Water Meter Reader Documentation Neptune E-Coder Version



Software Code

Written in C++ Arduino V1.0.2 for Windows

Target Board: Ethernet with USB Serial Light Serial Adapter for programming

<u>Arduino File:</u> <u>DataTimeSDServerFinal_Feb3_14</u>

Release 1.0

February 3, 2014

Reference:Pin Map

Pin 0	Serial Tx
Pin 1	Serial Rx
Pin 2	
Pin 3	
Pin 4	SD card CS (SPI Select)
Pin 5	
Pin 6	Rx Read Meter Data
Pin 7	Tx Clock to Meter
Pin 8	Relay
Pin 9	LED
Pin 10	Ethernet SPI (SS)
Pin 11	Ethernet SPI (MOSI)
Pin 12	Ethernet SPI (MISO)
Pin 13	Ethernet SPI (SCK)
Analog pins 1-6	

Initialization –

Definitions, libraries incuded, Global declarations

Void (setup) -

Initialize Serial Port, SD Card, Ethernet Client, Server.

IP: 192.168.17.176 [May be DHCP from Rozeware Checkbox park intranet server] See intranet setup

Void()

Prog Exec – once every hour

- Engage Relay contact with water meter

Void(GetTime) Get internet time from UDP NTP

Void(ReadMeter) Read Water Meter

- Void(SDCardWrite) Write date, time, Water Meter Reading to SD Card

- Disengage Relay contact with water meter

- Monitor Client request for data

- Send Requested SD Data

GetTime()

Disable SD

Enable Ethernet

Set UDP listen port to 8888

Set Ethernet client as DNS Client

Request Time Server IP address

Create NTP packet request

Send NTP request to DNS Server (pool.ntp.org)

Get UDP packet from assigned DNS server

Decode NTP time

- Add day to Microsoft date code
- Decode hour and minute

ReadMeter() *See Appendix

Put clock on Tx line until Rx line goes high (<10 Min)

Record bits when Rx line goes low (62 – 95mS)

Read 34 Data Bytes

- 11 bit bytes. (1 start, 8 data, 2 stop)
- 8 samples/bit read sample 5

Timing very critical. Should be hardware decoder not software Or use edge detect (Arduinos edge detect voids delay timing)

- Align data bits and strip out digit

SDCardWrite()

Disable Ethernet

Enable SD Card

Create String

- Write date, time, data (bytes 7-12)
- Add 24 Hour marker
- Add EOF (Null)

Open SD

Write SD

Close SD

Disable SD

Erase String

Client Monitor

Client Requests data from Server

- \$1 = All Data
- \$2 = All days one reading per day
- \$3 = Last 32 hours
- \$4 = All Data last 7 Days
- \$5 = All Data last 31 days
- \$6 = Once per day last 31 days

Respond to establish handshake with content type

Open SD data file DateData.TXT

Write data to Ethernet

Close SD Card

Disconnect Client

Code on Arduino Ethernet Card

<u>Arduino File: DataTimeSDServerFinal_Feb3_14</u>

/*

Web Server, Web client, water meter reader, MicroSD card

File: DateData.txt

Circuit: Ethernet shield attached to pins 10, 11, 12, 13

SD Enable attached to pin 4

TxClk pin 7

RxData pin 6

led pin 9

Relay pin 8

*/

```
#include <SPI.h>
#include <Ethernet.h>
#include <EthernetUdp.h>
#include < Dns.h>
#include <SD.h>
#define RxData 6
#define TxClock 7
#define Relay 8
//////Ethernet Setup
// Enter a MAC address for your controller below.
// Newer Ethernet shields have a MAC address printed on a sticker on the shield
byte mac[] = { OxDE, OxAD, OxBE, OxEF, OxFE, OxED };
byte ip[] = { 192,168,17,176 }; // ip in LAN
unsigned int localPort = 8888; // local port to listen for UDP packets
IPAddress timeServer; // pool.ntp.org NTP server
const int NTP_PACKET_SIZE= 48; // NTP time stamp is in the first 48 bytes of the message
byte packetBuffer[ NTP_PACKET_SIZE]; //buffer to hold incoming and outgoing packets
EthernetServer server(80);
EthernetClient client;
EthernetUDP Udp; // A UDP instance to let us send and receive packets over UDP
```

```
///////Read Meter declarations
                                // 35 is ok Buffer for bit read data
unsigned int dataAlign[35];
                                 // 35 is ok
unsigned int meterByte[35];
int count = 9;
                     //byte timing tuning
int bitcount =0;
int mask = 15;
                    // mask 0b0000 0000 0000 1111. Strips 4 bit integer
unsigned int last=0;
                     // Send Data record count
unsigned int last_A=0; // Send Data count register
byte set_P=0;
                // Send Data start / stop flag
              // command flag in ethernet read
byte set=0;
byte command =0; // Data command
unsigned long previousMillis = 0;// Delay between Meter reads
// added 1.25 seconds to hourly read - Feb 1st coldest month of year - to correct for time slippage
unsigned long interval = 3601250; //1 Hour Time delay between NTP reads(3,600,000)
unsigned int Current_Date = 0;
unsigned int Current_Hour = 0;
unsigned int Current_Minute = 0;
int bitRate=415;
                    // 1187hz. Seems more stable than 1200
boolean state=false:
```

```
boolean laststate = false;
void setup() {
Serial.begin(9600);
pinMode (RxData,INPUT_PULLUP);// Read
pinMode (TxClock,OUTPUT);// clock
pinMode (Relay,OUTPUT);
// disable w5100 while setting up SD
pinMode(10,OUTPUT);
digitalWrite(10,HIGH);
Ethernet.begin(mac, ip);
digitalWrite(10,HIGH);
 server.begin();
}
```

```
void loop() {
 unsigned long currentMillis = millis();
 if (currentMillis - previousMillis > interval) {
  previousMillis = currentMillis;
  digitalWrite(Relay,HIGH);
  delay (200);
  GetTime();
                                      // call GetTime function
  MeterRead();
                                      // call get meter data
  SDcardWrite();
                                      // call SD write
  return;
                       //seem to need to re initialize?
 }
 // Create a client connection
  EthernetClient client = server.available();
 if (client) {
  while (client.connected()) {
   if (client.available()) {
    char c = client.read();
     if(set==1){}
                       // set by receiving $ char
     command = c; // char following the $ char defines what to send
     set=0;
    }
```

```
if(c==36) set=1; // char $ recieved
if (c == '\n') {
                           // Null = HTTP request has ended
 client.println(F("HTTP/1.1 200 OK")); //send new page
 client.println(F("Content-Type: text"));
 client.println();
 SD.begin(4);
 File myFile = SD.open("DateData.TXT");
 delay(1);
 if (myFile) {
  while (myFile.available()) {
   char c=(myFile.read());
   if (c == 13) last++; // use CR as record increment count
   // All Data client.print command
   if(command==49) client.write(c); // command =1
   // 1 per day All data client.print command
   if((command==50)&&(c == 'h')) set_P=0;
   if((command==50)&&(set_P == 1)) client.write(c);
   if((command==50)&&(c == 'H')) set_P=1; // 1 per day all days (Written in SD string)
```

```
// All data last 32 hours client print command
  if((command==51) && (last > (last_A - 33))) client.write(c); //send last 32
  // All data last 7 days client print command
  if((command==52) && (last > (last_A - 169))) client.write(c); //send last 7 days
  // All data 31 days client print command
  if((command==53) && (last > (last_A - 745))) client.write(c); //send last 24
  // 1 per day last 31 days at 23 hour
  if((command==54)&&(c == 'h')) set_P=0;
  if((command==54)&&(set_P == 1)) client.write(c);
  if((command==54) \&\& (last > (last_A - 745)) \&\& (c == 'H')) set_P=1;
 }
 myFile.close();
}
delay(1);
client.stop();
digitalWrite(4,HIGH);
delay(1);
last_A=last; // cumulative SD record count (Also incremented in SD Write)
last=0; // clear 'last' record count register
```

}

// Look for Rx line to go Low (62 - 95mS)

```
//Quickly align transistion of state change
state = digitalRead(RxData);
while (state == digitalRead(RxData)) {
  for( int y=0; y<32; y++) {
    if (y==0) digitalWrite(TxClock, HIGH);
    if (y==15) digitalWrite(TxClock, LOW);
    delayMicroseconds(20);
    if(state != digitalRead(RxData)) break;
  }
}</pre>
```

// Read 34 Data bytes. 316mS to 319mS per 34 bytes read.

```
for(int mData=0; mData < 34; mData++){
  for (int bytecount=0; bytecount < 11; bytecount++) { // 11 bits per byte incl. 2 stop and 1 start
  for(bitcount =7; bitcount >=0; bitcount--){ // read each bit 8 times. 4 high, 4 low
        if (bitcount == 7) digitalWrite(TxClock, HIGH);
        if (bitcount == 3) digitalWrite(TxClock, LOW);
        delayMicroseconds(96); // 1180 bits/Sec. 107 bytes/Sec
        laststate =! digitalRead(RxData);
        if (bitcount==5)
        bitWrite(meterByte[mData], bytecount, laststate);// write bit state
```

```
}
   delayMicroseconds(count); // fine tune timing. Count from 7 to 11
  }
  //dataAlign[mData] = meterByte[mData]; //align 11 bit bytes
  if (bitRead(meterByte[mData], 10)==0) dataAlign[mData] = meterByte[mData]; //should be start bit
  if (bitRead(meterByte[mData], 10) >0) dataAlign[mData] = meterByte[mData] >>1; //shift right may
correct align
  if ((bitRead(meterByte[mData], 5) >0) && (bitRead (meterByte[mData], 6) >0)) dataAlign[mData] =
meterByte[mData] >>1; //bit 5 & 6 should be 1
  if ((bitRead(meterByte[mData], 6) >0) && (bitRead (meterByte[mData], 7) >0)) dataAlign[mData] =
meterByte[mData] >>2; //align 11 bit bytes
  meterByte[mData] = dataAlign[mData] & mask; // meterData is least 4 bits of masked aligned data
// delayMicroseconds(count); // maybe more fine timing tuning
}
//exit read loop
 digitalWrite(TxClock,HIGH); // put low on meter
 digitalWrite(Relay,LOW); //Turn off relay before writing to SD card
}
//end data capture
```

//Write data to SDCardFile

```
void SDcardWrite() {
pinMode(10,OUTPUT);
                           // disable w5100 SPI while starting SD
digitalWrite(10,HIGH);
SD.begin(4);
String dataString = "";
                                    // clear string
 dataString += Current_Date;
//dataString += ",";
 dataString += "\t";
                                       //TAB
 dataString += Current_Hour;
dataString += ":";
 if (Current_Minute < 10) { // In the first 10 minutes of each hour, we'll want a leading '0'
  dataString += "0";
}
 dataString += Current_Minute;
//dataString += ",";
dataString += "\t";
                                        //TAB
 dataString += meterByte[7];
 dataString += meterByte[8];
 dataString += meterByte[9];
 dataString += meterByte[10];
```

```
dataString += meterByte[11];
dataString += (".");
dataString += meterByte[12];
if (Current_Hour==23){
                                            //Write Hour marker
 dataString += "\t";
 dataString += "H";
}
else{
 dataString += "\t";
 dataString += "h";
}
dataString += "\0"; // null
// write to SD file
File dataFile = SD.open("DateData.txt", FILE_WRITE);
if (dataFile) {
 dataFile.println(dataString);
 dataFile.close();
}
dataString = ""; //delete string
digitalWrite(4,HIGH); // disable SD SPI
last_A++; // increment record count
```

void GetTime(){

```
pinMode(4,OUTPUT); // disable SD SPI while starting w5100
digitalWrite(4,HIGH);
pinMode(10,OUTPUT);
digitalWrite(10,HIGH);
Udp.begin(localPort);
DNSClient dns;
dns.begin(Ethernet.dnsServerIP());
if(dns.getHostByName("pool.ntp.org",timeServer))
 sendNTPpacket(timeServer); // send an NTP packet to a time server
 // wait to see if a reply is available
delay(4000); // was 1000
if (Udp.parsePacket()) { // We've received a packet, read the data from it
 Udp.read(packetBuffer,NTP_PACKET_SIZE); // read the packet into the buffer
 unsigned long highWord = word(packetBuffer[40], packetBuffer[41]);
 unsigned long lowWord = word(packetBuffer[42], packetBuffer[43]);
```

```
unsigned long secsSince1900 = highWord << 16 | lowWord;
  const unsigned long seventyYears = 2208988800UL;
  unsigned long epoch = secsSince1900 - seventyYears;
  //Current_Date = (41244 +((epoch - 1354341600) / 86400));// DST
  Current_Date = (41244 +((epoch - 1354338000) / 86400));// EST
  //Current_Hour = (((epoch - 14400) % 86400L) / 3600); // DST -4 Hrs from UTC
  Current_Hour = (((epoch - 18000) % 86400L) / 3600); // EST -5 Hrs from UTC
  Current_Minute = ((epoch % 3600) / 60); // print the minute (3600 equals secs per minute)
}
}
// send an NTP request to the time server at the given address
unsigned long sendNTPpacket(IPAddress& address)
{
 memset(packetBuffer, 0, NTP_PACKET_SIZE); // set all bytes in the buffer to 0
 packetBuffer[0] = 0b11100011; // LI, Version, Mode
 packetBuffer[1] = 0; // Stratum, or type of clock
 packetBuffer[2] = 6; // Polling Interval
 packetBuffer[3] = 0xEC; // Peer Clock Precision
 // 8 bytes of zero for Root Delay & Root Dispersion
```

```
packetBuffer[12] = 49;
packetBuffer[13] = 0x4E;
packetBuffer[14] = 49;
packetBuffer[15] = 52;

// all NTP fields have been given values, now
// you can send a packet requesting a timestamp:
Udp.beginPacket(address, 123); //NTP requests are to port 123
Udp.write(packetBuffer,NTP_PACKET_SIZE);
Udp.endPacket();
```

See below.

Appendix:

Bit 1: STX (2)

Bit 2: Some sort of Indicator. Either a 1 or a 2. Affects bits 26, 28, 29, 30

Bit 3 - 6: Always 0037

Bit 7: ETB (7)

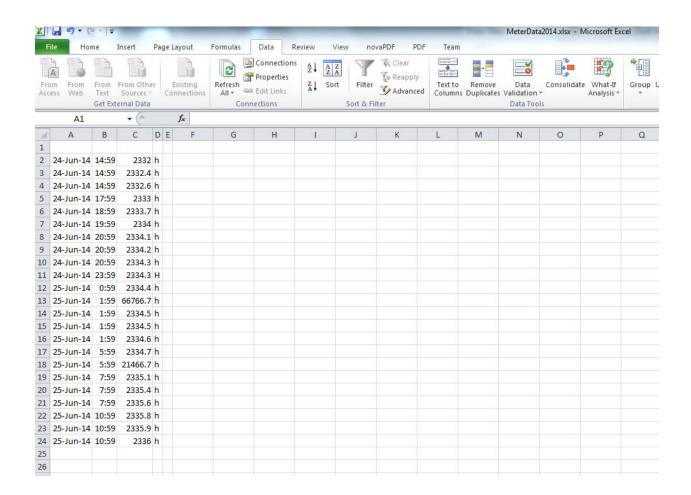
Bit 8 - 13: Data (Cubic Meters. (00000.0)

Bits 15 – 24: Meter Number: 9122130023

Bits 26 -34: Additional data: probably X.X00 data. 28, 29 are always 10, 7 if bit 2 is a 1. 26 changes to 8.

Red reads are bad reads

		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
		8	9	10	11	7	8	9	10	11	7	8	9	10	11	7	8	9	10	11	7	8	9	10	11
		4:52	5:20	5:47	6:17	6:46	7:30	8:35	9:14	9:50	10:22	10:55	4:52	5:36	6:22	8:12	8:56	9:34	10:13	10:49	11:26	11:56	12:32	12:56	14:22
1	STX(2)	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	1	1	1	1	2	1	2	1	2	1	1	1	2	1	1	1	1	1	1	2	1	2	1	1
3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
4	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
5	S(3)	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3
6	W(7)	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
7	ETB(7)	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
8	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
9	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
10	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7
11	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2
12	6	6	6	6	6	6	6	6	6	6	6	6	6	7	7	7	7	7	7	7	7	7	7	7	7
13	5	9	9	9	9	9	9	9	9	9	9	9	9	0	0	0	0	0	0	0	0	1	1	1	1
14	ETB(7)	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	7	-	7	7	7	7	7	7	7
15	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9	9		9	9	9	9	9	9	9
16	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1		1	1	1	1	1	1	1
17	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2		2	2	2	2	2	2	2
18	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2		2	2	2	2	2	2	2
19	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1		1	1	1	1	1	1	1
20	3	3	3	3	11	3	3	3	3	3	3	3	3	3	1	11	3		3	3	11	3	3	3	3
21	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	3	0		0	0	3	0	0	0	0
22	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	3	0		0	0	3	0	0	0	0
23	2	2	2	2	2	2	2	2	2	2	2	2	2	2	2	9	2		2	2	9	2	2	2	2
24	3	3	3	3	3	3	3	3	3	3	3	3	3	3	3	11	3		3	3	11	3	3	3	3
25	ETB(7)	7	7	7	7	7	7	7	7	7	14	7	7	7	14	11	7		7	7	11	7	7	7	7
26	(space) (0)	0	0	0	0	8	0	8	0	8	0	0	0	8	0	1	0		0	0	1	0	8	0	0
27	ETB(7)	11	7	7	7	7	7	7	7	7	14	7	7	7	14	11 0	7		7	7	11	7	7	7	7
28	1	9	10	10	10	4	10	4	10	5	4	10	10	2	4		10		10	10	2	10	0	10	10
29 30	6 @(0)	13	7	7	7	1	7	1	7	2	14	7 12	7 12	5	14	13	7 12		7	7	3	7 12	4	7	7
	V-7	1	12	12	12	0		0	12	0	8			0	8	11			12	12	1		0	12	12
31	ETB(7)	11	7	7	7	7	11	7	7	7	14	7	7	7	14	11	14		7	7	11	7	7	7	7
32	2	5	5 2	5	5	6 4	5 3	6	5 2	7	10 4	5 1 4	5 2	5	6	3 11	0	6 3	6 3	6 3	13	5 4	<u>6</u> 3	5	5
34	ETX(3)	3 11	6	6	0	3	პ 11	4	6	6 3	13	14	6	5	3 0	11	0		6	0	3 11	13	6	4	6
34	EIX(3)	TT	0	0	U	ర	TT	6	O	J	13	TT	0	6	U	- 11	9	6	O	U	H	13	D	6	O



This is a representation of acquired data in a spreadsheet. Note a couple of bad reads.

Could do better with a hardware implementation for data edge detect instead of Arduino.

Ran out of time to do it correctly, but it works.