Model Report 18 June, 2019

# DiagrammeDeClasses\_Observateur

Package in package 'Model'

DiagrammeDeClasses\_Observateur Version Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

# DiagrammeDeClasses\_Observateur diagram

Class diagram in package 'DiagrammeDeClasses Observateur'

DiagrammeDeClasses\_Observateur
Version 1.0
bodiaa created on 2019-06-18. Last modified 2019-06-18

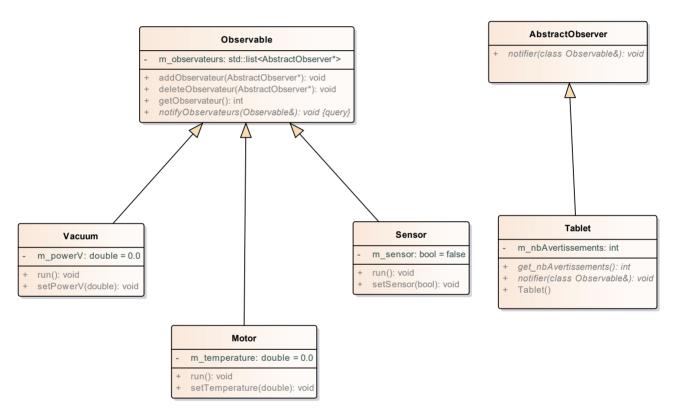


Figure 1: DiagrammeDeClasses\_Observateur

# **AbstractObserver**

Class in package 'Class Model'

AbstractObserver Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

# INCOMING STRUCTURAL RELATIONSHIPS → Generalization from Tablet to AbstractObserver [ Direction is 'Source -> Destination'. ] OPERATIONS

Model Report 18 June, 2019

#### **OPERATIONS**

notifier (obs : class Observable& ) : void Public

[ Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False. ]

# **Motor**

Class in package 'Class Model'

Motor Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

#### **OUTGOING STRUCTURAL RELATIONSHIPS**



Generalization from Motor to Observable

[ Direction is 'Source -> Destination'. ]

#### **ATTRIBUTES**



m temperature : double Private = 0.0

[ Is static False. Containment is Not Specified. ]

#### **OPERATIONS**



void Public (): void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

setTemperature (temperature : double ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

# **Observable**

Class in package 'Class Model'

Observable Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

### INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from Motor to Observable

[ Direction is 'Source -> Destination'. ]

→ Generalization from Vacuum to Observable

[ Direction is 'Source -> Destination'. ]

Model Report 18 June, 2019

#### INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from Sensor to Observable

[ Direction is 'Source -> Destination'. ]

#### ATTRIBUTES

m\_observateurs : std::list<AbstractObserver\*> Private

[ Is static False. Containment is Not Specified. ]

#### **OPERATIONS**

addObservateur (observateur : AbstractObserver\* ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

deleteObservateur (observateur : AbstractObserver\* ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

getObservateur (): int Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

notifyObservateurs (obs : Observable& ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query True . Is synchronized False. ]

# Sensor

Class in package 'Class Model'

Sensor Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

#### **OUTGOING STRUCTURAL RELATIONSHIPS**

Generalization from Sensor to Observable

[ Direction is 'Source -> Destination'. ]

# ATTRIBUTES

m\_sensor : bool Private = false

[ Is static False. Containment is Not Specified. ]

#### **OPERATIONS**

void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

Model Report 18 June, 2019

#### **OPERATIONS**



setSensor (sensor : bool ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

# **Tablet**

Class in package 'Class Model'

Tablet Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

#### **OUTGOING STRUCTURAL RELATIONSHIPS**



Generalization from Tablet to AbstractObserver

[ Direction is 'Source -> Destination'. ]

#### **ATTRIBUTES**



m nbAvertissements : int Private

[ Is static False. Containment is Not Specified. ]

#### **OPERATIONS**



get nbAvertissements (): int Public

Properties:

bodyLocation = classDec

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

notifier (obs : class Observable& ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

Tablet (): Public

Properties:

initializer = m\_nbAvertissements(0)

bodyLocation = classDec

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

# **Vacuum**

Class in package 'Class Model'

Vacuum Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

#### **OUTGOING STRUCTURAL RELATIONSHIPS**

Model Report 18 June, 2019

# OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from Vacuum to Observable

[ Direction is 'Source -> Destination'. ]

#### **ATTRIBUTES**

m\_powerV : double Private = 0.0

[ Is static False. Containment is Not Specified. ]

# **OPERATIONS**

vun (): void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]

setPowerV (powerV : double ) : void Public

[ Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False. ]