IPA robot and ipa-apartment manual

Manual for working with robots in the ipa-apartment

Autors: Florian Weisshardt Nadia Hammoudeh Garcia

Fraunhofer IPA

Institute for Manufacturing Engineering and Automation Stuttgart, Germany

Last modified on Wednesday $9^{\rm th}$ May, 2012

Contents

ii CONTENTS

1	IPA	apart	ment ru	des	2
	1.1	Working in the robot area			2
		1.1.1	Don't cl	hange any cabling	2
		1.1.2	Using yo	our own pc	2
			1.1.2.1	Don't use the plugs under the tables	2
			1.1.2.2	Use the plugs on the tables	3
			1.1.2.3	Don't disconnect to the pool pc monitors, mouse and keyboard	3
		1.1.3	Leaving	the robot area \dots	3
			1.1.3.1	Move all furniture back	3
			1.1.3.2	Tidy up working places	3
			1.1.3.3	Unplug additional network and power cables	3
			1.1.3.4	Logout your user from pool pcs	3
			1.1.3.5	Turn off the monitors	4
	1.2	Worki	ng on the	e student side	4
		1.2.1 Leaving your work place		your work place	4
			1.2.1.1	Tidy up working places	4
		1.2.2	Leaving	the room as the last person	4
			1.2.2.1	Close the windows	4
			1.2.2.2	Turn off the lights	4
	1.3	Worki	ng with p	pool pcs	5
		1.3.1	Using p	ool pcs	5
			1.3.1.1	Do not store huge data on home directory	5
		1.3.2	Finished	l working with pool pcs	5
			1.3.2.1	Don't turn off the pcs	5
			1.3.2.2	Turn off the monitors	5

C0	ONTE	ENTS			iii
	1.4	Floor	plan		5
2	IPA	robot	rules		6
	2.1	Robot	cob3-3 aı	nd cob3-5	6
		2.1.1	Working	with the robots	6
			2.1.1.1	Allocate a robot	6
			2.1.1.2	Pay attention to the safety and usage information	6
		2.1.2	Having a break		6
			2.1.2.1	Press the emergency button	7
		2.1.3	Leaving	the robot	7
			2.1.3.1	Mount all casings	7
			2.1.3.2	Move components in home position	7
			2.1.3.3	Move robot to charging station	7
			2.1.3.4	Disconnect power	7
			2.1.3.5	Charge the remote emergency stop	8
	2.2	Robot	raw3-1 .		8
		2.2.1	Leaving	the robot	8

About this manual

You can always get the latest version of this manual at ¹.

If you have comments, suggestions or would like to add something to the manual, please contact fmw@ipa.fng.de.

¹https://github.com/ipa320/setup/blob/master/manual/IPA_manual.pdf

Chapter 1

IPA apartment rules

1.1 Working in the robot area

The robot area is considered the left side of the room after entering from the main door.

1.1.1 Don't change any cabling

You should not add, remove or change any cabling. Especially all cables below the tables should not be touched at all because they are ordered in a way that power distribution and network distribution is optimized. Cabling includes power, network, monitors, keyboards and mouse. If you feel the need for changing anything, please contact fmw@ipa.fhg.de or nhg@ipa.fhg.de.

1.1.2 Using your own pc

You can use your own pc and connect to the network. Using the network plugs you should get an IP address over DHCP and connect to the internet.

1.1.2.1 Don't use the plugs under the tables

See section 1.1.1

1.1.2.2 Use the plugs on the tables

If you want to connect to power or network use the power and network plugs on the table. You can find additional power and network cables in cabinet III, see section 1.4. Please put them back when you leave the room.

1.1.2.3 Don't disconnect to the pool pc monitors, mouse and keyboard

If you need a monitor, mouse or keyboard for your laptop, please use the ones out of cabinet III, see section 1.4. Don't disconnect one of the pool pc monitors.

1.1.3 Leaving the robot area

1.1.3.1 Move all furniture back

Please move all tables, chairs and cupboards back to their default place. The default place for all objects can be found in the floor plan of section 1.4.

1.1.3.2 Tidy up working places

Please remove everything from the tables of cob-stud-6 to cob-stud-9. There should be nothing left on the tables except monitors, keyboard, mouse and telephone. Remove everything else, like coffee cups, bottles, paper, ...

1.1.3.3 Unplug additional network and power cables

Please unplug everything you plunged in on the tables and put the cables back to cabinet III, see section 1.4.

1.1.3.4 Logout your user from pool pcs

See section 1.3.2.1.

1.1.3.5 Turn off the monitors

See section 1.3.2.2.

1.2 Working on the student side

The student side is considered the right side of the room behind the cupboards after entering from the main door.

1.2.1 Leaving your work place

1.2.1.1 Tidy up working places

See section 1.1.3.2. Use your student storage shelf to store your personal belongings.

1.2.2 Leaving the room as the last person

If nobody else is in the room any more, which means robot and student side, please follow the following additional rules. You are probably the last one if you leave later than 6pm in the evening.

1.2.2.1 Close the windows

Please close all windows on both sides of the room.

1.2.2.2 Turn off the lights

Turn off all lights on both sides of the room.

5

1.3 Working with pool pcs

The pool pcs have a fixed configuration and the installed packages should all be the same on all machines. If you need an account, a new installation of packages or software in the pcs please contact nhg@ipa.fhg.de or fmw@ipa.fhg.de.

1.3.1 Using pool pcs

1.3.1.1 Do not store huge data on home directory

The home directory should only be used for code which is important and needs to be backuped. If you have big data files (like images, bag-files, etc.), please store them localy on the machines in /share. Therefore create a folder with your shortname, e.g. /share/fmw.

1.3.2 Finished working with pool pcs

1.3.2.1 Don't turn off the pcs

After finishing your work please log off so that other users can use the pc. You should not login in into two machines at the same time to avoid problems.

The pcs are used remotely during daytime, the night and the weekend, so please just log out and don't turn them off.

1.3.2.2 Turn off the monitors

see 1.3.2.2 To safe energy please turn off the monitor after using it but keep the pool pcs on, see section 1.3.2.1.

1.4 Floor plan

TODO: add floor plan for robot area and student side

Chapter 2

IPA robot rules

2.1 Robot cob3-3 and cob3-5

2.1.1 Working with the robots

2.1.1.1 Allocate a robot

Allocate a robot for you, see ¹.

2.1.1.2 Pay attention to the safety and usage information

For safety and usage information, see Care-O-bot manual².

2.1.2 Having a break

A break is considered a short interruption, e.g. for lunch time or toilet break, where the robot is still allocated for you and you will continue working with the robot afterwards.

¹http://care-o-bot.org/trac/wiki/WorkingWithIPARobots

²https://github.com/ipa320/setup/raw/master/manual/Care-O-bot_manual.pdf

2.1. ROBOT COB3-3 AND COB3-5

7

2.1.2.1Press the emergency button

Whenever you are out of reach of the emergency stop, e.g. leaving the room,

press one of the emergency buttons.

2.1.3Leaving the robot

2.1.3.1Mount all casings

Mount all casings of the robot which means green and grey parts from base and

head casing.

2.1.3.2Move components in home position

When finishing your work with the robot, leave the robot components in their

default position. The default position is

• Arm in "folded" position

• Torso in "home" position

• Tray in "down" position

• Hand in "home" position

TODO: ADD IMAGE

2.1.3.3Move robot to charging station

When finishing your work with the robot, leave it next to the charging station

which is the "home" position for the navigation.

TODO: ADD IMAGE

2.1.3.4Disconnect power

Unply the power cable and shut down the power supply.

2.1.3.5 Charge the remote emergency stop

When finishing your work with the robot, put the remote emergency stop into its charging station.

2.2 Robot raw3-1

2.2.1 Leaving the robot

disconnect power