DiagrammeDeClasses_Composite

Package in package 'Model'

DiagrammeDeClasses_Composite

Version Phase 1.0 Proposed
bodiaa created on 2019-06-18. Last modified 2019-06-18

DiagrammeDeClasses_Composite diagram

Class diagram in package 'DiagrammeDeClasses Composite'

DiagrammeDeClasses_Composite
Version 1.0
bodiaa created on 2019-06-18. Last modified 2019-06-18

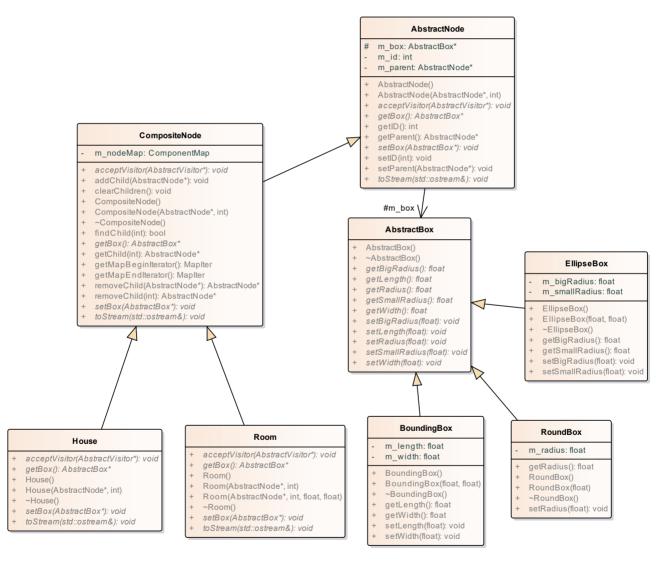


Figure 1: DiagrammeDeClasses_Composite

AbstractBox

Class in package 'Class Model'

AbstractBox Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from RoundBox to AbstractBox

[Direction is 'Source -> Destination'.]

→ Generalization from BoundingBox to AbstractBox

[Direction is 'Source -> Destination'.]

→ Generalization from EllipseBox to AbstractBox

[Direction is 'Source -> Destination'.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) AbstractNode

Target: Protected m box (Class) AbstractBox

OPERATIONS

AbstractBox (): Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

AbstractBox (): Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getBigRadius (): float Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getLength (): float Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getRadius (): float Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getSmallRadius (): float Public Const

Model Report 18 June, 2019 **OPERATIONS** Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getWidth (): float Public Const Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] setBigRadius (radius : float) : void Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] setLength (length: float): void Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] setRadius (radius : float) : void Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setSmallRadius (radius : float) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setWidth (width: float): void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

AbstractNode

Class in package 'Class Model'

AbstractNode Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

INCOMING STRUCTURAL RELATIONSHIPS

INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from CompositeNode to AbstractNode

[Direction is 'Source -> Destination'.]

→ Generalization from Obstacle to AbstractNode

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m box: AbstractBox* Protected

[Is static False. Containment is Not Specified.]

m id: int Private

[Is static False. Containment is Not Specified.]

m_parent : AbstractNode* Private

[Is static False. Containment is Not Specified.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) AbstractNode

Target: Protected m_box (Class) AbstractBox

Association (direction: Source -> Destination)

Source: Public (Class) ObstacleDetectionCommand

Target: Private m root (Class) AbstractNode

Association (direction: Source -> Destination)

Source: Public (Class) TotalSurfaceCalculatorCommand

Target: Private m_root (Class) AbstractNode

OPERATIONS

AbstractNode (): Public

Properties:

initializer = m parent(nullptr),m id(0)

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

AbstractNode (parent : AbstractNode*, id : int) : Public

Properties:

initializer = m_parent(parent),m_id(id)

bodyLocation = classDec

OPERATIONS

acceptVisitor (visitor : AbstractVisitor*) : void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

getBox (): AbstractBox* Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

getID (): int Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getParent () : AbstractNode* Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setBox (box : AbstractBox*) : void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

setID (id : int) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setParent (parent : AbstractNode*) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

toStream (s: std::ostream&): void Public

[Is static False. Is abstract True. Is return array False. Is query False. Is synchronized False.]

BoundingBox

Class in package 'Class Model'

BoundingBox Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from BoundingBox to AbstractBox

[Direction is 'Source -> Destination'.]

OPERATIONS BoundingBox (): Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] BoundingBox (width: float, length: float): Public Properties: initializer = m width(width),m length(length) bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] ~BoundingBox (): Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getLength (): float Public Const Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getWidth (): float Public Const Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] setLength (length: float): void Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] setWidth (width : float) : void Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

CompositeNode

Class in package 'Class Model'

CompositeNode Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from CompositeNode to AbstractNode

[Direction is 'Source -> Destination'.]

INCOMING STRUCTURAL RELATIONSHIPS

→ Generalization from Room to CompositeNode

[Direction is 'Source -> Destination'.]

→ Generalization from House to CompositeNode

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m nodeMap: ComponentMap Private

[Is static False. Containment is Not Specified.]

ASSOCIATIONS

Association (direction: Source -> Destination)

Source: Public (Class) CompositeNode Target: Private m_nodeMap (Class) ComponentMap «typedef»

OPERATIONS

acceptVisitor (visitor : AbstractVisitor*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

addChild (node : AbstractNode*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

void Public (): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

CompositeNode (): Public

Properties:

initializer = AbstractNode()

OPERATIONS [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] CompositeNode (parent : AbstractNode*, id : int) : Public Properties: initializer = AbstractNode(parent, id) [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] ~CompositeNode (): Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] findChild (id: int): bool Public [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getBox (): AbstractBox* Public [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getChild (id: int): AbstractNode* Public [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getMapBeginIterator (): MapIter Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] getMapEndIterator (): MapIter Public Properties: bodyLocation = classDec [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] removeChild (node : AbstractNode*) : AbstractNode* Public [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] removeChild (id : int) : AbstractNode* Public [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] setBox (box : AbstractBox*) : void Public [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.] toStream (s : std::ostream&): void Public return nullptr; [Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

OPERATIONS

EllipseBox

Class in package 'Class Model'

EllipseBox Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from EllipseBox to AbstractBox

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m bigRadius: float Private

[Is static False. Containment is Not Specified.]

m smallRadius: float Private

[Is static False. Containment is Not Specified.]

OPERATIONS

FilipseBox (): Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

EllipseBox (bigRadius : float , smallRadius : float) : Public

Properties:

 $initializer = m_bigRadius(bigRadius), m_smallRadius(smallRadius)$

bodyLocation = classDec

 $[\ Is\ static\ False.\ Is\ return\ array\ False.\ Is\ query\ False.\ Is\ synchronized\ False.\]$

~EllipseBox (): Public

Properties:

bodyLocation = classDec

 $[\ Is\ static\ False.\ Is\ return\ array\ False.\ Is\ query\ False.\ Is\ synchronized\ False.\]$

getBigRadius () : float Public Const

Properties:

bodyLocation = classDec

OPERATIONS

getSmallRadius () : float Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setBigRadius (radius : float) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setSmallRadius (radius : float) : void Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

House

Class in package 'Class Model'

House Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from House to CompositeNode

[Direction is 'Source -> Destination'.]

OPERATIONS



acceptVisitor (visitor : AbstractVisitor*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getBox () : AbstractBox* Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

House () : Public

initializer = CompositeNode()

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

House (parent : AbstractNode*, id : int) : Public

Properties:

initializer = CompositeNode(parent, id)

OPERATIONS

♦ ~House () : Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setBox (box : AbstractBox*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

toStream (s: std::ostream&): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Room

Class in package 'Class Model'

Room
Version 1.0 Phase 1.0 Proposed
bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from Room to CompositeNode

[Direction is 'Source -> Destination'.]

OPERATIONS

acceptVisitor (visitor : AbstractVisitor*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

getBox () : AbstractBox* Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Room (): Public

Properties:

initializer = CompositeNode()

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Room (parent : AbstractNode*, id : int): Public

Properties:

initializer = CompositeNode(parent, id)

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

Room (parent: AbstractNode*, id: int, width: float, length: float): Public

Properties:

OPERATIONS

initializer = CompositeNode(parent, id)

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

~Room (): Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setBox (box : AbstractBox*) : void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

toStream (s: std::ostream&): void Public

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

RoundBox

Class in package 'Class Model'

RoundBox Version 1.0 Phase 1.0 Proposed bodiaa created on 2019-06-18. Last modified 2019-06-18

OUTGOING STRUCTURAL RELATIONSHIPS

Generalization from RoundBox to AbstractBox

[Direction is 'Source -> Destination'.]

ATTRIBUTES

m radius: float Private

[Is static False. Containment is Not Specified.]

OPERATIONS

getRadius (): float Public Const

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

RoundBox (): Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

RoundBox (radius : float) : Public

OPERATIONS

Properties:

 $initializer = m_radius(radius)$

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

RoundBox (): Public

Properties:

bodyLocation = classDec

[Is static False. Is abstract False. Is return array False. Is query False. Is synchronized False.]

setRadius (radius : float) : void Public

Properties:

bodyLocation = classDec