

An Introduction to Multi-label Learning (ML-KNN & BP-MLL)

Bobby Lumpkin



1 Introduction to Multi-label Learning

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- Computing Model Probabilities
- Implementation (in scikit-multilearn)

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- Neural Network Loss Functions & Training for MLL
- Implementation (in TensorFlow/Keras)

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Why use novel approaches?

- Naive Approach: Train a sequence of independent binary classifiers (one per category)
- Doesn't capitalize on the information in the correlations between the different labels of each instance.

Multi-label Paradigm: Definitions & Notation

- Let \mathcal{X} denote the domain of instances and $\mathcal{Y} = \{1, \dots, Q\}$ be the finite set of labels.
- Given $x \in \mathcal{X}$ and its associated $Y \subseteq \mathcal{Y}$, let \vec{y}_x be the category vector for x such that (for all $\ell \in \mathcal{Y}$) $\vec{y}_x(\ell) = 1$ if $\ell \in Y$. Otherwise, $\vec{y}_x(\ell) = 0$.

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- Let H_0^ℓ denote the event that test instance t does not have a label ℓ and let H_1^ℓ denote the event that it does have label ℓ .

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- Let H_0^ℓ denote the event that test instance t does not have a label ℓ and let H_1^ℓ denote the event that it does have label ℓ .
- Let E_j^ℓ ($j \in \{1, \dots, K\}$) denote the event that, among the K nearest neighbors of t , there are exactly j instances which have label ℓ .

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$$\begin{aligned}\vec{y}_t(\ell) &= \operatorname{argmax}_{b \in \{0,1\}} \mathbb{P} \left(H_b^\ell | E_{\vec{C}_t(\ell)}^\ell \right), \quad \ell \in \mathcal{Y} \\ &= \operatorname{argmax}_{b \in \{0,1\}} \frac{\mathbb{P} \left(H_b^\ell \right) \cdot \mathbb{P} \left(E_{\vec{C}_t(\ell)}^\ell | H_b^\ell \right)}{\mathbb{P} \left(E_{\vec{C}_t(\ell)}^\ell \right)} \\ &= \operatorname{argmax}_{b \in \{0,1\}} \mathbb{P} \left(H_b^\ell \right) \cdot \mathbb{P} \left(E_{\vec{C}_t(\ell)}^\ell | H_b^\ell \right)\end{aligned}$$

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- Where we take a Bayesian approach towards estimating the prior probabilities, $\mathbb{P} \left(H_b^\ell \right)$, and conditional probabilities, $\mathbb{P} \left(E_{\vec{C}_t(\ell)}^\ell | H_b^\ell \right)$.

ML-KNN Algorithm: Overall Approach continued...

Definition: Let \vec{r}_t denote the real-valued vector with ℓ^{th} component:

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\Rightarrow Thus, given training data, \mathcal{X} , and a test instance, t , we wish to compute $[\vec{y}_t(\ell), \vec{r}_t(\ell)]$.

ML-KNN Algorithm: Computing the Prior Probabilities, $\widehat{\mathbb{P}}(H_b^\ell)$

We model $\mathbb{P}(H_1^\ell)$ with a $\text{Beta}(s, s)$ prior and $\text{Binomial}(m, \mathbb{P}(H_1^\ell))$ likelihood.
(When $s = 1$, $\text{Beta}(s, s)$ reduces to the uniform distribution on $[0, 1]$.)

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\Rightarrow The posterior distribution for $\mathbb{P}(\mathbf{H}_1^\ell)$ is:

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where m is the number of training instances.

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\Rightarrow We estimate $\widehat{\mathbb{P}}(H_0^\ell) := 1 - \widehat{\mathbb{P}}(H_1^\ell)$.

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- (i) Let c be a vector of length $K + 1$, where $c(j) =$ the number of training instances where $\vec{C}_{x_i}(\ell) = j$ when $\vec{y}_{x_i}(\ell) = 1$.

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- * We give $\overrightarrow{\mathbb{P}(E_j^\ell | H_1^\ell)}$ (and $\overrightarrow{\mathbb{P}(E_j^\ell | H_0^\ell)}$) a $\text{Dirichlet}(K + 1, (s, \dots, s))$ prior distribution.

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- * We use a $\text{Multinomial}(K + 1, (\frac{c(0)}{m_1}, \dots, \frac{c(K)}{m_1}))$ likelihood, where $m_1 = \sum_{i=1}^m \vec{y}_{x_i}(\ell)$ (analogously for $\overrightarrow{\mathbb{P}(E_j^\ell | H_0^\ell)}$).

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\Rightarrow The posterior distribution for $\overrightarrow{\mathbb{P}(E_j^\ell | H_1^\ell)}$ is

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$$\mathbb{P}(E_j^\ell | H_1^\ell) := \frac{(s + c(j))}{((K + 1)s + \sum_{n=0}^K c(n))}$$
$$\mathbb{P}(E_j^\ell | H_0^\ell) := \frac{(s + c'(j))}{((K + 1)s + \sum_{n=0}^K c'(n))}$$

Computing \vec{y}_t and \vec{r}_t

Using our previous derivation:

$$\widehat{\vec{y}_t(\ell)} := \operatorname{argmax}_{b \in \{0,1\}} \left[\widehat{\mathbb{P}(H_b^\ell)} \cdot \widehat{\mathbb{P}(E_{\vec{C}_T(\ell)}^\ell | H_b^\ell)} \right]$$

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NOTE: The larger the value for s , the less importance assigned to the training data: As $s \rightarrow \infty$, $\vec{r}_t(\ell) \rightarrow \frac{1}{2}$.

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→ MLkNN() from the scikit-multilearn module can be used to instantiate a ML-KNN object.

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from skmultilearn.adapt import MLkNN

classifier = MLkNN(k=3)

# train
classifier.fit(X_train, y_train)

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predictions = classifier.predict(X_test)
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ML-KNN Classification in scikit-multilearn:

- MLkNN() from the scikit-multilearn module can be used to instantiate a ML-KNN object.
- “MLkNN” class methods like “fit()” and “predict()” mirror those for standard scikit-learn objects.

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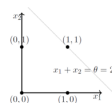
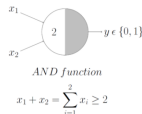
BP-MLL Approach

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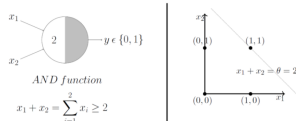
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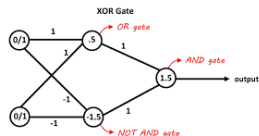
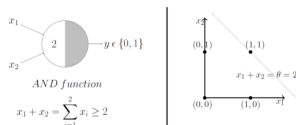
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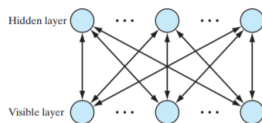
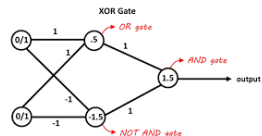
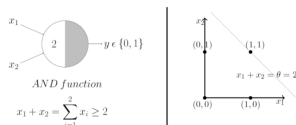
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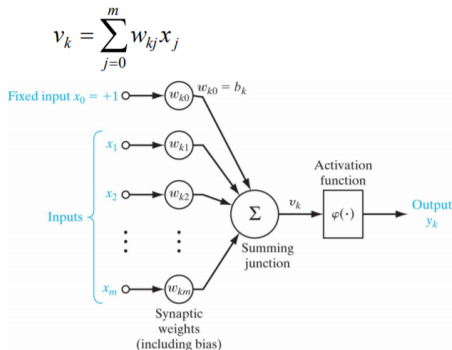
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- In the early 1980s, research on neural networks resurged largely due to successful learning algorithms for multi-layer neural networks and are used today for various tasks such as computer vision, associative memory, representation learning, NLP, etc..

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Introduction to Feed-forward Networks: Perceptron Model

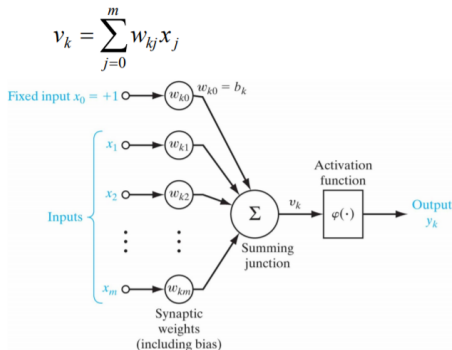
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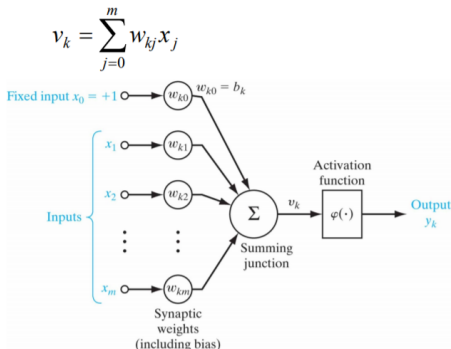
- Neurons in the first layer represent components of the input vectors.



Introduction to Feed-forward Networks: Perceptron Model

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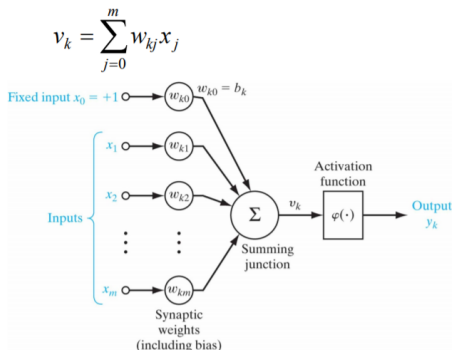
- Neurons in the first layer represent components of the input vectors.
- The output of the neuron in the next layer is determined by applying a non-linear “activation function” to a linear combination of the input components, plus a bias.



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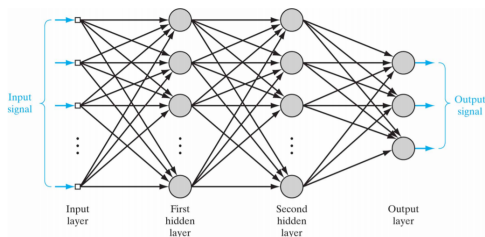
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- The output of the neuron in the next layer is determined by applying a non-linear “activation function” to a linear combination of the input components, plus a bias.
- Rosenblatt’s Perceptron model uses a step function non-linearity, but other common activation functions include the sigmoid function ($\sigma()$), $\tanh()$, ReLU, Leaky ReLU, softmax, etc..



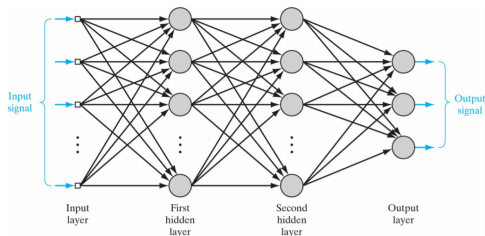
Multilayer Networks & Training

- Adding additional layers and units (like in the network pictured below) significantly expands the class of discrimination problems a network can learn.



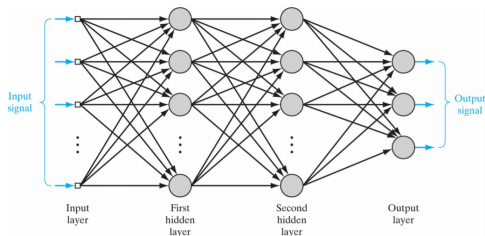
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- “Online” training involves evaluating an instance, and updating weights using gradient descent.
- For multi-label learning with Q instances, networks will have Q output layers, each with a $\tanh()$ activation.



Designing a Cost Function

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Naive Approach (“BasicBP”):

- Standard MSE:

$$E = \sum_{i=1}^m E_i = \sum_{i=1}^m \sum_{j=1}^q (c_j^i - d_j^i)^2$$

where $c_j^i = c_j(x_i)$ is the output of the network on x_i on the j^{th} class.

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- BP-MLL Cost function:

$$E = \sum_{i=1}^m E_i = \sum_{i=1}^m \frac{1}{|Y_i| |\bar{Y}_i|} \sum_{(k,l) \in Y_i \times \bar{Y}_i} \exp(-(c_k^i - c_l^i))$$

so that the i^{th} error term is severely penalized if c_k^i is much smaller than c_l^i .

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- Back-propagation for training is derived just as in the standard (MSE) case (details omitted here, but can be found in Zhang and Zhou's paper).

Deep Learning APIs in Python: TensorFlow/Keras

TensorFlow: an open source python library for numerical computation and large-scale machine learning, created by the Google Brain team.

- One of the most widely used APIs for deep learning, along with PyTorch and Keras.
- Later versions of TensorFlow began incorporating the Keras API, since users found its high-level design to be simpler.

```
import tensorflow as tf
mnist = tf.keras.datasets.mnist

(x_train, y_train), (x_test, y_test) = mnist.load_data()
x_train, x_test = x_train / 255.0, x_test / 255.0

model = tf.keras.models.Sequential([
    tf.keras.layers.Flatten(),
    tf.keras.layers.Dense(512, activation=tf.nn.relu),
    tf.keras.layers.Dropout(0.2),
    tf.keras.layers.Dense(10, activation=tf.nn.softmax)
])
model.compile(optimizer='adam',
              loss='sparse_categorical_crossentropy',
              metrics=['accuracy'])

model.fit(x_train, y_train, epochs=5)
model.evaluate(x_test, y_test)
```

TensorFlow Implementation of BP-MLL

BP-MLL in TensorFlow:

- Data Scientist, Lukas Huwald, published an implementation of the bp-mlm cost function for the TensorFlow API as part of the module “bpmll”.
- After installation, the bp-mlm loss function can be utilized just as any other TensorFlow loss function.

```
# create simple mlp
model = Sequential()
model.add(Dense(128, input_dim=dim_no, activation='relu', kernel_initializer='glorot_uniform'))
model.add(Dense(64, activation='relu', kernel_initializer='glorot_uniform'))
model.add(Dense(class_no, activation='sigmoid', kernel_initializer='glorot_uniform'))
model.compile(loss=bp_mll_loss, optimizer='adagrad', metrics=[])

# train a few epochs
model.fit(X_train, Y_train, epochs=100)
```


References (Original Method Papers)

- Min-Ling Zhang and Zhi-Hua Zhou. MI-knn: A lazy learning approach to multi-label learning. *Pattern Recognition*, 40(7):2038–2048, 2007. doi: 10.1016/j.patcog.2006.12.019.
- Min-Ling Zhang and Zhi-Hua Zhou. Multilabel neural networks with applications to functional genomics and text categorization. *IEEE Transactions on Knowledge and Data Engineering*, 18(10):1338–1351, 2006. doi: doi:10.1109/TKDE.2006.162.