Joint Space:

Teach	
x:	0.780
v:	0.094
z:	0.915
R:	-121.7
P:	47.6
Y:	-18.6

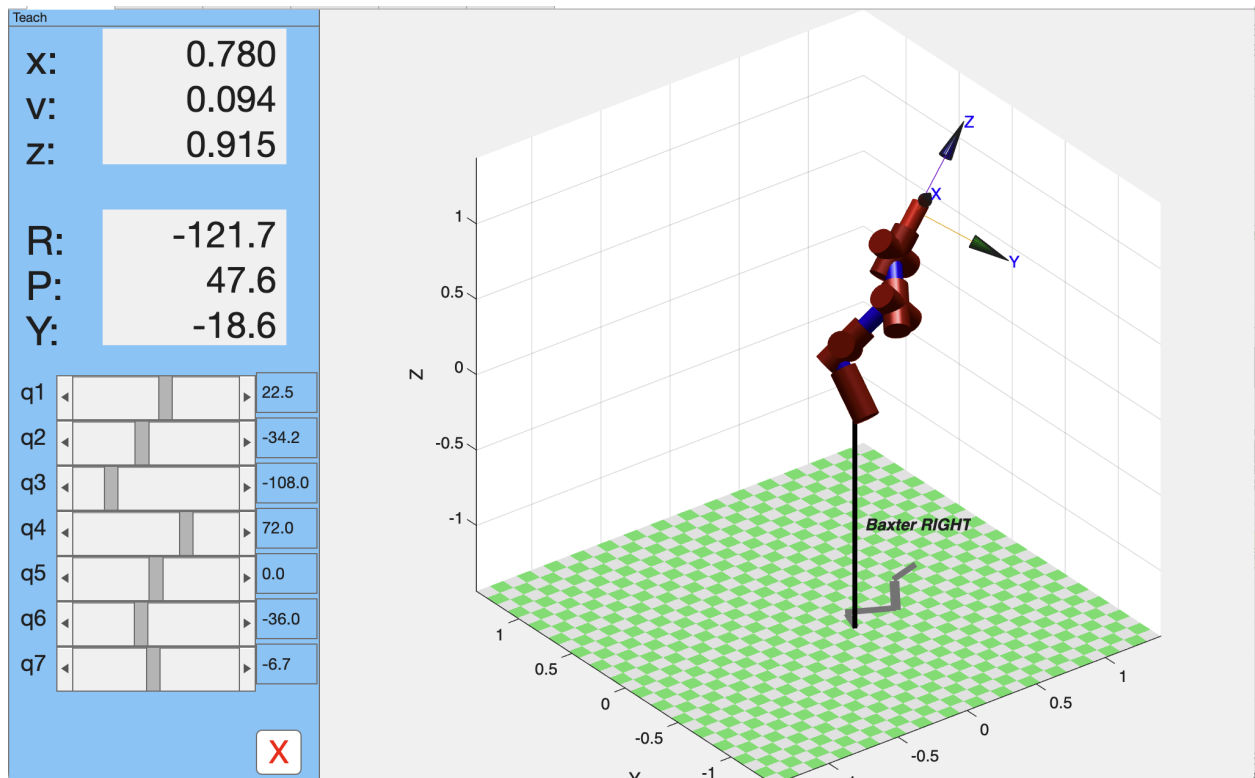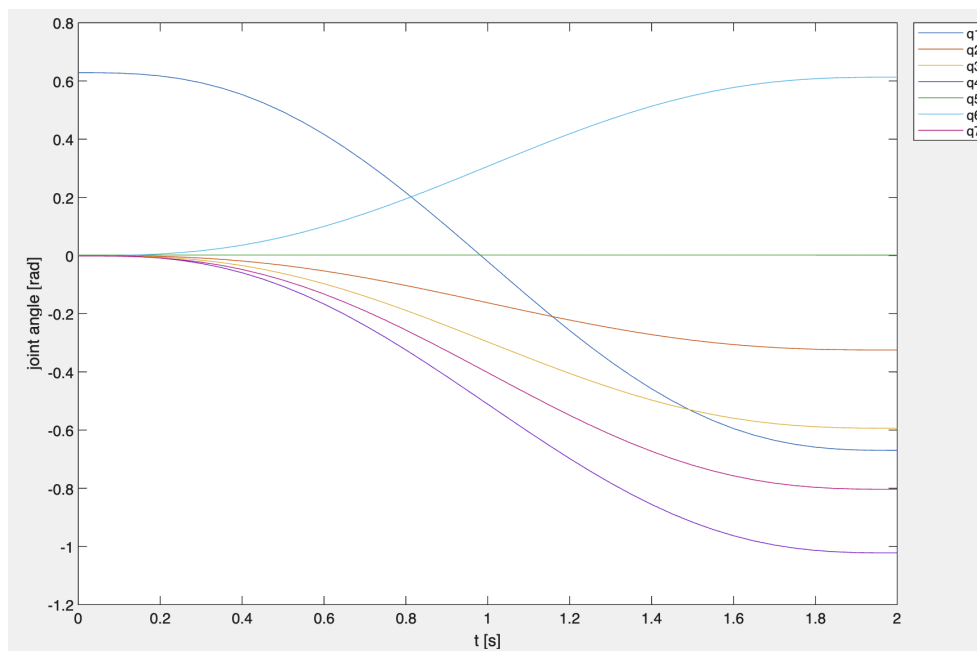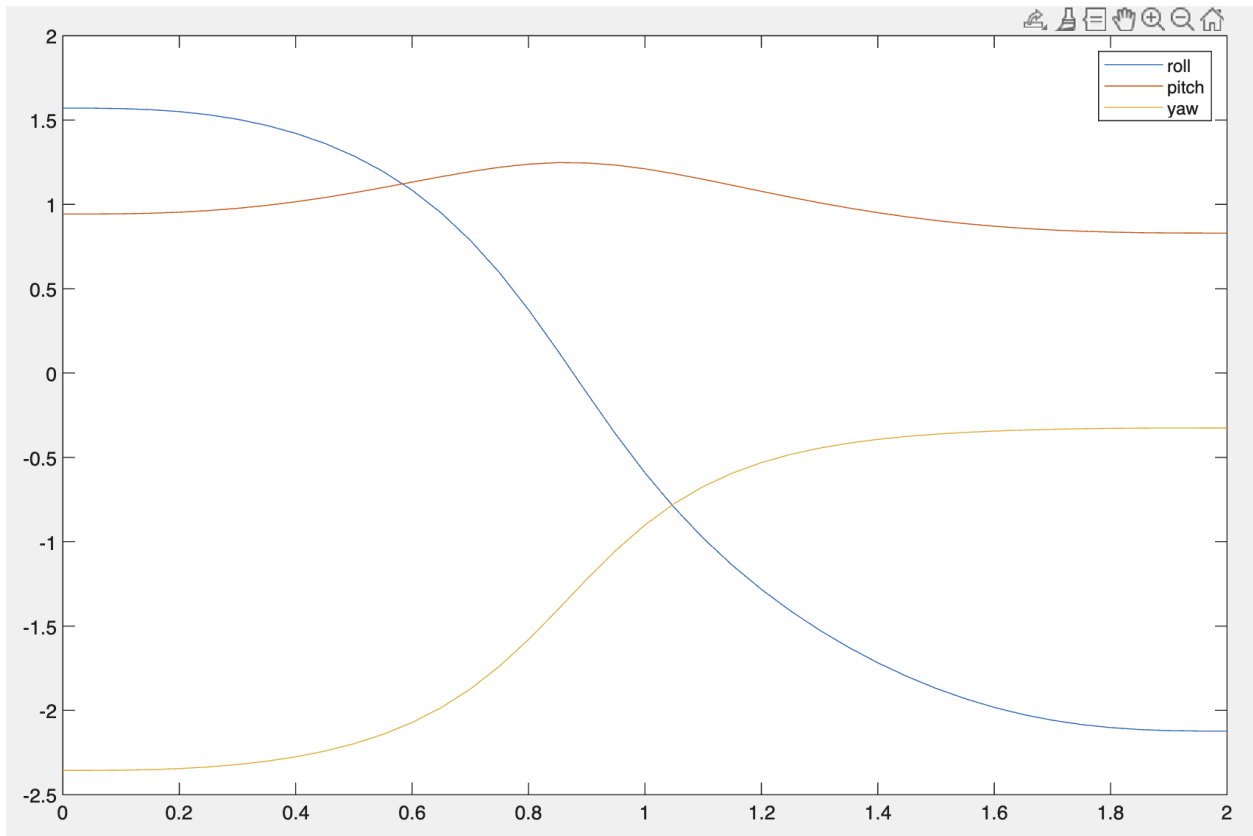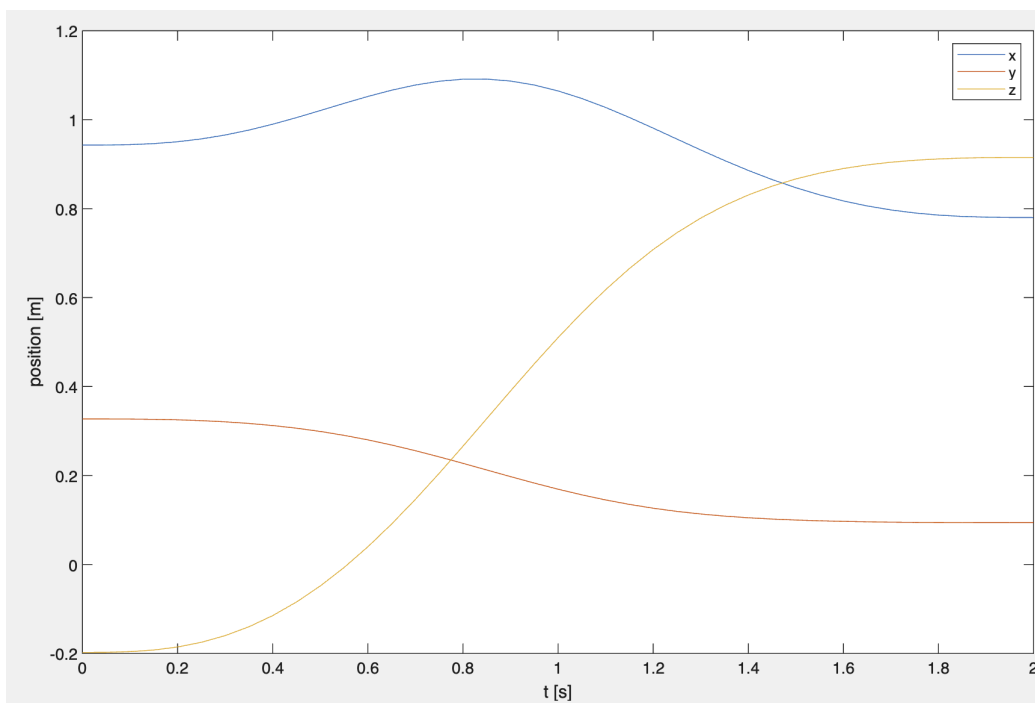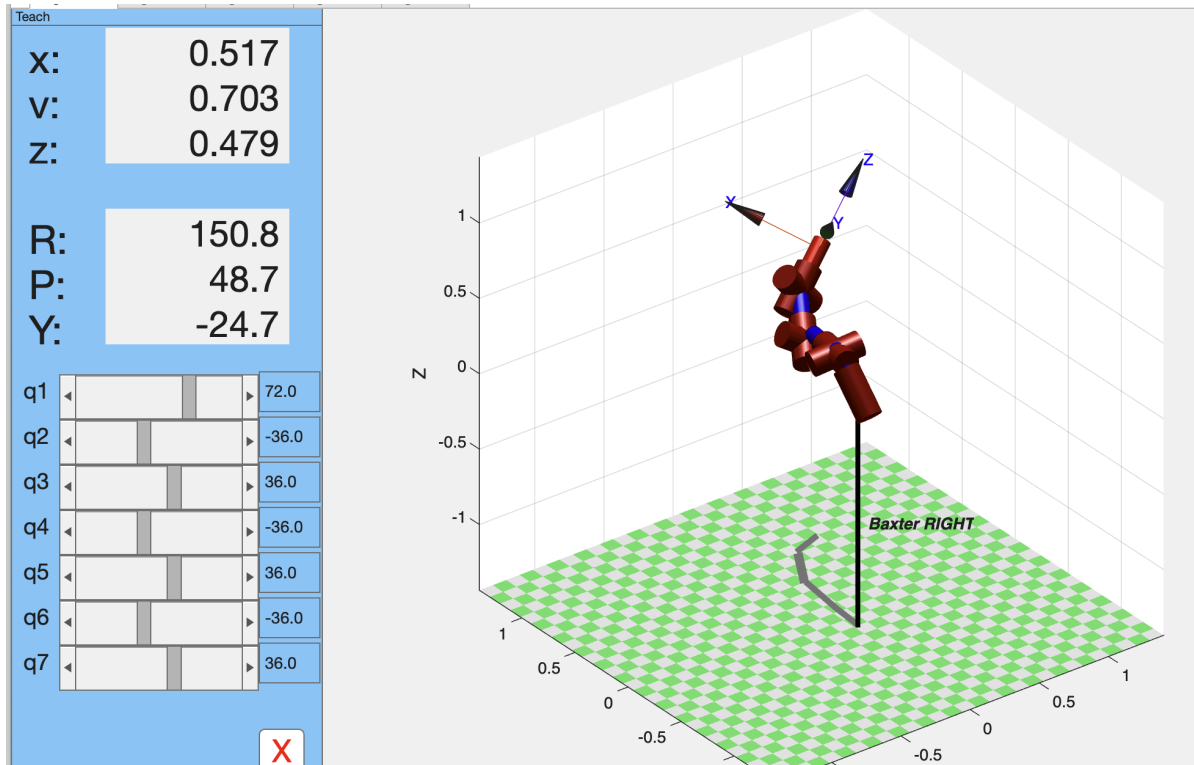|		
q1	◄ ▬ ►	22.5
q2	◄ ▬ ►	-34.2
q3	◄ ▬ ►	-108.0
q4	◄ ▬ ►	72.0
q5	◄ ▬ ►	0.0
q6	◄ ▬ ►	-36.0
q7	◄ ▬ ►	-6.7

Goal positions

joint coordinate trajectory
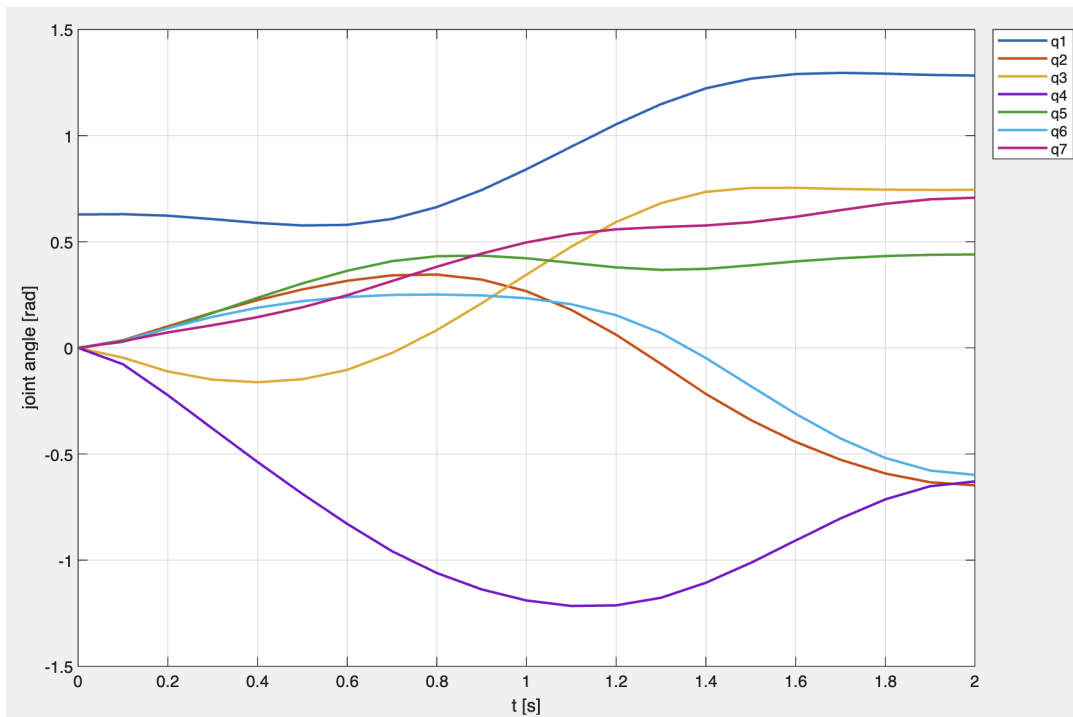
orientation of the end-effector. (`T.torpy('xyz')`)

the end-effector's position versus time.

CARTESIAN:

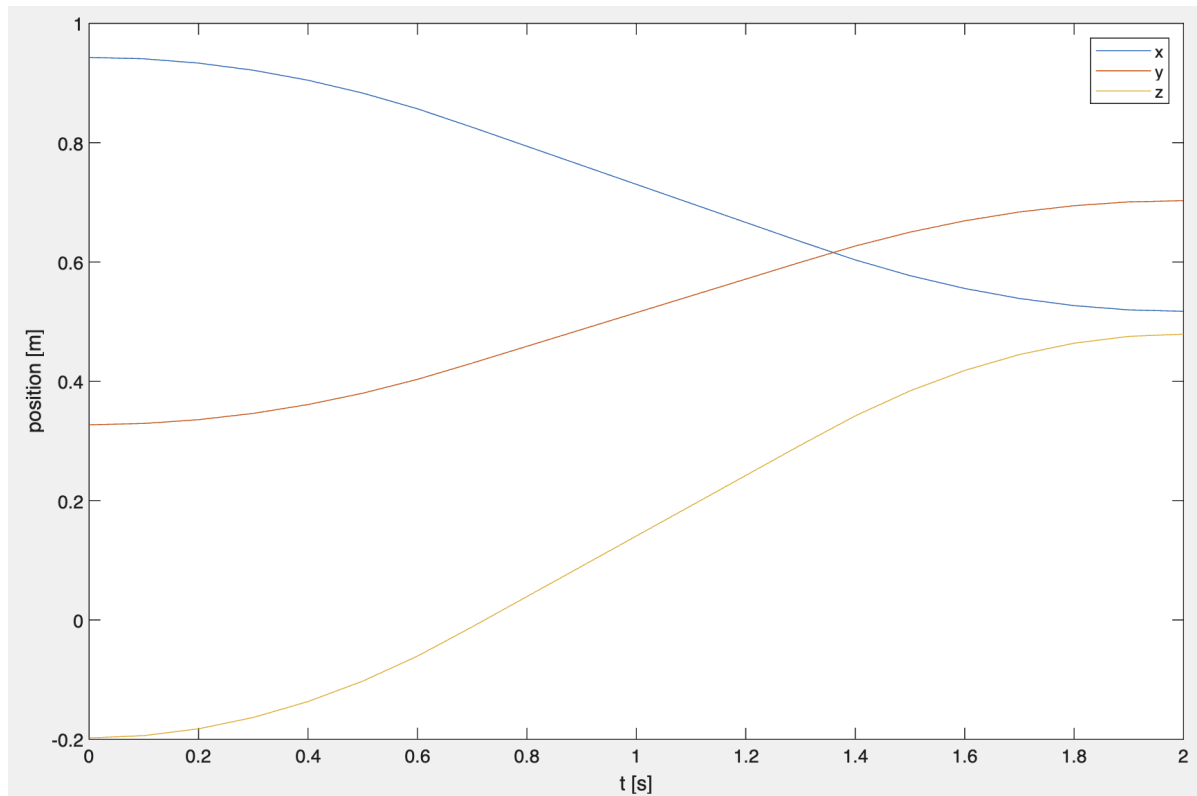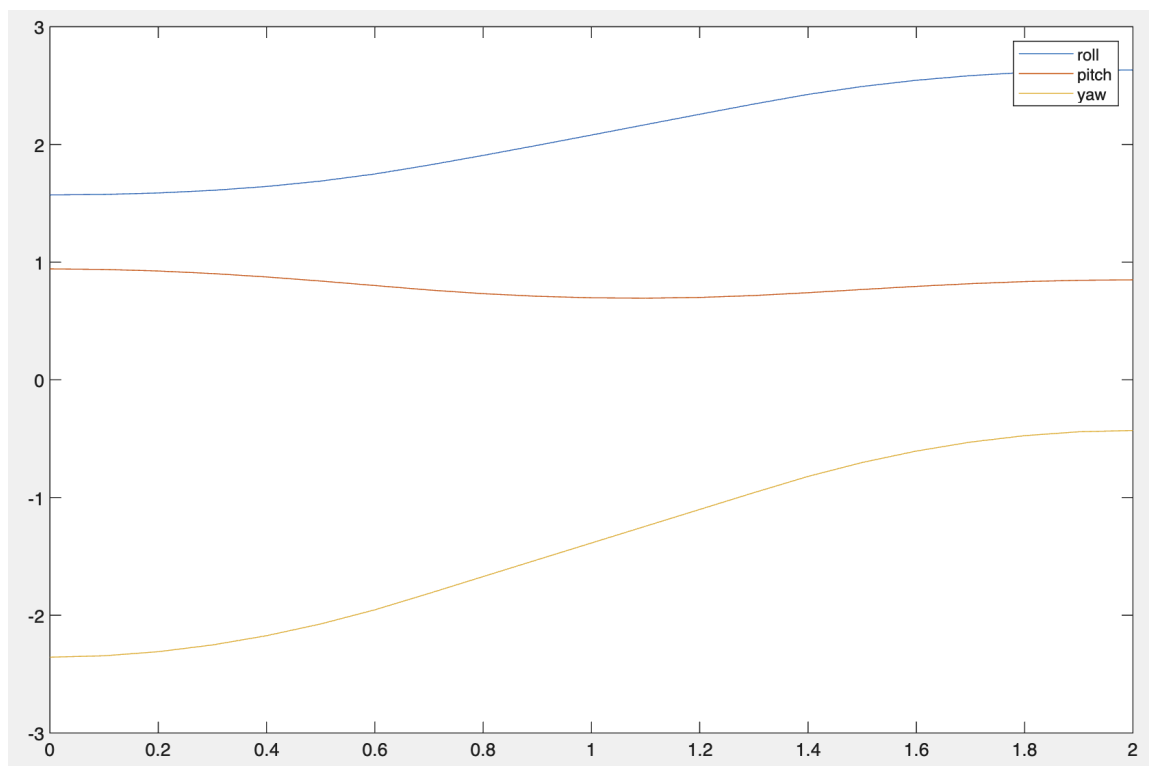| Teach	
x:	0.517
v:	0.703
z:	0.479
R:	150.8
P:	48.7
Y:	-24.7
q1	72.0
q2	-36.0
q3	36.0
q4	-36.0
q5	36.0
q6	-36.0
q7	36.0

Goal positions

joint coordinate trajectory

the end-effector's position versus time.

orientation of the end-effector. (`Ts.torpy('xyz')`)