

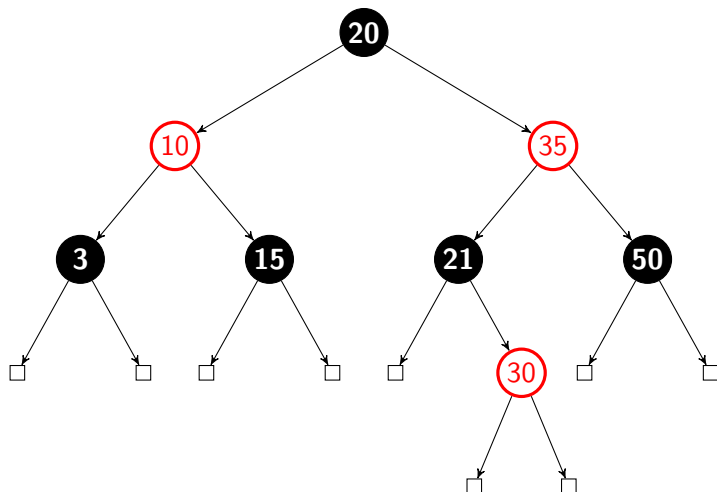
# Balanced search trees.

DS 2018/2019

# Red-black trees

- ▶ *Symmetric binary B-tree*, Rudolf Bayer, 1972.
- ▶ The balancing is maintained by using a coloring of the nodes.
- ▶ The red-black trees are binary search trees that satisfy the following properties:
  1. a node is colored with red or black;
  2. the root and the leaf nodes (*nil* – that belong to the structure) are colored with black;
  3. if a node is red, then his both children are black;
  4. the paths from a node to the boundary nodes have the same number of black nodes.

# Red-black trees - example



# Red-black trees

## Lemma:

*Any subtree of a red-black tree has at least  $2^{bh(v)} - 1$  internal nodes, where:*

- ▶  *$v$  the root of the subtree,*
- ▶  *$bh(v)$  the number of black nodes found on a path from  $v$  down to a leaf, not including  $v$ ;*

## Proof.

At class.



# Red-black trees

## Theorem:

*A red-black tree with  $n$  internal nodes has the height  $h \leq 2 \log_2(n + 1)$ .*

## Proof.

According to property 3,

$$n \geq 2^{h/2} - 1 \quad \Rightarrow \quad h/2 \leq \log_2(n + 1) \quad \Rightarrow \quad h \leq 2 \log_2(n + 1). \quad \square$$

# Red-black trees: operations

## Corollary:

*In a red-black tree with  $n$  nodes, the search operation has a time complexity of  $O(\log n)$ .*

# The insert operation

- ▶ Search for the insertion position and insert the new value as in the case of ordinary binary search trees.
- ▶ Color the new node with red.
- ▶ Restore the red-black properties by recoloring nodes and applying simple rotations.

# The insert operation

- ▶ Property 1: satisfied.
- ▶ Property 2 – satisfied (both children of the inserted node are *nil*). If the inserted node is the root → recolor it in black.
- ▶ Property 4 – satisfied (the new red node replaces a leaf).
- ▶ The property 3 may not hold - if the parent of the node is red.
  - ▶ Move above this situation by recoloring the nodes until it can be repaired by rotation operations and recoloring.

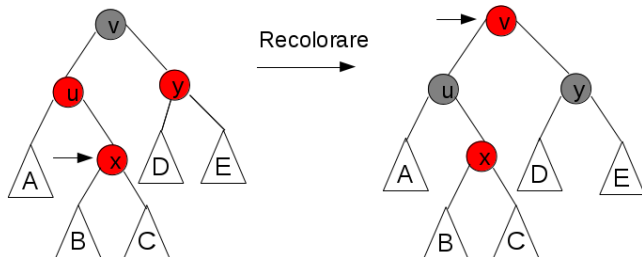


# The insert operation: the restauration of property 3

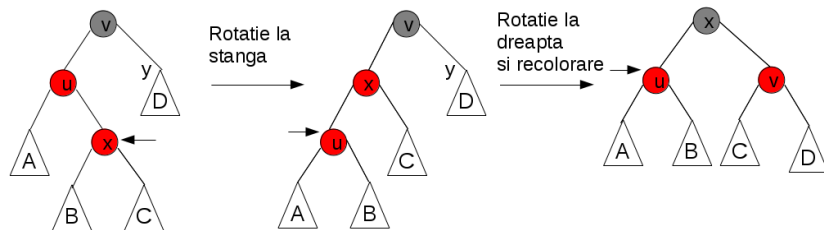
- ▶ **Case 1:** the “uncle” of the inserted node is red →  
Recolor the “parent” and the “uncle” in black and the “grandfather” in red.
- ▶ **Case 2:** the “uncle” of the inserted node is black and the inserted node is the right child of a left child →  
Apply a simple left rotation between the current node and the parent node.
- ▶ **Case 3:** the “uncle” of the inserted node is black and the inserted node is the left child of a left child →  
Apply a simple right rotation between the “parent” node and the “grandfather” node + recolor the “parent” node (in black) and the “grandfather” node (in red).

Obs.: Apply similar operations for the symmetric case.

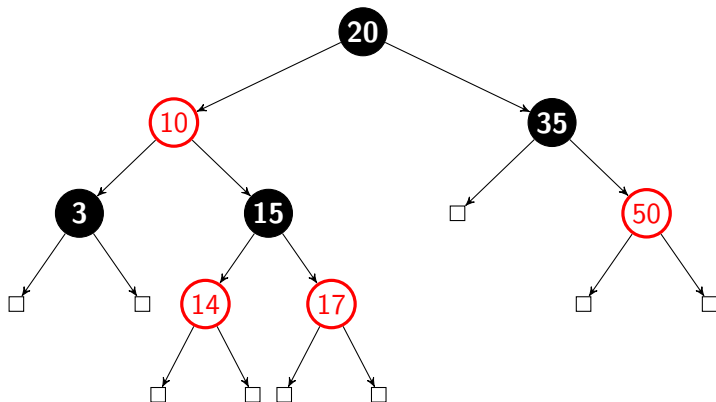
# The insert operation - case 1



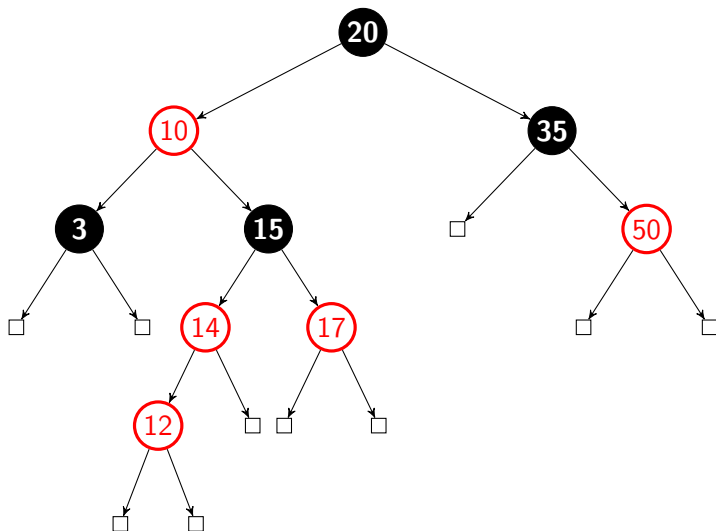
# The insert operation - Case 2 and 3



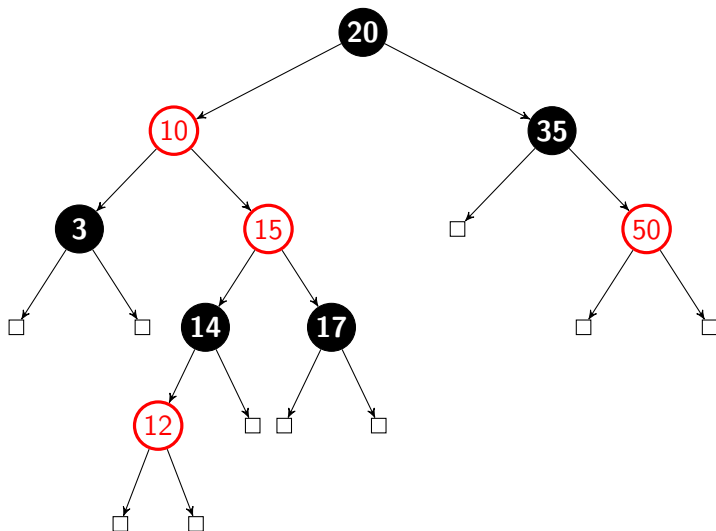
## Insertion – example: node 12



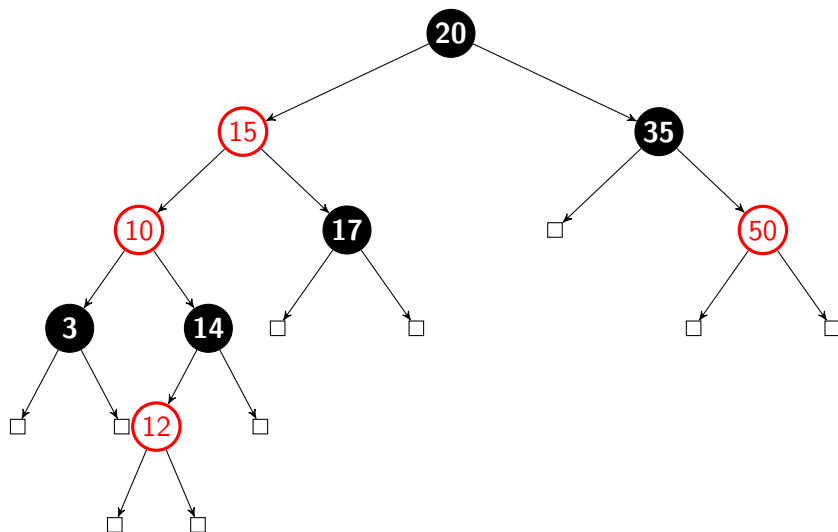
## Insertion – CASE 1: recoloring



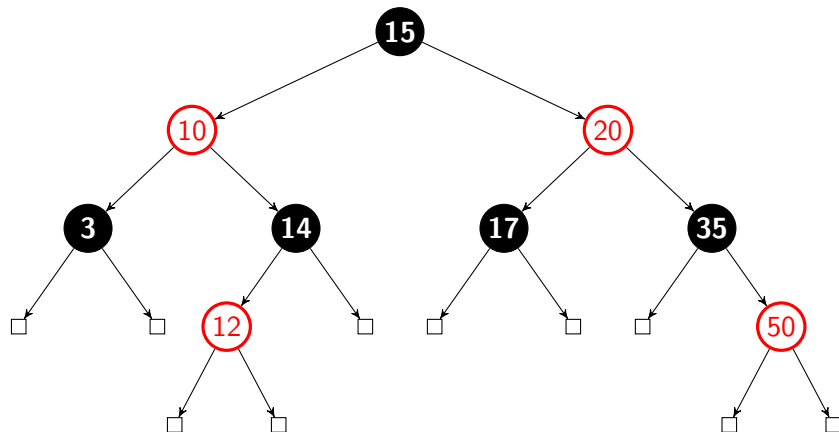
## Insertion – CASE 2: left rotation



## Insertion – CASE 3: right rotation + recoloring



# Insertion – The valid red-black tree





# The insert operation: algorithm

Consider that each node of the tree is a structure with the following fields:

- ▶ *key*: the useful information of the node;
- ▶ *color*: red / black;
- ▶ *pred*: the address of the parent node (null for the root);
- ▶ *left*: the address of the left child;
- ▶ *right*: the address of the right child.

# The insert operation: algorithm

**Procedure** *insert*(*t*, *x*)

**begin**

  insBinarySearchTree(*t*, *x*)

*x* → *color* ← red

**while** (*x* ≠ *t* and *x* → *pred* → *color* == red) **do**

**if** (*x* → *pred* == *x* → *pred* → *pred* → left) **then**

*y* ← *x* → *pred* → *pred* → right

**if** (*y* → *color* == red) **then**

        Case 1

**else**

**if** (*x* == *x* → *pred* → right) **then**

          Case 2

        Case 3

**else**

      similarly to the branch "then", but interchanging left with right

*t* → *color* ← black

**end**

# The insert operation: Case 1

$x \rightarrow pred \rightarrow color \leftarrow \text{black}$

$y \rightarrow color \leftarrow \text{black}$

$x \rightarrow pred \rightarrow pred \rightarrow color \leftarrow \text{red}$

$x \leftarrow x \rightarrow pred \rightarrow pred$

## The insert operation: Case 2

$x \leftarrow x \rightarrow pred$   
 $left\text{-}rotation(t, x)$

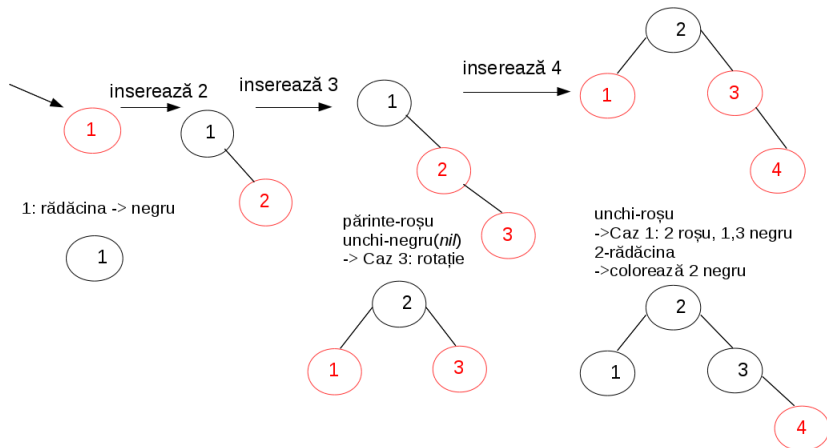
## The insert operation: Case 3

$x \rightarrow pred \rightarrow color \leftarrow \text{black}$

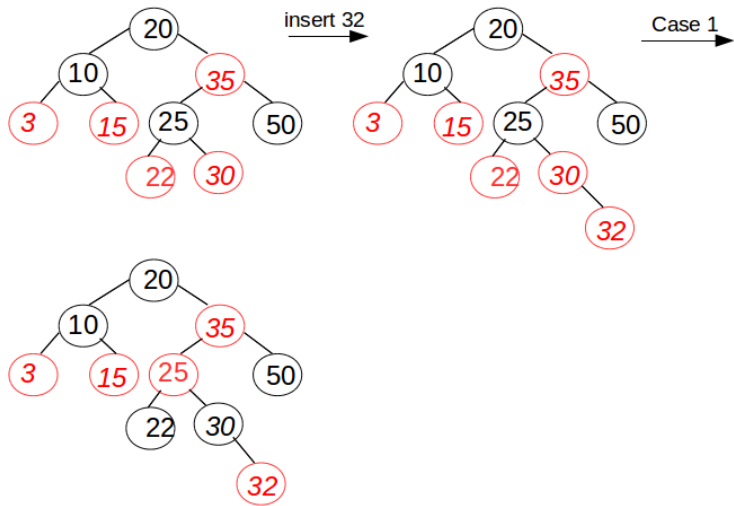
$x \rightarrow pred \rightarrow pred \rightarrow color \leftarrow \text{red}$

$\text{right-rotation}(t, x \rightarrow pred \rightarrow pred)$

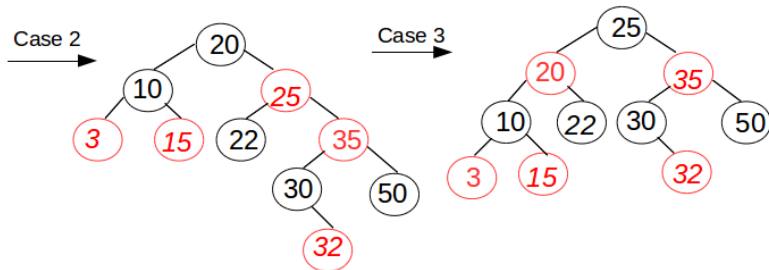
# The insert operation - example 2



# The insert operation - example 3



## The insert operation - example 3





# The delete operation

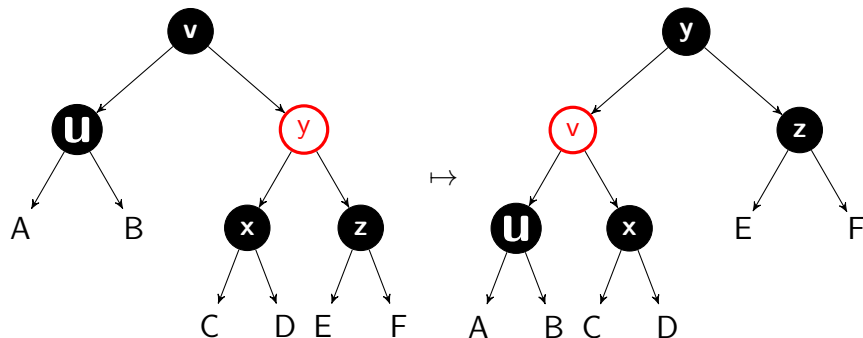
- ▶ Similarly to the delete operation from the ordinary binary search trees.
- ▶ Take into account that the “null” nodes belong to the structure.
- ▶ After deletion it is possible that the property 4 do not hold any more.
- ▶ Restore the properties of red-black trees by recoloring nodes and applying simple rotations.

# The delete operation: the restoration of property 4

- ▶ **Case 1:** Transform it into one of the cases 2), 3), 4) by a rotation.
- ▶ **Case 2:** The node for which the property is not satisfied is moved to the root with one level by recoloring a node.
- ▶ **Case 3:** Transform it into case 4) by an interchanging of colors and a rotation.
- ▶ **Case 4:** In this case restore the red-black tree property for the whole tree.

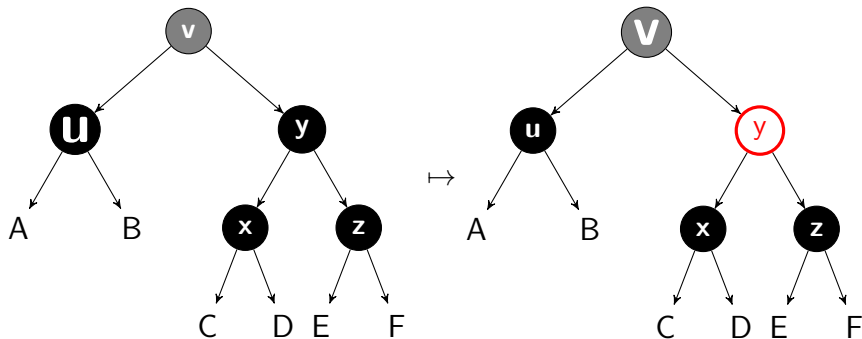
# Deletion – CASE 1

**Case 1:** Transform it into one of the cases 2), 3), 4) by a rotation.



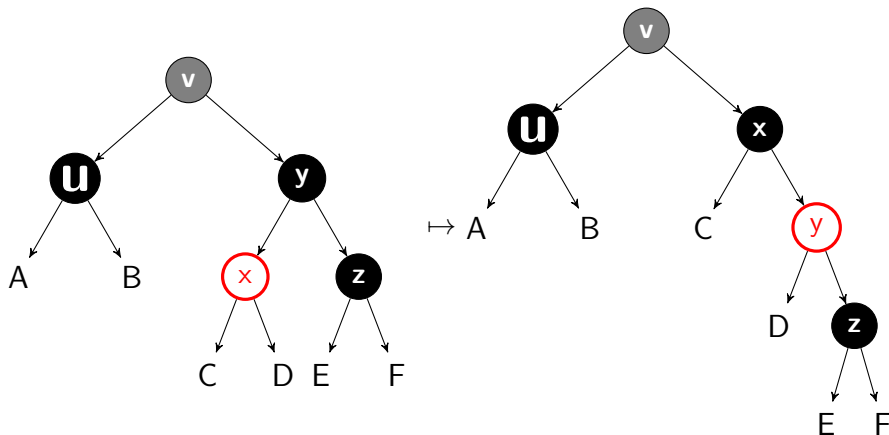
## Deletion – CASE 2

**Case 2:** The node for which the property is not satisfied is moved to the root with one level by recoloring a node.



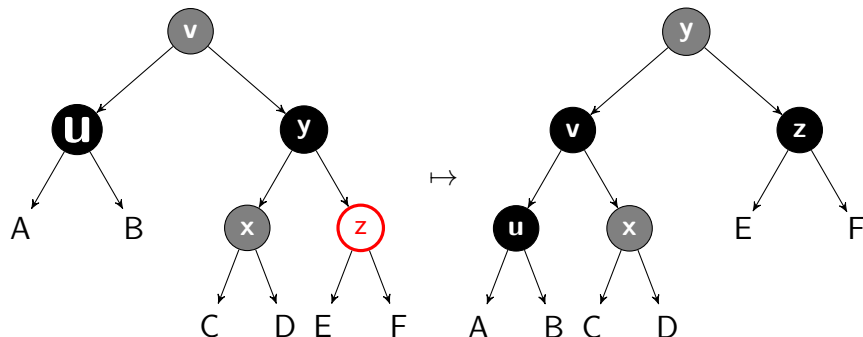
## Deletion – CASE 3

**Case 3:** Transform it into case 4) by an interchanging of colors and a rotation.



## Deletion – CASE 4

**Case 4:** In this case restore the red-black tree property for the whole tree.



# Red-black trees

- ▶ The complexity of insert / delete algorithms:  $O(\log n)$ .

## Corollary:

*The class of red-black trees is  $O(\log n)$ -stable.*

# Red-black trees

- ▶ The complexity of insert / delete algorithms:  $O(\log n)$ .

## Corollary:

*The class of red-black trees is  $O(\log n)$ -stable.*

- ▶ Applications:
  - ▶ System symbol tables.
  - ▶ Kernel Linux (Completely Fair Scheduler).
  - ▶ Runway reservation system
  - ▶ Java: TreeMap, TreeSet; C++ STL: map, multimap, multiset