

SG. 6

**S6.6** Fie  $T_1 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  endomorfismul care, în raport cu baza alcătuită din  $b_1 = (1, -1)$  și  $b_2 = (0, 1)$ , are matricea

$$A^{T_1} = \begin{bmatrix} 3 & 1 \\ -1 & 3 \end{bmatrix}.$$

De asemenea, fie  $T_2 : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  un endomorfism care, față de vectorii  $v_1 = (2, 1)$  și  $v_2 = (-1, 1)$ , are matricea

$$A^{T_2} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}.$$

Să se determine matricea endomorfismului  $T_2 \circ T_1$  în raport cu sistemul de vectori  $\{v_1, v_2\}$ , precum și matricea lui  $T_2 \circ T_1$  față de baza canonică a lui  $\mathbb{R}^2$ .

Verificăm că  $v_1, v_2$  formează bază

card  $B' = \dim \mathbb{R}^2$

$\Rightarrow$  Pt a verif că  $B'$  bază e suficient

să verif  $\det [v_1, v_2] \neq 0$

$$\begin{vmatrix} 2 & -1 \\ 1 & 1 \end{vmatrix} = 3 \neq 0$$

$\mathbb{R}^2$

$\mathbb{R}^2$

$T_2 \circ T_1$  în raport cu  $B'$

$C \longrightarrow C$

$\Rightarrow$  Vrem să exprimăm

$B \xrightarrow{T_1} B$

$T_1$  în raport cu  $B'$ .

$B' \xrightarrow{T_2} B'$

$$S_{B|B'} = (S_{C|B})^{-1} \cdot S_{C|B'}$$

$$(S_{C|B'})^{-1} = ?$$

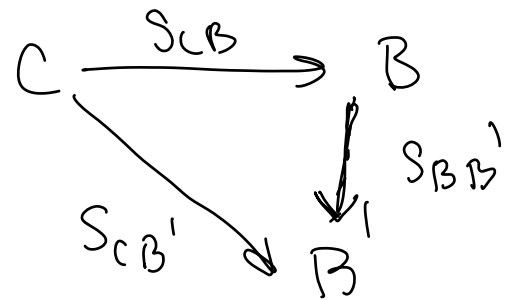
$$S_{C|B'} = \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix}$$

$$(S_{C|B'})^{-1} = \frac{1}{3} \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix}$$

$$S_{B'|B} = \frac{1}{3} \begin{pmatrix} 0 & 1 \\ -3 & 2 \end{pmatrix} \quad \left| \quad S_{B|B'} = (S_{B'|B})^{-1} = \begin{pmatrix} 2 & -1 \\ 3 & 0 \end{pmatrix} \right.$$

$$A_{B'}^{T_1} = (S_{B|B'})^{-1} \cdot A^{T_1} \cdot S_{B|B'}$$

$$\begin{aligned} A_{B'}^{T_1} &= \frac{1}{3} \begin{pmatrix} 0 & 1 \\ -3 & 2 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 3 & 0 \end{pmatrix} \\ &= \frac{1}{3} \begin{pmatrix} -1 & 3 \\ -11 & 3 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 3 & 0 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 7 & 1 \\ -13 & 11 \end{pmatrix} \end{aligned}$$



$$S_{C|B} \cdot S_{B|B'} = S_{C|B'}$$

$$S_{B|B'} = (S_{C|B})^{-1} S_{C|B'}$$

$$S_{B|B'} = (S_{B'|B})^{-1}$$

$$A_{B'}^{T_2-T_1} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} - \frac{1}{3} \begin{pmatrix} 7 & 1 \\ -13 & 11 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} -1 & 2 \\ 16 & -8 \end{pmatrix}$$

$$A_B^{T_1} = \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix} = S_{CB}^{-1} \cdot A_C^{T_1} \cdot S_{CB}$$

$$A_C^{T_1} = S_{CB} \cdot A_B^{T_1} \cdot (S_{CB})^{-1}$$

$$S_{CB} = \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix}$$

$$(S_{CB})^{-1} = \begin{pmatrix} 1 & 0 & | & 1 & 0 \\ -1 & 1 & | & 0 & 1 \end{pmatrix} \xrightarrow{L_2 = L_2 + L_1} \begin{pmatrix} 1 & 0 & | & 1 & 0 \\ 0 & 1 & | & 1 & 1 \end{pmatrix}$$

$$(S_{CB})^{-1} = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}$$

$$A_{\mathcal{C}}^{T_1} = \begin{pmatrix} 1 & 0 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} =$$

$$\begin{pmatrix} 3 & 1 \\ -4 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix}$$

$$A_{\mathcal{C}}^{T_2} = S_{\mathcal{C}|\mathcal{B}'} \cdot A_{\mathcal{B}'}^{T_2} \cdot (S_{\mathcal{C}|\mathcal{B}'})^{-1}$$

$$S_{\mathcal{C}|\mathcal{B}'} = \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix}$$

$$(S_{\mathcal{C}|\mathcal{B}'})^{-1} = \frac{1}{3} \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix}$$

$$A_{\mathcal{B}'}^{T_2} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

$$A_{\mathcal{C}}^{T_2} = \frac{1}{3} \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix} =$$

$$\frac{1}{3} \begin{pmatrix} 3 & 1 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix} =$$

$$\frac{1}{3} \begin{pmatrix} 2 & 5 \\ 1 & 7 \end{pmatrix}$$

$$A_{C}^{T_2 - T_1} = \frac{1}{3} \begin{pmatrix} 2 & 5 \\ 1 & 7 \end{pmatrix} - \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix} =$$

$$\begin{pmatrix} -\frac{10}{3} & \frac{2}{3} \\ \frac{7}{3} & \frac{1}{3} \end{pmatrix}$$

$$\begin{aligned} A_{B'}^{T_2 - T_1} &= (S_{C|B'})^{-1} \cdot A_{C}^{T_2 - T_1} \cdot S_{C|B'} \\ &= \frac{1}{3} \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix} \cdot \begin{pmatrix} -\frac{10}{3} & \frac{2}{3} \\ \frac{7}{3} & \frac{1}{3} \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix} \end{aligned}$$

$$= \frac{1}{9} \begin{pmatrix} 1 & 1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} -10 & 2 \\ 7 & 1 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix} =$$

$$\frac{1}{9} \begin{pmatrix} -3 & 3 \\ 24 & 0 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix} =$$

$$\frac{1}{3} \begin{pmatrix} -1 & 1 \\ 8 & 0 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 1 & 1 \end{pmatrix} =$$

$$\frac{1}{3} \begin{pmatrix} -1 & 2 \\ 16 & -8 \end{pmatrix}$$

$$A_c^{T_2 \circ T_1} = A_c^{T_2} \cdot A_c^{T_1} =$$

$$\frac{1}{3} \begin{pmatrix} 2 & 1 \\ 5 & 7 \end{pmatrix} \cdot \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix}$$

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$$\begin{matrix} & A_c & A_B \\ - & & \end{matrix}$$

$$A_B = (S_{C|B})^{-1} \cdot A_c \cdot S_{C|B} \mid (S_{C|B})^{-1}$$

Met I

$$S_{C|B} \mid A_B \cdot (S_{C|B})^{-1} = (S_{C|B})^{-1} \cdot A_c$$

$$S_{C|B} \cdot A_B \cdot (S_{C|B})^{-1} = A_c$$

Met II

$$A_c = (S_{B|C})^{-1} \cdot A_B \cdot S_{B|C}$$

$$(S_{B|C})^{-1} = S_{C|B}$$

$$A_c = S_{C|B} \cdot A_B \cdot (S_{C|B})^{-1}$$

$$T_1(x_1, x_2, x_3, x_4) = (x_1 + x_2 + x_3 + x_4, x_1 + x_2 - x_3 - x_4, x_1 - x_2 + x_3 - x_4, x_1 - x_2 - x_3 + x_4),$$

$$\forall (x_1, x_2, x_3, x_4) \in \mathbb{R}^4$$

și

$$T_2(x_1, x_2, x_3) = (2x_1 + x_2 + x_3, 2x_1 + 3x_2 + x_3, 3x_1 + 3x_2 + 4x_3), \forall (x_1, x_2, x_3) \in \mathbb{R}^3$$

- Să se afle valorile proprii și vectorii proprii corespunzători;
- Să se afle subspațiile proprii și dimensiunile lor;
- Să se analizeze posibilitatea diagonalizării lui  $T_1$  și  $T_2$ . În caz afirmativ, să se afle baza în care se manifestă forma diagonală, matricea schimbării de bază în cauză, precum și forma diagonală ca atare.

( $T_1$ )

1. Matricea operatorului

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & 1 & -1 \\ 1 & -1 & -1 & 1 \end{pmatrix}$$

2. Polinomul caracteristic

$$\det(A - \lambda I_4) = \begin{vmatrix} 1-\lambda & 1 & 1 & 1 \\ 1 & 1-\lambda & -1 & -1 \\ 1 & -1 & 1-\lambda & -1 \\ 1 & -1 & -1 & 1-\lambda \end{vmatrix}$$



$$(1-\lambda) \cdot (-1)^{1+1} \begin{vmatrix} 1-\lambda & -1 & -1 \\ -1 & 1-\lambda & -1 \\ -1 & -1 & 1-\lambda \end{vmatrix} +$$

$$1 \cdot (-1)^{1+2} \begin{vmatrix} 1 & 1 & 1 \\ -1 & 1-\lambda & -1 \\ -1 & -1 & 1-\lambda \end{vmatrix} +$$

$$1 \cdot (-1)^{1+3} \begin{vmatrix} 1 & 1 & 1 \\ 1-\lambda & -1 & -1 \\ -1 & -1 & 1-\lambda \end{vmatrix} +$$

$$1 \cdot (-1)^{1+4} \begin{vmatrix} 1 & 1 & 1 \\ 1-\lambda & -1 & -1 \\ -1 & 1-\lambda & -1 \end{vmatrix}$$

$$\det(A - \lambda I_4) = \begin{vmatrix} 1-\lambda & 1 & 1 & 1 \\ 1 & 1-\lambda & -1 & -1 \\ 1 & -1 & 1-\lambda & -1 \\ 1 & -1 & -1 & 1-\lambda \end{vmatrix} \begin{cases} L_2 = L_2 + L_1 \\ L_4 = L_4 - L_3 \end{cases}$$

$$\begin{vmatrix} 1-\lambda & 1 & 1 & 1 \\ 2-\lambda & 2-\lambda & 0 & 0 \\ 1 & -1 & 1-\lambda & -1 \\ 0 & 0 & -2+\lambda & 2-\lambda \end{vmatrix} = -1 - 1 + \lambda$$

$$(2-\lambda) \begin{vmatrix} 1-\lambda & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & -1 & 1-\lambda & -1 \\ 0 & 0 & -2+\lambda & 2-\lambda \end{vmatrix} \begin{cases} C_1 = C_1 - C_2 \end{cases}$$

$$(2-\lambda) \begin{vmatrix} -\lambda & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 2 & -1 & 1-\lambda & -1 \\ 0 & 0 & -2+\lambda & 2-\lambda \end{vmatrix} =$$

$$(2-\lambda) \cdot (-1)^{2+2} \begin{vmatrix} -\lambda & 1 & 1 \\ 2 & 1-\lambda & -1 \\ 0 & -2+\lambda & 2-\lambda \end{vmatrix} =$$

$$(2-\lambda)^2 \begin{vmatrix} -\lambda & 1 & 1 \\ 2 & 1-\lambda & -1 \\ 0 & -1 & 1 \end{vmatrix} \quad \underline{\underline{C_2 = C_2 + C_3}}$$

$$(2-\lambda)^2 \begin{vmatrix} -\lambda & 2 & 1 \\ 2 & -\lambda & -1 \\ 0 & 0 & 1 \end{vmatrix} =$$

$$(2-\lambda)^2 \begin{vmatrix} -\lambda & 2 \\ 2 & -\lambda \end{vmatrix} =$$

$$(2-\lambda)^2 (\lambda^2 - 4) =$$

$$(\lambda - 2)^3 (\lambda + 2)$$

3. Valori propriu

$$\lambda_1 = 2 \quad m_{\lambda_1} = 3$$

$$\lambda_2 = -2 \quad m_{\lambda_2} = 1$$

4. Subspații propriu

$$\lambda_1 = 2$$

$$(A - 2I_4) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1-2 & 1 & 1 & 1 \\ 1 & 1-2 & -1 & -1 \\ 1 & -1 & 1-2 & -1 \\ 1 & -1 & -1 & 1-2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 1 & 1 & 1 \\ 1 & -1 & -1 & -1 \\ 1 & -1 & -1 & -1 \\ 1 & -1 & -1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$S L_1 = L_1$$

$$\begin{pmatrix} 1 & -1 & -1 & -1 \\ 1 & -1 & -1 & -1 \\ 1 & -1 & -1 & -1 \\ 1 & -1 & -1 & -1 \end{pmatrix}$$

$$\Rightarrow \text{rang}(A - 2I_4) = 1$$

$$\Delta = \begin{vmatrix} 1 \\ 1 \\ 1 \\ 1 \end{vmatrix} \neq 0$$

Nec pp  $x_1$

Nec nec  $x_2 = \alpha$   $x_3 = \beta$   $x_4 = \gamma$

$$-x_1 + x_2 + x_3 + x_4 = 0$$

$$x_1 = \alpha + \beta + \gamma$$

$$V_{\lambda_1} = \left\{ (\alpha + \beta + \gamma, \alpha, \beta, \gamma) \mid \alpha, \beta, \gamma \in \mathbb{R} \right\}$$

$$\dim V_{\lambda_1} = 3$$

$$v_{\lambda_1}^1 \xrightarrow[\beta = \gamma = 0]{\alpha = 1} (1, 1, 0, 0)$$

$$v_{\lambda_1}^2 \xrightarrow[\alpha = \gamma = 0]{\beta = 1} (1, 0, 1, 0)$$

$$v_{\lambda_1}^3 \xrightarrow[\alpha = \beta = 0]{\gamma = 1} (1, 0, 0, 1)$$

$$B_{\lambda_1} = \{v_{\lambda_1}^1, v_{\lambda_1}^2, v_{\lambda_1}^3\}$$

$$\lambda_2 = -2$$

$$(A + 2I_2) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1+2 & 1 & 1 & 1 \\ 1 & 1+2 & -1 & -1 \\ 1 & -1 & 1+2 & -1 \\ 1 & -1 & -1 & 1+2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 1 & 1 & 1 \\ 1 & 3 & -1 & -1 \\ 1 & -1 & 3 & -1 \\ 1 & -1 & -1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$\det = 0$

$$\begin{pmatrix} 3 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{pmatrix} \quad \begin{matrix} L_1 = L_1 + L_2 + L_3 \\ \hline \hline \end{matrix}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{pmatrix} \quad \begin{matrix} R_1 = R_1 - R_2 \\ \hline \hline \end{matrix}$$

$$\begin{vmatrix} 0 & 1 & 1 \\ -4 & 3 & -1 \\ 0 & -1 & 3 \end{vmatrix} = 4 \begin{vmatrix} 1 & 1 \\ -1 & 3 \end{vmatrix} =$$

$$16 \neq 0$$

$x_1$  free var

$x_1 = \alpha$        $x_2, x_3, x_4$  free var

$$\begin{pmatrix} 3 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -\alpha \\ -\alpha \\ -\alpha \end{pmatrix} \quad \begin{matrix} L_1 = L_1 + L_2 \\ + L_3 \end{matrix}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -3\alpha \\ -\alpha \\ -\alpha \end{pmatrix}$$

$$\begin{array}{l} L_2 = L_2 + L_1 \\ L_3 = L_3 + L_1 \end{array}$$



$$\begin{pmatrix} 1 & 1 & 1 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -3\alpha \\ -4\alpha \\ -4\alpha \end{pmatrix}$$

$$4x_3 = -4\alpha \rightarrow x_3 = -\alpha$$

$$4x_4 = -4\alpha \rightarrow x_4 = -\alpha$$

$$x_2 + x_3 + x_4 = -3\alpha \rightarrow x_2 = -\alpha$$

$$V_{\lambda_2} = \{ (\alpha, -\alpha, -\alpha, -\alpha) \mid \alpha \in \mathbb{R} \}$$

$$v_{\lambda_2} = (1, -1, -1, -1)$$

5. Este diag?

$$m_{\lambda_1} + m_{\lambda_2} = \dim \mathbb{R}_4?$$

$$3 + 1 = 4$$



$$\underline{m_{\lambda_1}} = \dim V_{\lambda_1}?$$

$$3 = 3 \checkmark$$

$$m_{\lambda_2} = \dim V_{\lambda_2}?$$

$$1 = 1 \checkmark$$

→ Este diag?

$$A_D = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & -2 \end{pmatrix}$$

$$A_D = \begin{pmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_1 & \\ & & & \lambda_2 \end{pmatrix}$$

$$\vec{D} = \left\{ (1, 1, 0, 0), (1, 0, 1, 0), \right. \\ \left. (1, 0, 0, 1), (1, -1, -1, -1) \right\}$$


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$$A_D = (S_{CD})^{-1} \cdot A \cdot S_{CD}$$

$$S_{CD} = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & -1 \end{pmatrix}$$

$$T_2(x_1, x_2, x_3) = (2x_1 + x_2 + x_3, 2x_1 + 3x_2 + x_3, 3x_1 + 3x_2 + 4x_3), \forall (x_1, x_2, x_3) \in \mathbb{R}^3$$

$$1. \quad A = \begin{pmatrix} 2 & 1 & 1 \\ 2 & 3 & 1 \\ 3 & 3 & 4 \end{pmatrix}$$

$$2. \quad \left| \begin{array}{ccc|c} 2-\lambda & 1 & 1 & \\ 2 & 3-\lambda & 1 & \\ 3 & 3 & 4-\lambda & \end{array} \right| \quad \underline{\underline{C_1 = C_1 - C_2}}$$

$$\left| \begin{array}{ccc|c} 1-\lambda & 1 & 1 & \\ -1+\lambda & 3-\lambda & 1 & \\ 0 & 3 & 4-\lambda & \end{array} \right| =$$

$$(1-\lambda) \begin{vmatrix} 1 & 1 & 1 \\ -1 & 3-\lambda & 1 \\ 0 & 3 & 4-\lambda \end{vmatrix} \quad \underline{\underline{L_2 = L_2 + L_1}}$$

$$(1-\lambda) \begin{vmatrix} 1 & 1 & 1 \\ 0 & 4-\lambda & 2 \\ 0 & 3 & 4-\lambda \end{vmatrix} =$$

$$(1-\lambda) \begin{vmatrix} 4-\lambda & 2 \\ 3 & 4-\lambda \end{vmatrix} =$$

$$(1-\lambda) \left( (4-\lambda)^2 - 6 \right) =$$

$$(1-\lambda) (\lambda^2 - 8\lambda + 16 - 6)$$

$$(1-\lambda) (\lambda^2 - 8\lambda + 10)$$

$$\lambda^2 - 8\lambda + 10 = 0$$

$$3. \quad \lambda_{1,2} = \frac{8 \pm \sqrt{64 - 40}}{2}$$

$$\lambda_{1,2} = \frac{8 \pm \sqrt{24}}{2} =$$

$$\frac{8 \pm 2\sqrt{6}}{2} = 4 \pm \sqrt{6}$$

$$\lambda_1 = 4 - \sqrt{6} \quad m_{\lambda_1} = 1$$

$$\lambda_2 = 4 + \sqrt{6} \quad m_{\lambda_2} = 1$$

$$4. \quad \lambda_3 = 1 \quad m_{\lambda_3} = 1$$

$$V_{\lambda_1} \begin{pmatrix} 2 - 4 + \sqrt{6} & 1 & 1 \\ 2 & 3 - 4 + \sqrt{6} & 1 \\ 3 & 3 & 4 - 4 + \sqrt{6} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -2+\sqrt{6} & 1 & 1 \\ 2 & -1+\sqrt{6} & 1 \\ 3 & 3 & \sqrt{6} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$x_1 = \alpha \text{ free var}$$

$$\begin{pmatrix} 1 & 1 \\ -1+\sqrt{6} & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} = \alpha \begin{pmatrix} 2-\sqrt{6} \\ -2 \end{pmatrix}$$

$$x_2 + x_3 = (2-\sqrt{6})\alpha$$

$$(-1+\sqrt{6})x_2 + x_3 = -2\alpha \quad \text{---}$$

$$(2-\sqrt{6}) \cdot x_2 = (4-\sqrt{6})\alpha$$

$$x_2 = \frac{4-\sqrt{6}}{2-\sqrt{6}} \alpha$$

$$x_2 = \frac{8+4\sqrt{6}-2\sqrt{6}-6}{-2} \alpha$$

$$x_2 = \frac{2 + 2\sqrt{6}}{-2} \alpha$$

$$x_2 = (-1 - \sqrt{6}) \alpha$$

$$x_3 = (2 - \cancel{\sqrt{6}}) \alpha + (1 + \cancel{\sqrt{6}}) \alpha$$

$$x_3 = 3\alpha$$

$$V_{\lambda_1} = \{ (\alpha, (-1 - \sqrt{6})\alpha, 3\alpha) \mid \alpha \in \mathbb{R} \}$$

$$v_{\lambda_1} = (1, -1 - \sqrt{6}, 3)$$

$$(V_{\lambda_2})$$

$$\begin{pmatrix} -2 - \sqrt{6} & 1 & 1 \\ 2 & -1 - \sqrt{6} & 1 \\ 3 & 3 & -\sqrt{6} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$x_1 = \alpha \quad \begin{pmatrix} 1 & 1 \\ -1 - \sqrt{6} & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} = \alpha \begin{pmatrix} 2 + \sqrt{6} \\ -2 \end{pmatrix}$$

$$x_2 + x_3 = (2 + \sqrt{6})\alpha$$

$$x_2(-1 - \sqrt{6}) + x_3 = -2\alpha \quad \text{①}$$

$$x_2(2 + \sqrt{6}) = (4 + \sqrt{6})\alpha$$

$$x_2 = \frac{\sqrt{6} - 2}{2 + \sqrt{6}} \alpha$$

$$x_2 = \frac{4\sqrt{6} - 8 + 6 - 2\sqrt{6}}{6 - 4} \alpha$$

$$x_2 = \frac{2\sqrt{6} - 2}{2} \alpha$$

$$x_2 = (\sqrt{6} - 1)\alpha$$

$$x_3 = (2 + \sqrt{6})\alpha - (\sqrt{6} - 1)\alpha$$

$$x_3 = 3\alpha$$



$$V_{\lambda_2} = \{ (\alpha, (\sqrt{6}-1)\alpha, 3\alpha) \mid \alpha \in \mathbb{R} \}$$

$$v_{\lambda_2} = (1, \sqrt{6}-1, 3)$$

$$V_{\lambda_3} \quad \lambda_3 = 1$$

$$\begin{pmatrix} 2^{-1} & 1 & 1 \\ 2 & 3^{-1} & 1 \\ 3 & 3 & 4^{-1} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 1 \\ 3 & 3 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$x_1 = \alpha \quad \begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} = \alpha \begin{pmatrix} -1 \\ -2 \end{pmatrix} \quad L_2 = L_2 - L_1$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} = \alpha \begin{pmatrix} -1 \\ -1 \end{pmatrix} \quad L_1 = L_1 - L_2$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x_2 \\ x_3 \end{pmatrix} = \alpha \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

$$x_3 = 0$$

$$x_2 = -\alpha$$

$$V_{\lambda_3} = \{ (\alpha, -\alpha, 0) \mid \alpha \in \mathbb{R} \}$$

$$v_{\lambda_3} = (1, -1, 0)$$

Diagonalisierbar

$$D = \begin{pmatrix} 4 - \sqrt{6} & 0 & 0 \\ 0 & 4 + \sqrt{6} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$B = \left\{ \begin{array}{l} (1, -1-\sqrt{6}, 3), \\ (1, -1+\sqrt{6}, 3), \\ (-1, -1, 0) \end{array} \right\}$$