

Examples of manifolds:

Let  $f: M \rightarrow N$  be smooth. Then  $f$  is called an immersion if  $\forall p \in M \quad df_p: T_p M \rightarrow T_{f(p)} N$  is injective.  
 $f$  is called a submersion if  $\forall p \in M \quad df_p: T_p M \rightarrow T_{f(p)} N$  is surjective.  
 $f$  is called a local diffeomorphism if  $\forall p \in M \quad df_p: T_p M \rightarrow T_{f(p)} N$  is bijective.

Let  $q \in f(M) \subseteq N$  then  $q$  is a regular value if  $\forall q \in f^{-1}(\{q\}) \quad df_p: T_p M \rightarrow T_q N$  is surjective.

Let  $S \subseteq M$  then  $S$  is called a  $k$ -dimensional submanifold of  $M$  if  $\forall p \in S \exists (U, \varphi)$  a chart s.t.  $\varphi(U \cap S) = \varphi(U) \cap \mathbb{R}^k$

Implicit function theorem  $\Rightarrow$  If  $q$  is a regular for  $f: M \rightarrow N \Rightarrow f^{-1}(\{q\})$  is a submanifold of dimension  $\dim M - \dim N$ .

The above is called regular level set theorem.

Now lets go into examples:

i)  $\mathbb{R}^n$  any real/complex finite dimensional vector.

ii) let  $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$  given by  $f(x) = \|x\|^2$ . Let  $S^n = f^{-1}(\{1\}) = \{x \in \mathbb{R}^{n+1} \mid \|x\|^2 = 1\}$

$df_p: T_p \mathbb{R}^{n+1} \rightarrow T_p \mathbb{R}$  is surjective.  $df_p = [2p^1 \cdots 2p^{n+1}]$  since  $\|p\|^2 = 1 \Rightarrow p^i \neq 0$  for some  $i$

$$f(x) = \sum_{i=1}^{n+1} (x^i)^2 \Rightarrow \frac{\partial f}{\partial x^i} = \sum_{j=1}^{n+1} \delta_{ij} (2x^j) = 2x^i \Rightarrow \left. \frac{\partial f}{\partial x^i} \right|_p = 2p^i$$

Hence  $S^n$  is a manifold of dimension  $(n+1)-1 = n$ .

iii)  $GL(n, \mathbb{R}) = \{A: \mathbb{R}^n \rightarrow \mathbb{R}^n \mid A \text{ is invertible}\} \subseteq \mathbb{R}^{n^2}$  is open.  $GL(n, \mathbb{R}) = \det^{-1}(\mathbb{R} \setminus \{0\})$   
Hence  $GL(n, \mathbb{R})$  is a submanifold of  $\mathbb{R}^{n^2}$  and has dimension  $n^2$ .

iv)  $SL(n, \mathbb{R}) \subseteq GL(n, \mathbb{R})$  s.t.  $A \in SL(n, \mathbb{R}) \Leftrightarrow \det A = 1$ . Now we need to show that for all  $A \in \det^{-1}(\{1\}) = SL(n, \mathbb{R}) \quad d(\det)|_A: T_A GL(n, \mathbb{R}) \rightarrow T_1 \mathbb{R}$

$$\mathbb{R}^{n^2} \quad \mathbb{R}$$

$$\text{consider } \gamma(t) = A + tA \Rightarrow \gamma'(0) = A: \quad d(\det)|_A(A) = \left. \frac{d}{dt} \right|_{t=0} \det(A+tA) = \left. \frac{d}{dt} \right|_{t=0} \det((1+t)A)$$

$$= \left. \frac{d}{dt} \right|_{t=0} (1+t)^n \underbrace{\det(A)}_1$$

$$= n \neq 0$$

Hence 1 is a regular value for  $\det \Rightarrow SL(n, \mathbb{R})$  is a submanifold of dimension  $n^2 - 1$ .

v) let  $\mathcal{G}: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$  a nondegenerate, symmetric, bilinear form :  $\mathcal{G}(x, y) = x^T g y$ . Now  $\mathcal{G}$  has signature  $(p, q)$

Look at Sylvester's law of inertia

↑  
symmetric matrix

$$\mathcal{O}(p, q) = \{A \in GL(n, \mathbb{R}) \mid \mathcal{G}(x, y) = \mathcal{G}(Ax, Ay)\}. A \in \mathcal{O}(p, q) \Leftrightarrow A^T g A = g$$

show  $\mathbb{R}^n$  is a  
 vector space of  
 dimension  $\frac{n(n+1)}{2}$   
 ↓

$$\Leftrightarrow x^T A^T g A y = x^T g y = \mathcal{G}(x, y)$$

$$\mathcal{G}(Ax, Ay)$$

Consider the map  $f: \mathbb{R}^{n^2} \rightarrow \text{Sym}(n, \mathbb{R})$  by  $f(A) = A^T g A$ .  $\mathcal{O}(p, q) = f^{-1}(\{g\})$

We need to show that  $\forall A \in \mathcal{O}(p, q)$ ,  $df_A: \mathbb{R}^{n^2} \rightarrow \text{Sym}(n, \mathbb{R})$  is surjective.

$$df_A(X) = \left. \frac{d}{dt} \right|_{t=0} f(A + tX)$$

$$= \left. \frac{d}{dt} \right|_{t=0} A^T g A + t A^T g X + t X^T g A + t^2 X^T g X$$

$$= A^T g X + X^T g A$$

$$gg^{-1} = \text{Id}$$

$$(g^{-1})^T g^T = \text{Id}$$

$$\Rightarrow (g^{-1})^T = (g^T)^{-1} = g^{-1}$$

Now let  $Y \in \text{Sym}(n, \mathbb{R})$  then let  $X = \frac{1}{2} Ag^{-1}Y \Rightarrow df_A(X) = A^T g \left( \frac{1}{2} Ag^{-1}Y \right) + \frac{1}{2} Y^T (g^{-1})^T A^T g A$

$$= \frac{1}{2} \left( \underbrace{A^T g A g^{-1} Y}_g + \underbrace{Y g^{-1} A^T g A}_g \right)$$

$$= \frac{1}{2} (gg^{-1}Y + Yg^{-1}g)$$

$$= Y$$

Hence  $df_A$  is surjective  $\Rightarrow \mathcal{O}(p, q)$  are manifolds of dimension  $n^2 - \frac{n(n+1)}{2} = \frac{n(n-1)}{2}$

vi)  $\text{SO}(p, q) \subseteq \mathcal{O}(p, q)$  given by  $A \in \text{SO}(p, q) \Leftrightarrow \det A = 1$  and  $A \in \mathcal{O}(p, q)$

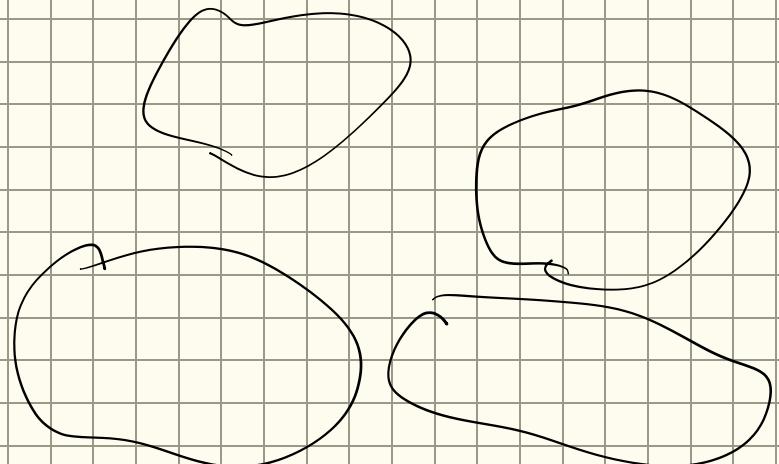
Hence  $f(A) = (A^T g A, \det A)$  is a submersion on  $\text{SO}(p, q) \Rightarrow \text{SO}(p, q)$  is a manifold of dimension  $\frac{n(n-1)}{2} - 1$

In special relativity we have inner product  $\eta(v, w) = -v^0 w^0 + v^1 w^1 + v^2 w^2 + v^3 w^3$

$$= \begin{bmatrix} v^0 & v^1 & v^2 & v^3 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} w^0 \\ w^1 \\ w^2 \\ w^3 \end{bmatrix}$$

Lorentz group is the group  $O(3, 1)$ . Note that  $\dim O(3, 1) = \frac{4(3)}{2} = 6$

The restricted Lorentz group  $SO^+(3,1)$  = identity component of  $O(3,1)$



Exercise 1: Show  $O(3,1)$  has 4 connected components

Exercise 2: let  $G$  be a Lie group and  $N$  be the connected component of  $e$ . then  $N \trianglelefteq G$  and  $N$  is submanifold.

We have  $\text{Spin}(3,1)$  which is the double cover of  $\text{SO}(3,1)$

$$\begin{array}{c} \text{SU}(2, \mathbb{C}) \\ \text{Sp}(2, \mathbb{C}) \end{array}$$

$S^n \subseteq \mathbb{R}^{n+1}$  is a manifold. Moreover  $i: S^n \hookrightarrow \mathbb{R}^{n+1}$  is smooth.  $T_p S^n \cong \text{dip}(T_p S^n) \subseteq T_p \mathbb{R}^{n+1}$

Exercise: If  $f: M \rightarrow N$  is smooth and  $f^{-1}(q^*)$  is a regular level set then  
 $T_p S = \ker(df_p)$

$$T_p S^n = \ker(df_p) \text{ where } df_p = \begin{bmatrix} 2p^1 & \cdots & 2p^{n+1} \end{bmatrix} \text{ but } df_p(v) = \begin{bmatrix} 2p^1 & \cdots & 2p^{n+1} \end{bmatrix} \begin{bmatrix} v^1 \\ \vdots \\ v^{n+1} \end{bmatrix}$$

=  $2p \cdot v$   
= 0

Next time we compute  $T_A O(p,q)$ ,  $T_{\text{Id}} SL(n, \mathbb{R}) \Rightarrow T_A SL(n, \mathbb{R})$