
R4G2DD=R2G*R2GDD
IF(RIGHT)THEN
C ...returned to right corner
DPSTRS(II,II)=R2G*(R1-R2GDD*R4G)
DPSTRS(II,MM)=R4G2DD*(DAA-DAB)
DPSTRS(II,JJ)=R4G2DD*(DBB-DBA)
DPSTRS(MM,II)=R4G2DD*R2G
DPSTRS(MM,MM)=R2G*(R1-R2GDD*DAA)
DPSTRS(MM,JJ)=R4G2DD*DBA
DPSTRS(JJ,II)=R4G2DD*R2G
DPSTRS(JJ,MM)=R4G2DD*DAB
DPSTRS(JJ,JJ)=R2G*(R1-R2GDD*DBB)
ELSE
C ...returned to left corner
DPSTRS(II,II)=R2G*(R1-R2GDD*DBB)
DPSTRS(II,MM)=R4G2DD*DAB
DPSTRS(II,JJ)=R4G2DD*R2G

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```

        DPSTRS(MM,II)=R4G2DD*DBA
        DPSTRS(MM,MM)=R2G*(R1-R2GDD*DAA)
        DPSTRS(MM,JJ)=R4G2DD*R2G
        DPSTRS(JJ,II)=R4G2DD*(DBB-DBA)
        DPSTRS(JJ,MM)=R4G2DD*(DAA-DAB)
        DPSTRS(JJ,JJ)=R2G*(R1-R2GDD*R4G)
    ENDIF
ELSE
C Tangent consistent with one-vector return algorithm
    FACTOR=R2G/(R4G+DPLEFUN(EPBAR,NHARD,RPROPS(IPHARD)))
    DPSTRS(II,II)=R2G*(R1-FACTOR)
    DPSTRS(II,MM)=R0
    DPSTRS(II,JJ)=R2G*FACTOR
    DPSTRS(MM,II)=DPSTRS(II,MM)
    DPSTRS(MM,MM)=R2G
    DPSTRS(MM,JJ)=R0
    DPSTRS(JJ,II)=DPSTRS(II,JJ)
    DPSTRS(JJ,MM)=DPSTRS(MM,JJ)
    DPSTRS(JJ,JJ)=DPSTRS(II,II)
ENDIF
1 DPSTRE(1,1)=+DPSTRS(1,1)*R2D3-DPSTRS(1,2)*R1D3-DPSTRS(1,3)*R1D3+
    BULK
1 DPSTRE(2,1)=+DPSTRS(2,1)*R2D3-DPSTRS(2,2)*R1D3-DPSTRS(2,3)*R1D3+
    BULK
1 DPSTRE(3,1)=+DPSTRS(3,1)*R2D3-DPSTRS(3,2)*R1D3-DPSTRS(3,3)*R1D3+
    BULK
1 DPSTRE(1,2)=-DPSTRS(1,1)*R1D3+DPSTRS(1,2)*R2D3-DPSTRS(1,3)*R1D3+
    BULK
1 DPSTRE(2,2)=-DPSTRS(2,1)*R1D3+DPSTRS(2,2)*R2D3-DPSTRS(2,3)*R1D3+
    BULK
1 DPSTRE(3,2)=-DPSTRS(3,1)*R1D3+DPSTRS(3,2)*R2D3-DPSTRS(3,3)*R1D3+
    BULK
1 DPSTRE(1,3)=-DPSTRS(1,1)*R1D3-DPSTRS(1,2)*R1D3+DPSTRS(1,3)*R2D3+
    BULK
1 DPSTRE(2,3)=-DPSTRS(2,1)*R1D3-DPSTRS(2,2)*R1D3+DPSTRS(2,3)*R2D3+
    BULK
1 DPSTRE(3,3)=-DPSTRS(3,1)*R1D3-DPSTRS(3,2)*R1D3+DPSTRS(3,3)*R2D3+
    BULK
    IF(NTYPE.EQ.2)THEN
        OUTOFP=.FALSE.
    ELSEIF(NTYPE.EQ.3)THEN
        OUTOFP=.TRUE.
    ENDIF
    CALL DGIISO2
1( DPSTRE ,DMATX ,EIGPRJ ,PSTRA ,PSTRS ,
2 OUTOFP ,REPEAT )
ELSE
C Compute elasticity matrix
C -----
    IF(NTYPE.EQ.2)THEN
        NSTRE=3
    ELSEIF(NTYPE.EQ.3)THEN
        NSTRE=4
    ENDIF
C
    FACTOR=BULK-R2G*R1D3
    DO 50 I=1,NSTRE
        DO 40 J=I,NSTRE
            DMATX(I,J)=R2G*FOID(I,J)+FACTOR*SOID(I)*SOID(J)
40 CONTINUE
50 CONTINUE
        DO 70 J=1,NSTRE-1
            DO 60 I=J+1,NSTRE
                DMATX(I,J)=DMATX(J,I)
60 CONTINUE
70 CONTINUE
    ENDIF
    RETURN
END

```

```

      SUBROUTINE CTRPN
1(   DMATX   ,EPFLAG   ,IPROPS   ,LALGVA   ,RPROPS   ,
2   RSTAVA   ,STRAT    ,STRES    )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER( MSTRE=4 )
C Arguments
      LOGICAL EPFLAG, LALGVA(4)
      DIMENSION
1   DMATX(MSTRE,MSTRE) ,IPROPS(*)      ,RPROPS(*)      ,
2   RSTAVA(MSTRE+1)   ,STRAT(*)      ,STRES(*)
C Local arrays and variables
      DIMENSION
1   D12(3)           ,D21(3)
C*****
C COMPUTATION OF CONSISTENT TANGENT MODULUS FOR TRESCA TYPE
C ELASTO-PLASTIC MATERIAL WITH PIECE-WISE LINEAR ISOTROPIC HARDENING.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 9.2
C*****
      STRAT(4)=RSTAVA(4)
C Compute the axisymmetric tangent matrix
      NTYPAX=3
      CALL CTR
1(   DMATX   ,EPFLAG   ,IPROPS   ,LALGVA   ,NTYPAX   ,
2   RPROPS   ,RSTAVA   ,STRAT    ,STRES    )
C Decompose into submatrices
      D12(1)=DMATX(1,4)
      D12(2)=DMATX(2,4)
      D12(3)=DMATX(3,4)
      D21(1)=DMATX(4,1)
      D21(2)=DMATX(4,2)
      D21(3)=DMATX(4,3)
      D22=DMATX(4,4)
C Assemble plane stress consistent tangent matrix
      DO 20 I=1,3
        DO 10 J=1,3
          DMATX(I,J)=DMATX(I,J)-D12(I)*D21(J)/D22
10      CONTINUE
20 CONTINUE
      RETURN
      END

```



```

SUBROUTINE CTVM
1( DGAMA ,DMATX ,EPFLAG ,IPROPS ,NTYPE ,
2 RPROPS ,RSTAVA ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=4 ,MSTRE=4)
LOGICAL EPFLAG
DIMENSION
1 DMATX(MSTRE,MSTRE),IPROPS(*) ,RPROPS(*) ,
2 RSTAVA(MSTRE+1) ,STRES(MSTRE)
DIMENSION
1 DEVPRJ(MSTRE,MSTRE),FOID(MSTRE,MSTRE) ,S(MSTRE) ,
2 SOID(MSTRE)
DATA
1 FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2 1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3 FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4 0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5 FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6 0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7 FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8 0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
DATA
1 SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2 1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
DATA
1 R1 ,R2 ,R3 ,R6 /
2 1.0D0,2.0D0,3.0D0,6.0D0/
C*****
C COMPUTATION OF THE CONSISTENT TANGENT MODULUS FOR VON MISES TYPE
C ELASTO-PLASTIC MATERIAL WITH PIECE-WISE LINEAR ISOTROPIC HARDENING.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 7.4.3
C*****
C Stops program if neither plane strain nor axisymmetric state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPR('EI0030')
C Current accumulated plastic strain
EPBAR=RSTAVA(MSTRE+1)
C Set material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
NHARD=IPROPS(3)
C Shear and bulk moduli
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R1D3=R1/R3
C Set deviatoric projection tensor
IF(NTYPE.EQ.2)THEN
NSTRE=3
ELSEIF(NTYPE.EQ.3)THEN
NSTRE=4
ENDIF
DO 20 I=1,NSTRE
DO 10 J=1,NSTRE
DEVPRJ(I,J)=FOID(I,J)-SOID(I)*SOID(J)*R1D3
10 CONTINUE
20 CONTINUE
IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent
C -----
R3G=R3*GMODU
ROO3D2=SQRT(R3/R2)
C Hydrostatic pressure
P=(STRES(1)+STRES(2)+STRES(4))*R1D3
C Deviatoric stress components
S(1)=STRES(1)-P
S(2)=STRES(2)-P
S(3)=STRES(3)
S(4)=STRES(4)-P
C Recover last elastic trial von Mises effective stress
SNORM=SQRT(S(1)*S(1)+S(2)*S(2)+R2*S(3)*S(3)+S(4)*S(4))
Q=ROO3D2*SNORM
QTRIAL=Q+R3G*DGAMA
C Assemble elastoplastic tangent (upper triangle only)
AFACT=R2G*(R1-R3G*DGAMA/QTRIAL)
BFACT=R6*GMODU*GMODU*(DGAMA/QTRIAL-
1 R1/(R3G+DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))))/
2 (SNORM*SNORM)
DO 40 I=1,NSTRE
DO 30 J=I,NSTRE
DMATX(I,J)=AFACT*DEVPRJ(I,J)+BFACT*S(I)*S(J)+
1 BULK*SOID(I)*SOID(J)
30 CONTINUE
40 CONTINUE
ELSE
C Compute elasticity matrix (upper triangle only)
C -----
DO 60 I=1,NSTRE
DO 50 J=I,NSTRE
DMATX(I,J)=R2G*DEVPRJ(I,J)+BULK*SOID(I)*SOID(J)
50 CONTINUE
60 CONTINUE
ENDIF
C Assemble lower triangle
C -----
DO 80 J=1,NSTRE-1
DO 70 I=J+1,NSTRE
DMATX(I,J)=DMATX(J,I)
70 CONTINUE
80 CONTINUE
RETURN
END

```

```

      SUBROUTINE CTVMMX
      1(  DGAMA ,DMATX      ,EPFLAG      ,IPROPS      ,NTYPE      ,
      2    RPROPS      ,RSTAVA      ,RSTAV2      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=4 ,MSTRE=4)
C Arguments
      LOGICAL EPFLAG
      DIMENSION
      1    DMATX(MSTRE,MSTRE) ,IPROPS(*)      ,RPROPS(*)      ,
      2    RSTAVA(2*MSTRE+1) ,RSTAV2(2*MSTRE+1) ,STRES(MSTRE)
C Local arrays and variables
      DIMENSION
      1    BACSTR(MSTRE)      ,DEVPRJ(MSTRE,MSTRE),ETA(MSTRE)      ,
      2    FOID(MSTRE,MSTRE) ,S(MSTRE)      ,SOID(MSTRE)
      DATA
      1    FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
      2    1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
      3    FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
      4    0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
      5    FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
      6    0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
      7    FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
      8    0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
      DATA
      1    SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
      2    1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
      DATA
      1    R1 ,R2 ,R3 ,R6 /
      2    1.0D0,2.0D0,3.0D0,6.0D0/
C*****
C COMPUTATION OF THE CONSISTENT TANGENT MODULUS FOR VON MISES TYPE
C ELASTO-PLASTIC WITH PIECE-WISE LINEAR MIXED ISOTROPIC/KINEMATIC
C HARDENING.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 7.6.6
C*****
C Stops program if neither plane strain nor axisymmetric state
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0048')
C Retrieve current accumulated plastic strain
      EPBAR=RSTAVA(MSTRE+1)
C Retrieve last converged accumulated plastic strain
      EPBARN=RSTAV2(MSTRE+1)
C Retrieve current backstress tensor components
      BACSTR(1)=RSTAVA(6)
      BACSTR(2)=RSTAVA(7)
      BACSTR(3)=RSTAVA(8)
      BACSTR(4)=RSTAVA(9)
C Set material properties
      YOUNG=RPROPS(2)
      POISS=RPROPS(3)
      NHARD=IPROPS(3)
C Set pointers to isotropic and kinematic hardening curves
      IPIHAR=IPHARD
      IPKHAR=IPHARD+2*NHARD
C Shear and bulk moduli
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
      R2G=R2*GMODU
      R1D3=R1/R3
C Set deviatoric projection tensor
      IF(NTYPE.EQ.2)THEN
        NSTRE=3
      ELSEIF(NTYPE.EQ.3)THEN
        NSTRE=4
      ENDIF
      DO 20 I=1,NSTRE
        DO 10 J=1,NSTRE
          DEVPRJ(I,J)=FOID(I,J)-SOID(I)*SOID(J)*R1D3
        10 CONTINUE
      20 CONTINUE
      IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent
C -----
        R3G=R3*GMODU
        ROO3D2=SQRT(R3/R2)
C Hydrostatic pressure
        P=(STRES(1)+STRES(2)+STRES(4))*R1D3
C Deviatoric stress components
        S(1)=STRES(1)-P
        S(2)=STRES(2)-P
        S(3)=STRES(3)
        S(4)=STRES(4)-P
C Relative stress components
        DO 30 ISTR=1,MSTRE
          ETA(ISTR)=S(ISTR)-BACSTR(ISTR)
        30 CONTINUE
        ETANOR=SQRT(ETA(1)**2+ETA(2)**2+R2*ETA(3)**2+ETA(4)**2)
C Recover last elastic trial relative effective stress
        QBAR=ROO3D2*ETANOR
        BETBAN=PLFUN(EPBARN,NHARD,RPROPS(IPKHAR))
        BETBAR=PLFUN(EPBAR,NHARD,RPROPS(IPKHAR))
        QBARTR=QBAR+R3G*DGAMA+BETBAR-BETBAN
C Assemble elastoplastic tangent (upper triangle only)
        HISLOP=DPLFUN(EPBAR,NHARD,RPROPS(IPIHAR))
        AFACT=R2G*(R1-R3G*DGAMA/QBARTR)
        HKSLOP=DPLFUN(EPBAR,NHARD,RPROPS(IPKHAR))
        BFACT=R6*GMODU*GMODU*(DGAMA/QBARTR-R1/(R3G+HISLOP+HKSLOP))/
        1    (ETANOR*ETANOR)
        DO 50 I=1,NSTRE
          DO 40 J=I,NSTRE
            DMATX(I,J)=AFACT*DEVPRJ(I,J)+BFACT*ETA(I)*ETA(J)+
            1    BULK*SOID(I)*SOID(J)
          40 CONTINUE
        50 CONTINUE
      ELSE
C Compute elasticity matrix (upper triangle only)
C -----
        DO 70 I=1,NSTRE
          DO 60 J=I,NSTRE
            DMATX(I,J)=R2G*DEVPRJ(I,J)+BULK*SOID(I)*SOID(J)
          60 CONTINUE
        70 CONTINUE

```

```
ENDIF
C Assemble lower triangle
C -----
      DO 90 J=1,NSTRE-1
        DO 80 I=J+1,NSTRE
          DMATX(I,J)=DMATX(J,I)
80      CONTINUE
90 CONTINUE
RETURN
END
```

```

      SUBROUTINE CTVMPS
1(   DGAMA   ,DMATX   ,EPFLAG   ,IPROPS   ,NTYPE   ,
2   RPROPS   ,RSTAVA   ,STRES    )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER (IPHARD=4 ,MSTRE=4)
      LOGICAL EPFLAG
C Array arguments
      DIMENSION
1   DMATX(MSTRE,MSTRE) ,IPROPS(*)           ,RPROPS(*)           ,
2   RSTAVA(MSTRE+1)   ,STRES(MSTRE)
C Local arrays
      DIMENSION
1   FOID(MSTRE,MSTRE)   ,SOID(MSTRE)       ,VECN(3)
      DATA
1   FOID(1,1),FOID(1,2),FOID(1,3),FOID(1,4)/
2   1.0D0 ,0.0D0 ,0.0D0 ,0.0D0 /
3   FOID(2,1),FOID(2,2),FOID(2,3),FOID(2,4)/
4   0.0D0 ,1.0D0 ,0.0D0 ,0.0D0 /
5   FOID(3,1),FOID(3,2),FOID(3,3),FOID(3,4)/
6   0.0D0 ,0.0D0 ,0.5D0 ,0.0D0 /
7   FOID(4,1),FOID(4,2),FOID(4,3),FOID(4,4)/
8   0.0D0 ,0.0D0 ,0.0D0 ,1.0D0 /
      DATA
1   SOID(1) ,SOID(2) ,SOID(3) ,SOID(4) /
2   1.0D0 ,1.0D0 ,0.0D0 ,1.0D0 /
      DATA
1   RP5 ,R1 ,R2 ,R3 ,R4 /
2   0.5D0,1.0D0,2.0D0,3.0D0,4.0D0/
C*****
C COMPUTATION OF THE CONSISTENT TANGENT MODULUS FOR VON MISES TYPE
C ELASTO-PLASTIC MATERIAL WITH PIECE-WISE LINEAR ISOTROPIC HARDENING.
C PLANE STRESS IMPLEMENTATION ONLY.
C
C REFERENCE: Section 9.4.5
C*****
C Stops program if neither not plane stress
      IF(NTYPE.NE.1)CALL ERRPR('EI0032')
C Current accumulated plastic strain
      EPBAR=RSTAVA(MSTRE+1)
C Set material properties
      YOUNG=RPROPS(2)
      POISS=RPROPS(3)
      NHARD=IPROPS(3)
C Shear and bulk moduli
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
      R2G=R2*GMODU
      R1D3=R1/R3
      R2D3=R2*R1D3
      IF(EPFLAG)THEN
C Compute elastoplastic consistent tangent (Box 9.6)
C =====
C Item (i):
C -----
C Compute XI
      XI=R2D3*(STRES(1)*STRES(1)+STRES(2)*STRES(2)-STRES(1)*STRES(2))+
1   R2*STRES(3)*STRES(3)
C Hardening slope
      HSLOPE=DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
C Matrix E components
      ESTAR1=R3*YOUNG/(R3*(R1-POISS)+YOUNG*DGAMA)
      ESTAR2=R2G/(R1+R2G*DGAMA)
      ESTAR3=GMODU/(R1+R2G*DGAMA)
      E11=RP5*(ESTAR1+ESTAR2)
      E22=E11
      E12=RP5*(ESTAR1-ESTAR2)
      E33=ESTAR3
C Components of the matrix product EP
      EPSTA1=R1D3*ESTAR1
      EPSTA2=ESTAR2
      EPSTA3=EPSTA2
      EP11=RP5*(EPSTA1+EPSTA2)
      EP22=EP11
      EP12=RP5*(EPSTA1-EPSTA2)
      EP21=EP12
      EP33=EPSTA3
C Vector n
      VECN(1)=EP11*STRES(1)+EP12*STRES(2)
      VECN(2)=EP21*STRES(1)+EP22*STRES(2)
      VECN(3)=EP33*STRES(3)
C Scalar alpha
      DENOM1=STRES(1)*(R2D3*VECN(1)-R1D3*VECN(2))+
1   STRES(2)*(R2D3*VECN(2)-R1D3*VECN(1))+
2   STRES(3)*R2*VECN(3)
      DENOM2=R2*XI*HSLOPE/(R3-R2*HSLOPE*DGAMA)
      ALPHA=R1/(DENOM1+DENOM2)
C Item (ii): Assemble elasto-plastic tangent
C -----
      DMATX(1,1)=E11-ALPHA*VECN(1)*VECN(1)
      DMATX(1,2)=E12-ALPHA*VECN(1)*VECN(2)
      DMATX(1,3)=-ALPHA*VECN(1)*VECN(3)
      DMATX(2,1)=DMATX(1,2)
      DMATX(2,2)=E22-ALPHA*VECN(2)*VECN(2)
      DMATX(2,3)=-ALPHA*VECN(2)*VECN(3)
      DMATX(3,1)=DMATX(1,3)
      DMATX(3,2)=DMATX(2,3)
      DMATX(3,3)=E33-ALPHA*VECN(3)*VECN(3)
      ELSE
C Compute plane stress elasticity matrix
C =====
      NSTRE=3
      R4GD3=R4*GMODU/R3
      FACTOR=(BULK-R2G/R3)*(R2G/(BULK+R4GD3))
      DO 20 I=1,NSTRE
        DO 10 J=I,NSTRE
          DMATX(I,J)=R2G*FOID(I,J)+FACTOR*SOID(I)*SOID(J)
        10 CONTINUE
      20 CONTINUE
C lower triangle
      DO 40 J=1,NSTRE-1
        DO 30 I=J+1,NSTRE
          DMATX(I,J)=DMATX(J,I)

```

```
30      CONTINUE
40      CONTINUE
      ENDIF
      RETURN
      END
```

```

C      DOUBLE PRECISION FUNCTION DDLGD2(X)
      DOUBLE PRECISION X
      DOUBLE PRECISION RP5
      DATA    RP5  /0.5D0/
C*****
C DERIVATIVE OF THE SCALAR FUNCTION 'DLGD2' THAT RELATES PRINCIPAL
C LOGARITHMIC STRETCHES AND EIGENVALUES OF THE CAUCHY-GREEN TENSOR
C*****
      DDLGD2=RP5/X
C
      RETURN
      END

```

```

      SUBROUTINE DEFGRA
1(      ELDISP      ,F      ,GMATX      ,MDOFN      ,MGDIM      ,
2      NDOFN      ,NTYPE      ,NNODE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(      MCOMP=5      )
      DIMENSION
1      ELDISP(MDOFN,*)      ,F(3,3)      ,GMATX(MGDIM,*)
      DIMENSION
1      FVEC(MCOMP)
      DATA R0 ,R1 / 0.0D0,1.0D0 /
C*****
C COMPUTES THE DEFORMATION GRADIENT TENSOR ASSOCIATED WITH THE ELEMENT
C DISPLACEMENT 'ELDISP'
C*****
C Set total number of deformation gradient components
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2)THEN
          NCOMP=4
      ELSEIF(NTYPE.EQ.3)THEN
          NCOMP=5
      ELSE
          CALL ERRPRT('EI0021')
      ENDIF
C Evaluate the deformation gradient stored in vector form
      CALL RVZERO(FVEC,NCOMP)
      DO 30 ICOMP=1,NCOMP
          IEVAB=0
          DO 20 INODE=1,NNODE
              DO 10 IDOFN=1,NDOFN
                  IEVAB=IEVAB+1
                  FVEC(ICOMP)=FVEC(ICOMP)+
1                      GMATX(ICOMP,IEVAB)*ELDISP(IDOFN,INODE)
10          CONTINUE
20          CONTINUE
30          CONTINUE
C Store the deformation gradient in matrix form
      F(1,1)=FVEC(1)+R1
      F(2,1)=FVEC(2)
      F(3,1)=R0
      F(1,2)=FVEC(3)
      F(2,2)=FVEC(4)+R1
      F(3,2)=R0
      F(1,3)=R0
      F(2,3)=R0
      IF(NTYPE.EQ.1)THEN
          F(3,3)=R0
      ELSEIF(NTYPE.EQ.2)THEN
          F(3,3)=R1
      ELSEIF(NTYPE.EQ.3)THEN
          F(3,3)=FVEC(5)+R1
      ENDIF
C
      RETURN
      END

```

```

SUBROUTINE DEXPMP
1( DEXPX ,NOCONV ,X )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER
1( NDIM=3 ,NDIM2=9 ,NDIM4=81 ,MAXN=100 )
C Arguments
LOGICAL NOCONV
DIMENSION
1 DEXPX(NDIM,NDIM,NDIM,NDIM),X(NDIM,NDIM)
C Local arrays and variables
C...matrix of powers of X
DIMENSION
1 R1DFAC(MAXN) ,XMATX(NDIM,NDIM,0:MAXN)
C...initialise identity matrix: X to the power 0
DATA
1 XMATX(1,1,0) ,XMATX(1,2,0) ,XMATX(1,3,0) /
2 1.D0 ,0.D0 ,0.D0 /
3 XMATX(2,1,0) ,XMATX(2,2,0) ,XMATX(2,3,0) /
4 0.D0 ,1.D0 ,0.D0 /
5 XMATX(3,1,0) ,XMATX(3,2,0) ,XMATX(3,3,0) /
6 0.D0 ,0.D0 ,1.D0 /
DATA
1 R0 ,RP5 ,R1 ,TOL ,OVER ,UNDER /
2 0.0D0,0.5D0,1.0D0,1.0D-10,1.0D+100,1.0D-100/
C*****
C COMPUTES THE DERIVATIVE OF THE EXPONENTIAL OF A (GENERALLY
C UNSYMMETRIC) 3-D TENSOR. USES THE SERIES REPRESENTATION OF THE TENSOR
C EXPONENTIAL.
C
C REFERENCE: Section B.2
C Box B.2
C*****
C Initialise convergence flag
NOCONV=.FALSE.
C X to the power 1
DO 20 I=1,NDIM
DO 10 J=1,NDIM
XMATX(I,J,1)=X(I,J)
10 CONTINUE
20 CONTINUE
C Zero remaining powers of X
CALL RVZERO(XMATX(1,1,2),NDIM*NDIM*(MAXN-1))
C Compute X square
DO 50 I=1,NDIM
DO 40 J=1,NDIM
DO 30 K=1,NDIM
XMATX(I,J,2)=XMATX(I,J,2)+X(I,K)*X(K,J)
30 CONTINUE
40 CONTINUE
50 CONTINUE
C Compute principal invariants of X
C1=X(1,1)+X(2,2)+X(3,3)
C2=RP5*(C1*C1-(XMATX(1,1,2)+XMATX(2,2,2)+XMATX(3,3,2)))
C3=X(1,1)*X(2,2)*X(3,3)+X(1,2)*X(2,3)*X(3,1)+
1 X(1,3)*X(2,1)*X(3,2)-X(1,2)*X(2,1)*X(3,3)-
2 X(1,1)*X(2,3)*X(3,2)-X(1,3)*X(2,2)*X(3,1)
C Compute X to the powers 3,4,...,NMAX using recursive formula
R1DFAC(1)=R1
R1DFAC(2)=RP5
DO 80 N=3,MAXN
R1DFAC(N)=R1DFAC(N-1)/DBLE(N)
DO 70 I=1,NDIM
DO 60 J=1,NDIM
XMATX(I,J,N)=C1*XMATX(I,J,N-1)-C2*XMATX(I,J,N-2)+
1 C3*XMATX(I,J,N-3)
60 CONTINUE
70 CONTINUE
XNNORM=SQRT(SCAPRD(XMATX(1,1,N),XMATX(1,1,N),NDIM2))
C...check number of terms required for series convergence
IF(XNNORM.GT.OVER.OR.(XNNORM.LT.UNDER.AND.XNNORM.GT.R0)
1 .OR.R1DFAC(N).LT.UNDER)THEN
C...numbers are too small or too big: Exit without computing derivative
NOCONV=.TRUE.
GOTO 999
ELSEIF(XNNORM*R1DFAC(N).LT.TOL)THEN
C...series will converge with NMAX terms:
C Carry on to derivative computation
NMAX=N
GOTO 90
ENDIF
80 CONTINUE
C...series will not converge for the currently prescribed tolerance
C with the currently prescribed maximum number of terms MAXN:
C Exit without computing derivative
NOCONV=.TRUE.
GOTO 999
90 CONTINUE
C Compute the derivative of exponential map
CALL RVZERO(DEXPX,NDIM4)
DO 150 I=1,NDIM
DO 140 J=1,NDIM
DO 130 K=1,NDIM
DO 120 L=1,NDIM
DO 110 N=1,NMAX
DO 100 M=1,N
DEXPX(I,J,K,L)=DEXPX(I,J,K,L)+
1 R1DFAC(N)*XMATX(I,K,M-1)*XMATX(L,J,N-M)
100 CONTINUE
110 CONTINUE
120 CONTINUE
130 CONTINUE
140 CONTINUE
150 CONTINUE
C
999 CONTINUE
RETURN
END

```



```

      SUBROUTINE DGISO2
1(   DEIGY      ,DYDX      ,EIGPRJ      ,EIGX      ,EIGY      ,
2   OUTOFP      ,REPEAT    )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(   MCOMP=4      ,MDIM=3      ,NDIM=2      )
C Arguments
      LOGICAL OUTOFP, REPEAT
      DIMENSION
1   DEIGY(MDIM,MDIM) ,DYDX(MCOMP,MCOMP) ,EIGPRJ(MCOMP,NDIM) ,
2   EIGX(NDIM)      ,EIGY(NDIM)
C Local arrays
      DIMENSION
1   EIGPR3(MCOMP)      ,FOID(MCOMP,MCOMP) ,SOPID(MCOMP)
      DATA
1   FOID(1,1)      ,FOID(1,2)      ,FOID(1,3)      /
2   1.0D0      ,0.0D0      ,0.0D0      /
3   FOID(2,1)      ,FOID(2,2)      ,FOID(2,3)      /
4   0.0D0      ,1.0D0      ,0.0D0      /
5   FOID(3,1)      ,FOID(3,2)      ,FOID(3,3)      /
6   0.0D0      ,0.0D0      ,0.5D0      /
      DATA
1   SOPID(1)      ,SOPID(2)      ,SOPID(3)      ,SOPID(4)      /
2   1.0D0      ,1.0D0      ,0.0D0      ,0.0D0      /
      DATA
1   EIGPR3(1)      ,EIGPR3(2)      ,EIGPR3(3)      ,EIGPR3(4)      /
2   0.0D0      ,0.0D0      ,0.0D0      ,1.0D0      /
C*****
C COMPUTE THE DERIVATIVE OF A GENERAL ISOTROPIC TENSOR FUNCTION OF ONE
C TENSOR IN 2-D (WITH ONE POSSIBLE OUT-OF-PLANE COMPONENT)
C
C REFERENCE: Sections A.3.1-2
C           Box A.2
C*****
      CALL RVZERO(DYDX,MCOMP*MCOMP)
      IF(REPEAT)THEN
C Derivative dY/dX for repeated in-plane eigenvalues of X
C -----
C In-plane component
      DO 20 I=1,3
        DO 10 J=1,3
          DYDX(I,J)=(DEIGY(1,1)-DEIGY(1,2))*FOID(I,J)+
1          DEIGY(1,2)*SOPID(I)*SOPID(J)
10        CONTINUE
20      CONTINUE
      IF(OUTOFP)THEN
C out-of-plane components required
      DO 40 I=1,4
        DO 30 J=1,4
          IF(I.EQ.4.OR.J.EQ.4)DYDX(I,J)=
1          DEIGY(1,3)*SOPID(I)*EIGPR3(J)+
2          DEIGY(3,1)*EIGPR3(I)*SOPID(J)+
3          DEIGY(3,3)*EIGPR3(I)*EIGPR3(J)
30        CONTINUE
40      CONTINUE
      ENDIF
      ELSE
C Derivative dY/dX for distinct in-plane eigenvalues of X
C -----
C Assemble in-plane DYDX
      A1=(EIGY(1)-EIGY(2))/(EIGX(1)-EIGX(2))
      DO 70 I=1,3
        DO 60 J=1,3
          DYDX(I,J)=A1*(FOID(I,J)-EIGPRJ(I,1)*EIGPRJ(J,1)-
1          EIGPRJ(I,2)*EIGPRJ(J,2))+
2          DEIGY(1,1)*EIGPRJ(I,1)*EIGPRJ(J,1)+
3          DEIGY(1,2)*EIGPRJ(I,1)*EIGPRJ(J,2)+
4          DEIGY(2,1)*EIGPRJ(I,2)*EIGPRJ(J,1)+
5          DEIGY(2,2)*EIGPRJ(I,2)*EIGPRJ(J,2)
60        CONTINUE
70      CONTINUE
      IF(OUTOFP) THEN
C out-of-plane components required
      DO 90 I=1,4
        DO 80 J=1,4
          IF(I.EQ.4.OR.J.EQ.4)DYDX(I,J)=
1          DEIGY(1,3)*EIGPRJ(I,1)*EIGPR3(J)+
2          DEIGY(2,3)*EIGPRJ(I,2)*EIGPR3(J)+
3          DEIGY(3,1)*EIGPR3(I)*EIGPRJ(J,1)+
4          DEIGY(3,2)*EIGPR3(I)*EIGPRJ(J,2)+
5          DEIGY(3,3)*EIGPR3(I)*EIGPR3(J)
80        CONTINUE
90      CONTINUE
      ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE DISO2
1(   DYDX      ,DFUNC      ,FUNC      ,OUTOFP      ,X      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      EXTERNAL
1   DFUNC      ,FUNC
      PARAMETER
1(   MCOMP=4      ,NDIM=2      )
C Arguments
      LOGICAL OUTOFP
      DIMENSION
1   DYDX(MCOMP,MCOMP) ,X(*)
C Local variables and arrays
      LOGICAL REPEAT
      DIMENSION
1   DEIGY(NDIM)      ,EIGPRJ(MCOMP,NDIM),EIGX(NDIM)      ,
2   EIGY(NDIM)      ,FOID(MCOMP,MCOMP)
      DATA
1   FOID(1,1)      ,FOID(1,2)      ,FOID(1,3)      /
2   1.0D0      ,0.0D0      ,0.0D0      /
3   FOID(2,1)      ,FOID(2,2)      ,FOID(2,3)      /
4   0.0D0      ,1.0D0      ,0.0D0      /
5   FOID(3,1)      ,FOID(3,2)      ,FOID(3,3)      /
6   0.0D0      ,0.0D0      ,0.5D0      /
C*****
C COMPUTE (AND STORE IN MATRIX FORM) THE DERIVATIVE dy/dx OF AN
C ISOTROPIC TENSOR FUNCTION OF THE TYPE:
C
C
C
C
C WHERE Y AND X ARE SYMMETRIC TENSORS, x_i AND E_i ARE, RESPECTIVELY
C THE EIGENVALUES AND EIGENPROJECTIONS OF X, AND y(.) IS A SCALAR
C FUNCTION. THIS ROUTINE IS RESTRICTED TO 2-D TENSORS WITH ONE
C POSSIBLE (TRANSVERSAL) OUT-OF-PLANE COMPONENT.
C
C
C REFERENCE: Section A.5
C*****
C Spectral decomposition of X
      CALL SPDEC2
1(   EIGPRJ      ,EIGX      ,REPEAT      ,X      )
C In-plane eigenvalues of Y (and derivatives)
      DO 10 IDIR=1,2
          EIGY(IDIR)=FUNC(EIGX(IDIR))
          DEIGY(IDIR)=DFUNC(EIGX(IDIR))
      10 CONTINUE
C
C In-plane components of dY/dX
C -----
      CALL RVZERO(DYDX,MCOMP*MCOMP)
      IF(REPEAT)THEN
C for repeated in-plane eigenvalues of X
          DO 20 I=1,3
              DYDX(I,I)=DEIGY(1)*FOID(I,I)
          20 CONTINUE
      ELSE
C for distinct in-plane eigenvalues of X
          A1=(EIGY(1)-EIGY(2))/(EIGX(1)-EIGX(2))
          DO 40 I=1,3
              DO 30 J=I,3
                  DYDX(I,J)=A1*(FOID(I,J)-EIGPRJ(I,1)*EIGPRJ(J,1)-
1                     EIGPRJ(I,2)*EIGPRJ(J,2))+
2                     DEIGY(1)*EIGPRJ(I,1)*EIGPRJ(J,1)+
3                     DEIGY(2)*EIGPRJ(I,2)*EIGPRJ(J,2)
                  IF(I.NE.J)DYDX(J,I)=DYDX(I,J)
              30 CONTINUE
          40 CONTINUE
      ENDIF
C
C Out-of-plane component required
C -----
      IF(OUTOFP)DYDX(4,4)=DFUNC(X(4))
C
      RETURN
      END

```

```
C      DOUBLE PRECISION FUNCTION DLGD2(X)
C
C      DOUBLE PRECISION X
C      DOUBLE PRECISION RP5
C      DATA    RP5  /0.5D0/
C*****
C SCALAR FUNCTION THAT RELATES PRINCIPAL LOGARITHMIC STRETCHES AND
C EIGENVALUES OF THE CAUCHY-GREEN TENSOR
C
C REFERENCE: Section 3.1.7
C*****
C      DLGD2=RP5*DLOG(X)
C
C      RETURN
C      END
```

```

C      DOUBLE PRECISION FUNCTION DPLFUN(X, NPOINT, XFX)
      INTEGER NPOINT, I
      DOUBLE PRECISION X, XFX(2,NPOINT), R0
      DATA R0 / 0.0D0 /
C*****
C DERIVATIVE OF THE PIECEWISE LINEAR FUNCTION 'PLFUN' DEFINED BY A SET
C OF NPOINT PAIRS {X,F(X)} STORED IN THE MATRIX XFX (DIM. 2*NPOINT).
C*****
      DO 100 I=1,NPOINT
        IF (X.GE.XFX(1,I)) THEN
          GOTO 100
        ELSE
          IF (I.EQ.1) THEN
C      -- x < x1 --> f(x)=f(x1) --> df(x)/dx=0 ---
            DPLFUN=R0
            GOTO 999
          ELSE
C      -- x(i-1) <= x < x(i) ---
            DPLFUN=(XFX(2,I)-XFX(2,I-1))/
1          (XFX(1,I)-XFX(1,I-1))
            GOTO 999
          ENDIF
        ENDIF
      CONTINUE
C      ---- x >= x(npnt) --> f(x) = f(x(npnt)) --> df/dx=0 ---
      DPLFUN=R0
999    CONTINUE
      RETURN
      END

```

```

SUBROUTINE ELEIIF
1( IELEM ,IFFAIL )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
INCLUDE '../MAXDIM.INC'
INCLUDE '../MATERIAL.INC'
INCLUDE '../ELEMENTS.INC'
INCLUDE '../GLBDBASE.INC'

C
LOGICAL IFFAIL
C*****
C ELEMENT INTERFACE FOR COMPUTATION OF ELEMENT INTERNAL FORCE VECTOR.
C CALL ELEMENT CLASS-SPECIFIC INTERNAL FORCE VECTOR CALCULATION ROUTINES
C
C REFERENCE: Section 5.5.1
C Figure 5.4
C*****
C Initialise internal force calculation failure flag
IFFAIL=.FALSE.
C Recover element and material type group identification numbers
C -----
IGRUP =IGRPID(IELEM)
IELIDN=IELTID(IGRUP)
MATIDN=MATTID(IGRUP)
C Identify element class
C -----
IELCLS=IELPRP(2,IELIDN)
C
C Call internal force computation routine according to element class
C -----
IF(IELCLS.EQ.STDARD)THEN
C Standard 2-D displacement-based isoparametric elements
CALL IFSTD2
1( IELEM ,IFFAIL ,MDIME ,MELEM ,MPOIN ,
2 MSTRE ,MTOTV ,NAXIS ,NLARGE ,NTYPE ,
3 COORD(1,1,1) ,DINCR ,
4 ELOAD(1,IELEM) ,IELPRP(1,IELIDN) ,IPROPS(1,MATIDN) ,
5 LALGVA(1,1,IELEM,1) ,LNODS ,RALGVA(1,1,IELEM,1) ,
6 RELPRP(1,IELIDN) ,RPROPS(1,MATIDN) ,RSTAVA(1,1,IELEM,1) ,
7 STRSG(1,1,IELEM,1) ,THKGP(1,IELEM,1) ,TDISP )
C 2-D F-bar elements (for large strain formulation only)
ELSEIF(IELCLS.EQ.FBAR)THEN
CALL IFFBA2
1( IELEM ,IFFAIL ,MDIME ,MELEM ,MPOIN ,
2 MSTRE ,MTOTV ,NAXIS ,NTYPE ,
3 COORD(1,1,1) ,DINCR ,
4 ELOAD(1,IELEM) ,IELPRP(1,IELIDN) ,IPROPS(1,MATIDN) ,
5 LALGVA(1,1,IELEM,1) ,LNODS ,RALGVA(1,1,IELEM,1) ,
6 RELPRP(1,IELIDN) ,RPROPS(1,MATIDN) ,RSTAVA(1,1,IELEM,1) ,
7 STRSG(1,1,IELEM,1) ,THKGP(1,IELEM,1) ,TDISP )
ENDIF
RETURN
END

```

```

SUBROUTINE ELEIST
1(  ESTIF      ,IELEM      ,KUNLD      ,UNSYM      )
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas global database
  INCLUDE '../MAXDIM.INC'
  INCLUDE '../MATERIAL.INC'
  INCLUDE '../ELEMENTS.INC'
  INCLUDE '../GLBDBASE.INC'
C
  LOGICAL UNSYM
  DIMENSION
1    ESTIF(MEVAB,MEVAB)
C*****
C ELEMENT INTERFACE ROUTINE FOR COMPUTATION OF ELEMENT TANGENT STIFFNESS
C MATRIX.
C CALL ELEMENT CLASS-SPECIFIC STIFFNESS MATRIX CALCULATION ROUTINES
C
C REFERENCE: Section 5.6.2
C           Figure 5.5
C*****
C Recover element and material type group identification numbers
C -----
      IGRUP=IGRPID(IELEM)
      IELIDN=IELTID(IGRUP)
      MATIDN=MATTID(IGRUP)
C Identify element class
      IELCLS=IELPRP(2,IELIDN)
C
C Call stiffness computation routine according to the element class
C -----
      IF(IELCLS.EQ.STDARD)THEN
        CALL STSTD2
1(  IELEM      ,KUNLD      ,MDIME      ,MELEM      ,
2    MPOIN      ,MSTRE      ,MTOTV      ,NAXIS      ,NLARGE      ,
3    NTYPE      ,UNSYM      ,
4    COORD(1,1,1)      ,DINCR      ,ESTIF      ,
5    IELPRP(1,IELIDN)      ,IPROPS(1,MATIDN)      ,LALGVA(1,1,IELEM,1) ,
6    LNODS      ,RALGVA(1,1,IELEM,1) ,RELPRP(1,IELIDN) ,
7    RPROPS(1,MATIDN)      ,RSTAVA(1,1,IELEM,1) ,RSTAVA(1,1,IELEM,2) ,
8    STRSG(1,1,IELEM,1) ,THKGP(1,IELEM,1)      ,TDISP      )
      ELSEIF(IELCLS.EQ.FBAR)THEN
        CALL STFBA2
1(  IELEM      ,KUNLD      ,MDIME      ,MELEM      ,
2    MPOIN      ,MSTRE      ,MTOTV      ,NAXIS      ,
3    NTYPE      ,UNSYM      ,
4    COORD(1,1,1)      ,DINCR      ,ESTIF      ,
5    IELPRP(1,IELIDN)      ,IPROPS(1,MATIDN)      ,LALGVA(1,1,IELEM,1) ,
6    LNODS      ,RALGVA(1,1,IELEM,1) ,RELPRP(1,IELIDN) ,
7    RPROPS(1,MATIDN)      ,RSTAVA(1,1,IELEM,1) ,RSTAVA(1,1,IELEM,2) ,
8    STRSG(1,1,IELEM,1) ,TDISP      )
      ENDIF
C
      RETURN
      END

```

```

SUBROUTINE ERRPRT(ERRCOD)
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
LOGICAL      AVAIL,FOUND
CHARACTER*6  ERRCOD
CHARACTER*22 HEADER
CHARACTER*72 INLINE
CHARACTER*256 HYPLASHOME
DIMENSION IWBEG(128), IWEND(128)
C*****
C PRINTS (TO THE STANDARD OUTPUT AND RESULTS FILE) MOST ERROR/WARNING
C MESSAGES OF HYPLAS.
C THE ARGUMENT "ERRCOD" CONTAINS THE ERROR/WARNING MESSAGE CODE. THE
C TEXT OF THE MESSAGE ASSOCIATED WITH THE GIVEN CODE MUST BE IN FILE
C "ERROR.RUN". THIS FILE IS KEPT IN THE FILE SYSTEM DIRECTORY WHOSE
C NAME IS STORED IN THE OPERATING SYSTEM ENVIRONMENT VARIABLE
C "HYPLASHOME" (SEE COMMENTS BELOW).
C*****
1000 FORMAT(///' ',74('*'))/' ',72X,'*'/ ' ',25X,A22,25X,'*'/ ' ',72X,
1      '*/' ' ',74('*'))/' ',72X,'*'/ ' * Code:      ',A6,51X,'*')
1010 FORMAT(' ',A72,'*')
1020 FORMAT(' ',72X,'*'/ ' ',74('*'))
1030 FORMAT(///' ASSOCIATED MESSAGES WILL NOT BE PRINTED !',//,
1      ' The above error code was not found in file ERROR.RUN.',//)
1040 FORMAT(///' ASSOCIATED MESSAGES WILL NOT BE PRINTED !',//,
1      ' File ERROR.RUN does not exist in HYPLASHOME directory.',//)
C
      IF(ERRCOD(1:2).EQ.'ED')THEN
        HEADER=' INPUT DATA ERROR '
      ELSEIF(ERRCOD(1:2).EQ.'WD')THEN
        HEADER=' INPUT DATA WARNING '
      ELSEIF(ERRCOD(1:2).EQ.'EI')THEN
        HEADER=' INTERNAL ERROR '
      ELSEIF(ERRCOD(1:2).EQ.'EE')THEN
        HEADER=' EXECUTION ERROR '
      ELSEIF(ERRCOD(1:2).EQ.'WE')THEN
        HEADER=' EXECUTION WARNING '
      ELSE
        HEADER=' UNKNOWN ERROR TYPE '
      ENDIF
      WRITE(*,1000)HEADER,ERRCOD
      WRITE(16,1000)HEADER,ERRCOD
C
C
C WARNING: GETENV is a non-standard FORTRAN 77 instruction, used here to
C obtain the value of the operating system environment variable
C HYPLASHOME - A character string containig the name of the
C directory where the file ERROR.RUN (containing the error/
C warning messages of HYPLAS) is kept in the file system. You
C may need to change this if your FORTRAN compiler does not
C support the instruction GETENV.
      CALL GETENV('HYPLASHOME',HYPLASHOME)
C
C Opens file ERROR.RUN
      NWRD=NWORD(HYPLASHOME,IWBEG,IWEND)
      INQUIRE(FILE=HYPLASHOME(1:IWEND(NWRD))//'/ERROR.RUN',EXIST=AVAIL)
      IF(.NOT.AVAIL)THEN
        WRITE(*,1040)
        WRITE(16,1040)
        GOTO 999
      ENDIF
      OPEN(23,FILE=HYPLASHOME(1:IWEND(NWRD))//'/ERROR.RUN',STATUS='OLD')
C
C Finds the character string with the given error code in file ERROR.RUN
      CALL FNDKEY
1(      FOUND      ,IWBEG      ,IWEND      ,ERRCOD      ,INLINE      ,
2      23          ,NWRD      )
      IF(.NOT.FOUND)THEN
        WRITE(*,1030)
        WRITE(16,1030)
        GOTO 998
      ENDIF
C
C Reads and echoes the associated error/warning message
      NLINES=INTNUM(INLINE(IWBEG(2):IWEND(2)))
      DO 10 I=1,NLINES
        READ(23,'(A72)')INLINE
        WRITE(*,1010)INLINE
        WRITE(16,1010)INLINE
10      CONTINUE
        WRITE(*,1020)
        WRITE(16,1020)
998      CONTINUE
        CLOSE(23,STATUS='KEEP')
999      CONTINUE
C
C All codes WE???? and WD???? are WARNING codes (execution warnings and
C input data warnings, respectively) and do not stop the execution
C of HYPLAS. Any other type of message code is seen as an ERROR code and
C will cause HYPLAS to stop its execution. Refer to comments in the
C file ERROR.RUN.
      IF(ERRCOD(1:2).NE.'WE'.AND.ERRCOD(1:2).NE.'WD')CALL PEXIT
      RETURN
      END

```

```

C      DOUBLE PRECISION FUNCTION EXP2X(X)
C
C      DOUBLE PRECISION X
C      DOUBLE PRECISION R2
C      DATA      R2      /2.0D0/
C*****
C SCALAR FUNCTION THAT RELATES EIGENVALUES OF THE CAUCHY-GREEN
C TENSOR TO THE PRINCIPAL LOGARITHMIC STRETCHES
C
C REFERENCE: Section 3.1.7
C*****
C      EXP2X=DEXP(R2*X)
C
C      RETURN
C      END

```



```

      SUBROUTINE EXPXMAP
      1( EXPX ,NOCONV ,X )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
      1( NDIM=3 ,NDIM2=9 )
C Arguments
      LOGICAL NOCONV
      DIMENSION
      1 EXPX(NDIM,NDIM) ,X(NDIM,NDIM)
C Local arrays and variables
      DIMENSION
      1 XN(NDIM,NDIM) ,XNM1(NDIM,NDIM) ,XNM2(NDIM,NDIM) ,
      2 XNM3(NDIM,NDIM) ,X2(NDIM,NDIM)
      DATA
      1 R0 ,RP5 ,R1 ,R2 ,TOL ,OVER ,UNDER /
      2 0.0D0,0.5D0,1.0D0,2.0D0,1.0D-10,1.0D+100,1.0D-100/
      DATA
      1 NMAX / 100 /
C*****
C COMPUTES THE EXPONENTIAL OF A (GENERALLY UNSYMMETRIC) 3-D TENSOR. USES
C THE SERIES REPRESENTATION OF THE TENSOR EXPONENTIAL
C
C REFERENCE: Section B.1
C Box B.1
C*****
C Initialise series convergence flag
      NOCONV=.FALSE.
C Compute X square
      CALL RVZERO(X2,NDIM2)
      DO 30 I=1,NDIM
        DO 20 J=1,NDIM
          DO 10 K=1,NDIM
            X2(I,J)= X2(I,J)+X(I,K)*X(K,J)
          10 CONTINUE
        20 CONTINUE
      30 CONTINUE
C Compute principal invariants of X
      C1=X(1,1)+X(2,2)+X(3,3)
      C2=RP5*(C1*C1-(X2(1,1)+X2(2,2)+X2(3,3)))
      C3=X(1,1)*X(2,2)*X(3,3)+X(1,2)*X(2,3)*X(3,1)+
      1 X(1,3)*X(2,1)*X(3,2)-X(1,2)*X(2,1)*X(3,3)-
      2 X(1,1)*X(2,3)*X(3,2)-X(1,3)*X(2,2)*X(3,1)
C Start computation of exponential using its series definition
C =====
      DO 50 I=1,NDIM
        DO 40 J=1,NDIM
          XNM1(I,J)=X2(I,J)
          XNM2(I,J)=X(I,J)
        40 CONTINUE
      50 CONTINUE
      XNM3(1,1)=R1
      XNM3(1,2)=R0
      XNM3(1,3)=R0
      XNM3(2,1)=R0
      XNM3(2,2)=R1
      XNM3(2,3)=R0
      XNM3(3,1)=R0
      XNM3(3,2)=R0
      XNM3(3,3)=R1
C Add first three terms of series
C -----
      DO 70 I=1,NDIM
        DO 60 J=1,NDIM
          EXPX(I,J)=RP5*XNM1(I,J)+XNM2(I,J)+XNM3(I,J)
        60 CONTINUE
      70 CONTINUE
C Add remaining terms (with X to the powers 3 to NMAX)
C -----
      FACTOR=R2
      DO 140 N=3,NMAX
C Use recursive formula to obtain X to the power N
        DO 90 I=1,NDIM
          DO 80 J=1,NDIM
            XN(I,J)=C1*XNM1(I,J)-C2*XNM2(I,J)+C3*XNM3(I,J)
          80 CONTINUE
        90 CONTINUE
C Update factorial
        FACTOR=DBLE(N)*FACTOR
        R1DFAC=R1/FACTOR
C Add Nth term of the series
        DO 110 I=1,NDIM
          DO 100 J=1,NDIM
            EXPX(I,J)=EXPX(I,J)+R1DFAC*XN(I,J)
          100 CONTINUE
        110 CONTINUE
C Check convergence of series
        XNNORM=SQRT(SCAPRD(XN(1,1),XN(1,1),NDIM2))
        IF(XNNORM.GT.OVER.OR.(XNNORM.LT.UNDER.AND.XNNORM.GT.R0)
      1 .OR.R1DFAC.LT.UNDER)THEN
C...first check possibility of overflow or underflow.
C...numbers are too small or too big: Break (unconverged) loop and exit
        NOCONV=.TRUE.
        GOTO 999
        ELSEIF(XNNORM*R1DFAC.LT.TOL)THEN
C...converged: Break series summation loop and exit with success
        GOTO 999
      ENDIF
      DO 130 I=1,NDIM
        DO 120 J=1,NDIM
          XNM3(I,J)=XNM2(I,J)
          XNM2(I,J)=XNM1(I,J)
          XNM1(I,J)=XN(I,J)
        120 CONTINUE
      130 CONTINUE
      140 CONTINUE
C Re-set convergence flag if series did not converge
      NOCONV=.TRUE.
C
      999 CONTINUE
      RETURN
      END

```



```

SUBROUTINE EXO4
1(   NGAUSP   ,EXMATX   )
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
  PARAMETER(NNODE=4)
  DIMENSION EXMATX(NNODE,NGAUSP)
  DATA R1 /
1    1.0D0 /
  DATA
1    A4      ,B4      ,C4      /
2    1.866025404D0 , -0.5D0 , 0.133974596D0 /
C*****
C SETS COEFFICIENTS MATRIX (EXMATX) FOR EXTRAPOLATION FROM GAUSS POINTS
C TO NODES FOR ELEMENT TYPE 'QUAD_4' (STANDARD 4-NODED BI-LINEAR
C QUADRILATERAL)
C
C REFERENCE: Section 5.6.1
C           E Hinton & JS Campbel. Local and global Smoothing of
C           discontinuous finite element functions using a least
C           squares method. Int. J. Num. meth. Engng., 8:461-480, 1974.
C           E Hinton & DRJ Owen. An introduction to finite element
C           computations. Pineridge Press, Swansea, 1979.
C*****
  IF(NGAUSP.EQ.1)THEN
    EXMATX(1,1)=R1
    EXMATX(2,1)=R1
    EXMATX(3,1)=R1
    EXMATX(4,1)=R1
  ELSEIF(NGAUSP.EQ.4)THEN
    EXMATX(1,1)=A4
    EXMATX(1,2)=B4
    EXMATX(1,3)=B4
    EXMATX(1,4)=C4
    EXMATX(2,1)=B4
    EXMATX(2,2)=C4
    EXMATX(2,3)=A4
    EXMATX(2,4)=B4
    EXMATX(3,1)=C4
    EXMATX(3,2)=B4
    EXMATX(3,3)=B4
    EXMATX(3,4)=A4
    EXMATX(4,1)=B4
    EXMATX(4,2)=A4
    EXMATX(4,3)=C4
    EXMATX(4,4)=B4
  ENDIF
  RETURN
END

```

```

SUBROUTINE EXO4FB( EXMATX )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER
1(      NGAUSP=4      ,NNODE=4      )
DIMENSION EXMATX(NNODE,NGAUSP)
DATA
1      A4      ,B4      ,C4      /
2      1.866025404D0      ,-0.5D0      ,0.133974596D0      /
C*****
C SET COEFFICIENTS MATRIX (EXMATX) FOR EXTRAPOLATION FROM GAUSS POINTS
C TO NODES FOR ELEMENT TYPE 'QUAD_4_FBAR' (F-BAR 4-NODED BI-LINEAR
C QUADRILATERAL)
C
C REFERENCE: Section 5.6.1
C      E Hinton & JS Campbel. Local and global Smoothing of
C      discontinuous finite element functions using a least
C      squares method. Int. J. Num. meth. Engng., 8:461-480, 1974.
C      E Hinton & DRJ Owen. An introduction to finite element
C      computations. Pineridge Press, Swansea, 1979.
C*****
      EXMATX(1,1)=A4
      EXMATX(1,2)=B4
      EXMATX(1,3)=B4
      EXMATX(1,4)=C4
      EXMATX(2,1)=B4
      EXMATX(2,2)=C4
      EXMATX(2,3)=A4
      EXMATX(2,4)=B4
      EXMATX(3,1)=C4
      EXMATX(3,2)=B4
      EXMATX(3,3)=B4
      EXMATX(3,4)=A4
      EXMATX(4,1)=B4
      EXMATX(4,2)=A4
      EXMATX(4,3)=C4
      EXMATX(4,4)=B4
      RETURN
      END

```

```

SUBROUTINE EXO8
1(   NGAUSP   ,EXMATX   )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(NNODE=8)
DIMENSION EXMATX(NNODE,NGAUSP)
DATA R0      ,RP5      ,R1      /
1  0.0D0 ,0.5D0 ,1.0D0 /
DATA
1  A4      ,B4      ,C4      /
2  1.866025404D0 , -0.5D0 ,0.133974596D0 /
DATA
1  A5      ,B5      ,C5      /
2  1.290994449D0 , -0.290994449D0 ,0.645497224D0 /
DATA
1  A9      ,B9      ,C9      ,
2  D9      ,E9      ,F9      ,
3  G9      ,H9      ,P9      /
4  2.186939819D0 ,0.277777778D0 ,0.035282404D0 ,
5  1.478830558D0 ,0.187836109D0 , -0.985887039D0 ,
6  -0.125224073D0 ,0.444444444D0 , -0.666666667D0 /
C*****
C SET COEFFICIENTS MATRIX (EXMATX) FOR EXTRAPOLATION FROM GAUSS POINTS
C TO NODES FOR ELEMENT TYPE 'QUAD_8' (STANDARD 8-NODED QUADRILATERAL)
C
C REFERENCE: Section 5.6.1
C           E Hinton & JS Campbel. Local and global Smoothing of
C           discontinuous finite element functions using a least
C           squares method. Int. J. Num. meth. Engng., 8:461-480, 1974.
C           E Hinton & DRJ Owen. An introduction to finite element
C           computations. Pineridge Press, Swansea, 1979.
C*****
IF(NGAUSP.EQ.1)THEN
  EXMATX(1,1)=R1
  EXMATX(2,1)=R1
  EXMATX(3,1)=R1
  EXMATX(4,1)=R1
  EXMATX(5,1)=R1
  EXMATX(6,1)=R1
  EXMATX(7,1)=R1
  EXMATX(8,1)=R1
ELSEIF(NGAUSP.EQ.4)THEN
  EXMATX(1,1)=A4
  EXMATX(1,2)=B4
  EXMATX(1,3)=B4
  EXMATX(1,4)=C4
  EXMATX(2,1)=RP5*(A4+B4)
  EXMATX(2,2)=RP5*(B4+C4)
  EXMATX(2,3)=RP5*(B4+A4)
  EXMATX(2,4)=RP5*(C4+B4)
  EXMATX(3,1)=B4
  EXMATX(3,2)=C4
  EXMATX(3,3)=A4
  EXMATX(3,4)=B4
  EXMATX(4,1)=RP5*(B4+C4)
  EXMATX(4,2)=RP5*(C4+B4)
  EXMATX(4,3)=RP5*(A4+B4)
  EXMATX(4,4)=RP5*(B4+A4)
  EXMATX(5,1)=C4
  EXMATX(5,2)=B4
  EXMATX(5,3)=B4
  EXMATX(5,4)=A4
  EXMATX(6,1)=RP5*(C4+B4)
  EXMATX(6,2)=RP5*(B4+A4)
  EXMATX(6,3)=RP5*(B4+C4)
  EXMATX(6,4)=RP5*(A4+B4)
  EXMATX(7,1)=B4
  EXMATX(7,2)=A4
  EXMATX(7,3)=C4
  EXMATX(7,4)=B4
  EXMATX(8,1)=RP5*(B4+A4)
  EXMATX(8,2)=RP5*(A4+B4)
  EXMATX(8,3)=RP5*(C4+B4)
  EXMATX(8,4)=RP5*(B4+C4)
ELSEIF(NGAUSP.EQ.5)THEN
  EXMATX(1,1)=A5
  EXMATX(1,2)=R0
  EXMATX(1,3)=R0
  EXMATX(1,4)=R0
  EXMATX(1,5)=B5
  EXMATX(2,1)=C5
  EXMATX(2,2)=R0
  EXMATX(2,3)=C5
  EXMATX(2,4)=R0
  EXMATX(2,5)=B5
  EXMATX(3,1)=R0
  EXMATX(3,2)=R0
  EXMATX(3,3)=A5
  EXMATX(3,4)=R0
  EXMATX(3,5)=B5
  EXMATX(4,1)=R0
  EXMATX(4,2)=R0
  EXMATX(4,3)=C5
  EXMATX(4,4)=C5
  EXMATX(4,5)=B5
  EXMATX(5,1)=R0
  EXMATX(5,2)=R0
  EXMATX(5,3)=R0
  EXMATX(5,4)=A5

```

```

EXMATX(5,5)=B5
EXMATX(6,1)=R0
EXMATX(6,2)=C5
EXMATX(6,3)=R0
EXMATX(6,4)=C5
EXMATX(6,5)=B5
EXMATX(7,1)=R0
EXMATX(7,2)=A5
EXMATX(7,3)=R0
EXMATX(7,4)=R0
EXMATX(7,5)=B5
EXMATX(8,1)=C5
EXMATX(8,2)=C5
EXMATX(8,3)=R0
EXMATX(8,4)=R0
EXMATX(8,5)=B5
ELSEIF(NGAUSP.EQ.9) THEN
EXMATX(1,1)=A9
EXMATX(1,2)=F9
EXMATX(1,3)=B9
EXMATX(1,4)=F9
EXMATX(1,5)=H9
EXMATX(1,6)=G9
EXMATX(1,7)=B9
EXMATX(1,8)=G9
EXMATX(1,9)=C9
EXMATX(2,1)=R0
EXMATX(2,2)=R0
EXMATX(2,3)=R0
EXMATX(2,4)=D9
EXMATX(2,5)=P9
EXMATX(2,6)=E9
EXMATX(2,7)=R0
EXMATX(2,8)=R0
EXMATX(2,9)=R0
EXMATX(3,1)=B9
EXMATX(3,2)=G9
EXMATX(3,3)=C9
EXMATX(3,4)=F9
EXMATX(3,5)=H9
EXMATX(3,6)=G9
EXMATX(3,7)=A9
EXMATX(3,8)=F9
EXMATX(3,9)=B9
EXMATX(4,1)=R0
EXMATX(4,2)=E9
EXMATX(4,3)=R0
EXMATX(4,4)=R0
EXMATX(4,5)=P9
EXMATX(4,6)=R0
EXMATX(4,7)=R0
EXMATX(4,8)=D9
EXMATX(4,9)=R0
EXMATX(5,1)=C9
EXMATX(5,2)=G9
EXMATX(5,3)=B9
EXMATX(5,4)=G9
EXMATX(5,5)=H9
EXMATX(5,6)=F9
EXMATX(5,7)=B9
EXMATX(5,8)=F9
EXMATX(5,9)=A9
EXMATX(6,1)=R0
EXMATX(6,2)=R0
EXMATX(6,3)=R0
EXMATX(6,4)=E9
EXMATX(6,5)=P9
EXMATX(6,6)=D9
EXMATX(6,7)=R0
EXMATX(6,8)=R0
EXMATX(6,9)=R0
EXMATX(7,1)=B9
EXMATX(7,2)=F9
EXMATX(7,3)=A9
EXMATX(7,4)=G9
EXMATX(7,5)=H9
EXMATX(7,6)=F9
EXMATX(7,7)=C9
EXMATX(7,8)=G9
EXMATX(7,9)=B9
EXMATX(8,1)=R0
EXMATX(8,2)=D9
EXMATX(8,3)=R0
EXMATX(8,4)=R0
EXMATX(8,5)=P9
EXMATX(8,6)=R0
EXMATX(8,7)=R0
EXMATX(8,8)=E9
EXMATX(8,9)=R0
ENDIF

```

C

```

RETURN
END

```

```

      SUBROUTINE EXT3
1(      EXMATX
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(NNODE=3,NGAUSP=1)
      DIMENSION EXMATX(NNODE,NGAUSP)
      DATA R1
1          1.0D0 /
C*****
C SET COEFFICIENTS MATRIX (EXMATX) FOR EXTRAPOLATION FROM GAUSS POINTS
C TO NODES FOR ELEMENT TYPE 'TRI_3' (STANDARD 3-NODED LINEAR TRIANGLE)
C
C REFERENCE: Section 5.6.1
C           E Hinton & JS Campbel. Local and global Smoothing of
C           discontinuous finite element functions using a least
C           squares method. Int. J. Num. meth. Engng., 8:461-480, 1974.
C           E Hinton & DRJ Owen. An introduction to finite element
C           computations. Pineridge Press, Swansea, 1979.
C*****
      EXMATX(1,1)=R1
      EXMATX(2,1)=R1
      EXMATX(3,1)=R1
C
      RETURN
      END

```

```

      SUBROUTINE EXTNOD
1(      EXMATX      ,VARGP      ,VARNOD      ,NVAR      ,NGAUSP      ,
2      NNODE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      INCLUDE '../ELEMENTS.INC'
      DIMENSION
1      EXMATX(NNODE,NGAUSP),VARGP(NVAR,NGAUSP),VARNOD(NVAR,NNODE)
C*****
C EXTRAPOLATES GAUSS POINT VALUES OF A GIVEN FIELD TO NODES
C
C REFERENCE: Section 5.6.1
C           E Hinton & JS Campbel. Local and global Smoothing of
C           discontinuous finite element functions using a least
C           squares method. Int. J. Num. meth. Engng., 8:461-480, 1974.
C           E Hinton & DRJ Owen. An introduction to finite element
C           computations. Pineridge Press, Swansea, 1979.
C*****
      CALL RVZERO(VARNOD,NVAR*NNODE)
      DO 30 IVAR=1,NVAR
        DO 20 INODE=1,NNODE
          DO 10 IGAUSP=1,NGAUSP
            VARNOD(IVAR,INODE)=VARNOD(IVAR,INODE)+
1              EXMATX(INODE,IGAUSP)*VARGP(IVAR,IGAUSP)
10          CONTINUE
20        CONTINUE
30      CONTINUE
C
      RETURN
      END

```



```
      SUBROUTINE FCLOSE
C*****
C CLOSSES DATA AND RESULTS FILES
C*****
      CLOSE(UNIT=15,STATUS='KEEP')
      CLOSE(UNIT=16,STATUS='KEEP')
      RETURN
      END
```

```

      SUBROUTINE FNDKEY
1(      FOUND      ,IWBE      ,IWEND      ,KEYWRD      ,INLINE      ,
2      NFILE      ,NWRD      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL FOUND
      CHARACTER*80 INLINE
      CHARACTER*(*) KEYWRD
      DIMENSION
1      IWBE(40), IWEND(40)
C*****
C FINDS AND READS A LINE CONTAINING A SPECIFIED KEYWORD FROM A FILE.
C THIS ROUTINE SEARCHES FOR A GIVEN KEYWORD POSITIONED AS THE FIRST
C WORD OF A LINE IN A FILE.
C IF THE GIVEN KEYWORD IS FOUND THEN THE CORRESPONDING LINE IS READ AND
C RETURNED TOGETHER WITH THE NUMBER OF WORDS IN THE LINE AND TWO INTEGER
C ARRAYS CONTAINING THE POSITION OF THE BEGINNING AND END OF EACH WORD.
C*****
1000 FORMAT(A80)
C
      FOUND=.TRUE.
      IEND=0
10 READ(NFILE,1000,END=20)INLINE
      NWRD=NWORD(INLINE,IWBE,IWEND)
      IF(NWRD.NE.0)THEN
        IF(INLINE(IWBE(1):IWEND(1)).EQ.KEYWRD)THEN
          GOTO 999
        ENDIF
      ENDIF
      GOTO 10
20 IF(IEND.EQ.0)THEN
      IEND=1
      REWIND NFILE
      GOTO 10
    ELSE
      FOUND=.FALSE.
    ENDIF
999 RETURN
      END

```

```

      SUBROUTINE FOPEN
1(   DATFIL   ,RESFIL   ,RSTOUT   )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      CHARACTER DATFIL*256,RESFIL*256,RSTOUT*256
      CHARACTER BELL*1
      LOGICAL AVAIL
C*****
C READ DATA FILE NAME FROM STANDARD INPUT, SET NAMES FOR AND OPEN DATA
C AND RESULTS FILES AND SET RE-START FILE NAME
C
C REFERENCE: Figure 5.1
C*****
C Read data file name from standard input
C -----
      WRITE(*,'(///15X,A,/15X,A)')
1'Data file name must have extension .dat or .DAT',
2'and must not contain blank spaces.'
      WRITE(*,'(/15X,A)')'(Type EXIT or QUIT to terminate)'
10 WRITE(*,'(//15X,A$)')'Input data file name -----> '
      READ(*,'(A)',ERR=10)DATFIL
C Sort out data, result and re-start file names and open data and
C result files
C -----
      BELL=CHAR(7)
C Find end of data file name
      I=INDEX(DATFIL,' ')-1
      IF(I.EQ.0)THEN
          WRITE(*,'(/15X,A)')
1          GOTO 10
      ELSEIF(I.EQ.4.AND.
1          (DATFIL(1:4).EQ.'EXIT'.OR.DATFIL(1:4).EQ.'exit'
2          .OR.DATFIL(1:4).EQ.'QUIT'.OR.DATFIL(1:4).EQ.'quit'))THEN
          WRITE(*,'(///15X,A,///)')'Program HYPLAS terminated by user.'
          STOP ' '
      ENDIF
C Check data file name extension: it must be either .dat or .DAT
      IF((I-3.LT.1).OR.(DATFIL(I-3:I).NE.'.dat'.AND.
1          DATFIL(I-3:I).NE.'.DAT'))THEN
          WRITE(*,'(/15X,A,/15X,A)')
1          'Data file name does not have extension .dat or .DAT !',
2          'Please try again'
          WRITE(*,'(1X,A$)')BELL
          GOTO 10
      ENDIF
C Check existence of data file
      INQUIRE(FILE=DATFIL,EXIST=AVAIL)
      IF(.NOT.AVAIL)THEN
          WRITE(*,'(/A,A,A,A)')
1          'File "',DATFIL(1:I)," not found ! ',
2          'Please try again'
          WRITE(*,'(1X,A$)')BELL
          GOTO 10
      ENDIF
C give name to results file (with extension .res)
      RESFIL(1:I-3)=DATFIL(1:I-3)
      RESFIL(I-3:I)='.res'
      RESFIL(I+1:256)=DATFIL(I+1:256)
C give name to output re-start file (with extension .rst)
      RSTOUT(1:I-3)=DATFIL(1:I-3)
      RSTOUT(I-3:I)='.rst'
      RSTOUT(I+1:256)=DATFIL(I+1:256)
C Open data and results file
      OPEN(UNIT=15,FILE=DATFIL,STATUS='OLD')
      OPEN(UNIT=16,FILE=RESFIL,STATUS='UNKNOWN')
C
      RETURN
      END

```

```

      SUBROUTINE FRONT
1(      IITER      ,KRESL      ,IFNEG      ,KUNLD      ,MXFRON      ,
2      UNSYM      ,INCCUT      )
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas global database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C Common block of arrays used only by the frontal solver. This common
C block is firstly defined in HYPLAS main program
      COMMON / FRONTA /
1      EQRHS(MTOTV,2)      ,EQROW(MFRON,MTOTV) ,EQCOL(MFRON,MTOTV) ,
2      DECAY(MFRON)      ,GLOAD(MFRON,2)      ,VECRV(MFRON,2)      ,
3      LOCEL(MEVAB,MELEM) ,NACVA(MFRON,MELEM) ,NAMEV(MTOTV)      ,
4      NDEST(MEVAB,MELEM) ,NPIVO(MTOTV)      ,NFRON(MELEM)
C Arguments
      LOGICAL UNSYM, INCCUT
C Local arrays and variables
      DIMENSION
1      ESTIF(MEVAB,MEVAB)
      DIMENSION
1      GSTIF(MFRON*MFRON),LACVA(MFRON)
C Numerical constants
      DATA R0,R2,E5,E10/0.0D0,2.0D0,1.0D5,1.0D10/
C*****
C ASSEMBLES AND SOLVES THE GLOBAL SYSTEM OF LINEAR ALGEBRAIC FINITE
C ELEMENT EQUILIBRIUM EQUATIONS (LINEARISED EQUILIBRIUM EQUATIONS FOR
C NON-LINEAR PROBLEMS) BY THE FRONTAL METHOD
C
C REFERENCE: Section 5.4.4
C*****
1010 FORMAT('// Zero pivot encountered for variable no.',
1I5,' of value',G14.6/)
1020 FORMAT('// *** WARNING ***/' Diagonal decay of',G14.6,
1' for variable no.',I5/
2' probable mechanism or flying structure'//)
1030 FORMAT('// *** WARNING ***/' Diagonal decay of',G14.6,
1' for variable no.',I5/
2' roundoff errors likely'//)
C Initialise increment cutting flag
      INCCUT=.FALSE.
C Decide solution required
      IF(NALGO.LT.0.AND.IITER.EQ.1.AND.KRESL.EQ.2)THEN
          NRHS=0
          MODE=0
      ELSE IF(NALGO.LT.0.AND.IITER.EQ.1.AND.KRESL.EQ.1)THEN
          NRHS=1
          MODE=2
      ELSE IF(NALGO.LT.0.AND.IITER.GT.1.AND.KRESL.EQ.1)THEN
          NRHS=2
          MODE=3
      ELSE IF(NALGO.LT.0.AND.IITER.GT.1.AND.KRESL.EQ.2)THEN
          NRHS=1
          MODE=1
      ELSE
          NRHS=1
          MODE=1
      ENDIF
      IF(MODE.EQ.0)GOTO 900
C Frontal stiffness (GSTIF)
C Start by initializing everything that matters to zero
      IF(IITER.GT.1)KUNLD=0
      IF(KRESL.EQ.1)THEN
          IF(.NOT.UNSYM)THEN
              MSTIF=(MXFRON*(MXFRON+1))/2
              DO 150 ISTIF=1,MSTIF
                  GSTIF(ISTIF)=R0
150          CONTINUE
              ENDIF
          ENDIF
          DO 160 IFRON=1,MXFRON
              DO 152 IRHS=1,NRHS
                  GLOAD(IFRON,IRHS)=R0
                  VECRV(IFRON,IRHS)=R0
152          CONTINUE
              IF(KRESL.EQ.1)THEN
                  DECAY(IFRON)=R0
                  IF(UNSYM)THEN
                      DO 155 JFRON=1,MXFRON
                          GSTIF((IFRON-1)*MXFRON+JFRON)=R0
155                      CONTINUE
                      ENDIF
                      DO 156 IBUFA=1,NTOTV
                          EQROW(IFRON,IBUFA)=R0
                          EQCOL(IFRON,IBUFA)=R0
156                      CONTINUE
                      ENDIF
160          CONTINUE
              IF(KRESL.EQ.1)IFNEG=1
              NBUFA=0
              NVARB=0
C
C Main element assembly-reduction loop
C =====
      KELVA=0
      DO 320 IELEM=1,NELEM
          IGRUP=IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NNODE=IELPRP(3,IELIDN)
          NEVAB=IELPRP(5,IELIDN)
          IF(KRESL.GT.1) GOTO 400
          IF(IELEM.EQ.1)THEN
              NFRON(IELEM)=0
              DO 161 IFRON=1,MXFRON
                  NACVA(IFRON,IELEM)=0
161          CONTINUE
          ELSE
              NFRON(IELEM)=NFRON(IELEM-1)
              DO 162 IFRON=1,MXFRON
                  NACVA(IFRON,IELEM)=LACVA(IFRON)
162          CONTINUE

```

```

ENDIF
C
C Call element interface routine for computation of element stiffness
C -----
      CALL ELEMIST
      1( ESTIF , IELEM , KUNLD , UNSYM )
C
C transform the stiffness matrix into the local nodal coordinate system
C for prescribed displacements at an angle (for 2-D only)
      DO 168 INODE=1,NNODE
        LNODE=IABS(LNODS(IELEM,INODE))
        DO 167 IVFIX=1,NVFIX
          IF(NOFIX(IVFIX).EQ.LNODE)THEN
            IF(ANGLE(IVFIX).EQ.R0)GOTO 168
            C=COS(ANGLE(IVFIX))
            S=SIN(ANGLE(IVFIX))
            IEVAB=(INODE-1)*NDOFN+1
            JEVAB=IEVAB+1
            DO 165 KEVAB=1,NEVAB
              GASHI= C*ESTIF(IEVAB,KEVAB)+S*ESTIF(JEVAB,KEVAB)
              GASHJ=-S*ESTIF(IEVAB,KEVAB)+C*ESTIF(JEVAB,KEVAB)
              ESTIF(IEVAB,KEVAB)=GASHI
              ESTIF(JEVAB,KEVAB)=GASHJ
            165 CONTINUE
            DO 166 KEVAB=1,NEVAB
              GASHI= ESTIF(KEVAB,IEVAB)*C+ESTIF(KEVAB,JEVAB)*S
              GASHJ=-ESTIF(KEVAB,IEVAB)*S+ESTIF(KEVAB,JEVAB)*C
              ESTIF(KEVAB,IEVAB)=GASHI
              ESTIF(KEVAB,JEVAB)=GASHJ
            166 CONTINUE
            GOTO 168
          ENDIF
        167 CONTINUE
      168 CONTINUE
C
      DO 175 INODE=1,NNODE
        DO 170 IDOFN=1,NDOFN
          IEVAB=(IDOFN-1)*NNODE+INODE
          NPOSI=(INODE-1)*NDOFN+IDOFN
          IPOIN=IABS(LNODS(IELEM,INODE))
          LOCEL(NPOSI,IELEM)=
            1 SIGN(MASTER(NDOFN*(IPOIN-1)+IDOFN),LNODS(IELEM,IEVAB))
        170 CONTINUE
      175 CONTINUE
C
C Start by looking for existing destinations
      KEVAB=0
      DO 210 IEVAB=1,NEVAB
        NIKNO=IABS(LOCEL(IEVAB,IELEM))
        KEXIS=0
        DO 180 IFRON=1,NFRON(IELEM)
          IF(NIKNO.NE.NACVA(IFRON,IELEM)) GOTO 180
          KEVAB=KEVAB+1
          KEXIS=1
          NDEST(KEVAB,IELEM)=IFRON
        180 CONTINUE
        IF(KEXIS.NE.0) GOTO 210
C
C Now seek new empty places for destination vector
      DO 190 IFRON=1,MXFRON
        IF(NACVA(IFRON,IELEM).NE.0) GOTO 190
        NACVA(IFRON,IELEM)=NIKNO
        KEVAB=KEVAB+1
        NDEST(KEVAB,IELEM)=IFRON
        GOTO 200
      190 CONTINUE
C
C The new places may demand an increase in current frontwidth
      200 IF(NDEST(KEVAB,IELEM).GT.NFRON(IELEM)) NFRON(IELEM)=
        1 NDEST(KEVAB,IELEM)
      210 CONTINUE
      400 CONTINUE
      LFRON=NFRON(IELEM)
      DO 205 IFRON=1,MXFRON
        LACVA(IFRON)=NACVA(IFRON,IELEM)
      205 CONTINUE
C Assemble element loads in local nodal coordinate system if node has
C prescribed displacements at an angle (for 2-D only)
      DO 215 INODE=1,NNODE
        IEVAB=(INODE-1)*NDOFN
        LNODE=IABS(LNODS(IELEM,INODE))
        DO 211 IVFIX=1,NVFIX
          IF(NOFIX(IVFIX).EQ.LNODE.AND.ANGLE(IVFIX).NE.R0)THEN
            C=COS(ANGLE(IVFIX))
            S=SIN(ANGLE(IVFIX))
            IEVAB=IEVAB+1
            JEVAB=IEVAB+1
            IDEST=NDEST(IEVAB,IELEM)
            JDEST=NDEST(JEVAB,IELEM)
            IF(MODE.EQ.1)THEN
              GLOAD(IDEST,1)=GLOAD(IDEST,1)+
                1 C*ELOAD(IEVAB,IELEM)+S*ELOAD(JEVAB,IELEM)
              GLOAD(JDEST,1)=GLOAD(JDEST,1)-
                1 S*ELOAD(IEVAB,IELEM)+C*ELOAD(JEVAB,IELEM)
            ELSE IF(MODE.EQ.2)THEN
              GLOAD(IDEST,1)=GLOAD(IDEST,1)+
                1 C*RLOAD(IEVAB,IELEM)+S*RLOAD(JEVAB,IELEM)
              GLOAD(JDEST,1)=GLOAD(JDEST,1)-
                1 S*RLOAD(IEVAB,IELEM)+C*RLOAD(JEVAB,IELEM)
            ELSE IF(MODE.EQ.3)THEN
              GLOAD(IDEST,1)=GLOAD(IDEST,1)+
                1 C*RLOAD(IEVAB,IELEM)+S*RLOAD(JEVAB,IELEM)
              GLOAD(JDEST,1)=GLOAD(JDEST,1)-
                1 S*RLOAD(IEVAB,IELEM)+C*RLOAD(JEVAB,IELEM)
              GLOAD(IDEST,2)=GLOAD(IDEST,2)+
                1 C*ELOAD(IEVAB,IELEM)+S*ELOAD(JEVAB,IELEM)
              GLOAD(JDEST,2)=GLOAD(JDEST,2)-
                1 S*ELOAD(IEVAB,IELEM)+C*ELOAD(JEVAB,IELEM)
            ENDIF
            GOTO 215
          ENDIF
        211 CONTINUE
      DO 212 IDOFN=1,NDOFN

```

```

        IEVAB=IEVAB+1
        IDEST=NDEST(IEVAB,IELEM)
        IF(MODE.EQ.1)THEN
            GLOAD(IDEST,1)=GLOAD(IDEST,1)+ELOAD(IEVAB,IELEM)
        ELSE IF(MODE.EQ.2)THEN
            GLOAD(IDEST,1)=GLOAD(IDEST,1)+RLOAD(IEVAB,IELEM)
        ELSE IF(MODE.EQ.3)THEN
            GLOAD(IDEST,1)=GLOAD(IDEST,1)+RLOAD(IEVAB,IELEM)
            GLOAD(IDEST,2)=GLOAD(IDEST,2)+ELOAD(IEVAB,IELEM)
        ENDIF
212    CONTINUE
215    CONTINUE
C
C Assemble the element stiffnesses - but not in resolution
        IF(KRESL.GT.1) GOTO 402
        DO 220 IEVAB=1,NEVAB
            IDEST=NDEST(IEVAB,IELEM)
            IF(UNSYM)THEN
                LEVAB=NEVAB
            ELSE
                LEVAB=IEVAB
            ENDIF
            DO 222 JEVAB=1,LEVAB
                JDEST=NDEST(JEVAB,IELEM)
                IF(UNSYM)THEN
                    NGESH=(IDEST-1)*MXFRON+JDEST
                ELSE
                    IF((IDEST.EQ.JDEST).AND.(IEVAB.NE.JEVAB))
1                        ESTIF(IEVAB,JEVAB)=R2*ESTIF(IEVAB,JEVAB)
                        NGASH=NFUNC(IDEST,JDEST)
                        NGISH=NFUNC(JDEST,IDEST)
                        IF(JDEST.GE.IDEST)NGESH=NGASH
                        IF(JDEST.LT.IDEST)NGESH=NGISH
                    ENDIF
                    GSTIF(NGESH)=GSTIF(NGESH)+ESTIF(IEVAB,JEVAB)
                222    CONTINUE
C If diagonal term modified evaluate contribution to diagonal decay
                DECAY(IDEST)=DECAY(IDEST)+GSTIF(NGESH)*GSTIF(NGESH)
                220    CONTINUE
                402    CONTINUE
C
C Re-examine each element node, to enquire which can be eliminated
        DO 310 IEVAB=1,NEVAB
            NIKNO=-LOCLE(IEVAB,IELEM)
            IF(NIKNO.LE.0) GOTO 310
C
C Find positions of variables ready for elimination
        DO 300 IFRON=1,LFRON
            IF(LACVA(IFRON).NE.NIKNO) GOTO 300
            NBUFA=NBUFA+1
            NVARB=NVARB+1
C
C Extract the coefficients of the new equation for elimination
        IF(KRESL.GT.1) GOTO 404
        DO 230 JFRON=1,MXFRON
            IF(UNSYM)THEN
                NLOCA=(IFRON-1)*MXFRON+JFRON
            ELSE
                IF(IFRON.LT.JFRON) NLOCA=NFUNC(IFRON,JFRON)
                IF(IFRON.GE.JFRON) NLOCA=NFUNC(JFRON,IFRON)
            ENDIF
            EQROW(JFRON,NBUFA)=GSTIF(NLOCA)
            GSTIF(NLOCA)=R0
            IF(UNSYM)THEN
                NLOCA=(JFRON-1)*MXFRON+IFRON
                EQCOL(JFRON,NBUFA)=GSTIF(NLOCA)
                GSTIF(NLOCA)=R0
            ENDIF
230    CONTINUE
404    CONTINUE
C
C ...and extract the corresponding right hand sides
        DO 235 IRHS=1,NRHS
            EQRHS(NVARB,IRHS)=GLOAD(IFRON,IRHS)
            GLOAD(IFRON,IRHS)=R0
235    CONTINUE
            KELVA=KELVA+1
            NAMEV(NVARB)=NIKNO
            NPIVO(NVARB)=IFRON
C
C Deal with pivot
            PIVOT=EQROW(IFRON,NBUFA)
            IF(KRESL.EQ.1.AND.PIVOT.LT.R0)THEN
                IFNEG=-1*IFNEG
            ENDIF
C
C Enquire whether present variable is free or prescribed
            IF(IFFIX(NIKNO).EQ.0) GOTO 250
C
C Deal with a prescribed nodal displacement
        DO 240 JFRON=1,LFRON
            IF(JFRON.EQ.IFRON)GOTO 240
            IF(.NOT.UNSYM)EQCOL(JFRON,NBUFA)=EQROW(JFRON,NBUFA)
            DO 237 IRHS=1,NRHS
                GLOAD(JFRON,IRHS)=GLOAD(JFRON,IRHS)-
1                    FIXED(NIKNO,IRHS)*EQCOL(JFRON,NBUFA)
237    CONTINUE
240    CONTINUE
            GOTO 280
C
C Eliminate a free variable - Deal with the right hand side first
250    CONTINUE
            IF(KRESL.EQ.1)THEN
                IF(PIVOT.EQ.R0)THEN
                    WRITE(16,1010) NIKNO,PIVOT
                    CALL ERRPR('WE0008')
                    INCCUT=.TRUE.
                    GOTO 900
                ENDIF
C Check diagonal decay
                DECAY(IFRON)=SQRT(DECAY(IFRON))/PIVOT
                IF(ABS(DECAY(IFRON)).GE.E10)THEN
C Print warning of mechanism or flying structure

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        WRITE(16,1020)DECAY(IFRON),NIKNO
        ELSE IF(ABS(DECAY(IFRON)).GE.E5)THEN
C Print warning of roundoff errors
        WRITE(16,1030)DECAY(IFRON),NIKNO
        ENDIF
    ENDIF
DO 270 JFRON=1,LFRON
    IF(JFRON.EQ.IFRON)GOTO 270
    IF(.NOT.UNSYM)EQCOL(JFRON,NBUFA)=EQROW(JFRON,NBUFA)
    DO 255 IRHS=1,NRHS
        GLOAD(JFRON,IRHS)=GLOAD(JFRON,IRHS)-EQCOL(JFRON,NBUFA)*
1          EQRHS(NVARB,IRHS)/PIVOT
    255 CONTINUE
C
C Now deal with the coefficients in core
    IF(KRESL.GT.1) GOTO 418
    IF(EQCOL(JFRON,NBUFA).EQ.R0) GOTO 270
    CUREQ=EQCOL(JFRON,NBUFA)
    IF(UNSYM)THEN
        NJFRON=LFRON
    ELSE
        NLOCA=NEUNC(0,JFRON)
        NJFRON=JFRON
    ENDIF
    DO 260 KFRON=1,NJFRON
        IF(KFRON.EQ.IFRON)GOTO 260
        IF(UNSYM)THEN
            NGASH=(JFRON-1)*MXFRON+KFRON
        ELSE
            NGASH=KFRON+NLOCA
        ENDIF
        GSTIF(NGASH)=GSTIF(NGASH)-CUREQ*EQROW(KFRON,NBUFA)/PIVOT
    260 CONTINUE
C If diagonal term modified evaluate contribution to diagonal decay
    DECAY(JFRON)=DECAY(JFRON)+GSTIF(NGASH)*GSTIF(NGASH)
    418 CONTINUE
    270 CONTINUE
    280 CONTINUE
C
C Record the new vacant space, and reduce frontwidth if possible
    LACVA(IFRON)=0
C Initialize diagonal decay
    DECAY(IFRON)=R0
    GOTO 290
C
C Complete the element loop in the forward elimination
C
    300 CONTINUE
    290 IF(LACVA(LFRON).NE.0) GOTO 310
    LFRON=LFRON-1
    IF(LFRON.GT.0) GOTO 290
    310 CONTINUE
    320 CONTINUE
C
C Back-substitution phase. Loop backwards through variables
C =====
    DO 340 IELVA=1,KELVA
C
C Prepare to back-substitute from the current equation
        IFRON=NPIVO(NVARB)
        NIKNO=NAMEV(NVARB)
        PIVOT=EQROW(IFRON,NBUFA)
        DO 325 IRHS=1,NRHS
            IF(IFFIX(NIKNO).NE.0) VECRV(IFRON,IRHS)=FIXED(NIKNO,IRHS)
    325 CONTINUE
        IF(IFFIX(NIKNO).EQ.0)SEQROW=EQROW(IFRON,NBUFA)
        IF(IFFIX(NIKNO).EQ.0)EQROW(IFRON,NBUFA)=R0
C
C Back-substitute in the current equation
        DO 331 JFRON=1,MXFRON
            DO 330 IRHS=1,NRHS
                EQRHS(NVARB,IRHS)=EQRHS(NVARB,IRHS)-
1          VECRV(JFRON,IRHS)*EQROW(JFRON,NBUFA)
            330 CONTINUE
        331 CONTINUE
        IF(IFFIX(NIKNO).EQ.0) EQROW(IFRON,NBUFA)=SEQROW
C
C Put the final values where they belong
        DO 335 IRHS=1,NRHS
            IF(IFFIX(NIKNO).EQ.0)VECRV(IFRON,IRHS)=EQRHS(NVARB,IRHS)/PIVOT
            IF(IFFIX(NIKNO).NE.0)FIXED(NIKNO,IRHS)=-EQRHS(NVARB,IRHS)
    335 CONTINUE
        NBUFA=NBUFA-1
        NVARB=NVARB-1
        IF(MODE.EQ.1)THEN
            DITER(NIKNO)=VECRV(IFRON,1)
        ELSE IF(MODE.EQ.2)THEN
            DTANG(NIKNO)=VECRV(IFRON,1)
        ELSE IF(MODE.EQ.3)THEN
            DTANG(NIKNO)=VECRV(IFRON,1)
            DITER(NIKNO)=VECRV(IFRON,2)
        ENDIF
    340 CONTINUE
C Copy displacements of master degrees of freedom to slaves
    DO 530 ITOTV=1,NTOTV
        IF(MODE.EQ.1)THEN
            DITER(ITOTV)=DITER(MASTER(ITOTV))
        ELSE IF(MODE.EQ.2)THEN
            DTANG(ITOTV)=DTANG(MASTER(ITOTV))
        ELSE IF(MODE.EQ.3)THEN
            DTANG(ITOTV)=DTANG(MASTER(ITOTV))
            DITER(ITOTV)=DITER(MASTER(ITOTV))
        ENDIF
    530 CONTINUE
C Transform local nodal displacements back to global values for
C prescribed displacements at an angle (for 2-D only)
    DO 370 IPOIN=1,NPOIN
        ISVAB=(IPOIN-1)*NDOFN
        DO 360 IVFIX=1,NVFIX
            IF(NOFIX(IVFIX).EQ.IPOIN.AND.ANGLE(IVFIX).NE.R0)THEN
                C=COS(ANGLE(IVFIX))
                S=SIN(ANGLE(IVFIX))
                ISVAB=ISVAB+1

```

```

JSVAB=ISVAB+1
IF (MODE.EQ.1) THEN
  GASHI= C*DITER ( ISVAB )-S*DITER (JSVAB)
  GASHJ= S*DITER ( ISVAB )+C*DITER (JSVAB)
  DITER ( ISVAB )=GASHI
  DITER (JSVAB )=GASHJ
ELSE IF (MODE.EQ.2) THEN
  GASHI= C*DTANG ( ISVAB )-S*DTANG (JSVAB)
  GASHJ= S*DTANG ( ISVAB )+C*DTANG (JSVAB)
  DTANG ( ISVAB )=GASHI
  DTANG (JSVAB )=GASHJ
ELSE IF (MODE.EQ.3) THEN
  GASHI= C*DTANG ( ISVAB )-S*DTANG (JSVAB)
  GASHJ= S*DTANG ( ISVAB )+C*DTANG (JSVAB)
  DTANG ( ISVAB )=GASHI
  DTANG (JSVAB )=GASHJ
  GASHI= C*DITER ( ISVAB )-S*DITER (JSVAB)
  GASHJ= S*DITER ( ISVAB )+C*DITER (JSVAB)
  DITER ( ISVAB )=GASHI
  DITER (JSVAB )=GASHJ
ENDIF
GOTO 370
ENDIF
360 CONTINUE
370 CONTINUE
900 CONTINUE
RETURN
END

```



```

SUBROUTINE GAUS1D
1(   NGAUS   ,POSGP   ,WEIGP   )
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
  DIMENSION
1   POSGP(*)   ,WEIGP(*)
C*****
C SET SAMPLING POINTS POSITIONS AND WEIGHTS FOR GAUSSIAN NUMERICAL
C INTEGRATION RULES IN 1-D (INTEGRATION OVER LIMITS [-1,1]).
C
C REFERENCE: Expression (4.36)
C           OC Zienkiewicz & RL Taylor. The finite element method,
C           Volume 1: The basis. 5th Edn. Butterworth Heinemann, 2000.
C           J Fish & T Belytschko. A first course in finite element
C           analysis. Wiley, Chichester, 2007.
C*****
  IF(NGAUS.EQ.1)THEN
    POSGP(1)=0.0D0
    WEIGP(1)=2.0D0
  ELSEIF(NGAUS.EQ.2)THEN
    POSGP(1)=-0.577350269189626D0
    WEIGP(1)=1.0D0
    POSGP(2)=+0.577350269189626D0
    WEIGP(2)=1.0D0
  ELSEIF(NGAUS.EQ.3)THEN
    POSGP(1)=-0.774596669241483D0
    WEIGP(1)=0.5555555555555556D0
    POSGP(2)=+0.0D0
    WEIGP(2)=0.8888888888888889D0
    POSGP(3)=+0.774596669241483D0
    WEIGP(3)=0.5555555555555556D0
  ELSEIF(NGAUS.EQ.4)THEN
    POSGP(1)=-0.861136311594053D0
    WEIGP(1)=0.347854845137454D0
    POSGP(2)=-0.339981043584856D0
    WEIGP(2)=0.652145154862546D0
    POSGP(3)=+0.339981043584856D0
    WEIGP(3)=0.652145154862546D0
    POSGP(4)=+0.861136311594053D0
    WEIGP(4)=0.347854845137454D0
  ELSE
    CALL ERRPR('EI0004')
  ENDIF
C
  RETURN
END

```

```

SUBROUTINE GAUS2D
1( DOMAIN ,NGAUS ,POSGP ,WEIGP )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
CHARACTER*3 DOMAIN
DIMENSION
1 POSGP(2,*),WEIGP(*)
C*****
C SET SAMPLING POINTS POSITIONS AND WEIGHTS FOR GAUSSIAN NUMERICAL
C INTEGRATION RULES IN 2-D
C
C REFERENCE: Expression (4.31)
C OC Zienkiewicz & RL Taylor. The finite element method,
C Volume 1: The basis. 5th Edn. Butterworth Heinemann, 2000.
C J Fish & T Belytschko. A first course in finite element
C analysis. Wiley, Chichester, 2007.
C*****
IF(DOMAIN.EQ.'QUA')THEN
C
C Integration over quadrilateral domain with vertices
C { (1,1), (1,-1), (-1,-1), (-1,1) }
C
IF(NGAUS.EQ.1)THEN
POSGP(1,1)=0.0D0
POSGP(2,1)=0.0D0
WEIGP(1)=4.0D0
ELSEIF(NGAUS.EQ.4)THEN
POSGP(1,1)=-0.577350269189626D0
POSGP(2,1)=-0.577350269189626D0
WEIGP(1)=1.0D0
POSGP(1,2)=-0.577350269189626D0
POSGP(2,2)=+0.577350269189626D0
WEIGP(2)=1.0D0
POSGP(1,3)=+0.577350269189626D0
POSGP(2,3)=-0.577350269189626D0
WEIGP(3)=1.0D0
POSGP(1,4)=+0.577350269189626D0
POSGP(2,4)=+0.577350269189626D0
WEIGP(4)=1.0D0
ELSEIF(NGAUS.EQ.5)THEN
POSGP(1,1)=-0.774596669241483D0
POSGP(2,1)=-0.774596669241483D0
WEIGP(1)=0.5555555555555556D0
POSGP(1,2)=-0.774596669241483D0
POSGP(2,2)=+0.774596669241483D0
WEIGP(2)=0.5555555555555556D0
POSGP(1,3)=+0.774596669241483D0
POSGP(2,3)=-0.774596669241483D0
WEIGP(3)=0.5555555555555556D0
POSGP(1,4)=+0.774596669241483D0
POSGP(2,4)=+0.774596669241483D0
WEIGP(4)=0.5555555555555556D0
POSGP(1,5)=+0.0D0
POSGP(2,5)=+0.0D0
WEIGP(5)=1.777777777777778D0
ELSEIF(NGAUS.EQ.9)THEN
POSGP(1,1)=-0.774596669241483D0
POSGP(2,1)=-0.774596669241483D0
WEIGP(1)=0.308641975308643D0
POSGP(1,2)=-0.774596669241483D0
POSGP(2,2)=+0.0D0
WEIGP(2)=0.493827160493828D0
POSGP(1,3)=-0.774596669241483D0
POSGP(2,3)=+0.774596669241483D0
WEIGP(3)=0.308641975308643D0
POSGP(1,4)=+0.0D0
POSGP(2,4)=-0.774596669241483D0
WEIGP(4)=0.493827160493828D0
POSGP(1,5)=+0.0D0
POSGP(2,5)=+0.0D0
WEIGP(5)=0.790123456790124D0
POSGP(1,6)=+0.0D0
POSGP(2,6)=+0.774596669241483D0
WEIGP(6)=0.493827160493828D0
POSGP(1,7)=+0.774596669241483D0
POSGP(2,7)=-0.774596669241483D0
WEIGP(7)=0.308641975308643D0
POSGP(1,8)=+0.774596669241483D0
POSGP(2,8)=+0.0D0
WEIGP(8)=0.493827160493828D0
POSGP(1,9)=+0.774596669241483D0
POSGP(2,9)=+0.774596669241483D0
WEIGP(9)=0.308641975308643D0
ELSE
CALL ERRPRT('EI0001')
ENDIF
ELSEIF(DOMAIN.EQ.'TRI')THEN
C
C Integration over triangular domain with vertices { (0,0), (1,0), (0,1) }
C
IF(NGAUS.EQ.1)THEN
POSGP(1,1)=0.333333333333333D0
POSGP(2,1)=0.333333333333333D0
WEIGP(1)=0.5D0
ELSEIF(NGAUS.EQ.3)THEN
POSGP(1,1)=0.166666666666667D0
POSGP(2,1)=0.166666666666667D0
WEIGP(1)=0.166666666666667D0
POSGP(1,2)=0.666666666666667D0

```

```
        POSGP(2,2)=0.166666666666667D0
        WEIGP(2)=0.166666666666667D0
        POSGP(1,3)=0.166666666666667D0
        POSGP(2,3)=0.666666666666667D0
        WEIGP(3)=0.166666666666667D0
    ELSE
        CALL ERRPRT('EI0002')
    ENDIF
ELSE
    CALL ERRPRT('EI0003')
ENDIF

RETURN
END
```

C

```

      SUBROUTINE GETBMX
1(   BMATX      ,CARTCO      ,CARTD      ,NDIME      ,MBDIM      ,
2   NAXIS      ,NNODE       ,NTYPE      ,SHAPE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1   BMATX(MBDIM,*)      ,CARTCO(NDIME)      ,CARTD(NDIME,*)      ,
2   SHAPE(*)
      DATA R0/0.0D0/
C*****
C EVALUATES THE DISCRETE SYMMETRIC GRADIENT OPERATOR 'B' (SMALL
C STRAIN-DISPLACEMENT MATRIX) FOR PLANE STRESS/STRAIN AND AXISYMMETRIC
C PROBLEMS
C
C REFERENCE: Expression (4.30)
C*****
C Plane strain/stress
C -----
      IY=0
      DO 10 INODE=1,NNODE
          IX=IY+1
          IY=IX+1
          BMATX(1,IX)=CARTD(1,INODE)
          BMATX(1,IY)=R0
          BMATX(2,IX)=R0
          BMATX(2,IY)=CARTD(2,INODE)
          BMATX(3,IX)=CARTD(2,INODE)
          BMATX(3,IY)=CARTD(1,INODE)
      10 CONTINUE
      IF(NTYPE.EQ.3)THEN
C Axisymmetric problem
C -----
          IY=0
          DO 20 INODE=1,NNODE
              IX=IY+1
              IY=IX+1
              IF(NAXIS.EQ.1)THEN
C Axisymmetric about Y axis
                  BMATX(4,IX)=SHAPE(INODE)/CARTCO(NAXIS)
                  BMATX(4,IY)=R0
              ELSE IF(NAXIS.EQ.2)THEN
C Axisymmetric about X axis
                  BMATX(4,IX)=R0
                  BMATX(4,IY)=SHAPE(INODE)/CARTCO(NAXIS)
              ENDIF
          20 CONTINUE
      ENDIF
C
      RETURN
      END

```

```

      SUBROUTINE GETGCO
      1(   CARTCO   ,ELCOD   ,MDIME   ,NDIME   ,NNODE   ,
      2   SHAPE    )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
      1   CARTCO(NDIME)   ,ELCOD(MDIME,NNODE) ,SHAPE(NNODE)
      DATA R0/0.0D0/
C*****
C EVALUATES THE GLOBAL CARTESIAN COORDINATES OF A POINT WITHIN AN
C ELEMENT BY INTERPOLATION OF THE ELEMENT NODAL COORDINATES
C
C REFERENCE: Expressions (4.39-40)
C*****
      DO 20 IDIME=1,NDIME
        CARTCO(IDIME)=R0
        DO 10 INODE=1,NNODE
          CARTCO(IDIME)=CARTCO(IDIME)+ELCOD(IDIME,INODE)*SHAPE(INODE)
      10  CONTINUE
      20 CONTINUE
C
      RETURN
      END

```

```

      SUBROUTINE GETGMX
1(   CARTCO      ,CARTD      ,GMATX      ,MDIME      ,MGDIM      ,
2   NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1   CARTCO(MDIME)      ,CARTD(MDIME,*)      ,GMATX(MGDIM,*)      ,
2   SHAPE(*)
      DATA R0/0.0D0/
C*****
C EVALUATES THE DISCRETE (FULL) GRADIENT OPERATOR 'G' FOR PLANE
C STRESS/STRAIN AND AXISYMMETRIC PROBLEMS. COMPONENT ORDERING
C (11,21,12,22,33).
C
C REFERENCE: Expression (4.97)
C*****
C Plane strain/stress
C -----
      IY=0
      DO 10 INODE=1,NNODE
          IX=IY+1
          IY=IX+1
          GMATX(1,IX)=CARTD(1,INODE)
          GMATX(1,IY)=R0
          GMATX(2,IX)=R0
          GMATX(2,IY)=CARTD(1,INODE)
          GMATX(3,IX)=CARTD(2,INODE)
          GMATX(3,IY)=R0
          GMATX(4,IX)=R0
          GMATX(4,IY)=CARTD(2,INODE)
10  CONTINUE
      IF(NTYPE.EQ.3)THEN
C Axisymmetric problem
C -----
          IY=0
          DO 20 INODE=1,NNODE
              IX=IY+1
              IY=IX+1
              IF(NAXIS.EQ.1)THEN
C Axisymmetric about Y axis
                  GMATX(5,IX)=SHAPE(INODE)/CARTCO(NAXIS)
                  GMATX(5,IY)=R0
              ELSE IF(NAXIS.EQ.2)THEN
C Axisymmetric about X axis
                  GMATX(5,IX)=R0
                  GMATX(5,IY)=SHAPE(INODE)/CARTCO(NAXIS)
              ENDIF
20  CONTINUE
          ENDIF
C
      RETURN
      END

```

```

SUBROUTINE GREET
1000 FORMAT(/////////////////,
1' _____',
2' _____',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
5' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
6' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
7' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
8' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
9' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
0' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
1' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
2' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
5' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
6' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
7' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
8' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|)
1010 FORMAT(
1' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
2' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
5' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
6' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
7' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
8' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
9' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
0' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
1' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
2' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|)
1020 FORMAT(
1' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
2' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
5' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
6' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
7' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
8' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
9' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
0' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
1' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
2' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
3' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|',
4' |_|_|_|_|_|_|_|_|_|_|_|_|_|_|)
WRITE(*,1000)
WRITE(*,1010)
WRITE(*,1020)
RETURN
END

```

```

*****
H Y P L A S      version 2.0

Program for implicit small and large strain
finite element analysis of hyperelastic and
elastoplastic solids.

Copyright (c) 1996-2008  EA de Souza Neto, D Peric & DRJ Owen
                          Civil and Computational Eng. Centre
                          School of Engineering
                          Swansea University

This program is a companion to the textbook:
EA de Souza Neto, D Peric & DRJ Owen. Computational
Methods for Plasticity: Theory and Applications. Wiley,
Chichester, 2008.

Please send BUG REPORTS to

                          hyplas_v2.0@live.co.uk

NOTE: Messages sent to the authors' personal email addresses
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*****

```

```

*****
C-----*
C
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C      in part) these conditions of use.
C-----*
*****

```

```

*****
C
C
C      PROGRAM HYPLAS
C
C      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C
C Hyplas database: Global parameters and common blocks
C      INCLUDE 'MAXDIM.INC'
C      INCLUDE 'MATERIAL.INC'
C      INCLUDE 'ELEMENTS.INC'
C      INCLUDE 'GLDBBASE.INC'
C Common block of arrays used only by the frontal solver
C      COMMON / FRONTA /
C      1      EQRHS(MTOTV,2)          ,EQROW(MFRON,MTOTV)  ,EQCOL(MFRON,MTOTV)  ,
C      2      DECAY(MFRON)             ,GLOAD(MFRON,2)      ,VECRV(MFRON,2)      ,
C      3      LOCEL(MEVAB,MELEM)        ,NACVA(MFRON,MELEM)  ,NAMEV(MTOTV)      ,
C      4      NDEST(MEVAB,MELEM)        ,NPIVO(MTOTV)       ,NFRON(MELEM)
C Logical control flags for main program
C      LOGICAL
C      1      CONVRG      ,DIVERG      ,INCCUT      ,RSTRT      ,UNSYM
C File names
C      CHARACTER*256
C      1      DATFIL      ,RESFIL      ,RSTINP      ,RSTOUT

```



```

C Increment control arrays for main program
  DIMENSION
  1 DFACTV(MINCS) ,DFSUB(MSUBIN) ,MITERV(MINCS) ,
  2 NOUTP(5) ,NOUTPV(5,MINCS) ,TOLERV(MINCS)
C Numerical constants
  PARAMETER
  1( R0=0.0D0 ,RP5=0.5D0 ,RP7=0.7D0 )
C*****
C
1000 FORMAT(/20X,' H Y P L A S ANALYSIS RESULTS' /
1
20X,'=====')
1010 FORMAT(
1 7X,' '
2 7X,' '
3 7X,' '
4 7X,' '
5 7X,' '
6 7X,' '
7 7X,' '
8 7X,' '
9 7X,' '
0 7X,' '
1 7X,' '
2 7X,' '
3 7X,' '
4
)


|                                                   |          |        |
|---------------------------------------------------|----------|--------|
| Program compiled with the dimensioning parameters |          |        |
| Maximum number of elements                        | (MELEM)  | ',I6,' |
| Maximum frontwidth allowed in solution            | (MFRON)  | ',I6,' |
| Maximum number of element groups                  | (MGRUP)  | ',I6,' |
| Maximum number of load increments                 | (MINCS)  | ',I6,' |
| Maximum number of nodal points                    | (MPOIN)  | ',I6,' |
| Size of increment cutting stack array             | (MSUBIN) | ',I6,' |
| Max. number of nodes with prescr.displ.           | (MVFIX)  | ',I6,' |


1015 FORMAT(/,' Data file name:' /
1
' =====' /,1X,A/)
1020 FORMAT(////15X,'Reading data...')
1030 FORMAT(////15X,' H Y P L A S ANALYSIS starting...')
1050 FORMAT(////
1 ' INCREMENT NUMBER',I5,19X,'TOTAL LOAD FACTOR =' ,G15.6/
2 ' -----' ,
3 ' -----' /
4 4X,' ' ,13X,'relative residual',13X,'maximum residual' /
5 4X,'iteration',13X,' norm (%) ' ,13X,' norm ' /
6 ' -----' ,
7 ' -----')
1055 FORMAT(////
1 ' INCREMENT NUMBER',I5,19X,' ARC LENGTH =' ,G15.6/
2 ' -----' ,
3 ' -----' /
4 4X,' ' ,6X,'relative residual',4X,'maximum residual',
5 5X,' total' /
6 4X,'iteration',6X,' norm (%) ' ,4X,' norm ' ,
7 5X,'load factor' /
8 ' -----' ,
9 ' -----')
1060 FORMAT(
1 ' -----' ,
2 ' -----')
1063 FORMAT(34X,'INCREMENTAL LOAD FACTOR =' ,G15.6)
1065 FORMAT(30X,'CONVERGED TOTAL LOAD FACTOR =' ,G15.6)
1067 FORMAT(24X,'CONVERGED INCREMENTAL LOAD FACTOR =' ,G15.6)
1070 FORMAT(////15X,'Program H Y P L A S successfully completed.')
1080 FORMAT(////15X,'Data file name was ----> ',A)
1090 FORMAT(/ 15X,'Results file name is ----> ',A//)
1095 FORMAT( 15X,'Re-start file name is ----> ',A//
1
15X,'Last increment written -->',I5//)
1040 FORMAT(/ ' Iterations not converged.')
1100 FORMAT(/ ' Iterations diverging.')
1110 FORMAT(/ ' Re-trying with reduced increment size...')
1120 FORMAT(/ ' Re-trying with reduced arc length...')
C
C
C
C Start up. Read data, initialise variables, etc...
C
C REFERENCE: Flowchart of Figure 5.1
C
C *****
C
C Send greeting message to standard output
  CALL GREET
C Read names and open relevant files
  CALL FOPEN( DATFIL ,RESFIL ,RSTOUT )
C Echo dimensioning parameters defined in file MAXDIM.INC
  WRITE(16,1000)
  WRITE(16,1010)MELEM,MFRON,MGRUP,MINCS,MPOIN,MSUBIN,MVFIX
C Echo data file name
  I=INDEX(DATFIL,' ')-1
  WRITE(16,1015)DATFIL(1:I)
C
C Read relevant data from input data/re-start file
C -----
C Check if main data is to be read from the input data file or from an
C input re-start file
  CALL RSTCHK( RSTINP ,RSTRT )
  WRITE(*,1020)
C
  IF(RSTRT)THEN
C Re-start mode: Read main data from input re-start file
  CALL RSTART
  1( DFOLD ,DLENG ,DLENGO ,DLENM ,DLAMD ,
  2 IFNEG ,IINCS ,MXFRON ,NOUTP ,TFACT ,
  3 TFACTO ,UNSYM ,RSTINP ,RSTOUT ,0 ,
  4 IDUMMY )
  ELSE

```

```

C Not re-start mode: Read main data from input data file
C ...read most of the problem data
  CALL INDATA(MXFRON ,UNSYM)
C ...read and evaluate the applied external loads
  CALL INLOAD
  ENDIF
C
C For any mode: Read load incrementation data from input data file
  CALL ININCR
  1(   DFACT      ,DLENP      ,FSTOP      ,ITDES      ,MINCS      ,
  2   MITER       ,NALGO      ,NINCS      ,TOLER      ,
  3   DFACTV      ,MITERV     ,NOUTP      ,NOUTPV     ,TOLERV     )
C
C Initialise some variables and arrays if not in re-start mode
C -----
  INCRST=0
  IF(.NOT.RSTRT)THEN
    CALL INITIA
  1(   DLAMD      ,IFNEG      ,KUNLD      ,TFACT      )
  ENDIF
C
C
C
C Start incremental finite element analysis...
C *****
C
  WRITE(*,1030)
C
C=====
C
C          Start loop over load increments
C
C REFERENCE: Chapter 4 (Boxes 4.1-4) of the companion textbook.
C           Section 5.4.
C           The load incrementation loops carried out here are those
C           of the Flowcharts of Figures 5.2-3.
C=====
C
  IF(.NOT.RSTRT)IINCS=0
  DO 50 ICOUNT=1,NINCS
C
    IPSUB=1
    IF(NALGO.GT.0)THEN
      DFSUB(1)=DFACTV(ICOUNT)
      TOLER=TOLERV(ICOUNT)
      MITER=MITERV(ICOUNT)
      NOUTP(1)=NOUTPV(1,ICOUNT)
      NOUTP(2)=NOUTPV(2,ICOUNT)
      NOUTP(3)=NOUTPV(3,ICOUNT)
      NOUTP(4)=NOUTPV(4,ICOUNT)
      NOUTP(5)=NOUTPV(5,ICOUNT)
    ENDIF
C
C Reset converged problem variables
C -----
    CALL SWITCH( 1 )
C
  10  CONTINUE
C
C Update increment counter
C -----
    IINCS=IINCS+1
C
C For fixed increments option only: Increment external load according
C to user-prescribed incremental proportional load factor
C -----
    IF(NALGO.GT.0)THEN
      DFACT=DFSUB(IPSUB)
      CALL INCREM
  1(   IINCS      ,TFACT      ,TOLER      ,MITER      ,NOUTP      ,
  2   DFACT      ,DFOLD      ,KUNLD      )
  ENDIF
C
C=====
C
C          Start loop over equilibrium iterations
C=====
C
  DO 20 IITER=1,MITER
C
C Select solution algorithm variable KRESL
  CALL ALGOR(IINCS ,IITER ,KRESL ,KUNLD )
C
  IF(NALGO.LT.0)THEN
C Set up prescribed displacements for tangential solution for the
C arc-length method
  CALL TANGEN
  ENDIF
C
C Assemble stiffness matrix and solve for iterative displacements
C (tangential solution for the arc-length method) the linearised system
C of discretised equilibrium equations using the frontal algorithm
C -----
  CALL FRONT
  1(   IITER      ,KRESL      ,IFNEG      ,KUNLD      ,MXFRON      ,
  2   UNSYM      ,INCCUT      )

```

```

C
C      IF(INCCUT)THEN
C System solution failed due to zero pivot: break equilibrium iteration
C loop and activate increment cutting
C      GOTO 30
C    ENDIF

C
C For Arc-Length method only: Compute iterative displacement according
C to the arc-length constraint and update the incremental and total
C load factors
C -----
C      IF(NALGO.LT.0)THEN
C        CALL ARCLEN
C      1( DFACT ,DLAMD ,DLENG ,DLENM ,DLENP ,
C      2  IFNEG ,IINCS ,IITER ,INCCUT ,TFACT )
C
C      IF(INCCUT)THEN
C No real roots for arc-length constraint equation: break equilibrium
C iteration loop and activate increment cutting
C      GOTO 30
C    ENDIF
C  ENDIF

C
C Update incremental and total displacements. Also update nodal
C coordinates for large deformation analyses
C -----
C      CALL UPCONV

C
C Re-set converged load factors and print out increment information
C -----
C      IF(IITER.EQ.1)THEN
C        IF(IINCS.EQ.1)THEN
C Re-set previous converged load factors/arc-length
C        IF(NALGO.LT.0)DLENGO=DLENG
C        DFACTO=DFACT
C        TFACTO=R0
C      ENDIF
C      IF(NALGO.GT.0)THEN
C Fixed increments option: print current total load factor
C        WRITE(*,1050) IINCS,TFACT
C        WRITE(16,1050)IINCS,TFACT
C      ELSE
C Arc-length: print current arc-length
C        WRITE(*,1055) IINCS,DLENG
C        WRITE(16,1055)IINCS,DLENG
C      ENDIF
C    ENDIF

C
C Re-set relevant problem variables to last converged solution
C -----
C      CALL SWITCH( 2 )

C
C Update problem variables (stress and other state variables) and
C evaluate internal force vectors of all elements
C -----
C      CALL INTFOR( INCCUT )

C
C      IF(INCCUT)THEN
C Internal force calculation failed: break equilibrium iteration loop
C and activate load increment cutting
C      GOTO 30
C    ENDIF

C
C Assemble internal and external global force vectors, reactions,
C compute residual and check for convergence
C -----
C      CALL CONVER(CONVRG,DIVERG,IITER,TOLER,TFACT)

C
C      ITACT=IITER

C
C      IF(CONVRG)THEN
C Iterations have converged: break equilibrium iteration loop and go to
C next load increment
C      WRITE(*,1060)
C      WRITE(16,1060)
C      IF(NALGO.GT.0)THEN
C        WRITE(*,1063) DFACT
C        WRITE(16,1063)DFACT
C      ELSE
C        WRITE(*,1065) TFACT
C        WRITE(*,1067) DFACT
C        WRITE(16,1065)TFACT
C        WRITE(16,1067)DFACT
C      ENDIF
C      WRITE(*,1060)
C      WRITE(16,1060)
C      GOTO 40
C    ELSEIF(DIVERG)THEN
C Iterations are diverging: break equilibrium iteration loop and
C activate load increment cutting
C      WRITE(16,1100)
C      WRITE(*,1100)
C      GOTO 30
C    ENDIF

C
C 20 CONTINUE
C

```

[illegible]

```
C=====
C
C   60 CONTINUE
C
C
C
C Exit HYPLAS
C *****
C
C Close files before exit
C   CALL FCLOSE
C Echo file names back to standard output and stop
C   WRITE(*,1070)
C   I=INDEX(RESFIL,' ')-1
C   WRITE(*,1080)DATFIL(1:I)
C   WRITE(*,1090)RESFIL(1:I)
C   IF(INCRST.NE.0)THEN
C     WRITE(*,1095)RSTOUT(1:I),INCRST
C   ENDIF
C   STOP ' '
C   END
```

```

SUBROUTINE IFFBA2
1( IELEM ,INCCUT ,MDIME ,MELEM ,MPOIN ,
2 MSTRE ,MTOTV ,NAXIS ,NTYPE ,
3 COORD1 ,DINCR ,ELOAD ,IELPRP ,IPROPS ,
4 LALGVA ,LNODS ,RALGVA ,RELPRP ,RPROPS ,
5 RSTAVA ,STRSG ,THKGP ,TDISP )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
INCLUDE '../ELEMENTS.INC'
INCLUDE '../MATERIAL.INC'

C
PARAMETER( MGDIM=5 ,MBDIM=4 ,NDIME=2 ,NDOFN=2 )
C Arguments
LOGICAL INCCUT ,LALGVA
DIMENSION
1 COORD1(MDIME,MPOIN) ,DINCR(MTOTV) ,ELOAD(MEVAB) ,
2 IELPRP(*) ,IPROPS(*) ,LALGVA(MLALGV,MTOTG) ,
3 LNODS(MELEM,MEVAB) ,RALGVA(MRALGV,MTOTG) ,RELPRP(*) ,
4 RPROPS(*) ,RSTAVA(MRSTAV,MTOTG) ,STRSG(MSTRE,MTOTG) ,
5 THKGP(MTOTG) ,TDISP(MTOTV)
C Local variables and arrays
LOGICAL SUFAIL
DIMENSION
1 BMATX(MBDIM,MEVAB) ,CARTD(NDIME,MNODE) ,DELDIS(MDOFN,MNODE) ,
2 DERIV(NDIME,MNODE) ,EINCR(MBDIM) ,ELCOD(NDIME,MNODE) ,
3 FINCIN(3,3) ,FINCR(3,3) ,FINV(3,3) ,
4 GMATX(MGDIM,MEVAB) ,GPCOD(NDIME) ,SHAPE(MNODE) ,
5 TELDIS(MDOFN,MNODE)
C Local numerical constants
DATA
1 R0 ,RP5 ,R1 ,R3 ,R8 /
2 0.0D0,0.5D0,1.0D0,3.0D0,8.0D0/
C*****
C COMPUTE INTERNAL FORCE VECTOR OF ALL ELEMENTS OF CLASS 'FBAR'
C (F-Bar ELEMENTS) IN 2-D: PLANE STRAIN AND AXISYMMETRIC
C
C REFERENCE: Box 15.1
C*****
R1D3=R1/R3
IF(NTYPE.EQ.2)THEN
NBDIM=3
ELSEIF(NTYPE.EQ.3)THEN
TWOPI=R8*ATAN(R1)
NBDIM=4
ELSE
C F-bar implementation valid only for plane strain and axisymmetric
CALL ERRPR('EI0033')
ENDIF
C Identify element type
IELTYP=IELPRP(1)
C retrieve some element integer properties
NNODE =IELPRP(3)
NGAUSP=IELPRP(4)
NEVAB =IELPRP(5)

C
C Set element arrays of current nodal coordinates, total and incremental
C displacements
DO 20 INODE =1,NNODE
LNODE=IABS(LNODS(IELEM,INODE))
NPOSN=(LNODE-1)*NDOFN
DO 10 IDOFN=1,NDOFN
NPOSN=NPOSN+1
ELCOD(IDOFN,INODE)=COORD1(IDOFN,LNODE)
TELDIS(IDOFN,INODE)=-TDISP(NPOSN)
DELDIS(IDOFN,INODE)=-DINCR(NPOSN)
10 CONTINUE
20 CONTINUE

C
C Initialize element force vector
C
CALL RVZERO(ELOAD,NEVAB)

C-----
C Calculation of the F-bar deformation gradient determinat
C-----
C Evaluate inverse of the incremental deformation gradient at the
C centroid of the F-bar element
NGAUSB=IELPRP(8)
IPOS =NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+2*NGAUSB+1
EXISC =RELPRP(IPOS)
ETASC =RELPRP(IPOS+1)

C
CALL SHPFUN
1( DERIV ,ETASC ,EXISC ,0 ,IELTYP ,
2 NDIME ,SHAPE )
CALL JACOB2
1( CARTD ,DERIV ,DETJAC ,ELCOD ,IELEM ,
2 NDIME ,NDIME ,NNODE )
IF(DETJAC.LE.R0)THEN
C cut increment if element jacobian is not positive definite
CALL ERRPR('WE0021')
INCCUT=.TRUE.
GOTO 999
ENDIF
IF(NTYPE.EQ.3)CALL GETGCO
1( GPCOD ,ELCOD ,NDIME ,NDIME ,NNODE ,
2 SHAPE )
C

```

```

      CALL GETGMX
      1( GPCOD      ,CARTD      ,GMATX      ,NDIME      ,MGDIM      ,
      2  NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C Determinant of the incremental deformation gradient at the centroid
      CALL DEFGRA
      1( DELDIS      ,FINCIN      ,GMATX      ,MDOFN      ,MGDIM      ,
      2  NDOFN      ,NTYPE      ,NNODE      )
      IF(NTYPE.EQ.2)THEN
        AFACT=RP5
        DET=FINCIN(1,1)*FINCIN(2,2)-FINCIN(1,2)*FINCIN(2,1)
      ELSEIF(NTYPE.EQ.3)THEN
C... cut increment if incr. def. gradient is not positive definite
        IF(FINCIN(3,3).LE.R0)THEN
          CALL ERRPRT('WE0022')
          INCCUT=.TRUE.
          GOTO 999
        ENDIF
        AFACT=R1D3
        DET=(FINCIN(1,1)*FINCIN(2,2)-FINCIN(1,2)*FINCIN(2,1))*
      1 FINCIN(3,3)
      ENDIF
      DET0=R1/DET
C Determinant of the total deformation gradient at the centroid
      CALL DEFGRA
      1( TELDIS      ,FINV      ,GMATX      ,MDOFN      ,MGDIM      ,
      2  NDOFN      ,NTYPE      ,NNODE      )
      IF(NTYPE.EQ.2)THEN
        DET=FINV(1,1)*FINV(2,2)-FINV(1,2)*FINV(2,1)
      ELSEIF(NTYPE.EQ.3)THEN
C... cut increment if deformation gradient is not positive definite
        IF(FINV(3,3).LE.R0)THEN
          CALL ERRPRT('WE0023')
          INCCUT=.TRUE.
          GOTO 999
        ENDIF
        DET=(FINV(1,1)*FINV(2,2)-FINV(1,2)*FINV(2,1))*FINV(3,3)
      ENDIF
      DETF0=R1/DET
C-----
C
C=====
C          Begin loop over Gauss points
C=====
C
      IPPOS=1
      IPWEI=NGAUSP*NDIME+1
      DO 40 IGAUSP=1,NGAUSP
C Set Gauss points positions and weights
        EXISP=RELPRP(IPPOS-1+IGAUSP*2-1)
        ETASP=RELPRP(IPPOS-1+IGAUSP*2)
        WEIGP=RELPRP(IPWEI-1+IGAUSP)
C Evaluate shape functions and their derivatives (use current
C configuration for large strains)
        CALL SHPFUN
        1( DERIV      ,ETASP      ,EXISP      ,0          ,IELTYP      ,
        2  NDIME      ,SHAPE      )
        CALL JACOB2
        1( CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
        2  NDIME      ,NDIME      ,NNODE      )
        IF(DETJAC.LE.R0)THEN
C ...cut increment if current jacobian is not positive definite
          CALL ERRPRT('WE0024')
          INCCUT=.TRUE.
          GOTO 999
        ENDIF
        IF(NTYPE.EQ.3)CALL GETGCO
        1( GPCOD      ,ELCOD      ,NDIME      ,NDIME      ,NNODE      ,
        2  SHAPE      )
C Evaluate symmetric gradient operator B
        CALL GETBMX
        1( BMATX      ,GPCOD      ,CARTD      ,NDIME      ,NBDIM      ,
        2  NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C
C Compute basic kinematic variables needed for state update
C=====
C
C Large strains: compute incremental deformation gradient
C-----
C gradient operator G in current configuration
        CALL GETGMX
        1( GPCOD      ,CARTD      ,GMATX      ,NDIME      ,MGDIM      ,
        2  NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C incremental deformation gradient
        CALL DEFGRA
        1( DELDIS      ,FINCIN      ,GMATX      ,MDOFN      ,MGDIM      ,
        2  NDOFN      ,NTYPE      ,NNODE      )
        IF(NTYPE.EQ.3.AND.FINCIN(3,3).LE.R0)THEN
C ...cut increment if determinant of incr. def. gradient non positive
          CALL ERRPRT('WE0025')
          INCCUT=.TRUE.
          GOTO 999
        ENDIF
        CALL INV2
        1( FINCIN      ,FINCR      ,NTYPE      )
C modified incremental deformation gradient for F-bar element
        IF(NTYPE.EQ.2)THEN
          DET=FINCR(1,1)*FINCR(2,2)-FINCR(1,2)*FINCR(2,1)
        ELSEIF(NTYPE.EQ.3)THEN

```

```

      DET=(FINCR(1,1)*FINCR(2,2)-FINCR(1,2)*FINCR(2,1))*
1      FINCR(3,3)
      ENDIF
      FACTOR=(DET0/DET)**AFACT
      FINCR(1,1)=FACTOR*FINCR(1,1)
      FINCR(1,2)=FACTOR*FINCR(1,2)
      FINCR(2,1)=FACTOR*FINCR(2,1)
      FINCR(2,2)=FACTOR*FINCR(2,2)
      IF(NTYPE.EQ.3)FINCR(3,3)=FACTOR*FINCR(3,3)
C... determinant of total deformation gradient
      DETF=DETF0
C
C Call material interface routine for state update calls: Update stress
C and other state variables
C =====
C
      NLARGE=1
      CALL MATISU
1(      DETF      ,NLARGE      ,NTYPE      ,SUFAIL      ,
2      THKGP(IGAUSP)      ,EINCR      ,FINCR      ,IPROPS      ,
3      LALGVA(1,IGAUSP)      ,RALGVA(1,IGAUSP)      ,RPROPS      ,
4      RSTAVA(1,IGAUSP)      ,STRSG(1,IGAUSP)      )
      IF(SUFAIL)THEN
C State updating failed for current Gauss point: break loop over Gauss
C points and exit with increment cutting flag activated
      INCCUT=.TRUE.
      GOTO 999
      ENDIF
C
C Add current Gauss point contribution to the element internal force
C vector
C =====
C
C evaluate elemental volume
      DVOLU=DETJAC*WEIGP
      IF(NTYPE.EQ.3)THEN
        DVOLU=DVOLU*TWOPI*GPCOD(NAXIS)
      ENDIF
C
C add current gauss point B [sigma]
      CALL RTV
1(      0      ,NBDIM      ,NEVAB      ,NBDIM      ,ELOAD      ,
2      BMATX      ,STRSG(1,IGAUSP)      ,DVOLU      )
C
40 CONTINUE
C
C=====
C      End of loop over Gauss points
C=====
C
999 CONTINUE
      RETURN
      END

```



```

      SUBROUTINE IFSTD2
1(   IELEM      ,INCCUT      ,MDIME      ,MELEM      ,MPOIN      ,
2   MSTRE      ,MTOTV      ,NAXIS      ,NLARGE      ,NTYPE      ,
3   COORD1      ,DINCR      ,ELOAD      ,IELPRP      ,IPROPS      ,
4   LALGVA      ,LNODS      ,RALGVA      ,RELPRP      ,RPROPS      ,
5   RSTAVA      ,STRSG      ,THKGP      ,TDISP      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../MATERIAL.INC'

C
      PARAMETER( MGDIM=5 ,MBDIM=4 ,NDIME=2 ,NDOFN=2 )
C Arguments
      LOGICAL INCCUT ,LALGVA
      DIMENSION
1   COORD1(MDIME,MPOIN) ,DINCR(MTOTV)      ,ELOAD(MEVAB)      ,
2   IELPRP(*)      ,IPROPS(*)      ,LALGVA(MLALGV,MTOTG) ,
3   LNODS(MELEM,MEVAB) ,RALGVA(MRALGV,MTOTG) ,RELPRP(*)      ,
4   RPROPS(*)      ,RSTAVA(MRSTAV,MTOTG) ,STRSG(MSTRE,MTOTG) ,
5   THKGP(MTOTG)      ,TDISP(MTOTV)
C Local variables and arrays
      LOGICAL SUFAIL
      DIMENSION
1   BMATX(MBDIM,MEVAB) ,CARTD(NDIME,MNODE) ,DELDIS(MDOFN,MNODE) ,
2   DERIV(NDIME,MNODE) ,EINCR(MBDIM)      ,ELCOD(NDIME,MNODE) ,
3   FINCIN(3,3)      ,FINCR(3,3)      ,FINV(3,3)      ,
4   GMATX(MGDIM,MEVAB) ,GPCOD(NDIME)      ,SHAPE(MNODE)      ,
5   TELDIS(MDOFN,MNODE)
C Local numerical constants
      DATA
1   R0 ,R1 ,R8 /
2   0.0D0,1.0D0,8.0D0/
C*****
C COMPUTE INTERNAL FORCE VECTOR OF ALL ELEMENTS OF CLASS 'STDARD'
C (STANDARD ISOPARAMETRIC ELEMENTS) IN 2-D: PLANE STRAIN, PLANE STRESS
C AND AXISYMMETRIC
C
C REFERENCE: Section 4.1.2
C           Box 4.2, item (viii)
C*****
      IF(NTYPE.EQ.1)THEN
        NBDIM=3
      ELSEIF(NTYPE.EQ.2)THEN
        NBDIM=3
      ELSEIF(NTYPE.EQ.3)THEN
        TWOPI=R8*ATAN(R1)
        NBDIM=4
      ELSE
        CALL ERRPR('EI0012')
      ENDIF
C Identify element type
      IELTYP=IELPRP(1)
C retrieve some element integer properties
      NNODE =IELPRP(3)
      NGAUSP=IELPRP(4)
      NEVAB =IELPRP(5)

C
C Set element arrays of current nodal coordinates, total and incremental
C displacements
      DO 20 INODE =1,NNODE
        LNODE=IABS(LNODS(IELEM,INODE))
        NPOSN=(LNODE-1)*NDOFN
        DO 10 IDOFN=1,NDOFN
          NPOSN=NPOSN+1
          IF(NLARGE.EQ.1)THEN
            ELCOD(IDOFN,INODE)=COORD1(IDOFN,LNODE)
            TELDIS(IDOFN,INODE)=-TDISP(NPOSN)
            DELDIS(IDOFN,INODE)=-DINCR(NPOSN)
          ELSE
            ELCOD(IDOFN,INODE)=COORD1(IDOFN,LNODE)
            DELDIS(IDOFN,INODE)=DINCR(NPOSN)
          ENDIF
10      CONTINUE
20      CONTINUE

C
C Initialize element force vector
C
      CALL RVZERO(ELOAD,NEVAB)

C=====
C           Begin loop over Gauss points
C=====
C
      IPPOS=1
      IPWEI=NGAUSP*NDIME+1
      DO 40 IGAUSP=1,NGAUSP
C Set Gauss points positions and weights
      EXISP=RELPRP(IPPOS-1+IGAUSP*2-1)
      ETASP=RELPRP(IPPOS-1+IGAUSP*2)
      WEIGP=RELPRP(IPWEI-1+IGAUSP)
C Evaluate shape functions and their derivatives (use current
C configuration for large strains)
      CALL SHPFUN
1(   DERIV      ,ETASP      ,EXISP      ,0      ,IELTYP      ,
2   NDIME      ,SHAPE      )
      CALL JACOB2
1(   CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
2   NDIME      ,NDIME      ,NNODE      )

```

```

      IF(DETJAC.LE.R0)THEN
C ...cut increment if current jacobian is not positive definite
      CALL ERRPRT('WE0009')
      INCCUT=.TRUE.
      GOTO 999
    ENDIF
    IF(NTYPE.EQ.3)CALL GETGCO
  1(   GPCOD      ,ELCOD      ,NDIME      ,NDIME      ,NNODE      ,
  2     SHAPE      )
C Evaluate symmetric gradient operator B
  CALL GETBMX
  1(   BMATX      ,GPCOD      ,CARTD      ,NDIME      ,NBDIM      ,
  2     NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C
C Compute basic kinematic variables needed for state update
C =====
C
      IF(NLARGE.EQ.1)THEN
C Large strains: compute incremental deformation gradient
C -----
C gradient operator G in current configuration
      CALL GETGMX
  1(   GPCOD      ,CARTD      ,GMATX      ,NDIME      ,MGDIM      ,
  2     NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C incremental deformation gradient
      CALL DEFGRA
  1(   DELDIS      ,FINCIN      ,GMATX      ,MDOFN      ,MGDIM      ,
  2     NDOFN      ,NTYPE      ,NNODE      )
      IF(NTYPE.EQ.3.AND.FINCIN(3,3).LE.R0)THEN
C ...cut increment if determinant of incr. def. gradient non positive
      CALL ERRPRT('WE0010')
      INCCUT=.TRUE.
      GOTO 999
    ENDIF
    CALL INV2
  1(   FINCIN      ,FINCR      ,NTYPE      )
C... compute determinant of total deformation gradient
      CALL DEFGRA
  1(   TELDIS      ,FINV      ,GMATX      ,MDOFN      ,MGDIM      ,
  2     NDOFN      ,NTYPE      ,NNODE      )
      DETFIN=FINV(1,1)*FINV(2,2)-FINV(1,2)*FINV(2,1)
      IF(NTYPE.EQ.3)THEN
        IF(FINV(3,3).LE.R0)THEN
C... cut increment if deformation gradient is not positive definite
          CALL ERRPRT('WE0010')
          INCCUT=.TRUE.
          GOTO 999
        ENDIF
        DETFIN=DETFIN*FINV(3,3)
      ENDIF
      DETF=R1/DETFIN
    ELSE
C Small strains: compute incremental infinitesimal strain
C -----
      CALL LISTRA
  1(   BMATX      ,DELDIS      ,MDOFN      ,NBDIM      ,NDOFN      ,
  2     NNODE      ,NTYPE      ,EINCR      )
    ENDIF
C
C Call material interface routine for state update calls: Update stress
C and other state variables
C =====
C
      CALL MATISU
  1(   DETF      ,NLARGE      ,NTYPE      ,SUFAIL      ,
  2     THKGP(IGAUSP)      ,EINCR      ,FINCR      ,IPROPS      ,
  3     LALGVA(1,IGAUSP)      ,RALGVA(1,IGAUSP)      ,RPROPS      ,
  4     RSTAVA(1,IGAUSP)      ,STRSG(1,IGAUSP)      )
      IF(SUFAIL)THEN
C State updating failed for current Gauss point: break loop over Gauss
C points and exit with increment cutting flag activated
      INCCUT=.TRUE.
      GOTO 999
    ENDIF
C
C Add current Gauss point contribution to the element internal force
C vector
C =====
C
C evaluate elemental volume
      DVOLU=DETJAC*WEIGP
      IF(NTYPE.EQ.1)THEN
        DVOLU=DVOLU*THKGP(IGAUSP)
      ELSEIF(NTYPE.EQ.3)THEN
        DVOLU=DVOLU*TWOPI*GPCOD(NAXIS)
      ENDIF
C
C add current gauss point B [sigma]
      CALL RTV
  1(   0      ,NBDIM      ,NEVAB      ,NBDIM      ,ELOAD      ,
  2     BMATX      ,STRSG(1,IGAUSP)      ,DVOLU      )
C
40 CONTINUE
C
C=====
C                               End of loop over Gauss points
C=====
C

```

999 CONTINUE
RETURN
END

```

      SUBROUTINE INCREM
      1( IINCS ,TFACT ,TOLER ,MITER ,
      2 NOUTP ,DFACT ,DFOLD ,KUNLD )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas global database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C Arguments
      DIMENSION NOUTP(5)
C Numerical constants
      DATA R0 ,RP01 /
      1 0.0D0,0.01D0/
C*****
C INCREMENTS THE APPLIED EXTERNAL LOAD, SETS GLOBAL UNLOADING FLAG AND
C OUTPUTS CURRENT INCREMENT PARAMETERS TO RESULTS FILE (FOR FIXED LOAD
C INCREMENTS OPTION)
C
C REFERENCE: Figure 5.2
C*****
1000 FORMAT(////' INCREMENT NUMBER',I5/
      1 ' =====')
1010 FORMAT(//' Total load factor ..... = ',G15.6/
      1 ' Incremental load factor ..... = ',G15.6/
      2 ' Convergence tolerance ..... = ',G15.6/
      3 ' Max. No. of iterations ..... = ',I5)
1020 FORMAT(//' Output control flags for results'/
      1 ' ( 0 - No, 1 - Yes )',/,
      2 ' Displacements..... = ',I3/
      3 ' Reactions..... = ',I3/
      4 ' State variables at gauss points.... = ',I3/
      5 ' State variables at nodes..... = ',I3/
      6 ' Output to re-start file..... = ',I3)
C
C Output current increment parameters to results file
C -----
      WRITE(16,1000)IINCS
C
      IF(TOLER.EQ.R0)TOLER=RP01
      TFACT=TFACT+DFACT
C
      WRITE(16,1010)TFACT,DFACT,TOLER,MITER
      WRITE(16,1020)(NOUTP(I),I=1,5)
C
C Increment forces
C -----
C New out-of-balance force := out-of-balance force at the end of the
C previous (converged) load increment + current external load increment
      DO 20 IELEM=1,NELEM
        IGRUP =IGRPID(IELEM)
        IELIDN=IELTID(IGRUP)
        NEVAB =IELPRP(5,IELIDN)
        DO 10 IEVAB=1,NEVAB
          ELOAD(IEVAB,IELEM)=ELOAD(IEVAB,IELEM)+RLOAD(IEVAB,IELEM)*DFACT
        10 CONTINUE
      20 CONTINUE
C
C Increment prescribed displacements
C -----
      DO 40 ITOTV=1,NTOTV
        DO 30 IRHS=1,2
          FIXED(ITOTV,IRHS)=R0
        30 CONTINUE
      40 CONTINUE
      DO 60 IVFIX=1,NVFIX
        NLOCA=(NOFIX(IVFIX)-1)*NDOFN
        DO 50 IDOFN=1,NDOFN
          NGASH=NLOCA+IDOFN
          FIXED(NGASH,1)=PRESC(IVFIX,IDOFN)*DFACT
        50 CONTINUE
      60 CONTINUE
C
C Set unloading (load reversal) global flag
C -----
      KUNLD=0
      IF(IINCS.GT.1)THEN
        IF((DFOLD*DFACT).LT.R0)KUNLD=1
      ENDIF
      DFOLD=DFACT
C
      RETURN
      END

```

```

SUBROUTINE INDATA(MXFRON ,UNSYM)
C
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C
C Hyplas database: Global parameters and common blocks
  INCLUDE '../MAXDIM.INC'
  INCLUDE '../MATERIAL.INC'
  INCLUDE '../ELEMENTS.INC'
  INCLUDE '../GLBDBASE.INC'
C Local array and variables
  LOGICAL CARTES ,CYLIND ,FOUND ,UNSYM ,UNSAUX
  CHARACTER*80 ELTNAM ,MATNAM
  CHARACTER*72 TITLE
  CHARACTER*80 SUBKEY ,INLINE
  DIMENSION
1    AUXCOR(MDIME) ,DERIV(MDIME,MNODE) ,ELTHK(MNODE) ,
2    IELCHK(MELEM) ,IETCHK(MGRUP) ,IGRCHK(MGRUP) ,
3    INDCHK(MPOIN) ,IWBEG(40) ,IWEND(40) ,
4    KSLAV(48) ,MATCHK(MGRUP) ,SHAPE(MNODE) ,
5    THKNOD(MPOIN)
C Numerical constants
  PARAMETER
1( R0=0.0D0 ,R1=1.0D0 ,R45=45.0D0 )
C*****
C READS MOST OF THE INPUT DATA
C
C REFERENCE: Section 5.3.2
C*****
1000 FORMAT('/' Title:'/' ====='/)
1010 FORMAT(A)
1015 FORMAT(1X,A)
1020 FORMAT(A80)
1030 FORMAT('/' Analysis description:'/' ====='/)
1040 FORMAT(
1 ' Analysis type ..... =',I5/
2 ' 1 = Plane stress'/
3 ' 2 = Plane strain'/
4 ' 3 = Axisymmetric')
1050 FORMAT(
1 ' Large deformation flag ..... =',A5)
1060 FORMAT(
1 ' Nonlinear solution algorithm ..... =',I5/
2 ' Negative for the arc length method'/
3 ' 1 = Initial stiffness method'/
4 ' 2 = Newton-Raphson tangential stiffness method'/
5 ' 3 = Modified Newton KT1'/
6 ' 4 = Modified Newton KT2'/
7 ' 5 = Secant Newton - Initial stiffness'/
8 ' 6 = Secant Newton - KT1'/
9 ' 7 = Secant Newton - KT2')
1065 FORMAT(
1 ' Arc-length option ..... =',I5/
2 ' 1 = Follow stiffness determinant sign'/
3 ' 2 = Follow current path')
1070 FORMAT(
1 ' Element connectivities: Number of elements = ',I5,/
3 ' =====//
4 ' Elem. Group Node numbers')
1080 FORMAT(I4,I8,10X,9I5)
1090 FORMAT(
1 ' Nodal point co-ordinates: Number of nodes = ',I5,/
2 ' =====//
3 ' Node X-Coord Y-Coord')
1100 FORMAT(
1 ' Nodal point co-ordinates: Number of nodes = ',I5,/
2 ' =====//
3 ' Node R-Coord Z-Coord')
1110 FORMAT(I5,3G15.6)
1120 FORMAT(
1 ' Prescribed displacements: Number of nodes with',
2 ' prescribed displacement = ',I5/
3 ' =====//
4 ' Node Code Prescribed values ',
5 ' Angle')
1130 FORMAT(1X,I4,1X,I6,3X,7G15.6)
1140 FORMAT(
1 ' Element Groups: Number of element groups = ',I5/
2 ' =====//
3 ' Group Element type Material type')
1150 FORMAT(1X,I5,6X,I5,13X,I5)
1160 FORMAT(
1 ' Element types: Number of element types = ',I5/
2 ' =====')
1170 FORMAT('/' Element type number ',I2/,' -----')
1180 FORMAT(
1 ' Material properties: Number of materials = ',I5/
2 ' =====')
1190 FORMAT('/' Material type number ',I2/,' -----')
1200 FORMAT(
1 ' Axis of symmetry ..... = ',A)
1210 FORMAT('/' No Master/Slave nodal constraints specified'/
1 ' =====//)
1220 FORMAT(
1 ' Master/slave constraint sets: Number of sets = ',I5/
2 ' =====')
1230 FORMAT('/' Master node =',I4,' Number of slave nodes =',I3,
1 ' Fixity condition =',I3/)
1240 FORMAT(' Slaves =',12I5:/(9X,12I5))
1250 FORMAT(
1 ' Thickness distribution (initial thickness for large strains)'/
2 ' =====//)
1260 FORMAT(' Uniform thickness = ',G15.6/)
1270 FORMAT(' Elem. thickness')
1280 FORMAT(' Node thickness')
1290 FORMAT(I5,1X,G15.6)
C
C Read basic analysis information
C =====
C
CALL FNDKEY
1( FOUND ,IWBEG ,IWEND ,'TITLE',
2 INLINE ,15 ,NWRD )
IF(.NOT.FOUND)CALL ERRPR('ED0080')

```

```

        READ(15,1010)TITLE
        WRITE(16,1000)
        WRITE(16,1015)TITLE
C
        WRITE(16,1030)
C
        CALL FNDKEY
1(   FOUND   ,IWBEGL   ,IWEND   , 'ANALYSIS_TYPE' ,
2(   INLINE  ,15      ,NWRD    )
    IF(.NOT.FOUND)CALL ERRPRT('ED0081')
    IF(NWRD.EQ.1)CALL ERRPRT('ED0018')
    NTYPE=INTNUM(INLINE(IWBEGL(2):IWEND(2)))
    WRITE(16,1040)NTYPE
    IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NDOFN=2
        NDIME=2
    ELSE
        CALL ERRPRT('ED0009')
    ENDIF
    IF(NTYPE.EQ.3)THEN
        CALL FNDKEY
1(   FOUND   ,IWBEGL   ,IWEND   , 'AXIS_OF_SYMMETRY' ,
2(   INLINE  ,15      ,NWRD    )
    IF(.NOT.FOUND)CALL ERRPRT('ED0082')
    IF(NWRD.EQ.1)CALL ERRPRT('ED0016')
    WRITE(16,1200)INLINE(IWBEGL(2):IWEND(2))
    IF(INLINE(IWBEGL(2):IWEND(2)).EQ.'Y')THEN
        NAXIS=1
    ELSEIF(INLINE(IWBEGL(2):IWEND(2)).EQ.'X')THEN
        NAXIS=2
    ELSE
        CALL ERRPRT('ED0017')
    ENDIF
ENDIF
C
        CALL FNDKEY
1(   FOUND   ,IWBEGL   ,IWEND   , 'LARGE_STRAIN_FORMULATION' ,
2(   INLINE  ,15      ,NWRD    )
    IF(.NOT.FOUND)CALL ERRPRT('ED0083')
    IF(NWRD.EQ.1)CALL ERRPRT('ED0022')
    WRITE(16,1050)INLINE(IWBEGL(2):IWEND(2))
    IF(INLINE(IWBEGL(2):IWEND(2)).EQ.'ON')THEN
        NLARGE=1
    ELSEIF(INLINE(IWBEGL(2):IWEND(2)).EQ.'OFF')THEN
        NLARGE=0
    ELSE
        CALL ERRPRT('ED0014')
    ENDIF
C
C Read non-linear equilibrium solution algorithm information
C =====
C
        CALL FNDKEY
1(   FOUND   ,IWBEGL   ,IWEND   , 'SOLUTION_ALGORITHM' ,
2(   INLINE  ,15      ,NWRD    )
    IF(.NOT.FOUND)CALL ERRPRT('ED0084')
    IF(NWRD.EQ.1)CALL ERRPRT('ED0021')
    NALGO=INTNUM(INLINE(IWBEGL(2):IWEND(2)))
    WRITE(16,1060)NALGO
    IF(IABS(NALGO).NE.1.AND.IABS(NALGO).NE.2.AND.IABS(NALGO).NE.3.AND.
1  IABS(NALGO).NE.4.AND.IABS(NALGO).NE.5.AND.IABS(NALGO).NE.6.AND.
2  IABS(NALGO).NE.7)CALL ERRPRT('ED0010')
    NARCL=0
    IF(NALGO.LT.0)THEN
        CALL FNDKEY
1(   FOUND   ,IWBEGL   ,IWEND   , 'ARC_LENGTH_PREDICTOR_OPTION' ,
2(   INLINE  ,15      ,NWRD    )
    IF(NWRD.EQ.1)CALL ERRPRT('ED0140')
    IF(FOUND)THEN
        IF(INLINE(IWBEGL(2):IWEND(2)).EQ.'STIFFNESS_SIGN')THEN
            NARCL=1
        ELSEIF(INLINE(IWBEGL(2):IWEND(2)).EQ.'SECANT_PATH')THEN
            NARCL=2
        ELSE
            CALL ERRPRT('ED0141')
        ENDIF
        WRITE(16,1065)NARCL
    ELSE
        CALL ERRPRT('ED0139')
    ENDIF
ENDIF
C
C Read all information concerning element groups
C =====
C
        CALL FNDKEY
1(   FOUND   ,IWBEGL   ,IWEND   , 'ELEMENT_GROUPS' ,
2(   INLINE  ,15      ,NWRD    )
    IF(.NOT.FOUND)CALL ERRPRT('ED0085')
    IF(NWRD.EQ.1)CALL ERRPRT('ED0052')
    NGRUP=INTNUM(INLINE(IWBEGL(2):IWEND(2)))
    WRITE(16,1140)NGRUP
    IF(NGRUP.LT.1)CALL ERRPRT('ED0053')
    IF(NGRUP.GT.MGRUP)CALL ERRPRT('ED0054')
C
C assign element & material type identification numbers to each group
C
        DO 101 IGRUP=1,NGRUP
            IGRCHK(IGRUP)=0
101 CONTINUE
        DO 102 IGRUP=1,NGRUP
            READ(15,*)IGRP,IELIDN,MATIDN
            WRITE(16,1150)IGRP,IELIDN,MATIDN
            IF(IGRP.GT.IGRUP.OR.IELIDN.GT.IGRUP.OR.MATIDN.GT.IGRUP.OR.
1  IGRP.LT.1.OR.IELIDN.LT.1.OR.MATIDN.LT.1)CALL ERRPRT('ED0062')
            IF(IGRCHK(IGRP).EQ.1)CALL ERRPRT('ED0063')
            IGRCHK(IGRP)=1
            IELTID(IGRP)=IELIDN
            MATTID(IGRP)=MATIDN
102 CONTINUE
C
C Read type of element associated with each element type identification
C number and call the appropriate routines to read the element

```

C properties and set vectors IELPRP and RELPRP of integer and real
C element properties

```
C
CALL FNDKEY
1( FOUND ,IWBE ,IWEND , 'ELEMENT_TYPES',
2  INLINE ,15 ,NWRD )
IF(.NOT.FOUND)CALL ERRPRT('ED0086')
IF(NWRD.EQ.1)CALL ERRPRT('ED0055')
NELTS=INTNUM(INLINE(IWBE(2):IWEND(2)))
WRITE(16,1160)NELTS
IF(NELTS.LT.1)CALL ERRPRT('ED0056')
IF(NELTS.GT.NGRUP)CALL ERRPRT('ED0057')
DO 84 IELTS=1,NGRUP
  IETCHK(IELTS)=0
84 CONTINUE
UNSYM=.FALSE.
DO 82 IELTS=1,NELTS
  READ(15,1020)SUBKEY
  NSKWRD=NWORD(SUBKEY,IWBE,IWEND)
  IF(NSKWRD.EQ.0)CALL ERRPRT('ED0058')
  IF(NSKWRD.EQ.1)CALL ERRPRT('ED0059')
  IELIDN=INTNUM(SUBKEY(IWBE(1):IWEND(1)))
  ELTNAM=SUBKEY(IWBE(2):IWEND(2))
  WRITE(16,1170)IELIDN
  IF(IELIDN.LE.0.OR.IELIDN.GT.NELTS)CALL ERRPRT('ED0060')
  IF(IETCHK(IELIDN).EQ.1)CALL ERRPRT('ED0061')
  IETCHK(IELIDN)=1
C Set type, class and read and set other properties
IF(ELTNAM.EQ.'TRI_3')THEN
  IELTYP=TRI3
  IELCLS=STDARD
  CALL RST3
1( IELPRP(1,IELIDN) ,16 ,RELPRP(1,IELIDN) ,UNSAUX)
  ELSEIF(ELTNAM.EQ.'QUAD_4')THEN
    IELTYP=QUAD4
    IELCLS=STDARD
    CALL RSO4
1( IELPRP(1,IELIDN) ,15 ,16 ,RELPRP(1,IELIDN) ,UNSAUX)
    ELSEIF(ELTNAM.EQ.'QUAD_8')THEN
      IELTYP=QUAD8
      IELCLS=STDARD
      CALL RSO8
1( IELPRP(1,IELIDN) ,15 ,16 ,RELPRP(1,IELIDN) ,UNSAUX)
    ELSEIF(ELTNAM.EQ.'QUAD_4_FBAR')THEN
      IELTYP=QUA4FB
      IELCLS=FBAR
      IF(NLARGE.NE.1)THEN
        CALL ERRPRT('ED0180')
      ENDIF
      CALL RSO4FB
1( IELPRP(1,IELIDN) ,15 ,16 ,NTYPE ,RELPRP(1,IELIDN) ,
2  UNSAUX )
    ELSE
      CALL ERRPRT('ED0064')
    ENDIF
    IELPRP(1,IELIDN)=IELTYP
    IELPRP(2,IELIDN)=IELCLS
    IF(UNSAUX)UNSYM=.TRUE.
82 CONTINUE
```

C Check that the properties associated with all element type

C identification numbers have been read

```
DO 83 IGRUP=1,NGRUP
  IELIDN=IELTID(IGRUP)
  IF(IETCHK(IELIDN).NE.1)CALL ERRPRT('ED0065')
83 CONTINUE
```

C

C Read type of material associated with each material type

C identification number and call the appropriate routines to read the

C material properties and set vectors IPROPS and RPROPS of integer and

C real material properties

C

```
CALL FNDKEY
1( FOUND ,IWBE ,IWEND , 'MATERIALS',
2  INLINE ,15 ,NWRD )
IF(.NOT.FOUND)CALL ERRPRT('ED0087')
IF(NWRD.EQ.1)CALL ERRPRT('ED0027')
NMATS=INTNUM(INLINE(IWBE(2):IWEND(2)))
WRITE(16,1180)NMATS
IF(NMATS.LE.0.OR.NMATS.GT.NGRUP)CALL ERRPRT('ED0007')
DO 99 IMATS=1,NMATS
  MATCHK(IMATS)=0
99 CONTINUE
DO 100 IMATS=1,NMATS
  READ(15,1020)SUBKEY
  NSKWRD=NWORD(SUBKEY,IWBE,IWEND)
  IF(NSKWRD.EQ.0)CALL ERRPRT('ED0028')
  IF(NSKWRD.EQ.1)CALL ERRPRT('ED0029')
  MATIDN=INTNUM(SUBKEY(IWBE(1):IWEND(1)))
  MATNAM=SUBKEY(IWBE(2):IWEND(2))
  WRITE(16,1190)MATIDN
  IF(MATIDN.LE.0.OR.MATIDN.GT.NMATS)CALL ERRPRT('ED0044')
  IF(MATCHK(MATIDN).EQ.1)CALL ERRPRT('ED0045')
  MATCHK(MATIDN)=1
```

C

C Call material interface for reading material-specific data

C

```
CALL MATIRD
1( MATNAM ,NLARGE ,NTYPE ,UNSAUX ,
2  IPROPS(1,MATIDN) ,RPROPS(1,MATIDN) )
IF(UNSAUX)UNSYM=.TRUE.
```

C

```
100 CONTINUE
DO 103 IGRUP=1,NGRUP
  MATIDN=MATTID(IGRUP)
  IF(MATCHK(MATIDN).NE.1)CALL ERRPRT('ED0066')
103 CONTINUE
```

C

C Read elements nodal connectivities and group

C =====

C

```
CALL FNDKEY
1( FOUND ,IWBE ,IWEND , 'ELEMENTS',
2  INLINE ,15 ,NWRD )
```

```

        IF(.NOT.FOUND)CALL ERRPRT('ED0088')
        IF(NWRD.EQ.1)CALL ERRPRT('ED0023')
        NELEM=INTNUM(INLINE(IWBEG(2):IWEND(2)))
        WRITE(16,1070)NELEM
        IF(NELEM.LE.0)      CALL ERRPRT('ED0001')
        IF(NELEM.GT.MELEM)CALL ERRPRT('ED0002')
        CALL IVZERO(IELCHK,NELEM)
        MPOSPO=0
        DO 10 IELEM=1,NELEM
C Read element connectivity list
        READ(15,*)NUMEL,IGRPID(NUMEL),(LNODS(NUMEL,INODE),
            INODE=1,IELPRP(3,IELTID(IGRPID(NUMEL))))
        NNODE=IELPRP(3,IELTID(IGRPID(NUMEL)))
        WRITE(16,1080)NUMEL,IGRPID(NUMEL),(LNODS(NUMEL,INODE),
            INODE=1,NNODE)
        MPOSPO=MPOSPO+NNODE
C Check for repeated element connectivity specification
        IF(IELCHK(NUMEL).EQ.1)CALL ERRPRT('ED0047')
        IELCHK(NUMEL)=1
C Check for invalid element and group numbers
        IF(NUMEL.LE.0.OR.NUMEL.GT.NELEM)CALL ERRPRT('ED0046')
        IF(IGRPID(NUMEL).EQ.0.OR.IGRPID(NUMEL).GT.NGRUP)
            1 CALL ERRPRT('ED0037')
        10 CONTINUE
C
C Read nodal coordinates and thickness
C =====
C
        CALL FNDKEY
        1( FOUND      ,IWBEG      ,IWEND      , 'NODE_COORDINATES',
          2  INLINE    ,15        ,NWRD      )
        IF(.NOT.FOUND)CALL ERRPRT('ED0089')
        IF(NWRD.EQ.1)CALL ERRPRT('ED0024')
        IF(NDIME.EQ.2.AND.NWRD.LT.3)CALL ERRPRT('ED0144')
        CYLIND=.FALSE.
        CARTES=.TRUE.
        IF(NDIME.EQ.2)THEN
C accepts data either in polar or cartesian system
            IF(INLINE(IWBEG(3):IWEND(3)).EQ.'CYLINDRICAL')THEN
                CYLIND=.TRUE.
                CARTES=.FALSE.
            ELSEIF(INLINE(IWBEG(3):IWEND(3)).EQ.'CARTESIAN')THEN
                CYLIND=.FALSE.
                CARTES=.TRUE.
            ELSE
                CALL ERRPRT('ED0145')
            ENDIF
        ENDIF
        NPOIN=INTNUM(INLINE(IWBEG(2):IWEND(2)))
        IF(NTYPE.EQ.1.OR.NTYPE.EQ.2)THEN
            WRITE(16,1090)NPOIN
        ELSEIF(NTYPE.EQ.3)THEN
            WRITE(16,1100)NPOIN
        ENDIF
        IF(NPOIN.LE.0)      CALL ERRPRT('ED0003')
        IF(NPOIN.GT.MPOIN)  CALL ERRPRT('ED0004')
        IF(NPOIN.GT.MPOSPO)CALL ERRPRT('ED0049')
C
C Set global variable NTOTV (total number of degrees of freedom)
C
        NTOTV=NPOIN*NDOFN
C
C Read coordinates
        CALL IVZERO(INDCHK,NPOIN)
        DO 20 ICOUNT=1,NPOIN
            IF(CYLIND)THEN
C...in polar system
                READ(15,*)IPOIN,(AUXCOR(IDIME),IDIME=1,NDIME),RAD,THET
            ELSEIF(CARTES)THEN
C...in cartesian system
                READ(15,*)IPOIN,(AUXCOR(IDIME),IDIME=1,NDIME)
            ENDIF
            IF(IPOIN.GT.NPOIN.OR.IPOIN.LE.0)CALL ERRPRT('ED0127')
            DO 15 IDIME=1,NDIME
                COORD(IDIME,IPOIN,1)=AUXCOR(IDIME)
            15 CONTINUE
            IF(INDCHK(IPOIN).NE.0)CALL ERRPRT('ED0126')
            INDCHK(IPOIN)=1
            IF(CYLIND)THEN
                IF(RAD.NE.R0)THEN
C Input data in polar coordinates - transform into cartesian coordinates
                    THET=THET*ATAN(R1)/R45
                    COORD(1,IPOIN,1)=COORD(1,IPOIN,1)+RAD*COS(THET)
                    COORD(2,IPOIN,1)=COORD(2,IPOIN,1)+RAD*SIN(THET)
                ENDIF
            ENDIF
C Echo coordinates
            WRITE(16,1110)IPOIN,(COORD(IDIME,IPOIN,1),IDIME=1,NDIME)
            20 CONTINUE
            DO 30 IPOIN=1,NPOIN
C check that the coordinates of all nodes have been defined
                IF(INDCHK(IPOIN).NE.1)CALL ERRPRT('ED0125')
C initialise initial and last converged coordinates sub-arrays
                DO 25 IDIME=1,NDIME
                    COORD(IDIME,IPOIN,0)=COORD(IDIME,IPOIN,1)
                    COORD(IDIME,IPOIN,2)=COORD(IDIME,IPOIN,1)
                25 CONTINUE
            30 CONTINUE
C
C Read initial thickness (for plane stress only)
C =====
C
        IF(NTYPE.EQ.1)THEN
            CALL FNDKEY
            1( FOUND      ,IWBEG      ,IWEND      , 'THICKNESS',
              2  INLINE    ,15        ,NWRD      )
            IF(.NOT.FOUND)CALL ERRPRT('ED0090')
            IF(NWRD.EQ.1)CALL ERRPRT('ED0072')
            WRITE(16,1250)
C
C Uniform initial thickness in the whole mesh
C -----
            IF(INLINE(IWBEG(2):IWEND(2)).EQ.'UNIFORM')THEN

```



```

      READ(15,*)THICK
      WRITE(16,1260)THICK
      DO 35 IELEM=1,NELEM
        IGRUP=IGRPID(IELEM)
        IELIDN=IELTID(IGRUP)
        NGAUSP=IELPRP(4,IELIDN)
        DO 34 IGAUSP=1,NGAUSP
          THKGP(IGAUSP,IELEM,0)=THICK
          THKGP(IGAUSP,IELEM,1)=THICK
34      CONTINUE
35      CONTINUE
C
C Non-uniform initial thickness (constant within each element)
C -----
      ELSEIF(INLINE(IWBEG(2):IWEND(2)).EQ.'DEFINED_BY_ELEMENT')THEN
        WRITE(16,1270)
        CALL IVZERO(IELCHK,NELEM)
C Read element thicknesses and set corresponding gauss point thicknesses
        IF(NWRD.EQ.2)THEN
          DO 41 I=1,NELEM
            READ(15,*)IELEM,THICK
            WRITE(16,1290)IELEM,THICK
            IF(IELEM.LE.0.OR.IELEM.GT.NELEM)CALL ERRPRT('ED0068')
            IF(IELCHK(IELEM).EQ.1)CALL ERRPRT('ED0069')
            IELCHK(IELEM)=1
            IGRUP=IGRPID(IELEM)
            IELIDN=IELTID(IGRUP)
            NGAUSP=IELPRP(4,IELIDN)
            DO 40 IGAUSP=1,NGAUSP
              THKGP(IGAUSP,IELEM,0)=THICK
              THKGP(IGAUSP,IELEM,1)=THICK
40      CONTINUE
41      CONTINUE
          ELSE
            NSET=INTNUM(INLINE(IWBEG(3):IWEND(3)))
            DO 45 ISET=1,NSET
              READ(15,*)IFIRST,ILAST,INC,THICK
              DO 44 IELEM=IFIRST,ILAST,INC
                WRITE(16,1290)IELEM,THICK
                IF(IELEM.LE.0.OR.IELEM.GT.NELEM)CALL ERRPRT('ED0068')
                IF(IELCHK(IELEM).EQ.1)CALL ERRPRT('ED0069')
                IELCHK(IELEM)=1
                IGRUP=IGRPID(IELEM)
                IELIDN=IELTID(IGRUP)
                NGAUSP=IELPRP(4,IELIDN)
                DO 43 IGAUSP=1,NGAUSP
                  THKGP(IGAUSP,IELEM,0)=THICK
                  THKGP(IGAUSP,IELEM,1)=THICK
43      CONTINUE
44      CONTINUE
45      CONTINUE
            ENDIF
C Check that the thickness has been defined for all elements
            DO 46 IELEM=1,NELEM
              IF(IELCHK(IELEM).NE.1)CALL ERRPRT('ED0075')
46      CONTINUE
C
C Non-uniform initial thickness (continuous across elements)
C -----
      ELSEIF(INLINE(IWBEG(2):IWEND(2)).EQ.'DEFINED_BY_NODE')THEN
        WRITE(16,1280)
        CALL IVZERO(INDCHK,NPOIN)
C Read nodal thicknesses
        IF(NWRD.EQ.2)THEN
          DO 50 I=1,NPOIN
            READ(15,*)IPOIN,THICK
            WRITE(16,1290)IPOIN,THICK
            IF(IPOIN.LE.0.OR.IPOIN.GT.NPOIN)CALL ERRPRT('ED0070')
            IF(INDCHK(IPOIN).EQ.1)CALL ERRPRT('ED0071')
            INDCHK(IPOIN)=1
            THKNOD(IPOIN)=THICK
50      CONTINUE
          ELSE
            NSET=INTNUM(INLINE(IWBEG(3):IWEND(3)))
            DO 55 ISET=1,NSET
              READ(15,*)IFIRST,ILAST,INC,THICK
              DO 54 IPOIN=IFIRST,ILAST,INC
                WRITE(16,1290)IPOIN,THICK
                IF(IPOIN.LE.0.OR.IPOIN.GT.NPOIN)CALL ERRPRT('ED0070')
                IF(INDCHK(IPOIN).EQ.1)CALL ERRPRT('ED0071')
                INDCHK(IPOIN)=1
                THKNOD(IPOIN)=THICK
54      CONTINUE
55      CONTINUE
            ENDIF
C Check that the thickness has been defined for all nodes
            DO 56 IPOIN=1,NPOIN
              IF(INDCHK(IPOIN).NE.1)CALL ERRPRT('ED0076')
56      CONTINUE
            DO 60 IELEM=1,NELEM
C Set element nodal thicknesses array
              IGRUP=IGRPID(IELEM)
              IELIDN=IELTID(IGRUP)
              IELTYP=IELPRP(1,IELIDN)
              NNODE=IELPRP(3,IELIDN)
              NGAUSP=IELPRP(4,IELIDN)
              DO 58 INODE=1,NNODE
                LNODE=IABS(LNODS(IELEM,INODE))
                ELTHK(INODE)=THKNOD(LNODE)
58      CONTINUE
C Interpolate nodal thicknesses to gauss points
              IPPOS=1
              DO 59 IGAUSP=1,NGAUSP
                EXISP=RELPRP(IPPOS-1+IGAUSP*2-1,IELIDN)
                ETASP=RELPRP(IPPOS-1+IGAUSP*2,IELIDN)
                CALL SHPFUN
1(      DERIV      ,ETASP      ,EXISP      ,0      ,IELTYP      ,
2      MDIME      ,SHAPE      )
              THKGP(IGAUSP,IELEM,0)=SCAPRD(ELTHK,SHAPE,NNODE)
              THKGP(IGAUSP,IELEM,1)=SCAPRD(ELTHK,SHAPE,NNODE)
59      CONTINUE
60      CONTINUE
          ELSE

```

```

      CALL ERRPRT('ED0073')
    ENDIF
  ENDIF
C
C
C Read prescribed displacements
C =====
      CALL FNDKEY
1(   FOUND   ,IWBE    ,IWEND   , 'NODES_WITH_PRESCRIBED_DISPLACEMENTS',
2   INLINE   ,15      ,NWRD    )
  IF(.NOT.FOUND)CALL ERRPRT('ED0091')
  IF(NWRD.EQ.1)CALL ERRPRT('ED0025')
  NVFIX=INTNUM(INLINE(IWBE(2):IWEND(2)))
  IF(NDIME.EQ.2)THEN
    WRITE(16,1120)NVFIX
  ENDIF
  IF(NVFIX.LT.1)      CALL ERRPRT('ED0005')
  IF(NVFIX.GT.MVFIX)CALL ERRPRT('ED0006')
  IF(NVFIX.GT.NPOIN)CALL ERRPRT('ED0048')
  DO 70 ITOTV=1,NTOTV
    IFFIX(ITOTV)=0
    DO 65 IRHS=1,2
      FIXED(ITOTV,IRHS)=R0
65  CONTINUE
70  CONTINUE
  DO 91 IVFIX=1,NVFIX
    IF(NDIME.EQ.2)THEN
      READ(15,*)NOFIX(IVFIX),IFPRE,(PRESC(IVFIX,IDOFN),
1      IDOFN=1,NDOFN),THETA
      WRITE(16,1130)NOFIX(IVFIX),IFPRE,(PRESC(IVFIX,IDOFN),
1      IDOFN=1,NDOFN),THETA
      ANGLE(IVFIX)=THETA*ATAN(R1)/R45
    ENDIF
    NLOCA=(NOFIX(IVFIX)-1)*NDOFN
    IFDOF=10**((NDOFN-1))
    DO 90 IDOFN=1,NDOFN
      NGASH=NLOCA+IDOFN
      IF(IFPRE.LT.IFDOF)GOTO 80
      IFFIX(NGASH)=1
      FIXED(NGASH,1)=PRESC(IVFIX,IDOFN)
      FIXED(NGASH,2)=R0
      IFPRE=IFPRE-IFDOF
80    CONTINUE
      IFDOF=IFDOF/10
90    CONTINUE
91  CONTINUE
C Initialize master array
  DO 93 ITOTV=1,NTOTV
    MASTER(ITOTV)=ITOTV
93  CONTINUE
C
C Master/slave nodal constraints
C =====
      CALL FNDKEY
1(   FOUND   ,IWBE    ,IWEND   , 'MASTER_SLAVE_SETS',
2   INLINE   ,15      ,NWRD    )
  IF(.NOT.FOUND)THEN
    NMAST=0
  ELSE
    IF(NWRD.EQ.1)CALL ERRPRT('ED0026')
    NMAST=INTNUM(INLINE(IWBE(2):IWEND(2)))
  ENDIF
C Master/slave nodes specified
  IF(NMAST.NE.0)THEN
    WRITE(16,1220)NMAST
    IF(NMAST.LT.0)CALL ERRPRT('ED0036')
C Loop over sets of slave nodes
    DO 97 IMAST=1,NMAST
      READ(15,*)NODEM,ISLAV,ISFIX
      WRITE(16,1230)NODEM,ISLAV,ISFIX
      READ(15,*)(KSLAV(I),I=1,ISLAV)
      WRITE(16,1240)(KSLAV(I),I=1,ISLAV)
C Place these degrees of freedom in the master array
      IDOFN=(NODEM-1)*NDOFN+1
      IDOF1=IDOFN+1
      DO 96 IS=1,ISLAV
        KDOFN=(KSLAV(IS)-1)*NDOFN+1
        IF(NDOFN.EQ.2)THEN
          IF(ISFIX.EQ.10.OR.ISFIX.EQ.11)THEN
            IF(MASTER(KDOFN).NE.KDOFN)CALL ERRPRT('ED0050')
            MASTER(KDOFN)=IDOFN
          ENDIF
          KDOFN=KDOFN+1
          IF(ISFIX.EQ.1.OR.ISFIX.EQ.11)THEN
            IF(MASTER(KDOFN).NE.KDOFN)CALL ERRPRT('ED0051')
            MASTER(KDOFN)=IDOF1
          ENDIF
        ENDIF
96      CONTINUE
97    CONTINUE
      ELSE
C No master/slave nodes specified
        WRITE(16,1210)
      ENDIF
C
C Does some further checks on input data
C =====
      CALL CHECK2(MXFRON)
C
C Set up nodal valencies for nodal averaging
C =====
      DO 110 IPOIN=1,NPOIN
        DO 105 IGRUP=1,NGRUP
          NVALEN(IPOIN,IGRUP)=0
105      CONTINUE
110    CONTINUE
C Evaluate nodal valencies
  DO 130 IELEM=1,NELEM
    IGRUP=IGRPID(IELEM)
    IELIDN=IELTID(IGRUP)

```

```
      NNODE=IELPRP(3,IELIDN)
      DO 120 INODE=1,NNODE
        LNODE=IABS(LNODS(IELEM,INODE))
        NVALEN(LNODE,IGRUP)=NVALEN(LNODE,IGRUP)+1
120    CONTINUE
130  CONTINUE
      RETURN
      END
```

```

SUBROUTINE ININCR
1( DFACT ,DLENP ,FSTOP ,ITDES ,MINCS ,
2 MITER ,NALGO ,NINCS ,TOLER ,
3 DFACTV ,MITERV ,NOUTP ,NOUTPV ,TOLERV )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION
1 DFACTV(MINCS) ,MITERV(MINCS) ,NOUTP(5) ,
2 NOUTPV(5,MINCS) ,TOLERV(MINCS)

C
LOGICAL FOUND
CHARACTER*80 INLINE
DIMENSION
1 IWBE(40) , IWEN(40)
PARAMETER
1( R0=0.0D0 )
C*****
C READS INPUT DATA FOR LOAD INCREMENTATION
C
C REFERENCE: Figure 5.1
C*****
1000 FORMAT(///' Increment control with fixed load increments selected'
1 '/' , ' ====='
2 '/' , ' Number of proportional load increments =',I5/)

C
1010 FORMAT(///' Increment control by the Arc-Length method selected'//
1 ' ====='//
2 ' Arc length data'/' -----'//
3 ' Maximum allowed number of increments .....= ',I5)
1020 FORMAT(
1 ' Initial load increment factor ..... = ',G15.6/
2 ' Convergence tolerance ..... = ',G15.6/
3 ' Max. No. of iterations ..... = ',I5)
1030 FORMAT(' Output control parameter for results'//
1 ' ( Output frequencies )'//
2 ' Displacements..... = ',I3/
3 ' Reactions..... = ',I3/
4 ' State variables at gauss points..... = ',I3/
5 ' State variables at nodes..... = ',I3/
6 ' Output to re-start file..... = ',I3)
1040 FORMAT(
1 ' Desired number of iterations per increment .. =',I5/
2 ' Maximum load factor ..... =',G15.6/
3 ' Maximum arc length parameter ..... =',G15.6)

C
CALL FNDKEY
1( FOUND ,IWBE ,IWEN , 'INCREMENTS' ,
2 INLINE ,15 ,NWRD )
IF(.NOT.FOUND)CALL ERRPRT('ED0079')

C
IF(NALGO.GT.0)THEN
C Fixed increments option
C -----
IF(NWRD.EQ.1)CALL ERRPRT('ED0034')
NINCS=INTNUM(INLINE(IWBE(2):IWEN(2)))
WRITE(16,1000)NINCS
IF(NINCS.LE.0) CALL ERRPRT('ED0013')
IF(NINCS.GT.MINCS)CALL ERRPRT('ED0035')
DO 10 IINCS=1,NINCS
READ(15,*,ERR=997,END=997)DFACTV(IINCS),TOLERV(IINCS),
1 MITERV(IINCS),(NOUTPV(I,IINCS),I=1,5)
IF(TOLERV(IINCS).LE.R0)CALL ERRPRT('ED0142')
IF(MITERV(IINCS).LT.1)CALL ERRPRT('ED0146')
10 CONTINUE
ELSE
C Arc-length control
C -----
IF(NWRD.EQ.1) CALL ERRPRT('ED0097')
NINCS=INTNUM(INLINE(IWBE(2):IWEN(2)))
WRITE(16,1010)NINCS
IF(NINCS.LE.0)CALL ERRPRT('ED0098')

C
READ(15,*,ERR=998,END=998)DFACT,TOLER,MITER,(NOUTP(I),I=1,5),
1 ITDES,FSTOP,DLENP
IF(TOLER.LT.R0)CALL ERRPRT('ED0142')
IF(ITDES.LT.0)CALL ERRPRT('ED0143')
WRITE(16,1020)DFACT,TOLER,MITER
WRITE(16,1030)(NOUTP(I),I=1,5)
WRITE(16,1040)ITDES,FSTOP,DLENP
ENDIF
C Send error messages in case of I/O error while reading increment data
GOTO 999
997 CALL ERRPRT('ED0178')
GOTO 999
998 CALL ERRPRT('ED0179')
999 CONTINUE
RETURN
END

```

```

      SUBROUTINE INITIA
1(      DLAMD      ,IFNEG      ,KUNLD      ,TFACT      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas global database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C Local variables and numerical constants
      LOGICAL LDUMMY
      DATA R0 /
1      0.0D0/
C*****
C INITIALISES SOME ARRAYS AND VARIABLES
C
C REFERENCE: Section 5.3.4
C*****
      KUNLD=0
      TFACT=R0
      DLAMD=R0
      IFNEG=1
      DO 10 IELEM=1,NELEM
          IGRUP=IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NEVAB=IELPRP(5,IELIDN)
          CALL RVZERO(ELOAD(1,IELEM),NEVAB)
          CALL RVZERO(ELOADO(1,IELEM),NEVAB)
10 CONTINUE
      CALL RVZERO(DTANG,NTOTV)
      CALL RVZERO(TDISP,NTOTV)
      CALL RVZERO(TDISPO,NTOTV)
      CALL RVZERO(DINCR,NTOTV)
      CALL RVZERO(DINCRO,NTOTV)
      CALL RVZERO(DITER,NTOTV)
C Arrays from common block STATE
      DO 30 IELEM=1,NELEM
          IGRUP=IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NGAUSP=IELPRP(4,IELIDN)
          DO 20 IGAUSP=1,NGAUSP
C Call material interface routine to initialise material-specific Gauss
C point data
          MODE=0
          CALL MATISW
1(      MODE      ,NLARGE      ,NTYPE      ,
2      IPROPS(1,MATTID(IGRUP)),LALGVA(1,IGAUSP,IELEM,1)      ,
3      LDUMMY      ,RALGVA(1,IGAUSP,IELEM,1)      ,DUMMY      ,
4      RPROPS(1,MATTID(IGRUP))      ,
5      RSTAVA(1,IGAUSP,IELEM,1)      ,DUMMY      ,
6      STRSG(1,IGAUSP,IELEM,1)      ,DUMMY      )
20 CONTINUE
30 CONTINUE
      RETURN
      END

```

```

SUBROUTINE INLOAD
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas global database
INCLUDE '../MAXDIM.INC'
INCLUDE '../MATERIAL.INC'
INCLUDE '../ELEMENTS.INC'
INCLUDE '../GLBDBASE.INC'

C
LOGICAL FOUND
CHARACTER*80 INLINE
DIMENSION
1 SHAPE(MNODE) ,DERIV(MDIME,MNODE) ,CARTD(MDIME,MNODE) ,
2 GPCOD(MDIME)
DIMENSION
1 DGASH(MDOFN) ,ELCOD(MDIME,MNODE) ,NOPRS(MNODE) ,
2 PGASH(MDOFN) ,POINT(MDOFN) ,PRESS(MNODE,MDOFN) ,
DIMENSION
1 IWBE(40) ,IWEND(40) ,NODCHK(MNODE) ,
2 NODAUX(MPOIN) ,THKN(MNODE)
DATA R0,R1,R8,R45/0.0D0,1.0D0,8.0D0,45.0D0/
C*****
C READS EXTERNAL LOADINGS (BODY FORCE AND SURFACE TRACTIONS) FROM INPUT
C DATA FILE AND ASSEMBLES THE GLOBAL EXTERNAL FORCE VECTOR
C
C REFERENCE: Figure 5.1
C Section 5.3.3
C*****
1040 FORMAT(///
1' Loading specification (other than prescribed displacements)'/
1' ====='//
2' If any of the flags below is set to 1, then'/
3' the corresponding type of loading is applied'/
4' to the structure.'//
5' Point loading flag .....=' ,I3/
6' Gravity loading flag .....=' ,I3/
7' Distributed edge loading flag .....=' ,I3)
1050 FORMAT(///' Point load applied in',I6,' nodes'//
1' -----'//
2' Node X-Component Y-Component')
1055 FORMAT(///' Point load applied in',I6,' nodes'//
1' -----'//
2' Node R-Component Z-Component')
1070 FORMAT(I5,5X,3G15.6)
1080 FORMAT(///' Gravity load'//
1' -----'//
2' Gravity angle (degrees) =' ,G15.6/
3' Gravity constant .....=' ,G15.6)
1110 FORMAT(///' Edge load applied in ',I6,' edges'//
1' -----')
1130 FORMAT(// Element Number =' ,I5/' Node X-Coord. ' ,
1' Y-Coord. Norm. Load Tang. Load')
1135 FORMAT(// Element Number =' ,I5/' Node R-Coord. ' ,
1' Z-Coord. Norm. Load Tang. Load')
1140 FORMAT(I5,2X,2G15.6,3X,2G15.6)
C
C IF(NTYPE.EQ.3)TWOPI=R8*ATAN(R1)
C
C Initialize load vector of all elements
C =====
DO 10 IELEM=1,NELEM
IGRUP=IGRPID(IELEM)
IELIDN=IELTID(IGRUP)
NEVAB=IELPRP(5,IELIDN)
CALL RVZERO(RLOAD(1,IELEM),NEVAB)
10 CONTINUE
C
C Read data controlling loading types to be inputted
C =====
IPLOD=0
IGRAV=0
IEDGE=0
C
CALL FNDKEY
1( FOUND ,IWBE ,IWEND , 'LOADINGS',
2 INLINE ,15 ,NWRD )
IF(.NOT.FOUND)CALL ERRPR('ED0092')
NLOADS=NWRD-1
IF(NLOADS.NE.0)THEN
DO 12 I=1,NLOADS
IF(INLINE(IWBE(1+I):IWEND(1+I)).EQ.'POINT')THEN
IPLOD=1
ELSEIF(INLINE(IWBE(1+I):IWEND(1+I)).EQ.'EDGE')THEN
IEDGE=1
ELSEIF(INLINE(IWBE(1+I):IWEND(1+I)).EQ.'GRAVITY')THEN
IGRAV=1
ELSEIF((INLINE(IWBE(1+I):IWEND(1+I)).EQ.'0').OR.
1 (INLINE(IWBE(1+I):IWEND(1+I)).EQ.'NONE'))THEN
CONTINUE
ELSE
CALL ERRPR('ED0030')
ENDIF
12 CONTINUE
ENDIF
C
WRITE(16,1040)IPLOD,IGRAV,IEDGE
C
C Read nodal point loads
C =====
IF(IPLOD.NE.0)THEN
CALL FNDKEY
1( FOUND ,IWBE ,IWEND , 'POINT_LOADS',
2 INLINE ,15 ,NWRD )
IF(.NOT.FOUND)CALL ERRPR('ED0093')
IF(NWRD.EQ.1)CALL ERRPR('ED0031')
NPLOAD=INTNUM(INLINE(IWBE(2):IWEND(2)))
IF(NTYPE.EQ.1.OR.NTYPE.EQ.2)THEN
WRITE(16,1050)NPLOAD
ELSEIF(NTYPE.EQ.3)THEN

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```

        WRITE(16,1055)NPLOAD
    ENDIF
    DO 55 IPLOAD=1,NPLOAD
        READ(15,*)LODPT,(POINT(IDOFN),IDOFN=1,NDOFN)
        WRITE(16,1070)LODPT,(POINT(IDOFN),IDOFN=1,NDOFN)
        IF(LODPT.LE.0.OR.LODPT.GT.NPOIN)CALL ERRPR('ED0134')
C
C Associate the nodal point loads with an element
C
        DO 35 IELEM=1,NELEM
            IGRUP=IGRPID(IELEM)
            IELIDN=IELTID(IGRUP)
            NNODE=IELPRP(3,IELIDN)
            DO 30 INODE=1,NNODE
                NLOCA=IABS(LNODS(IELEM,INODE))
                IF(LODPT.EQ.NLOCA)GOTO 40
30          CONTINUE
35          CONTINUE
40          CONTINUE
            DO 50 IDOFN=1,NDOFN
                NGASH=(INODE-1)*NDOFN+IDOFN
                RLOAD(NGASH,IELEM)=RLOAD(NGASH,IELEM)+POINT(IDOFN)
50          CONTINUE
55          CONTINUE
        ENDIF
C
C Gravity loading
C =====
        IF(IGRAV.NE.0)THEN
C
C Read gravity angle and gravitational constant
C
            CALL ENDKEY
1(         FOUND      ,IWBE      ,IWEND      , 'GRAVITY_LOAD' ,
2         INLINE      ,15       ,NWRD       )
            IF(.NOT.FOUND)CALL ERRPR('ED0094')
            READ(15,*)THETA,GRAVY
            WRITE(16,1080)THETA,GRAVY
            THETA=THETA*ATAN(R1)/R45
C
C Loop over elements
C
            DO 90 IELEM=1,NELEM
                IGRUP =IGRPID(IELEM)
                IELIDN=IELTID(IGRUP)
                IELTYP=IELPRP(1,IELIDN)
                NNODE =IELPRP(3,IELIDN)
                NGAUSP=IELPRP(4,IELIDN)
C Set up preliminary constants
                MATIDN=MATTID(IGRPID(IELEM))
                DENSE=RPROPS(1,MATIDN)
                IF(DENSE.EQ.R0) GOTO 90
                GXCOM=DENSE*GRAVY*SIN(THETA)
                GYCOM=-DENSE*GRAVY*COS(THETA)
C Compute coordinates of the element nodal points
                DO 65 INODE=1,NNODE
                    LNODE=IABS(LNODS(IELEM,INODE))
                    DO 60 IDIME=1,NDIME
                        ELCOD(IDIME,INODE)=COORD(IDIME,LNODE,1)
60          CONTINUE
65          CONTINUE
C
C Loop for numerical integration over element domain
C
                IPPOS=1
                IPWEI=NGAUSP*NDIME+1
                DO 85 IGAUSP=1,NGAUSP
                    EXISP=RELPRP(IPPOS-1+IGAUSP*2-1,IELIDN)
                    ETASP=RELPRP(IPPOS-1+IGAUSP*2 ,IELIDN)
                    WEIGP=RELPRP(IPWEI-1+IGAUSP ,IELIDN)
C Compute the shape functions at the sampling points and elemental
C volume
                    CALL SHPFUN
1(         DERIV      ,ETASP      ,EXISP      ,0          ,IELTYP      ,
2         MDIME      ,SHAPE      )
                    CALL JACOB2
1(         CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
2         MDIME      ,NDIME      ,NNODE      )
                    CALL GETGCO
1(         GPCOD      ,ELCOD      ,MDIME      ,NDIME      ,NNODE      ,
2         SHAPE      )
C
                    DVOLU=DETJAC*WEIGP
                    IF(NTYPE.EQ.1)THEN
                        DVOLU=DVOLU*THKGP(IGAUSP,IELEM,1)
                    ELSEIF(NTYPE.EQ.3)THEN
                        DVOLU=DVOLU*TWOPI*GPCOD(NAXIS)
                    ENDIF
C Calculate equivalent nodal loads and add them to element force vector
                    DO 70 INODE=1,NNODE
                        NGASH=(INODE-1)*NDOFN+1
                        MGASH=(INODE-1)*NDOFN+2
                        RLOAD(NGASH,IELEM)=RLOAD(NGASH,IELEM)+
1                        GXCOM*SHAPE(INODE)*DVOLU
                        RLOAD(MGASH,IELEM)=RLOAD(MGASH,IELEM)+
1                        GYCOM*SHAPE(INODE)*DVOLU
70          CONTINUE
85          CONTINUE
90          CONTINUE
                ENDIF
C
C Distributed edge loads (pressure)
C =====
        IF(IEDGE.NE.0)THEN
            CALL ENDKEY
1(         FOUND      ,IWBE      ,IWEND      , 'EDGE_LOADS' ,
2         INLINE      ,15       ,NWRD       )
            IF(.NOT.FOUND)CALL ERRPR('ED0095')
            IF(NWRD.EQ.1)CALL ERRPR('ED0032')
            NLOADE=INTNUM(INLINE(IWBEG(2):IWEND(2)))

```

```

WRITE(16,1110)NLOADE
C
C Loop over loaded edges
C
DO 160 ILOADE=1,NLOADE
C Read and echo the element number and corresponding global node numbers
C with prescribed pressure
READ(15,*)IELEM,NNODEG,(NOPRS(INODEG),INODEG=1,NNODEG)
IF(NTYPE.NE.3)THEN
WRITE(16,1130)IELEM
ELSE
WRITE(16,1135)IELEM
ENDIF
IF(IELEM.LE.0.OR.IELEM.GT.NELEM)CALL ERRPRT('ED0019')
DO 80 INODEG=1,NNODEG
IPOIN=NOPRS(INODEG)
IF(IPOIN.LE.0.OR.IPOIN.GT.NPOIN)CALL ERRPRT('ED0020')
80 CONTINUE
C Set properties of the current element
IGRUP=IGRPID(IELEM)
IELIDN=IELTID(IGRUP)
IELTYP=IELPRP(1,IELIDN)
NNODE =IELPRP(3,IELIDN)
NGAUSP=IELPRP(4,IELIDN)
NEDGEL=IELPRP(6,IELIDN)
MNODEG=IELPRP(7,IELIDN)
NGAUSB=IELPRP(8,IELIDN)
IPOS=9
C Read and echo pressures
READ(15,*)((PRESS(INODEG,IDOFN),INODEG=1,NNODEG),
1 IDOFN=1,NDOFN)
DO 95 INODEG=1,NNODEG
IPOIN=NOPRS(INODEG)
WRITE(16,1140)IPOIN,(COORD(I,IPOIN,1),I=1,NDIME),
1 (PRESS(INODEG,I),I=1,NDIME)
95 CONTINUE
IF(NNODEG.GT.MNODEG)CALL ERRPRT('ED0011')
C Check that global node numbers supplied correspond exactly to an edge
C of the current element
DO 96 INODE=1,NNODE
NODCHK(INODE)=0
96 CONTINUE
DO 98 INODEG=1,NNODEG
DO 97 INODE=1,NNODE
IPOIN=IABS(LNODS(IELEM,INODE))
IF(IPOIN.EQ.NOPRS(INODEG))NODCHK(INODE)=1
97 CONTINUE
98 CONTINUE
CALL CHKNDE
1( FOUND ,NNODE ,NEDGEL ,NODCHK ,IELPRP(IPOS,IELIDN))
IF(.NOT.FOUND)CALL ERRPRT('ED0012')
C
C Get the global coordinates of the nodes of the loaded edge
DO 104 INODEG=1,NNODEG
IPOIN=NOPRS(INODEG)
DO 100 IDIME=1,NDIME
ELCOD(IDIME,INODEG)=COORD(IDIME,IPOIN,1)
100 CONTINUE
C
DO 102 II=1,NNODEG
IF(IABS(LNODS(IELEM,NODCHK(II)))EQ.IPOIN)NODAX(IPOIN)=II
102 CONTINUE
104 CONTINUE
C Extrapolate thickness to nodes (for plane stress only)
IF(NTYPE.EQ.1)THEN
IPOS=NGAUSP*NDIME+NGAUSP+1
CALL EXTNOD
1( RELPRP(IPOS,IELIDN),
2 THKGP(1,IELEM,1) ,THKN ,1 ,NGAUSP ,NNODE )
ENDIF
C
C Loop for (boundary) numerical integration over loaded edge
C
DO 150 IGAUSB=1,NGAUSB
C Evaluate the shape functions at the boundary sampling points
IPPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+1
IPWEI=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+NGAUSB+1
EXISPB=RELPRP(IPPOS-1+IGAUSB,IELIDN)
WEIGPB=RELPRP(IPWEI-1+IGAUSB,IELIDN)
CALL SHPFUN
1( DERIV ,DUMMY ,EXISPB ,1 ,IELTYP ,
2 MDIME ,SHAPE )
C Calculate components of the equivalent nodal loads
DO 114 IDOFN=1,NDOFN
PGASH(IDOFN)=R0
DGASH(IDOFN)=R0
DO 110 INODEG=1,NNODEG
II=NODAX(NOPRS(INODEG))
PGASH(IDOFN)=PGASH(IDOFN)+
1 PRESS(INODEG,IDOFN)*SHAPE(II)
DGASH(IDOFN)=DGASH(IDOFN)+
1 ELCOD(IDOFN,INODEG)*DERIV(1,II)
110 CONTINUE
114 CONTINUE
PXCOMP=DGASH(1)*PGASH(2)-DGASH(2)*PGASH(1)
PYCOMP=DGASH(1)*PGASH(1)+DGASH(2)*PGASH(2)
C
DVOLU=WEIGPB
IF(NTYPE.EQ.1)THEN
C interpolate to find thickness at boundary gauss point (plane stress)
THICK=R0
DO 115 INODEG=1,NNODEG
II=NODAX(NOPRS(INODEG))
INODE=NODCHK(II)
THICK=THICK+THKN(INODE)*SHAPE(II)
115 CONTINUE
DVOLU=DVOLU*THICK
ELSEIF(NTYPE.EQ.3)THEN
C interpolate to find radius at boundary gauss point (axisymmetric case)
RADUS=R0
DO 117 INODEG=1,NNODEG
II=NODAX(NOPRS(INODEG))

```



```

117         RADUS=RADUS+SHAPE(II)*ELCOD(NAXIS,INODEG)
          CONTINUE
          DVOLU=DVOLU*TWOPI*RADUS
        ENDIF
C
C Add the equivalent nodal loads to the element force vector
      DO 130 INODEG=1,NNODEG
        INODE=NODCHK(INODEG)
        NGASH=(INODE-1)*NDOFN+1
        MGASH=(INODE-1)*NDOFN+2
        RLOAD(NGASH,IELEM)=RLOAD(NGASH,IELEM)+
          1          SHAPE(INODEG)*PXCOMP*DVOLU
        RLOAD(MGASH,IELEM)=RLOAD(MGASH,IELEM)+
          1          SHAPE(INODEG)*PYCOMP*DVOLU
      130    CONTINUE
      150    CONTINUE
      160    CONTINUE
        ENDIF
C
      RETURN
      END

```

```

SUBROUTINE INTFOR( INCCUT )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
  INCLUDE './MAXDIM.INC'
  INCLUDE './MATERIAL.INC'
  INCLUDE './ELEMENTS.INC'
  INCLUDE './GLBDBASE.INC'

C Arguments
  LOGICAL INCCUT
C Local variables
  LOGICAL IFFAIL
C*****
C LOOPS OVER ALL ELEMENTS OF THE STRUCTURE TO COMPUTE ELEMENT INTERNAL
C FORCE VECTORS
C
C REFERENCE: Figures 5.2-3
C*****
C Initialise increment cutting flag
  INCCUT=.FALSE.
C
C Begin loop over elements
C =====
  DO 50 IELEM=1,NELEM
C
C Call element interface for internal force vector computation
C -----
  CALL ELEIIF
    1( IELEM ,IFFAIL )
C
  IF(IFFAIL)THEN
C Internal force calculation failed for current element: Break loop
C over elements and return to main program with increment cutting
C flag activated
    INCCUT=.TRUE.
    GOTO 999
  ENDIF
C
  50 CONTINUE
C Emergency exit
  999 CONTINUE
  RETURN
  END

```

```

      INTEGER FUNCTION INTNUM(CHRSTR)
      IMPLICIT NONE
      CHARACTER*(*) CHRSTR
      INTEGER I, IASCII, IEND, IPOWER, LEN, LENGTH, NUMBER
C*****
C CONVERTS A NUMBER CONTAINED IN A CHARACTER STRING INTO AN INTEGER
C*****
1000 FORMAT(/15X,'ERROR: String of blank characters passed'/
1      22X,'into integer conversion function INTMUN')
1100 FORMAT(/15X,'ERROR: Invalid character in string','',A,''' passed'/
1      22X,'into integer conversion function INTMUN')
C
      LENGTH=LEN(CHRSTR)
      DO 10 I=LENGTH,1,-1
        IF(CHRSTR(I:I).NE.' ')THEN
          IEND=I
          GOTO 20
        ENDIF
10 CONTINUE
      WRITE(*,1000)
      WRITE(16,1000)
      CALL PEXIT
20 CONTINUE
      INTNUM=0
      IPOWER=0
      DO 30 I=IEND,1,-1
        IASCII=ICHAR(CHRSTR(I:I))
        IF(IASCII.GE.48.AND.IASCII.LE.57)THEN
          NUMBER=IASCII-48
          INTNUM=INTNUM+NUMBER*(10**IPOWER)
          IPOWER=IPOWER+1
        ELSEIF(CHRSTR(I:I).EQ.' ')THEN
          GOTO 40
        ELSEIF(CHRSTR(I:I).EQ.'-' .OR. CHRSTR(I:I).EQ.'+')THEN
          IF(I.NE.IEND)THEN
            IF(CHRSTR(I:I).EQ.'-') INTNUM=-INTNUM
            GOTO 40
          ELSE
            WRITE(*,1100)CHRSTR(1:IEND)
            WRITE(16,1100)CHRSTR(1:IEND)
            CALL PEXIT
          ENDIF
        ELSE
          WRITE(*,1100)CHRSTR(1:IEND)
          WRITE(16,1100)CHRSTR(1:IEND)
          CALL PEXIT
        ENDIF
30 CONTINUE
40 CONTINUE
      RETURN
      END

```

```

SUBROUTINE INVF2
1(      F      ,FINV      ,NTYPE      )
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
  DIMENSION
1      F(3,3)      ,FINV(3,3)
  DATA
1      R0      ,R1      /
2      0.0D0,1.0D0/
C*****
C INVERTS DEFORMATION GRADIENT TENSORS FOR PLANE STRESS/STRAIN AND
C AXISYMMETRIC PROBLEMS
C*****
      DETFPL=F(1,1)*F(2,2)-F(1,2)*F(2,1)
      IF(DETFPL.EQ.R0)CALL ERRPRN('EE0001')
      IF(NTYPE.EQ.3.AND.F(3,3).EQ.R0)CALL ERRPRN('EE0001')
C
      DETFIN=R1/DETFPL
      FINV(1,1)=F(2,2)*DETFIN
      FINV(2,2)=F(1,1)*DETFIN
      FINV(1,2)=-F(1,2)*DETFIN
      FINV(2,1)=-F(2,1)*DETFIN
      IF(NTYPE.EQ.2)THEN
        FINV(3,3)=R1
      ELSEIF(NTYPE.EQ.3)THEN
        FINV(3,3)=R1/F(3,3)
      ENDIF
C
      RETURN
      END

```

```

SUBROUTINE INVT3
1(      S      ,SINV      ,DETS      )
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
  DIMENSION
1      S(3,3)      ,SINV(3,3)
  DATA
1      R0      ,R1      /
2      0.0D0,1.0D0/
C*****
C INVERT A REAL 3x3 MATRIX
C*****
  DETS=S(1,1)*S(2,2)*S(3,3)+S(1,2)*S(2,3)*S(3,1)+
1      S(1,3)*S(2,1)*S(3,2)-S(1,2)*S(2,1)*S(3,3)-
2      S(1,1)*S(2,3)*S(3,2)-S(1,3)*S(2,2)*S(3,1)
  IF(DETS.EQ.R0)CALL ERRPRT('EE0011')
C
  DETSIN=R1/DETS
  SINV(1,1)=+DETSIN*(S(2,2)*S(3,3)-S(2,3)*S(3,2))
  SINV(2,1)=-DETSIN*(S(2,1)*S(3,3)-S(2,3)*S(3,1))
  SINV(3,1)=+DETSIN*(S(2,1)*S(3,2)-S(2,2)*S(3,1))
  SINV(1,2)=-DETSIN*(S(1,2)*S(3,3)-S(1,3)*S(3,2))
  SINV(2,2)=+DETSIN*(S(1,1)*S(3,3)-S(1,3)*S(3,1))
  SINV(3,2)=-DETSIN*(S(1,1)*S(3,2)-S(1,2)*S(3,1))
  SINV(1,3)=+DETSIN*(S(1,2)*S(2,3)-S(1,3)*S(2,2))
  SINV(2,3)=-DETSIN*(S(1,1)*S(2,3)-S(1,3)*S(2,1))
  SINV(3,3)=+DETSIN*(S(1,1)*S(2,2)-S(1,2)*S(2,1))
C
  RETURN
END

```

```

      SUBROUTINE ISO2
1(      FUNC      ,OUTOFP      ,X      ,Y      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(      MCOMP=4      ,NDIM=2      )
      LOGICAL OUTOFP ,REPEAT
      DIMENSION
1      X(*)      ,Y(*)
      DIMENSION
1      EIGPRJ(MCOMP,NDIM)      ,EIGX(NDIM)      ,
1      EIGY(NDIM)
C*****
C COMPUTE THE TENSOR Y (STORED IN VECTOR FORM) AS AN ISOTROPIC
C FUNCTION OF THE TYPE:
C
C          Y(X) = sum{ y(x_i) E_i }
C
C WHERE Y AND X ARE SYMMETRIC TENSORS, x_i AND E_i ARE, RESPECTIVELY
C THE EIGENVALUES AND EIGENPROJECTIONS OF X, AND y(.) IS A SCALAR
C FUNCTION. THIS ROUTINE IS RESTRICTED TO 2-D TENSORS WITH ONE
C POSSIBLE (TRANSVERSAL) OUT-OF-PLANE COMPONENT.
C
C REFERENCE: Section A.5
C*****
C Performs the spectral decomposition of X
      CALL SPDEC2
1(      EIGPRJ      ,EIGX      ,REPEAT      ,X      )
C Computes the in-plane eigenvalues of Y
      DO 10 IDIR=1,2
          EIGY(IDIR)=FUNC(EIGX(IDIR))
10 CONTINUE
C Assembles in-plane component of Y (in vector form)
      CALL RVZERO(Y,3)
      DO 30 ICOMP=1,3
          DO 20 IDIR=1,2
              Y(ICOMP)=Y(ICOMP)+EIGY(IDIR)*EIGPRJ(ICOMP,IDIR)
20 CONTINUE
30 CONTINUE
C Out-of-plane component required
      IF(OUTOFP)Y(4)=FUNC(X(4))
C
      RETURN
      END

```

```
      SUBROUTINE IVZERO
1(      IV      ,N      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION IV(N)
C*****
C INITIALISES TO ZERO AN INTEGER ARRAY OF DIMENSION N
C*****
      DO 10 I=1,N
          IV(I)=0
10 CONTINUE
      RETURN
      END
```

```

SUBROUTINE JACOB(A,D,V,N)
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER (MJITER=50,NMAX=100)
DIMENSION
1  A(N,N) ,D(N) ,V(N,N)
DIMENSION
1  B(NMAX) ,Z(NMAX)
DATA R0 ,RP2 ,RP5 ,R1 ,R100 /
1  0.0D0,0.2D0,0.5D0,1.0D0,100.0D0/
DATA TOLER /
1  1.0D-12/
C*****
C JACOBI ITERATIVE PROCEDURE FOR SPECTRAL DECOMPOSITION OF A
C N-DIMENSIONAL SYMMETRIC MATRIX
C
C REFERENCE: WH Press, SA Teukolsky, WT Vetting & BP Flannery. Numerical
C recipes in FORTRAN: The art of scientific computing. 2nd
C Edn., Cambridge University Press, 1992.
C*****
IF(N.GT.NMAX)THEN
CALL ERRPR('EI0025')
ENDIF
DO 20 IP=1,N
DO 10 IQ=1,N
V(IP,IQ)=R0
10 CONTINUE
V(IP,IP)=R1
20 CONTINUE
DO 30 IP=1,N
B(IP)=A(IP,IP)
D(IP)=B(IP)
Z(IP)=R0
30 CONTINUE
DO 130 I=1,MJITER
SM=R0
DO 50 IP=1,N-1
DO 40 IQ=IP+1,N
SM=SM+ABS(A(IP,IQ))
40 CONTINUE
50 CONTINUE
IF(SM.LT.TOLER)GOTO 999
IF(I.LT.4)THEN
TRESH=RP2*SM/DBLE(N**2)
ELSE
TRESH=R0
ENDIF
DO 110 IP=1,N-1
DO 100 IQ=IP+1,N
G=R100*ABS(A(IP,IQ))
IF((I.GT.4).AND.(ABS(D(IP))+G.EQ.ABS(D(IP))))
1 .AND.(ABS(D(IQ))+G.EQ.ABS(D(IQ))))THEN
A(IP,IQ)=R0
ELSE IF(ABS(A(IP,IQ)).GT.TRESH)THEN
H=D(IQ)-D(IP)
IF(ABS(H)+G.EQ.ABS(H))THEN
T=A(IP,IQ)/H
ELSE
THETA=RP5*H/A(IP,IQ)
T=R1/(ABS(THETA)+SQRT(R1+THETA**2))
IF(THETA.LT.R0)T=-T
ENDIF
C=R1/SQRT(R1+T**2)
S=T*C
TAU=S/(R1+C)
H=T*A(IP,IQ)
Z(IP)=Z(IP)-H
Z(IQ)=Z(IQ)+H
D(IP)=D(IP)-H
D(IQ)=D(IQ)+H
A(IP,IQ)=R0
DO 60 J=1,IP-1
G=A(J,IP)
H=A(J,IQ)
A(J,IP)=G-S*(H+G*TAU)
A(J,IQ)=H+S*(G-H*TAU)
60 CONTINUE
DO 70 J=IP+1,IQ-1
G=A(IP,J)
H=A(J,IQ)
A(IP,J)=G-S*(H+G*TAU)
A(J,IQ)=H+S*(G-H*TAU)
70 CONTINUE
DO 80 J=IQ+1,N
G=A(IP,J)
H=A(IQ,J)
A(IP,J)=G-S*(H+G*TAU)
A(IQ,J)=H+S*(G-H*TAU)
80 CONTINUE
DO 90 J=1,N
G=V(J,IP)
H=V(J,IQ)
V(J,IP)=G-S*(H+G*TAU)
V(J,IQ)=H+S*(G-H*TAU)
90 CONTINUE
ENDIF
100 CONTINUE
110 CONTINUE
DO 120 IP=1,N

```



```
        B(IP)=B(IP)+Z(IP)
        D(IP)=B(IP)
        Z(IP)=R0
120    CONTINUE
130    CONTINUE
      CALL ERRPRT('EE0005')
999    CONTINUE
      RETURN
      END
```

```

      SUBROUTINE JACOB2
1(   CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
2   MDIME      ,NDIME      ,NNODE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1   CARTD(MDIME,*)      ,DERIV(MDIME,*)      ,ELCOD(MDIME,*)
      DIMENSION
1   XJACI(2,2)      ,XJACM(2,2)
      DATA R0
1   0.0D0/
C*****
C EVALUATES THE JACOBIAN MATRIX, ITS DETERMINANT AND THE CARTESIAN
C DERIVATIVES OF THE SHAPE FUNCTIONS OF 2-D ISOPARAMETRIC ELEMENTS
C
C REFERENCE: Section 4.1.2
C           Expression (4.33)
C*****
1000 FORMAT(' Warning from subroutine JACOB2: '//
1 10X,'Negative jacobian determinant ',G12.4,' Element number ',I5)
1010 FORMAT(' Warning from subroutine JACOB2: '//
1 10X,'Zero jacobian determinant ',I2X,' Element number ',I5/
2 10X,'Jacobian matrix not inverted and cartesian derivatives ',/,
3 10X,'of shape functions not computed')
C
C Evaluate jacobian matrix XJACM
C -----
C
      DO 30 IDIME=1,NDIME
      DO 20 JDIME=1,NDIME
      XJACM(IDIME,JDIME)=R0
      DO 10 INODE=1,NNODE
      XJACM(IDIME,JDIME)=XJACM(IDIME,JDIME)+DERIV(IDIME,INODE)*
1      ELCOD(JDIME,INODE)
10   CONTINUE
20   CONTINUE
30   CONTINUE
C Determinant of jacobian matrix
      DETJAC=XJACM(1,1)*XJACM(2,2)-XJACM(1,2)*XJACM(2,1)
      IF(DETJAC.LT.R0)THEN
      WRITE(*,1000)DETJAC,IELEM
      WRITE(16,1000)DETJAC,IELEM
      ELSEIF(DETJAC.EQ.R0)THEN
      WRITE(*,1010)IELEM
      WRITE(16,1010)IELEM
      GOTO 999
      ENDIF
C Inverse of jacobian matrix
      XJACI(1,1)=XJACM(2,2)/DETJAC
      XJACI(2,2)=XJACM(1,1)/DETJAC
      XJACI(1,2)=-XJACM(1,2)/DETJAC
      XJACI(2,1)=-XJACM(2,1)/DETJAC
C
C Evaluate cartesian derivatives of shape functions
C -----
C
      DO 60 IDIME=1,NDIME
      DO 50 INODE=1,NNODE
      CARTD(IDIME,INODE)=R0
      DO 40 JDIME=1,NDIME
      CARTD(IDIME,INODE)=CARTD(IDIME,INODE)+XJACI(IDIME,JDIME)*
1      DERIV(JDIME,INODE)
40   CONTINUE
50   CONTINUE
60   CONTINUE
999  CONTINUE
      RETURN
      END

```

```

      SUBROUTINE LEFTCG
      1( BN ,BNP1 ,FINCR ,NTYPE )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
      1 BN(*) ,BNP1(*) ,FINCR(3,3)
      DIMENSION
      1 AUXM(2,2) ,BNMTX(2,2) ,BNP1M(2,2)
C*****
C COMPUTES THE LEFT CAUCHY-GREEN STRAIN TENSOR ACCORDING TO THE
C FORMULA:
C
C
C
C
C

$$B_{n+1} := F^T B F$$

C REFERENCE: Box 13.1. The formula used here is equivalent to that of
C item (i) of Box 13.1.
C*****
C Convert previously converged left Cauchy-Green strain tensor from
C vector form to matrix form
      BNMIX(1,1)=BN(1)
      BNMIX(2,1)=BN(3)
      BNMIX(1,2)=BN(3)
      BNMIX(2,2)=BN(2)
C
C In-plane components of the left Cauchy-Green tensor
C
      CALL RVZERO(AUXM,4)
      DO 30 I=1,2
        DO 20 J=1,2
          DO 10 K=1,2
            AUXM(I,J)=AUXM(I,J)+FINCR(I,K)*BNMTX(K,J)
          10 CONTINUE
        20 CONTINUE
      30 CONTINUE
      CALL RVZERO(BNP1M,4)
      DO 60 I=1,2
        DO 50 J=1,2
          DO 40 K=1,2
            BNP1M(I,J)=BNP1M(I,J)+AUXM(I,K)*FINCR(J,K)
          40 CONTINUE
        50 CONTINUE
      60 CONTINUE
C
C Store B in vector form
C
      n+1
      BNP1(1)=BNP1M(1,1)
      BNP1(2)=BNP1M(2,2)
      BNP1(3)=BNP1M(1,2)
C out-of-plane component
      IF(NTYPE.EQ.2)THEN
        BNP1(4)=BN(4)
      ELSEIF(NTYPE.EQ.3)THEN
        BNP1(4)=BN(4)*FINCR(3,3)*FINCR(3,3)
      ENDIF
C
      RETURN
      END

```

```

      SUBROUTINE LENGTH(DLENG ,DLENM ,ITACT ,ITDES )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C*****
C ADJUSTS STEP LENGTH ACCORDING TO THE DESIRED NUMBER OF ITERATIONS AND
C THE NUMBER OF ITERATIONS REQUIRED FOR CONVERGENCE IN THE PREVIOUS
C LOAD STEP (USED FOR ARC-LENGTH METHOD ONLY)
C
C REFERENCE: Expression (5.3)
C*****
      DLENG=DLENG*DBLE(ITDES)/DBLE(ITACT)
      DLENG=MIN(DLENG,DLENM)
      RETURN
      END

```

```

      SUBROUTINE LISTRA
1(      BMATX      ,ELDISP      ,MDOFN      ,MBDIM      ,NDOFN      ,
2      NNODE      ,NTYPE      ,STRAN      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1      BMATX(MBDIM,*)      ,ELDISP(MDOFN,*)      ,STRAN(*)
C*****
C COMPUTES THE SYMMETRIC GRADIENT (LINEAR STRAIN MEASURE) ASSOCIATED
C WITH THE ELEMENT DISPLACEMENT 'ELDISP' IN 2-D: PLANE STRAIN, PLANE
C STRESS AND AXISYMMETRIC PROBLEMS
C
C REFERENCE: Expression (4.53)
C*****
      IF(NTYPE.EQ.1)THEN
        NSTRE=3
        NBDIM=3
      ELSEIF(NTYPE.EQ.2)THEN
        NSTRE=4
        NBDIM=3
      ELSEIF(NTYPE.EQ.3)THEN
        NSTRE=4
        NBDIM=4
      ELSE
        CALL ERRPRT('EI0023')
      ENDIF
C
      CALL RVZERO(STRAN,NSTRE)
      DO 30 ISTR=1,NBDIM
        IEVAB=0
        DO 20 INODE=1,NNODE
          DO 10 IDOFN=1,NDOFN
            IEVAB=IEVAB+1
            STRAN(ISTR)=STRAN(ISTR)+
1            BMATX(ISTR,IEVAB)*ELDISP(IDOFN,INODE)
10          CONTINUE
20        CONTINUE
30      CONTINUE
      RETURN
      END

```

```

SUBROUTINE LOGSTR
1( B ,E ,NTYPE )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
EXTERNAL DLGD2
LOGICAL OUTOFP
DIMENSION
1 B(*) ,E(*)
DATA R2 /2.0D0/
C*****
C COMPUTES THE LOGARITHMIC STRAIN TENSOR:
C
C      E := 1/2 ln[ B ]
C
C REFERENCE: Box 14.3, item (ii)
C*****
IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
OUTOFP=.TRUE.
ELSEIF(NTYPE.EQ.1)THEN
OUTOFP=.FALSE.
ELSE
CALL ERRPR('EI0022')
ENDIF
C
C Use isotropic tensor function to compute the logarithmic (physical)
C strain components
C
CALL ISO2
1( DLGD2 ,OUTOFP ,B ,E )
C
C Convert physical components into engineering strain components
C
E(3)=R2*E(3)
C
RETURN
END

```

```

SUBROUTINE MATICT
1( DETF ,KUNLD ,MBDIM ,MGDIM ,
2 NLARGE ,NTYPE ,
3 AMATX ,DMATX ,EINCR ,FINCR ,IPROPS ,
4 LALGVA ,RALGVA ,RPROPS ,RSTAVA ,RSTAV2 ,
5 STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
INCLUDE '../MATERIAL.INC'

C
PARAMETER( MSTR=4 )
C Arguments
LOGICAL LALGVA
DIMENSION
1 AMATX(MGDIM,MGDIM) ,DMATX(MBDIM,MBDIM) ,EINCR(MBDIM) ,
2 FINCR(3,3) ,IPROPS(*) ,LALGVA(*) ,
3 RALGVA(*) ,RPROPS(*) ,RSTAVA(*) ,
4 RSTAV2(*) ,STRES(*)
C Local arrays and variables
LOGICAL EPFLAG ,IFPLAS
DIMENSION
1 BETRL(MSTR) ,STRAT(MSTR) ,STRESK(4)
C*****
C MATERIAL INTERFACE FOR CONSISTENT TANGENT COMPUTATION ROUTINE CALLS:
C ACCORDING TO THE MATERIAL TYPE, CALLS MATERIAL-SPECIFIC TANGENT
C COMPUTATION ROUTINE
C
C REFERENCE: Figure 5.5
C Sections 5.7.4, 5.7.6
C*****
C Start by identifying the material type and class
MATTP=IPROPS(1)
MATCLS=IPROPS(2)

C
C Then call material class/type-specific routines
C
IF(MATCLS.EQ.HYPEPL)THEN
C
C Elastic/elasto-plastic materials with logarithmic finite strain
C extension
C =====
C
C Retrieve current stress
DO 50 ISTRE=1,4
STRESK(ISTRE)=STRES(ISTRE)
50 CONTINUE
IF(NLARGE.EQ.1)THEN
C Large strains: compute last elastic trial LOGARITHMIC strain
C -----
C elastic trial left Cauchy-Green tensor
CALL BETRIA
1( BETRL ,RSTAV2 ,FINCR ,NTYPE )
C elastic trial eulerian logarithmic strain
CALL LOGSTR
1( BETRL ,STRAT ,NTYPE )
DETFT=DETF
IF(NTYPE.EQ.1)THEN
C compute total deformation gradient (including thickness strain
C contribution) for plane stress, according to material model
IF(MATTP.EQ.ELASTC)THEN
C... Elastic (Hencky material in large strain)
CALL TUEL
1( DETFT ,RSTAVA ,DUMMY ,0 )
ELSEIF(MATTP.EQ.VMISES)THEN
C... von Mises elasto-plastic
CALL TUVM
1( DETFT ,RSTAVA ,DUMMY ,0 )
ELSE
C... Error: Material type not recognised or not implemented for finite
C strains under plane stress
CALL ERRPR('EI0059')
ENDIF
ENDIF
C retrieve current KIRCHHOFF stress in large strains
CALL RVSCAL(STRESK,4,DETFT)
ELSE
C Small strains: compute last elastic trial INFINITESIMAL strain
C -----
DO 60 ISTRE=1,4
STRA(ISTRE)=RSTAV2(ISTRE)+EINCR(ISTRE)
60 CONTINUE
ENDIF
C Set plastic elasto-plastic tangent flag
C -----
IF(MATTP.NE.ELASTC)THEN
IFPLAS=LALGVA(1)
IF((.NOT.IFPLAS).OR.KUNLD.EQ.1)THEN
EPFLAG=.FALSE.
ELSE
EPFLAG=.TRUE.
ENDIF
ENDIF
C Call material type-specific routines
C -----
IF(MATTP.EQ.ELASTC)THEN
C Elastic
CALL CTEL
1( DMATX ,NTYPE ,RPROPS )

```

```

      ELSEIF(MATTYP.EQ.TRESCA)THEN
C Tresca
      IF(NTYPE.EQ.1)THEN
        CALL CTTRPN
1(   DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,RPROPS      ,
2     RSTAVA      ,STRAT      ,STRESK      )
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        CALL CTTR
1(   DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,NTYPE      ,
2     RPROPS      ,RSTAVA      ,STRAT      ,STRESK      )
      ENDIF
      ELSEIF(MATTYP.EQ.VMISES)THEN
C von Mises
      IF(NTYPE.EQ.1)THEN
        CALL CTVMPS
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,NTYPE      ,
2     RPROPS      ,RSTAVA      ,STRESK      )
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        CALL CTVM
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,NTYPE      ,
2     RPROPS      ,RSTAVA      ,STRESK      )
      ENDIF
      ELSEIF(MATTYP.EQ.MOHCOU)THEN
C Mohr-Coulomb
      CALL CTMC
1(   DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,NTYPE      ,
2     RPROPS      ,RSTAVA      ,STRAT      ,STRESK      )
      ELSEIF(MATTYP.EQ.DRUPRA)THEN
C Drucker-Prager
      IF(NTYPE.EQ.1)THEN
        CALL CTDPN
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,
2     NTYPE      ,RPROPS      ,RSTAVA      ,STRAT      )
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        CALL CTDP
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,
2     NTYPE      ,RPROPS      ,RSTAVA      ,STRAT      )
      ENDIF
      ELSEIF(MATTYP.EQ.LEMDAM)THEN
C Lemaitre's ductile damage model
      CALL CTDAMA
1(   RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,NTYPE      ,
2     RPROPS      ,RSTAVA      ,STRESK      )
      ELSEIF(MATTYP.EQ.DAMELA)THEN
C Isotropically damaged isotropic elastic material with crack closure
C effects
      CALL CTDMEL
1(   DMATX      ,NTYPE      ,RPROPS      ,STRAT      ,STRESK      )
      ELSE
C Error: Material type not recognised
      CALL ERRPRT('EI0044')
      ENDIF
C Perform extra kinematical operations required by materials of this
C class at large strains for computation of the spatial modulus 'a'
C -----
      IF(NLARGE.EQ.1)THEN
        CALL CSTEP2
1(   AMATX      ,BETRL      ,DMATX      ,STRES      ,DETFT      ,
2     NTYPE      )
      ENDIF
      ELSEIF(MATCLS.EQ.SINCRY)THEN
C
C Single crystal anisotropic elasto-plastic models
C =====
C
C Set plastic loading/unloading flag
      IFPLAS=LALGVA(1)
      IF((.NOT.IFPLAS).OR.KUNLD.EQ.1)THEN
        EPFLAG=.FALSE.
      ELSE
        EPFLAG=.TRUE.
      ENDIF
C Call material type-specific routines
C -----
      IF(MATTYP.EQ.PDSCRY)THEN
C Planar double slip single crystal
      CALL CSTPDS
1(   AMATX      ,RALGVA      ,EPFLAG      ,FINCR      ,IPROPS      ,
2     LALGVA      ,NTYPE      ,RPROPS      ,RSTAVA      ,RSTAV2      ,
3     STRES      )
      ELSE
C... Error: Material type not recognised
      CALL ERRPRT('EI0044')
      ENDIF
      ELSEIF(MATCLS.EQ.HYPER)THEN
C
C Generic isotropic finite hyperelasticity models
C =====
C
C Call material type-specific routines
C -----
      IF(MATTYP.EQ.OGDEN)THEN
C Ogden model
      CALL CSTOGD
1(   AMATX      ,RSTAVA      ,IPROPS      ,NTYPE      ,RPROPS      ,
2     STRES      )
      ELSE
C Error: Material type not recognised

```



```

        CALL ERRPRT('EI0044')
    ENDIF
ELSEIF(MATCLS.EQ.PLASTC)THEN
C
C Elasto-plastic materials with small strain implementation only
C =====
C
        IFPLAS=LALGVA(1)
        IF((.NOT.IFPLAS).OR.KUNLD.EQ.1)THEN
            EPFLAG=.FALSE.
        ELSE
            EPFLAG=.TRUE.
        ENDIF
        IF(MATTYP.EQ.VMMIXD)THEN
C von Mises with mixed isotropic/kinematic hardening
            CALL CTVMMX
            1( RALGVA      ,DMATX      ,EPFLAG      ,IPROPS      ,NTYPE      ,
            2  RPROPS     ,RSTAVA     ,RSTAV2      ,STRES       )
        ELSE
C Error: Material type not recognised
            CALL ERRPRT('EI0044')
        ENDIF
    ELSE
C Error: Material class not recognised
        CALL ERRPRT('EI0043')
    ENDIF
C
    RETURN
END

```

```

      SUBROUTINE MATIOR
1(      NTYPE      ,IPROPS      ,RALGVA      ,RPROPS      ,RSTAVA      ,
2      STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      INCLUDE ' ../MATERIAL.INC'
C Arguments
      DIMENSION
1      IPROPS(*)      ,RALGVA(*)      ,RPROPS(*)      ,
2      RSTAVA(*)      ,STRES(*)
C*****
C MATERIAL INTERFACE FOR OUTPUT RESULT ROUTINE CALLS:
C ACCORDING TO THE MATERIAL TYPE, CALLS MATERIAL-SPECIFIC OUTPUT
C ROUTINE
C
C REFERENCE: Sections 5.7.5-6
C*****
C First identify material type
C -----
      MATTYP=IPROPS(1)
C Then call corresponding routine to output material-specific results
C -----
      IF(MATTYP.EQ.ELASTC)THEN
C Elastic
      CALL OREL(16      ,NTYPE      ,STRES      )
      ELSEIF(MATTYP.EQ.TRESCA)THEN
C Tresca
      CALL ORTR(RALGVA      ,16      ,NTYPE      ,RSTAVA      ,STRES      )
      ELSEIF(MATTYP.EQ.VMISES)THEN
C von Mises
      CALL ORVM(RALGVA      ,16      ,NTYPE      ,RSTAVA      ,STRES      )
      ELSEIF(MATTYP.EQ.MOHCOU)THEN
C Mohr-Coulomb
      CALL ORMC(RALGVA      ,16      ,NTYPE      ,RSTAVA      ,STRES      )
      ELSEIF(MATTYP.EQ.DRUPRA)THEN
C Drucker-Prager
      CALL ORDP(RALGVA      ,16      ,NTYPE      ,RSTAVA      ,STRES      )
      ELSEIF(MATTYP.EQ.LEMDAM)THEN
C Lemaitre's ductile damage model
      CALL ORDAMA(RALGVA      ,16      ,NTYPE      ,RSTAVA      ,STRES      )
      ELSEIF(MATTYP.EQ.DAMELA)THEN
C Isotropically damaged isotropic elastic material with crack closure
C effects
      CALL ORDMEL(16      ,NTYPE      ,STRES      )
      ELSEIF(MATTYP.EQ.OGDEN)THEN
C Ogden hyperelastic
      CALL OROGD(16      ,NTYPE      ,STRES      )
      ELSEIF(MATTYP.EQ.PDSCRY)THEN
C Planar double-slip single crystal plasticity model
      CALL ORPDSC(RALGVA,16      ,NTYPE      ,RPROPS      ,RSTAVA      ,STRES      )
      ELSEIF(MATTYP.EQ.VMMIXD)THEN
C von Mises with mixed isotropic/kinematic hardening (infinitesimal
C only)
      CALL ORVMMX(RALGVA,16      ,NTYPE      ,RSTAVA      ,STRES      )
      ELSE
C Error: Material type not recognised
      CALL ERRPRT('EI0045')
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE MATIRD
      1( MATNAM ,NLARGE ,NTYPE ,UNSAUX ,IPROPS ,
      2 RPROPS )
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE '../MATERIAL.INC'
C Arguments
      LOGICAL UNSAUX
      CHARACTER*80 MATNAM
      DIMENSION
      1 IPROPS(*) ,RPROPS(*)
C*****
C MATERIAL INTERFACE FOR READING MATERIAL-SPECIFIC INPUT DATA
C
C REFERENCE: Sections 5.7.1, 5.7.6
C*****
C According to MATNAM, call the appropriate routine to read the
C the material-specific data from the input file and store it
C -----
      IF(MATNAM.EQ.'ELASTIC')THEN
C Elastic
      MATTYP=ELASTC
      MATCLS=HYPEPL
      CALL RDEL
      1( MRPROP ,MRSTAV ,RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'TRESCA')THEN
C Tresca elasto-plastic
      MATTYP=TRESCA
      MATCLS=HYPEPL
      CALL RDTR
      1( IPROPS ,MIPROP ,MLALGV ,MRALGV ,MRPROP ,MRSTAV ,
      2 NLARGE ,NTYPE ,RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'VON_MISES')THEN
C von Mises elasto-plastic
      MATTYP=VMISES
      MATCLS=HYPEPL
      CALL RDVM
      1( IPROPS ,MIPROP ,MLALGV ,MRPROP ,MRSTAV ,
      2 RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'MOHR-COULOMB')THEN
C Mohr-Coulomb elasto-plastic
      MATTYP=MOHCOU
      MATCLS=HYPEPL
      CALL RDMC
      1( IPROPS ,MIPROP ,MLALGV ,MRALGV ,MRPROP ,MRSTAV ,
      2 RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'DRUCKER_PRAGER')THEN
C Drucker-Prager elasto-plastic
      MATTYP=DRUPRA
      MATCLS=HYPEPL
      CALL RDDP
      1( IPROPS ,MIPROP ,MLALGV ,MRALGV ,MRPROP ,MRSTAV ,
      2 RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'LEMAITRE_DAMAGE')THEN
C Lemaitre's ductile damage model
      MATTYP=LEMDAM
      MATCLS=HYPEPL
      CALL RDDAMA
      1( IPROPS ,MIPROP ,MLALGV ,MRPROP ,MRSTAV ,NTYPE ,
      2 RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'DAMAGED_ELASTIC')THEN
C Isotropically damaged isotropic elastic material with crack closure
C effects
      MATTYP=DAMELA
      MATCLS=HYPEPL
      CALL RDDMEL
      1( NTYPE ,MRPROP ,MRSTAV ,RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'OGDEN')THEN
C Ogden hyperelastic
      MATTYP=OGDEN
      MATCLS=HYPER
      CALL RDOGD
      1( IPROPS ,MIPROP ,MRPROP ,MRSTAV ,RPROPS ,UNSAUX)
      ELSEIF(MATNAM.EQ.'PLANAR_DOUBLE_SLIP_SINGLE_CRYSTAL')THEN
C Planar double-slip single crystal elasto-plastic model
      MATTYP=PDSCRY
      MATCLS=SINCRY
      CALL RDPDSC
      1( IPROPS ,MIPROP ,MLALGV ,MRALGV ,MRPROP ,MRSTAV ,
      2 NLARGE ,NTYPE ,RPROPS ,UNSAUX )
      ELSEIF(MATNAM.EQ.'VON_MISES_MIXED')THEN
C von Mises elasto-plastic with mixed hardening (small strains only)
      MATTYP=VMMIXD
      MATCLS=PLASTC
      CALL RDVMMX
      1( IPROPS ,MIPROP ,MLALGV ,MRPROP ,MRSTAV ,
      2 NLARGE ,NTYPE ,RPROPS ,UNSAUX )
      ELSE
      CALL ERRPRT('ED0015')
      ENDIF
C Store material type and class flags in IPROPS
C -----
      IPROPS(1)=MATTYP
      IPROPS(2)=MATCLS
C
      RETURN
      END

```



```

SUBROUTINE MATISU
1( DETF ,NLARGE ,NTYPE ,SUFALL ,THKGP ,
3 EINCR ,FINCR ,IPROPS ,LALGVA ,RALGVA ,
4 RPROPS ,RSTAVA ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
INCLUDE '../MATERIAL.INC'

C
PARAMETER( MSTR=4 )

C Arguments
LOGICAL
1 SUFAIL ,LALGVA
1 DIMENSION
1 EINCR(*) ,FINCR(3,3) ,IPROPS(*) ,
2 LALGVA(*) ,RALGVA(*) ,RPROPS(*) ,
3 RSTAVA(*) ,STRES(*)

C Local arrays
1 DIMENSION
1 B(MSTR) ,BETRL(MSTR) ,STRAT(MSTR)

C Local numerical constants
DATA
1 R1 /
2 1.0D0/

C*****
C MATERIAL INTERFACE FOR STATE UPDATE ROUTINE CALLS:
C ACCORDING TO THE MATERIAL TYPE, CALLS MATERIAL-SPECIFIC STATE UPDATE
C ROUTINE TO UPDATE STRESS AND OTHER STATE VARIABLES
C
C REFERENCE: Figure 5.4
C Sections 5.7.2, 5.7.6
C*****
C Set up number of stress components
IF(NTYPE.EQ.1)THEN
NSTRE=3
ELSEIF(NTYPE.EQ.2)THEN
NSTRE=4
ELSEIF(NTYPE.EQ.3)THEN
NSTRE=4
ELSE
CALL ERRPRT('EI0040')
ENDIF
C Identify material type and class
MATTP=IPROPS(1)
MATCLS=IPROPS(2)

C
C Then call material class/type-specific routines
C
IF(MATCLS.EQ.HYPEPL)THEN
C
C Isotropic elastic/elasto-plastic materials with logarithmic finite
C strain extension
C =====
C
C Compute elastic trial strains. Note that for the purely elastic models
C the elastic trial strain equals the total strain
C -----
IF(NLARGE.EQ.0)THEN
C Small strains: compute elastic trial INFINITESIMAL strain
DO 10 ISTR=1,NSTRE
STRAT(ISTR)=RSTAVA(ISTR)+EINCR(ISTR)
10 CONTINUE
ELSEIF(NLARGE.EQ.1)THEN
C Large strains: compute elastic trial LOGARITHMIC strain
C... elastic trial left Cauchy-Green tensor
CALL BETRIA
1( BETRL ,RSTAVA ,FINCR ,NTYPE )
C... elastic trial eulerian logarithmic strain
CALL LOGSTR
1( BETRL ,STRAT ,NTYPE )
ENDIF
C Apply small strain material type-specific state updating procedure
C -----
IF(MATTP.EQ.ELASTC)THEN
C Linear elastic (Hencky material in large strains)
CALL SUEL
1( NTYPE ,RPROPS ,RSTAVA ,STRAT ,STRES )
C...set elasto-plastic flag and state update failure flag
LALGVA(1)=.FALSE.
LALGVA(2)=.FALSE.
ELSEIF(MATTP.EQ.TRESCA)THEN
C Tresca elasto-plastic
IF(NTYPE.EQ.1)THEN
CALL SUTRPN
1( RALGVA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
CALL SUTR
1( RALGVA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
ENDIF
ELSEIF(MATTP.EQ.VMISES)THEN
C von Mises elasto-plastic
IF(NTYPE.EQ.1)THEN
CALL SUVMPS
1( RALGVA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
CALL SUVM

```

```

1(   RALGVA      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT       ,STRES       )
ENDIF
ELSEIF(MATTYP.EQ.MOHCOU)THEN
C Mohr-Coulomb elasto-plastic
CALL SUMC
1(   RALGVA      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT       ,STRES       )
ELSEIF(MATTYP.EQ.DRUPRA)THEN
C Drucker-Prager elasto-plastic
IF(NTYPE.EQ.1)THEN
CALL SUDDPN
1(   RALGVA      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT       ,STRES       )
ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
CALL SUDDP
1(   RALGVA      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT       ,STRES       )
ENDIF
ELSEIF(MATTYP.EQ.LEMDAM)THEN
C Lemaitre's ductile damage elasto-plastic model
CALL SUDAMA
1(   RALGVA      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT       ,STRES       )
ELSEIF(MATTYP.EQ.DAMELA)THEN
C Isotropically damaged isotropic elastic material with crack closure
C effects
CALL SUDMEL
1(   NTYPE      ,RPROPS      ,RSTAVA      ,STRAT       ,STRES       ,
2   LALGVA(2)   )
C...set elasto-plastic flag to false
LALGVA(1)=.FALSE.
ELSE
C Error: Material type not recognised
CALL ERRPRT('EI0042')
ENDIF
C Exit routine in case of failure of the state update procedure
SUFAIL=LALGVA(2)
IF(SUFAIL)GOTO 999
IF(NLARGE.EQ.1)THEN
C Perform extra updating operations required by this class of
C elasto-pastic materials at large strains only
C -----
DETFT=DETF
IF(NTYPE.EQ.1)THEN
C Plane stress: update Gauss point thickness according to material
C model. Also update the total deformation gradient (taking the
C thickness strain into account)
IF(MATTYP.EQ.ELASTC)THEN
C... Elastic (Hencky material in large strains)
CALL TUEL
1(   DETFT      ,RSTAVA      ,THKGP      ,1           )
ELSEIF(MATTYP.EQ.VMISES)THEN
C... von Mises elasto-plastic
CALL TUVM
1(   DETFT      ,RSTAVA      ,THKGP      ,1           )
ELSE
C... Error: Material type not recognised or not implemented for finite
C strains under plane stress
CALL ERRPRT('EI0058')
ENDIF
ENDIF
C Transform Kirchhoff into Cauchy stress
DETFIN=R1/DETF
CALL RVSCAL(STRES,NSTRE,DETFIN)
ENDIF
C
ELSEIF(MATCLS.EQ.SINCRY)THEN
C
C Single crystal anisotropic finite elasto-plastic models
C =====
C
IF(MATTYP.EQ.PDSCRY)THEN
C Planar double slip single crystal
CALL SUPDSC
1(   RALGVA      ,FINCR      ,IPROPS      ,LALGVA      ,NTYPE      ,
2   RPROPS      ,RSTAVA      ,STRES       )
ELSE
C Error: Material type not recognised
CALL ERRPRT('EI0042')
ENDIF
SUFAIL=LALGVA(2)
IF(SUFAIL)GOTO 999
ELSEIF(MATCLS.EQ.HYPER)THEN
C
C Generic isotropic finite hyperelasticity models
C =====
C
C First compute current Left Cauchy-Green strain tensor, B
CALL LEFTCG
1(   RSTAVA      ,B          ,FINCR      ,NTYPE      )
C Then call the material type-specific state update procedure
IF(MATTYP.EQ.OGDEN)THEN
C Ogden model
CALL SUOGD
1(   B          ,IPROPS      ,NTYPE      ,RPROPS      ,RSTAVA      ,
2   STRES       ,THKGP      )
SUFAIL=.FALSE.

```

```

ELSE
C Error: Material type not recognised
  CALL ERRPRT('EI0042')
ENDIF
ELSEIF(MATCLS.EQ.PLASTC)THEN
C
C Elasto-plastic materials with small strain implementation only
C =====
C
C compute elastic trial INFINITESIMAL strain
  DO 20 ISTRE=1,NSTRE
    STRAT(ISTRE)=RSTAVA(ISTRE)+EINCR(ISTRE)
  20  CONTINUE
  IF(MATTYP.EQ.VMMIXD)THEN
C von Mises with mixed isotropic/kinematic hardening
    CALL SUVVMX
      1( RALGVA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
      2  RSTAVA ,STRAT ,STRES )
  ELSE
C Error: Material type not recognised
    CALL ERRPRT('EI0042')
  ENDIF
  SUFAIL=LALGVA(2)
  IF(SUFAIL)GOTO 999
ELSE
C Error: Material class not recognised
  CALL ERRPRT('EI0041')
ENDIF
999 CONTINUE
RETURN
END

```

```

      SUBROUTINE MATISW
1(   MODE      ,NLARGE      ,NTYPE      ,IPROPS      ,LALGVC      ,
2   LALGVL      ,RALGVC      ,RALGVL      ,RPROPS      ,RSTAVC      ,
3   RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      INCLUDE './MATERIAL.INC'
C Arguments
      LOGICAL
1   LALGVC      ,LALGVL
      DIMENSION
1   IPROPS(*)      ,LALGVC(*)      ,LALGVL(*)      ,
2   RALGVC(*)      ,RALGVL(*)      ,RPROPS(*)      ,
3   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
4   STRESL(*)
C*****
C MATERIAL INTERFACE FOR INITIALISATION/SWITCHING ROUTINE CALLS:
C ACCORDING TO THE MATERIAL TYPE, CALLS MATERIAL-SPECIFIC ROUTINE TO
C INITIALISE/SWITCH GAUSS POINT STATE AND ALGORITHMIC VARIABLES
C
C REFERENCE: Sections 5.7.3, 5.7.6
C*****
C First identify material type and class
C -----
      MATTYP=IPROPS(1)
C
C Then call material type-specific routines
C -----
      IF(MATTYP.EQ.ELASTC)THEN
C Elastic (Hencky material in large strains)
      CALL SWEL
1(   MODE      ,NTYPE      ,RSTAVC      ,RSTAVL      ,STRESC      ,
2   STRESL      )
      ELSEIF(MATTYP.EQ.TRESCA)THEN
C Tresca elasto-plastic
      CALL SWTR
1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      ELSEIF(MATTYP.EQ.VMISES)THEN
C von Mises elasto-plastic
      CALL SWVM
1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      ELSEIF(MATTYP.EQ.MOHCOU)THEN
C Mohr-Coulomb elasto-plastic
      CALL SWMC
1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      ELSEIF(MATTYP.EQ.DRUPRA)THEN
C Drucker-Prager elasto-plastic
      CALL SWDP
1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      ELSEIF(MATTYP.EQ.LEMDAM)THEN
C Lemaitre's ductile damage elasto-plastic model
      CALL SWDAMA
1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      ELSEIF(MATTYP.EQ.DAMELA)THEN
C Isotropically damaged isotropic elastic material with crack closure
C effects
      CALL SWDMEL
1(   MODE      ,NTYPE      ,RSTAVC      ,RSTAVL      ,STRESC      ,
2   STRESL      )
      ELSEIF(MATTYP.EQ.PDSCRY)THEN
C Planar double-slip single crystal
      CALL SWPDSC
1(   MODE      ,LALGVC      ,LALGVL      ,RALGVC      ,RSTAVC      ,
2   RSTAVL      ,STRESC      ,STRESL      )
      ELSEIF(MATTYP.EQ.OGDEN)THEN
C Ogden hyperelasticity model
      CALL SWOGD
1(   MODE      ,NTYPE      ,RSTAVC      ,RSTAVL      ,STRESC      ,
2   STRESL      )
      ELSEIF(MATTYP.EQ.VMMIXD)THEN
C von Mises with mixed isotropic/kinematic hardening (infinitesimal
C only)
      CALL SWVMMX
1(   MODE      ,NLARGE      ,NTYPE      ,LALGVC      ,LALGVL      ,
2   RALGVC      ,RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      ELSE
C Error: Material type not recognised
      CALL ERRPRT('EI0046')
      ENDIF
      RETURN
      END

```



```
INTEGER FUNCTION NFUNC(N1,N2)
I = N1
J = N2
NF = (J*J-J)/2+I
NFUNC=NF
RETURN
END
```

```

SUBROUTINE NODAVE
  IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
  INCLUDE '../MAXDIM.INC'
  INCLUDE '../MATERIAL.INC'
  INCLUDE '../ELEMENTS.INC'
  INCLUDE '../GLDBASE.INC'
C
  DIMENSION
1  RALGN(MRALGV,MNODE),RSTAN(MRSTAV,MNODE),STRSN(MSTRE,MNODE),
2  THKN(MNODE)
  DIMENSION
1  STRSA(MSTRE,MGRUP,MPOIN),PSTRA(3),
2  RALGA(MRALGV,MGRUP,MPOIN),RSTAA(MRSTAV,MGRUP,MPOIN),
3  THKA(MGRUP,MPOIN)
  DATA R0,R1 /0.0D0,1.0D0/
C*****
C PRINTS AVERAGED (SMOOTHED) NODAL STRESSES AND OTHER STATE AND
C ALGORITHMIC VARIABLES. THE SMOOTHED VARIABLE AT EACH NODE IS OBTAINED
C BY EXTRAPOLATING THE VALUE OF THE VARIABLE FROM THE GAUSS POINTS TO
C THE NODE AND THEN AVERAGING THE VALUES OBTAINED FROM ALL ELEMENTS
C SHARING THAT NODE.
C
C REFERENCE: E Hinton & JS Campbel. Local and global smoothing of
C discontinuous finite element functions using a least
C squares method. Int. J. Num. Meth. Engng., 8:461-480, 1974.
C E Hinton & DRJ Owen. An introduction to finite element
C computations. Pineridge Press, Swansea, 1979.
C*****
1000 FORMAT(// ' Averaged nodal stresses and other state',
1  ' variables for group number ',I2/
1  ' =====',
3  ' =====')
1010 FORMAT(// ' Node number ',I5,3X,' X-Coord= ',G11.4,
1  ' Y-Coord= ',G11.4)
1020 FORMAT(// ' Node number ',I5,3X,' R-Coord= ',G11.4,
1  ' Z-Coord= ',G11.4)
1030 FORMAT(// ' Node number ',I5,3X,' X-Coord= ',G11.4,
1  ' R-Coord= ',G11.4)
1040 FORMAT(' S-xx = ',G12.4,' S-yy = ',G12.4,' S-xy = ',G12.4)
1050 FORMAT(' S-xx = ',G12.4,' S-yy = ',G12.4,' S-xy = ',G12.4,
1  ' S-zz = ',G12.4)
1060 FORMAT(' S-rr = ',G12.4,' S-zz = ',G12.4,' S-rz = ',G12.4,
1  ' S-h = ',G12.4)
1070 FORMAT(' S-xx = ',G12.4,' S-rr = ',G12.4,' S-xr = ',G12.4,
1  ' S-h = ',G12.4)
1080 FORMAT(' S-max = ',G12.4,' S-min = ',G12.4,' Angle = ',G12.4)
1090 FORMAT(' Thick = ',G12.4)
C
C Loop over element groups
C =====
DO 90 IGRUP=1,NGRUP
  WRITE(16,1000)IGRUP
  DO 10 IPOIN=1,NPOIN
    CALL RVZERO(STRSA(1,IGRUP,IPOIN),MSTRE)
    CALL RVZERO(PSTRA,3)
    CALL RVZERO(RSTAA(1,IGRUP,IPOIN),MRSTAV)
    CALL RVZERO(RALGA(1,IGRUP,IPOIN),MRALGV)
    THKA(IGRUP,IPOIN)=R0
  10 CONTINUE
C Loop over elements
C -----
DO 70 IELEM=1,NELEM
  LGRUP=IGRPID(IELEM)
  IF(LGRUP.NE.IGRUP)GOTO 70
  IELIDN=IELTID(IGRUP)
  NNODE =IELPRP(3,IELIDN)
  NGAUSP=IELPRP(4,IELIDN)
C Extrapolate stresses and other state and algorithmic variables from
C gauss points to nodes
  IPOSP=NGAUSP*NDIME+NGAUSP+1
  CALL EXTNOD
1( RELPRP(IPOSP,IELIDN),
2  STRSG(1,1,IELEM,1),STRSN,MSTRE,NGAUSP,NNODE )
  CALL EXTNOD
1( RELPRP(IPOSP,IELIDN),
2  RSTAVA(1,1,IELEM,1),RSTAN,MRSTAV,NGAUSP,NNODE )
  CALL EXTNOD
1( RELPRP(IPOSP,IELIDN),
2  RALGVA(1,1,IELEM,1),RALGN,MRALGV,NGAUSP,NNODE )
C thickness (for large strains in plane stress only)
  IF(NLARGE.EQ.1.AND.NTYPE.EQ.1)CALL EXTNOD
1( RELPRP(IPOSP,IELIDN),
2  THKGP(1,IELEM,1),THKN,1,NGAUSP,NNODE )
C Nodal averaging
DO 60 INODE=1,NNODE
  IPOIN=IABS(LNODS(IELEM,INODE))
  R1DVAL=R1/DBLE(NVALEN(IPOIN,IGRUP))
  DO 30 ISTR=1,MSTRE
    STRSA(ISTR,IGRUP,IPOIN)=STRSA(ISTR,IGRUP,IPOIN)+
1  STRSN(ISTR,INODE)*R1DVAL
30 CONTINUE
DO 40 INTV=1,MRSTAV
  RSTAA(INTV,IGRUP,IPOIN)=RSTAA(INTV,IGRUP,IPOIN)+
1  RSTAN(INTV,INODE)*R1DVAL
40 CONTINUE
DO 50 IALGV=1,MRALGV
  RALGA(IALGV,IGRUP,IPOIN)=RALGA(IALGV,IGRUP,IPOIN)+

```

```

1                                RALGN(IALGV,INODE)*R1DVAL
50      CONTINUE
      IF(NLARGE.EQ.1.AND.NTYPE.EQ.1)
1        THKA(IGRUP,IPOIN)=THKA(IGRUP,IPOIN)+
2        THKN(INODE)*R1DVAL
60      CONTINUE
70      CONTINUE

C
C Output average stresses to results file (common to all materials)
C -----
C
      DO 80 IPOIN=1,NPOIN
      IF(NVALEN(IPOIN,IGRUP).EQ.0)GOTO 80
      IF(NTYPE.EQ.1)THEN
        LSTRE=3
        WRITE(16,1010)IPOIN,(COORD(I,IPOIN,1),I=1,NDIME)
        WRITE(16,1040)(STRSA(I,IGRUP,IPOIN),I=1,LSTRE)
      ELSEIF(NTYPE.EQ.2)THEN
        LSTRE=4
        WRITE(16,1010)IPOIN,(COORD(I,IPOIN,1),I=1,NDIME)
        WRITE(16,1050)(STRSA(I,IGRUP,IPOIN),I=1,LSTRE)
      ELSEIF(NTYPE.EQ.3)THEN
        LSTRE=4
        IF(NAXIS.EQ.1)THEN
          WRITE(16,1020)IPOIN,(COORD(I,IPOIN,1),I=1,NDIME)
          WRITE(16,1060)(STRSA(I,IGRUP,IPOIN),I=1,LSTRE)
        ELSE
          WRITE(16,1030)IPOIN,(COORD(I,IPOIN,1),I=1,NDIME)
          WRITE(16,1070)(STRSA(I,IGRUP,IPOIN),I=1,LSTRE)
        ENDIF
      ENDIF
C compute and output principal stresses and angle
      CALL PRINC2(PSTRA,STRSA(1,IGRUP,IPOIN))
      WRITE(16,1080)(PSTRA(I),I=1,3)
C current thickness (for large strains in plane stress only)
      IF(NLARGE.EQ.1.AND.NTYPE.EQ.1)WRITE(16,1090)THKA(IGRUP,IPOIN)

C
C and other (material-specific) state and algorithmic variables
C -----
C
      CALL MATIOR
1(      NTYPE      ,IPROPS(1,MATTID(IGRUP))      ,RALGA(1,IGRUP,IPOIN)      ,
2      RPROPS(1,MATTID(IGRUP))      ,RSTAA(1,IGRUP,IPOIN)      ,
3      STRSA(1,IGRUP,IPOIN)      )

C
80      CONTINUE
90      CONTINUE
      RETURN
      END

```

```

INTEGER FUNCTION NWORD(CHRSTR,IWBEG,IWEND)
IMPLICIT NONE
CHARACTER*(*) CHRSTR
INTEGER IWBEG(*), IWEND(*)
LOGICAL OUT
INTEGER I, LEN, LENGTH
C*****
C FIND NUMBER OF WORDS CONTAINED IN A CHARACTER STRING AND SET POINTERS
C TO BEGINNING AND END OF EACH WORD
C*****
LENGTH=LEN(CHRSTR)
NWORD=0
OUT=.TRUE.
DO 10 I=1,LENGTH
  IF(OUT)THEN
    IF(CHRSTR(I:I).NE.' ')THEN
      OUT=.FALSE.
      NWORD=NWORD+1
      IWBEG(NWORD)=I
    ENDIF
  ELSE
    IF(CHRSTR(I:I).EQ.' ')THEN
      OUT=.TRUE.
      IWEND(NWORD)=I-1
    ELSEIF(I.EQ.LENGTH)THEN
      IWEND(NWORD)=I
    ENDIF
  ENDIF
10 CONTINUE
RETURN
END

```

```

      SUBROUTINE ORDAMA
1(   DGAMA      ,NOUTF      ,NTYPE      ,RSTAVA      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=6 ,MSTRE=4)
      DIMENSION RSTAVA(MSTRE+2), STRES(*)
      DATA R2 ,R3 / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR LEMAITRE'S
C DUCTILE DAMAGE ELASTO-PLASTIC MODEL WITH NON-LINEAR ISOTROPIC
C HARDENING
C*****
1000 FORMAT(' S-eff = ',G12.4,' R      = ',G12.4,' dgama = ',G12.4)
2000 FORMAT(' Damage= ',G12.4)
C
C Retrieve current values of hardening variable and damage
      HVAR=RSTAVA(MSTRE+1)
      DAMAGE=RSTAVA(MSTRE+2)
      IF(NTYPE.EQ.1)THEN
C Plane stress
      P=(STRES(1)+STRES(2))/R3
      EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1      R2*STRES(3)**2+P**2))
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
C Plane strain and axisymmetric
      P=(STRES(1)+STRES(2)+STRES(4))/R3
      EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1      R2*STRES(3)**2+(STRES(4)-P)**2))
      ENDIF
C Write to output file
      WRITE(NOUTF,1000)EFFST,HVAR,DGAMA
      WRITE(NOUTF,2000)DAMAGE
      RETURN
      END

```

```

      SUBROUTINE ORDMEL
1(      NOUTF      ,NTYPE      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(MSTRE=4)
      DIMENSION STRES(*)
      DATA      R2      ,R3      / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS FOR ISOTROPICALLY DAMAGED ISOTROPIC ELASTIC MODEL
C ACCOUNTING FOR PARTIAL MICROCRACK/VOID CLOSURE EFFECTS
C*****
1000 FORMAT(' S-eff = ',G12.4,' Press.= ',G12.4)
C
      IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        P=(STRES(1)+STRES(2)+STRES(4))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1          R2*STRES(3)**2+(STRES(4)-P)**2))
      ELSE
        CALL ERRPRT('EI0055')
      ENDIF
C Write to output file
      WRITE(NOUTF,1000)EFFST,P
      RETURN
      END

```

```

SUBROUTINE ORDP
1( DGAM ,NOUTF ,NTYPE ,RSTAVA ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=7 ,MSTRE=4)
DIMENSION DGAM(1), RSTAVA(MSTRE+1), STRES(*)
DATA R2 ,R3 / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR DRUCKER-PRAGER
C TYPE ELASTO-PLASTIC MATERIAL WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW
C RULE AND NON-LINEAR ISOTROPIC HARDENING
C*****
1000 FORMAT(' S-eff = ',G12.4,' Press.= ',G12.4,' Eps. = ',G12.4,
1 ' dgama = ',G12.4)
C
EPBAR=RSTAVA(MSTRE+1)
IF(NTYPE.EQ.1)THEN
P=(STRES(1)+STRES(2))/R3
EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1 R2*STRES(3)**2+P**2))
ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
P=(STRES(1)+STRES(2)+STRES(4))/R3
EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1 R2*STRES(3)**2+(STRES(4)-P)**2))
ENDIF
C Write to output file
WRITE(NOUTF,1000)EFFST,P,EPBAR,DGAM(1)
RETURN
END

```

```

      SUBROUTINE OREL
1(      NOUTF      ,NTYPE      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(MSTRE=4)
      DIMENSION STRES(*)
      DATA      R2      ,R3      / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS FOR LINEAR ELASTIC MATERIAL MODEL
C*****
      1000 FORMAT(' S-eff = ',G12.4,' Press.= ',G12.4)
C
      IF(NTYPE.EQ.1)THEN
        P=(STRES(1)+STRES(2))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1          R2*STRES(3)**2+P**2))
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        P=(STRES(1)+STRES(2)+STRES(4))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1          R2*STRES(3)**2+(STRES(4)-P)**2))
      ENDIF
C Write to output file
      WRITE(NOUTF,1000)EFFST,P
      RETURN
      END

```



```

SUBROUTINE ORMC
1( DGAM ,NOUTF ,NTYPE ,RSTAVA ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=7 ,MSTRE=4)
DIMENSION DGAM(2), RSTAVA(MSTRE+1), STRES(*)
DATA R2 ,R3 / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR THE
C MOHR-COULOMB TYPE ELASTO-PLASTIC MATERIAL WITH ASSOCIATIVE/NON-
C ASSOCIATIVE FLOW RULE AND NON-LINEAR ISOTROPIC HARDENING
C*****
1000 FORMAT(' S-eff = ',G12.4,' Press.= ',G12.4,' Eps. = ',G12.4,
1 ' dgama = ',G12.4,' dgamb = ',G12.4)
C
EPBAR=RSTAVA(MSTRE+1)
IF(NTYPE.EQ.1)THEN
P=(STRES(1)+STRES(2))/R3
EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1 R2*STRES(3)**2+P**2))
ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
P=(STRES(1)+STRES(2)+STRES(4))/R3
EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1 R2*STRES(3)**2+(STRES(4)-P)**2))
ENDIF
C Write to output file
WRITE(NOUTF,1000)EFFST,P,EPBAR,DGAM(1),DGAM(2)
RETURN
END

```

```

      SUBROUTINE OROGD
1(      NOUTF      ,NTYPE      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION STRES(*)
      DATA      R2      ,R3      / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS FOR OGDEN TYPE HYPERELASTIC MATERIAL MODEL
C*****
1000 FORMAT(' S-eff = ',G12.4,' Press.= ',G12.4)
C
      IF(NTYPE.EQ.1)THEN
        P=(STRES(1)+STRES(2))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1          R2*STRES(3)**2+P**2))
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        P=(STRES(1)+STRES(2)+STRES(4))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1          R2*STRES(3)**2+(STRES(4)-P)**2))
      ENDIF
C Write to output file
      WRITE(NOUTF,1000)EFFST,P
      RETURN
      END

```

```

      SUBROUTINE ORPDSC
1(   DGAM      ,NOUTF      ,NTYPE      ,RPROPS      ,RSTAVA      ,
2   STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(   IPHARD=6      ,NDIM=2      ,NRSTAV=5      ,NSYST=4      )
C Arguments
      DIMENSION
1   DGAM(NSYST)      ,RPROPS(*)      ,RSTAVA(NRSTAV)      ,
2   STRES(*)
C Local arrays and variables
      DIMENSION
1   AUX1(NDIM,NDIM)      ,DKIRCH(NDIM,NDIM)      ,FE(NDIM,NDIM)      ,
2   RE(NDIM,NDIM)      ,ROTSTR(NDIM,NDIM)      ,SCHMID(NSYST)      ,
3   UE(NDIM,NDIM)      ,VECM0(NDIM,NSYST)      ,VECS0(NDIM,NSYST)
      DATA R0      ,R1      ,R3      ,R180      /
1   0.0D0,1.0D0,3.0D0,180.0D0/
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR THE PLANAR
C DOUBLE-SLIP SINGLE CRYSTAL ELASTO-PLASTIC MODEL
C*****
1000 FORMAT(' Lattice rotation (degrees) = ',G12.4/
1   ' Accumulated plastic slip = ',G12.4/
2   ' tau_1 = ',G12.4,' tau_2 = ',G12.4,' tau_3 = ',G12.4,
3   ' tau_4 = ',G12.4/
4   ' dlmd1 = ',G12.4,' dlmd2 = ',G12.4,' dlmd3 = ',G12.4,
5   ' dlmd4 = ',G12.4)
C Stops program if not plane strain
      IF(NTYPE.NE.2)CALL ERRPRT('EI0037')
C Retrieve stored state variables
C -----
C... current elastic deformation gradient
      FE(1,1)=RSTAVA(1)
      FE(2,1)=RSTAVA(2)
      FE(1,2)=RSTAVA(3)
      FE(2,2)=RSTAVA(4)
C... current Taylor hardening variable (acummulated slip)
      HRVAR=RSTAVA(NRSTAV)
C Compute lattice rotation
C -----
C Perform polar decomposition of the elastic deformation gradient
      CALL PODEC2
1(   FE      ,RE      ,UE      )
C From the elastic rotation tensor, compute crystal lattice rotation
      SINE=RE(2,1)
      IF(SINE.GT.R1)SINE=R1
      IF(SINE.LT.-R1)SINE=-R1
      COSINE=RE(1,1)
      IF(COSINE.GT.R1)COSINE=R1
      IF(COSINE.LT.-R1)COSINE=-R1
      DEGRAD=R180/ACOS(-R1)
      SANGLE=DEGRAD*ASIN(SINE)
      CANGLE=DEGRAD*ACOS(COSINE)
      IF(SINE.GE.R0)THEN
        CLROT=CANGLE
      ELSEIF(SINE.LT.R0.AND.COSINE.LT.R0)THEN
        CLROT=-CANGLE
      ELSE
        CLROT=SANGLE
      ENDIF
C Evaluate resolved Schmid stresses (these are not stored in memory)
C -----
C Set up initial slip systems vectors
C... retrieve initial system orientation
      THETA=RPROPS(4)
C... retrieve relative angle between systems
      BETA=RPROPS(5)
C... system 1:
      VECS0(1,1)=COS(THETA)
      VECS0(2,1)=SIN(THETA)
      VECM0(1,1)=-SIN(THETA)
      VECM0(2,1)=COS(THETA)
C... system 2:
      VECS0(1,2)=COS(THETA+BETA)
      VECS0(2,2)=SIN(THETA+BETA)
      VECM0(1,2)=-SIN(THETA+BETA)
      VECM0(2,2)=COS(THETA+BETA)
C... system 3:
      VECS0(1,3)=-VECS0(1,1)
      VECS0(2,3)=-VECS0(2,1)
      VECM0(1,3)=VECM0(1,1)
      VECM0(2,3)=VECM0(2,1)
C... system 4:
      VECS0(1,4)=-VECS0(1,2)
      VECS0(2,4)=-VECS0(2,2)
      VECM0(1,4)=VECM0(1,2)
      VECM0(2,4)=VECM0(2,2)
C compute rotated stress tensor
      DETF=FE(1,1)*FE(2,2)-FE(1,2)*FE(2,1)
C... deviatoric Kirchhoff stress
      PKIRCH=R1/R3*DETF*(STRES(1)+STRES(2)+STRES(4))
      DKIRCH(1,1)=DETF*STRES(1)-PKIRCH
      DKIRCH(2,2)=DETF*STRES(2)-PKIRCH
      DKIRCH(1,2)=DETF*STRES(3)
      DKIRCH(2,1)=DKIRCH(1,2)
C... rotated deviatoric Kirchhoff stress
      CALL RVZERO(AUX1,NDIM*NDIM)
      DO 30 I=1,NDIM

```

```

        DO 20 J=1,NDIM
          DO 10 K=1,NDIM
            AUX1(I,J)=AUX1(I,J)+RE(K,I)*DKIRCH(K,J)
10      CONTINUE
20    CONTINUE
30  CONTINUE
    CALL RVZERO(ROTSTR,NDIM*NDIM)
    DO 60 I=1,NDIM
      DO 50 J=1,NDIM
        DO 40 K=1,NDIM
          ROTSTR(I,J)=ROTSTR(I,J)+AUX1(I,K)*RE(K,J)
40      CONTINUE
50    CONTINUE
60  CONTINUE
C Current Schmid resolved stresses
    CALL RVZERO(SCHMID,NSYST)
    DO 90 ISYST=1,NSYST
      DO 80 I=1,NDIM
        DO 70 J=1,NDIM
          SCHMID(ISYST)=SCHMID(ISYST)+
1          ROTSTR(I,J)*VECS0(I,ISYST)*VECM0(J,ISYST)
70      CONTINUE
80    CONTINUE
90  CONTINUE
C
C Write results to output file
C -----
      WRITE(NUOTF,1000)CLROT,HRVAR,SCHMID(1),SCHMID(2),SCHMID(3),
1      SCHMID(4),DGAM(1),DGAM(2),DGAM(3),DGAM(4)
C
      RETURN
    END

```

```

      SUBROUTINE ORTR
1(   DGAM   ,NOUTF   ,NTYPE   ,RSTAVA   ,STRES   )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=4 ,MSTRE=4)
      DIMENSION DGAM(2), RSTAVA(MSTRE+1), STRES(*)
      DATA   R2   ,R3   / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR TRESCA
C TYPE ELASTO-PLASTIC MATERIAL WITH NON-LINEAR ISOTROPIC HARDENING
C*****
1000 FORMAT(' S-eff = ',G12.4,' Eps.   = ',G12.4,' dgama = ',G12.4,
1         ' dgamb = ',G12.4)
C
      EPBAR=RSTAVA(MSTRE+1)
      IF(NTYPE.EQ.1)THEN
        P=(STRES(1)+STRES(2))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1         R2*STRES(3)**2+P**2))
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        P=(STRES(1)+STRES(2)+STRES(4))/R3
        EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1         R2*STRES(3)**2+(STRES(4)-P)**2))
      ENDIF
C Write to output file
      WRITE(NOUTF,1000)EFFST,EPBAR,DGAM(1),DGAM(2)
      RETURN
      END

```

```

      SUBROUTINE ORVM
1(   DGAMA      ,NOUTF      ,NTYPE      ,RSTAVA      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=4 ,MSTRE=4)
      DIMENSION RSTAVA(MSTRE+1), STRES(*)
      DATA  R2      ,R3      / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR VON MISES
C TYPE ELASTO-PLASTIC MATERIAL WITH NON-LINEAR ISOTROPIC HARDENING
C*****
1000 FORMAT(' S-eff = ',G12.4,' Eps.  = ',G12.4,' dgama = ',G12.4)
C
      EPBAR=RSTAVA(MSTRE+1)
      IF(NTYPE.EQ.1)THEN
C Plane stress
      P=(STRES(1)+STRES(2))/R3
      EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1      R2*STRES(3)**2+P**2))
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
C Plane strain and axisymmetric
      P=(STRES(1)+STRES(2)+STRES(4))/R3
      EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1      R2*STRES(3)**2+(STRES(4)-P)**2))
      ENDIF
C Write to output file
      WRITE(NOUTF,1000)EFFST,EPBAR,DGAMA
      RETURN
      END

```

```

SUBROUTINE ORVMMX
1(   DGAMA      ,NOUTF      ,NTYPE      ,RSTAVA      ,STRES      )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=4 ,MSTRE=4)

C Arguments
  DIMENSION RSTAVA(2*MSTRE+1), STRES(*)

C Local arrays and variables
  DIMENSION BACSTR(MSTRE)
  DATA R2 ,R3 / 2.0D0,3.0D0 /
C*****
C OUTPUT RESULTS (INTERNAL AND ALGORITHMIC VARIABLES) FOR VON MISES
C ELASTO-PLASTIC MATERIAL WITH NON-LINEAR MIXED HARDENING
C*****
1000 FORMAT(' b-xx = ',G12.4,' b-yy = ',G12.4,' b-xy = ',G12.4,
1         ' b-zz = ',G12.4)
1100 FORMAT(' S-eff = ',G12.4,' Eps. = ',G12.4,' dgama = ',G12.4)

C
C Plane strain and axisymmetric only
  IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPR('EI0050')

C Print backstress tensor
  BACSTR(1)=RSTAVA(6)
  BACSTR(2)=RSTAVA(7)
  BACSTR(3)=RSTAVA(8)
  BACSTR(4)=RSTAVA(9)
  WRITE(NOUTF,1000)BACSTR(1),BACSTR(2),BACSTR(3),BACSTR(4)

C Compute effective stress
  IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
    P=(STRES(1)+STRES(2)+STRES(4))/R3
    EFFST=SQRT(R3/R2*((STRES(1)-P)**2+(STRES(2)-P)**2+
1          R2*STRES(3)**2+(STRES(4)-P)**2))
  ENDIF
  EPBAR=RSTAVA(MSTRE+1)
  WRITE(NOUTF,1100)EFFST,EPBAR,DGAMA
  RETURN
END

```

```

      SUBROUTINE OUTPUT
1(   TFACT   ,IINCS   ,IITER   ,NOUTP   )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'

C
      DIMENSION NOUTP(5)

C
      DIMENSION
1      DERIV(MDIME,MNODE) ,ELCOD(MDIME,MNODE) ,GPCOD(MDIME) ,
2      PSTRS(3) ,SHAPE(MNODE)
      DATA R0/0.0D0/
C*****
C OUTPUTS DISPLACEMENTS, REACTIONS, STRESSES AND OTHER STATE AND
C ALGORITHMIC VARIABLES TO RESULTS FILE
C
C REFERENCE: Section 5.4.7
C*****
1020 FORMAT(// ' Results for load increment ',I3,' Load factor =',G15.6/
1 1X,59('=')// ' Converged solution at iteration number =',2I5/)
1030 FORMAT(// ' Displacement of structure from initial configuration',/
1 ' =====')
1040 FORMAT(// ' Node      R-Disp      Z-Disp')
1045 FORMAT(// ' Node      X-Disp      R-Disp')
1050 FORMAT(// ' Node      X-Disp      Y-Disp')
1060 FORMAT(I5,2X,6G15.6)
1070 FORMAT(// ' Reactions'/1X,9('='))
1080 FORMAT(// ' Node      R-Force      Z-Force')
1081 FORMAT(// ' Node      X-Force      R-Force')
1085 FORMAT(// ' Node      R-Force      Z-Force      X-Local',
1 ' Y-Local')
1086 FORMAT(// ' Node      X-Force      R-Force      X-Local',
1 ' Y-Local')
1090 FORMAT(// ' Node      X-Force      Y-Force')
1095 FORMAT(// ' Node      X-Force      Y-Force      X-Local',
1 ' Y-Local')
1100 FORMAT(I5,6(2X,G15.6))
1105 FORMAT(' ----- '/' Totals',
1G15.6,2X,G15.6)
1110 FORMAT(// ' Gauss point stresses and and other state variables'/
1 ' =====')
1115 FORMAT(// ' Element number',I5)
1150 FORMAT(// ' Gauss point ',I2,6X,' X-Coord= ',G11.4,
1 ' Y-Coord= ',G11.4)
1152 FORMAT(// ' Gauss point ',I2,6X,' R-Coord= ',G11.4,
1 ' Z-Coord= ',G11.4)
1153 FORMAT(// ' Gauss point ',I2,6X,' X-Coord= ',G11.4,
1 ' R-Coord= ',G11.4)
1160 FORMAT(' S-xx = ',G12.4,' S-yy = ',G12.4,' S-xy = ',G12.4)
1161 FORMAT(' S-xx = ',G12.4,' S-yy = ',G12.4,' S-xy = ',G12.4,
1 ' S-zz = ',G12.4)
1162 FORMAT(' S-rr = ',G12.4,' S-zz = ',G12.4,' S-rz = ',G12.4,
1 ' S-h = ',G12.4)
1163 FORMAT(' S-xx = ',G12.4,' S-rr = ',G12.4,' S-xr = ',G12.4,
1 ' S-h = ',G12.4)
1164 FORMAT(' S-max = ',G12.4,' S-min = ',G12.4,' Angle = ',G12.4)
1165 FORMAT(' Thick = ',G12.4)

C
C
C Set output flags
C =====
C
      N1=NOUTP(1)
      N2=NOUTP(2)
      N3=NOUTP(3)
      N4=NOUTP(4)
      IF(NALGO.LT.0)THEN
        IF(N1.NE.0)THEN
          IF(MOD(IINCS,N1).EQ.0)THEN
            N1=1
          ELSE
            N1=0
          ENDIF
        ENDIF
      ENDIF
      IF(N2.NE.0)THEN
        IF(MOD(IINCS,N2).EQ.0)THEN
          N2=1
        ELSE
          N2=0
        ENDIF
      ENDIF
      IF(N3.NE.0)THEN
        IF(MOD(IINCS,N3).EQ.0)THEN
          N3=1
        ELSE
          N3=0
        ENDIF
      ENDIF
      IF(N4.NE.0)THEN
        IF(MOD(IINCS,N4).EQ.0)THEN
          N4=1
        ELSE
          N4=0
        ENDIF
      ENDIF

```



```

ENDIF
IF(N1.EQ.0.AND.N2.EQ.0.AND.N3.EQ.0.AND.N4.EQ.0)RETURN
C
C
WRITE(16,1020)IINCS,TFACT,IITER
C
C Output displacements
C =====
C
IF(N1.NE.0)THEN
WRITE(16,1030)
IF(NTYPE.EQ.3)THEN
IF(NAXIS.EQ.1)THEN
WRITE(16,1040)
ELSE
WRITE(16,1045)
ENDIF
ELSE
WRITE(16,1050)
ENDIF
DO 10 IPOIN=1,NPOIN
NGASH=IPOIN*NDOFN
NGISH=NGASH-NDOFN+1
WRITE(16,1060)IPOIN,(TDISP(IGASH),IGASH=NGISH,NGASH)
10 CONTINUE
ENDIF
C
C Output reactions
C =====
C
IF(N2.NE.0)THEN
WRITE(16,1070)
DO 45 IVFIX=1,NVFIX
IF(ANGLE(IVFIX).NE.R0)THEN
IF(NTYPE.EQ.3)THEN
IF(NAXIS.EQ.1)THEN
WRITE(16,1085)
ELSE
WRITE(16,1086)
ENDIF
ELSE
WRITE(16,1095)
ENDIF
GOTO 47
ENDIF
45 CONTINUE
IF(NTYPE.EQ.3)THEN
IF(NAXIS.EQ.1)THEN
WRITE(16,1080)
ELSE
WRITE(16,1081)
ENDIF
ELSE
WRITE(16,1090)
ENDIF
47 CONTINUE
TRX=R0
TRY=R0
DO 70 IPOIN=1,NPOIN
ISVAB=(IPOIN-1)*NDOFN
DO 50 IVFIX=1,NVFIX
IF(NOFIX(IVFIX).EQ.IPOIN)GOTO 60
50 CONTINUE
GOTO 70
60 CONTINUE
IF(ANGLE(IVFIX).NE.R0)THEN
C=COS(ANGLE(IVFIX))
S=SIN(ANGLE(IVFIX))
GASHI= C*TREAC(IVFIX,1)+S*TREAC(IVFIX,2)
GASHJ=-S*TREAC(IVFIX,1)+C*TREAC(IVFIX,2)
IF(IFFIX(ISVAB+1).EQ.0)GASHI=R0
IF(IFFIX(ISVAB+2).EQ.0)GASHJ=R0
WRITE(16,1100)IPOIN,(TREAC(IVFIX,IDOFN),IDOFN=1,NDOFN),
1 GASHI,GASHJ
ELSE
WRITE(16,1100)IPOIN,(TREAC(IVFIX,IDOFN),IDOFN=1,NDOFN)
ENDIF
TRX=TRX+TREAC(IVFIX,1)
TRY=TRY+TREAC(IVFIX,2)
70 CONTINUE
WRITE(16,1105)TRX,TRY
ENDIF
C
C Stresses and other state and algorithmic variables at gauss points
C =====
C
IF(N3.NE.0)THEN
WRITE(16,1110)
DO 120 IELEM=1,NELEM
IGRUP=IGRPID(IELEM)
IELIDN=IELTID(IGRUP)
IELTYP=IELPRP(1,IELIDN)
NNODE =IELPRP(3,IELIDN)
NGAUSP=IELPRP(4,IELIDN)
C
WRITE(16,1115)IELEM
C Evaluate Gauss point coordinates
DO 91 INODE=1,NNODE

```

```

        LNODE=IABS(LNODS(IELEM,INODE))
        DO 90 IDIME=1,NDIME
            ELCOD(IDIME,INODE)=COORD(IDIME,LNODE,1)
90      CONTINUE
91      CONTINUE
        IF(NTYPE.EQ.1)THEN
            LSTRE=3
        ELSEIF(NTYPE.EQ.2)THEN
            LSTRE=4
        ELSEIF(NTYPE.EQ.3)THEN
            LSTRE=4
        ENDIF
        IPPOS=1
        DO 110 IGAUSP=1,NGAUSP
            EXISP=RELPRP(IPPOS-1+IGAUSP*2-1,IELIDN)
            ETASP=RELPRP(IPPOS-1+IGAUSP*2,IELIDN)
            CALL SHPFUN
1(      DERIV      ,ETASP      ,EXISP      ,0      ,IELTYP      ,
2      MDIME      ,SHAPE      )
            CALL GETGCO
1(      GPCOD      ,ELCOD      ,MDIME      ,NDIME      ,NNODE      ,
2      SHAPE      )
C Output gauss points stresses (common to all materials)
C -----
        IF(NTYPE.EQ.1)THEN
            WRITE(16,1150)IGAUSP,(GPCOD(I),I=1,NDIME)
            WRITE(16,1160)(STRSG(I,IGAUSP,IELEM,1),I=1,LSTRE)
        ELSEIF(NTYPE.EQ.2)THEN
            WRITE(16,1150)IGAUSP,(GPCOD(I),I=1,NDIME)
            WRITE(16,1161)(STRSG(I,IGAUSP,IELEM,1),I=1,LSTRE)
        ELSEIF(NTYPE.EQ.3)THEN
            IF(NAXIS.EQ.1)THEN
                WRITE(16,1152)IGAUSP,(GPCOD(I),I=1,NDIME)
                WRITE(16,1162)(STRSG(I,IGAUSP,IELEM,1),I=1,LSTRE)
            ELSE
                WRITE(16,1153)IGAUSP,(GPCOD(I),I=1,NDIME)
                WRITE(16,1163)(STRSG(I,IGAUSP,IELEM,1),I=1,LSTRE)
            ENDIF
        ENDIF
C and principal stresses
        CALL PRINC2(PSTRS,STRSG(1,IGAUSP,IELEM,1))
        WRITE(16,1164)(PSTRS(I),I=1,3)
C output current thickness (for large strains in plane stress only)
        IF(NLARGE.EQ.1.AND.NTYPE.EQ.1)THEN
            WRITE(16,1165)THKGP(IGAUSP,IELEM,1)
        ENDIF
C Output other (material-specific) state and algorithmic variables
C -----
        CALL MATIOR
1(      NTYPE      ,IPROPS(1,MATTID(IGRPID(IELEM))) ,
2      RALGVA(1,IGAUSP,IELEM,1) ,RPROPS(1,MATTID(IGRPID(IELEM))) ,
3      RSTAVA(1,IGAUSP,IELEM,1) ,STRSG(1,IGAUSP,IELEM,1) )
C
110     CONTINUE
120     CONTINUE
        ENDIF
C
C Stresses and other state and algorithmic variables at nodes
C =====
C
        IF(N4.NE.0)THEN
            CALL NODAVE
        ENDIF
C
        RETURN
        END

```

```
      SUBROUTINE PEXIT
C Print message
      WRITE(*,'(///15X,A,///)')'Program HYPLAS aborted.'
      WRITE(16,'(///15X,A,///)')'Program HYPLAS aborted.'
C Close files
      CALL FCLOSE
C and exit program
      STOP ''
      END
```

```

C      DOUBLE PRECISION FUNCTION PLFUN(X, NPOINT, XFX)
C      INTEGER NPOINT, I
C      DOUBLE PRECISION X, XFX(2,*)
C*****
C PIECEWISE LINEAR FUNCTION DEFINED BY A SET OF NPOINT PAIRS
C {X,F(X)} STORED IN THE MATRIX XFX (DIM. 2*NPOINT).
C*****
      DO 100 I=1,NPOINT
        IF (X.GE.XFX(1,I)) THEN
          GOTO 100
        ELSE
          IF (I.EQ.1) THEN
C
            -- x < x1 --> f(x)=f(x1) ---
            PLFUN=XFX(2,1)
            GOTO 999
          ELSE
C
            -- x(i-1) <= x < x(i) ---
            PLFUN=XFX(2,I-1)+(X-XFX(1,I-1))*
1          (XFX(2,I)-XFX(2,I-1))/
2          (XFX(1,I)-XFX(1,I-1))
            GOTO 999
          ENDIF
        ENDIF
      100 CONTINUE
C      ---- x >= x(npoin) --> f(x) = f(x(npoin)) ---
      PLFUN=XFX(2,NPOINT)
      999 CONTINUE
      RETURN
      END

```

```

      SUBROUTINE PODEC2
      1( F ,R ,U )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
      1( NDIM=2 )
C Arguments
      DIMENSION
      1 F(NDIM,NDIM) ,R(NDIM,NDIM) ,U(NDIM,NDIM)
C Local variables and arrays
      LOGICAL DUMMY
      DIMENSION
      1 C(NDIM,NDIM) ,CVEC(4) ,EIGPRJ(4,NDIM) ,
      2 EIGC(NDIM) ,UM1(NDIM,NDIM) ,UM1VEC(3) ,
      3 UVEC(3)
      DATA
      1 R1 /
      2 1.0D0/
C*****
C PERFORMS THE RIGHT POLAR DECOMPOSITION OF A 2-D TENSOR
C
C REFERENCE: Section 2.2.9
C*****
C T
C Compute C := F F
C -----
      CALL RVZERO(C,NDIM*NDIM)
      DO 30 I=1,NDIM
        DO 20 J=1,NDIM
          DO 10 K=1,NDIM
            C(I,J)=C(I,J)+F(K,I)*F(K,J)
          10 CONTINUE
        20 CONTINUE
      30 CONTINUE
C Perform spectral decomposition of C
C -----
      CVEC(1)=C(1,1)
      CVEC(2)=C(2,2)
      CVEC(3)=C(1,2)
      CALL SPDEC2(EIGPRJ ,EIGC ,DUMMY ,CVEC )
C
C 1/2 -1
C Compute U := (C) and U
C -----
C assemble in vector form
      CALL RVZERO(UVEC,3)
      CALL RVZERO(UM1VEC,3)
      DO 50 IDIM=1,NDIM
        UEIG=SQRT(EIGC(IDIM))
        UM1EIG=R1/UEIG
        DO 40 ICOMP=1,3
          UVEC(ICOMP)=UVEC(ICOMP)+UEIG*EIGPRJ(ICOMP,IDIM)
          UM1VEC(ICOMP)=UM1VEC(ICOMP)+UM1EIG*EIGPRJ(ICOMP,IDIM)
        40 CONTINUE
      50 CONTINUE
C and matrix form
      U(1,1)=UVEC(1)
      U(2,2)=UVEC(2)
      U(1,2)=UVEC(3)
      U(2,1)=UVEC(3)
      UM1(1,1)=UM1VEC(1)
      UM1(2,2)=UM1VEC(2)
      UM1(1,2)=UM1VEC(3)
      UM1(2,1)=UM1VEC(3)
C -1
C Compute rotation R := F U
C -----
      CALL RVZERO(R,NDIM*NDIM)
      DO 80 I=1,NDIM
        DO 70 J=1,NDIM
          DO 60 K=1,NDIM
            R(I,J)=R(I,J)+F(I,K)*UM1(K,J)
          60 CONTINUE
        70 CONTINUE
      80 CONTINUE
C
      RETURN
      END

```

```

SUBROUTINE PRINC2(PSTRS ,STRSG )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION PSTRS(3),STRSG(3)
DATA R0 ,RP01 ,RP5 ,R1 ,R4 ,R90 ,SMALL/
1 0.0D0,0.01D0,0.5D0,1.0D0,4.0D0,90.0D0,1.D-6/
C*****
C COMPUTES THE PRINCIPAL STRESSES FOR TWO-DIMENSIONAL STRESSES
C*****
PI=R4*ATAN(R1)
XGASH=(STRSG(1)+STRSG(2))*RP5
XGISH=(STRSG(1)-STRSG(2))*RP5
XGESH=STRSG(3)
XGOSH=SQRT(XGISH*XGISH+XGESH*XGESH)
PSTRS(1)=XGASH+XGOSH
PSTRS(2)=XGASH-XGOSH
AUX=SQRT(STRSG(1)**2+STRSG(2)**2+STRSG(3)**2)
IF(AUX.EQ.R0)AUX=R1
IF(ABS(XGESH/AUX).LT.SMALL.AND.ABS(XGISH/AUX).LT.SMALL)THEN
PSTRS(3)=R0
ELSE
PSTRS(3)=(ATAN2(XGESH,XGISH))*R90/PI
IF(PSTRS(3).LT.(-R90+RP01))PSTRS(3)=R90
ENDIF
RETURN
END

```

```

      SUBROUTINE RDDAMA
1(   IPROPS      ,MIPROP      ,MLALGV      ,MRPROP      ,MRSTAV      ,
2   NTYPE      ,RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( IPHARD=6 ,NLALGV=2 ,NRSTAV=6 )
      DIMENSION
1   IPROPS(*)      ,RPROPS(*)
      DATA R0 /0.0D0/
C*****
C READS AND ECHOES MATERIAL PROPERTIES FOR LEMAITRE'S DUCTILE DAMAGE
C ELASTO-PLASTIC MATERIAL MODEL WITH NON-LINEAR (PIECEWISE LINEAR)
C ISOTROPIC HARDENING
C
C REFERENCE Box: 12.3
C*****
1000 FORMAT(' LEMAITRE'S DUCTILE DAMAGE elasto-plastic model'/)
1100 FORMAT(
1' Mass density ..... =',G15.6/
2' Young's modulus ..... =',G15.6/
3' Poisson's ratio ..... =',G15.6/
4' Damage evolution law exponent ..... =',G15.6/
5' Damage evolution law denominator ..... =',G15.6)
1200 FORMAT(
1' Number of points on hardening curve ..... =',I3//
2'      R      uniaxial yield stress '/')
1300 FORMAT(2(5X,G15.6))
C
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('ED0172')
C Set unsymmetric tangent stiffness flag
      UNSYM=.TRUE.
C
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS,DAMEXP,DAMDEN
      WRITE(16,1100)DENSE,YOUNG,POISS,DAMEXP,DAMDEN
      IF(YOUNG.LE.R0)CALL ERRPRT('ED0164')
      IF(DAMEXP.LE.R0)CALL ERRPRT('ED0170')
      IF(DAMDEN.LE.R0)CALL ERRPRT('ED0171')
C number of points on hardening curve
      READ(15,*)NHARD
      WRITE(16,1200)NHARD
      IF(NHARD.LT.2) CALL ERRPRT('ED0165')
C check dimensions of IPROPS
      IF(MIPROP.LT.3)CALL ERRPRT('ED0166')
      IPROPS(3)=NHARD
C check dimensions of RPROPS
      NRPROP=IPHARD+NHARD*2-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0167')
C
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
      RPROPS(4)=DAMEXP
      RPROPS(5)=DAMDEN
C Read and set hardening curve
      DO 10 IHARD=1,NHARD
         READ(15,*)RPROPS(IPHARD+IHARD*2-2),
1          RPROPS(IPHARD+IHARD*2-1)
         WRITE(16,1300)RPROPS(IPHARD+IHARD*2-2),
1          RPROPS(IPHARD+IHARD*2-1)
10 CONTINUE
C Check dimension of RSTAVA and LALGVA
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0168')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0169')
C
      RETURN
      END

```

```

      SUBROUTINE RDDMEL
1(      NTYPE      ,MRPROP      ,MRSTAV      ,RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( NRPROP=7      ,NRSTAV=4      )
      DIMENSION
1      RPROPS(*)
      DATA R0      ,RP5      ,R1      ,R2      ,R3      /
1      0.0D0,0.5D0,1.0D0,2.0D0,3.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR ISOTROPICALLY DAMAGED ISOTROPIC
C ELASTIC MATERIAL MODEL WITH PARTIAL MICROCRACK/VOID CLOSURE EFFECTS
C
C REFERENCE: Section 12.6.1
C*****
1000 FORMAT(' DAMAGED ELASTIC material (damaged HENCKY material in',
1      ' large strains)'/
2      ' with partial microcrack closure effect'/)
1010 FORMAT(
1' Mass density ..... =',G15.6/
2' Young's modulus ..... =',G15.6/
3' Poisson's ratio ..... =',G15.6/
4' Damage constant (D) ..... =',G15.6/
5' Crack closure parameter (h) ..... =',G15.6)
C
C Check that required stress state type is implemented
C
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('ED0173')
C
C Set unsymmetric tangent stiffness flag
C
      UNSYM=.FALSE.
C
C Read and echo material properties
C
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS
      READ(15,*)DAMAGE,HFACT
      WRITE(16,1010)DENSE,YOUNG,POISS,DAMAGE,HFACT
C Perform checks
      IF(YOUNG.LT.R0)CALL ERRPRT('ED0174')
      IF(POISS.LE.-R1.AND.POISS.GE.RP5)CALL ERRPRT('ED0175')
      IF(DAMAGE.LT.R0.OR.DAMAGE.GE.R1)CALL ERRPRT('ED0176')
      IF(HFACT.LT.R0.OR.HFACT.GT.R1)CALL ERRPRT('ED0177')
C
C Check dimensioning
C
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0193')
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0194')
C
C Set vector of real material properties
C
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
      RPROPS(4)=DAMAGE
      RPROPS(5)=HFACT
      RPROPS(6)=GMODU
      RPROPS(7)=BULK
C
      RETURN
      END

```



```

SUBROUTINE RDDP
1( IPROPS ,MIPROP ,MLALGV ,MRALGV ,MRPROP ,
2 MRSTAV ,RPROPS ,UNSYM )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
LOGICAL UNSYM
PARAMETER( IPHARD=7 ,NIPROP=3 ,NLALGV=3 ,NRALGV=3 ,NRSTAV=5 )
DIMENSION
1 IPROPS(*) ,RPROPS(*)
DATA R0 ,R1 ,R2 ,R3 ,R6 ,R9 ,R12 ,R90 ,R180 /
1 0.0D0,1.0D0,2.0D0,3.0D0,6.0D0,9.0D0,12.0D0,90.0D0,180.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR DRUCKER-PRAGER TYPE
C ELASTO-PLASTIC MATERIAL WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW
C RULE AND NON-LINEAR ISOTROPIC HARDENING
C
C REFERENCE: Section 8.3
C*****
1000 FORMAT(' Elasto-plastic with DRUCKER-PRAGER yield criterion'/)
1100 FORMAT(
1 ' Mass density ..... =',G15.6/
2 ' Young's modulus ..... =',G15.6/
3 ' Poisson's ratio ..... =',G15.6/
4 ' Friction angle (degrees) ..... =',G15.6/
5 ' Dilatancy angle (degrees) ..... =',G15.6)
1200 FORMAT(
1 ' Friction and dilatancy angles coincide ->',
2 ' ASSOCIATIVE flow')
1300 FORMAT(
1 ' Friction and dilatancy angles are distinct ->',
2 ' NON-ASSOCIATIVE flow')
1350 FORMAT(
1 ' OUTER EDGES match with Mohr-Coulomb criterion selected')
1360 FORMAT(
1 ' INNER EDGES match with Mohr-Coulomb criterion selected')
1370 FORMAT(
1 ' PLANE STRAIN match with Mohr-Coulomb criterion selected')
1380 FORMAT(
1 ' UNIAXIAL COMPRESSION and UNIAXIAL TENSION match with',/,
2 ' Mohr-Coulomb criterion selected')
1390 FORMAT(
1 ' BIAXIAL COMPRESSION and BIAXIAL TENSION match with',/,
2 ' Mohr-Coulomb criterion selected')
1400 FORMAT(
1 ' Number of points on hardening curve ..... =',I3//
2 ' Epstn cohesion'/)
1500 FORMAT(2(5X,G15.6))
C
C Read and echo some of the real properties
WRITE(16,1000)
READ(15,*)DENSE
READ(15,*)YOUNG,POISS,PHI,PSI,IFLAG
WRITE(16,1100)DENSE,YOUNG,POISS,PHI,PSI
C Check validity if some material properties
IF(YOUNG.LT.R0)THEN
CALL ERRPRT('ED0114')
ENDIF
IF(PHI.LT.R0.OR.PHI.GE.R90.OR.PSI.LT.R0.OR.PSI.GE.R90)THEN
CALL ERRPRT('ED0115')
ENDIF
C Check friction and dilatancy angles
IF(PHI.EQ.PSI)THEN
WRITE(16,1200)
ELSE
WRITE(16,1300)
ENDIF
C Echo selected approximation of Mohr-Coulomb criterion
C and set related material constants
ROOT3=SQRT(R3)
RADEG=ACOS(-R1)/R180
PHIRAD=PHI*RADEG
SINPHI=SIN(PHIRAD)
COSPHI=COS(PHIRAD)
TANPHI=TAN(PHIRAD)
PSIRAD=PSI*RADEG
SINPSI=SIN(PSIRAD)
TANPSI=TAN(PSIRAD)
IF(IFLAG.EQ.0)THEN
C Outer edge match with Mohr-Coulomb criterion
WRITE(16,1350)
DENOMA=ROOT3*(R3-SINPHI)
DENOMB=ROOT3*(R3-SINPSI)
ETA=R6*SINPHI/DENOMA
XI=R6*COSPHI/DENOMA
ETABAR=R6*SINPSI/DENOMB
ELSEIF(IFLAG.EQ.1)THEN
C Inner edge match with Mohr-Coulomb criterion
WRITE(16,1360)
DENOMA=ROOT3*(R3+SINPHI)
DENOMB=ROOT3*(R3+SINPSI)
ETA=R6*SINPHI/DENOMA
XI=R6*COSPHI/DENOMA
ETABAR=R6*SINPSI/DENOMB
ELSEIF(IFLAG.EQ.2)THEN
C Plane strain match with Mohr-Coulomb criterion
WRITE(16,1370)
DENOMA=SQRT(R9+R12*TANPHI**2)
DENOMB=SQRT(R9+R12*TANPSI**2)
ETA=R3*TANPHI/DENOMA

```

```

      XI=R3/DENOMA
      ETABAR=R3*TANPSI/DENOMB
      ELSEIF(IFLAG.EQ.3)THEN
C Match Mohr-Coulomb criterion in uniaxial compression and uniaxial
C tension
      WRITE(16,1380)
      ETA=R3*SINPHI/ROOT3
      XI=R2*COSPHI/ROOT3
      ETABAR=R3*SINPSI/ROOT3
      ELSEIF(IFLAG.EQ.4)THEN
C Match Mohr-Coulomb criterion in biaxial compression and biaxial
C tension
      WRITE(16,1390)
      ETA=R3*SINPHI/(R2*ROOT3)
      XI=R2*COSPHI/ROOT3
      ETABAR=R3*SINPSI/(R2*ROOT3)
      ELSE
      CALL ERRPRT('ED0116')
      ENDIF
C Hardening curve
      READ(15,*)NHARD
      WRITE(16,1400)NHARD
      IF(NHARD.LT.2)THEN
      CALL ERRPRT('ED0117')
      ENDIF
C Check dimensions of IPROPS
      IF(MIPROP.LT.NIPROP)CALL ERRPRT('ED0189')
      IPROPS(3)=NHARD
C Check dimensions of RPROPS
      NRPROP=IPHARD+NHARD*2-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0188')
C Store real properties in RPROPS
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
      RPROPS(4)=ETA
      RPROPS(5)=XI
      RPROPS(6)=ETABAR
      DO 10 IHARD=1,NHARD
      READ(15,*)RPROPS(IPHARD+IHARD*2-2),
1      RPROPS(IPHARD+IHARD*2-1)
      WRITE(16,1500)RPROPS(IPHARD+IHARD*2-2),
1      RPROPS(IPHARD+IHARD*2-1)
10 CONTINUE
C
C Check dimension of RSTAVA, LALGVA and RALGVA
C
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0190')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0191')
      IF(NRALGV.GT.MRALGV)CALL ERRPRT('ED0192')
C
C Set unsymmetric tangent stiffness flag
      IF(PHI.EQ.PSI)THEN
      UNSYM=.FALSE.
      ELSE
      UNSYM=.TRUE.
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE RDEL
1(  MRPROP ,MRSTAV ,RPROPS ,UNSYM )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( NRSTAV=4 )
      DIMENSION
1      RPROPS(*)
      DATA R0 ,RP5 ,R1 ,R2 ,R3 /
1      0.0D0,0.5D0,1.0D0,2.0D0,3.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR LINEAR ELASTIC MATERIAL MODEL
C*****
1000 FORMAT(' LINEAR ELASTIC material (HENCKY material in large',
1      ' strains)')
1010 FORMAT(
1      ' Mass density ..... =',G15.6/
2      ' Young's modulus ..... =',G15.6/
3      ' Poisson's ratio ..... =',G15.6)
C
C Set unsymmetric tangent stiffness flag
C
      UNSYM=.FALSE.
C
C Read and echo material properties
C
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS
      WRITE(16,1010)DENSE,YOUNG,POISS
      IF(YOUNG.LT.R0)CALL ERRPRT('ED0077')
      IF(POISS.LE.-R1.AND.POISS.GE.RP5)CALL ERRPRT('ED0078')
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
C
C Set vector of real material properties
C
      NRPROP=4
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0181')
      RPROPS(1)=DENSE
      RPROPS(2)=GMODU
      RPROPS(3)=BULK
      RPROPS(4)=YOUNG
C
C Check dimensioning of RSTAVA
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0182')
C
      RETURN
      END

```

```

      SUBROUTINE RDMC
1(   IPROPS      ,MIPROP      ,MLALGV      ,MRALGV      ,MRPROP      ,
2   MRSTAV      ,RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( IPHARD=7 ,NIPROP=3 ,NLALGV=5 ,NRALGV=2 ,NRSTAV=5 )
      DIMENSION
1   IPROPS(*)      ,RPROPS(*)
      DATA R0 ,R1 ,R90 ,R180 /
1   0.0D0,1.0D0,90.0D0,180.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR MOHR-COULOMB TYPE
C ELASTO-PLASTIC MATERIAL WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW
C RULE AND NON-LINEAR ISOTROPIC HARDENING
C
C REFERENCE: Section 8.2
C*****
1000 FORMAT(' Elasto-plastic with MOHR-COULOMB yield criterion'/)
1100 FORMAT(
1' Mass density ..... =',G15.6/
2' Young's modulus ..... =',G15.6/
3' Poisson's ratio ..... =',G15.6/
4' Friction angle (degrees) ..... =',G15.6/
5' Dilatancy angle (degrees) ..... =',G15.6)
1200 FORMAT(
1' Friction and dilatancy angles coincide ->',
2' ASSOCIATIVE flow')
1300 FORMAT(
1' Friction and dilatancy angles are distinct ->',
2' NON-ASSOCIATIVE flow')
1400 FORMAT(
1' Number of points on hardening curve ..... =',I3//
2' Epstn cohesion')
1500 FORMAT(2(5X,G15.6))
C
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS,PHI,PSI
      WRITE(16,1100)DENSE,YOUNG,POISS,PHI,PSI
C Check validity if some material properties
      IF(YOUNG.LT.R0)CALL ERRPRT('ED0136')
      IF(PHI.LT.R0.OR.PHI.GE.R90)CALL ERRPRT('ED0137')
C Check and echo if flow rule is associative or non-associative
      IF(PHI.EQ.PSI)THEN
        WRITE(16,1200)
      ELSE
        WRITE(16,1300)
      ENDIF
C Set material constants array
      RADEG=ACOS(-R1)/R180
      PHIRAD=PHI*RADEG
      SINPHI=SIN(PHIRAD)
      COSPHI=COS(PHIRAD)
      PSIRAD=PSI*RADEG
      SINPSI=SIN(PSIRAD)
C Hardening curve
      READ(15,*)NHARD
      WRITE(16,1400)NHARD
      IF(NHARD.LT.2)CALL ERRPRT('ED0138')
C Check dimension of IPROPS
      IF(MIPROP.LT.NIPROP)CALL ERRPRT('ED0187')
      IPROPS(3)=NHARD
C Check dimension of RPROPS
      NRPROP=IPHARD+NHARD*2-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0183')
C Store real properties in RPROPS
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
      RPROPS(4)=SINPHI
      RPROPS(5)=COSPHI
      RPROPS(6)=SINPSI
      DO 10 IHARD=1,NHARD
        READ(15,*)RPROPS(IPHARD+IHARD*2-2),
1        RPROPS(IPHARD+IHARD*2-1)
        WRITE(16,1500)RPROPS(IPHARD+IHARD*2-2),
1        RPROPS(IPHARD+IHARD*2-1)
      10 CONTINUE
C
C Check dimension of RSTAVA, LALGVA and RALGVA
C
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0184')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0185')
      IF(NRALGV.GT.MRALGV)CALL ERRPRT('ED0186')
C
C Set unsymmetric tangent stiffness flag for non-associative flow
      IF(PHI.NE.PSI)THEN
        UNSYM=.TRUE.
      ELSE
        UNSYM=.FALSE.
      ENDIF
C
      RETURN
      END

```

```

      SUBROUTINE RDOGD
1(      IPROPS      ,MIPROP      ,MRPROP      ,MRSTAV      ,RPROPS      ,
2      UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( IPOGDC=2      ,NIPROP=3      ,NRSTAV=4 )
      DIMENSION
1      IPROPS(*)      ,RPROPS(*)
C*****
C READS AND ECHOES MATERIAL PROPERTIES FOR OGDEN TYPE HYPERELASTIC
C MATERIAL MODEL
C
C REFERENCE: Section 13.2.2
C*****
1000 FORMAT(' Ogden type hyperelastic material'/)
1010 FORMAT(
1' Mass density ..... =',G15.6)
1020 FORMAT(
1' Number of terms in Ogden's strain-energy function.. =',I3//
2'      mu      alpha'/)
1030 FORMAT(2(5X,G15.6))
1040 FORMAT(
1' Bulk modulus ..... =',G15.6/)
C
C Set unsymmetric tangent stiffness flag
      UNSYM=.FALSE.
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      WRITE(16,1010)DENSE
C Ogden's constants
      READ(15,*)NOGTRM
      WRITE(16,1020)NOGTRM
      IF(NOGTRM.LT.1)CALL ERRPRT('ED0067')
C Check dimension of IPROPS
      IF(MIPROP.LT.NIPROP)CALL ERRPRT('ED0195')
      IPROPS(3)=NOGTRM
C Check dimension of RPROPS
      NRPROP=IPOGDC+NOGTRM*2
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0196')
C Store real properties in RPROPS
      RPROPS(1)=DENSE
      DO 10 I=1,NOGTRM
         READ(15,*)RPROPS(IPOGDC+I*2-2),RPROPS(IPOGDC+I*2-1)
         WRITE(16,1030)RPROPS(IPOGDC+I*2-2),RPROPS(IPOGDC+I*2-1)
      10 CONTINUE
C Bulk modulus
      READ(15,*)BULK
      RPROPS(IPOGDC+NOGTRM*2)=BULK
      WRITE(16,1040)BULK
C Check dimension of RSTAVA
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0197')
C
      RETURN
      END

```

```

      SUBROUTINE RDPDSC
1(  IPROPS      ,MIPROP      ,MLALGV      ,MRALGV      ,MRPROP      ,
2  MRSTAV      ,NLARGE      ,NTYPE      ,RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(  IPHARD=6      ,NIPROP=3      ,NLALGV=6      ,NRALGV=4      ,NRSTAV=5      )
C Arguments
      LOGICAL UNSYM
      DIMENSION
1  IPROPS(MIPROP)      ,RPROPS(MRPROP)
C Local data
      DATA R1      ,R180      /
1  1.0D0,180.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR THE LARGE STRAIN PLANAR
C DOUBLE-SLIP SINGLE CRYSTAL ELASTO-PLASTIC MODEL WITH NON-LINEAR
C (PIECEWISE LINEAR) ISOTROPIC TAYLOR HARDENING
C*****
1000 FORMAT(' Large strain planar double-slip SINGLE CRYSTAL'/)
1100 FORMAT(
1' Mass density ..... =',G15.6/
2' Shear modulus ..... =',G15.6/
3' Bulk modulus ..... =',G15.6/
4' Initial orientation of FIRST SLIP SYSTEM relative' /
5' to X-axis (degrees, counterclockwise-positive) .... =',G15.6/
6' Initial orientation of SECOND SLIP SYSTEM relative' /
7' to first syst. (degrees, counterclockwise-positive) =',G15.6)
1200 FORMAT(/
1' Number of points on Taylor hardening curve ..... =',I3//
2' Accum. slip Resolved Schmid yield stress '/')
1300 FORMAT(2(5X,G15.6))
C
C Set unsymmetric tangent stiffness flag
      UNSYM=.TRUE.
C Check that stress state type and large strain flags are compatible
C with the present model
      IF(NTYPE.NE.2)CALL ERRPRT('ED0154')
      IF(NLARGE.NE.1)CALL ERRPRT('ED0155')
C
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)GMODU,BULK,THETA,BETA
      WRITE(16,1100)DENSE,GMODU,BULK,THETA,BETA
C number of points on hardening curve
      READ(15,*)NHARD
      WRITE(16,1200)NHARD
      IF(NHARD.LT.2) CALL ERRPRT('ED0148')
C check dimensions of IPROPS
      IF(NIPROP.GT.MIPROP)CALL ERRPRT('ED0149')
      IPROPS(3)=NHARD
C check dimensions of RPROPS
      NRPROP=IPHARD+NHARD*2-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0150')
C convert angles into radians
      RADEG=ACOS(-R1)/R180
      THETA=RADEG*THETA
      BETA=RADEG*BETA
      RPROPS(1)=DENSE
      RPROPS(2)=GMODU
      RPROPS(3)=BULK
      RPROPS(4)=THETA
      RPROPS(5)=BETA
C Read and set hardening curve
      DO 10 IPHARD=1,NHARD
          READ(15,*)RPROPS(IPHARD+IPHARD*2-2),
1          RPROPS(IPHARD+IPHARD*2-1)
          WRITE(16,1300)RPROPS(IPHARD+IPHARD*2-2),
1          RPROPS(IPHARD+IPHARD*2-1)
      10 CONTINUE
C Check dimension of RSTAVA, RALGVA and LALGVA
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0151')
      IF(NRALGV.GT.MRALGV)CALL ERRPRT('ED0152')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0153')
C
      RETURN
      END

```

```

      SUBROUTINE RDTR
1(  IPROPS      ,MIPROP      ,MLALGV      ,MRALGV      ,MRPROP      ,
2  MRSTAV      ,NLARGE      ,NTYPE      ,RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( IPHARD=4 ,NIPROP=3 ,NLALGV=4 ,NRALGV=2 ,NRSTAV=5 )
      DIMENSION
1  IPROPS(*)      ,RPROPS(*)
      DATA R0 / 0.0D0 /
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR TRESCA TYPE ELASTO-PLASTIC
C MATERIAL WITH NON-LINEAR ISOTROPIC HARDENING
C
C REFERENCE: Section 8.1
C*****
1000 FORMAT(' Elasto-plastic with TRESCA yield criterion'/)
1100 FORMAT(
1' Mass density ..... =',G15.6/
2' Young's modulus ..... =',G15.6/
3' Poisson's ratio ..... =',G15.6)
1200 FORMAT(/
1' Number of points on hardening curve ..... =',I3//
2'      Epstn      uniaxial yield stress '/')
1300 FORMAT(2(5X,G15.6))
C
C Model not yet implemented for large strains with plane stress
      IF(NLARGE.EQ.1.AND.NTYPE.EQ.1)CALL ERRPRT('ED0198')
C Set unsymmetric tangent stiffness flag
      UNSYM=.FALSE.
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS
      WRITE(16,1100)DENSE,YOUNG,POISS
      IF(YOUNG.LT.R0)CALL ERRPRT('ED0107')
C Hardening curve
      READ(15,*)NHARD
      WRITE(16,1200)NHARD
      IF(NHARD.LT.2) CALL ERRPRT('ED0108')
C Check dimensions of IPROPS
      IF(MIPROP.LT.NIPROP)CALL ERRPRT('ED0109')
      IPROPS(3)=NHARD
C Check dimensions of RPROPS
      NRPROP=IPHARD+NHARD*2-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0110')
C Store real properties in RPROPS
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
C
C Read and set hardening curve
C
      DO 10 IHARD=1,NHARD
          READ(15,*)RPROPS(IPHARD+IHARD*2-2),
1          RPROPS(IPHARD+IHARD*2-1)
          WRITE(16,1300)RPROPS(IPHARD+IHARD*2-2),
1          RPROPS(IPHARD+IHARD*2-1)
10 CONTINUE
C
C Check dimension of RSTAVA, LALGVA and RALGVA
C
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0111')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0112')
      IF(NRALGV.GT.MRALGV)CALL ERRPRT('ED0113')
C
      RETURN
      END

```

```

      SUBROUTINE RDVM
1(   IPROPS      ,MIPROP      ,MLALGV      ,MRPROP      ,MRSTAV      ,
2   RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( IPHARD=4      ,NLALGV=2      ,NRSTAV=5 )
      DIMENSION
1   IPROPS(*)      ,RPROPS(*)
      DATA R0      /0.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR VON MISES TYPE ELASTO-PLASTIC
C MATERIAL WITH NON-LINEAR (PIECEWISE LINEAR) ISOTROPIC HARDENING
C
C REFERENCE: Section 7.3.5
C*****
1000 FORMAT(' Elasto-plastic with VON MISES yield criterion'/)
1100 FORMAT(
1' Mass density ..... =',G15.6/
2' Young's modulus ..... =',G15.6/
3' Poisson's ratio ..... =',G15.6)
1200 FORMAT(
1' Number of points on hardening curve ..... =',I3//
2'      Epstn      uniaxial yield stress '/')
1300 FORMAT(2(5X,G15.6))
C
C Set unsymmetric tangent stiffness flag
      UNSYM=.FALSE.
C
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS
      WRITE(16,1100)DENSE,YOUNG,POISS
      IF(YOUNG.LE.R0)CALL ERRPRT('ED0100')
C number of points on hardening curve
      READ(15,*)NHARD
      WRITE(16,1200)NHARD
      IF(NHARD.LT.2) CALL ERRPRT('ED0101')
C check dimensions of IPROPS
      IF(MIPROP.LT.3)CALL ERRPRT('ED0102')
      IPROPS(3)=NHARD
C check dimensions of RPROPS
      NRPROP=IPHARD+NHARD*2-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0103')
C
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
C Read and set hardening curve
      DO 10 IHARD=1,NHARD
         READ(15,*)RPROPS(IPHARD+IHARD*2-2),
1          RPROPS(IPHARD+IHARD*2-1)
         WRITE(16,1300)RPROPS(IPHARD+IHARD*2-2),
1          RPROPS(IPHARD+IHARD*2-1)
      10 CONTINUE
C Check dimension of RSTAVA and LALGVA
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0104')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0105')
C
      RETURN
      END

```



```

      SUBROUTINE RDVMMX
1(   IPROPS      ,MIPROP      ,MLALGV      ,MRPROP      ,MRSTAV      ,
2   NLARGE      ,NTYPE      ,RPROPS      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      PARAMETER( IPHARD=4 ,NLALGV=2 ,NRSTAV=9 )
      DIMENSION
1   IPROPS(*)      ,RPROPS(*)
      DATA R0 /0.0D0/
C*****
C READ AND ECHO MATERIAL PROPERTIES FOR VON MISES TYPE ELASTO-PLASTIC
C MATERIAL WITH NON-LINEAR (PIECEWISE LINEAR) MIXED HARDENING
C
C REFERENCE: Section 7.6.1
C*****
1000 FORMAT(' VON MISES elasto-plastic model with mixed hardening'/)
1100 FORMAT(
1' Mass density ..... =',G15.6/
2' Young's modulus ..... =',G15.6/
3' Poisson's ratio ..... =',G15.6)
1200 FORMAT(
1' Number of points on hardening curves ..... =',I3//
2'      Epbar      isotr.hard. stress ',
3'      kin.hard. stress'/)
1300 FORMAT(3(5X,G15.6))
C
C Model currently implemented for plane strain and axisymmetric states
C only
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('ED0156')
C Only small strain implementation is currently available
      IF(NLARGE.EQ.1)CALL ERRPRT('ED0157')
C
C Set unsymmetric tangent stiffness flag
      UNSYM=.FALSE.
C Read and echo some of the real properties
      WRITE(16,1000)
      READ(15,*)DENSE
      READ(15,*)YOUNG,POISS
      WRITE(16,1100)DENSE,YOUNG,POISS
      IF(YOUNG.LT.R0)CALL ERRPRT('ED0158')
C number of points on hardening curve
      READ(15,*)NHARD
      WRITE(16,1200)NHARD
      IF(NHARD.LT.2) CALL ERRPRT('ED0159')
C check dimensions of IPROPS
      IF(MIPROP.LT.3)CALL ERRPRT('ED0160')
      IPROPS(3)=NHARD
C check dimensions of RPROPS
      NRPROP=IPHARD+NHARD*4-1
      IF(NRPROP.GT.MRPROP)CALL ERRPRT('ED0161')
C
      RPROPS(1)=DENSE
      RPROPS(2)=YOUNG
      RPROPS(3)=POISS
C Read and set isotropic and kinematic hardening curves
      IPIHAR=IPHARD
      IPKHAR=IPHARD+2*NHARD
      DO 10 IHARD=1,NHARD
         READ(15,*)RPROPS(IPIHAR+IHARD*2-2),RPROPS(IPIHAR+IHARD*2-1),
1          RPROPS(IPKHAR+IHARD*2-1)
         RPROPS(IPKHAR+IHARD*2-2)=RPROPS(IPIHAR+IHARD*2-2)
         WRITE(16,1300)RPROPS(IPHARD+IHARD*2-2),RPROPS(IPHARD+IHARD*2-1),
1          RPROPS(IPKHAR+IHARD*2-1)
10 CONTINUE
C Check dimension of RSTAVA and LALGVA
      IF(NRSTAV.GT.MRSTAV)CALL ERRPRT('ED0162')
      IF(NLALGV.GT.MLALGV)CALL ERRPRT('ED0163')
C
      RETURN
      END

```

```

      SUBROUTINE RSO4
1(   IELPRP      ,NDATF      ,NRESF      ,RELPRP      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(   MGAUSP=4      ,MNODEG=2      ,NDIME=2      ,NDOFEL=8      ,NEDGEL=4      ,
2   NGAUSB=1      ,NNODE=4      )
      LOGICAL UNSYM
      DIMENSION
1   IELPRP(*)      ,RELPRP(*)
      DIMENSION
1   NORDEB(NNODE,NEDGEL),POSGP(2,MGAUSP)      ,POSGPB(NGAUSB)      ,
2   WEIGP(MGAUSP)      ,WEIGPB(NGAUSB)
C*****
C READ INPUT DATA AND SET PROPERTIES FOR ELEMENT TYPE 'QUAD_4'
C (STANDARD ISOPARAMETRIC 4-NODED BI-LINEAR QUADRILATERAL)
C
C REFERENCE: Figure 4.5
C*****
1000 FORMAT(' QUAD_4 (standard 4-noded quadrilateral)'/
1   ' Integration rule: ',I2,' gauss points')
C
C Read number of gauss points for domain integration
C -----
      READ(NDATF,*)NGAUSP
      WRITE(NRESF,1000)NGAUSP
      IF(NGAUSP.NE.1.AND.NGAUSP.NE.4)CALL ERRPRT('ED0033')
C Set element integer properties (stored in vector IELPRP)
C -----
C total number of nodes and gauss points for domain integration
      IELPRP(3)=NNODE
      IELPRP(4)=NGAUSP
C number of degrees of freedom of the element
      IELPRP(5)=NDOFEL
C number of edges of the element
      IELPRP(6)=NEDGEL
C maximum number of nodes per edge
      IELPRP(7)=MNODEG
C number of gauss points for boundary integration
      IELPRP(8)=NGAUSB
C node numbering order on boundaries (set correspondance between local
C element node numbers and "edge" node numbering for boundary
C integration)
      NORDEB(1,1)=1
      NORDEB(2,1)=2
      NORDEB(3,1)=0
      NORDEB(4,1)=0
      NORDEB(1,2)=0
      NORDEB(2,2)=1
      NORDEB(3,2)=2
      NORDEB(4,2)=0
      NORDEB(1,3)=0
      NORDEB(2,3)=0
      NORDEB(3,3)=1
      NORDEB(4,3)=2
      NORDEB(1,4)=2
      NORDEB(2,4)=0
      NORDEB(3,4)=0
      NORDEB(4,4)=1
      IPOS=9
      DO 20 IEDGEL=1,NEDGEL
        DO 10 INODE=1,NNODE
          IELPRP(IPOS)=NORDEB(INODE,IEDGEL)
          IPOS=IPOS+1
        10 CONTINUE
      20 CONTINUE
C Set element real properties (stored in vector RELPRP)
C -----
C gaussian constants for domain integration
      CALL GAUS2D
1(   'QUA'      ,NGAUSP      ,POSGP      ,WEIGP      )
      IPOS=1
      DO 30 IGAUSP=1,NGAUSP
        RELPRP(IPOS)=POSGP(1,IGAUSP)
        RELPRP(IPOS+1)=POSGP(2,IGAUSP)
        IPOS=IPOS+NDIME
      30 CONTINUE
      IPOS=NGAUSP*NDIME+1
      DO 40 IGAUSP=1,NGAUSP
        RELPRP(IPOS)=WEIGP(IGAUSP)
        IPOS=IPOS+1
      40 CONTINUE
C set matrix of coefficients for extrapolation from gauss points to
C nodes
      IPOS=NGAUSP*NDIME+NGAUSP+1
      CALL EXO4
1(   NGAUSP      ,RELPRP(IPOS))
C gaussian constants for boundary integration (intergration over edges)
      CALL GAUS1D
1(   NGAUSB      ,POSGPB      ,WEIGPB      )
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+1
      DO 50 IGAUSB=1,NGAUSB
        RELPRP(IPOS)=POSGPB(IGAUSB)
        IPOS=IPOS+1
      50 CONTINUE
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+NGAUSB+1
      DO 60 IGAUSB=1,NGAUSB
        RELPRP(IPOS)=WEIGPB(IGAUSB)
        IPOS=IPOS+1

```

```
      60 CONTINUE
C Set unsymmetric solver flag
C -----
      UNSYM=.FALSE.
C
      RETURN
      END
```

```

      SUBROUTINE RSO4FB
1(      IELPRP      ,NDATF      ,NRESF      ,NTYPE      ,RELPRP      ,
2      UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(      MGAUSP=4      ,MNODEG=2      ,NDIME=2      ,NDOFEL=8      ,NEDGEL=4      ,
2      NGAUSB=1      ,NNODE=4      )
      LOGICAL UNSYM
      DIMENSION
1      IELPRP(*)      ,RELPRP(*)
      DIMENSION
1      NORDEB(NNODE,NEDGEL),POSGP(2,MGAUSP)      ,POSGPB(NGAUSB)      ,
2      WEIGP(MGAUSP)      ,WEIGPB(NGAUSB)
      DATA R0 /
1      0.0D0/
C*****
C READ INPUT DATA AND SET PROPERTIES FOR ELEMENT TYPE 'QUAD_4_FBAR'
C (F-BAR 4-NODED BI-LINEAR QUADRILATERAL FOR PLANE STRAIN AND
C AXISYMMETRIC ANALYSIS)
C*****
1000 FORMAT(' QUAD_4_FBAR (F-Bar 4-noded quadrilateral)'/
1      ' Integration rule: ',I2,' gauss points')
C
C Stops program if not plane strain neither axisymmetric
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)THEN
          CALL ERRPRT('ED0147')
      ENDIF
C
C Read number of gauss points for domain integration
C -----
      READ(NDATF,*)NGAUSP
      WRITE(NRESF,1000)NGAUSP
      IF(NGAUSP.NE.4)CALL ERRPRT('ED0099')
C Set element integer properties (stored in vector IELPRP)
C -----
C total number of nodes and gauss points for domain integration
      IELPRP(3)=NNODE
      IELPRP(4)=NGAUSP
C number of degrees of freedom of the element
      IELPRP(5)=NDOFEL
C number of edges of the element
      IELPRP(6)=NEDGEL
C maximum number of nodes per edge
      IELPRP(7)=MNODEG
C number of gauss points for boundary integration
      IELPRP(8)=NGAUSB
C node numbering order on boundaries (set correspondance between local
C element node numbers and "edge" node numbering for boundary
C integration)
      NORDEB(1,1)=1
      NORDEB(2,1)=2
      NORDEB(3,1)=0
      NORDEB(4,1)=0
      NORDEB(1,2)=0
      NORDEB(2,2)=1
      NORDEB(3,2)=2
      NORDEB(4,2)=0
      NORDEB(1,3)=0
      NORDEB(2,3)=0
      NORDEB(3,3)=1
      NORDEB(4,3)=2
      NORDEB(1,4)=2
      NORDEB(2,4)=0
      NORDEB(3,4)=0
      NORDEB(4,4)=1
      IPOS=9
      DO 20 IEDGEL=1,NEDGEL
          DO 10 INODE=1,NNODE
              IELPRP(IPOS)=NORDEB(INODE,IEDGEL)
              IPOS=IPOS+1
          10 CONTINUE
      20 CONTINUE
C Set element real properties (stored in vector RELPRP)
C -----
C gaussian constants for domain integration
      CALL GAUS2D
1(      'QUA'      ,NGAUSP      ,POSGP      ,WEIGP      )
      IPOS=1
      DO 30 IGAUSP=1,NGAUSP
          RELPRP(IPOS)=POSGP(1,IGAUSP)
          RELPRP(IPOS+1)=POSGP(2,IGAUSP)
          IPOS=IPOS+NDIME
      30 CONTINUE
      IPOS=NGAUSP*NDIME+1
      DO 40 IGAUSP=1,NGAUSP
          RELPRP(IPOS)=WEIGP(IGAUSP)
          IPOS=IPOS+1
      40 CONTINUE
C set matrix of coefficients for extrapolation from gauss points to
C nodes
      IPOS=NGAUSP*NDIME+NGAUSP+1
      CALL EXQ4FB
1(      RELPRP(IPOS)      )
C gaussian constants for boundary integration (intergration over edges)
      CALL GAUS1D
1(      NGAUSB      ,POSGPB      ,WEIGPB      )
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+1
      DO 50 IGAUSB=1,NGAUSB

```

```

        RELPRP(IPOS)=POSGPB(IGAUSB)
        IPOS=IPOS+1
50 CONTINUE
        IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+NGAUSB+1
        DO 60 IGAUSB=1,NGAUSB
            RELPRP(IPOS)=WEIGPB(IGAUSB)
            IPOS=IPOS+1
        60 CONTINUE
C set coordinates of the element centroid
        EXISC=R0
        ETASC=R0
        IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+2*NGAUSB+1
        RELPRP(IPOS)=EXISC
        RELPRP(IPOS+1)=ETASC
C Set unsymmetric solver flag
C -----
        UNSYM=.TRUE.
C
        RETURN
END

```

```

      SUBROUTINE RSQ8
1(   IELPRP      ,NDATF      ,NRESF      ,RELPRP      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(   MGAUSP=9      ,MNODEG=3      ,NDIME=2      ,NDOFEL=16      ,NEDGEL=4      ,
2   NGAUSB=2      ,NNODE=8      )
      LOGICAL UNSYM
      DIMENSION
1   IELPRP(*)      ,RELPRP(*)
      DIMENSION
1   NORDEB(NNODE,NEDGEL),POSGP(2,MGAUSP)      ,POSGPB(NGAUSB)      ,
2   WEIGP(MGAUSP)      ,WEIGPB(NGAUSB)
C*****
C READ INPUT DATA AND SET PROPERTIES FOR ELEMENT TYPE 'QUAD_8'
C (STANDARD ISOPARAMETRIC 8-NODED QUADRILATERAL)
C
C REFERENCE: Section 4.1.3
C*****
1000 FORMAT(' QUAD_8 (standard 8-noded quadrilateral)'/
1   ' Integration rule: ',I2,' gauss points')
C
C Read number of gauss points for domain integration
C -----
      READ(NDATF,*)NGAUSP
      WRITE(NRESF,1000)NGAUSP
      IF(NGAUSP.NE.1.AND.INGAUSP.NE.4.AND.
1   NGAUSP.NE.5.AND.INGAUSP.NE.9)THEN
      CALL ERRPR1('ED0008')
      ENDIF
C Set element integer properties (stored in vector IELPRP)
C -----
C total number of nodes and gauss points for domain integration
      IELPRP(3)=NNODE
      IELPRP(4)=NGAUSP
C number of degrees of freedom of the element
      IELPRP(5)=NDOFEL
C number of edges of the element
      IELPRP(6)=NEDGEL
C maximum number of nodes per edge
      IELPRP(7)=MNODEG
C number of gauss points for boundary integration
      IELPRP(8)=NGAUSB
C node numbering order on boundaries (set correspondance between local
C element node numbers and "edge" node numbering for boundary
C integration)
      NORDEB(1,1)=1
      NORDEB(2,1)=2
      NORDEB(3,1)=3
      NORDEB(4,1)=0
      NORDEB(5,1)=0
      NORDEB(6,1)=0
      NORDEB(7,1)=0
      NORDEB(8,1)=0
      NORDEB(1,2)=0
      NORDEB(2,2)=0
      NORDEB(3,2)=1
      NORDEB(4,2)=2
      NORDEB(5,2)=3
      NORDEB(6,2)=0
      NORDEB(7,2)=0
      NORDEB(8,2)=0
      NORDEB(1,3)=0
      NORDEB(2,3)=0
      NORDEB(3,3)=0
      NORDEB(4,3)=0
      NORDEB(5,3)=1
      NORDEB(6,3)=2
      NORDEB(7,3)=3
      NORDEB(8,3)=0
      NORDEB(1,4)=3
      NORDEB(2,4)=0
      NORDEB(3,4)=0
      NORDEB(4,4)=0
      NORDEB(5,4)=0
      NORDEB(6,4)=0
      NORDEB(7,4)=1
      NORDEB(8,4)=2
      IPOS=9
      DO 20 IEDGEL=1,NEDGEL
      DO 10 INODE=1,NNODE
      IELPRP(IPOS)=NORDEB(INODE,IEDGEL)
      IPOS=IPOS+1
10   CONTINUE
20   CONTINUE
C Set element real properties (stored in vector RELPRP)
C -----
C gaussian constants for domain integration
      CALL GAUS2D
1(   'QUA'      ,NGAUSP      ,POSGP      ,WEIGP      )
      IPOS=1
      DO 30 IGAUSP=1,NGAUSP
      RELPRP(IPOS)=POSGP(1,IGAUSP)
      RELPRP(IPOS+1)=POSGP(2,IGAUSP)
      IPOS=IPOS+NDIME
30   CONTINUE
      IPOS=NGAUSP*NDIME+1
      DO 40 IGAUSP=1,NGAUSP
      RELPRP(IPOS)=WEIGP(IGAUSP)

```

```

      IPOS=IPOS+1
40 CONTINUE
C set matrix of coefficients for extrapolation from gauss points to
C nodes
      IPOS=NGAUSP*NDIME+NGAUSP+1
      CALL EXQ8
      1(   NGAUSP      ,RELPRP(IPOS))
C gaussian constants for boundary integration (intergration over edges)
      CALL GAUS1D
      1(   NGAUSB      ,POSGPB      ,WEIGPB      )
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+1
      DO 50 IGAUSB=1,NGAUSB
          RELPRP(IPOS)=POSGPB(IGAUSB)
          IPOS=IPOS+1
50 CONTINUE
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+NGAUSB+1
      DO 60 IGAUSB=1,NGAUSB
          RELPRP(IPOS)=WEIGPB(IGAUSB)
          IPOS=IPOS+1
60 CONTINUE
C Set unsymmetric solver flag
C -----
      UNSYM=.FALSE.
C
      RETURN
      END

```

```

      SUBROUTINE RST3
1(   IELPRP      ,NRESF      ,RELPRP      ,UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(   MGAUSP=1      ,MNODEG=2      ,NDIME=2      ,NDOFEL=6      ,NEDGEL=3      ,
2   NGAUSB=1      ,NNODE=3      )
      LOGICAL UNSYM
      DIMENSION
1   IELPRP(*)      ,RELPRP(*)
      DIMENSION
1   NORDEB(NNODE,NEDGEL),POSGP(2,MGAUSP)      ,POSGPB(NGAUSB)      ,
2   WEIGP(MGAUSP)      ,WEIGPB(NGAUSB)
C*****
C READ INPUT DATA AND SET PROPERTIES FOR ELEMENT TYPE 'TRI_3'
C (STANDARD ISOPARAMETRIC 3-NODED LINEAR TRIANGLE)
C
C REFERENCE: Figure 4.4
C*****
1000 FORMAT(' TRI_3 (standard 3-noded quadrilateral)'/
1   ' with 1 gauss point')
      WRITE(NRESF,1000)
C
C Set number of gauss points for domain integration
C -----
      NGAUSP=1
C Set element integer properties (stored in vector IELPRP)
C -----
C total number of nodes and gauss points for domain integration
      IELPRP(3)=NNODE
      IELPRP(4)=NGAUSP
C number of degrees of freedom of the element
      IELPRP(5)=NDOFEL
C number of edges of the element
      IELPRP(6)=NEDGEL
C maximum number of nodes per edge
      IELPRP(7)=MNODEG
C number of gauss points for boundary integration
      IELPRP(8)=NGAUSB
C node numbering order on boundaries (set correspondance between local
C element node numbers and "edge" node numbering for boundary
C integration)
      NORDEB(1,1)=1
      NORDEB(2,1)=2
      NORDEB(3,1)=0
      NORDEB(1,2)=0
      NORDEB(2,2)=1
      NORDEB(3,2)=2
      NORDEB(1,3)=2
      NORDEB(2,3)=0
      NORDEB(3,3)=1
      IPOS=9
      DO 20 IEDGEL=1,NEDGEL
        DO 10 INODE=1,NNODE
          IELPRP(IPOS)=NORDEB(INODE,IEDGEL)
          IPOS=IPOS+1
        10 CONTINUE
      20 CONTINUE
C Set element real properties (stored in vector RELPRP)
C -----
C gaussian constants for domain integration
      CALL GAUS2D
1(   'TRI'      ,NGAUSP      ,POSGP      ,WEIGP      )
      IPOS=1
      DO 30 IGAUSP=1,NGAUSP
        RELPRP(IPOS)=POSGP(1,IGAUSP)
        RELPRP(IPOS+1)=POSGP(2,IGAUSP)
        IPOS=IPOS+NDIME
      30 CONTINUE
      IPOS=NGAUSP*NDIME+1
      DO 40 IGAUSP=1,NGAUSP
        RELPRP(IPOS)=WEIGP(IGAUSP)
        IPOS=IPOS+1
      40 CONTINUE
C set matrix of coefficients for extrapolation from gauss points to
C nodes
      IPOS=NGAUSP*NDIME+NGAUSP+1
      CALL EXT3
1(   RELPRP(IPOS)      )
C gaussian constants for boundary integration (intergration over edges)
      CALL GAUS1D
1(   NGAUSB      ,POSGPB      ,WEIGPB      )
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+1
      DO 50 IGAUSB=1,NGAUSB
        RELPRP(IPOS)=POSGPB(IGAUSB)
        IPOS=IPOS+1
      50 CONTINUE
      IPOS=NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+NGAUSB+1
      DO 60 IGAUSB=1,NGAUSB
        RELPRP(IPOS)=WEIGPB(IGAUSB)
        IPOS=IPOS+1
      60 CONTINUE
C Set unsymmetric solver flag
C -----
      UNSYM=.FALSE.
C
      RETURN
      END

```



```

SUBROUTINE RSTART
1( DFOLD ,DLENG ,DLENGO ,DLENM ,DLAMD ,
2 IFNEG ,IINCS ,MXFRON ,NOUTP ,TFACT ,
3 TFACTO ,UNSYM ,RSTINP ,RSTOUT ,MODE ,
4 INCRST )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
INCLUDE '../MAXDIM.INC'
INCLUDE '../MATERIAL.INC'
INCLUDE '../ELEMENTS.INC'
INCLUDE '../GLDBASE.INC'

C
DIMENSION NOUTP(5)
LOGICAL UNSYM
CHARACTER*256 RSTINP,RSTOUT
C*****
C WRITE DATA TO OUTPUT RE-START FILE AND READ DATA FROM INPUT RE-START
C FILE
C
C REFERENCE: Figures 5.1-3
C*****
1000 FORMAT(//15X,
1 'Writing converged results to re-start file ...'//)
1010 FORMAT(///15X,
1 'Reading data from input re-start file ...')

C
C IF(MODE.EQ.1)THEN
C Writing (output) mode
C =====
C Check re-start output flag
C
IF(NOUTP(5).EQ.0)GOTO 999
IF(NOUTP(5).NE.0.AND.NALGO.LT.0)THEN
IF(MOD(IINCS,NOUTP(5)).NE.0)GOTO 999
ENDIF

C
INCRST=IINCS
WRITE(*,1000)
WRITE(16,1000)
OPEN(UNIT=17,FILE=RSTOUT,STATUS='UNKNOWN',FORM='UNFORMATTED')

C
C Write some global variables first
C -----
WRITE(17)DFOLD,DLENG,DLENGO,DLENM,DLAMD,IFNEG,IINCS,MXFRON,
1 TFACT,TFACTO,UNSYM

C
C Then write all common blocks
C -----
C COMMON/CONTRL/
WRITE(17)
1 NDOFN ,NELEM ,NGRUP ,NPOIN ,NTOTV ,
2 NVFIX ,NTYPE ,NALGO ,NARCL ,NDIME ,
3 NLARGE ,NAXIS
C COMMON/CORE /
WRITE(17)
1 FIXED ,STFOR ,
2 TOFOR ,ELOAD ,
3 ELOADO ,RLOAD
C COMMON/MATERL/
WRITE(17)
1 RPROPS ,IPROPS
C COMMON/MESH /
WRITE(17)
1 ANGLE ,COORD ,PRESC ,
2 IELTID ,IFFIX ,IGRPID ,
3 LNODS ,MASTER ,MATTID ,
4 NOFIX ,NVALEN
C COMMON/ELEMEN/
WRITE(17)
1 RELPRP ,IELPRP
C COMMON/RESULT/
WRITE(17)
1 DITER ,DINCR ,DINCRO ,
2 DTANG ,TDISP ,TDISPO ,
3 TREAC
C COMMON/STATE /
WRITE(17)
1 RALGVA ,RSTAVA ,
2 STRSG ,THKGP ,
3 LALGVA

C
C ELSEIF(MODE.EQ.0)THEN
C
C Reading (input) mode
C =====
C
WRITE(*,1010)
OPEN(UNIT=17,FILE=RSTINP,STATUS='OLD',FORM='UNFORMATTED')

C
C Read some global variables first
C -----
READ(17)DFOLD,DLENG,DLENGO,DLENM,DLAMD,IFNEG,IINCS,MXFRON,
1 TFACT,TFACTO,UNSYM
C

```

```

C Then read all common blocks
C -----
C COMMON/CONTRL/
  READ(17)
  1   NDOFN      ,NELEM      ,NGRUP      ,NPOIN      ,NTOTV      ,
  2   NVFIX      ,NTYPE      ,NALGO      ,NARCL      ,NDIME      ,
  3   NLARGE      ,NAXIS
C COMMON/CORE /
  READ(17)
  1   FIXED      ,STFOR      ,
  2   TOFOR      ,ELOAD      ,
  3   ELOADO      ,RLOAD
C COMMON/MATERL/
  READ(17)
  1   RPROPS      ,IPROPS
C COMMON/MESH /
  READ(17)
  1   ANGLE      ,COORD      ,PRESC      ,
  2   IELTID      ,IFFIX      ,IGRPID      ,
  3   LNODS      ,MASTER      ,MATTID      ,
  4   NOFIX      ,NVALEN
C COMMON/ELEMEN/
  READ(17)
  1   RELPRP      ,IELPRP
C COMMON/RESULT/
  READ(17)
  1   DITER      ,DINCR      ,DINCRO      ,
  2   DTANG      ,TDISP      ,TDISPO      ,
  3   TREAC
C COMMON/STATE /
  READ(17)
  1   RALGVA      ,RSTAVA      ,
  2   STRSG      ,THKGP      ,
  3   LALGVA
C
  ENDIF
C
  CLOSE(UNIT=17,STATUS='KEEP')
C
999 CONTINUE
  RETURN
  END

```

```

SUBROUTINE RSTCHK( RSTINP      ,RSTRT      )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
LOGICAL RSTRT
CHARACTER*256 RSTINP

C
LOGICAL AVAIL,FOUND
CHARACTER*80 INLINE
DIMENSION IWBE(40),IWEN(40)
C*****
C CHECKS WETHER MAIN DATA IS TO BE READ FROM INPUT RE-START FILE
C AND SET INPUT RE-START FILE NAME IF REQUIRED
C*****
1000 FORMAT(////,
1' Main input data read from re-start file'/
2' ====='////
3'          Input re-start file name -----> ',A)

C
C Checks whether the input data file contains the keyword RESTART
C
CALL FNDKEY
1( FOUND      ,IWBE      ,IWEN      , 'RESTART',
2  INLINE    ,15        ,NWRD      )
IF(FOUND)THEN
C sets re-start flag and name of input re-start file
RSTRT=.TRUE.
RSTINP=INLINE(IWBE(2):IWEN(2))//'.rst'
WRITE(16,1000)INLINE(IWBE(2):IWEN(2))//'.rst'
C checks existence of the input re-start file
INQUIRE(FILE=RSTINP,EXIST=AVAIL)
IF(.NOT.AVAIL)CALL ERRPRT('ED0096')
ELSE
RSTRT=.FALSE.
ENDIF

C
RETURN
END

```

```

      SUBROUTINE RTSR
1(   AUXM      ,MODE      ,MROWQ      ,MROWR      ,NCOLR      ,
2   NROWR      ,Q         ,R          ,S          ,SCAL       ,
3   UNSYM      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL UNSYM
      DIMENSION
1   AUXM(NCOLR,NROWR) ,Q(MROWQ,MROWQ) ,R(MROWR,NCOLR) ,
2   S(MROWR,MROWR)
      DATA R0 /0.0D0/
C*****
C PERFORMS THE MATRIX PRODUCTS
C
C           T
C      Q := SCAL * R  S R      (IF MODE=1)
C OR
C           T
C      Q := Q + SCAL * R  S R      (OTHERWISE)
C
C WHERE 'R' IS A REAL RECTANGULAR MATRIX, 'S' A REAL SQUARE MATRIX
C AND 'SCAL' A SCALAR.
C*****
      CALL RVZERO(AUXM,NCOLR*NROWR)
      DO 30 I=1,NCOLR
        DO 20 K=1,NROWR
          IF(R(K,I).NE.R0)THEN
            DO 10 J=1,NROWR
              AUXM(I,J)=AUXM(I,J)+SCAL*R(K,I)*S(K,J)
10          CONTINUE
            ENDIF
          20 CONTINUE
        30 CONTINUE
C
      IF(MODE.EQ.1)THEN
        DO 50 I=1,NCOLR
          DO 40 J=1,NCOLR
            Q(I,J)=R0
40          CONTINUE
          50 CONTINUE
        ENDIF
C
      IF(UNSYM)THEN
C Construct the whole matrix Q at once
        DO 80 J=1,NCOLR
          DO 70 K=1,NROWR
            IF(R(K,J).NE.R0)THEN
              DO 60 I=1,NCOLR
                Q(I,J)=Q(I,J)+AUXM(I,K)*R(K,J)
60              CONTINUE
            ENDIF
          70 CONTINUE
        80 CONTINUE
      ELSE
C Construct the lower triangle of Q first
        DO 110 J=1,NCOLR
          DO 100 K=1,NROWR
            IF(R(K,J).NE.R0)THEN
              DO 90 I=J,NCOLR
                Q(I,J)=Q(I,J)+AUXM(I,K)*R(K,J)
90              CONTINUE
            ENDIF
          100 CONTINUE
        110 CONTINUE
C and then assemble the upper triangle
        DO 130 I=1,NCOLR
          DO 120 J=I+1,NCOLR
            Q(I,J)=Q(J,I)
120          CONTINUE
        130 CONTINUE
      ENDIF
C
      RETURN
      END

```

```

SUBROUTINE RTSX
1(      AUXM      ,MODE      ,MROWQ      ,MROWR      ,NCOLR      ,
2      NROWR      ,Q        ,R          ,S          ,X          ,
3      SCAL       )
    IMPLICIT DOUBLE PRECISION (A-H,O-Z)
    DIMENSION
1      AUXM(NCOLR,NROWR)   ,Q(MROWQ,MROWQ)           ,R(MROWR,NCOLR)
2      S(MROWR,MROWR)     ,X(MROWR,NCOLR)
    DATA R0 /0.0D0/
C*****
C PERFORMS THE MATRIX PRODUCTS
C                                     T
C               Q := SCAL * R  S X             (IF MODE=1)
C OR
C                                     T
C               Q := Q + SCAL * R  S X         (OTHERWISE)
C WHERE 'R' AND 'X' ARE REAL RECTANGULAR MATRICES OF IDENTICAL
C DIMENSIONS, 'S' A REAL SQUARE MATRIX AND 'SCAL' A SCALAR.
C*****
    CALL RVZERO(AUXM,NCOLR*NROWR)
    DO 30 I=1,NCOLR
        DO 20 K=1,NROWR
            IF(R(K,I).NE.R0)THEN
                DO 10 J=1,NROWR
                    AUXM(I,J)=AUXM(I,J)+SCAL*R(K,I)*S(K,J)
10                CONTINUE
            ENDIF
20            CONTINUE
30        CONTINUE
C
    IF(MODE.EQ.1)THEN
        DO 50 I=1,NCOLR
            DO 40 J=1,NCOLR
                Q(I,J)=R0
40            CONTINUE
50        CONTINUE
        ENDIF
C Construct the matrix Q
    DO 80 J=1,NCOLR
        DO 70 K=1,NROWR
            IF(X(K,J).NE.R0)THEN
                DO 60 I=1,NCOLR
                    Q(I,J)=Q(I,J)+AUXM(I,K)*X(K,J)
60                CONTINUE
            ENDIF
70            CONTINUE
80        CONTINUE
C
    RETURN
END
```

```

      SUBROUTINE RTV
1(   MODE      ,MROWR      ,NCOLR      ,NROWR      ,P      ,
2   R          ,V          ,SCAL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1   P(NCOLR)      ,R(MROWR,NCOLR)      ,V(NROWR)
      DATA R0 /0.0D0/
C*****
C PERFORMS THE PRODUCT
C
C           T
C   P := SCAL * R  V      (IF MODE=1)
C OR
C           T
C   P := P + SCAL * R  V      (OTHERWISE)
C
C WHERE 'R' IS A REAL RECTANGULAR MATRIX, 'V' A REAL VECTOR AND
C 'SCAL' A SCALAR.
C*****
      IF(MODE.EQ.1)CALL RVZERO(P,NCOLR)
      DO 30 I=1,NCOLR
        DO 20 J=1,NROWR
          IF(R(J,I).NE.R0)THEN
            P(I)=P(I)+SCAL*R(J,I)*V(J)
          ENDIF
        20 CONTINUE
      30 CONTINUE
C
      RETURN
      END

```

```
      SUBROUTINE RVSCAL
1(      V      ,N      ,SCAL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION V(N)
C*****
C MULTIPLIES THE DOUBLE PRECISION VECTOR 'V', OF DIMENSION 'N',
C BY THE SCALAR 'SCAL'
C*****
      DO 10 I=1,N
          V(I)=SCAL*V(I)
10 CONTINUE
      RETURN
      END
```



```

      SUBROUTINE RVSUB
1(      U      ,V      ,W      ,N      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1      U(N)      ,V(N)      ,W(N)
C*****
C SUBTRACTS THE VECTOR 'W' FROM THE VECTOR 'V' AND STORE THE RESULT
C IN 'U'. U ,V AND W ARE DOUBLE PRECISION VECTORS OF DIMENSION N.
C*****
      DO 10 I=1,N
          U(I)=V(I)-W(I)
10 CONTINUE
      RETURN
      END

```

```
      SUBROUTINE RVZERO
1(      V      ,N      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION V(N)
      DATA R0/0.0D0/
C*****
C INITIALISES TO ZERO A DOUBLE PRECISION ARRAY OF DIMENSION N
C*****
      DO 10 I=1,N
         V(I)=R0
10 CONTINUE
      RETURN
      END
```

```

C      DOUBLE PRECISION FUNCTION SCAPRD(U ,V ,N )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION U(N), V(N)
      DATA R0 / 0.0D0 /
C*****
C SCALAR PRODUCT OF DOUBLE PRECISION VECTORS U AND V OF DIMENSION N
C*****
      SCAPRD=R0
      DO 10 I=1,N
        SCAPRD=SCAPRD+U(I)*V(I)
10    CONTINUE
      RETURN
      END

```

```

SUBROUTINE SETBE
1( BE ,NTYPE )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
EXTERNAL EXP2X
LOGICAL OUTOFP
DIMENSION BE(*)
DATA RP5 /0.5D0/
C*****
C COMPUTES THE ELASTIC CAUCHY-GREEN TENSOR AS A FUNCTION OF
C THE ELASTIC LOGARITHMIC STRAIN TENSOR:
C
C      Be := exp[ 2 Ee ]
C
C REFERENCE: Box 14.3, item (ii)
C*****
IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
  OUTOFP=.TRUE.
ELSEIF(NTYPE.EQ.1)THEN
  OUTOFP=.TRUE.
ELSE
  CALL ERRPR('EI0024')
ENDIF
C Convert engineering elastic strain components into physical components
BE(3)=RP5*BE(3)
C Use isotropic tensor function to compute elastic Cauchy-Green tensor
CALL ISO2
1( EXP2X ,OUTOFP ,BE ,BE )
C
RETURN
END

```

[illegible]

```

SUBROUTINE SFO4FB
1(   DERIV    ,ETASP      ,EXISP      ,IBOUND    ,MDIME      ,
2   SHAPE     )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION
1   DERIV(MDIME,*),SHAPE(*)
DATA RP25 ,RP5 ,R1 /0.25D0,0.5D0,1.0D0/
C*****
C COMPUTES SHAPE FUNCTIONS AND SHAPE FUNCTION DERIVATIVES FOR
C ELEMENT 'QUAD_4_FBAR':
C
C          4           3
C        O-----O
C          |         |
C          Fo       F-BAR BI-LINEAR
C          x         4 NODE QUADRILATERAL
C          |         |
C        O-----O
C          1           2
C
C REFERENCE: Expression (4.42)
C*****
IF(IBOUND.EQ.0)THEN
C Shape functions and derivatives on element DOMAIN
C -----
S=EXISP
T=ETASP
ST=S*T
C Shape functions
SHAPE(1)=(R1-T-S+ST)*RP25
SHAPE(2)=(R1-T+S-ST)*RP25
SHAPE(3)=(R1+T+S+ST)*RP25
SHAPE(4)=(R1+T-S-ST)*RP25
C Shape function derivatives
DERIV(1,1)=(-R1+T)*RP25
DERIV(1,2)=(+R1-T)*RP25
DERIV(1,3)=(+R1+T)*RP25
DERIV(1,4)=(-R1-T)*RP25
DERIV(2,1)=(-R1+S)*RP25
DERIV(2,2)=(-R1-S)*RP25
DERIV(2,3)=(+R1+S)*RP25
DERIV(2,4)=(+R1-S)*RP25
ELSE
C Shape function and derivatives on element BOUNDARY (1-D)
C -----
S=EXISP
C Shape functions
SHAPE(1)=(-S+R1)*RP5
SHAPE(2)=(+S+R1)*RP5
C Shape functions derivatives
DERIV(1,1)=-RP5
DERIV(1,2)=RP5
C
ENDIF
C
RETURN
END
```

```

      SUBROUTINE SFO8
1(      DERIV      ,ETASP      ,EXISP      ,IBOUND      ,MDIME      ,
2      SHAPE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      DIMENSION
1      DERIV(MDIME,*)      ,SHAPE(*)
      DATA RP25      ,RP5      ,R1      ,R2      /
1      0.25D0,0.5D0,1.0D0,2.0D0/
C*****
C COMPUTES SHAPE FUNCTIONS AND SHAPE FUNCTION DERIVATIVES FOR
C ELEMENT 'QUAD_8' (STANDARD ISOPARAMETRIC 8-NODED QUADRILATERAL)
C
C REFERENCE: Section 4.1.3
C*****
      IF(IBOUND.EQ.0)THEN
C Shape functions and derivatives on element DOMAIN
C -----
          S=EXISP
          T=ETASP
          S2=S*R2
          T2=T*R2
          SS=S*S
          TT=T*T
          ST=S*T
          SST=S*S*T
          STT=S*T*T
          ST2=S*T*R2
C Shape functions
          SHAPE(1)=(-R1+ST+SS+TT-SST-STT)*RP25
          SHAPE(2)=(R1-T-SS+SST)*RP5
          SHAPE(3)=(-R1-ST+SS+TT-SST+STT)*RP25
          SHAPE(4)=(R1+S-TT-STT)*RP5
          SHAPE(5)=(-R1+ST+SS+TT+SST+STT)*RP25
          SHAPE(6)=(R1+T-SS-SST)*RP5
          SHAPE(7)=(-R1-ST+SS+TT+SST-STT)*RP25
          SHAPE(8)=(R1-S-TT+STT)*RP5
C Shape functions derivatives
          DERIV(1,1)=(T+S2-ST2-TT)*RP25
          DERIV(1,2)=-S+ST
          DERIV(1,3)=(-T+S2-ST2+TT)*RP25
          DERIV(1,4)=(R1-TT)*RP5
          DERIV(1,5)=(T+S2+ST2+TT)*RP25
          DERIV(1,6)=-S-ST
          DERIV(1,7)=(-T+S2+ST2-TT)*RP25
          DERIV(1,8)=(-R1+TT)*RP5
          DERIV(2,1)=(S+T2-SS-ST2)*RP25
          DERIV(2,2)=(-R1+SS)*RP5
          DERIV(2,3)=(-S+T2-SS+ST2)*RP25
          DERIV(2,4)=-T-ST
          DERIV(2,5)=(S+T2+SS+ST2)*RP25
          DERIV(2,6)=(R1-SS)*RP5
          DERIV(2,7)=(-S+T2+SS-ST2)*RP25
          DERIV(2,8)=-T+ST
      ELSE
C Shape function and derivatives on element BOUNDARY (1-D)
C -----
          S=EXISP
          SS=S*S
          S2=S*R2
C Shape functions
          SHAPE(1)=(-S+SS)*RP5
          SHAPE(2)=R1-SS
          SHAPE(3)=(S+SS)*RP5
C Shape functions derivatives
          DERIV(1,1)=(-R1+S2)*RP5
          DERIV(1,2)=-S2
          DERIV(1,3)=(R1+S2)*RP5
      ENDIF
C
      RETURN
      END

```

[illegible]


```

      SUBROUTINE SHPFUN
1(   DERIV      ,ETASP      ,EXISP      ,IBOUND      ,IELTYP      ,
2     MDIME      ,SHAPE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      INCLUDE ' ../ELEMENTS.INC'
      DIMENSION
1     DERIV(MDIME,*)      ,SHAPE(*)
C*****
C CALL SPECIFIC ROUTINES FOR COMPUTATION OF SHAPE FUNCTIONS AND
C SHAPE FUNCTION DERIVATIVES FOR EACH TYPE OF ELEMENT
C
C REFERENCE: Section 5.6.3
C*****
      IF(IELTYP.EQ.TRI3)THEN
        CALL SFT3
1(   DERIV      ,ETASP      ,EXISP      ,IBOUND      ,MDIME      ,
2     SHAPE      )
      ELSEIF(IELTYP.EQ.QUAD4)THEN
        CALL SFO4
1(   DERIV      ,ETASP      ,EXISP      ,IBOUND      ,MDIME      ,
2     SHAPE      )
      ELSEIF(IELTYP.EQ.QUAD8)THEN
        CALL SFO8
1(   DERIV      ,ETASP      ,EXISP      ,IBOUND      ,MDIME      ,
2     SHAPE      )
      ELSEIF(IELTYP.EQ.QUA4FB)THEN
        CALL SFO4FB
1(   DERIV      ,ETASP      ,EXISP      ,IBOUND      ,MDIME      ,
2     SHAPE      )
      ELSE
        CALL ERRPRT('EI0005')
      ENDIF
C
      RETURN
      END

```

```

      SUBROUTINE SOLOUA
1(      A      ,B      ,C      ,ONEROO      ,TWOORO      ,
2      ROOT1      ,ROOT2      )
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      LOGICAL ONEROO ,TWOORO
      DATA
1      R0 ,R1 ,R2 ,R4 ,SMALL /
2      0.D0 ,1.0D0,2.0D0,4.0D0,1.D-12/
C*****
C FINDS THE REAL ROOTS OF A QUADRATIC EQUATION:  A X**2 + B X + C = 0.
C
C REFERENCE:
C W.H.Press, S.A.Teukolsky, W.T.Vetterling and B.P.Flannery. Numerical
C recipes in FORTRAN. The art of scientific computing. 2nd Ed.,
C Cambridge Univ. Press, 1992. (Section 5.6)
C*****
C Initialises logical flags
      ONEROO=.FALSE.
      TWOORO=.FALSE.
      IF(A.NE.R0)THEN
C The equation is non-linear in fact
C -----
      IF(B.NE.R0)THEN
          SIGNB=B/ABS(B)
      ELSE
          SIGNB=R1
      ENDIF
      B2=B*B
      R4AC=R4*A*C
      SQUAR=B2-R4AC
      IF(SQUAR.GT.R0)THEN
C there are two distinct real roots: uses formula which minimises
C round-off errors when the coefficients A and/or C are small
          TWOORO=.TRUE.
          SQUAR=SQRT(SQUAR)
          Q=-(B+SIGNB*SQUAR)/R2
          ROOT1=Q/A
          ROOT2=C/Q
      ELSEIF(SQUAR.EQ.R0.OR.
1          (SQUAR/DMAX1(B2,ABS(R4AC))+SMALL).GE.R0)THEN
C there is only one root
          ONEROO=.TRUE.
          ROOT1=-B/(R2*A)
      ENDIF
      ELSE
C The equation is linear
C -----
      IF(B.NE.R0)THEN
C and well defined -> (only) one root exists
          ONEROO=.TRUE.
          ROOT1=-C/B
      ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE SPDEC2
1(   EIGPRJ   ,EIGX   ,REPEAT   ,X   )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER
1(   MCOMP=4   ,NDIM=2   )
      LOGICAL REPEAT
      DIMENSION
1   EIGPRJ(MCOMP,NDIM)   ,EIGX(NDIM)   ,
2   X(MCOMP)
      DIMENSION
1   AUXMTX(NDIM,NDIM)   ,EIGVEC(NDIM,NDIM)
      DATA
1   R0   ,RP5   ,R1   ,R4   ,SMALL /
2   0.0D0,0.5D0,1.0D0,4.0D0,1.D-5 /
C*****
C PERFORMS THE CLOSED FORM SPECTRAL DECOMPOSITION OF A
C SYMMETRIC 2-D TENSOR STORED IN VECTOR FORM
C
C REFERENCE: Box A.2
C*****
      REPEAT=.FALSE.
C Compute eigenvalues of X
C -----
      TRX=X(1)+X(2)
      B=SQRT((X(1)-X(2))**2+R4*X(3)*X(3))
      EIGX(1)=RP5*(TRX+B)
      EIGX(2)=RP5*(TRX-B)
C Compute eigenprojection tensors
C -----
      DIFFER=ABS(EIGX(1)-EIGX(2))
      AMXEIG=DMAX1(ABS(EIGX(1)),ABS(EIGX(2)))
      IF(AMXEIG.NE.R0)DIFFER=DIFFER/AMXEIG
      IF(DIFFER.LT.SMALL)THEN
        REPEAT=.TRUE.
C for repeated (or nearly repeated) eigenvalues, re-compute eigenvalues
C and compute eigenvectors using the iterative procedure. In such cases,
C the closed formula for the eigenvectors is singular (or dominated by
C round-off errors)
        AUXMTX(1,1)=X(1)
        AUXMTX(2,2)=X(2)
        AUXMTX(1,2)=X(3)
        AUXMTX(2,1)=AUXMTX(1,2)
        CALL JACOB(AUXMTX,EIGX,EIGVEC,2)
        DO 10 IDIR=1,2
          EIGPRJ(1,IDIR)=EIGVEC(1,IDIR)*EIGVEC(1,IDIR)
          EIGPRJ(2,IDIR)=EIGVEC(2,IDIR)*EIGVEC(2,IDIR)
          EIGPRJ(3,IDIR)=EIGVEC(1,IDIR)*EIGVEC(2,IDIR)
          EIGPRJ(4,IDIR)=R0
10      CONTINUE
        ELSE
C Use closed formula to compute eigenprojection tensors
        DO 20 IDIR=1,2
          B=EIGX(IDIR)-TRX
          C=R1/(EIGX(IDIR)+B)
          EIGPRJ(1,IDIR)=C*(X(1)+B)
          EIGPRJ(2,IDIR)=C*(X(2)+B)
          EIGPRJ(3,IDIR)=C*X(3)
          EIGPRJ(4,IDIR)=R0
20      CONTINUE
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE STFBA2
1(   IELEM      ,KUNLD      ,MDIME      ,MELEM      ,
2   MPOIN      ,MSTRE      ,MTOTV      ,NAXIS      ,
3   NTYPE      ,UNSYM      ,
4   COORD1      ,DINCR      ,ESTIF      ,IELPRP      ,IPROPS      ,
5   LALGVA      ,LNODS      ,RALGVA      ,RELPRP      ,RPROPS      ,
6   RSTAVA      ,RSTAV2      ,STRSG      ,TDISP      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'

C
      PARAMETER( MGDIM=5 ,MBDIM=4 ,NDIME=2 ,NDOFN=2 )
C Arguments
      LOGICAL LALGVA ,UNSYM
      DIMENSION
1   COORD1(MDIME,MPOIN) ,DINCR(MTOTV)      ,ESTIF(MEVAB,MEVAB) ,
2   IELPRP(*)      ,IPROPS(*)      ,LALGVA(MLALGV,MTOTG) ,
3   LNODS(MELEM,MEVAB) ,RALGVA(MRALGV,MTOTG) ,RELPRP(*) ,
4   RPROPS(*)      ,RSTAVA(MRSTAV,MTOTG) ,RSTAV2(MRSTAV,MTOTG) ,
5   STRSG(MSTRE,MTOTG) ,TDISP(MTOTV)

C Local arrays and variables
      DIMENSION
1   AUXM(MEVAB,MGDIM) ,AMATX(MGDIM,MGDIM) ,
2   CARTD(NDIME,MNODE) ,DELDIS(2,MNODE) ,DERIV(NDIME,MNODE) ,
3   DMATX(MBDIM,MBDIM) ,EINCR(MBDIM)      ,ELCOD(NDIME,MNODE) ,
4   FINCIN(3,3)      ,FINCR(3,3)      ,FINV(3,3) ,
5   GMATX(MGDIM,MEVAB) ,GOMGMX(MGDIM,MEVAB) ,
6   GPCOD(NDIME)      ,QMATX(MGDIM,MGDIM) ,SHAPE(MNODE) ,
7   TELDIS(2,MNODE)

      DATA R0 ,RP5 ,R1 ,R3 ,R8 /
1   0.0D0,0.5D0,1.0D0,3.0D0,8.0D0/
C*****
C EVALUATES THE ELEMENT TANGENT STIFFNESS MATRIX FOR ELEMENTS OF CLASS
C 'FBAR' (F-bar ELEMENTS) IN 2-D (PLANE STRAIN AND AXISYMMETRIC
C PROBLEMS)
C
C REFERENCE: Box 15.2
C             Section 15.1.3
C*****
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)THEN
C F-bar implementation valid only for plane strain and axisymmetric
      CALL ERRPRT('EI0034')
      ENDIF
      IF(NTYPE.EQ.3)TWOPI=R8*ATAN(R1)
      RID3=R1/R3
C Identify element type
      IELTYP=IELPRP(1)
C Recover element information
      NNODE =IELPRP(3)
      NGAUSP=IELPRP(4)
      NEVAB =IELPRP(5)

C
C Set element nodal coordinates, total and incremental displacements
C vectors
C
      DO 20 INODE =1,NNODE
          LNODE=IABS(LNODS(IELEM,INODE))
          NPOSN=(LNODE-1)*NDOFN
          DO 10 IDOFN=1,NDOFN
              NPOSN=NPOSN+1
              ELCOD(IDOFN,INODE)=COORD1(IDOFN,LNODE)
              TELDIS(IDOFN,INODE)=-TDISP(NPOSN)
              DELDIS(IDOFN,INODE)=-DINCR(NPOSN)
          10 CONTINUE
      20 CONTINUE

C
C Initialize the element stiffness matrix
C
      DO 40 IEVAB=1,NEVAB
          DO 30 JEVAB=1,NEVAB
              ESTIF(IEVAB,JEVAB)=R0
          30 CONTINUE
      40 CONTINUE

C
C
C Evaluate inverse of the incremental deformation gradient at the
C element centroid for F-bar element
      NGAUSB=IELPRP(8)
      IPOS =NGAUSP*NDIME+NGAUSP+NGAUSP*NNODE+2*NGAUSB+1
      EXISC =RELPRP(IPOS)
      ETASC =RELPRP(IPOS+1)

C
      CALL SHPFUN
1(   DERIV      ,ETASC      ,EXISC      ,0      ,IELTYP      ,
2   NDIME      ,SHAPE      )
      CALL JACOB2
1(   CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
2   NDIME      ,NDIME      ,NNODE      )
      IF(DETJAC.LE.R0)THEN
C stops program if element jacobian is not positive definite
      CALL ERRPRT('EE0007')
      ENDIF
      IF(NTYPE.EQ.3)CALL GETGCO
1(   GPCOD      ,ELCOD      ,NDIME      ,NDIME      ,NNODE      ,
2   SHAPE      )

C
      CALL GETGMX

```

```

1(   GPCOD      ,CARTD      ,GOMATX      ,NDIME      ,MGDIM      ,
2   NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C Determinant of the incremental deformation gradient at the centroid
CALL DEFGRGA
1(   DELDIS      ,FINCIN      ,GOMATX      ,2          ,MGDIM      ,
2   NDOFN      ,NTYPE      ,NNODE      )
IF(NTYPE.EQ.2)THEN
  AFACT=RP5
  DET=FINCIN(1,1)*FINCIN(2,2)-FINCIN(1,2)*FINCIN(2,1)
ELSEIF(NTYPE.EQ.3)THEN
C stops program if deformation gradient determinant is non-positive
  IF(FINCIN(3,3).LE.R0)CALL ERRPR('EE0008')
  AFACT=R1D3
  DET=(FINCIN(1,1)*FINCIN(2,2)-FINCIN(1,2)*FINCIN(2,1))*
1   FINCIN(3,3)
ENDIF
DET0=R1/DET
C Determinant of the total deformation gradient at the centroid
CALL DEFGRGA
1(   TELDIS      ,FINV      ,GOMATX      ,2          ,MGDIM      ,
2   NDOFN      ,NTYPE      ,NNODE      )
IF(NTYPE.EQ.2)THEN
  DET=FINV(1,1)*FINV(2,2)-FINV(1,2)*FINV(2,1)
ELSEIF(NTYPE.EQ.3)THEN
C stops program if deformation gradient determinant is non-positive
  IF(FINV(3,3).LE.R0)CALL ERRPR('EE0008')
  DET=(FINV(1,1)*FINV(2,2)-FINV(1,2)*FINV(2,1))*FINV(3,3)
ENDIF
DETF0=R1/DET
C
C=====
C          Begin loop over Gauss points
C=====
  IPPOS=1
  IPWEI=NGAUSP*NDIME+1
  DO 70 IGAUSP=1,NGAUSP
    EXISP=RELPRP(IPPOS-1+IGAUSP*2-1)
    ETASP=RELPRP(IPPOS-1+IGAUSP*2)
    WEIGP=RELPRP(IPWEI-1+IGAUSP)
C Evaluate the shape functions and derivatives
    CALL SHPFUN
1(   DERIV      ,ETASP      ,EXISP      ,0          ,IELTYP      ,
2   NDIME      ,SHAPE      )
    CALL JACOB2
1(   CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
2   NDIME      ,NDIME      ,NNODE      )
    IF(DETJAC.LE.R0)THEN
C... stops program if element jacobian is not positive definite
      CALL ERRPR('EE0007')
    ENDIF
    IF(NTYPE.EQ.3)CALL GETGCO
1(   GPCOD      ,ELCOD      ,NDIME      ,NDIME      ,NNODE      ,
2   SHAPE      )
C
C Large strains: compute incremental deformation gradient
C -----
C gradient operator G in the current configuration
CALL GETGMX
1(   GPCOD      ,CARTD      ,GMATX      ,NDIME      ,MGDIM      ,
2   NAXIS      ,NNODE      ,NTYPE      ,SHAPE      )
C inverse of incremental deformation gradient
CALL DEFGRGA
1(   DELDIS      ,FINCIN      ,GMATX      ,2          ,MGDIM      ,
2   NDOFN      ,NTYPE      ,NNODE      )
C stops program if deformation gradient determinant is non-positive
  IF(NTYPE.EQ.3.AND.FINCIN(3,3).LE.R0)CALL ERRPR('EE0008')
C incremental deformation gradient
CALL INV2
1(   FINCIN      ,FINCR      ,NTYPE      )
C Modified incremental deformation gradient for F-bar element
  IF(NTYPE.EQ.2)THEN
    DET=FINCR(1,1)*FINCR(2,2)-FINCR(1,2)*FINCR(2,1)
  ELSEIF(NTYPE.EQ.3)THEN
    DET=(FINCR(1,1)*FINCR(2,2)-FINCR(1,2)*FINCR(2,1))*
1   FINCR(3,3)
  ENDIF
  FACTOR=(DET0/DET)**AFACT
  FINCR(1,1)=FACTOR*FINCR(1,1)
  FINCR(1,2)=FACTOR*FINCR(1,2)
  FINCR(2,1)=FACTOR*FINCR(2,1)
  FINCR(2,2)=FACTOR*FINCR(2,2)
  IF(NTYPE.EQ.3)FINCR(3,3)=FACTOR*FINCR(3,3)
C... and the determinant of the total deformation gradient
  DETF=DETF0
C
C Call material interface routine for consistent tangent computation
C calls: Compute the spatial tangent modulus AMATX (large strains)
C =====
C
  NLARGE=1
  CALL MATICT
1(   DETF      ,KUNLD      ,MBDIM      ,MGDIM      ,
2   NLARGE      ,NTYPE      ,
3   AMATX      ,DMATX      ,EINCR      ,FINCR      ,IPROPS      ,
4   LALGVA(1,IGAUSP) ,RALGVA(1,IGAUSP) ,RPROPS      ,
5   RSTAVA(1,IGAUSP) ,RSTAV2(1,IGAUSP) ,
5   STRSG(1,IGAUSP) )
C

```

```

C Add current Gauss point contribution to element stiffness
C =====
C
C Compute elemental volume
  DVOLU=DETJAC*WEIGP
  IF(NTYPE.EQ.3)THEN
    DVOLU=DVOLU*TWOPI*GPCOD(NAXIS)
  ENDIF
C
C Large strains: assemble the element stiffness as  $K = G [a] G^T$ 
C -----
  IF(NTYPE.EQ.3)THEN
    NGDIM=5
  ELSE
    NGDIM=4
  ENDIF
  CALL RTSR
  1(   AUXM      ,0      ,MEVAB      ,MGDIM      ,NEVAB      ,
  2   NGDIM      ,ESTIF   ,GMATX      ,AMATX      ,DVOLU      ,
  3   UNSYM      )
C Add extra matrix required by F-bar type element
  CALL ATMDEB
  1(   AMATX      ,NTYPE   ,QMATX      ,STRSG(1,IGAUSP) )
CC NGDIM*NEVAB ??? Fix this!!!
  CALL RVSUB(GOMGMX,GOMATX,GMATX,MGDIM*MEVAB)
  CALL RTSX
  1(   AUXM      ,0      ,MEVAB      ,MGDIM      ,NEVAB      ,
  2   NGDIM      ,ESTIF   ,GMATX      ,QMATX      ,GOMGMX      ,
  3   DVOLU      )
C
  70 CONTINUE
C=====
C                               End of loop over Gauss points |
C=====
  RETURN
END

```

```

      SUBROUTINE STSTD2
1(   IELEM      ,KUNLD      ,MDIME      ,MELEM      ,
2   MPOIN      ,MSTRE      ,MTOTV      ,NAXIS      ,NLARGE      ,
3   NTYPE      ,UNSYM      ,
4   COORD1      ,DINCR      ,ESTIF      ,IELPRP      ,IPROPS      ,
5   LALGVA      ,LNODS      ,RALGVA      ,RELPRP      ,RPROPS      ,
6   RSTAVA      ,RSTAV2      ,STRSG      ,THKGP      ,TDISP      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
C
      PARAMETER( MGDIM=5 ,MBDIM=4 ,NDIME=2 ,NDOFN=2 )
C Arguments
      LOGICAL LALGVA ,UNSYM
      DIMENSION
1   COORD1(MDIME,MPOIN) ,DINCR(MTOTV)      ,ESTIF(MEVAB,MEVAB) ,
2   IELPRP(*)      ,IPROPS(*)      ,LALGVA(MLALGV,MTOTG) ,
3   LNODS(MELEM,MEVAB) ,RALGVA(MRALGV,MTOTG) ,RELPRP(*) ,
4   RPROPS(*)      ,RSTAVA(MRSTAV,MTOTG) ,RSTAV2(MRSTAV,MTOTG) ,
5   STRSG(MSTRE,MTOTG) ,THKGP(MTOTG)      ,TDISP(MTOTV)
C Local arrays and variables
      DIMENSION
1   AUXM(MEVAB,MGDIM) ,AMATX(MGDIM,MGDIM) ,BMATX(4,MEVAB) ,
2   CARTD(NDIME,MNODE) ,DELDIS(2,MNODE) ,DERIV(NDIME,MNODE) ,
3   DMATX(MBDIM,MBDIM) ,EINCR(MBDIM)      ,ELCOD(NDIME,MNODE) ,
4   FINCIN(3,3)      ,FINCR(3,3)      ,FINV(3,3) ,
5   GMATX(MGDIM,MEVAB) ,GPCOD(NDIME)      ,SHAPE(MNODE) ,
6   TELDIS(2,MNODE)
      DATA R0 ,R1 ,R8 /
1   0.0D0,1.0D0,8.0D0/
C*****
C EVALUATES THE ELEMENT TANGENT STIFFNESS MATRIX FOR ELEMENTS OF CLASS
C 'STDARD' (STANDARD ISOPARAMETRIC ELEMENTS) IN 2-D (PLANE STRAIN,
C PLANE STRESS AND AXISYMMETRIC PROBLEMS
C
C REFERENCE: Sections 4.2.4, 4.3.4
C           Box 4.2, item (iii)
C           Box 4.3
C*****
      IF(NTYPE.EQ.3)TWOPI=R8*ATAN(R1)
C Identify element type
      IELTYP=IELPRP(1)
C Recover element information
      NNODE =IELPRP(3)
      NGAUSP=IELPRP(4)
      NEVAB =IELPRP(5)
C
C Set element nodal coordinates, total and incremental displacements
C vectors
C
      DO 20 INODE =1,NNODE
          LNODE=IABS(LNODS(IELEM,INODE))
          NPOSN=(LNODE-1)*NDOFN
          DO 10 IDOFN=1,NDOFN
              NPOSN=NPOSN+1
              ELCOD(IDOFN,INODE)=COORD1(IDOFN,LNODE)
              IF(NLARGE.EQ.1)THEN
                  TELDIS(IDOFN,INODE)=-TDISP(NPOSN)
                  DELDIS(IDOFN,INODE)=-DINCR(NPOSN)
              ELSE
                  DELDIS(IDOFN,INODE)=DINCR(NPOSN)
              ENDIF
          10 CONTINUE
      20 CONTINUE
C
C Initialize the element stiffness matrix
C
      DO 40 IEVAB=1,NEVAB
          DO 30 JEVAB=1,NEVAB
              ESTIF(IEVAB,JEVAB)=R0
          30 CONTINUE
      40 CONTINUE
C
C=====
C           Begin loop over Gauss points
C=====
      IPPOS=1
      IPWEI=NGAUSP*NDIME+1
      DO 70 IGAUSP=1,NGAUSP
          EXISP=RELPRP(IPPOS-1+IGAUSP*2-1)
          ETASP=RELPRP(IPPOS-1+IGAUSP*2)
          WEIGP=RELPRP(IPWEI-1+IGAUSP)
C Evaluate the shape functions and derivatives
          CALL SHPFUN
1(   DERIV      ,ETASP      ,EXISP      ,0      ,IELTYP      ,
2   NDIME      ,SHAPE      )
          CALL JACOB2
1(   CARTD      ,DERIV      ,DETJAC      ,ELCOD      ,IELEM      ,
2   NDIME      ,NDIME      ,NNODE      )
          IF(DETJAC.LE.R0)THEN
C... stops program if element jacobian is not positive definite
              CALL ERRPRT('EE0003')
          ENDIF
          IF(NTYPE.EQ.3)CALL GETGCO
1(   GPCOD      ,ELCOD      ,NDIME      ,NDIME      ,NNODE      ,
2   SHAPE      )
C

```

```

      IF(NLARGE.EQ.1)THEN
C Large strains: compute incremental deformation gradient
C -----
C gradient operator G in the current configuration
      CALL GETGMX
      1( GPCOD ,CARTD ,GMATX ,NDIME ,MGDIM ,
      2 NAXIS ,NNODE ,NTYPE ,SHAPE )
C inverse of incremental deformation gradient
      CALL DEFGRA
      1( DELDIS ,FINCIN ,GMATX ,2 ,MGDIM ,
      2 NDOFN ,NTYPE ,NNODE )
C stops program if deformation gradient determinant is non-positive
      IF(NTYPE.EQ.3.AND.FINCIN(3,3).LE.R0)CALL ERRPRT('EE0004')
C incremental deformation gradient
      CALL INV2
      1( FINCIN ,FINCR ,NTYPE )
C... and the determinant of the total deformation gradient
      CALL DEFGRA
      1( TELDIS ,FINV ,GMATX ,2 ,MGDIM ,
      2 NDOFN ,NTYPE ,NNODE )
      DETFIN=FINV(1,1)*FINV(2,2)-FINV(1,2)*FINV(2,1)
      IF(NTYPE.EQ.3)THEN
C stops program if deformation gradient is not positive definite
      IF(FINV(3,3).LE.R0)CALL ERRPRT('EE0004')
      DETFIN=DETFIN*FINV(3,3)
      ENDIF
      DETF=R1/DETFIN
      ELSE
C Small strains: compute incremental infinitesimal strain
C -----
C compute the symmetric gradient operator B
      CALL GETBMX
      1( BMATX ,GPCOD ,CARTD ,NDIME ,4 ,
      2 NAXIS ,NNODE ,NTYPE ,SHAPE )
C and the incremental infinitesimal strain
      CALL LISTRA
      1( BMATX ,DELDIS ,2 ,4 ,NDOFN ,
      2 NNODE ,NTYPE ,EINCR )
      ENDIF
C
C Call material interface routine for consistent tangent computation
C calls: Compute either the standard consistent tangent matrix DMATX
C (small strains) or the spatial tangent modulus AMATX (large strains)
C =====
C
      CALL MATICT
      1( DETF ,KUNLD ,MBDIM ,MGDIM ,
      2 NLARGE ,NTYPE ,
      3 AMATX ,DMATX ,EINCR ,FINCR ,IPROPS ,
      4 LALGVA(1,IGAUSP) ,RALGVA(1,IGAUSP) ,RPROPS ,
      5 RSTAVA(1,IGAUSP) ,RSTAV2(1,IGAUSP) ,
      5 STRSG(1,IGAUSP) )
C
C Add current Gauss point contribution to element stiffness
C =====
C
C Compute elemental volume
      DVOLU=DETJAC*WEIGP
      IF(NTYPE.EQ.1)THEN
      DVOLU=DVOLU*THKGP(IGAUSP)
      ELSEIF(NTYPE.EQ.3)THEN
      DVOLU=DVOLU*TWOPI*GPCOD(NAXIS)
      ENDIF
      IF(NLARGE.EQ.1)THEN
C
C Large strains: assemble the element stiffness as  $K := G [a] G^T$ 
C -----
      IF(NTYPE.EQ.3)THEN
      NGDIM=5
      ELSE
      NGDIM=4
      ENDIF
      CALL RTSR
      1( AUXM ,0 ,MEVAB ,MGDIM ,NEVAB ,
      2 NGDIM ,ESTIF ,GMATX ,AMATX ,DVOLU ,
      3 UNSYM )
      ELSE
C
C Small strains: assemble the element stiffness as  $K := B D B^T$ 
C -----
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2)THEN
      NBDIM=3
      ELSEIF(NTYPE.EQ.3)THEN
      NBDIM=4
      ENDIF
      CALL RTSR
      1( AUXM ,0 ,MEVAB ,4 ,NEVAB ,
      2 NBDIM ,ESTIF ,BMATX ,DMATX ,DVOLU ,
      3 UNSYM )
      ENDIF
C
70 CONTINUE
C=====
C End of loop over Gauss points |
C=====
      RETURN
      END

```



```

SUBROUTINE SUDAMA
1( DGAMA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=6 ,MSTRE=4)
LOGICAL IFPLAS, LALGVA(2), SUFAIL
DIMENSION
1 IPROPS(*) ,RPROPS(*) ,RSTAVA(MSTRE+2) ,
2 STRAT(MSTRE) ,STRES(MSTRE)
DIMENSION
1 EET(MSTRE)
DATA
1 R0 ,RP5 ,R1 ,R2 ,R3 ,R6 ,SMALL ,TOL /
2 0.0D0,0.5D0,1.0D0,2.0D0,3.0D0,6.0D0,1.D-20,1.D-08/
DATA MXITER / 25 /
C*****
C STATE UPDATE PROCEDURE FOR LEMAITRE'S DUCTILE DAMAGE MATERIAL MODEL
C WITH NON-LINEAR (PIECEWISE LINEAR) ISOTROPIC HARDENING:
C IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM.
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Box 12.4
C*****
C Stop program if neither plane strain nor axisymmetric state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0051')
C Initialise some algorithmic and internal variables
DGAMA=R0
IFPLAS=.FALSE.
SUFAIL=.FALSE.
C Retrieve hardening and damage internal variables
HVARN=RSTAVA(MSTRE+1)
DAMAGN=RSTAVA(MSTRE+2)
C... integrity
OMEGAN=R1-DAMAGN
C Retrieve some material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
DAMEXP=RPROPS(4)
DAMDEN=RPROPS(5)
NHARD=IPROPS(3)
C Shear and bulk moduli and other necessary constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2BULK=R2*BULK
R2G=R2*GMODU
R3G=R3*GMODU
R6G=R6*GMODU
C Elastic predictor: Compute elastic trial state
C =====
C Volumetric strain and (undamaged) pressure stress
EEV=STRAT(1)+STRAT(2)+STRAT(4)
PTILDE=BULK*EEV
C Elastic trial deviatoric strain
EEVD3=EEV/R3
EET(1)=STRAT(1)-EEVD3
EET(2)=STRAT(2)-EEVD3
EET(4)=STRAT(4)-EEVD3
C Convert engineering shear component into physical component
EET(3)=STRAT(3)/R2
C Compute trial (undamaged) von Mises effective stress and uniaxial
C yield stress
VARJ2T=R2G*R2G*(EET(3)*EET(3)+RP5*(EET(1)*EET(1)+
1 EET(2)*EET(2)+EET(4)*EET(4)))
QTILTR=SQRT(R3*VARJ2T)
SIGMAY=PLFUN(HVARN,NHARD,RPROPS(IPHARD))
C Check for plastic admissibility
C =====
PHI=QTILTR-SIGMAY
IF(PHI/SIGMAY.GT.TOL)THEN
C Plastic step: Apply return mapping - use Newton-Raphson algorithm
C to solve the return mapping equation for DGAMA
C =====
C Reset plastic flag
IFPLAS=.TRUE.
C Initial guess for DGAMA: Use perfectly plastic solution with frozen
C yield surface at the beginning of the load increment
DGAMA=OMEGAN*PHI/R3G
C Initialise hardening variable
HVAR=HVARN+DGAMA
C Start N-R iterations
C -----
PTILD2=PTILDE**2
DO 10 NRITER=1,MXITER
C yield stress
SIGMAY=PLFUN(HVAR,NHARD,RPROPS(IPHARD))
C integrity
AUX2=R3G/(QTILTR-SIGMAY)
OMEGA=AUX2*DGAMA
C stress triaxiality and damage energy release rate
Y=-SIGMAY**2/R6G-PTILD2/R2BULK
C Compute residual function
RES=OMEGA-OMEGAN+(-Y/DAMDEN)**DAMEXP/AUX2
C Check for convergence
IF(ABS(RES).LE.TOL)THEN
C... update hardening and damage variables
IF(OMEGA.LT.SMALL)THEN
C... check if converged damage variable is acceptable
SUFAIL=.TRUE.
CALL ERRPRT('WE0019')
GOTO 999
ENDIF
DAMAGE=R1-OMEGA
RSTAVA(MSTRE+1)=HVAR
RSTAVA(MSTRE+2)=DAMAGE
C... update stress components
P=OMEGA*PTILDE
Q=SIGMAY*OMEGA
FACTOR=R2G*Q/QTILTR
STRES(1)=FACTOR*EET(1)+P
STRES(2)=FACTOR*EET(2)+P
STRES(3)=FACTOR*EET(3)
STRES(4)=FACTOR*EET(4)+P
C... compute and store converged elastic (engineering) strain components

```

```

        FACTOR=R1-R3G*DGAMA/(OMEGA*QTILTR)
        RSTAVA(1)=FACTOR*EET(1)+EEVD3
        RSTAVA(2)=FACTOR*EET(2)+EEVD3
        RSTAVA(3)=FACTOR*EET(3)*R2
        RSTAVA(4)=FACTOR*EET(4)+EEVD3
        GOTO 999
    ENDIF
C Compute derivative of residual function
C... slope of hardening function
        HSLOPE=DPLEUN(HVAR,NHARD,RPROPS(IPHARD))
C... derivative of -Y
        DY=-HSLOPE*SIGMAY/R3G
C... residual derivative
        AUX=-Y/DAMDEN
        DRES=AUX2+AUX2*DGAMA*HSLOPE/(QTILTR-SIGMAY)-
1          HSLOPE/R3G*AUX**DAMEXP-
2          DAMEXP*DY/(AUX2*DAMDEN)*AUX**(DAMEXP-R1)
C Apply N-R correction to DGAMA
        DDGAMA=-RES/DRES
        DGAMA=DGAMA+DDGAMA
C... update hardening variable
        HVAR=HVARN+DGAMA
10    CONTINUE
C N-R loop failed to converge: Reset failure flag and issue warning
C          message before exiting
        SUFAIL=.TRUE.
        CALL ERRPRN('WE0018')
    ELSE
C Elastic step: Update stress using damaged elastic law
C =====
        FACTOR=R2G*OMEGAN
        P=OMEGAN*PTILDE
        STRES(1)=FACTOR*EET(1)+P
        STRES(2)=FACTOR*EET(2)+P
        STRES(3)=FACTOR*EET(3)
        STRES(4)=FACTOR*EET(4)+P
C elastic engineering strain
        RSTAVA(1)=STRAT(1)
        RSTAVA(2)=STRAT(2)
        RSTAVA(3)=STRAT(3)
        RSTAVA(4)=STRAT(4)
    ENDIF
999 CONTINUE
C Update some algorithmic variables before exit
        LALGVA(1)=IFPLAS
        LALGVA(2)=SUFAIL
        RETURN
    END

```

```

SUBROUTINE SUDMEL
1( NTYPE ,RPROPS ,RSTAVA ,STRAN ,STRES ,
2 SUFAIL )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(MSTRE=4)
C Arguments
LOGICAL SUFAIL
DIMENSION
1 RPROPS(*) ,RSTAVA(MSTRE) ,STRAN(MSTRE) ,
2 STRES(MSTRE)
C Local variables and arrays
LOGICAL DUMMY
DIMENSION
1 DPSTRA(3,3) ,DPSTRE(3,3) ,EED(MSTRE) ,
2 EIGPRJ(MSTRE,2) ,PDMINU(3,3) ,PDPLUS(3,3) ,
4 PSTRA(3) ,PSTRES(3) ,RESVEC(3) ,
5 SIGMA(MSTRE) ,STRAIN(MSTRE) ,VI(3) ,
6 VIDMIN(3) ,VIDPLU(3)
DATA
1 VI(1),VI(2),VI(3)/
2 1.D0 ,1.D0 ,1.D0 /
DATA
1 R0 ,R1 ,R2 ,R3 ,TOL /
2 0.D0 ,1.D0 ,2.0D0 ,3.0D0 ,1.D-10/
DATA
1 MXITER/ 10/
C*****
C STATE UPDATE PROCEDURE FOR ISOTROPICALLY DAMAGED ISOTROPIC ELASTIC
C MODEL ACCOUNTING FOR PARTIAL MICROCRACK/VOID CLOSURE EFFECTS
C
C REFERENCE: Box 12.7
C*****
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0057')
C Initialise logical flag
SUFAIL=.FALSE.
C Set material constants
YOUNG=RPROPS(2)
POISS=RPROPS(3)
DAMAGE=RPROPS(4)
HFACT=RPROPS(5)
GMODU=RPROPS(6)
BULK=RPROPS(7)
C Transform engineering into physical strains
STRAIN(1)=STRAN(1)
STRAIN(2)=STRAN(2)
STRAIN(3)=STRAN(3)/R2
STRAIN(4)=STRAN(4)
C Perform spectral decomposition of the strain tensor
CALL SPDEC2(EIGPRJ,PSTRA,DUMMY,STRAIN)
PSTRA(3)=STRAN(4)
C
C Newton-Raphson iterations to solve the piece-wise linear elastic
C constitutive equation
C -----
C
C Set initial guess for principal stresses as the stresses obtained for
C the damaged elastic material without partial crack closure effects
C... compute corresponding stress tensor components first
EEV=STRAN(1)+STRAN(2)+STRAN(4)
EEVD3=EEV/R3
EED(1)=STRAN(1)-EEVD3
EED(2)=STRAN(2)-EEVD3
EED(4)=STRAN(4)-EEVD3
P=(R1-DAMAGE)*BULK*EEV
R1DR2G=(R1-DAMAGE)*R2*GMODU
SIGMA(1)=R1DR2G*EED(1)+P
SIGMA(2)=R1DR2G*EED(2)+P
SIGMA(3)=R1DR2G*EED(3)
SIGMA(4)=R1DR2G*EED(4)+P
C... and then the principal stresses (internal product between stress
C tensor and individual eigenprojection tensors)
PSTRES(1)=SIGMA(1)*EIGPRJ(1,1)+SIGMA(2)*EIGPRJ(2,1)+
1 R2*SIGMA(3)*EIGPRJ(3,1)
PSTRES(2)=SIGMA(1)*EIGPRJ(1,2)+SIGMA(2)*EIGPRJ(2,2)+
1 R2*SIGMA(3)*EIGPRJ(3,2)
PSTRES(3)=SIGMA(4)
C Zero relevant arrays
CALL RVZERO(PDPLUS,9)
CALL RVZERO(PDMINU,9)
C
C Begin N-R iterations
C
DO 80 ITER=1,MXITER
C Construct current projection matrices
C... positive and negative principal stress projection matrices
IF(PSTRES(1).GE.R0)THEN
PDPLUS(1,1)=R1/(R1-DAMAGE)
PDMINU(1,1)=R0
ELSE
PDPLUS(1,1)=R0
PDMINU(1,1)=R1/(R1-HFACT*DAMAGE)
ENDIF
IF(PSTRES(2).GE.R0)THEN
PDPLUS(2,2)=R1/(R1-DAMAGE)
PDMINU(2,2)=R0
ELSE
PDPLUS(2,2)=R0
PDMINU(2,2)=R1/(R1-HFACT*DAMAGE)

```

```

ENDIF
IF (PSTRES(3).GE.R0) THEN
  PDPLUS(3,3)=R1/(R1-DAMAGE)
  PDMINU(3,3)=R0
ELSE
  PDPLUS(3,3)=R0
  PDMINU(3,3)=R1/(R1-HFACT*DAMAGE)
ENDIF
C... positive and negative trace operators
TRACE=PSTRES(1)+PSTRES(2)+PSTRES(3)
IF (TRACE.GE.R0) THEN
  VIDPLU(1)=R1/(R1-DAMAGE)
  VIDPLU(2)=R1/(R1-DAMAGE)
  VIDPLU(3)=R1/(R1-DAMAGE)
  VIDMIN(1)=R0
  VIDMIN(2)=R0
  VIDMIN(3)=R0
ELSE
  VIDPLU(1)=R0
  VIDPLU(2)=R0
  VIDPLU(3)=R0
  VIDMIN(1)=R1/(R1-HFACT*DAMAGE)
  VIDMIN(2)=R1/(R1-HFACT*DAMAGE)
  VIDMIN(3)=R1/(R1-HFACT*DAMAGE)
ENDIF
C Inverse elasticity operator that transforms principal stresses into
C principal strains (matrix of derivatives of principal strains with
C respect to principal stresses)
DO 20 I=1,3
  DO 10 J=1,3
    DPSTRA(I,J)=(R1+POISS)/YOUNG*(PDPLUS(I,J)+PDMINU(I,J))-
    POISS/YOUNG*(VI(I)*(VIDPLU(J)+VIDMIN(J)))
  10 CONTINUE
20 CONTINUE
C Compute residual of constitutive equation
DO 40 I=1,3
  RESVEC(I)=R0
  DO 30 J=1,3
    RESVEC(I)=RESVEC(I)-DPSTRA(I,J)*PSTRES(J)
  30 CONTINUE
  RESVEC(I)=PSTRA(I)+RESVEC(I)
40 CONTINUE
C... residual norm
RESNOR=SQRT(RESVEC(1)**2+RESVEC(2)**2+RESVEC(3)**2)
IF (RESNOR.LT.TOL) THEN
C Iterations converged: update stress tensor components, store
C engineering strain in RSTAVA, break N-R loop
C and exit this routine
  STRES(1)=PSTRES(1)*EIGPRJ(1,1)+PSTRES(2)*EIGPRJ(1,2)
  STRES(2)=PSTRES(1)*EIGPRJ(2,1)+PSTRES(2)*EIGPRJ(2,2)
  STRES(3)=PSTRES(1)*EIGPRJ(3,1)+PSTRES(2)*EIGPRJ(3,2)
  STRES(4)=PSTRES(3)
  RSTAVA(1)=STRAN(1)
  RSTAVA(2)=STRAN(2)
  RSTAVA(3)=STRAN(3)
  RSTAVA(4)=STRAN(4)
  GOTO 999
ENDIF
C Compute elasticity operator that transforms principal strains into
C principal stresses (matrix of derivatives of principal stresses with
C respect to principal strains). This is the inverse of the residual
C vector derivative
CALL INVT3(DPSTRA,DPSTRE,DET)
C Apply N-R correction to principal stresses
DO 70 I=1,3
  DO 60 J=1,3
    PSTRES(I)=PSTRES(I)+DPSTRE(I,J)*RESVEC(J)
  60 CONTINUE
70 CONTINUE
80 CONTINUE
C N-R loop not converged: Failure of stress update procedure.
C Stresses are not updated. Send warning message
  SUFAIL=.TRUE.
  CALL ERRPR('WE0020')
C
999 RETURN
END

```

```

      SUBROUTINE SUDE
1(   DGAM   ,IPROPS   ,LALGVA   ,NTYPE   ,RPROPS   ,
2   RSTAVA   ,STRAT   ,STRES   )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=7 ,MSTRE=4)
      LOGICAL APEX, IFPLAS, LALGVA(3), SUFAIL
      DIMENSION
1   IPROPS(*)           ,RPROPS(*)           ,RSTAVA(MSTRE+1)
2   STRAT(MSTRE)       ,STRES(MSTRE)
      DIMENSION
1   STRIAL(MSTRE)
      DATA
1   R0 ,RP5 ,R1 ,R2 ,R3 ,TOL /
2   0.0D0,0.5D0,1.0D0,2.0D0,3.0D0,1.D-08/
      DATA MAXRT / 50 /
C*****
C STRESS UPDATE PROCEDURE FOR DRUCKER PRAGER TYPE ELASTO-PLASTIC
C MATERIAL WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW RULE AND PIECE_WISE
C LINEAR ISOTROPIC HARDENING:
C IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM (Boxes 8.8-10)
C
C REFERENCE: Boxes 8.8-10
C*****
C Stops program if neither plane strain nor axisymmetric
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0016')
C Initialize some algorithmic and internal variables
      DGAMA=R0
      IFPLAS=.FALSE.
      SUFAIL=.FALSE.
      EPBARN=RSTAVA(MSTRE+1)
      EPBAR=EPBARN
C Set some material properties
      YOUNG=RPROPS(2)
      POISS=RPROPS(3)
      ETA=RPROPS(4)
      XI=RPROPS(5)
      ETABAR=RPROPS(6)
      NHARD=IPROPS(3)
C and some constants
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
      R2G=R2*GMODU
      R1D3=R1/R3
C Compute elastic trial state
C -----
C Elastic trial volumetric strain and pressure stress
      EETV=STRAT(1)+STRAT(2)+STRAT(4)
      PT=BULK*EETV
C Elastic trial deviatoric stress
      EEVD3=EETV*R1D3
      STRIAL(1)=R2G*(STRAT(1)-EEVD3)
      STRIAL(2)=R2G*(STRAT(2)-EEVD3)
      STRIAL(4)=R2G*(STRAT(4)-EEVD3)
C shear component
      STRIAL(3)=R2G*(STRAT(3)*RP5)
C Compute elastic trial stress J2 invariant and cohesion
      VARJ2T=STRIAL(3)*STRIAL(3)+RP5*(STRIAL(1)*STRIAL(1)+
1   STRIAL(2)*STRIAL(2)+STRIAL(4)*STRIAL(4))
      COHE=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
C Check for plastic consistency
C -----
      SQRJ2T=SQRT(VARJ2T)
      PHI=SQRJ2T+ETA*PT-XI*COHE
      RES=PHI
      IF(COHE.NE.R0)RES=RES/ABS(COHE)
      IF(RES.GT.TOL)THEN
C Plastic step: Use return mapping
C =====
      IFPLAS=.TRUE.
      APEX=.FALSE.
C Apply return mapping to smooth portion of cone - REFERENCE: Box 8.9
C -----
      DO 20 IPTER1=1,MAXRT
C Compute residual derivative
      DENOM=-GMODU-BULK*ETABAR*ETA-
1   XI*XI*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
C Compute Newton-Raphson increment and update variable DGAMA
      DDGAMA=-PHI/DENOM
      DGAMA=DGAMA+DDGAMA
C Compute new residual
      EPBAR=EPBARN+XI*DGAMA
      COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
      SQRJ2=SQRJ2T-GMODU*DGAMA
      P=PT-BULK*ETABAR*DGAMA
      PHI=SQRJ2+ETA*P-XI*COHE
C Check convergence
      RESNOR=ABS(PHI)
      IF(COHE.NE.R0)RESNOR=RESNOR/ABS(COHE)
      IF(RESNOR.LE.TOL)THEN
C Check validity of return to smooth portion
      IF(SQRJ2.GE.R0)THEN
C results are valid, update stress components and other variables
      IF(SQRJ2T.EQ.R0)THEN
          FACTOR=R0
      ELSE
          FACTOR=R1-GMODU*DGAMA/SQRJ2T
      ENDIF
      GOTO 50
      ELSE
C smooth wall return not valid - go to apex return procedure
      GOTO 30
      ENDIF
      ENDIF
20 CONTINUE
C failure of stress update procedure
      SUFAIL=.TRUE.
      CALL ERRPRT('WE0002')
      GOTO 999
30 CONTINUE
C Apply return mapping to APEX - REFERENCE: Box 8.10
C -----
C perform checks and set some variables
      APEX=.TRUE.

```

```

      IF(ETA.EQ.R0)CALL ERRPRT('EE0011')
      IF(ETABAR.EQ.R0)CALL ERRPRT('EE0012')
      ALPHA=XI/ETABAR
      BETA=XI/ETA
C Set initial guess for unknown DEPV and start iterations
      DEPV=R0
      EPBAR=EPBARN
      COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
      RES=BETA*COHE-PT
      DO 40 IPTER2=1,MAXRT
        DENOM=ALPHA*BETA*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))+BULK
C Compute Newton-Raphson increment and update variable DEPV
        DDEPV=-RES/DENOM
        DEPV=DEPV+DDEPV
C Compute new residual
        EPBAR=EPBARN+ALPHA*DEPV
        COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
        P=PT-BULK*DEPV
        RES=BETA*COHE-P
C Check convergence
        RESNOR=ABS(RES)
        IF(COHE.NE.R0)RESNOR=RESNOR/ABS(COHE)
        IF(RESNOR.LE.TOL)THEN
C update stress components and other variables
          DGAMA=DEPV/ETABAR
          FACTOR=R0
          GOTO 50
        ENDIF
      40 CONTINUE
C failure of stress update procedure
      SUFAIL=.TRUE.
      CALL ERRPRT('WE0002')
      GOTO 999
C Store converged stress components and other state variables
C -----
      50 CONTINUE
      STRES(1)=FACTOR*STRIAL(1)+P
      STRES(2)=FACTOR*STRIAL(2)+P
      STRES(3)=FACTOR*STRIAL(3)
      STRES(4)=FACTOR*STRIAL(4)+P
C update EPBAR
      RSTAVA(MSTRE+1)=EPBAR
C compute converged elastic (engineering) strain components
      FACTOR=FACTOR/R2G
      EEVD3=P/(BULK*R3)
      RSTAVA(1)=FACTOR*STRIAL(1)+EEVD3
      RSTAVA(2)=FACTOR*STRIAL(2)+EEVD3
      RSTAVA(3)=FACTOR*STRIAL(3)*R2
      RSTAVA(4)=FACTOR*STRIAL(4)+EEVD3
      ELSE
C Elastic step: update stress using linear elastic law
C =====
      STRES(1)=STRIAL(1)+PT
      STRES(2)=STRIAL(2)+PT
      STRES(3)=STRIAL(3)
      STRES(4)=STRIAL(4)+PT
C elastic engineering strain
      RSTAVA(1)=STRAT(1)
      RSTAVA(2)=STRAT(2)
      RSTAVA(3)=STRAT(3)
      RSTAVA(4)=STRAT(4)
      ENDIF
      999 CONTINUE
C Update some algorithmic variables before exit
C =====
      LALGVA(1)=IFPLAS
      LALGVA(2)=SUFAIL
      LALGVA(3)=APEX
      DGAM=DGAMA
      RETURN
      END

```

```

      SUBROUTINE SUDPPN
1(   RALGVA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2   RSTAVA ,STRAT ,STRES
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=7 ,MSTRE=4)
C Arguments
      LOGICAL LALGVA(3)
      DIMENSION
1   RALGVA(3) ,IPROPS(*) ,RPROPS(*) ,
2   RSTAVA(MSTRE+1) ,STRAT(MSTRE) ,STRES(MSTRE)
C Local arrays and variables
      LOGICAL EPFLAG ,IFPLAS ,SUFAIL
      DIMENSION
1   DMATX(MSTRE,MSTRE) ,RSTAX(MSTRE+1)
      DATA
1   R0 ,TOL /
2   0.0D0 ,1.D-08 /
      DATA MXITER / 20 /
C*****
C STATE UPDATE PROCEDURE FOR THE DRUCKER-PRAGER ELASTO-PLASTIC MODEL
C WITH NON-LINEAR (PIECEWISE LINEAR) ISOTROPIC HARDENING IN PLANE
C STRESS. NESTED ITERATION APPROACH.
C
C REFERENCE: Section 9.2.2
C*****
C Stop program if not plane stress
      IF(NTYPE.NE.1)CALL ERRPR('EI0038')
C Initialise the state update failure flag
      SUFAIL=.FALSE.
C Set some material properties
      NHARD=IPROPS(3)
C
C Begin Newton-Raphson iteration loop for plane stress enforcement
C -----
C
C Set initial guess for elastic trial thickness strain. Use previously
C converged elastic thickness strain.
      E33TRL=RSTAVA(4)
C Start N-R loop
      DO 20 ITER=1,MXITER
C Set state variables to values at beginning of increment
      DO 10 I=1,MSTRE+1
          RSTAX(I)=RSTAVA(I)
10      CONTINUE
C Use axisymmetric integration algorithm to compute stresses, etc.
      STRAT(4)=E33TRL
      CALL SUDE
1(   RALGVA ,IPROPS ,LALGVA ,3 ,RPROPS ,
2   RSTAX ,STRAT ,STRES
      SUFAIL=LALGVA(2)
      IF(SUFAIL)THEN
C... emergency exit in case of failure of the state update procedure
          GOTO 999
      ENDIF
      IFPLAS=LALGVA(1)
C Check plane stress convergence
      EPBAR=RSTAVA(MSTRE+1)
      COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
      RES=ABS(STRES(4))
C...use normalised out-of-plane stress
      IF(COHE.NE.R0)RES=RES/ABS(COHE)
      IF(RES.LE.TOL)THEN
C...and break N-R loop in case of convergence
          GOTO 30
      ENDIF
C Compute axisymmetric consistent tangent components
      EPFLAG=IFPLAS
      CALL CTDE
1(   RALGVA ,DMATX ,EPFLAG ,IPROPS ,LALGVA ,
2   3 ,RPROPS ,RSTAX ,STRAT
C Apply Newton-Raphson correction to normal elastic trial strain
      D22=DMATX(4,4)
      E33TRL=E33TRL-STRES(4)/D22
20      CONTINUE
C Emergency exit in case of failure of the plane stress enforcement loop
      SUFAIL=.TRUE.
      LALGVA(2)=SUFAIL
      CALL ERRPR('WE0016')
      GOTO 999
30      CONTINUE
C Set state variables to current updated values
      DO 40 I=1,MSTRE+1
          RSTAVA(I)=RSTAX(I)
40      CONTINUE
C Store the converged elastic trial thickness strain in the array of
C real algorithmic variables
      RALGVA(3)=E33TRL
C
999      CONTINUE
      RETURN
      END

```



```

      SUBROUTINE SUEL
1(   NTYPE ,RPROPS ,RSTAVA ,STRAN ,STRES )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(MSTRE=4)
      DIMENSION
1   RPROPS(*) ,RSTAVA(MSTRE) ,STRAN(*) ,
2   STRES(*)
      DIMENSION
1   EED(MSTRE)
      DATA
1   RP5 ,R2 ,R3 ,R4 /
2   0.5D0,2.0D0,3.0D0,4.0D0/
C*****
C STATE UPDATE PROCEDURE FOR LINEAR ELASTIC MATERIAL MODEL
C
C REFERENCE: Expression (4.43)
C*****
C
C Set shear and bulk modulus
C
      GMODU=RPROPS(2)
      BULK=RPROPS(3)
C
C Decompose strain into deviatoric and volumetric components
C -----
C
      R2G=R2*GMODU
      IF(NTYPE.EQ.1)THEN
C for plane stress
      R4G=R4*GMODU
      R4GD3=R4G/R3
      FACTOR=R2G/(BULK+R4GD3)
      EEV=(STRAN(1)+STRAN(2))*FACTOR
      EEVD3=EEV/R3
      EED(1)=STRAN(1)-EEVD3
      EED(2)=STRAN(2)-EEVD3
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
C for plane strain and axisymmetric cases
      EEV=STRAN(1)+STRAN(2)+STRAN(4)
      EEVD3=EEV/R3
      EED(1)=STRAN(1)-EEVD3
      EED(2)=STRAN(2)-EEVD3
      EED(4)=STRAN(4)-EEVD3
      ELSE
      CALL ERRPRT('EI0018')
      ENDIF
C Convert engineering shear component into physical component
      EED(3)=STRAN(3)*RP5
C
C Update stress using linear elastic law
C -----
C
C hydrostatic stress
      P=BULK*EEV
C stress tensor components
      STRES(1)=R2G*EED(1)+P
      STRES(2)=R2G*EED(2)+P
      STRES(3)=R2G*EED(3)
      IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)STRES(4)=R2G*EED(4)+P
C
C Store elastic engineering strain in RSTAVA
C -----
C
      RSTAVA(1)=STRAN(1)
      RSTAVA(2)=STRAN(2)
      RSTAVA(3)=STRAN(3)
      IF(NTYPE.EQ.1)THEN
      R3BULK=R3*BULK
      RSTAVA(4)=- (STRAN(1)+STRAN(2)) * (R3BULK-R2G) / (R3BULK+R4G)
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
      RSTAVA(4)=STRAN(4)
      ENDIF
C
      RETURN
      END

```

```

SUBROUTINE SUMC
1( DGAM ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=7 ,MSTRE=4)
C Arguments
LOGICAL
1 LALGVA(5)
DIMENSION
1 DGAM(2) ,IPROPS(*) ,RPROPS(*) ,
2 RSTAVA(MSTRE+1) ,STRAT(MSTRE) ,STRES(MSTRE)
C Local variables and arrays
LOGICAL
1 APEX, DUMMY, EDGE, IFPLAS, RIGHT, SUFAIL
DIMENSION
1 EIGPRJ(MSTRE,2) ,PSTRS(3) ,STREST(3)
DATA
1 R0 ,R1 ,R2 ,R3 ,R4 ,SMALL ,TOL /
2 0.0D0,1.0D0,2.0D0,3.0D0,4.0D0,1.D-06,1.D-10/
DATA MXITER / 50 /
C*****
C STATE UPDATE PROCEDURE FOR MOHR-COULOMB TYPE ELASTO-PLASTIC MATERIAL
C WITH ASSOCIATIVE/NON-ASSOCIATIVE FLOW RULE AND PIECE-WISE LINEAR
C ISOTROPIC HARDENING:
C IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM (BOXES 8.4-7).
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Boxes 8.4-7
C Section 8.2.2
C*****
C Stops program if neither plane strain nor plane stress state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0027')
C Initialize some algorithmic and internal variables
DGAMA=R0
DGAMB=R0
IFPLAS=.FALSE.
SUFAIL=.FALSE.
EDGE=.FALSE.
APEX=.FALSE.
EPBARN=RSTAVA(MSTRE+1)
EPBAR=EPBARN
C Set some material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
SINPHI=RPROPS(4)
COSPHI=RPROPS(5)
SINPSI=RPROPS(6)
NHARD=IPROPS(3)
C Set some constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R4G=R4*GMODU
R2BULK=R2*BULK
R2CPHI=R2*COSPHI
R1D3=R1/R3
C Compute elastic trial state
C -----
C Elastic trial volumetric strain and pressure stress
EETV=STRAT(1)+STRAT(2)+STRAT(4)
PT=BULK*EETV
C Spectral decomposition of the elastic trial stress
EETVD3=EETV*R1D3
STREST(1)=R2G*(STRAT(1)-EETVD3)+PT
STREST(2)=R2G*(STRAT(2)-EETVD3)+PT
STREST(3)=GMODU*STRAT(3)
CALL SPDEC2(EIGPRJ,PSTRS,DUMMY,STREST)
PSTRS(3)=R2G*(STRAT(4)-EETVD3)+PT
C Identify maximum (PSTRS1) and minimum (PSTRS3) principal stresses
II=1
JJ=1
PSTRS1=PSTRS(II)
PSTRS3=PSTRS(JJ)
DO 10 I=2,3
IF(PSTRS(I).GE.PSTRS1)THEN
II=I
PSTRS1=PSTRS(II)
ENDIF
IF(PSTRS(I).LT.PSTRS3)THEN
JJ=I
PSTRS3=PSTRS(JJ)
ENDIF
10 CONTINUE
IF(II.NE.1.AND.JJ.NE.1)MM=1
IF(II.NE.2.AND.JJ.NE.2)MM=2
IF(II.NE.3.AND.JJ.NE.3)MM=3
PSTRS2=PSTRS(MM)
C Compute trial yield function and check for plastic consistency
C -----
COHE=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
SMCT=PSTRS1-PSTRS3+(PSTRS1+PSTRS3)*SINPHI
PHIA=SMCT-R2CPHI*COHE
RES=PHIA
IF(COHE.NE.R0)RES=RES/ABS(COHE)
IF(RES.GT.TOL)THEN
C Plastic step: Apply return mapping
C =====
IFPLAS=.TRUE.
C identify possible edge return: either right or left of main plane
SCAPRD=PSTRS1*(R1-SINPSI)+PSTRS2*(-R2)+PSTRS3*(R1+SINPSI)
IF(SCAPRD.GE.R0)THEN
RIGHT=.TRUE.
ELSE
RIGHT=.FALSE.
ENDIF
C Apply one-vector return mapping first (return to MAIN PLANE)
C -----
SPHSPS=SINPHI*SINPSI
CONSTA=R4G*(R1+R1D3*SPHSPS)+R4*BULK*SPHSPS
R4C2PH=R2CPHI*R2CPHI
C Start Newton-Raphson iterations for DGAMA
DO 20 NRITER=1,MXITER
C Compute residual derivative

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DENOM=-CONSTA-R4C2PH*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
C Compute Newton-Raphson increment and update variable DGAMA
DDGAMA=-PHIA/DENOM
DGAMA=DGAMA+DDGAMA
C Compute new residual
EPBAR=EPBARN+R2CPHI*DGAMA
COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
PHIA=SMCT-CONSTA*DGAMA-R2CPHI*COHE
C Check convergence
RESNOR=ABS(PHIA)
IF(SMCT.NE.R0)RESNOR=RESNOR/ABS(SMCT)
IF(RESNOR.LE.TOL)THEN
C Check validity of 1-vector return (check sextant of converged stress)
S1=PSTRS1-(R2G*(R1+R1D3*SINPSI)+R2BULK*SINPSI)*DGAMA
S2=PSTRS2+(R4G*R1D3-R2BULK)*SINPSI*DGAMA
S3=PSTRS3+(R2G*(R1-R1D3*SINPSI)-R2BULK*SINPSI)*DGAMA
DELTA=DMAX1(ABS(S1),ABS(S2),ABS(S3))*SMALL
IF(S1+DELTA.GE.S2.AND.S2+DELTA.GE.S3)THEN
C converged stress is in the same sextant as trial stress -> 1-vector
C return is valid.
P=(S1+S2+S3)*R1D3
GOTO 70
ELSE
C converged stress is not in the same sextant -> 1-vector result is
C not valid. Go to two-vector return map to edge
GOTO 30
ENDIF
ENDIF
20 CONTINUE
C failure of stress update procedure
SUFAIL=.TRUE.
CALL ERRPR('WE0003')
GOTO 999
30 CONTINUE
C Apply two-vector return mapping to appropriate EDGE
C -----
DGAMA=R0
EPBAR=EPBARN
COHE=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
SMCTA=PSTRS1-PSTRS3+(PSTRS1+PSTRS3)*SINPHI
IF(RIGHT)THEN
SMCTB=PSTRS1-PSTRS2+(PSTRS1+PSTRS2)*SINPHI
ELSE
SMCTB=PSTRS2-PSTRS3+(PSTRS2+PSTRS3)*SINPHI
ENDIF
PHIA=SMCTA-R2CPHI*COHE
PHIB=SMCTB-R2CPHI*COHE
IF(RIGHT)THEN
CONSTB=R2G*(R1+SINPHI+SINPSI-R1D3*SPHSPS)+R4*BULK*SPHSPS
ELSE
CONSTB=R2G*(R1-SINPHI-SINPSI-R1D3*SPHSPS)+R4*BULK*SPHSPS
ENDIF
C Start Newton-Raphson iterations for DGAMA and DGAMB
DO 40 NRITER=1,MXITER
C Compute residual derivative matrix
FACTA=R4C2PH*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
DRVAA=-CONSTA-FACTA
DRVAB=-CONSTB-FACTA
DRVBA=-CONSTB-FACTA
DRVBB=-CONSTA-FACTA
C Compute Newton-Raphson increment and update variables DGAMA and DGAMB
R1DDET=R1/(DRVAA*DRVBB-DRVAB*DRVBA)
DDGAMA=(-DRVBB*PHIA+DRVAB*PHIB)*R1DDET
DDGAMB=(DRVBA*PHIA-DRVAA*PHIB)*R1DDET
DGAMA=DGAMA+DDGAMA
DGAMB=DGAMB+DDGAMB
C Compute new residual
EPBAR=EPBARN+R2CPHI*(DGAMA+DGAMB)
COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
PHIA=SMCTA-CONSTA*DGAMA-CONSTB*DGAMB-R2CPHI*COHE
PHIB=SMCTB-CONSTB*DGAMA-CONSTA*DGAMB-R2CPHI*COHE
C Check convergence
RESNOR=(ABS(PHIA)+ABS(PHIB))
FACTOR=(ABS(SMCTA)+ABS(SMCTB))
IF(FACTOR.NE.R0)RESNOR=RESNOR/FACTOR
IF(RESNOR.LE.TOL)THEN
C Check validity of 2-vector return to edge
AUX1=R2G*(R1+R1D3*SINPSI)+R2BULK*SINPSI
AUX2=(R4G*R1D3-R2BULK)*SINPSI
AUX3=R2G*(R1-R1D3*SINPSI)-R2BULK*SINPSI
IF(RIGHT)THEN
S1=PSTRS1-AUX1*(DGAMA+DGAMB)
S2=PSTRS2+AUX2*DGAMA+AUX3*DGAMB
S3=PSTRS3+AUX3*DGAMA+AUX2*DGAMB
ELSE
S1=PSTRS1-AUX1*DGAMA+AUX2*DGAMB
S2=PSTRS2+AUX2*DGAMA-AUX1*DGAMB
S3=PSTRS3+AUX3*(DGAMA+DGAMB)
ENDIF
DELTA=DMAX1(ABS(S1),ABS(S2),ABS(S3))*SMALL
IF(S1+DELTA.GE.S2.AND.S2+DELTA.GE.S3)THEN
C converged stress is in the same sextant as trial stress -> 2-vector
C return to edge is valid.
EDGE=.TRUE.
P=(S1+S2+S3)*R1D3
GOTO 70
ELSE
C converged stress is not in the same sextant -> 2-vector return to edge
C is not valid. Go to two-vector return map to APEX
GOTO 50
ENDIF
ENDIF
40 CONTINUE
C failure of stress update procedure
SUFAIL=.TRUE.
CALL ERRPR('WE0003')
GOTO 999
50 CONTINUE
C Apply multi-vector return mapping to APEX
C -----
C Check conditions for which return to apex does not make sense
IF(SINPHI.EQ.R0)CALL ERRPR('EE0009')
IF(SINPSI.EQ.R0)CALL ERRPR('EE0010')

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```

C Set initial guess for volumetric plastic strain increment DEPV
  DEPV=R0
  EPBAR=EPBARN
  COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
  COTPHI=COSPHI/SINPHI
  RES=COTPHI*COHE-PT
C Newton-Raphson iterations for DEPV
  DO 60 NRITER=1,MXITER
    DENOM=COSPHI*COTPHI/SINPSI*DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))+
      1
    BULK
    DDEPV=-RES/DENOM
    DEPV=DEPV+DDEPV
    EPBAR=EPBARN+COSPHI/SINPSI*DEPV
    COHE=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
    P=PT-BULK*DEPV
    RES=COTPHI*COHE-P
C check for convergence
    RESNOR=ABS(RES)
    IF (PT.NE.R0)RESNOR=RESNOR/ABS(PT)
    IF (RESNOR.LE.TOL)THEN
      APEX=.TRUE.
      DGAMA=DEPV
      DGAMB=R0
C update principal stresses
      S1=P
      S2=P
      S3=P
      GOTO 70
    ENDIF
  60  CONTINUE
  SUFAIL=.TRUE.
  CALL ERRPR1('WE0003')
  GOTO 999
70  CONTINUE
C update internal variable EPBAR and stress components
C -----
  RSTAVA(MSTRE+1)=EPBAR
  PSTRS(II)=S1
  PSTRS(JJ)=S3
  PSTRS(MM)=S2
  STRES(1)=PSTRS(1)*EIGPRJ(1,1)+PSTRS(2)*EIGPRJ(1,2)
  STRES(2)=PSTRS(1)*EIGPRJ(2,1)+PSTRS(2)*EIGPRJ(2,2)
  STRES(3)=PSTRS(1)*EIGPRJ(3,1)+PSTRS(2)*EIGPRJ(3,2)
  STRES(4)=PSTRS(3)
C and elastic engineering strain
  EEVD3=P/BULK*R1D3
  RSTAVA(1)=(STRES(1)-P)/R2G+EEVD3
  RSTAVA(2)=(STRES(2)-P)/R2G+EEVD3
  RSTAVA(3)=STRES(3)/GMODU
  RSTAVA(4)=(STRES(4)-P)/R2G+EEVD3
  ELSE
C Elastic step: update stress using linear elastic law
C =====
  STRES(1)=STREST(1)
  STRES(2)=STREST(2)
  STRES(3)=STREST(3)
  STRES(4)=PSTRS(3)
C elastic engineering strain
  RSTAVA(1)=STRAT(1)
  RSTAVA(2)=STRAT(2)
  RSTAVA(3)=STRAT(3)
  RSTAVA(4)=STRAT(4)
  ENDIF
999 CONTINUE
C Update algorithmic variables before exit
C =====
  DGAM(1)=DGAMA
  DGAM(2)=DGAMB
  LALGVA(1)=IFPLAS
  LALGVA(2)=SUFAIL
  LALGVA(3)=EDGE
  LALGVA(4)=RIGHT
  LALGVA(5)=APEX
  RETURN
END

```

```

SUBROUTINE SUOGD
1( B ,IPROPS ,NTYPE ,RPROPS ,RSTAVA ,
2 STRES ,THICK )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPOGDC=2)
LOGICAL DUMMY
PARAMETER
1( MCOMP=4 ,MSTRE=4 ,NDIM=2 )
DIMENSION
1 B(MCOMP) ,IPROPS(*) ,RPROPS(*) ,
2 RSTAVA(MSTRE) ,STRES(MSTRE)
DIMENSION
1 EIGPRJ(MCOMP,NDIM) ,EIGB(NDIM) ,PSTRES(3) ,
2 PSTRTC(3)
DATA R1 ,R3 /
1 1.0D0,3.0D0/
C*****
C STRESS UPDATE PROCEDURE FOR OGDEN TYPE HYPERELASTIC MATERIAL MODEL.
C PLANE STRESS, PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 13.5.1
C Box 13.1
C*****
C Retrieve Ogden material constants
C =====
C Number of terms in Ogden's strain-energy function
NOGTRM=IPROPS(3)
C Bulk modulus
BULK=RPROPS(IPOGDC+NOGTRM*2)
C Compute principal stretches
C =====
C Perform spectral decomposition of the left Cauchy-Green tensor B
CALL SPDEC2
1( EIGPRJ ,EIGB ,DUMMY ,B )
C Compute in-plane principal stretches
PSTRTC(1)=SQRT(EIGB(1))
PSTRTC(2)=SQRT(EIGB(2))
C...and out-of-plane stretches
IF(NTYPE.EQ.1)THEN
PSTRTC(3)=R1/(PSTRTC(1)*PSTRTC(2))
ELSEIF(NTYPE.EQ.2)THEN
PSTRTC(3)=R1
ELSEIF(NTYPE.EQ.3)THEN
PSTRTC(3)=SQRT(B(4))
ENDIF
C Compute principal Kirchhoff stresses
C =====
CALL RVZERO(PSTRES,3)
IF(NTYPE.EQ.1) THEN
C Plane stress: Exact incompressibility assumed
C -----
DO 10 I=1,NOGTRM
CMU=RPROPS(IPOGDC-1+I*2-1)
ALPHA=RPROPS(IPOGDC-1+I*2)
PSTRES(1)=PSTRES(1)+CMU*(PSTRTC(1)**ALPHA-
1 (PSTRTC(1)*PSTRTC(2))**(-ALPHA))
PSTRES(2)=PSTRES(2)+CMU*(PSTRTC(2)**ALPHA-
1 (PSTRTC(1)*PSTRTC(2))**(-ALPHA))
10 CONTINUE
DETF=R1
ELSE IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
C Plane strain and axisymmetric: Regularised Ogden constitutive law
C -----
C Compute principal deviatoric Kirchhoff stresses
R1D3=R1/R3
DETF=PSTRTC(1)*PSTRTC(2)
IF(NTYPE.EQ.3)DETF=DETF*PSTRTC(3)
DO 20 I=1,NOGTRM
CMU=RPROPS(IPOGDC-1+I*2-1)
ALPHA=RPROPS(IPOGDC-1+I*2)
FACTOR=R1D3*(PSTRTC(1)**ALPHA+PSTRTC(2)**ALPHA+
1 PSTRTC(3)**ALPHA)
FACVOL=DETF**(-ALPHA*R1D3)
PSTRES(1)=PSTRES(1)+CMU*FACVOL*(PSTRTC(1)**ALPHA-FACTOR)
PSTRES(2)=PSTRES(2)+CMU*FACVOL*(PSTRTC(2)**ALPHA-FACTOR)
PSTRES(3)=PSTRES(3)+CMU*FACVOL*(PSTRTC(3)**ALPHA-FACTOR)
20 CONTINUE
C Add hydrostatic Kirchhoff pressure (incompressibility penalty term)
PRESS=BULK*LOG(DETF)
DO 30 I=1,3
PSTRES(I)=PSTRES(I)+PRESS
30 CONTINUE
ENDIF
C Assemble array of Cauchy stress tensor components
C =====
CALL RVZERO(STRES,3)
R1DDET=R1/DETF
PSTRES(1)=PSTRES(1)*R1DDET
PSTRES(2)=PSTRES(2)*R1DDET
DO 50 ICOMP=1,3
DO 40 IDIR=1,2
STRES(ICOMP)=STRES(ICOMP)+PSTRES(IDIR)*EIGPRJ(ICOMP,IDIR)
40 CONTINUE
50 CONTINUE
IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)STRES(4)=PSTRES(3)*R1DDET
C Update thickness (plane stress only) and store left Cauchy-Green
C tensor components in state variables vector RSTAVA
C =====

```

```
RSTAVA(1)=B(1)
RSTAVA(2)=B(2)
RSTAVA(3)=B(3)
IF(NTYPE.EQ.1)THEN
  THICK=THICK*PSTRTC(3)
  RSTAVA(4)=PSTRTC(3)*PSTRTC(3)
ELSEIF(NTYPE.EQ.2)THEN
  RSTAVA(4)=R1
ELSEIF(NTYPE.EQ.3)THEN
  RSTAVA(4)=B(4)
ENDIF

RETURN
END
```

C

```

SUBROUTINE SUPDSC
1( DGAM ,FINCR ,IPROPS ,LALGVA ,NTYPE ,
2 RPROPS ,RSTAVA ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER
1( IPHARD=6 ,IPHVAR=5 ,MTRIAL=5 ,NDIM=2 ,NIPROP=3 ,
2 NLALGV=6 ,NRALGV=4 ,NRSTAV=5 ,NSTRE=4 ,NSYST=4 )

C Arguments
LOGICAL
1 LALGVA(NLALGV)
DIMENSION
1 DGAM(NRALGV) ,FINCR(3,3) ,IPROPS(NIPROP) ,
2 RPROPS(*) ,RSTAVA(NRSTAV) ,STRES(NSTRE)

C Local arrays and variables
LOGICAL
1 IFPLAS ,NOCONV ,SUFAIL ,SIACT ,S2ACT ,S3ACT ,S4ACT
DIMENSION
1 BEDEV(4) ,BEISO(3,3) ,BMATX(NDIM,NDIM,NSYST) ,
2 DDGAM(NSYST) ,DEREXP(3,3,3,3) ,DSOMO(NDIM,NDIM) ,
3 FEISO(2,2) ,FEN(2,2) ,FETISO(2,2) ,
4 FETRL(2,2) ,FPILOG(3,3) ,FPINCI(3,3) ,
5 GINV(NSYST,NSYST) ,GMATX(NSYST,NSYST) ,IACSET(NSYST,MTRIAL) ,
6 IPACT(0:5) ,NACSYS(MTRIAL) ,PHI(NSYST) ,
7 SCHMID(NSYST) ,SMOMS0(NDIM,NDIM,NSYST) ,
8 SOMO(NDIM,NDIM,NSYST) ,VECM(NDIM,NSYST) ,VECM0(NDIM,NSYST) ,
9 VECS(NDIM,NSYST) ,VECS0(NDIM,NSYST)
DATA
1 IPACT(0) ,IPACT(1) ,IPACT(2) ,IPACT(3) ,IPACT(4) ,IPACT(5) /
2 4 ,1 ,2 ,3 ,4 ,1 /
DATA
1 R0 ,R1 ,R3 ,SMALL ,TOL /
2 0.0D0,1.0D0,3.0D0,1.D-10,1.D-08/
DATA MXITER / 50 /

C*****
C STRESS UPDATE PROCEDURE FOR THE ANISOTROPIC PLANAR DOUBLE-SLIP SINGLE
C CRYSTAL ELASTO-PLASTIC MODEL WITH PIECE-WISE LINEAR TAYLOR ISOTROPIC
C HARDENING:
C MULTI-SURFACE TYPE IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM
C BASED ON THE EXPONENTIAL MAP APPROXIMATION OF THE PLASTIC FLOW RULE.
C
C REFERENCE: Section 16.6.2
C Boxes 16.2-3
C*****
C Stops program if not plane strain
IF(NTYPE.NE.2)CALL ERRPR('EI0036')
C Initialize some algorithmic and internal variables
CALL RVZERO(DGAM,NSYST)
IFPLAS=.FALSE.
SUFAIL=.FALSE.
SIACT=.FALSE.
S2ACT=.FALSE.
S3ACT=.FALSE.
S4ACT=.FALSE.
C... hardening internal variable
HRVARN=RSTAVA(IPHVAR)
HRVAR=HRVARN
C... elastic deformation gradient
FEN(1,1)=RSTAVA(1)
FEN(2,1)=RSTAVA(2)
FEN(1,2)=RSTAVA(3)
FEN(2,2)=RSTAVA(4)
C Retrieve material properties
C... neo-Hookean constants
GMODU=RPROPS(2)
BULK=RPROPS(3)
C... initial system orientation
THETA=RPROPS(4)
C... relative angle between systems
BETA=RPROPS(5)
C... number of sampling points on hardening curve
NHARD=IPROPS(3)
C Set up initial slip systems vectors
C... system 1:
VECS0(1,1)=COS(THETA)
VECS0(2,1)=SIN(THETA)
VECM0(1,1)=-SIN(THETA)
VECM0(2,1)=COS(THETA)
C... system 2:
VECS0(1,2)=COS(THETA+BETA)
VECS0(2,2)=SIN(THETA+BETA)
VECM0(1,2)=-SIN(THETA+BETA)
VECM0(2,2)=COS(THETA+BETA)
C... system 3:
VECS0(1,3)=-VECS0(1,1)
VECS0(2,3)=-VECS0(2,1)
VECM0(1,3)=VECM0(1,1)
VECM0(2,3)=VECM0(2,1)
C... system 4:
VECS0(1,4)=-VECS0(1,2)
VECS0(2,4)=-VECS0(2,2)
VECM0(1,4)=VECM0(1,2)
VECM0(2,4)=VECM0(2,2)
C Set some constants
RLD3=R1/R3
C Compute elastic trial state
C -----
C Elastic trial deformation gradient
CALL RVZERO(FETRL,NDIM*NDIM)
DO 30 I=1,NDIM
DO 20 J=1,NDIM
DO 10 K=1,NDIM
FETRL(I,J)=FETRL(I,J)+FINCR(I,K)*FEN(K,J)
10 CONTINUE
20 CONTINUE
30 CONTINUE
C Perform isochoric/volumetric split of elastic trial def. grad.
DETFET=FETRL(1,1)*FETRL(2,2)-FETRL(1,2)*FETRL(2,1)
VOLFAC=DETFET**(-RLD3)
FETISO(1,1)=VOLFAC*FETRL(1,1)
FETISO(2,1)=VOLFAC*FETRL(2,1)
FETISO(1,2)=VOLFAC*FETRL(1,2)
FETISO(2,2)=VOLFAC*FETRL(2,2)
C Check plastic consistency

```

```

C -----
C Compute yield functions values
C... elastic push forward of slip-systems vectors
  CALL RVZERO(VECS,NDIM*NSYST)
  CALL RVZERO(VECM,NDIM*NSYST)
  DO 60 I=1,NDIM
    DO 50 J=1,NDIM
      DO 40 ISYST=1,NSYST
        VECS(I,ISYST)=VECS(I,ISYST)+FETISO(I,J)*VECS0(J,ISYST)
        VECM(I,ISYST)=VECM(I,ISYST)+FETISO(I,J)*VECM0(J,ISYST)
      40 CONTINUE
    50 CONTINUE
  60 CONTINUE
C... current resolved yield stress
  RYIELD=PLFUN(HRVAR,NHARD,RPROPS(IPHARD))
C... elastic trial Schmid resolved shear stresses
  DO 70 ISYST=1,NSYST
    SCHMID(ISYST)=GMODU*SCAPRD(VECS(1,ISYST),VECM(1,ISYST),2)
  70 CONTINUE
C Check consistency
C... compute yield functions values and determine set of active systems
C at elastic trial state
  IACSYS=0
  DO 80 ISYST=1,NSYST
    PHI(ISYST)=SCHMID(ISYST)-RYIELD
    IF(PHI(ISYST)/RYIELD.GT.TOL)THEN
      IFPLAS=.TRUE.
      IACSYS=IACSYS+1
      IACSET(IACSYS,1)=ISYST
    ENDIF
  80 CONTINUE
  NACSYS(1)=IACSYS
C... define the other possible tentative sets of active systems
  IF(NACSYS(1).EQ.1)THEN
    NTENT=3
    NACSYS(2)=2
    IACSET(1,2)=IACSET(1,1)
    IACSET(2,2)=IPACT(IACSET(1,1)-1)
    NACSYS(3)=2
    IACSET(1,3)=IACSET(1,1)
    IACSET(2,3)=IPACT(IACSET(1,1)+1)
  ELSEIF(NACSYS(1).EQ.2)THEN
    NTENT=5
    NACSYS(2)=1
    IACSET(1,2)=IACSET(1,1)
    NACSYS(3)=1
    IACSET(1,3)=IACSET(2,1)
    IF(IACSET(1,1).EQ.1.AND.IACSET(2,1).EQ.4)THEN
      NACSYS(4)=2
      IACSET(1,4)=1
      IACSET(2,4)=2
      NACSYS(5)=2
      IACSET(1,5)=3
      IACSET(2,5)=4
    ELSE
      NACSYS(4)=2
      IACSET(1,4)=IACSET(1,1)
      IACSET(2,4)=IPACT(IACSET(1,1)-1)
      NACSYS(5)=2
      IACSET(1,5)=IACSET(2,1)
      IACSET(2,5)=IPACT(IACSET(2,1)+1)
    ENDIF
  ENDIF
  IF(IFPLAS)THEN
C Plastic step: Apply return mapping
C =====
C Loop over the tentative sets of active systems
C -----
    DO 420 ITENT=1,NTENT
C re-set elastic push-forward of slip systems vectors
      CALL RVZERO(VECS,NDIM*NSYST)
      CALL RVZERO(VECM,NDIM*NSYST)
      DO 110 I=1,NDIM
        DO 100 J=1,NDIM
          DO 90 ISYST=1,NSYST
            VECS(I,ISYST)=VECS(I,ISYST)+FETISO(I,J)*VECS0(J,ISYST)
            VECM(I,ISYST)=VECM(I,ISYST)+FETISO(I,J)*VECM0(J,ISYST)
          90 CONTINUE
        100 CONTINUE
      110 CONTINUE
C re-set hardening variable
      HRVAR=HRVARN
C re-set yield function values at trial state
      RYIELD=PLFUN(HRVAR,NHARD,RPROPS(IPHARD))
C... elastic trial Schmid resolved shear stresses
      DO 120 ISYST=1,NSYST
        SCHMID(ISYST)=GMODU*SCAPRD(VECS(1,ISYST),VECM(1,ISYST),NDIM)
        PHI(ISYST)=SCHMID(ISYST)-RYIELD
      120 CONTINUE
C Start Newton-Raphson iterations for plastic multipliers
      CALL RVZERO(DGAM,NSYST)
      DO 410 NRITER=1,MXITER
        HSLOPE=DPLFUN(HRVAR,NHARD,RPROPS(IPHARD))
        IF(NRITER.EQ.1)CALL RVZERO(FPILOG,9)
        CALL DEXPMP( DEREXP ,NOCONV ,FPILOG )
        CALL RVZERO(BMATX,NDIM*NDIM*NSYST)
        DO 220 II=1,NACSYS(ITENT)
          ISYST=IACSET(II,ITENT)
          DO 140 I=1,NDIM
            DO 130 J=1,NDIM
              SOM0(I,J,ISYST)=VECS0(I,ISYST)*VECM0(J,ISYST)
              SOM0MS0(I,J,ISYST)=VECS(I,ISYST)*VECM0(J,ISYST)+
                VECM(I,ISYST)*VECS0(J,ISYST)
            130 CONTINUE
          140 CONTINUE
          CALL RVZERO(DSOM0,NDIM*NDIM)
          DO 180 I=1,NDIM
            DO 170 J=1,NDIM
              DO 160 K=1,NDIM
                DO 150 L=1,NDIM
                  DSOM0(I,J)=DSOM0(I,J)+
                    DEREXP(I,J,K,L)*SOM0(K,L,ISYST)
                150 CONTINUE
              160 CONTINUE
            170 CONTINUE
          180 CONTINUE
        410 CONTINUE
      420 CONTINUE
    ENDIF
  ENDIF

```



```

160         CONTINUE
170         CONTINUE
180         CONTINUE
          DO 210 I=1,NDIM
            DO 200 J=1,NDIM
              DO 190 K=1,NDIM
                BMATX(I,J,ISYST)=BMATX(I,J,ISYST)+
1          FETISO(I,K)*DSOM0(K,J)
190         CONTINUE
200         CONTINUE
210         CONTINUE
220         CONTINUE
          DO 240 II=1,NACSYS(ITENT)
            ISYST=IACSET(II,ITENT)
C Compute exact jacobian of non-linear system of equations
          DO 230 JJ=1,NACSYS(ITENT)
            JSYST=IACSET(JJ,ITENT)

            GMATX(II,JJ)=GMODU*
1          SCAPRD(SM0MS0(1,1,ISYST),BMATX(1,1,JSYST),NDIM*NDIM)+
2          HSLOPE

230         CONTINUE
240         CONTINUE
C Invert jacobian: Note that for the double slip model only one or two
C systems may be active
          IF(NACSYS(ITENT).EQ.1)THEN
            IF(GMATX(1,1).LT.SMALL)THEN
C... jacobian is singular: Try another active set or exit if
C          all possible sets have already been tried
              GOTO 420
            ENDIF
            GINV(1,1)=R1/GMATX(1,1)
          ELSEIF(NACSYS(ITENT).EQ.2)THEN
            DETG=GMATX(1,1)*GMATX(2,2)-GMATX(1,2)*GMATX(2,1)
            IF(DETG.LT.SMALL)THEN
C... jacobian is singular: Try another active set or exit if
C          all possible sets have already been tried
              GOTO 420
            ENDIF
            DETGIN=R1/DETG
            GINV(1,1)=GMATX(2,2)*DETG
            GINV(2,2)=GMATX(1,1)*DETG
            GINV(1,2)=-GMATX(1,2)*DETG
            GINV(2,1)=-GMATX(2,1)*DETG
          ENDIF
C Apply Newton-Raphson correction to plastic multipliers
          CALL RVZERO(DDGAM,NSYST)
          DO 260 II=1,NACSYS(ITENT)
            ISYST=IACSET(II,ITENT)
            DO 250 JJ=1,NACSYS(ITENT)
              JSYST=IACSET(JJ,ITENT)
              DDGAM(ISYST)=DDGAM(ISYST)+GINV(II,JJ)*PHI(JSYST)
250         CONTINUE
            DGAM(ISYST)=DGAM(ISYST)+DDGAM(ISYST)
260         CONTINUE
C Compute inverse of incremental plastic deformation gradient
C... sum up contributions from each active slip system
          CALL RVZERO(FPILOG,9)
          DO 290 II=1,NACSYS(ITENT)
            ISYST=IACSET(II,ITENT)
            DO 280 I=1,NDIM
              DO 270 J=1,NDIM
                FPILOG(I,J)=FPILOG(I,J)-
1          DGAM(ISYST)*VECS0(I,ISYST)*VECM0(J,ISYST)
270         CONTINUE
280         CONTINUE
290         CONTINUE
C... use exponential map to update inverse of incremental Fp
          CALL EXPMAP
1( FPINCI ,NOCONV ,FPILOG )
          IF(NOCONV)THEN
C... exponential map algorithm failed: Break loop and exit
            SUFAIL=.TRUE.
            CALL ERRPR('WE0014')
            GOTO 999
          ENDIF
C Update isochoric component of elastic deformation gradient
          CALL RVZERO(FEISO,4)
          DO 320 I=1,NDIM
            DO 310 J=1,NDIM
              DO 300 K=1,NDIM
                FEISO(I,J)=FEISO(I,J)+FETISO(I,K)*FPINCI(K,J)
300         CONTINUE
310         CONTINUE
320         CONTINUE
C Update hardening internal variable and yield resolved shear stress
          HRVAR=HRVAR
          DO 330 II=1,NACSYS(ITENT)
            ISYST=IACSET(II,ITENT)
            HRVAR=HRVAR+DGAM(ISYST)
330         CONTINUE
C Compute yield functions values and check for convergence
C... elastic push forward of all slip-systems vectors
          CALL RVZERO(VECS,NDIM*NSYST)
          CALL RVZERO(VECM,NDIM*NSYST)
          DO 360 I=1,NDIM
            DO 350 J=1,NDIM
              DO 340 ISYST=1,NSYST
                VECS(I,ISYST)=VECS(I,ISYST)+FEISO(I,J)*VECS0(J,ISYST)
                VECM(I,ISYST)=VECM(I,ISYST)+FEISO(I,J)*VECM0(J,ISYST)
340         CONTINUE
350         CONTINUE
360         CONTINUE
C... update resolved yield stress
          RYIELD=PLFUN(HRVAR,NHARD,RPROPS(IPHARD))
C... Schmid resolved shear stresses for all systems and corresponding
C yield function values
          DO 370 ISYST=1,NSYST
            SCHMID(ISYST)=GMODU*
1          SCAPRD(VECS(1,ISYST),VECM(1,ISYST),NDIM)
370         CONTINUE

```

```

C... check for convergence
      RESNOR=R0
      DO 380 II=1,NACSYS(ITENT)
        ISYST=IACSET(II,ITENT)
        RESNOR=RESNOR+ABS(PHI(ISYST))
380    CONTINUE
      RESNOR=RESNOR/RYIELD
      IF(RESNOR.LE.TOL)THEN
C... N-R loop converged: check validity of current solution
      DO 390 ISYST=1,NSYST
        IF(DGAM(ISYST).LT.R0.OR.
1          PHI(ISYST)/RYIELD-TOL.GT.R0)THEN
C... current solution is not valid: Try another active set or exit if
C                                     all possible sets have already been
C                                     tried
          GOTO 420
        ENDIF
390    CONTINUE
C... Stress updated converged: Break loop to update necessary variables
C                                     and exit
      DO 400 II=1,NACSYS(ITENT)
        ISYST=IACSET(II,ITENT)
        IF(ISYST.EQ.1)S1ACT=.TRUE.
        IF(ISYST.EQ.2)S2ACT=.TRUE.
        IF(ISYST.EQ.3)S3ACT=.TRUE.
        IF(ISYST.EQ.4)S4ACT=.TRUE.
400    CONTINUE
      GOTO 450
    ENDIF
410    CONTINUE
420    CONTINUE
C Stress update procedure failed to converge: Break loop and exit
      SUFAIL=.TRUE.
      CALL ERRPRF('WE0015')
      GOTO 999
    ELSE
C Elastic step: Trial state is the actual one
C =====
      DO 440 I=1,NDIM
        DO 430 J=1,NDIM
          FEISO(I,J)=FETISO(I,J)
430      CONTINUE
440    CONTINUE
    ENDIF
C Use neo-Hookean law to update stresses
C =====
450 CONTINUE
C Compute elastic left Cauchy-Green tensor
      CALL RVZERO(BEISO,9)
      DO 480 I=1,NDIM
        DO 470 J=1,NDIM
          DO 460 K=1,NDIM
            BEISO(I,J)=BEISO(I,J)+FEISO(I,K)*FEISO(J,K)
460      CONTINUE
470    CONTINUE
480 CONTINUE
      BEISO(3,3)=VOLFAC*VOLFAC
C Hydrostatic pressure
      P=BULK*LOG(DETFET)
C Deviatoric component of isochoric elastic left Cauchy-Green tensor
      TRACE=BEISO(1,1)+BEISO(2,2)+BEISO(3,3)
      BEDEV(1)=BEISO(1,1)-R1D3*TRACE
      BEDEV(2)=BEISO(2,2)-R1D3*TRACE
      BEDEV(3)=BEISO(1,2)
      BEDEV(4)=BEISO(3,3)-R1D3*TRACE
C Update Cauchy stress components
      DETINV=R1/DETFET
      STRES(1)=(GMODU*BEDEV(1)+P)*DETVIN
      STRES(2)=(GMODU*BEDEV(2)+P)*DETVIN
      STRES(3)=(GMODU*BEDEV(3))*DETVIN
      STRES(4)=(GMODU*BEDEV(4)+P)*DETVIN
C Update elastic deformation gradient components
      RSTAVA(1)=FEISO(1,1)/VOLFAC
      RSTAVA(2)=FEISO(2,1)/VOLFAC
      RSTAVA(3)=FEISO(1,2)/VOLFAC
      RSTAVA(4)=FEISO(2,2)/VOLFAC
C Store updated hardening variable
      RSTAVA(5)=HRVAR
999 CONTINUE
C Update some algorithmic variables before exit
C =====
      LALGVA(1)=IFPLAS
      LALGVA(2)=SUFAIL
      IF(.NOT.SUFAIL)THEN
C Update active system flags if state update was successful
      LALGVA(3)=S1ACT
      LALGVA(4)=S2ACT
      LALGVA(5)=S3ACT
      LALGVA(6)=S4ACT
    ENDIF
      RETURN
      END

```

```

      SUBROUTINE SUTR
1(   DGAM      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=4 ,MSTRE=4)
C Arguments
      LOGICAL
1   LALGVA(4)
      DIMENSION
1   DGAM(2)      ,IPROPS(*)      ,RPROPS(*)      ,
2   RSTAVA(MSTRE+1)      ,STRAT(MSTRE)      ,STRES(MSTRE)
C Local arrays and variables
      LOGICAL
1   DUMMY, IFPLAS, RIGHT, SUFAIL, TWOVEC
      DIMENSION
1   EIGPRJ(MSTRE,2)      ,PSTRS(3)      ,STREST(3)

      DATA
1   R0 ,R1 ,R2 ,R3 ,R4 ,SMALL ,TOL /
2   0.0D0,1.0D0,2.0D0,3.0D0,4.0D0,1.D-10,1.D-10/
      DATA MXITER / 50 /
C*****
C STRESS UPDATE PROCEDURE FOR TRESCA TYPE ELASTO-PLASTIC MATERIAL WITH
C PIECE-WISE LINEAR ISOTROPIC HARDENING:
C IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM (Boxes 8.1-3).
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Boxes 8.1-3
C           Section 8.1.2
C*****
C Stops program if neither plane strain nor axisymmetric state
      IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0029')
C Initialize some algorithmic and internal variables
      DGAMA=R0
      DGAMB=R0
      IFPLAS=.FALSE.
      SUFAIL=.FALSE.
      EPBARN=RSTAVA(MSTRE+1)
      EPBAR=EPBARN
C Set some material properties
      YOUNG=RPROPS(2)
      POISS=RPROPS(3)
      NHARD=IPROPS(3)
C Set some constants
      GMODU=YOUNG/(R2*(R1+POISS))
      BULK=YOUNG/(R3*(R1-R2*POISS))
      R2G=R2*GMODU
      R4G=R4*GMODU
      R1D3=R1/R3
C Compute elastic trial state
C -----
C Volumetric strain and pressure stress
      EEV=STRAT(1)+STRAT(2)+STRAT(4)
      P=BULK*EEV
C Spectral decomposition of the elastic trial deviatoric stress
      EEVD3=EEV*R1D3
      STREST(1)=R2G*(STRAT(1)-EEVD3)
      STREST(2)=R2G*(STRAT(2)-EEVD3)
      STREST(3)=GMODU*STRAT(3)
      CALL SPDEC2(EIGPRJ,PSTRS,DUMMY,STREST)
      PSTRS(3)=R2G*(STRAT(4)-EEVD3)
C Identify maximum (PSTRS1) and minimum (PSTRS3) principal stresses
      II=1
      JJ=1
      PSTRS1=PSTRS(II)
      PSTRS3=PSTRS(JJ)
      DO 10 I=2,3
         IF(PSTRS(I).GE.PSTRS1)THEN
            II=I
            PSTRS1=PSTRS(II)
         ENDIF
         IF(PSTRS(I).LT.PSTRS3)THEN
            JJ=I
            PSTRS3=PSTRS(JJ)
         ENDIF
      10 CONTINUE
      IF(II.NE.1.AND.JJ.NE.1)MM=1
      IF(II.NE.2.AND.JJ.NE.2)MM=2
      IF(II.NE.3.AND.JJ.NE.3)MM=3
      PSTRS2=PSTRS(MM)
C Compute trial yield function and check for plastic consistency
C -----
      SHMAXT=PSTRS1-PSTRS3
      SIGMAY=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
      PHIA=SHMAXT-SIGMAY
      IF(PHIA/SIGMAY.GT.TOL)THEN
C Plastic step: Apply return mapping
C =====
         IFPLAS=.TRUE.
C identify possible two-vector return: right or left of main plane
         SCAPRD=PSTRS1+PSTRS3-PSTRS2*R2
         IF(SCAPRD.GE.R0)THEN
            RIGHT=.TRUE.
         ELSE
            RIGHT=.FALSE.
         ENDIF
C Apply one-vector return mapping first (return to main plane)
C -----
         TWOVEC=.FALSE.
C Start Newton-Raphson iterations
         DO 20 NRITER=1,MXITER
C Compute residual derivative
            DENOM=-R4G-DPLEUN(EPBAR,NHARD,RPROPS(IPHARD))
C Compute Newton-Raphson increment and update variable DGAMA
            DDGAMA=-PHIA/DENOM
            DGAMA=DGAMA+DDGAMA
C Compute new residual
            EPBAR=EPBARN+DGAMA
            SIGMAY=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
            SHMAX=SHMAXT-R4G*DGAMA
            PHIA=SHMAX-SIGMAY
C Check convergence
            RESNOR=ABS(PHIA/SIGMAY)

```

```

        IF(RESNOR.LE.TOL)THEN
C Check validity of one-vector return
        S1=PSTRS1-R2G*DGAMA
        S2=PSTRS2
        S3=PSTRS3+R2G*DGAMA
        DELTA=DMAX1(ABS(S1),ABS(S2),ABS(S3))*SMALL
        IF(S1+DELTA.GE.S2.AND.S2+DELTA.GE.S3)THEN
C converged stress is in the same sextant as trial stress -> 1-vector
C return is valid. Update EPBAR and principal deviatoric stresses
        RSTAVA(MSTRE+1)=EPBAR
        PSTRS1=S1
        PSTRS3=S3
        GOTO 50
    ELSE
C 1-vector return is not valid - go to two-vector procedure
        GOTO 30
    ENDIF
ENDIF
20 CONTINUE
C failure of stress update procedure
SUFAIL=.TRUE.
CALL ERRPR('WE0001')
GOTO 999
30 CONTINUE
C Apply two-vector return mapping (return to corner - right or left)
C -----
        TWOVEC=.TRUE.
        DGAMA=R0
        DGABAR=R1
        EPBAR=EPBARN
        SIGMAY=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
        SHMXTA=PSTRS1-PSTRS3
        IF(RIGHT)THEN
            SHMXTB=PSTRS1-PSTRS2
        ELSE
            SHMXTB=PSTRS2-PSTRS3
        ENDIF
        PHIA=SHMXTA-SIGMAY
        PHIB=SHMXTB-SIGMAY
C Start Newton-Raphson iterations
DO 40 NRITER=1,MXITER
C Compute residual derivative
        HSLOPE=DPLEFUN(EPBAR,NHARD,RPROPS(IPHARD))
        DRVAA=-R4G-HSLOPE
        DRVAB=-R2G-HSLOPE
        DRVBA=-R2G-HSLOPE
        DRVBB=-R4G-HSLOPE
C Compute Newton-Raphson increment and update variables DGAMA and DGAMB
        R1DDET=R1/(DRVAA*DRVBB-DRVAB*DRVBA)
        DDGAMA=(-DRVBB*PHIA+DRVAB*PHIB)*R1DDET
        DDGAMB=(DRVBA*PHIA-DRVAA*PHIB)*R1DDET
        DGAMA=DGAMA+DDGAMA
        DGAMB=DGAMB+DDGAMB
C Compute new residual
        DGABAR=DGAMA+DGAMB
        EPBAR=EPBARN+DGABAR
        SIGMAY=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
        PHIA=SHMXTA-R2G*(R2*DGAMA+DGAMB)-SIGMAY
        PHIB=SHMXTB-R2G*(DGAMA+R2*DGAMB)-SIGMAY
C Check convergence
        RESNOR=(ABS(PHIA)+ABS(PHIB))/SIGMAY
        IF(RESNOR.LE.TOL)THEN
C Update EPBAR and principal deviatoric stresses
            RSTAVA(MSTRE+1)=EPBAR
            IF(RIGHT)THEN
                PSTRS1=PSTRS1-R2G*(DGAMA+DGAMB)
                PSTRS3=PSTRS3+R2G*DGAMA
                PSTRS2=PSTRS2+R2G*DGAMB
            ELSE
                PSTRS1=PSTRS1-R2G*DGAMA
                PSTRS3=PSTRS3+R2G*(DGAMA+DGAMB)
                PSTRS2=PSTRS2-R2G*DGAMB
            ENDIF
            GOTO 50
        ENDIF
40 CONTINUE
C failure of stress update procedure
SUFAIL=.TRUE.
CALL ERRPR('WE0001')
GOTO 999
50 CONTINUE
C update stress components
C -----
        PSTRS(11)=PSTRS1
        PSTRS(JJ)=PSTRS3
        PSTRS(MM)=PSTRS2
        STRES(1)=PSTRS(1)*EIGPRJ(1,1)+PSTRS(2)*EIGPRJ(1,2)+P
        STRES(2)=PSTRS(1)*EIGPRJ(2,1)+PSTRS(2)*EIGPRJ(2,2)+P
        STRES(3)=PSTRS(1)*EIGPRJ(3,1)+PSTRS(2)*EIGPRJ(3,2)
        STRES(4)=PSTRS(3)+P
C and elastic engineering strain
        RSTAVA(1)=(STRES(1)-P)/R2G+EEVD3
        RSTAVA(2)=(STRES(2)-P)/R2G+EEVD3
        RSTAVA(3)=STRES(3)/GMODU
        RSTAVA(4)=PSTRS(3)/R2G+EEVD3
    ELSE
C Elastic step: update stress using linear elastic law
C =====
        STRES(1)=STREST(1)+P
        STRES(2)=STREST(2)+P
        STRES(3)=STREST(3)
        STRES(4)=PSTRS(3)+P
C elastic engineering strain
        RSTAVA(1)=STRAT(1)
        RSTAVA(2)=STRAT(2)
        RSTAVA(3)=STRAT(3)
        RSTAVA(4)=STRAT(4)
    ENDIF
999 CONTINUE
C Update algorithmic variables before exit
C =====
        DGAM(1)=DGAMA
        DGAM(2)=DGAMB

```

```
LALGVA(1)=IFPLAS  
LALGVA(2)=SUFALL  
LALGVA(3)=TWOVEC  
LALGVA(4)=RIGHT  
RETURN  
END
```

```

      SUBROUTINE SUTRPN
1(   DGAM      ,IPROPS      ,LALGVA      ,NTYPE      ,RPROPS      ,
2   RSTAVA      ,STRAT      ,STRES      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER(IPHARD=4 ,MSTRE=4)
C Arguments
      LOGICAL
1   LALGVA(4)
      DIMENSION
1   DGAM(2)      ,IPROPS(*)      ,RPROPS(*)      ,
2   RSTAVA(MSTRE+1) ,STRAT(*)      ,STRES(*)
C Local arrays and variables
      LOGICAL EPFLAG, IFPLAS, SUFAIL
      DIMENSION
1   DMATX(MSTRE,MSTRE) ,RSTAX(MSTRE+1)
      DATA
1   R0      ,TOL      /
2   0.D0    ,1.D-08/
      DATA MXITER / 20 /
C*****
C STRESS UPDATE PROCEDURE FOR TRESCA TYPE ELASTO-PLASTIC MATERIAL WITH
C PIECE-WISE LINEAR ISOTROPIC HARDENING IN PLANE STRESS. NESTED
C ITERATION APPROACH.
C
C REFERENCE: Section 9.2.2
C*****
C Stop program if not plane stress
      IF(NTYPE.NE.1)CALL ERRPR('EI0060')
C Initialise state update failure flag
      SUFAIL=.FALSE.
C Set some material properties
      NHARD=IPROPS(3)
C
C Newton-Raphson iteration loop for plane stress enforcement
C
C Set initial guess for elastic trial thickness strain. Use previously
C converged elastic trial thickness strain.
      E33TRL=RSTAVA(4)
C Set axisymmetric state flag
      NTYPAX=3
C Start N-R loop
      DO 20 ITER=1,MXITER
C Set state variables to values at beginning of increment
      DO 10 I=1,MSTRE+1
          RSTAX(I)=RSTAVA(I)
10      CONTINUE
C Use axisymmetric integration algorithm to compute stresses
      STRAT(4)=E33TRL
      CALL SUTR
1(   DGAM      ,IPROPS      ,LALGVA      ,NTYPAX      ,RPROPS      ,
2   RSTAX      ,STRAT      ,STRES      )
      SUFAIL=LALGVA(2)
C ...emergency exit in case of failure of state update procedure
      IF(SUFAIL)THEN
          GOTO 999
      ENDIF
      IFPLAS=LALGVA(1)
C Check plane stress convergence
      EPBAR=RSTAX(MSTRE+1)
      SIGMAY=PLEFUN(EPBAR,NHARD,RPROPS(IPHARD))
      RES=ABS(STRES(4))
C ...use normalised out-of-plane stress
      IF(SIGMAY.NE.R0)RES=RES/SIGMAY
      IF(RES.LE.TOL)THEN
C ...and break N-R loop in case of convergence
          GOTO 30
      ENDIF
C Compute axisymmetric consistent tangent components
      EPFLAG=IFPLAS
      CALL CTTR
1(   DMATX      ,EPFLAG      ,IPROPS      ,LALGVA      ,NTYPAX      ,
2   RPROPS      ,RSTAX      ,STRAT      ,STRES      )
C Apply Newton-Raphson correction to normal elastic trial strain
      D22=DMATX(4,4)
      E33TRL=E33TRL-STRES(4)/D22
20 CONTINUE
C Emergency exit in case of failure of plane stress enforcement loop
      SUFAIL=.TRUE.
      CALL ERRPR('WE0026')
      GOTO 999
30 CONTINUE
C Set state variables to current updated values
      DO 40 I=1,MSTRE+1
          RSTAVA(I)=RSTAX(I)
40 CONTINUE
      RSTAVA(4)=E33TRL
C
999 CONTINUE
      RETURN
      END

```

```

SUBROUTINE SUVM
1( DGAMA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=4 ,MSTRE=4)
LOGICAL IFPLAS, LALGVA(2), SUFAIL
DIMENSION
1 IPROPS(*) ,RPROPS(*) ,RSTAVA(MSTRE+1) ,
2 STRAT(MSTRE) ,STRES(MSTRE)
DIMENSION
1 EET(MSTRE)
DATA
1 R0 ,RP5 ,R1 ,R2 ,R3 ,TOL /
2 0.0D0,0.5D0,1.0D0,2.0D0,3.0D0,1.D-06/
DATA MXITER / 50 /
C*****
C STATE UPDATE PROCEDURE FOR THE VON MISES ELASTO-PLASTIC MATERIAL MODEL
C WITH NON-LINEAR (PIECEWISE LINEAR) ISOTROPIC HARDENING:
C IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM (BOXES 7.3-4).
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS.
C
C REFERENCE: Section 7.3.5
C*****
C Stop program if neither plane strain nor axisymmetric state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPRT('EI0013')
C Initialise some algorithmic and internal variables
DGAMA=R0
IFPLAS=.FALSE.
SUFAIL=.FALSE.
EPBARN=RSTAVA(MSTRE+1)
C Set some material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
NHARD=IPROPS(3)
C Shear and bulk moduli and other necessary constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R3G=R3*GMODU
C Elastic predictor: Compute elastic trial state
C -----
C Volumetric strain and pressure stress
EEV=STRAT(1)+STRAT(2)+STRAT(4)
P=BULK*EEV
C Elastic trial deviatoric strain
EEVD3=EEV/R3
EET(1)=STRAT(1)-EEVD3
EET(2)=STRAT(2)-EEVD3
EET(4)=STRAT(4)-EEVD3
C Convert engineering shear component into physical component
EET(3)=STRAT(3)/R2
C Compute trial effective stress and uniaxial yield stress
VARJ2T=R2G*R2G*(EET(3)*EET(3)+RP5*(EET(1)*EET(1)+
1 EET(2)*EET(2)+EET(4)*EET(4)))
QTRIAL=SQRT(R3*VARJ2T)
SIGMAY=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
C Check for plastic admissibility
C -----
PHI=QTRIAL-SIGMAY
IF(PHI/SIGMAY.GT.TOL)THEN
C Plastic step: Apply return mapping - use Newton-Raphson algorithm
C to solve the return mapping equation (Box 7.4)
C -----
IFPLAS=.TRUE.
EPBAR=EPBARN
DO 10 NRITER=1,MXITER
C Compute residual derivative
DENOM=-R3G-DPLFUN(EPBAR,NHARD,RPROPS(IPHARD))
C Compute Newton-Raphson increment and update variable DGAMA
DDGAMA=-PHI/DENOM
DGAMA=DGAMA+DDGAMA
C Compute new residual
EPBAR=EPBAR+DDGAMA
SIGMAY=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
PHI=QTRIAL-R3G*DGAMA-SIGMAY
C Check convergence
RESNOR=ABS(PHI/SIGMAY)
IF(RESNOR.LE.TOL)THEN
C update accumulated plastic strain
RSTAVA(MSTRE+1)=EPBAR
C update stress components
FACTOR=R2G*(R1-R3G*DGAMA/QTRIAL)
STRES(1)=FACTOR*EET(1)+P
STRES(2)=FACTOR*EET(2)+P
STRES(3)=FACTOR*EET(3)
STRES(4)=FACTOR*EET(4)+P
C compute converged elastic (engineering) strain components
FACTOR=FACTOR/R2G
RSTAVA(1)=FACTOR*EET(1)+EEVD3
RSTAVA(2)=FACTOR*EET(2)+EEVD3
RSTAVA(3)=FACTOR*EET(3)*R2
RSTAVA(4)=FACTOR*EET(4)+EEVD3
GOTO 999
ENDIF
10 CONTINUE
C reset failure flag and print warning message if the algorithm fails
SUFAIL=.TRUE.
CALL ERRPRT('WE0004')
ELSE
C Elastic step: Update stress using linear elastic law
C -----
STRES(1)=R2G*EET(1)+P
STRES(2)=R2G*EET(2)+P
STRES(3)=R2G*EET(3)
STRES(4)=R2G*EET(4)+P
C elastic engineering strain
RSTAVA(1)=STRAT(1)
RSTAVA(2)=STRAT(2)
RSTAVA(3)=STRAT(3)
RSTAVA(4)=STRAT(4)
ENDIF
999 CONTINUE
C Update some algorithmic variables before exit

```

```
LALGVA(1)=IFPLAS  
LALGVA(2)=SUFAIL  
RETURN  
END
```



```

SUBROUTINE SUVMMX
1( DGAMA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER(IPHARD=4 ,MSTRE=4)
C Arguments
LOGICAL LALGVA(2)
DIMENSION
1 IPROPS(*) ,RPROPS(*) ,RSTAVA(2*MSTRE+1) ,
2 STRAT(MSTRE) ,STRES(MSTRE)
C Local arrays and variables
LOGICAL IFPLAS, SUFAIL
DIMENSION
1 BACSTN(MSTRE) ,BACSTR(MSTRE) ,EET(MSTRE) ,
2 ETATRL(MSTRE) ,FLOVEC(MSTRE) ,STRIAL(MSTRE)
DATA
1 R0 ,R1 ,R2 ,R3 ,TOL /
2 0.0D0,1.0D0,2.0D0,3.0D0,1.D-08/
DATA MXITER / 50 /
C*****
C STATE UPDATE PROCEDURE FOR THE VON MISES ELASTO-PLASTIC MATERIAL MODEL
C WITH NON-LINEAR (PIECEWISE LINEAR) MIXED ISOTROPIC/KINEMATIC
C HARDENING:
C IMPLICIT ELASTIC PREDICTOR/RETURN MAPPING ALGORITHM (Box 7.5).
C PLANE STRAIN AND AXISYMMETRIC IMPLEMENTATIONS ONLY.
C
C REFERENCE: Box 7.5
C*****
C Stop program if neither plane strain nor axisymmetric state
IF(NTYPE.NE.2.AND.NTYPE.NE.3)CALL ERRPR('EI0047')
C Retrieve some previous converged state variables
C... accumulated plastic strain (hardening internal variable)
EPBARN=RSTAVA(5)
C... backstress tensor components
BACSTN(1)=RSTAVA(6)
BACSTN(2)=RSTAVA(7)
BACSTN(3)=RSTAVA(8)
BACSTN(4)=RSTAVA(9)
C Initialise some algorithmic and internal variables
DGAMA=R0
IFPLAS=.FALSE.
SUFAIL=.FALSE.
C Retrieve some material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
NHARD=IPROPS(3)
C Set pointers to isotropic and kinematic hardening curves
IPIHAR=IPHARD
IPKHAR=IPHARD+2*NHARD
C Shear and bulk moduli and other necessary constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R3G=R3*GMODU
C Elastic predictor: Compute elastic trial state [item(i) Box 7.5]
C -----
C Volumetric strain and pressure stress
EEV=STRAT(1)+STRAT(2)+STRAT(4)
P=BULK*EEV
C Elastic trial deviatoric strain
EEVD3=EEV/R3
EET(1)=STRAT(1)-EEVD3
EET(2)=STRAT(2)-EEVD3
EET(4)=STRAT(4)-EEVD3
C Convert engineering shear component into physical component
EET(3)=STRAT(3)/R2
C Compute trial deviatoric stress and trial relative stress
DO 10 ISTORE=1,MSTRE
STRIAL(ISTORE)=R2G*EET(ISTORE)
ETATRL(ISTORE)=STRIAL(ISTORE)-BACSTN(ISTORE)
10 CONTINUE
C Compute trial effective relative stress
QBARTR=SQRT(R3/R2*(ETATRL(1)**2+ETATRL(2)**2+R2*ETATRL(3)**2+
1 ETATRL(4)**2))
C and radius of von Mises cylinder
SIGMAY=PLFUN(EPBARN,NHARD,RPROPS(IPIHAR))
C Check for plastic admissibility [item (ii) Box 7.5]
C -----
PHI=QBARTR-SIGMAY
IF(PHI/SIGMAY.GT.TOL)THEN
C Plastic step: Apply return mapping - use Newton-Raphson algorithm to
C solve the return mapping equation [item (iii) Box 7.5]
C -----
IFPLAS=.TRUE.
EPBAR=EPBARN
BETBAN=PLFUN(EPBARN,NHARD,RPROPS(IPKHAR))
DO 40 NRITER=1,MXITER
C Compute residual derivative
HISLOP=DPLFUN(EPBAR,NHARD,RPROPS(IPIHAR))
HKSLOP=DPLFUN(EPBAR,NHARD,RPROPS(IPKHAR))
DENOM=-R3G-HISLOP-HKSLOP
C Compute Newton-Raphson increment and update variable DGAMA
DDGAMA=-PHI/DENOM
DGAMA=DGAMA+DDGAMA
C Compute new residual
EPBAR=EPBAR+DDGAMA
SIGMAY=PLFUN(EPBAR,NHARD,RPROPS(IPIHAR))
BETBAR=PLFUN(EPBAR,NHARD,RPROPS(IPKHAR))
PHI=QBARTR-R3G*DGAMA-BETBAR+BETBAN-SIGMAY
C Check convergence
RESNOR=ABS(PHI/SIGMAY)
IF(RESNOR.LE.TOL)THEN
C update stress components
ETANOR=SQRT(ETATRL(1)**2+ETATRL(2)**2+R2*ETATRL(3)**2+
1 ETATRL(4)**2)
FACTOR=SQRT(R3/R2)/ETANOR
DO 20 ISTORE=1,MSTRE
FLOVEC(ISTORE)=FACTOR*ETATRL(ISTORE)
20 CONTINUE
FACTOR=R2G*DGAMA
STRES(1)=STRIAL(1)-FACTOR*FLOVEC(1)+P
STRES(2)=STRIAL(2)-FACTOR*FLOVEC(2)+P
STRES(3)=STRIAL(3)-FACTOR*FLOVEC(3)

```

```

        STRES(4)=STRAL(4)-FACTOR*FLOVEC(4)+P
C compute and store converged elastic (engineering) strain components
        RSTAVA(1)=EET(1)-DGAMA*FLOVEC(1)+EEVD3
        RSTAVA(2)=EET(2)-DGAMA*FLOVEC(2)+EEVD3
        RSTAVA(3)=R2*(EET(3)-DGAMA*FLOVEC(3))
        RSTAVA(4)=EET(4)-DGAMA*FLOVEC(4)+EEVD3
C store updated accumulated plastic strain
        RSTAVA(5)=EPBAR
C compute and store updated backstress tensor components
        FACTOR=R2/R3*(BETBAR-BETBAN)
        DO 30 ISTR=1,MSTRE
            BACSTR(ISTR)=BACSTN(ISTR)+FACTOR*FLOVEC(ISTR)
30      CONTINUE
        RSTAVA(6)=BACSTR(1)
        RSTAVA(7)=BACSTR(2)
        RSTAVA(8)=BACSTR(3)
        RSTAVA(9)=BACSTR(4)
        GOTO 999
    ENDIF
40  CONTINUE
C reset failure flag and print warning message if the algorithm fails
    SUFAIL=.TRUE.
    CALL ERRPR1('WE0017')
ELSE
C Elastic step: Update stress using linear elastic law
C -----
        STRES(1)=R2G*EET(1)+P
        STRES(2)=R2G*EET(2)+P
        STRES(3)=R2G*EET(3)
        STRES(4)=R2G*EET(4)+P
C elastic engineering strain
        RSTAVA(1)=STRAT(1)
        RSTAVA(2)=STRAT(2)
        RSTAVA(3)=STRAT(3)
        RSTAVA(4)=STRAT(4)
    ENDIF
999 CONTINUE
C Update some algorithmic variables before exit
    LALGVA(1)=IFPLAS
    LALGVA(2)=SUFAIL
    RETURN
END

```

```

SUBROUTINE SUVMPS
1( DGAMA ,IPROPS ,LALGVA ,NTYPE ,RPROPS ,
2 RSTAVA ,STRAT ,STRES )
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
PARAMETER( IPHARD=4 ,MSTRE=4 ,NSTRE=3 )
LOGICAL IFPLAS, LALGVA(2), SUFAIL
DIMENSION
1 IPROPS(*) ,RPROPS(*) ,RSTAVA(MSTRE+1) ,
2 STRAT(MSTRE) ,STRES(MSTRE)
DIMENSION
1 EET(MSTRE) ,STREST(NSTRE)
DATA
1 R0 ,RP5 ,R1 ,R2 ,R3 ,R4 ,R6 ,TOL /
2 0.0D0,0.5D0,1.0D0,2.0D0,3.0D0,4.0D0,6.0D0,1.D-08/
DATA MXITER / 50 /
C*****
C STATE UPDATE PROCEDURE FOR THE VON MISES ELASTO-PLASTIC MODEL WITH
C NON-LINEAR (PIECEWISE LINEAR) ISOTROPIC HARDENING IN PLANE STRESS:
C IMPLICIT PLANE STRESS-PROJECTED ELASTIC PREDICTOR/RETURN MAPPING
C ALGORITHM (BOXES 9.4-5).
C
C REFERENCE: Section 9.4.3
C Boxes 9.4-5
C*****
C Stop program if not plane stress
IF(NTYPE.NE.1)CALL ERRPRT('EI0031')
C Initialise some algorithmic and internal variables
DGAMA=R0
IFPLAS=.FALSE.
SUFAIL=.FALSE.
C...set previously (equilibrium) converged accumulated plastic strain
EPBARN=RSTAVA(MSTRE+1)
C Set some material properties
YOUNG=RPROPS(2)
POISS=RPROPS(3)
NHARD=IPROPS(3)
C Shear and bulk moduli and other necessary constants
GMODU=YOUNG/(R2*(R1+POISS))
BULK=YOUNG/(R3*(R1-R2*POISS))
R2G=R2*GMODU
R4G=R4*GMODU
R1D3=R1/R3
R1D6=R1/R6
R2D3=R2*R1D3
SQR2D3=SQRT(R2D3)
R4GD3=R4G*R1D3
C Elastic predictor: Compute elastic trial state
C -----
C Volumetric strain
FACTOR=R2G/(BULK+R4GD3)
EEV=(STRAT(1)+STRAT(2))*FACTOR
C Elastic trial deviatoric strain
EEVD3=EEV/R3
EET(1)=STRAT(1)-EEVD3
EET(2)=STRAT(2)-EEVD3
C Convert engineering shear component into physical component
EET(3)=STRAT(3)*RP5
C Elastic trial stress components
PT=BULK*EEV
STREST(1)=R2G*EET(1)+PT
STREST(2)=R2G*EET(2)+PT
STREST(3)=R2G*EET(3)
C Compute yield function value at trial state
A1=(STREST(1)+STREST(2))*(STREST(1)+STREST(2))
A2=(STREST(2)-STREST(1))*(STREST(2)-STREST(1))
A3=STREST(3)*STREST(3)
XI=R1D6*A1+RP5*A2+R2*A3
SIGMAY=PLFUN(EPBARN,NHARD,RPROPS(IPHARD))
C...yield function
PHI=RP5*XI-R1D3*SIGMAY*SIGMAY
C Check for plastic admissibility
C -----
IF(PHI/SIGMAY.GT.TOL)THEN
C Plastic step: Apply return mapping - use Newton-Raphson algorithm
C to solve the plane stress-projected return mapping
C equation for the plastic multiplier (Box 9.5)
C -----
IFPLAS=.TRUE.
EPBAR=EPBARN
SQRTXI=SQRT(XI)
B1=R1
B2=R1
FMODU=YOUNG/(R3*(R1-POISS))
DO 10 NRITER=1,MXITER
C Compute residual derivative
HSLOPE=DPLEUN(EPBAR,NHARD,RPROPS(IPHARD))
DXI=-A1*FMODU/(R3*B1*B1*B1)-R2G*(A2+R4*A3)/(B2*B2*B2)
HBAR=R2*SIGMAY*HSLOPE*SQR2D3*(SQRTXI+DGAMA*DXI/(R2*SQRTXI))
DPHI=RP5*DXI-R1D3*HBAR
C Compute Newton-Raphson increment and update equation variable DGAMA
DGAMA=DGAMA-PHI/DPHI
C Compute new residual (yield function value)
B1=R1+FMODU*DGAMA
B2=R1+R2G*DGAMA
XI=R1D6*A1/(B1*B1)+(RP5*A2+R2*A3)/(B2*B2)
SQRTXI=SQRT(XI)
EPBAR=EPBARN+DGAMA*SQR2D3*SQRTXI
SIGMAY=PLFUN(EPBAR,NHARD,RPROPS(IPHARD))
PHI=RP5*XI-R1D3*SIGMAY*SIGMAY
C Check for convergence
RESNOR=ABS(PHI/SIGMAY)
IF(RESNOR.LE.TOL)THEN
C update accumulated plastic strain
RSTAVA(MSTRE+1)=EPBAR
C update stress components: sigma := A sigma^trial
ASTAR1=R3*(R1-POISS)/(R3*(R1-POISS)+YOUNG*DGAMA)
ASTAR2=R1/(R1+R2G*DGAMA)
A11=RP5*(ASTAR1+ASTAR2)
A22=A11
A12=RP5*(ASTAR1-ASTAR2)
A21=A12
A33=ASTAR2
STRES(1)=A11*STREST(1)+A12*STREST(2)

```

```

        STRES(2)=A21*STREST(1)+A22*STREST(2)
        STRES(3)=A33*STREST(3)
C compute corresponding elastic (engineering) strain components
        FACTG=R1/R2G
        P=R1D3*(STRES(1)+STRES(2))
        EEV=P/BULK
        EEVD3=R1D3*EEV
        RSTAVA(1)=FACTG*(R2D3*STRES(1)-R1D3*STRES(2))+EEVD3
        RSTAVA(2)=FACTG*(R2D3*STRES(2)-R1D3*STRES(1))+EEVD3
        RSTAVA(3)=FACTG*STRES(3)*R2
        RSTAVA(4)=-POISS/(R1-POISS)*(RSTAVA(1)+RSTAVA(2))
        GOTO 999
    ENDIF
10    CONTINUE
C reset failure flag and print warning message if N-R algorithm fails
    SUFAIL=.TRUE.
    CALL ERRPRN('WE0013')
ELSE
C Elastic step: Update stress using linear elastic law
C -----
        STRES(1)=STREST(1)
        STRES(2)=STREST(2)
        STRES(3)=STREST(3)
C elastic engineering strain
        RSTAVA(1)=STRAT(1)
        RSTAVA(2)=STRAT(2)
        RSTAVA(3)=STRAT(3)
        RSTAVA(4)=-POISS/(R1-POISS)*(STRAT(1)+STRAT(2))
    ENDIF
999 CONTINUE
C Update some algorithmic variables before exit
    LALGVA(1)=IFPLAS
    LALGVA(2)=SUFAIL
    RETURN
END

```

```

      SUBROUTINE SWDAMA
      1(  MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
      2  RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      LOGICAL
      1  LALGVC      ,LALGVL
      DIMENSION
      1  LALGVC(*)      ,LALGVL(*)      ,RALGVC(*)      ,
      2  RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      3  STRESL(*)
C*****
C INITIALISE/SWITCH DATA FOR LEMAITRE'S DUCTILE DAMAGE ELASTO-PLASTIC
C MODEL WITH ISOTROPIC HARDENING
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C              converged solution (when the current iteration
C              satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C              variables values (when a new iteration is required by
C              the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C              variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=6
      ENDIF
      NRALGV=1
      NLALGV=2
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
        CALL RVZERO(RALGVC,NRALGV)
        DO 10 I=1,NLALGV
          LALGVC(I)=.FALSE.
        10 CONTINUE
C RSTAVA stores the infinitesimal elastic engineering strain tensor
C components (logarithmic strains inlarge strains), the hardening
C variable and damage variable. All initialised to zero.
        CALL RVZERO(RSTAVC,NRSTAV)
      ELSE
C Switching mode
C =====
        IF(MODE.EQ.1)THEN
          DO 20 I=1,NSTRE
            STRESL(I)=STRESC(I)
          20 CONTINUE
          DO 30 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
          30 CONTINUE
          DO 40 I=1,NLALGV
            LALGVL(I)=LALGVC(I)
          40 CONTINUE
C Zero plastic multiplier before starting a new increment
          CALL RVZERO(RALGVC,NRALGV)
        ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
          DO 50 I=1,NSTRE
            STRESC(I)=STRESL(I)
          50 CONTINUE
          DO 60 I=1,NRSTAV
            RSTAVC(I)=RSTAVL(I)
          60 CONTINUE
          DO 70 I=1,NLALGV
            LALGVC(I)=LALGVL(I)
          70 CONTINUE
          IF(MODE.EQ.3)THEN
C Zero plastic multiplier before starting a new increment
            CALL RVZERO(RALGVC,NRALGV)
          ENDIF
        ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWDMEL
      1(  MODE      ,NTYPE      ,RSTAVC      ,RSTAVL      ,STRESC      ,
      2  STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      DIMENSION
      1  RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      2  STRESL(*)
C*****
C INITIALISE/SWITCH DATA FOR THE DAMAGED ELASTIC MATERIAL MODEL WITH
C PARTIAL MICROCRACK/VOID CLOSURE EFFECTS
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C              converged solution (when the current iteration
C              satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C              variables values (when a new iteration is required by
C              the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C              variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
      ELSE
        CALL ERRPRT('EI0054')
      ENDIF
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
C RSTAVA stores the infinitesimal engineering strain tensor components
C (logarithmic strains in large strains)
        CALL RVZERO(RSTAVC,NSTRE)
      ELSE
C Switching mode
C =====
        IF(MODE.EQ.1)THEN
          DO 10 ISTR=1,NSTRE
            STRESL(ISTR)=STRESC(ISTR)
            RSTAVL(ISTR)=RSTAVC(ISTR)
10          CONTINUE
        ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
          DO 20 ISTR=1,NSTRE
            STRESC(ISTR)=STRESL(ISTR)
            RSTAVC(ISTR)=RSTAVL(ISTR)
20          CONTINUE
        ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWDP
1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
2   RSTAVC     ,RSTAVL     ,STRESC     ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      LOGICAL
1   LALGVC      ,LALGVL
      DIMENSION
1   LALGVC(*)    ,LALGVL(*)    ,RALGVC(*)
2   RSTAVC(*)    ,RSTAVL(*)    ,STRESC(*)
3   STRESL(*)
      DATA R0 /
1   0.0D0/
C*****
C INITIALISE/SWITCH DATA FOR THE DRUCKER-PRAGER MATERIAL MODEL
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.1)THEN
        NSTRE=4
        NRSTAV=5
        NRALGV=3
      ELSEIF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=5
        NRALGV=2
      ENDIF
      NLALGV=3
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
        CALL RVZERO(RALGVC,NRALGV)
        DO 10 I=1,NLALGV
          LALGVC(I)=.FALSE.
        10 CONTINUE
C RSTAVA stores the infinitesimal engineering elastic strain tensor
C (engineering logarithmic strains in large strains) and the effective
C plastic strain
        CALL RVZERO(RSTAVC,NRSTAV)
      ELSE
C Switching modes
C =====
        IF(MODE.EQ.1)THEN
          DO 20 I=1,NSTRE
            STRESL(I)=STRESC(I)
          20 CONTINUE
          DO 30 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
          30 CONTINUE
          DO 40 I=1,NLALGV
            LALGVL(I)=LALGVC(I)
          40 CONTINUE
C Zero plastic multipliers before starting a new increment
          RALGVC(1)=R0
          RALGVC(2)=R0
          IF(NTYPE.EQ.1)THEN
C Reset elastic trial thickness strain to the current (converged) value
C of the elastic thickness strain (used by the nested iteration plane
C stress algorithm only)
            RALGVC(3)=RSTAVC(4)
          ENDIF
          ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
            DO 50 I=1,NSTRE
              STRESC(I)=STRESL(I)
            50 CONTINUE
            DO 60 I=1,NRSTAV
              RSTAVC(I)=RSTAVL(I)
            60 CONTINUE
            DO 70 I=1,NLALGV
              LALGVC(I)=LALGVL(I)
            70 CONTINUE
            IF(MODE.EQ.3)THEN
C Zero plastic multipliers before starting a new increment
              RALGVC(1)=R0
              RALGVC(2)=R0
              IF(NTYPE.EQ.1)THEN
C Reset elastic trial thickness strain to the last converged value of
C the elastic thickness strain (used by the nested iteration plane
C stress algorithm only)
                RALGVC(3)=RSTAVL(4)
              ENDIF
            ENDIF
          ENDIF
        ENDIF
      ENDIF

```

RETURN
END


```

      SUBROUTINE SWEL
      1(   MODE      ,NTYPE      ,RSTAVC      ,RSTAVL      ,STRESC      ,
      2   STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      DIMENSION
      1   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      2   STRESL(*)
C*****
C INITIALISE/SWITCH DATA FOR THE ELASTIC MATERIAL MODEL
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)NSTRE=4
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
          CALL RVZERO(STRESC,NSTRE)
C RSTAVA stores the infinitesimal engineering strain tensor components
C in small strains and the logarithmic eng. strains in large strain
C analysis
          CALL RVZERO(RSTAVC,NSTRE)
      ELSE
C Switching mode
C =====
          IF(MODE.EQ.1)THEN
              DO 10 ISTR=1,NSTRE
                  STRESL(ISTR)=STRESC(ISTR)
                  RSTAVL(ISTR)=RSTAVC(ISTR)
          10  CONTINUE
          ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
              DO 20 ISTR=1,NSTRE
                  STRESC(ISTR)=STRESL(ISTR)
                  RSTAVC(ISTR)=RSTAVL(ISTR)
          20  CONTINUE
          ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWITCH( MODE )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE './MAXDIM.INC'
      INCLUDE './MATERIAL.INC'
      INCLUDE './ELEMENTS.INC'
      INCLUDE './GLDBASE.INC'
C
      DATA R0 /0.0D0 /
C*****
C SWITCHES STATE VARIABLES VALUES AND COORDINATES BETWEEN CURRENT
C AND LAST CONVERGED SOLUTION DURING GLOBAL EQUILIBRIUM ITERATIONS
C
C   MODE=1 -> Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C             -----
C
C   MODE=2 -> Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process). -----
C
C   MODE=3 -> Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C             -----
C
C NOTE THAT FOR GAUSS POINT THICKNESS THE INITIAL VALUE IS NEEDED.
C FOR THIS VARIABLE, APPROPRIATE ASSIGNMENTS ARE MADE WHICH DIFFER
C FROM THE CONVENTIONAL ONES
C
C REFERENCE: Section 5.4.6
C           Figure 5.4
C*****
      IF(MODE.EQ.1)THEN
        NTI=1
        NTO=2
        NTITHK=1
        NTOTHK=2
      ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
        NTI=2
        NTO=1
        NTITHK=0
        NTOTHK=1
      ENDIF
C
C Set stress, other state variables, thickness and algorithmic variables
C =====
      DO 20 IELEM=1,NELEM
        IGRUP =IGRPID(IELEM)
        IELIDN=IELTID(IGRUP)
        NGAUSP=IELPRP(4,IELIDN)
        DO 10 IGAUSP=1,NGAUSP
C
C Call material interface to switch Gauss point data (state and
C algorithmic variables)
          CALL MATISW
          1(  MODE      ,NLARGE      ,NTYPE      ,IPROPS(1,MATTID(IGRUP)) ,
            2  LALGVA(1,IGAUSP,IELEM,1)      ,LALGVA(1,IGAUSP,IELEM,2)      ,
            3  RALGVA(1,IGAUSP,IELEM,1)      ,RALGVA(1,IGAUSP,IELEM,2)      ,
            4  RPROPS(1,MATTID(IGRUP))      ,RSTAVA(1,IGAUSP,IELEM,1)      ,
            5  RSTAVA(1,IGAUSP,IELEM,2)      ,STRSG(1,IGAUSP,IELEM,1)      ,
            6  STRSG(1,IGAUSP,IELEM,2)      )
C
C thickness (for large strain analysis in plane stress only)
C
          IF(NLARGE.EQ.1.AND.NTYPE.EQ.1)THEN
            THKGP(IGAUSP,IELEM,NTOTHK)=THKGP(IGAUSP,IELEM,NTITHK)
          ENDIF
C
          10  CONTINUE
          20  CONTINUE
C
C Set nodal coordinates (for large strain analysis only)
C =====
C
          IF(NLARGE.EQ.1.AND.(MODE.EQ.1.OR.MODE.EQ.3))THEN
            DO 40 IPOIN=1,NPOIN
              DO 30 IDIME=1,NDIME
                COORD(IDIME,IPOIN,NTO)=COORD(IDIME,IPOIN,NTI)
              30  CONTINUE
            40  CONTINUE
          ENDIF
C
C Set converged ELOAD and displacements
C =====
C
          IF(MODE.EQ.1)THEN
            DO 50 ITOTV=1,NTOTV
              TDISPO(ITOTV)=TDISP(ITOTV)
              DINCRO(ITOTV)=DINCR(ITOTV)
              DINCR(ITOTV)=R0
              DITER(ITOTV)=R0
            50  CONTINUE

```

```

        DO 70 IELEM=1,NELEM
          IGRUP =IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NEVAB =IELPRP(5,IELIDN)
          DO 60 IEVAB=1,NEVAB
            ELOADO(IEVAB,IELEM)=ELOAD(IEVAB,IELEM)
60      CONTINUE
70    CONTINUE
      ENDIF
C
C Reset displacements, logical algorithmic variables and
C ELOAD to last converged values (for increment cutting mode only)
C =====
C
      IF(MODE.EQ.3)THEN
        DO 80 ITOTV=1,NTOTV
          TDISP(ITOTV)=TDISPO(ITOTV)
          DINCR(ITOTV)=R0
          DITER(ITOTV)=R0
80      CONTINUE
        DO 100 IELEM=1,NELEM
          IGRUP =IGRPID(IELEM)
          IELIDN=IELTID(IGRUP)
          NEVAB =IELPRP(5,IELIDN)
          DO 90 IEVAB=1,NEVAB
            ELOAD(IEVAB,IELEM)=ELOADO(IEVAB,IELEM)
90      CONTINUE
100    CONTINUE
      ENDIF
C
      RETURN
      END

```

```

      SUBROUTINE SWMC
      1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
      2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      LOGICAL
      1   LALGVC      ,LALGVL
      DIMENSION
      1   LALGVC(*)      ,LALGVL(*)      ,RALGVC(*)      ,
      2   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      3   STRESL(*)
C*****
C INITIALISE/SWITCH DATA FOR THE MOHR-COULOMB MATERIAL MODEL
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=5
        ENDIF
        NRALGV=2
        NLALGV=5
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
        CALL RVZERO(RALGVC,NRALGV)
        DO 10 I=1,NLALGV
          LALGVC(I)=.FALSE.
        10 CONTINUE
C RSTAVA stores the infinitesimal elastic engineering strain tensor
C (engineering logarithmic strains in large strains) and the effective
C plastic strain
        CALL RVZERO(RSTAVC,NRSTAV)
      ELSE
C Switching mode
C =====
        IF(MODE.EQ.1)THEN
          DO 20 I=1,NSTRE
            STRESL(I)=STRESC(I)
          20 CONTINUE
          DO 30 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
          30 CONTINUE
          DO 40 I=1,NLALGV
            LALGVL(I)=LALGVC(I)
          40 CONTINUE
C Zero plastic multipliers before starting a new increment
          CALL RVZERO(RALGVC,NRALGV)
          ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
            DO 50 I=1,NSTRE
              STRESC(I)=STRESL(I)
            50 CONTINUE
            DO 60 I=1,NRSTAV
              RSTAVC(I)=RSTAVL(I)
            60 CONTINUE
            DO 70 I=1,NLALGV
              LALGVC(I)=LALGVL(I)
            70 CONTINUE
          IF(MODE.EQ.3)THEN
C Zero plastic multipliers before starting a new increment
            CALL RVZERO(RALGVC,NRALGV)
          ENDIF
        ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWOGD
1(   MODE      ,NTYPE      ,RSTAVC      ,RSTAVL      ,STRESC      ,
2   STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      DIMENSION
1   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
2   STRESL(*)
C Local numerical constants
      DATA R0 ,R1 /
1   0.0D0,1.0D0/
C*****
C INITIALISE/SWITCH DATA FOR THE OGDEN MATERIAL MODEL
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=4
      ENDIF
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
C Zero stress component array
        CALL RVZERO(STRESC,NSTRE)
C RSTAVA stores the left Cauchy-Green strain tensor components.
C Initialised as identity
        IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
          RSTAVC(1)=R1
          RSTAVC(2)=R1
          RSTAVC(3)=R0
          RSTAVC(4)=R1
        ENDIF
C Switching modes
C =====
        ELSEIF(MODE.EQ.1)THEN
          DO 10 I=1,NSTRE
            STRESL(I)=STRESC(I)
10      CONTINUE
          DO 20 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
20      CONTINUE
        ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
          DO 30 I=1,NSTRE
            STRESC(I)=STRESL(I)
30      CONTINUE
          DO 40 I=1,NRSTAV
            RSTAVC(I)=RSTAVL(I)
40      CONTINUE
        ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWPDSC
1(   MODE      ,LALGVC      ,LALGVL      ,RALGVC      ,RSTAVC      ,
2   RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      LOGICAL
1   LALGVC      ,LALGVL
      DIMENSION
1   LALGVC(*)      ,LALGVL(*)      ,RALGVC(*)      ,
2   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
3   STRESL(*)
      DATA R0 ,R1 /
1   0.0D0,1.0D0/
C*****
C INITIALISE/SWITCH DATA FOR THE PLANAR DOUBLE-SLIP SINGLE CRYSTAL
C ELASTO-PLASTIC MATERIAL MODEL
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
C
      NSTRE=4
      NRSTAV=5
      NRALGV=4
      NLALGV=6
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
      CALL RVZERO(STRESC,NSTRE)
      CALL RVZERO(RALGVC,NRALGV)
      DO 10 I=1,NLALGV
        LALGVC(I)=.FALSE.
      10 CONTINUE
C RSTAVA stores the elastic deformation gradient tensor (in-plane
C component only)
      RSTAVC(1)=R1
      RSTAVC(2)=R0
      RSTAVC(3)=R0
      RSTAVC(4)=R1
C and the accumulated plastic slip
      RSTAVC(5)=R0
      ELSE
C Switching modes
C =====
      IF(MODE.EQ.1)THEN
        DO 20 I=1,NSTRE
          STRESL(I)=STRESC(I)
        20 CONTINUE
        DO 30 I=1,NRSTAV
          RSTAVL(I)=RSTAVC(I)
        30 CONTINUE
        DO 40 I=1,NLALGV
          LALGVL(I)=LALGVC(I)
        40 CONTINUE
C Zero plastic multipliers before starting a new increment
        CALL RVZERO(RALGVC,NRALGV)
      ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
        DO 50 I=1,NSTRE
          STRESC(I)=STRESL(I)
        50 CONTINUE
        DO 60 I=1,NRSTAV
          RSTAVC(I)=RSTAVL(I)
        60 CONTINUE
        DO 70 I=1,NLALGV
          LALGVC(I)=LALGVL(I)
        70 CONTINUE
      IF(MODE.EQ.3)THEN
C Zero plastic multipliers before starting a new increment
        CALL RVZERO(RALGVC,NRALGV)
      ENDIF
      ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWTR
      1(  MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
      2  RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      LOGICAL
      1  LALGVC      ,LALGVL
      DIMENSION
      1  LALGVC(*)      ,LALGVL(*)      ,RALGVC(*)      ,
      2  RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      3  STRESL(*)
C*****
C INITIALISE/SWITCH DATA FOR THE TRESCA MATERIAL MODEL
C
C  MODE=0:  Initialises the relevant data.
C
C  MODE=1:  Assigns current values of the state variables to
C            converged solution (when the current iteration
C            satisfies the convergence criterion).
C
C  MODE=2:  Assigns the last converged solution to current state
C            variables values (when a new iteration is required by
C            the iterative process).
C
C  MODE=3:  Assigns the last converged solution to current state
C            variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=5
        ENDIF
        NRALGV=2
        NLALGV=4
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
        CALL RVZERO(RALGVC,NRALGV)
        DO 10 I=1,NLALGV
          LALGVC(I)=.FALSE.
        10 CONTINUE
C RSTAVA stores the infinitesimal elastic engineering strain tensor
C (engineering logarithmic strains in large strains) and the
C effective plastic strain
        CALL RVZERO(RSTAVC,NRSTAV)
      ELSE
C Switching mode
C =====
        IF(MODE.EQ.1)THEN
          DO 20 I=1,NSTRE
            STRESL(I)=STRESC(I)
          20 CONTINUE
          DO 30 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
          30 CONTINUE
          DO 40 I=1,NLALGV
            LALGVL(I)=LALGVC(I)
          40 CONTINUE
C Zero plastic multipliers before starting a new increment
          CALL RVZERO(RALGVC,NRALGV)
          ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
            DO 50 I=1,NSTRE
              STRESC(I)=STRESL(I)
            50 CONTINUE
            DO 60 I=1,NRSTAV
              RSTAVC(I)=RSTAVL(I)
            60 CONTINUE
            DO 70 I=1,NLALGV
              LALGVC(I)=LALGVL(I)
            70 CONTINUE
            IF(MODE.EQ.3)THEN
C Zero plastic multipliers before starting a new increment
              CALL RVZERO(RALGVC,NRALGV)
            ENDIF
          ENDIF
        ENDIF
      RETURN
      END

```

```

      SUBROUTINE SWVM
      1(   MODE      ,NTYPE      ,LALGVC      ,LALGVL      ,RALGVC      ,
      2   RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Arguments
      LOGICAL
      1   LALGVC      ,LALGVL
      DIMENSION
      1   LALGVC(*)      ,LALGVL(*)      ,RALGVC(*)      ,
      2   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      3   STRESL(*)
C*****
C INITIALISE/SWITCH DATA FOR THE VON MISES MODEL WITH ISOTROPIC
C HARDENING
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
C
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=5
      ENDIF
      NRALGV=1
      NLALGV=2
C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
        CALL RVZERO(RALGVC,NRALGV)
        DO 10 I=1,NLALGV
          LALGVC(I)=.FALSE.
        10 CONTINUE
C RSTAVA stores the infinitesimal elastic engineering strain tensor
C (engineering logarithmic strains in large strains) and the effective
C plastic strain
        CALL RVZERO(RSTAVC,NRSTAV)
      ELSE
C Switching mode
C =====
        IF(MODE.EQ.1)THEN
          DO 20 I=1,NSTRE
            STRESL(I)=STRESC(I)
          20 CONTINUE
          DO 30 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
          30 CONTINUE
          DO 40 I=1,NLALGV
            LALGVL(I)=LALGVC(I)
          40 CONTINUE
C Zero plastic multipliers before starting a new increment
          CALL RVZERO(RALGVC,NRALGV)
        ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
          DO 50 I=1,NSTRE
            STRESC(I)=STRESL(I)
          50 CONTINUE
          DO 60 I=1,NRSTAV
            RSTAVC(I)=RSTAVL(I)
          60 CONTINUE
          DO 70 I=1,NLALGV
            LALGVC(I)=LALGVL(I)
          70 CONTINUE
          IF(MODE.EQ.3)THEN
C Zero plastic multipliers before starting a new increment
            CALL RVZERO(RALGVC,NRALGV)
          ENDIF
        ENDIF
      ENDIF
      RETURN
      END

```



```

      SUBROUTINE SWVMMX
      1(   MODE      ,NLARGE      ,NTYPE      ,LALGVC      ,LALGVL      ,
      2   RALGVC      ,RSTAVC      ,RSTAVL      ,STRESC      ,STRESL      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)

C Arguments
      LOGICAL
      1   LALGVC      ,LALGVL
      DIMENSION
      1   LALGVC(*)      ,LALGVL(*)      ,RALGVC(*)      ,
      2   RSTAVC(*)      ,RSTAVL(*)      ,STRESC(*)      ,
      3   STRESL(*)

C*****
C INITIALISE/SWITCH DATA FOR THE VON MISES MODEL WITH MIXED HARDENING
C
C   MODE=0:   Initialises the relevant data.
C
C   MODE=1:   Assigns current values of the state variables to
C             converged solution (when the current iteration
C             satisfies the convergence criterion).
C
C   MODE=2:   Assigns the last converged solution to current state
C             variables values (when a new iteration is required by
C             the iterative process).
C
C   MODE=3:   Assigns the last converged solution to current state
C             variables values (when increment cutting is required).
C*****
      IF(NLARGE.EQ.1)THEN
C Internal error: Model implemented only for small strain
      CALL ERRPR('EI0049')
      ENDIF
      IF(NTYPE.EQ.1.OR.NTYPE.EQ.2.OR.NTYPE.EQ.3)THEN
        NSTRE=4
        NRSTAV=9
      ENDIF
      NRALGV=1
      NLALGV=2

C
      IF(MODE.EQ.0)THEN
C Initialisation mode
C =====
        CALL RVZERO(STRESC,NSTRE)
        CALL RVZERO(RALGVC,NRALGV)
        DO 10 I=1,NLALGV
          LALGVC(I)=.FALSE.
        10 CONTINUE
C RSTAVA stores the infinitesimal elastic engineering strain tensor
C components, the effective plastic strain and the backstress tensor
C components
        CALL RVZERO(RSTAVC,NRSTAV)
      ELSE
C Switching mode
C =====
        IF(MODE.EQ.1)THEN
          DO 20 I=1,NSTRE
            STRESL(I)=STRESC(I)
          20 CONTINUE
          DO 30 I=1,NRSTAV
            RSTAVL(I)=RSTAVC(I)
          30 CONTINUE
          DO 40 I=1,NLALGV
            LALGVL(I)=LALGVC(I)
          40 CONTINUE
C Zero plastic multipliers before starting a new increment
          CALL RVZERO(RALGVC,NRALGV)
        ELSEIF(MODE.EQ.2.OR.MODE.EQ.3)THEN
          DO 50 I=1,NSTRE
            STRESC(I)=STRESL(I)
          50 CONTINUE
          DO 60 I=1,NRSTAV
            RSTAVC(I)=RSTAVL(I)
          60 CONTINUE
          DO 70 I=1,NLALGV
            LALGVC(I)=LALGVL(I)
          70 CONTINUE
          IF(MODE.EQ.3)THEN
C Zero plastic multipliers before starting a new increment
            CALL RVZERO(RALGVC,NRALGV)
          ENDIF
        ENDIF
      ENDIF
      RETURN
      END

```

```

      SUBROUTINE TANGEN
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C
      DATA R0/0.0D0/
C*****
C SETS UP PRESCRIBED DISPLACEMENTS FOR THE TANGENTIAL SOLUTION FOR
C THE ARC-LENGTH METHOD
C
C REFERENCE: Item (iii), Box 4.4
C*****
      DO 20 IVFIX=1,NVFIX
         NLOCA=(NOFIX(IVFIX)-1)*NDOFN
         DO 10 IDOFN=1,NDOFN
            NPOS=NLOCA+IDOFN
            FIXED(NPOS,1)=PRESC(IVFIX,IDOFN)
            FIXED(NPOS,2)=R0
10      CONTINUE
20 CONTINUE
      RETURN
      END

```

```

      SUBROUTINE TUEL
1(      DETF      ,RSTAVA      ,THICK      ,MODE      )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER( MSTRE=4 )
      DIMENSION
1      RSTAVA(MSTRE)
C*****
C THICKNESS UPDATE FOR THE HENCKY ELASTIC MODEL MODEL UNDER LARGE
C STRAINS AND PLANE STRESS
C
C REFERENCE: Section 13.3.2
C*****
C Compute determinant of total deformation gradient (including
C out-of-plane contribution).
C ...start by retrieving the diagonal components of the logarithmic
C strain tensor
      E11=RSTAVA(1)
      E22=RSTAVA(2)
      E33=RSTAVA(4)
C ...then compute determinant of total deformation gradient
      DETF=EXP(E11+E22+E33)
      IF(MODE.EQ.1)THEN
C Compute thickness stretch
      STRTC3=EXP(E33)
C Update thickness
      THICK=THICK*STRTC3
      ENDIF
C
      RETURN
      END

```

```

      SUBROUTINE TUVM
1(   DETF   ,RSTAVA   ,THICK   ,MODE   )
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
      PARAMETER( MSTRE=4 )
      DIMENSION
1      RSTAVA(MSTRE+1)
C*****
C THICKNESS UPDATE FOR THE VON MISES ELASTO-PLASTIC MODEL UNDER LARGE
C STRAINS AND PLANE STRESS
C
C REFERENCE: Expressions (14.113-115)
C*****
C Compute determinant of total deformation gradient (including
C out-of-plane contribution). Note that, for this model, the determinant
C of the total and elastic deformation gradient coincide due to plastic
C incompressibility.
C... start by retrieving the diagonal components of the elastic
C logarithmic strain tensor
      EE11=RSTAVA(1)
      EE22=RSTAVA(2)
      EE33=RSTAVA(4)
C... then compute determinant of total deformation gradient
      DETFT=EXP(EE11+EE22+EE33)
      IF(MODE.EQ.1)THEN
C Compute thickness stretch
      STRTC3=DETFT/DETF
C Update thickness
      THICK=THICK*STRTC3
      ENDIF
C return total deformation gradient determinant in DETF
      DETF=DETFT
C
      RETURN
      END

```

```

      SUBROUTINE UPCONF
C
      IMPLICIT DOUBLE PRECISION (A-H,O-Z)
C Hyplas database
      INCLUDE '../MAXDIM.INC'
      INCLUDE '../MATERIAL.INC'
      INCLUDE '../ELEMENTS.INC'
      INCLUDE '../GLBDBASE.INC'
C*****
C KINEMATIC/GEOMETRIC CONFIGUTATION UPDATE:
C GIVEN THE ITERATIVE DISPLACEMENTS, THIS ROUTINE UPDATES THE GLOBAL
C ARRAYS OF INCREMENTAL AND TOTAL DISPLACEMENTS.
C FOR GEOMETRICALLY NON-LINEAR ANALYSES (LARGE DEFORMATIONS) IT ALSO
C UPDATES THE CURRENT NODAL COORDINATES.
C
C REFERENCE: Figures 5.2-3
C*****
C
C Update incremental and total displacements
C =====
C
      DO 10 ITOTV=1,NTOTV
         DINCR(ITOTV)=DINCR(ITOTV)+DITER(ITOTV)
         TDISP(ITOTV)=TDISP(ITOTV)+DITER(ITOTV)
      10 CONTINUE
C
C Update current nodal coordinates for large deformation analyses
C =====
C
      IF(NLARGE.EQ.1)THEN
         DO 30 IPOIN=1,NPOIN
            NPOSN=(IPOIN-1)*NDOFN
            DO 20 IDOFN=1,NDIME
               NPOSN=NPOSN+1
               COORD(IDOFN,IPOIN,1)=COORD(IDOFN,IPOIN,2)+DINCR(NPOSN)
            20 CONTINUE
          30 CONTINUE
        ENDIF
C
      RETURN
      END

```