

Recall: Manifold is a 2^{nd} countable, Hausdorff locally Euclidean topological space
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 paracompactness

last time: we took the tangent bundle TM we dualized it to get the cotangent bundle T^*M .

Sections: $\pi: E \rightarrow M$ then a section σ of this surjection is a right inverse:
 $\pi \circ \sigma = \text{id}_M$

$$E_p = \pi^{-1}(p) \text{ and } v_p \in E_p$$

so sections of TM are vector fields
 sections of T^*M are called covector fields
 sections of $M \times N$ are maps from $M \rightarrow N$

We denote by $\mathcal{X}(M) = \{X \text{ section of } TM \rightarrow M \text{ and smooth}\}$
 $\Omega^1(M) = \{\omega \text{ sections of } T^*M \rightarrow M \text{ and smooth}\} = \{\text{space of 1-forms}\}$ (differential)

Exercise: Show sections of $M \times \mathbb{R}$ is the same as the space $\mathcal{C}^\infty(M)$

John Baez - Gauge Fields, knots and Gravity.

Smooth sections of a vector bundle $\pi: E \rightarrow M$ will be denoted $\Gamma(E)$

Take TM we used some representation of $GL(\mathbb{R}^n)$ to get cocycles gap for TM .

So now we take tensor representations of $GL(\mathbb{R}^n)$. $\rho: GL(\mathbb{R}^n) \rightarrow GL(T^k \mathbb{R}^n)_{\mathbb{R}}$
 $A \mapsto \bigotimes_{i=1}^k (A^*)^{-1} \otimes \bigotimes_{i=1}^k A$

then we define tensor bundles $T^k_{\mathbb{R}} M = T^{(k,0)} M$.

In local coordinate (U, φ) with coordinate vector fields $\frac{\partial}{\partial x^i}$ and coordinate 1-forms dx^i $[(dx^i)_p: T_p U \rightarrow \mathbb{R} \text{ so that } dx^i(\frac{\partial}{\partial x^j}) = \delta^i_j]$
 $T_p M$

$$\omega_p \in T_p^{(k,0)} M, \quad \omega_p = \omega_{i_1 \dots i_k}^{j_1 \dots j_k}(p) dx_{j_1}^{i_1} \otimes dx_{j_2}^{i_2} \otimes \dots \otimes dx_{j_k}^{i_k} \otimes \frac{\partial}{\partial x^{i_1}} \Big|_p \otimes \dots \otimes \frac{\partial}{\partial x^{i_k}} \Big|_p$$

Exercise: Suppose (V, ψ) is another coordinate system. How do the components transform?

New $\omega \in \Gamma(T^{(k,0)}M) \Leftrightarrow \forall p \in M$ and charts (U, φ) around p . The component functions are smooth.

We can look at $\omega \in \Gamma(T^{(k,l)}M)$ as a $C^\infty(M)$ -linear function

$$\omega: \underbrace{\mathcal{F}(M) \times \dots \times \mathcal{F}(M)}_k \times \underbrace{\Omega^1(M) \times \dots \times \Omega^1(M)}_l \rightarrow C^\infty(M)$$

Examples of smooth tensor fields:

1) Riemannian metric: $g \in \Gamma(T^{(2,0)}M)$ that is symmetric, positive definite and non-degenerate.

$g_p: T_p M \times T_p M \rightarrow \mathbb{R}$ that is an inner product

locally $g = g_{ij} dx^i \otimes dx^j$ where $g_{ij} = g_{ji}$

2) Symplectic form: $\omega \in \Gamma(T^{(2,0)}M)$ that is antisymmetric, non-degenerate and is closed. $\omega = \omega_{ij} dx^i \wedge dx^j$.

$$\downarrow$$

$$d\omega = 0$$

\uparrow
wedge from
linear algebra