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SF1673 (HT25)

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1. The Real Numbers

1.1. Reals

1.1.1. Prerequisites

Theorem 1.1.1 (Induction)

(ii) $n \in S \Longrightarrow n+1 \in S$ (inductive step), then $S = \mathbb{N}$.

Let $S \subseteq \mathbb{N}$. If (i) $1 \in S$, and

Definition 1.1.2 (Injective/Surjective/Bijective)

equivalently if $f(x_1) = f(x_2) \Longrightarrow x_1 = x_2$.

 $f: X \to Y$ is injective (or one-to-one) if $x_1 \neq x_2 \Longrightarrow f(x_1) \neq f(x_2)$ or

f is surjective if $\forall y \ \exists x : f(x) = y$. f is bijective if is both injective and surjective or equivalently if each y is

mapped to exactly one x. 1.1.2. Comparison

Definition 1.1.3 (Equality) $a = b \iff (\forall \varepsilon > 0 \Rightarrow |a - b| < \varepsilon)$ Theorem 1.1.4 (Triangle Inequalities)

Axiom 1.1.5 (Supremum Property or Axiom of Completeness) Every bounded, nonempty set of real numbers has a least upper bound.

 $s = \sup A \iff \forall \varepsilon > 0 \ \exists a \in A : s - \varepsilon < a.$

 $A_n = \{ \pm p/q : p, q \in \mathbb{N}_+, \gcd(p, q) = 1, p + q = n \}$

 $I_1 \supseteq I_2 \supseteq I_3 \supseteq \cdots$

 $\bigcap_{n=1}^{\infty}I_{n}\neq\emptyset$

1.2. CARDINALITY Definition 1.2.1 (Cardinality) A has the same *cardinality* as B if there exists a bijective $f: A \to B$.

Theorem 1.2.3 (Countability of \mathbb{Q} , \mathbb{R}) O is countable. *Proof.* Let $A_1 = \{0\}$ and let for all $n \geq 2$. Each A_n is finite and every rational numbers appears in

 \mathbb{R} is uncountable. *Proof.* Cantor's diagonalization method. \mathbb{I} is uncountable. *Proof.* $\mathbb{I} = \mathbb{R} \setminus \mathbb{Q}$ where \mathbb{Q} is countable.

Theorem 1.3.3 (Nested Interval Property) Let (I_n) be a nested sequence of nonempty closed and bounded intervals with . Then

1.3.2. Open and Closed Sets

Theorem 1.3.5 (Clopen Sets) \mathbb{R} and \emptyset are *clopen* (both opened and closed).

A set K in a topological space is *compact* if every open cover has a finite subcover.

(i) $|a+b| \le |a| + |b|$ (ii) $|a-b| \le |a-c| + |c-b|$ (iii) $|a-b| \ge ||a| - |b||$ The reverse triangle inequality (iii) is seldom used. 1.1.3. Bounds

(i) Note The same does not apply for the rationals. Definition 1.1.6 (Least Upper Bound) Assume $s \in \mathbb{R}$ is an upper bound for a set $A \subseteq \mathbb{R}$. Then,

Definition 1.2.2 (Countable/Uncountable) A is countably infinite if $\mathbb{N} \sim A$. A is *countable* if it is finite or countably infinite. Otherwise, A is uncountable.

exactly one set.

Theorem 1.2.4 (Density of \mathbb{Q} in \mathbb{R}) (ii) $\forall y \in \mathbb{R} \ \exists (r_n) \in \mathbb{Q} : (r_n) \to y$ 1.3. Topology 1.3.1. Points

(i) $\forall a < b \in \mathbb{R} \ \exists r \in \mathbb{Q} : a < r < b$

Definition 1.3.1 (Limit Point)

Definition 1.3.4 (Open/Closed Set)

x is a limit point of A if every $V_{\varepsilon}(x)$ intersects A at some point other than x. Theorem 1.3.2 (Sequential Limit Point) x is a limit point of A if $x = \lim a_n$ for some $(a_n) \subseteq A : a_n \neq x \ \forall n \in \mathbb{N}$.

. In particular, there exists $a \in \bigcap_{n=1}^{\infty} I_n$.

 $A \subseteq \mathbb{R}$ is open if $\forall a \in A \ \exists V_{\varepsilon}(a) \subseteq A$ or equivalently if its complement is closed. $A \subseteq \mathbb{R}$ is *closed* if it contains its limit points or equivalently if its complement is open.

Theorem 1.3.6 (Unions/Intersections) (i) Arbitrary unions of open sets are open; finite intersections of open

A set $K \subseteq \mathbb{R}^n$ is compact if and only if it is closed and bounded. (i) Note

sets are open. (ii) Arbitrary intersections of closed sets are closed; finite unions of closed sets are closed. 1.3.3. Compactness Definition 1.3.7 (Compact)

Theorem 1.3.8 (Heine–Borel)

Compactness is like a generalization of closed intervals.

 $\forall \varepsilon > 0 \ \exists N \in \mathbb{N} : n \ge N \Longrightarrow |a_n - a| < \varepsilon$ or equivalently if for any $V_{\varepsilon}(a)$ there exists a point in the sequence after which all terms are in $V_{\varepsilon}(a)$. In other words if every ε -neighborhood contains all but a finite number of the terms in (a_n) . We write this $\lim_{n\to\infty} a_n = \lim a_n = a$ or $a_n \to a$. Example. Template of a typical convergence proof: (i) Let $\varepsilon > 0$ be arbitrary. (ii) Propose an $N \in \mathbb{N}$ (found before writing the proof). (iii) Assume $n \geq N$. (iv) Show that $|a_n - a| < \varepsilon$. Theorem 2.1.3 (Uniqueness of Limits) The limit of a sequence, if it exists, is unique. 2.1.1. Bounded Definition 2.1.4 (Bounded) A sequence is bounded if $\exists M > 0 : |a_n| < M \ \forall n \in \mathbb{N}$. Theorem 2.1.5 (Convergent) Every convergent sequence is bounded. If a sequence is monotone and bounded it converges. Subsequences of a convergent sequence converge to the same limit. Theorem 2.1.6 (Bolzano-Weierstrass) Every bounded sequence contains a convergent subsequence. 2.1.2. Cauchy Definition 2.1.7 (Cauchy Sequence) A sequence (a_n) is a Cauchy sequence if $\forall \varepsilon > 0 \ \exists N \in \mathbb{N} : m,n \geq N \Longrightarrow |a_n - a_m| < \varepsilon.$ Theorem 2.1.8 (Cauchy Criterion) A sequence converges if and only if it is a Cauchy sequence.

If $\sum_{k=1}^{\infty} a_k$ converges, then $a_k \to 0$. However, the reverse implication is

 $L = \limsup_{n \to \infty} \left| \frac{a_{n+1}}{a_n} \right|.$

Let (a_n) be a decreasing sequence of nonnegative real numbers. Then

Let $\sum_{j=0}^{\infty} a_j$ and $\sum_{j=0}^{\infty} b_j$ be positive series with terms such that

for some $K \neq 0$. Then, $\sum_{j=0}^{\infty} a_j$ converges if and only if $\sum_{j=0}^{\infty} b_j$

 $\lim_{j \to \infty} \frac{a_j}{b_i} = K$

2. Limits

2.1. SEQUENCES

Definition 2.1.1 (Sequence)

Definition 2.1.2 (Convergence)

A sequence converges to a if

A sequence is a function whose domain is \mathbb{N} .

2.2. Series Definition 2.2.1 (Infinite Series) Let $(a_j)_{i=0}^{\infty}$ and let $(s_n)_{n=0}^{\infty}$. The sum of the infinite series is defined as $\sum_{j=0}^{\infty} a_j = \lim_{n \to \infty} s_n = \lim_{n \to \infty} \sum_{j=0}^n a_j.$ If $a_j \geq 0$ for every j we say that the series is positive. (!) Caution Beware of treating infinite series like elementary algebra, e.g., by rearranging terms. Theorem 2.2.2 (Cauchy Criterion for Series) The series $\sum_{k=0}^{\infty} a_k$ converges if and only if $\forall \varepsilon > 0 \; \exists N : n > m > N \Longrightarrow \left| a_m + a_{m+1} + \dots + a_{n-1} + a_n \right| < \varepsilon.$ Corollary 2.2.3 (Series Term Test)

Theorem 2.2.4

Theorem 2.2.5

The series $\sum_{j=1}^{\infty} 1/j$ is divergent.

Theorem 2.2.6 (Ratio Test)

The series $\sum_{j=1}^{\infty} 1/j^p$ converges if and only if p > 1.

Let (a_n) be a sequence of positive terms and define

(i) If L < 1, the series $\sum_{n=1}^{\infty} a_n$ converges.

(iii) If L=1, the test is inconclusive.

Theorem 2.2.9 (Comparison Test)

Let (a_k) and (b_k) satisfy $0 \le a_k \le b_k$. Then,

(i) $\sum_{k=1}^{\infty} (a_k)$ converges if $\sum_{k=1}^{\infty} (b_k)$ converges. (ii) $\sum_{k=1}^{\infty} (b_k)$ diverges if $\sum_{k=1}^{\infty} (a_k)$ diverges.

Theorem 2.2.10 (Alternating Series Test)

Definition 2.2.11 (Absolutely Convergent)

If a series is absolutely convergent then it is convergent.

A series $\sum_{j=0}^{\infty} a_j$ is absolutely convergent if $\sum_{j=0}^{\infty} |a_j|$ is convergent.

 $\sum_{i=0}^{\infty} x^j = \frac{1}{1-x}$

 $s_n = \sum_{j=0}^{n} x^j = \frac{1 - x^{n+1}}{1 - x}.$

(ii) if $\forall (x_n) \subseteq A : (x_n \neq c \text{ and } x_n \to c)$ it follows that $f(x_n) \to L$.

Given a limit point $c \in D_f$, we say that $\lim_{x\to c} f(x) = \infty$ if

In the $\varepsilon\delta$ -definition of limits, the additional restriction that 0 < |x-a| is

 $\forall M \; \exists \delta > 0 : 0 < |x - c| < \delta \Longrightarrow f(x) \ge M.$

(ii) $\forall \varepsilon > 0 \; \exists \delta > 0 : |x - c| < \delta \Longrightarrow |f(x) - f(c)| < \varepsilon$, where $x \in A$.

(v) $\lim_{x\to c} f(x) = f(c)$, also written $\lim_{h\to 0} f(c+h) - f(c) = 0$.

The Dirichlet function $f: \mathbb{R} \to \mathbb{R}$ such that f(x) = 1 if $x \in \mathbb{Q}$ and

 $\forall \varepsilon > 0 \ \exists \delta > 0 : x, y \in I, |x - y| < \delta \Longrightarrow |f(x) - f(y)| < \varepsilon.$

(iii) $\forall V_{\varepsilon}(f(c)) \ \exists V_{\delta}(c) : x \in V_{\delta}(c) \cap A \Longrightarrow f(x) \in V_{\varepsilon}(f(c))$

Note that (ii) defines (i). Mostly (v) is used in practice.

(iv) $x_n \to c$, where $(x_n) \subseteq A$, implies $f(x_n) \to f(c)$.

(i) $a_1 \ge a_2 \ge \cdots \ge a_n \ge a_{n+1} \ge \cdots$ and

Theorem 2.2.13 (Geometric Series)

Theorem 2.3.1 (Function Limit)

Definition 2.3.2 (Infinite Limit)

Theorem 2.4.1 (Continuity)

(i) $f: A \subseteq \mathbb{R} \to \mathbb{R}$ is continuous at $c \in A$.

Corollary 2.4.2 (Isolated Continuity)

All functions are continuous at isolated points.

Theorem 2.4.3 (Dirichlet Discontinuous)

f(x) = 0 if $x \in \mathbb{I}$ is discontinuous everywhere.

Definition 2.4.4 (Uniform Continuity)

In particular, δ can be chosen independent of y.

If a function is uniformly continuous, it is also continuous.

If f is continuous and defined on a compact set K, then it is also

Proof. Assume the opposite, that f is continuous but not uniformly.

 $\exists \varepsilon_0 > 0 : \forall \delta > 0 \ \exists x, y \in K : \ |x - y| < \delta \ \text{but} \ |f(x) - f(y)| \ge \varepsilon_0.$

 $|x_n - y_n| < \frac{1}{2}$ and $|f(x_n) - f(y_n)| \ge \varepsilon_0$.

Theorem 2.1.6 asserts that there exists some subsequence $x_{n_k} \to x_0$ for

 $\left|x_{n_k}-y_{n_k}\right|\to 0,$

 $\left| f(x_{n_k}) - f(x_{n_k}) \right| \to 0.$

 $|f(x_{n_k}) \to f(y_{n_k})| \ge \varepsilon_0.$

Given $f: A \to B$ and $g: B \to \mathbb{R}$ with $f(A) \subseteq B$, if f is continuous at $c \in$

A and g is continuous at $f(c) \in B$, then $g \circ f$ is continuous at c.

Theorem 2.4.11 (Limit of Bounded Function)

If f is bounded then $\lim_{h\to 0} f(h)h = 0$.

some $x_0 \in K$. From $|x_n - y_n| < \frac{1}{n}$ it follows that $y_{n_k} \to x_0$. Thus,

and, because f is continuous with $f(x_{n_k}) \to x_0$ and $f(y_{n_k}) \to x_0$,

We say f is uniformly continuous on I if

Theorem 2.4.6 (Heine-Cantor)

Since f is not uniformly continuous,

Now, choose (x_n) and (y_n) such that

However, this contradicts our assumption that

uniformly continuous on K.

Theorem 2.4.5

The following are equivalent:

If c is a limit point of A:

Given $f: A \to \mathbb{R}$ with the limit point c, (i) $\lim_{x\to c} f(x) = L$ is equivalent to

Then, $\sum_{n=1}^{\infty} (-1)^{n+1} a_n$ converges.

(ii) If L > 1 (including $L = \infty$), the series diverges.

Theorem 2.2.7 (Cauchy Condensation Test)

 $\sum_{n=1}^{\infty} a_n$ converges if and only if $\sum_{n=0}^{\infty} 2^n a_{2^n}$ converges.

Then:

Theorem 2.2.8

converges.

Let (a_n) satisfy

(ii) $(a_n) \to 0$.

Theorem 2.2.12

If |x| < 1, then

2.3. Functions

(i) Note

just a way to say $x \neq c$.

2.4. Continuity

2.4.1. Existence

since

Theorem 2.4.8 (Composition Limit) If f is continuous at y and $\lim_{x\to c} g(x) = y$, then 2.4.3. Results

2.4.2. Composition

Theorem 2.4.7 (Composition)

 $\lim_{x\to c} f(g(x)) = f\Bigl(\lim_{x\to c} g(x)\Bigr) = f(y).$ Theorem 2.4.9 (Intermediate Value) If f is continuous on [a, b], then for any y between f(a) and f(b), there exists some $c \in (a, b)$ such that f(c) = y. Theorem 2.4.10 (Weierstrass Extreme Value) If f is continuous on the compact set K, then f attains a maximum and a minimum value on K.

3. Calculus 3.1. The Derivative 3.1.1. Differentiation Definition 3.1.1 (Derivative at a Point) Let $f: A \to \mathbb{R}$ and c a limit point of A. If $f'(c) = \lim_{h \to 0} \frac{f(c+h) - f(c)}{h}$ exists (finite), we say f is differentiable at c. Theorem 3.1.2 (Chain Rule) Let $f: X \to Y$ and $g: Y \to \mathbb{R}$. If f is differentiable at $c \in X$ and g is differentiable at $f(c) \in Y$, then $g \circ f$ is differentiable at c with $(g \circ f)'(c) = g'(f(c))f'(c).$ Theorem 3.1.3 (Basic Derivatives) $\frac{\mathrm{d}}{\mathrm{d}x}(\arcsin x) = \frac{1}{\sqrt{1-x^2}} \qquad \frac{\mathrm{d}}{\mathrm{d}x}(\sin x) = \cos x$ $\frac{\mathrm{d}}{\mathrm{d}x}(\arccos x) = -\frac{1}{\sqrt{1-x^2}} \qquad \frac{\mathrm{d}}{\mathrm{d}x}(\cos x) = -\sin x$ $\frac{\mathrm{d}}{\mathrm{d}x}(\arctan x) = \frac{1}{1+x^2} \qquad \quad \frac{\mathrm{d}}{\mathrm{d}x}(\tan x) = \frac{1}{\cos^2 x}$ $\frac{\mathrm{d}}{\mathrm{d}x}(\ln|x|) = \frac{1}{x}$ $\frac{\mathrm{d}}{\mathrm{d}x}(\operatorname{arccot} x) = -\frac{1}{1+x^2}$ $\frac{\mathrm{d}}{\mathrm{d}x}(x^a) = ax^{a-1} \quad (a \neq 0) \qquad \big(f^{-1}\big)'(y) = \frac{1}{f'(x)} \quad (y = f(x), f'(x) \neq 0)$ Theorem 3.1.4 (L'Hôpital's Rule) Let f and g be differentiable on an open interval containing c (except possibly at c), with $g'(x) \neq 0$ near c. Suppose (i) $\lim_{x\to c} f(x) = \lim_{x\to c} g(x) = 0$ (or both $\pm \infty$), and (i) $\lim_{x\to c} \frac{f'(x)}{g'(x)} = L$ exists (or $\pm \infty$). Then $\lim_{x \to c} \frac{f(x)}{g(x)} = L.$ *Proof of the zero case.* Assume the limits are zero. Let the functions be differentiable on the open interval (c, x). Then, rewriting and applying Theorem 3.1.10 gives $\lim_{x \to c} \frac{f(x)}{g(x)} = \lim_{x \to c} \frac{f(x) - f(c)}{g(x) - g(c)} = \lim_{x \to c} \frac{f'(p)}{g'(p)} = \lim_{p \to c} \frac{f'(p)}{g'(p)}$ for some p between c and x. Proof of the infinity case. The proof is too complicated. This is only an implication, not an equivalence, so there may exist some other solution if this method fails. 3.1.2. Function Character Theorem 3.1.5 (Fermat's or Interior Extremum) Let $f:(a,b)\to\mathbb{R}$ be differentiable at the local extremum $c\in(a,b)$. Then f'(x) = 0. However, note that a zero-derivative point may also be a stationary point of inflection. Theorem 3.1.6 (Darboux's) If f is differentiable on [a, b] and if y lies strictly between f'(a) and f'(b), then $\exists c \in (a,b) : f'(c) = y$. In other words, if f is differentiable on an interval, then f' satisfies the Intermediate Value Property (IVP). *Proof.* Assume that f'(a) < y < f'(b). Let g(x) = f(x) - yx with g'(x) = f'(x) - y. Note that f'(c) = y if g'(c) = 0 for some $c \in (a, b)$. Theorem 2.4.10 states that g must have a minimum point $c \in [a, b]$. More precisely $c \in (a, b)$ since, from the assumption, g'(a) < 0 and g'(b) > 0. Furthermore, g'(c) = 0 according to Theorem 3.1.5. Theorem 3.1.7 (Newton's Method) Find roots to a differentiable function f(x). Given x_n with the coordinates $(x_n, f(x_n))$, the tangent line is given by $T(x) = f'(x_n)(x - x_n) + f(x_n)$ and intersects the x-axis at $T(x_{n+1})=0 \iff x_{n+1}=x_n-\frac{f(x_n)}{f'(x_n)}.$ The method fails if it iterates endlessly or $f'(x_n) = 0$. 3.1.3. The Mean Value Theorems Let f and g be continuous on [a, b] and differentiable on (a, b). Theorem 3.1.8 (Rolle's) $f(a) = f(b) \Longrightarrow \exists c \in (a, b) : f'(c) = 0$ *Proof.* f(x) is bounded and f'(x) = 0 at its interior extreme points. Theorem 3.1.9 (Mean Value) $\exists c \in (a,b) : f'(c) = \frac{f(b) - f(a)}{b - a}$ *Proof.* Let the signed distance d between the function value f and the secant y through a and b be $d(x)=f(x)-y(x)=f(x)-\frac{f(b)-f(a)}{b-a}(x-a)-f(a)$ and note that d(a) = d(b) = 0. Then apply Theorem 3.1.8. Theorem 3.1.10 (Generalized Mean Value) $\exists c \in (a,b) : [f(b) - f(a)]g'(c) = [g(b) - g(a)]f'(c)$ If g' is never zero on (a, b), then the above can be stated as $\frac{f'(c)}{a'(c)} = \frac{f(b) - f(a)}{g(b) - g(a)}.$ *Proof.* Let h = f(x)[g(b) - g(a)] - g(x)[f(b) - f(a)] and then apply Theorem 3.1.8. 3.2. Function Graphs Ω Tip (Sketching Graphs) — Information (i) symmetries (ii) split into cases (iii) domain \rightarrow vertical asymptotes (iv) factorize \rightarrow oblique asymptotes & roots (v) first and second derivative and their roots (vi) sign tables (vii) calculate interesting points: intersection with y-axis, defined nondifferentiable points, local extremums, endpoints, inflection points — Sketching (i) axes (ii) symmetries (iii) asymptotes (iv) interesting points (v) curves 3.2.1. Asymptotes Definition 3.2.1 (Asymptote) The line y = kx + m is an *oblique* asymptote of f if $\lim_{x \to \infty} (f(x) - (kx + m)) = 0.$ The line x = c is a *vertical* asymptote of f if $\lim_{x \to c+} f(x) = \pm \infty \quad \text{or}$ $\lim_{x \to c^{-}} f(x) = \pm \infty.$ The line y = b is a horizontal asymptote of f if $\lim_{x \to \infty} f(x) = b \quad \text{or} \quad \lim_{x \to -\infty} f(x) = b.$ Theorem 3.2.2 (Oblique Asymptote) If f(x) has an oblique asymptote y = kx + m, then $k = \lim_{x \to \infty} \frac{f(x)}{x}$ and $m = \lim_{x \to \infty} (f(x) - kx).$ 3.2.2. Convexity Theorem 3.2.3 (Convexity) Let f be twice differentiable on (a, b). Then, $f''(x) \ge 0$ if and only if f is convex on (a, b). Definition 3.2.4 (Concave) On [a, b], a function $f : [a, b] \to \mathbb{R}$ is *concave* if -f is convex. **3.2.3.** Points Definition 3.2.5 (Local Extremum) A local maximum of $f:D\subseteq\mathbb{R}\to\mathbb{R}$ is a point c for which there exists an open neighborhood $N(c) \subseteq D$ such that $f(c) \ge f(x) \quad \forall x \in N(c).$ Definition 3.2.6 (Stationary) The point c is a stationary point of f if f'(c) = 0. The stationary order is the smallest $n \geq 2$ such that $f'(c) = f''(c) = \dots = f^{(n-1)}(c) = 0$ but $f^{(n)}(c) \neq 0$. Definition 3.2.7 (Critical) The point c is a *critical point* if f(c) is stationary or undefined. Definition 3.2.8 (Inflection) A point c is an inflection point of f if f is continuous at c and if f is convex on one side of c and concave on the other side. Theorem 3.2.9 (First Nonzero Derivative) If f has stationary order n, then: • If n is $even \to f$ has a local extremum at c. Furthermore: $f^{(n)}(c) > 0 \to \text{local minimum}, f^{(n)}(c) < 0 \to \text{local}$ maximum. • If n is $odd \rightarrow c$ is a stationary inflection point. *Proof.* The Taylor series with remainder simplifies to $f(c+h) = f(c) + \frac{f^{(n)}(c)}{n!}h^n + O(h^{n+1}).$ Its change close to c is thus $f(c+h) - f(c) \approx \frac{f^{(n)}(c)}{n!} h^n,$ which changes sign if and only if n is odd. Similarly, $f'(c+h) - f'(c) \approx \frac{f^{(n-1)}(c)}{(n-1)!} h^{n-1}$ for the first derivative and $f''(c+h) - f''(c) \approx \frac{f^{(n-2)}(c)}{(n-2)!}h^{n-2}$ for the second derivative. Corollary 3.2.10 (Second Derivative Test) If f'' is continuous at c and f'(c) = 0, then: • $f''(c) > 0 \rightarrow \text{local minimum}$. • $f''(c) < 0 \rightarrow \text{local maximum}$. • f''(c) = 0 and $f^{(3)}(c) \neq 0 \rightarrow$ stationary inflection point. Note: f''(c) = 0 alone is insufficient for an inflection; the curvature must change sign. Examples. • $f(x) = x^3$: f'(0) = f''(0) = 0, $f^{(3)}(0) = 6 \neq 0$ (odd n = 3) \rightarrow stationary inflection at 0. • $f(x) = x^4$: $f'(0) = f''(0) = f^{(3)}(0) = 0$, $f^{(4)}(0) = 24 > 0$ (even n = 4) local minimum at 0, no inflection. • $f(x) = -x^4$: local maximum at 0, no inflection. 3.3. Taylor's Theorem Theorem 3.3.1 (Taylor's) Suppose f is continuously differentiable n times on [a, b] and n + 1 times on (a, b). Fix $c \in [a, b]$. Then, $f(x) = P_n(x) + R_n(x),$ where the $Taylor \ polynomial$ of degree n around c is $P_n(x) = \sum_{k=0}^{n} \frac{f^{(k)}(c)}{k!} (x - c)^k$ and the Lagrange remainder of degree n around c is $R_n(x) = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x-c)^{n+1}$ for some ξ strictly between c and x. Note that other remainder forms exist. *Proof.* Let h = x - c be the deviation from the point. Then, $f(x) = f(c+h) = \sum_{k=0}^n \frac{f^{(k)}(c)}{k!} h^k + \frac{f^{(n+1)}(\xi)}{(n+1)!} h^{n+1} = p_n(h) + r_n(h),$ where $p_n(h)$ and $r_n(h)$ correspond to $P_n(x)$ and $R_n(x)$. Define $F_{n,h}(t) = \sum_{k=0}^{n} \frac{f^{(k)}(t)}{k!} (c+h-t)^{k},$ with $F_{n,h}(c) = p_{n(h)}$ and $F_{n,h}(c+h) = f(c+h)$, and derivative $F'_{n,h}(\xi) = \frac{f^{(n+1)}(\xi)}{n!}(c+h-\xi)^n.$ Also let $g_{n,h}(t) = (c+h-t)^{n+1},$ with $g_{n,h}(c) = h^{n+1}$ and $g_{n,h}(c+h) = 0$ and $g'_{n,h}(\xi) = -(n+1)(c+h-\xi)^n$. Theorem 3.1.10 gives $\frac{F_{n,h}(c+h) - F_{n,h}(c)}{q_{n,h}(c+h) - q_{n,h}(c)} = \frac{F'_{n,h}(\xi)}{q'_{n,h}(\xi)}$ for some ξ between c and c + h. Substituting, $\frac{f(c+h)-p_n(h)}{0-h^{n+1}} = \frac{f^{(n+1)}(\xi)(c+h-\xi)^n/n!}{-(n+1)(c+h-\xi)^n}$ SO $f(c+h) - p_n(h) = \frac{f^{(n+1)}(\xi)}{(n+1)!} h^{n+1}.$ Hence $f(c+h) = p_n(h) + r_n(h)$ or in x-notation $f(x) = P_n(x) + R_n(x)$ with ξ strictly between c and x. Definition 3.3.2 (Radius of Convergence) Let $R_n(x)$ be the remainder to the Taylor polynomial around a point c. The radius of convergence R is the supremum of $r \geq 0$ such that $\forall x : |x - c| < r \Longrightarrow \lim_{n \to \infty} R_n(x) = 0,$ which implies that the Taylor series converges to f(x) for all such x (so $f(x) = P_{\infty}(x).$ Theorem 3.3.3 (Common Maclaurin Series) The following functions have a Maclaurin series with radius of convergence $r = \infty$: $e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots$ $\sin x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{\{2k+1\}}}{(2k+1)!} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$ $\cos x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{\{2k\}}}{(2k)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots$ $\arctan x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{\{2k+1\}}}{2k+1} = x - \frac{x^3}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \cdots \quad (|x| \le 1)$ $\ln(1+x) = \sum_{k=1}^{\infty} (-1)^{\{k+1\}} \frac{x^k}{k} = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \cdots \quad (|x| < 1)$ $(1+x)^a = \sum_{k=0}^{\infty} {a \choose k} x^k \quad (|x| < 1)$ 3.3.1. Function Order Definition 3.3.4 (Big O at Infinity) Let f and g be defined on (c, ∞) . We say that f belongs to the set O of g as $x \to \infty$, writing O(g(x)), if there exists M and x_0 such that $|f(x)| \le M|g(x)|,$ for every $x > x_0$. Definition 3.3.5 (Big O at a Point) Let f and g be defined on a neighborhood of c. We say that f belongs to the set O of g around c, writing O(g(x)), if there exists M and $\delta > 0$ such that $|f(x)| \le M|g(x)|$ for every $x \in (c - \delta, c + \delta)$. Theorem 3.3.6 (Big O Behavior) If h(x) = O(f(x)) and k(x) = O(g(x)) (same limiting regime), then h(x)k(x) = O(f(x)g(x)).If $m \le n$ then as $x \to 0$, $x^n = O(x^m)$ so $O(x^m) + O(x^n) = O(x^m)$. As $x \to \infty$, $x^m = O(x^n)$ so $O(x^m) + O(x^n) = O(x^n)$. Theorem 3.3.7 Let $f(x):[a,b]\to\mathbb{R}$ and fix $c\in[a,b]$. Suppose f is continuously differentiable n times on [a, b] and n + 1 times on (a, b). Then, $f(x) = \sum_{k=0}^{n} \frac{f^{(k)}(c)}{k!} (x - c)^k + O(|x - c|^{n+1}) \text{ as } x \to c.$ Furthermore, the coefficients $f^{(k)}(c)/k!$ are unique to each $(x-c)^k$. 3.4. THE RIEMANN INTEGRAL 3.4.1. Definition Definition 3.4.1 (Partition) A partition of [a, b] is a finite set $P = \{x_0, x_1, \dots, x_n\}$ such that $a = x_0 < x_1 < \dots < x_n = b,$ The partition P has subintervals $[x_{i-1}, x_i]$ i = 1, 2, ..., nof which the length of the largest is its mesh or norm $\|P\| = \max_{1 \le i \le n} (x_i - x_{i-1}).$ A smaller such is indicative of a finer partition. Let $f:[a,b]\to\mathbb{R}$ be bounded. We now define its definite integral. Definition 3.4.2 (Darboux Integral) Define the lower sum $L(f,P) = \sum_{i=1}^{n} (\inf\{f(x): x \in [x_{i-1},x_i]\})(x_i - x_{i-1}).$ and the upper sum $U(f,P) = \sum_{i=1}^{n} (\sup\{f(x): x \in [x_{i-1},x_i]\})(x_i - x_{i-1})$ The function f is Darboux integrable if $\sup_{P} L(f, P) = \inf_{P} U(f, P)$. The common value is denoted as the definite integral $\int_a^b f(x) dx$. Definition 3.4.3 (Alternative Darboux Integral) Let Φ and Ψ be the lower and upper step functions such that $\Phi(x) \le f(x) \le \Psi(x) \quad \forall x \in [a, b],$ forming the lower integral $L(f) = \sup \left\{ \int_a^b \Phi(x) \, \mathrm{d}x : \Phi \text{ is a lower step function to } f \right\}$ and the *upper integral* $U(f) = \inf \left\{ \int_{a}^{b} \Psi(x) dx : \Psi \text{ is an upper step function to } f \right\}$ which, if equal, give the definite integral. Note that the integral of a step function is simply its signed area. Definition 3.4.4 (Riemann Integral) From a partition P of [a, b] pick sample points $t_i \in [x_{i-1}, x_i], \quad i = 1, 2, ..., n$ and form the (tagged) Riemann sum $S(f, P, (t_i)) = \sum_{i=1}^{n} f(t_i)(x_i - x_{i-1}).$ We say f is Riemann integrable if there exists $L \in \mathbb{R}$ such that $\forall \varepsilon > 0 \ \exists \delta > 0 : \|P\| < \delta \Longrightarrow |S(f,P,(t_i)) - L| < \varepsilon$ for every choice of sample points (t_i) . In that case we write $L = \int_{a}^{b} f(x) \, \mathrm{d}x.$ Theorem 3.4.5 The Darboux and Riemann integrals are equivalent. Theorem 3.4.6 (Integrability) Let $f:[a,b]\to\mathbb{R}$ be bounded. The function is integrable if and only if: (i) $\forall \varepsilon > 0 \ \exists P : U(f, P) - L(f, P) < \varepsilon$. $\text{(ii)} \ \ \forall (P_n): \|P_n\| \to 0 \Longrightarrow U(f,P_n) - L(f,P_n) \to 0.$ $\forall \varepsilon > 0 \; \exists \Phi, \Psi : \int_{a}^{b} \Psi(x) \, \mathrm{d}x - \int_{a}^{b} \Phi(x) \, \mathrm{d}x < \varepsilon,$ where Φ and Ψ are lower and upper step functions. The function is integrable if: (iii) f is monotone on [a, b](iv) (Lebesgue criterion for Riemann integrability) f is Riemann integrable on [a, b] if and only if the set of its discontinuities has Lebesgue measure zero. In particular, it suffices that f is continuous except at finitely many points, or at countably many points where it has only removable or jump discontinuities. Theorem 3.4.7 Assume f is continuous on [a, b]. Let $M_i = \max_{x \in [x_{i-1}, x_i]} f(x) \ \ \text{and} \ \ m_i = \min_{x \in [x_{i-1}, x_i]} f(x).$ Then, $\lim_{\|P\| \to 0} \sum_{i=1}^n M_i(x_i - x_{i-1}) = \lim_{\|P\| \to 0} \sum_{i=1}^n m_i(x_i - x_{i-1}) = \int_a^b f(x) \, \mathrm{d}x \, .$ Theorem 3.4.8 (Fundamental Theorems of Calculus) If f is continuous on [a, b], then the two theorems follow: (i) Let $F(x) = \int_a^x f(t) dt$ for $x \in [a, b]$. Then, F is continuous on [a, b], differentiable on (a, b), and F'(x) = f(x). (ii) If F'(x) = f(x) for $x \in (a, b)$, then $\int_{a}^{b} f(x) \, \mathrm{d}x = F(b) - F(a).$ 3.4.2. Properties Theorem 3.4.9 (Linearity) If f, g are integrable and $\alpha, \beta \in \mathbb{R}$, then $\int_{a}^{b} (\alpha f(x) + \beta g(x)) dx = \alpha \int_{a}^{b} f(x) dx + \beta \int_{a}^{b} g(x) dx.$ Theorem 3.4.10 (Additivity of the Interval) If $c \in (a, b)$ and f integrable on [a, b], then $\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx.$ It follows that $\int_a^a f(x) dx = 0$ and $\int_b^a f(x) dx = -\int_a^b f(x) dx$. Theorem 3.4.11 (Order / Comparison) If f, g integrable and $f(x) \leq g(x)$ on [a, b], then $\int_a^b f(x) \, \mathrm{d}x \le \int_a^b g(x) \, \mathrm{d}x.$ Corollary 3.4.12 (Positivity) If $f(x) \ge 0$ on [a, b], then $\int_a^b f(x) dx \ge 0$. Moreover, if f is continuous and the integral is 0, then $f \equiv 0$. Theorem 3.4.13 (Bounding by a Supremum) If $|f(x)| \leq M$ on [a, b], then $\left| \int_{a}^{b} f(x) \, \mathrm{d}x \right| \le M(b-a).$ Theorem 3.4.14 (Absolute Value / Triangle) If f integrable, then |f| integrable and $\left| \int_{a}^{b} f(x) \, \mathrm{d}x \right| \leq \int_{a}^{b} |f(x)| \, \mathrm{d}x.$ Theorem 3.4.15 (Products and Composition) If f, g integrable, then fg is integrable. If f integrable and φ continuous on a set containing f([a,b]), then $\varphi \circ f$ is integrable. Theorem 3.4.16 (Uniform Limit) If (f_n) are integrable on [a,b] and $f_n \to f$ uniformly, then f is integrable and $\int_{a}^{b} f_n(x) dx \to \int_{a}^{b} f(x) dx.$ Theorem 3.4.17 (Mean Value for Integrals) If f is continuous on [a, b], $\exists \xi \in (a,b) : \int_{a}^{b} f(x) \, \mathrm{d}x = f(\xi)(b-a).$ Theorem 3.4.18 (Generalized Mean Value for Integrals) If f is continuous and g is integrable and does not change sign on [a, b], $\exists \xi \in (a,b) : \int_a^b f(x)g(x) \, \mathrm{d}x = f(\xi) \int_a^b g(x) \, \mathrm{d}x.$ *Proof.* Let $m = \min f(x)$ and $M = \max f(x)$ for $x \in [a, b]$. Then, $m \int_{a}^{b} g(x) \le \int_{a}^{b} f(x)g(x) \le M \int_{a}^{b} g(x)$ by Theorem 3.4.11, or rewritten, $m \leq \frac{1}{\int_a^b g(x)} \int_a^b f(x)g(x) \leq M.$ Since $m \le f(x) \le M$, Theorem 2.4.9 gives that $f(\xi) = \frac{1}{\int_a^b g(x)} \int_a^b f(x)g(x)$ for some $\xi \in [a, b]$. Rewritten, this is the theorem. 3.4.3. Techniques Theorem 3.4.19 (Change of Variables / Substitution) Let u = g(x) with g continuously differentiable and strictly monotone on [a,b]. If f is continuous on [g(a),g(b)], then $\int_a^b f(g(x))g'(x) dx = \int_{g(x)}^{g(b)} f(u) du.$ Theorem 3.4.20 (Integration by Parts) If f, g are continuously differentiable on [a, b], then $\int_{a}^{b} f(x)g(x) dx = [F(x)g(x)]_{a}^{b} - \int_{a}^{b} F(x)g'(x) dx.$ Ω LIATE Rule The LIATE rule helps choose f(x) and g(x) for integration by parts: • Logarithmic: ln(x), $log_{a(x)}$ • Inverse trigonometric: $\arctan(x)$, $\arcsin(x)$, $\arccos(x)$ • Algebraic: x, x^2, x^3 , etc. • Trigonometric: $\sin(x)$, $\cos(x)$, $\tan(x)$, etc. • Exponential: e^x , a^x Choose g(x) as the function that appears first in this list. 3.5. Ordinary Differential Equations