DiagrammeDeClasses_Commande

Package in package 'Model'

DiagrammeDeClasses_Commande Version Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

DiagrammeDeClasses_Commande diagram

Class diagram in package 'DiagrammeDeClasses Commande'

DiagrammeDeClasses_Commande Version 1.0 bodiaa created on 2019-06-18. Last modified 2019-06-18

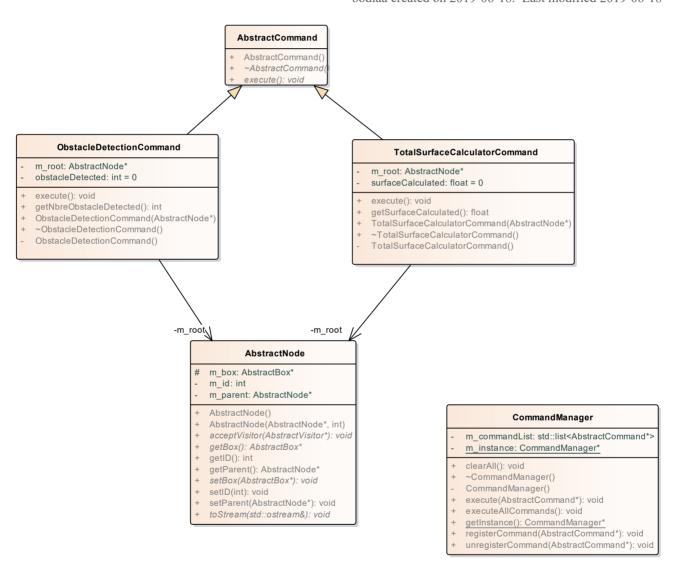


Figure 1: DiagrammeDeClasses_Commande

AbstractCommand

Class in package 'Class Model'

AbstractCommand Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

INCOMING STRUCTURAL RELATIONSHIPS → Generalization from TotalSurfaceCalculatorCommand to AbstractCommand [Direction is 'Source -> Destination'.] → Generalization from ObstacleDetectionCommand to AbstractCommand [Direction is 'Source -> Destination'.]

OPERATIONS AbstractCommand (): Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] AbstractCommand (): Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] execute (): void Public [Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

AbstractNode

Class in package 'Class Model'

AbstractNode Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

INCOMING STRUCTURAL RELATIONSHIPS	
→ Generalization from CompositeNode to AbstractNode	[Direction is 'Source -> Destination'.]
→ Generalization from Obstacle to AbstractNode	[Direction is 'Source -> Destination'.]

ATTRIBUTES	
	[Is static False. Containment is Not Specified.]
• m_id : int Private	[Is static False. Containment is Not Specified.]

ATTRIBUTES

m parent: AbstractNode* Private

[Is static False. Containment is Not Specified.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) AbstractNode

Target: Protected m box (Class) AbstractBox

Association (direction: Source -> Destination)

Source: Public (Class) ObstacleDetectionCommand

Target: Private m root (Class) AbstractNode

Association (direction: Source -> Destination)

Source: Public (Class) TotalSurfaceCalculatorCommand

Target: Private m_root (Class) AbstractNode

OPERATIONS

AbstractNode (): Public

Properties:

initializer = m parent(nullptr),m id(0)

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

AbstractNode (parent : AbstractNode*, id : int) : Public

Properties:

initializer = m_parent(parent),m_id(id)

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

acceptVisitor (visitor : AbstractVisitor*) : void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

getBox (): AbstractBox* Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

getID (): int Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getParent (): AbstractNode* Public Const

Properties:

OPERATIONS

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setBox (box : AbstractBox*) : void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

setID (id : int) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setParent (parent : AbstractNode*) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

toStream (s: std::ostream&): void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

CommandManager

Class in package 'Class Model'

CommandManager Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

ATTRIBUTES

m commandList:std::list<AbstractCommand*> Private

[Is static False. Containment is Not Specified.]

m instance: CommandManager* Private

[Is static True. Containment is Not Specified.]

OPERATIONS

clearAll (): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

~CommandManager (): Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

CommandManager (): Private

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

OPERATIONS

execute (Command : AbstractCommand*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

executeAllCommands (): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getInstance (): CommandManager* Public

Properties:

bodyLocation = classDec

[Is static True. Is abstract False. Is return array False. Is query False. Is synchronized False.]

registerCommand (Command : AbstractCommand*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

unregisterCommand (Command : AbstractCommand*): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

ObstacleDetectionCommand

Class in package 'Class Model'

ObstacleDetectionCommand Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from ObstacleDetectionCommand to AbstractCommand

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m_root : AbstractNode* Private

[Is static False. Containment is Not Specified.]

• obstacleDetected : int Private = 0

[Is static False. Containment is Not Specified.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) ObstacleDetectionCommand Target: Private m_root (Class) AbstractNode

OPERATIONS

OPERATIONS

execute (): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getNbreObstacleDetected (): int Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

ObstacleDetectionCommand (root : AbstractNode*): Public

Properties:

initializer = AbstractCommand(),m root(root)

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

ObstacleDetectionCommand (): Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

ObstacleDetectionCommand (): Private

Properties:

initializer = AbstractCommand(),m_root(nullptr)

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

TotalSurfaceCalculatorCommand

Class in package 'Class Model'

TotalSurfaceCalculatorCommand Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from TotalSurfaceCalculatorCommand to AbstractCommand

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m root : AbstractNode* Private

[Is static False. Containment is Not Specified.]

surfaceCalculated : float Private = 0

[Is static False. Containment is Not Specified.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) TotalSurfaceCalculatorCommand Target: Private m root (Class) AbstractNode

OPERATIONS

execute (): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getSurfaceCalculated (): float Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

▼ TotalSurfaceCalculatorCommand (root : AbstractNode*) : Public

Properties:

initializer = AbstractCommand(),m root(root)

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

◆ ~TotalSurfaceCalculatorCommand (): Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

TotalSurfaceCalculatorCommand (): Private

Properties:

initializer = AbstractCommand(),m root(nullptr)

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]