

FlexRay

BLF Logging Format

Specification

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Document Management

Revision list

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1.0	2008-06-03	Wbn	All	Initial version created
1.1	2008-09-16	Wbn	2.10	POC state for CC2
1.2	2009-12-04	Wbn	2.3.5	Bit 22 added, description for Bit 17 updated
1.3	2009-05-19	Wbn	1	Added Disclaimer
1.4	2009-09-08	Wbn	3.8, 3.3.4	Tx Conflict (Bit 12) for VN interfaces and member <mblflogmask> and <mreservedw> added for CANoe/CANalyzer 7.2</mreservedw></mblflogmask>
1.5	2011-05-09	Wbn	3.8	Corrected mDir parameter type
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Contents

1	Discla	aimer		4
2	Over	view		4
3	Form	at Desc	ription	5
	3.1	Terms	s and Acronyms	5
	3.2	Gene	ral	5
	3.3	Comn	non Data Types	5
	3.	3.1	Direction Flags	5
	3.	3.2	Channel Mask	5
	3.	3.3	CC-Types	5
	3.	3.4	Controller Specific Frame State Information	5
	3.	3.5	Frame Flags	6
	3.4	Obsol	ete Types	7
	3.5	VBLFL	.EXRAYV6StartCycleEvent	7
	3.6	VBLFL	EXRAYV6Message	8
	3.7	VBLFL	.EXRAYVFrReceiveMsg	8
	3.8	VBLFL	.EXRAYVFrReceiveMsgEx	9
	3.9	VBLFL	.EXRAYVFrStartCycle	10
	3.	9.1	Controller Specific Information	10
	3.	9.2	Descriptions of Parameters	10
	3.10	VBLFL	EXRAYVFrStatus	11
	3.	10.1	Controller Specific Information	11
	3.	10.2	Attributes	13
	3.11	VBLFL	.EXRAYVFrError	14
	3.	11.1	Controller Specific Information	14
	3.	11.2	Attributes	16



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2 Overview

The document specifies the format of FlexRay events in the CANoe/CANalyzer BLF logging. The described structures can be used to read and write BLF logging files using the binlog.dll, which can be found in the CANoe/CANalyzer User Data folder:

<UserDataFolder>\Programming\BLF_Logging



3 Format Description

3.1 Terms and Acronyms

Term	Definition	
сс	Communication controller	

3.2 General

Note: unused members or flags are not used yet and must be always set to 0 if logging object is written by another application.

3.3 Common Data Types

3.3.1 Direction Flags

0 = Rx

1 = Tx

2 = Tx Request

3 and 4 are for internal use only.

3.3.2 Channel Mask

0 = Reserved or invalid

1 = FlexRay Channel A

2 = FlexRay Channel B

3 = FlexRay Channels A and B

3.3.3 CC-Types

Communication controllers (CC-Types):

0 = Architecture independent

1 = Invalid CC type (for internal use only)

2 = Cyclone I

3 = BUSDOCTOR

4 = Cyclone II

5 = Vector VN interface

6 = VN-Sync-Pulse (only in Status Event, for debugging purposes only)

3.3.4 Controller Specific Frame State Information

Note: unused bits in frame status field are not used yet and must be always set to 0 if logging object is written by another application.

Bit	Cyclone I	BUSDOCTOR	Cyclone II	VN
0	TX Conflict (TXCON)	Decoding Error (CODERR)	Syntax Error (SERR)	Syntax Error (SERR)
1	Boundary Violation (BVIOL)	Violation Error (TSSVIOL)	Content Error (CERR)	Content Error (CERR)
2	Content Error (CERR)	Header CRC Error (HCRCERR)	Slot BoundaryViolation (BVIOL)	Slot BoundaryViolation (BVIOL)
3	Syntax Error (SERR)	Frame CRC Error (FCRCERR)	Empty Slot (SLEMPTY)	Empty Slot (SLEMPTY)



Bit	Cyclone I	BUSDOCTOR Cyclone II		VN
4	StartUP Frame indication (SUPF)	Frame End Sequence Message Lost (MLOST) Error (FESERR)		Message Lost (MLOST)
5	NULL Frame indication (NF)	Symbol (SYMB)	Valid Frame (VAL)	Valid Frame (VAL)
6	SYNC Frame indication (SF)	Valid Frame (VAL)		TX Conflict (TXCON)
7	Valid Communication Element (VCE)	Boundary Violation Error (MASB)		Framing Error (FrmERR)
8		NIT Violation Error (NITVIOL)		
9				Frame CRC Error (FrmCRC)
10		Slot Overbooked Re Error (SOVERR)		Reserved Bit Error
11		(INFE) level failure d		Tx Conflict (bus signal level failure during transmission)
12		up Error (ISFE) channel frame different paylo		Redundancy Error (dual channel frame with different payload or header flags detected)
13				Bus Error (Spikes detected)
14		Cycle Counter Error Unknown error (CCE)		Unknown error
15		Static Payload Length Error (PLSE)		

3.3.5 Frame Flags

Description of frame flags.

Bit	Description
0	1 = Null frame.
1	1 = Data segment contains valid data
2	1 = Sync bit
3	1 = Startup flag
4	1 = Payload preamble bit
5	1 = Reserved bit
6	1 = Error flag (error frame or invalid frame)
7	Reserved
8	Internally used in CANoe/CANalyzer
9	Internally used in CANoe/CANalyzer
10	Internally used in CANoe/CANalyzer
11	Internally used in CANoe/CANalyzer
12	Internally used in CANoe/CANalyzer



Bit	Description
13	Internally used in CANoe/CANalyzer
14	Internally used in CANoe/CANalyzer
15	1 = Async. monitoring has generated this event
16	1 = Event is a PDU
17	Valid for PDUs only. The bit is set if the PDU is valid (either if the PDU has no update bit, or the update bit for the PDU was set in the received frame).
18	Reserved
19	1 = Raw frame (only valid if PDUs are used in the configuration). A raw frame may contain PDUs in its payload
20	1 = Dynamic segment 0 = Static segment
21	This flag is only valid for frames and not for PDUs.
	1 = The PDUs in the payload of this frame are logged in separate logging entries.
	0 = The PDUs in the payload of this frame must be extracted out of this frame. The logging file does not contain separate PDU-entries.
22	Valid for PDUs only. The bit is set if the PDU has an update bit

The reserved bits and the bits which are for internally CANoe/CANalyzer usage must be ignored from other applications. Other applications must set these bits to 0 when writing logging files.

3.4 Obsolete Types

The types listed below are not provided by CANoe and CANalyzer applications any more.

- 1. VBLFLEXRAYData
- 2. VBLFLEXRAYSync
- 3. VBLFLEXRAYStatusEvent

3.5 VBLFLEXRAYV6StartCycleEvent

Description: Start of cycle event transmitted by the hardware interface on a FlexRay channel.

Note: this type is provided only for compatibility with previews logging file formats. Applications should use the VBLFLEXRAYVFrStartCycle (section 3.9) type instead.

Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type
mChannel	WORD	Application channel
mDir	ВҮТЕ	See 3.3.1
mLowTime	ВҮТЕ	Additional time field in simulation
mFPGATick	DWORD	Timestamp generated from xModule
mFPGATickOverflow	DWORD	Overflow counter of the timestamp
mClientIndex	DWORD	Client index of send node. Must be set to 0 if file is written from other applications
mClusterTime	DWORD	Relative cluster time, from 0 to cycle length
mDataBytes[2]	ВҮТЕ	Array of data bytes
mReserved	WORD	Reserved



3.6 VBLFLEXRAYV6Message

Description: FlexRay Message received or transmitted on a FlexRay channel.

Note: this type is provided only for compatibility with previews logging file formats. Applications should use the VBLFLEXRAYVFrReceiveMsgEx type (section 3.8) instead.

Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type
mChannel	WORD	Application channel
mDir	BYTE	See 3.3.1
mLowTime	ВҮТЕ	Additional time field in simulation
mFPGATick	DWORD	Timestamp generated from xModule
mFPGATickOverflow	DWORD	Overflow counter of the timestamp
mClientIndex	DWORD	Client index of send node
mClusterTime	DWORD	Relatvie clustertime, from 0 to cyclelength
mFrameId	WORD	slot identifier
mHeaderCRC	WORD	CRC of the frame header
mFrameState	WORD	V6 framestate: 0 Payload preample indicator bit 1 Sync. frame indicator 2 Reserved bit 3 Null frame indicator 4 Startup frame indicator 5-7 Frame state format mask (see below) Bit 5-7 meaning: 0 (0x00) Motorola V.6 1 (0x20) reserved 2 (0x40) BusDoctor 3 (0x60) reserved 4 (0x80) FlexCard Cyclone 5 (0xA0) reserved 6 (0xC0) reserved 7 (0xE0) reserved
mLength	ВҮТЕ	Payload length
mCycle	BYTE	Current cycle number
mHeaderBitMask	ВҮТЕ	Bit 0 = NMBit, Bit 1 = SyncBit, Bit 2 = Reserved
mReserved1	ВҮТЕ	Reserved
mReserved2	WORD	Reserved
mDataBytes[64]	BYTE	Payload

3.7 VBLFLEXRAYVFrReceiveMsg

Description: FlexRay message received or transmitted on FlexRay bus.

Note: this type is provided only for compatibility with previews logging file formats. Applications should use the VBLFLEXRAYVFrReceiveMsgEx type (section 3.8) instead.

Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type



Parameter	Туре	Description
mChannel	WORD	Application channel
mVersion	WORD	Object version, for internal use
mChannelMask	WORD	See 3.3.2
mDir	BYTE	See 3.3.1
mClientIndex	DWORD	Client index of send node. Must be set to 0 if file is written from other applications.
mClusterNo	DWORD	Number of cluster: channel number - 1
mFrameId	WORD	Slot identifier
mHeaderCRC1	WORD	Header CRC FlexRay channel 1 (A)
mHeaderCRC2	WORD	Header CRC FlexRay channel 2 (B)
mByteCount	WORD	Payload length in bytes
mDataCount	WORD	Number of bytes of the payload stored in mDataBytes. If the CC-frame buffer was too small to receive the complete payload, then mDataCount is smaller than mByteCount.
mCycle	ВУТЕ	Cycle number
mTag	DWORD	Type of communication controller, see 3.3.3
mData	DWORD	Controller specific frame state information, see 3.3.4
mFrameFlags	DWORD	See description of flags, see 3.3.5
mAppParameter	DWORD	Not used, reserved
mDataBytes[254]	BYTE	Payload

3.8 VBLFLEXRAYVFrReceiveMsgEx

Description: FlexRay message or PDU received or transmitted on FlexRay bus.

Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type
mChannel	WORD	Application channel
mVersion	WORD	Object version, for internal use
mChannelMask	WORD	See 3.3.2
mDir	WORD	See 3.3.1
mClientIndex	DWORD	Client index of send node. Must be set to 0 if file is written from other applications.
mClusterNo	DWORD	Number of cluster: channel number - 1
mFrameId	WORD	Slot identifier
mHeaderCRC1	WORD	Header CRC FlexRay channel 1 (A)
mHeaderCRC2	WORD	Header CRC FlexRay channel 2 (B)
mByteCount	WORD	Payload length in bytes
mDataCount	WORD	Number of bytes of the payload stored in mDataBytes. If the CC-frame buffer was too small to receive the complete payload, then mDataCount is smaller than mByteCount.
mCycle	ВУТЕ	Cycle number
mTag	DWORD	Type of communication controller, see 3.3.3



Parameter	Туре	Description
mData	DWORD	Controller specific frame state information, see 3.3.4
mFrameFlags	DWORD	See description of flags, see 3.3.5
mAppParameter	DWORD	Not used, reserved
mFrameCRC	DWORD	Frame CRC
mFrameLengthNS	DWORD	Length of frame in ns (only valid for frames received in asynchronous mode, bit 15 is set in the frame flags)
mFrameld1	WORD	For PDUs only: This is the slot ID of the frame which contains this PDU
mPDUOffset	WORD	For PDUs only: offset in bytes of PDU in an owner (raw) frame
mBlfLogMask	WORD	Only valid for frames. Every stands for one PDU. If set, the PDU must be extracted out of the frame. The bit order is the PDU order in the frame starting with the PDU with the smallest offset.
mReservedW	WORD	Reserved
mReserved[7]	DWORD	Reserved
mDataBytes[254]	BYTE	Payload

3.9 VBLFLEXRAYVFrStartCycle

 $Description: FlexRay\ StartCycle\ event\ transmitted\ by\ the\ FlexRay\ hardware.$

3.9.1 Controller Specific Information

Field	Cyclone I	Cyclone II	VN-Interface
mData[0]	Rate correction of CC, read from RCVR register	Sync correction of CC, read from RCV register	Sync correction of CC, read from RCV register
mData[1]	Offset correction of CC, read from OCVR register	Offset correction of CC, read from OCV register	Offset correction of CC, read from OCV register
mData[2]		Cycles with no correction, read from CCEV register	Cycles with no correction, read from CCEV register
mData[3]		Cycles with correction in passive mode, read from CCEV register	Cycles with correction in passive mode, read from CCEV register
mData[4]		Sync Frame status, read from SFS register	Sync Frame status, read from SFS register

3.9.2 Descriptions of Parameters

3.3.2 Descriptions of Farameters		
Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type
mChannel	WORD	Application channel
mVersion	WORD	Object version, for internal use
mChannelMask	WORD	See 3.3.2
mDir	BYTE	See 3.3.1
mCycle	ВҮТЕ	Cycle number



Parameter	Туре	Description
mClientIndex	DWORD	Client index of send node
mClusterNo	DWORD	Number of cluster: channel number - 1
mNmSize	WORD	Length of NM-Vector in bytes
mDataBytes[12]	BYTE	Array of databytes (NM vector max. length)
mTag	DWORD	Type of communication controller, see 3.3.3
mData[5]	DWORD	Driver flags for internal usage
mReserved	WORD	Reserved

3.10 VBLFLEXRAYVFrStatus

Description: The content of the FlexRay status event depends on the type of hardware interface. The event is generated in one of the following situations:

- A symbol is received
- The POC state or wakeup state of the CC has changed
- The status of the symbol window has changed

3.10.1 Controller Specific Information

CC-Type: Cylone I

Field	Description
mData[0]	Content of Protocol state register (PSR)
mData[1]	Content of Module config register (MCR0)

CC-Type: BUSDOCTOR

Field	Description
LOW-WORD of mData[0]	Symbol length
HI-WORD of mData[0]	Flags: 1 = possible CAS
mData[1]	Reserved

CC-Type: VN-Interface

Field	Description	
mData[0]	POC state	of E-Ray register CCSV. Only valid
	for Vector	interfaces
	if wakeup	state is 0
	POC State	in the operation control phase:
	Mask	Description
	0x00	DEFAULT_CONFIG
	0x01	READY
	0x02	NORMAL_ACTIVE
	0x03 NORMAL_PASSIVE	
	0x04	HALT
	0x05	MONITOR_MODE
	0x0F	CONFIG



Field	Description		
	POC State in the wake-up phase:		
	Mask	Description	
	0x10	WAKEUP_STANDBY	
	0x11	WAKEUP_LISTEN	
	0x12	WAKEUP_SEND	
	0x13	WAKEUP_DETECT	
	POC State	in the start-up phase:	
	Mask	Description	
	0x20	STARTUP_PREPARE	
	0x21	COLDSTART_LISTEN	
	0x22	COLDSTART_COLLISION_RESOLUTION	
	0x23	COLDSTART_CONSISTENCY_CHECK	
	0x24	COLDSTART_GAP	
	0x25	COLDSTART_JOIN	
	0x26	INTEGRATION_COLDSTART_CHECK	
	0x27	INTEGRATION_LISTEN	
	0x28	INTEGRATION_CONSISTENCY_CHECK	
	0x29	INITIALIZE_SCHEDULE	
	0x30	ABORT_STARTUP	
	0x31	STARTUP_SUCCESS	
	All other	values are reserved.	
LOW-WORD of		Bit field indicating the symbol window status of the controller and the event source.	
mData[1]	Value	Meaning	
	1	SESA (Syntax error in symbol window channel A)	
	2	SBSA (Slot boundary violation in symbol window channel A)	
	4	TCSA (Transmission conflict in symbol window channel A)	
	8	SESB (Syntax error in symbol window channel B)	
	16	SBSB (Slot boundary violation in symbol window channel B)	
	32	TCSB (Transmission conflict in symbol window channel B)	
	64	The event was generated from a controller-independent protocol interpreter (Spy).	
	128	Cold-start helper POC indicator, if set, event contains the POC state of the cold-start helper	
		oits are reserved. CANoe/CANalyzer may set some of these bits to 1. Other ons must set them to 0.	
HI-WORD of mData[1]	Symbol length in bit times. Only valid for symbol type 4 and if the value is not zero.		



3.10.2 Attributes

Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type
mChannel	WORD	Application channel
mVersion	WORD	Object version, for internal use
mChannelMask	WORD	See 3.3.2
mCycle	BYTE	Cycle number
mClientIndex	DWORD	Client index of send node. Must be set to 0 if file is written from other applications
mClusterNo	DWORD	Number of cluster: channel number – 1
mWus	DWORD	WakeUp state. Only valid
		for Vector interfaces and for Cyclone II,
		if symbol is void (mReserved[0] = 0)
		Value Meaning (see E-Ray specification for a detailed description)
		0 UNDEFINED
		1 RECEIVED_HEADER
		2 RECEIVED_WUP
		3 COLLISION_HEADER
		4 COLLISION_WUP
		5 COLLISION_UNKNOWN
		6 TRANSMITTED
		7 EXTERNAL_WAKEUP
		8 WUP_RECEIVED_WITHOUT_WUS_TX
mCcSyncState	DWORD	Sync-State, only valid
		for Cyclone 1
		for Cyclone II if the wakup state value is 0.
		0 = Not synced passive
		1 = Synced active
_	DIMODD	2 = Not synced
mTag	DWORD	Type of communication controller, see 3.3.3
mData[2]	DWORD	Driver flags for internal usage
mReserved[0]	WORD	If this value is not zero, then the event contains the information about a symbol.
		0 = Void
		1 = CAS
		2 = MTS
		3 = WUS
		4 = Network interface doesn't provide a symbol interpretation, e.g. if spy-mode is used or the BUSDOCTOR interface. In spy mode, the symbol length is stored in the HI-WORD of mData[1].
mReserved[15]	WORD	Reserved



3.11 VBLFLEXRAYVFrError

 $Description: FlexRay\ Error\ event\ transmitted\ by\ the\ FlexRay\ hardware.$

3.11.1 Controller Specific Information

CC-Type: Cylone I

Field	Description
mData[0]	Error flags from driver API

CC-Type: Cylone II

Field	Description		
mData[0]	Error packet flag:		
	0 = No error		
	1 = FlexCard overflow		
	2 = PCO error mode changed		
	3 = Sync frames b	elow minimum	
	4 = Sync frame ov	erflow	
	5 = Clock correction	on failure	
	6 = Parity error		
	7 = Receive FIFO o	overrun	
	8 = Empty FIFO ac	cess	
	9 = Illegal input bu	uffer access	
	10 = Illegal output	buffer access	
	11 = Syntax error		
	12 = Content erro		
	13 = Slot boundar		
	14 = Transmission		
	15 = Latest transm	nit violation	
mData[1]	DWORD layout de	pends on the error packet value (see previous row)	
	Error packet	Description	
	2	0 = Unknown state	
		1 = FlexRay protocol spec. > CONFIG	
		2 = FlexRay protocol spec. > NORMAL_ACTIVE	
		3 = FlexRay protocol spec. > NORMAL_PASSIVE	
		4 = FlexRay protocol spec. > HALT	
		5 = FlexRay protocol spec. > READY	
		6 = FlexRay protocol spec. > STARTUP	
		7 = FlexRay protocol spec. > WAKEUP	
	3 or 4	Bits 03 > Sync frames even on channel A	
		Bits 47 > Sync frames even on channel B	
		Bits 811 > Sync frames odd on channel A	
		Bits 1215 > Sync frames odd on channel B	
	5	Bit 0 > Missing rate correction	
		Bit 1 > Rate correction limit reached	
		Bit 2 > Offset correction limit reached	
		Bit 3 > Missing offset correction	
		Bit 47 > Sync frames even on channel A	
		Bits 811 > Sync frames even on channel B	



Field	Description		
		Bits 1215 > Sync frames odd on channel A	
		Bits 1619 > Sync frames odd on channel B	
	11 15	LOW-WORD of mData[1] > Channel	
		HI-WORD of mData[1] > Slot count	

CC-Type: BUSDOCTOR

Field	Description	
mData[0]	Error flags from driver API	

CC-Type: VN-Interface

Field	Description				
mData[0]	Error tag: 0 = FR_ERROR_POC_MODE 1 = FR_ERROR_SYNC_FRAMES_BELOWMIN 2 = FR_ERROR_SYNC_FRAMES_OVERLOAD 3 = FR_ERROR_CLOCK_CORR_FAILURE 4 = FR_ERROR_NIT_FAILURE 5 = FR_ERROR_CC_ERROR 6 = FR_ERROR_OVERFLOW				
mData[1]	DWORD layout depends on the error tag value (see previous row):				
and mData[2]	Error tag	Value or Bit- Range	Description		
	0	0	FR_ERROR_POC_ACTIVE		
		1	FR_ERROR_POC_PASSIVE		
		2	FR_ERROR_POC_COMM_HALT		
	1 or 2	Bits 03	Sync frames even on channel A		
		Bits 47	Sync frames even on channel B		
		Bits 811	Sync frames odd on channel A		
		Bits 1215	Sync frames odd on channel B		
	3	Bit 0	Missing rate correction		
		Bit 1	Missing rate correction limit reached		
		Bit 2	Offset correction limit reached		
		Bit 3	Missing offset correction		
		Bits 419	Clock correction failed counter		
		Bit 2023	Sync frames even on channel A		
		Bit 2427	Sync frames even on channel B		
		Bit 2831	Sync frames odd on channel A		
		Bit 3235	Sync frames odd on channel B		
	4	1	FR_ERROR_NIT_SENA		
		2	FR_ERROR_NIT_SBNA		
		4	FR_ERROR_NIT_SENB		
		8	FR_ERROR_NIT_SBNB		
	5	0x0000001	POC Error Mode Changed		



Field	Description		
		0x0000004	Sync Frames Below Minimum
		0x0000008	Sync Frame Overflow
		0x00000010	Clock Correction Failure
		0x00000040	Parity Error, data from MHDS (internal ERay error)
		0x00000200	Illegal Input Buffer Access (internal ERay error)
		0x00000400	Illegal Output Buffer Access (internal ERay error)
		0x00000800	Message Handler Constraints Flag data from MHDF (internal ERay error)
		0x00010000	Error Detection on channel A, data from ACS
		0x00020000	Latest Transmit Violation on channel A
		0x00040000	Transmit Across Boundary on Channel A
		0x01000000	Error Detection on channel B, data from ACS
		0x02000000	Latest Transmit Violation on channel B
		0x04000000	Transmit Across Boundary on Channel B

3.11.2 Attributes

Parameter	Туре	Description
mHeader	VBLObjectHeader	Common header type
mChannel	WORD	Application channel
mVersion	WORD	Object version, for internal use
mChannelMask	WORD	See 3.3.2
mCycle	BYTE	Cycle number
mClientIndex	DWORD	Client index of send node. Must be set to 0 if file is written from other applications
mClusterNo	DWORD	Number of cluster: channel number - 1
mTag	DWORD	Type of communication controller, see 3.3.3
mData[4]	DWORD	Driver flags for internal usage
mReserved	WORD	Reserved