DiagrammeDeClasses_Observateur

Package in package 'Model'

DiagrammeDeClasses_Observateur Version Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

DiagrammeDeClasses_Observateur diagram

Class diagram in package 'DiagrammeDeClasses Observateur'

DiagrammeDeClasses_Observateur Version 1.0 bodiaa created on 2019-06-18. Last modified 2019-06-18

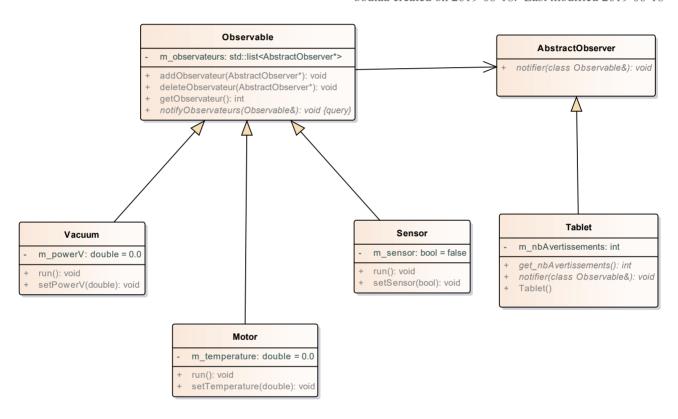


Figure 1: DiagrammeDeClasses_Observateur

AbstractObserver

Class in package 'Class Model'

AbstractObserver Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

INCOMING STRUCTURAL RELATIONSHIPS → Generalization from Tablet to AbstractObserver [Direction is 'Source -> Destination'.] ASSOCIATIONS

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) Observable Target: Public (Class) AbstractObserver

OPERATIONS

notifier (obs : class Observable&) : void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

Motor

Class in package 'Class Model'

Motor Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from Motor to Observable

[Direction is 'Source -> Destination'.]

ATTRIBUTES

ightharpoonup m temperature : double Private = 0.0

[Is static False. Containment is Not Specified.]

OPERATIONS

vun () : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setTemperature (temperature : double) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Observable

Class in package 'Class Model'

Observable Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from Motor to Observable

[Direction is 'Source -> Destination'.]

INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from Vacuum to Observable

[Direction is 'Source -> Destination'.]

→ Generalization from Sensor to Observable

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m observateurs : std::list<AbstractObserver*> Private

[Is static False. Containment is Not Specified.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) Observable

Target: Public (Class) AbstractObserver

OPERATIONS

addObservateur (observateur : AbstractObserver*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

deleteObservateur (observateur : AbstractObserver*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getObservateur (): int Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

notifyObservateurs (obs : Observable&) : void Public

[Is static False. Is abstract False. Is return array False. Is query True . Is synchronized False.]

Sensor

Class in package 'Class Model'

Sensor Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from Sensor to Observable

[Direction is 'Source -> Destination'.]

ATTRIBUTES

ATTRIBUTES

m sensor : bool Private = false

[Is static False. Containment is Not Specified.]

OPERATIONS

vun () : void Public

[Is static False. Is abstract False. Is return array False. Is guery False. Is synchronized False.]

setSensor (sensor : bool) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Tablet

Class in package 'Class Model'

Tablet
Version 1.0 Phase 1.0 Proposed
bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from Tablet to AbstractObserver

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m_nbAvertissements : int Private

[Is static False. Containment is Not Specified.]

OPERATIONS

get_nbAvertissements () : int Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

notifier (obs : class Observable&) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Tablet (): Public

Properties:

initializer = m_nbAvertissements(0)

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Vacuum

Class in package 'Class Model'

Vacuum Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from Vacuum to Observable

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m_powerV : double Private = 0.0

[Is static False. Containment is Not Specified.]

OPERATIONS

void Public (): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setPowerV (powerV : double) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]