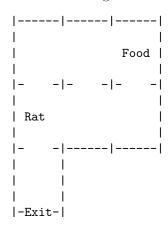
## Statistics 831: Probability and Statistical Modeling

Homework #8 Due 3/30/2020

## **Problems:**

- 1. Solve the following by defining an appropriate Markov chain and using first-step analysis:
  - (a) In repeated (fair) coin tosses:
    - i. Calculate the expected number of tosses until 2 successive heads.
    - ii. Of the two patterns HHT and HTH, which do you expect to observe first and why.
  - (b) Rat maze: for a rat located as shown performing a random walk calculate the probability of finding food before exiting.



Note that the exit is on the wall, ie the rat can move down 1 step without exiting the maze.

2. Define a Markov chain on  $0, \ldots, N$  by:

$$P_{i,j} = \begin{cases} 1 & i = j = 0\\ 1/i & 0 \le j < i \le N\\ 0 & \text{otherwise} \end{cases}$$
 (1)

- i.e. from state j the chain is equally likely to go to  $0, \ldots, j-1$ .
- (a) Determine the fundamental matrix for the transient states.
- (b) Determine the distribution of the last positive integer visited.
- 3. Choose one of the above problems (either 1(a)ii, 1b, or 2b) and validate your results by:
  - (a) Computing large powers of the transition matrix.
  - (b) Simulating realizations of the Markov chain.

4. The Gibbs sampler defined in class cycles through coordinates in a fixed order. Alternatively, we may define a random-scan Gibbs sampler, which iteratively chooses  $i \in \{1, ..., d\}$  at random (according to probabilities  $p_i$  say), and sets

$$\theta^{(n+1)} = (\theta_1^{(n)}, \dots, \theta_{i-1}^{(n)}, \theta_i^*, \theta_{i+1}^{(n)}, \dots, \theta_d^{(n)})$$

with

$$\theta_i^* \sim \pi(\theta_i \mid \theta_1^{(n)}, \dots, \theta_{i-1}^{(n)}, \theta_{i+1}^{(n)}, \dots, \theta_d^{(n)})$$

- (a) Show that this also produces a Markov chain with stationary distribution  $\pi$ .
- (b) Give sufficient conditions for this chain to have limiting distribution  $\pi$ .
- 5. The famous "braking data" of Tukey (1977) is available in R under the dataset name **cars**. It gives the speeds traveled (mph) and braking distances (feet) for 50 cars. It is thought that a good model for this dataset is a quadratic model:

$$y_{ij} = a + bx_i + cx_i^2 + \epsilon_{ij}$$
 for  $i = 1, ..., k; j = 1, ..., n_i$ 

- (a) Write down the likelihood function assuming  $\epsilon_{ij} \sim N(0, \sigma^2)$ .
- (b) Obtain estimates of a, b, c and  $\sigma^2$  from a standard linear regression.
- (c) View the likelihood in part (a) as a posterior distribution under flat priors, and construct a Metropolis-Hastings algorithm to sample from it using a *Metropolized independence* sampler with proposal distributions selected based on your estimates in (b). Use normals for a, b, c and inverse-gamma for  $\sigma^2$ .
- (d) Make histograms of the posterior distributions of the parameters. Show any plots or diagnostics used to monitor convergence.
- (e) Consider robustness by modifying the error distribution to  $\epsilon_{ij} \sim t_4(0, \sigma^2)$  and re-running your analysis. Do you need to modify your proposal distributions?