Householder: A=QR; Q-ortogordie R-sep, triunghisdore Besid r: Resid r:

$$P_{m-1} \cdot P_{m-2} \cdots P_1 \Delta = \widehat{Q} \Delta = R$$

$$\widehat{Q} = P_{m-1} \cdot P_{m-2} \cdots P_1$$

Exercitin. Soi se colculere descompunera a R a motricii sistemului utilizand metoda Householden.

$$A = \begin{pmatrix} 4 & 4 & 1 \\ 0 & 10 & -5 \\ 3 & 3 & 7 \end{pmatrix} \qquad \mathcal{L} = \begin{pmatrix} 12 \\ 12 \\ 5 \end{pmatrix}$$

$$u = \begin{pmatrix} \alpha_{11} - k \\ \alpha_{21} \\ \alpha_{21} \end{pmatrix} \quad 2 \quad \begin{pmatrix} 3 \\ 0 \\ 3 \end{pmatrix}$$

$$u = \begin{pmatrix} \alpha_{11} - 4 \\ \alpha_{21} \end{pmatrix} \quad 2 \begin{pmatrix} 9 \\ 0 \\ 3 \end{pmatrix} \qquad \frac{1}{\beta} \quad \mu \quad \mu^{T} = \begin{pmatrix} 1.8 & 0 & 0.6 \\ 0 & 0 & 0 \\ 0.6 & 0 & 0.2 \end{pmatrix}$$

$$P_1 = \frac{1}{3} - \frac{1}{\beta} \cdot u u^7 = \begin{pmatrix} -0.8 & 0 & -0.6 \\ 0 & 1 & 0 \\ -0.6 & 0 & 0.8 \end{pmatrix}$$

$$\Delta = P_1 \Delta = \begin{pmatrix} -5 & -5 & -5 \\ 0 & 10 & -5 \\ 0 & 0 & 5 \end{pmatrix}$$

Perul 2

$$R = P_2 + (P_1 + A) = A^{m-1}(A & base la ullime iterative)$$

$$Q^T = P_2 + P_1 = P_1 \quad (pentru e a em soriel & perul 2)$$

· Soum putem variable sistemul prin substitute in nerso ex=aTL