

Bitmine CoinCraft A1

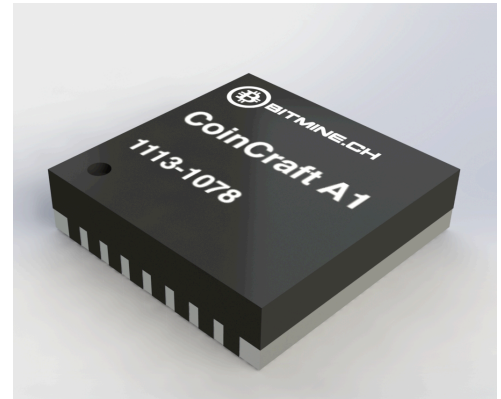


Bitcoin mining dedicated ASIC

Product outline:

The CoinCraft A1 is a custom developed, highly optimized hardware implementation of the Bitcoin block hashing algorithm.

The A1 uses an industry standard SPI interface and supports daisy chain configurations up to 253 units. The A1 can cover a wide range of applications, from ultra low power to high end, high performances.



Specifications:

- Developed on 28nm HPP (High Performance Process) from Global Foundries.
- Custom IC package with power bars for low voltage, high current feeding.
- Configurable in daisy chain mode for distributed work with up to 253 ASICs.
- Standard SPI interface.
- 32 highly optimized hashing engines based on custom ASIC cells.
- Hashing power of 20 GH/s in low power, 25 GH/s in nominal and up to 40 GH/s in Turbo mode.
- Power usage of 0.35 W/GH in low power, 0.6 W/GH in nominal and 1 W/GH in Turbo mode.
- Supply voltage of 0.65V in low power, 0.765 V in nominal and 0.85 V in Turbo mode.
- Product available starting from the second week of December 2013.

1. Protocol specification

1.1 General protocol specifications.

The CoinCraft A1 uses two SPI ports, one used in slave mode as an input from the uC or the previous A1 in the chain (pins SDO_R, SDI_R, SCK_R, CS_R) and one in master mode to the next A1 in the chain (pins SDO_L, SDI_L, SCK_L, CS_L), if any.

The SPI bus can operate at any clock speed up to 20 MHz. The clock is supplied by the uC through the IN_SCLK pin and passed to the next A1 in the chain through OUT_SCLK.

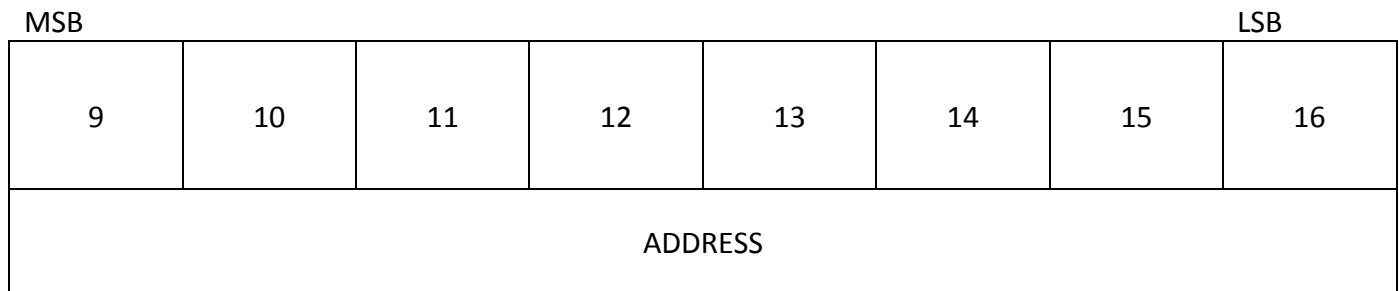
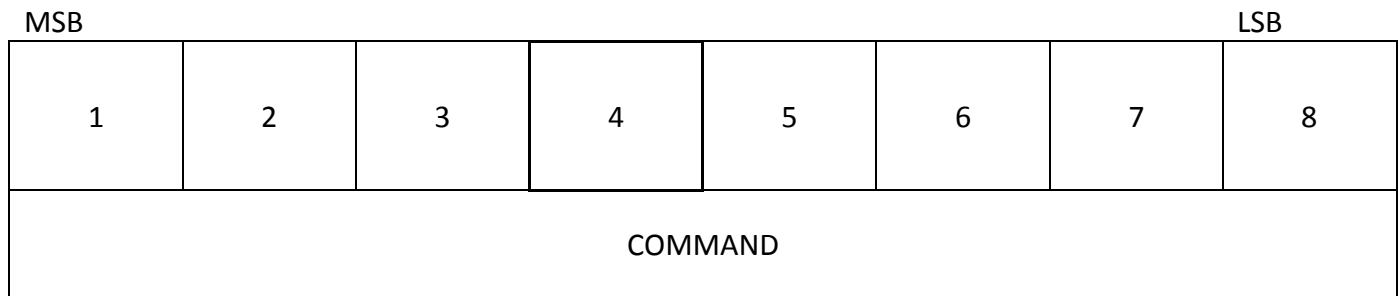
A 16 bit SPI bus is used all the time, every frame is made of 16 bit command/address field followed by 16 bit based data, if any data is to be followed by the command. The CS pins are used to qualify one frame from the master. There is no need for CS on the response frames because the uC has knowledge of the length that the frame should have.

The first 8 bit in the frame is the command field which is listed on Table 1 below, the second 8 bit is the addressing. If the address is set to 00, the command is meant to be broadcast among all the A1 in the chain.

At reset, an automatic configuration mode enumerates and assigns addresses to all the chips in the chain. The first one will get address 0x01, the second one 0x02 and so on up to the last chip in the chain or to the maximum possible address of 0xFF.

Most command will loop back to uC through the chain to indicate to the uC that the job was executed. Some command such as BIST_ON or AUTO_ADDRESSING command will modify the 0x00 address field. For example, the AUTO_ADDRESSING command returns the frame with the highest chip address in the chain back to the uC.

1.1.1 Command/address field (16 bit)



1.2 Failure detection and resolution

Due to the nature of silicon process, it is possible that a limited number of chips could have defective hashing engines. This is detected and bypassed automatically through an internal check called BIST where each of the 32 hashing engines in the chip are requested to solve a particular job and the expected output hash is then compared to see if that particular hashing engine is faulty.

This check can be enabled or disabled, or just used to read the number of faulty engines.

2. Command reference

Command format from uC	Name	Broadcast / Individual type	Return format to uC	Description
0x0100	BIST_START / Auto Address	Broadcast	0x0100 0x00NN	Starts BIST check in all chips and auto addressing returns to uC. This returns one 16bit command and one 16 bit data. NN means the last device address in the chain.
0x01NN	BIST_START	Individual	0x01NN	Starts BIST check in the address matching chip and report the same command back to uC.
0x0300	BIST_FIX	Broadcast	0x0300	Ask each chip to mux out the bad hashing engines, fix all chips and bypass the hash engines that have been found to be faulty (if any).
0x03NN	BIST_FIX	Individual	0x03NN	Fix one particular chip and bypass the faulty hash engines (if any).
0x0400	RESET	Broadcast	0x0400	Reset all chips: reset SPI state machine, the status of the hashing units and the queues based on the configuration currently present in the registers.
0x04NN	RESET	Individual	0x04NN	Reset a particular chip: reset SPI state machine, the status of the hashing units and the queues based on the configuration currently present in the registers.

Command format from uC	Name	Broadcast / Individual type	Return format to uC	Description
0x17NN	WRITE_JOB	Individual	0x17NN	Send a new job to a specific chip, pushing it in the input queue and assigning it the JOB_ID 1.
0x27NN	WRITE_JOB	Individual	0x27NN	Send a new job to a specific chip, pushing it in the input queue and assigning it the JOB_ID 2.
0x37NN	WRITE_JOB	Individual	0x37NN	Send a new job to a specific chip, pushing it in the input queue and assigning it the JOB_ID 3.
0x47NN	WRITE_JOB	Individual	0x47NN	Send a new job to a specific chip, pushing it in the input queue and assigning it the JOB_ID 4.
0x0800	READ_RESULT	Broadcast	0x0800 if no match 0xY8NN DATA if match, JOB_ID is Y.	Read result frame from all chips, 1st chip in the chain that has a result in the output queue will swap command bit and return it as 0xY8NN, followed by the matched data. The Y identifies the JOB_ID of the returned nonce. The uC should store the data, then send out another 0x0800 to see if any other chip has results pending to be read, and so on till 0x0800 is read back, which means no more results are available in the chain. The uC can associate the returned nonce to a particular work by checking the JOB_ID field.
0x08NN	READ_RESULT	Individual	0x08NN if no match 0xY8NN DATA if match, JOB_ID is Y.	Read result frame from a specific chip, if it has a result in the output queue it will swap command bit and return it as 0xY8NN, followed by the matched data. The Y identifies the JOB_ID of the

				returned nonce. The uC should store the data, then send out another 0x0800 to see if any other chip has results pending to be read, and so on till 0x0800 is read back, which means no more results are available in the output queue. The uC can associate the returned nonce to a particular work by checking the JOB_ID field.
0x0900	WRITE_REG	Broadcast	0x0900	Write configuration register values to all chips, such as PLL registers or chip internal counters.
0x09NN	WRITE_REG	Individual	0x09NN	Write register values to particular chip. 48 bits for the total registers.
0x0ANN	READ_REG	Individual	0x1ANN reg DATA	Read values from the addressed chip register and return to uC.

3. Registers reference

The 48 bits register inside each chip is described as below.
Through command 0x0900 WRITE_REG, the payload data is fed in the format of MSByte and MSBit first.

Register	Pins	Description
register[46:45]	pll_postdiv[1:0]	PLL post divider
register[44:40]	pll_prediv[4:0]	PLL pre divider
register[39:31]	pll_fbdiv[7:0], pll_fbdiv[8]	PLL fb divider
register[30]	pll_incz	
register[29]	pll_lock_en	
register[28]	pll_clock_out_enable	
register[27]	pll_powerdown	
register[26]	pll_test_enable	
register[25:24]	pll_test_select	
register[23:8]	reserved	Reserved for future use
register[7:0]	bct_good_cnt[7:0]	Read only field, indicates how many hashing engines have passed the BIST self test. Maximum 32, minimum 1.

4. Firmware implementation reference guide

All command follows the standard SPI format with CS to indicate the start and end of packet. There is a MPU and a chip chain which is driven by MPU clocks to flow through command/address/data packets. The SPI bus clock can run as high as 20MHz. Any command and data is 16 bits based and MPU will receive a response for each command execution. All payload data, such as register value, job data or hashout result are MSB first.

The workflow follows the sequence, and this is what firmware should do.

1. System Initialization

Power up and Hardware reset

MPU broadcast the reset packet (0x0400) to all chips

Command packet format: 0x0400 with CS then keep the SCLK going to push forward

After the whole chain, MCU will receive a response: 0x0400

Action: All chips in the chain, when receiving this command, will all clear out any ongoing activities and reassert the reset values in the registers.

2. WRITE_REG, overwrite the PLL and any additional configuration registers if needed

MPU broadcasts the wanted configuration register values to all chips if the default values aren't already fine.

REG_WRITE command format: **0x0900 0xXXXX 0xXXXX 0xXXXX (48 bit data payload)**

After the whole chain, MCU will receive a response: **0x0900 0xXXXX 0xXXXX 0xXXXX**

Action: The default values of register in the recipient chip will be overwritten by this command, such as PLL divider, reset_ and so on. This command consists of four 16 bit values. The first one is the WRITE_REG command. Next three are the assigned register values (0xXXXX indicates 16 bits value in hexadecimal format).

3. BIST_START/Auto addressing

MPU broadcasts the BIST_START command to all chips, starts BIST and auto addressing

Command packet format: 0x0100

Response: 0x0100 0x00NN (NN comes back with auto addressing's total number of chips in the chain).

Action: This message starts the BIST mode for all the chips in the chain. In addition, system auto addressing completes (all chips will be assigned the address automatically). When the BIST runs for a certain period (66 internal clock cycles), the BIST will be finished and will store the number of good hashing units into each chip's register but won't disable the hashing engines found to be faulty.

4. BIST_FIX to bypass all bad hash engines inside a chip

MPU broadcast the BIST_FIX to all chips

Command packet format: 0x0300

Response: 0x0300

Action: This fixes all bad hashes inside chips and bypasses the faulty hash engines.

5. Read the register from specific chip such as good Hash count inside each chip

MPU sends the READ_REG to specific chips in the chain.

Command packet format: 0x0aNN (NN indicates the specific chip's address) Response: 0x1ANN 0xFFFF 0xFFFF 0xFFFF

Action: The good hashing engines number is stored in the register and can be read from the chip. 0x1ANN indicates that this command is acknowledged by the specific chip and returns its three 16 bit register values back to MPU (NN is the specific chip address, XX is the register value).

6. Write the job to individual chip and start the computation

MPU broadcast the job to all chips

Command packet format: **0xY7NN 0xFFFF ... 0xFFFF**

Response: 0xY7NN

Action: Jobs are pushed in the input queue of each chip and are identified by the Y parameter which can be anything from 1 to 4, these will be used later by the uC when the results are read to understand which nonce is associated to what job. The job payload has 448 bits data,

including 128 bits wData, 256 bits midState, 32 bits TargetDifficulty and 32 bits endNonce (NN is the individual chip address, 0XXXXX indicates 16 bits value). After the job assignment is finished, the hash engine will compute immediately and will push to the output queue all the hash results that are equal or better than the supplied TargetDifficulty parameter. Each chip has two input queue slots, so right after the reset, two distinct jobs should be sent to the chip in order to queue the work. The job ID doesn't have to be sequential, just make sure that it doesn't overlap with a job already queued or being processed.

7. Read the matched result from all chips

MPU broadcast the command (0x0800) to all the chips in the chain. Command packet format: 0x0800,

Response: **0x0800 if there are no chips get the matched hash value. 0xY8NN 0XXXXX ... 0XXXXX if NN chip gets the matched hash result.**

Action: 0xY8NN is the acknowledge command returned back to MPU, followed by 32 bits Nonceout (NN is the response chip address, 0XXXXX indicates 16 bits value). The original job id of the resulting nonce is given back with the Y parameter. Depending on the set target difficulty, more than one match is possible within the same job, as such the searching will not stop when a match is found but will continue till the 32 bit nonce counter overflows.

Each chip has five output queues so each chip has potentially enough room to hold results for any match given by the queues jobs.

8. Read the matched result and keep feeding new jobs

Knowing the speed at which hashes are tried, the uC should keep trace of the elapsed time since the last job was sent and make sure that another new job is sent before the second job is pulled from the queue, so that optimal performances are achieved without the chip ever stopping to run.

Otherwise, the uC can repeat step 7 until 0xY8NN is received. When 0x0800 is received, it means that the specific chip that answered has run out of jobs and that its input queue should be filled again by getting back to step 6.

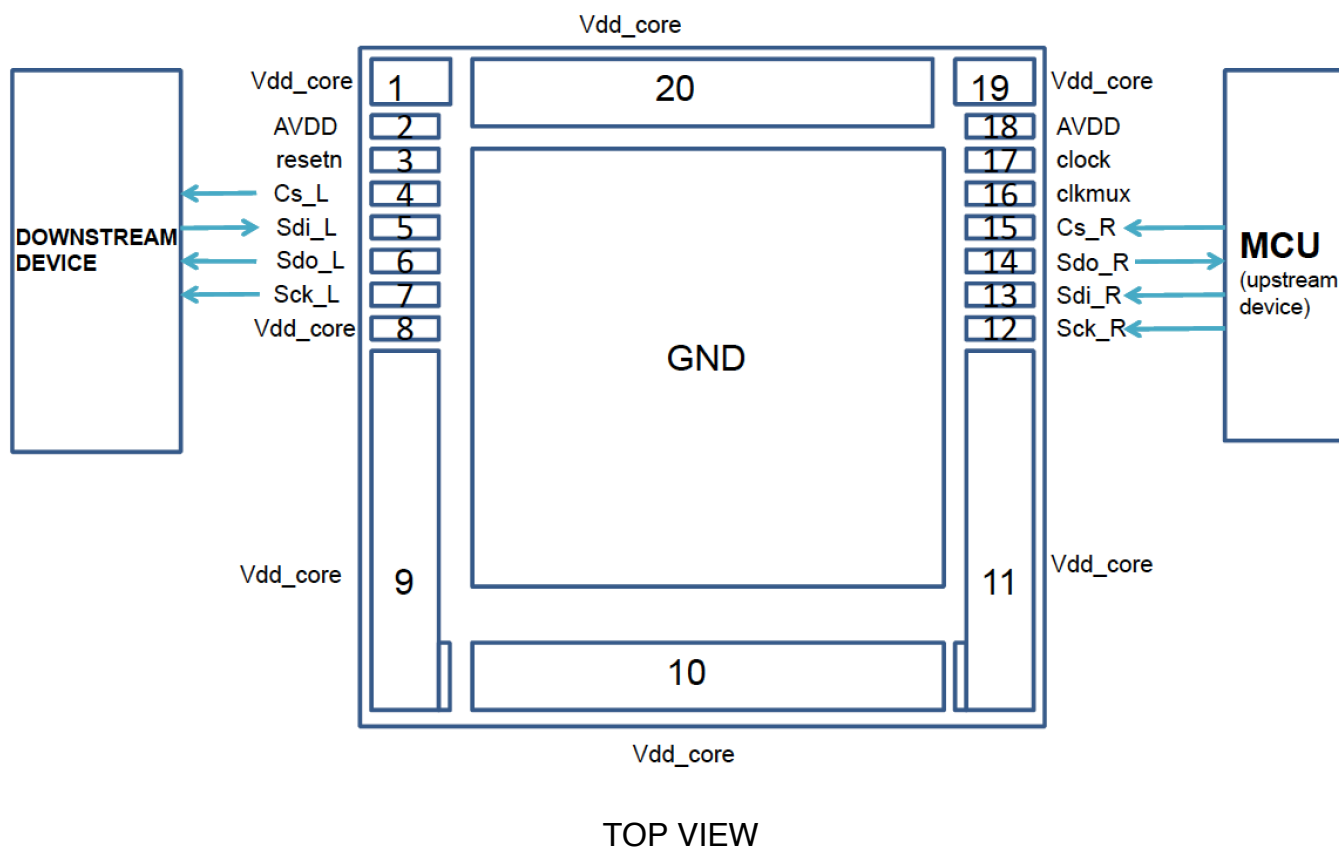
9. Watch for new blocks coming from the network

In the case that a new network block is broadcast by the Bitcoin network, all currently running jobs should be stopped and discarded to make place for the new ones. This can be achieved by sending the WRITE_REG command with the appropriate fields set to 1 for Input queue and

Output queue reset, while keeping the registers for BIST_FIX and BC set to 0 so that these are not reset. After this, send a broadcast RESET command with 0x0400 and return to step 6 for feeding the new jobs to the chain.

5. Electrical specifications

5.1 Pinout



Name	Direction	PIN	Description
VDD_CORE	I	1,8,9,10,11,19,20	Core supply voltage
AVDD	I	2,18	IO reference supply voltage 1.8V
RESETN	I	3	Reset signal, active low.
CS_L	O	4	SPI master signal chip select
SDI_L	I	5	SPI master serial data in
SDO_L	O	6	SPI master serial data out
SCK_L	O	7	SPI master clock out
SCK_R	I	12	SPI slave clock in
SDI_R	I	13	SPI slave serial data in
SDO_R	O	14	SPI slave serial data out
CS_R	I	15	SPI chip select signal in

CLKMUX	I	16	Mux the reference clock and internal PLL clock option: 0 for internal PLL clock as system clock, 1 for reference clock as internal system clock.
CLOCK	I	17	Reference clock in, see CLKMUX for function of this pin.
GND			Ground

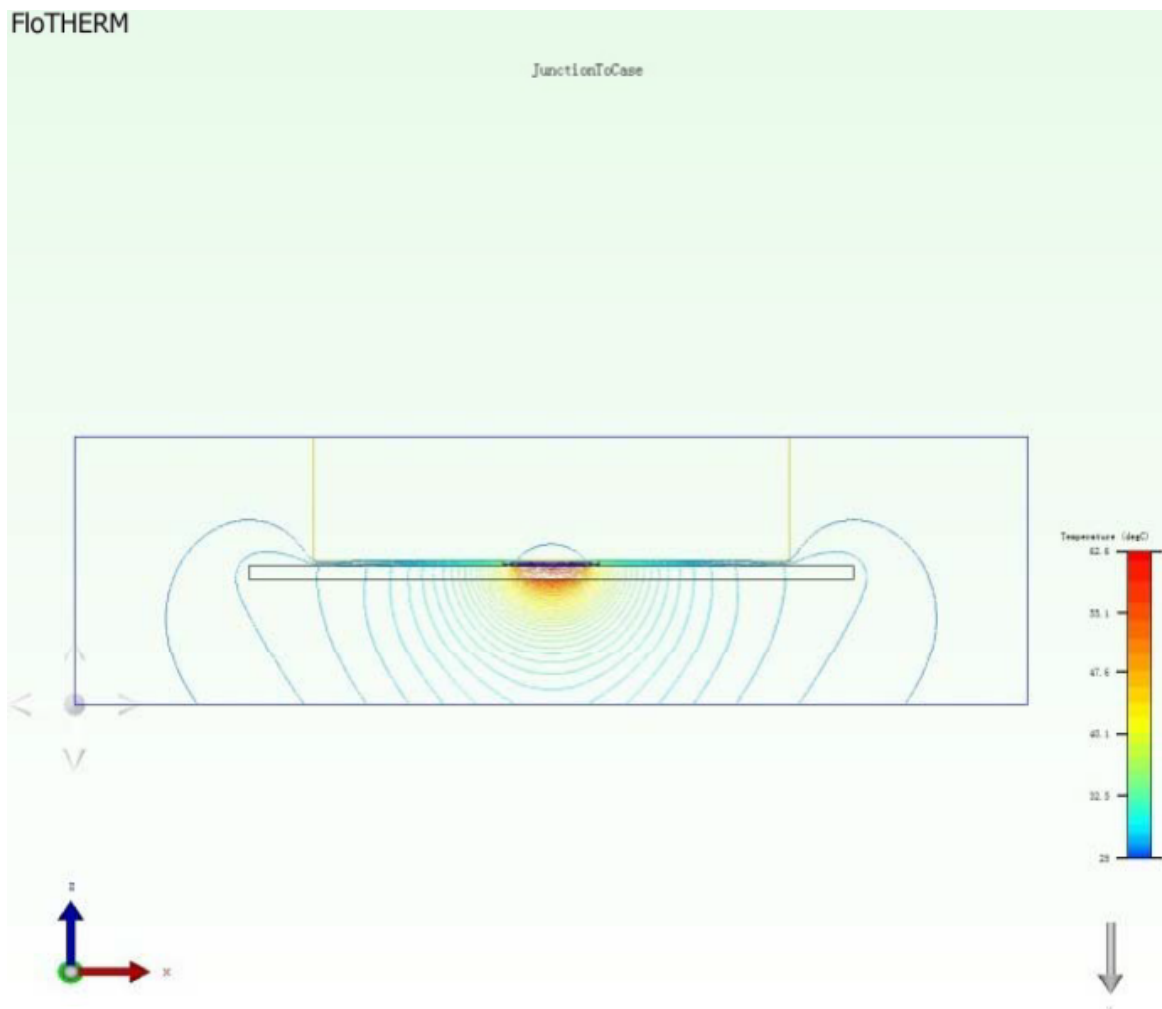
5.2 Electrical specifications

Parameter	Unit	Min.	Typ.	Max.
Core supply voltage (VDD_CORE)	V	0.65	0.765	0.85
Core supply current (VDD_CORE)	A	12.5	20	30
I/O reference voltage (AVDD)	V	-	1.8	-
I/O reference current (AVDD)	A			
Reference clock for internal PLL (CLKMUX=0)	MHz	12	12	32
System clock (CLKMUX=1)	MHz	600	800	1000
SPI clock (SCK_R and SCK_L)	MHz	4	8	20
Junction operating temperature	°C	0	-	100
Dissipated power	%	25	25	30

6. Thermal specifications

The IC package of the CoinCraft A1 is specifically developed to withstand the high power figures implied in Bitcoin mining specific applications.

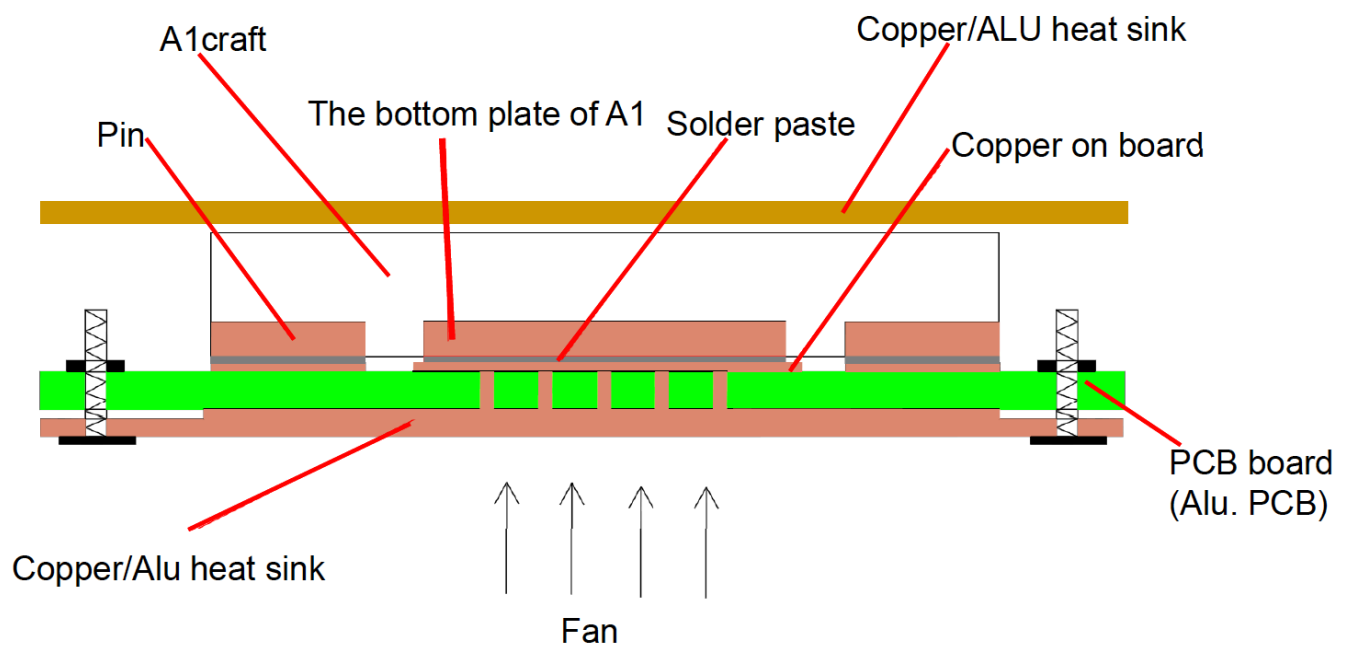
The QFN package is engineered to transfer most of the generated heat through the ground pad, as illustrated in the typical thermal simulation below:

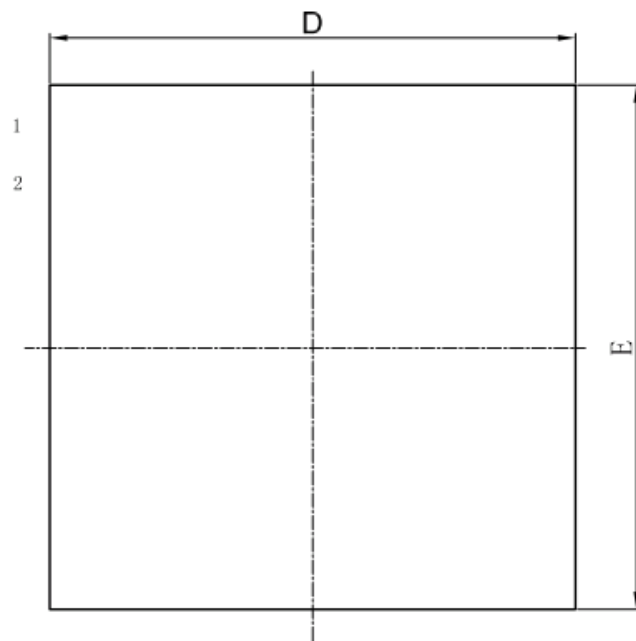


A system design should account for about 70% of the power being dissipated through the ground pad and about 30% through the top of the package.

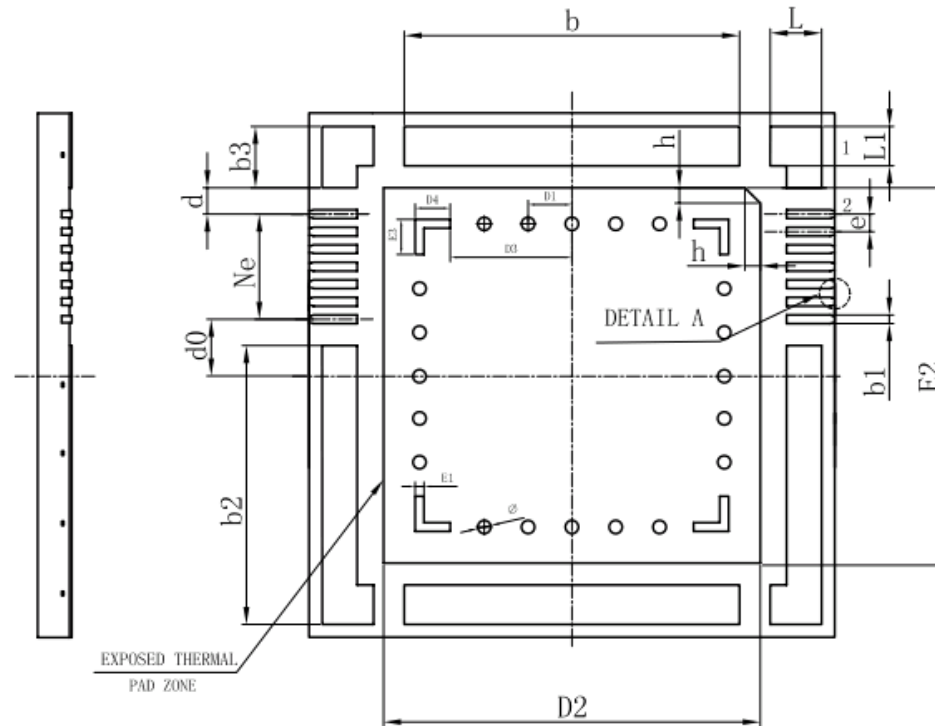
Appropriate dissipation through ground vias should be engineered in order to transfer the heat from the bottom pad to the bottom layer of the PCB board where an aluminum heat sink should be placed.

The illustration below summarizes the typical application of the thermal design of a system featuring the CoinCraft A1.

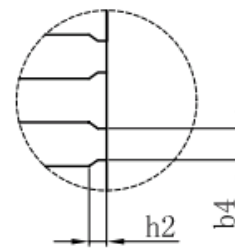




TOP VIEW



BOTTOM VIEW



DETAIL A

4:1

SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	—	0.02	0.05
b	7.60	7.65	7.70
b1	0.15	0.20	0.25
b2	6.35	6.40	6.45
b3	1.35	1.40	1.45
b4	0.11	0.16	0.21
c	0.18	0.20	0.23
D	11.90	12.00	12.10
D1	0.90	1.00	1.10
D2	8.50	8.60	8.70
D3	2.73	2.78	2.83
D4	0.75	0.80	0.85
d	0.55	0.60	0.65
d0	1.30REF		
e	0.40BSC		
Ne	2.40BSC		
E	11.90	12.00	12.10
E1	0.15	0.20	0.25
E2	8.50	8.60	8.70
E3	0.75	0.80	0.85
h	0.30	0.35	0.40
h2	0.10REF		
L	1.12	1.17	1.22
L1	0.85	0.90	0.95
∅	0.30		

Revision history

Version	Date	Comments
0.1.A	09.10.13	First public release, work in progress.
0.1.B	17.10.13	Updated IC package to newest version. Updated PINOUT list. Removed old references to RESP_BIT.
1.0.A	10.11.13	First final release. Updated package drawing. Added electrical specifications. Added thermal specifications.

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