Software Specification

11th of March 2015

2IO70

Version 1.0

The purpose of this document is to give an as accurately as possible description of the required behaviour of the PP2, without describing how this is achieved, and a UPPAAL model of this behaviour. In order to do this, we translate the system level requirements to a high level specification of what the software controlling the physical machine should do.

Group 16

Rolf Verschuuren

Wigger Boelens

Stefan van den Berg

Dat Phung

Maarten Keet

Tudor Petrescu

Table of Contents

Inputs and Outputs

Inputs

[Insert table of inputs to the program]

Outputs

[Insert table of outputs from the program]

Relations

Lens lamp of the black white detector

The lens lamp of the black white detector will go on when the disc is expected at the sensor. We can calculate when we expect a disc according to the speed of the conveyor belt and the input of the photo transistor of the position sensor. The lens lamp goes on when the timer hits calculates time of arrival.

Lens lamp of the position sensor

The lens lamp of the position sensor reacts only to the "START/STOP" button and the "ABORT" button. The lens lamp will be on after the "START/STOP" button is pressed and the machine is in its resting state. If at any other point in time the "ABORT" button is pressed it will go off. When the "START/STOP" button is pressed and the machine is running then the lens lamp also goes off.

Engine of the conveyor belt

The engine of on the conveyor belt only reacts to the input of the "START/STOP" button and the "ABORT" button. The engine will start when the machine is in its resting state and the "START/STOP" button is pressed. If however the "START/STOP" button is pressed and the machine is not in its resting state then the machine will stop after it completed its current cycle. Whenever the "ABORT" button is pressed the engine stops within 50ms.

Engine of the feeder

The engine for the feeder also only reacts to the input of the "START/STOP" button and the "ABORT" button. This engine also starts when the machine is in its resting state and the "START/STOP" button is pressed. If however the machine is running then the engine will stop. When the "ABORT" button is pressed the engine stops within 50ms.

Engine for the sorter

When the machine is running the engine of the sorter reacts to inputs of the colour detector, the push sensor and the timer. When a signal is received from the colour detector the engine pulls the sorter down, the engine then waits until the timer gives a signal to go up again as to let disks

through, it knows when it is in the correct “up” position from the push sensor . If the “START/STOP” button is pressed when the machine is in its resting state, then the sorter will wait for a signal from the timer that marks the end of the current cycle. If at any time the ““ABORT”” button is pressed, the sorting mechanism is to stop within 50ms.

Display for counting

The display output depends on how many times the colour detector detects a white disc and how many times a disc passes the position sensor without the colour detector detecting it.

In the initial state the counters get reset.

Description of States

Initial state

Outputs	Value for output
Lens lamp position	0
Lens lamp sorter	0
Engine conveyor	0
Engine feeder	0
Engine sorter	1
Display	0
LED state indicator	0
Timer start	0

Resting state

Outputs	Value for output
Lens lamp	0
Lens lamp	0
Engine conveyor	0
Engine feeder	0
Engine sorter	0
Display	0
LED state indicator	1
Timer start	0

Running state

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	0
Display	0
LED state indicator	0
Timer start	2 + Belt

Timer Start (Ru, SS = 1)

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	0
Display	0
LED state indicator	0
Timer start	Belt

Running State 2

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	0
Display	0
LED state indicator	0
Timer start	0

Running State 3

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	0
Display	0
LED state indicator	0
Timer start	2 + Belt

Motor Up

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Sort

Motor Up 2

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Sort

Motor Down

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Sort

Motor Up'

Outputs	Value for output
Lens lamp position	0
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	0
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Sort

Motor Up 22

Outputs	Value for output
Lens lamp position	0
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	0
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Sort

Motor Down '

Outputs	Value for output
Lens lamp position	0
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	0
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Sort

Timer Start

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	0
Display	0
LED state indicator	0
Timer start	0

Timer Start 2 (SS = 1)

Outputs	Value for output
Lens lamp position	0
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	0
Engine sorter	1
Display	0
LED state indicator	0
Timer start	Belt

Aborted (A)

Outputs	Value for output
Lens lamp position	0
Lens lamp sorter	0
Engine conveyor	0
Engine feeder	0
Engine sorter	0
Display	0
LED state indicator	0
Timer start	0

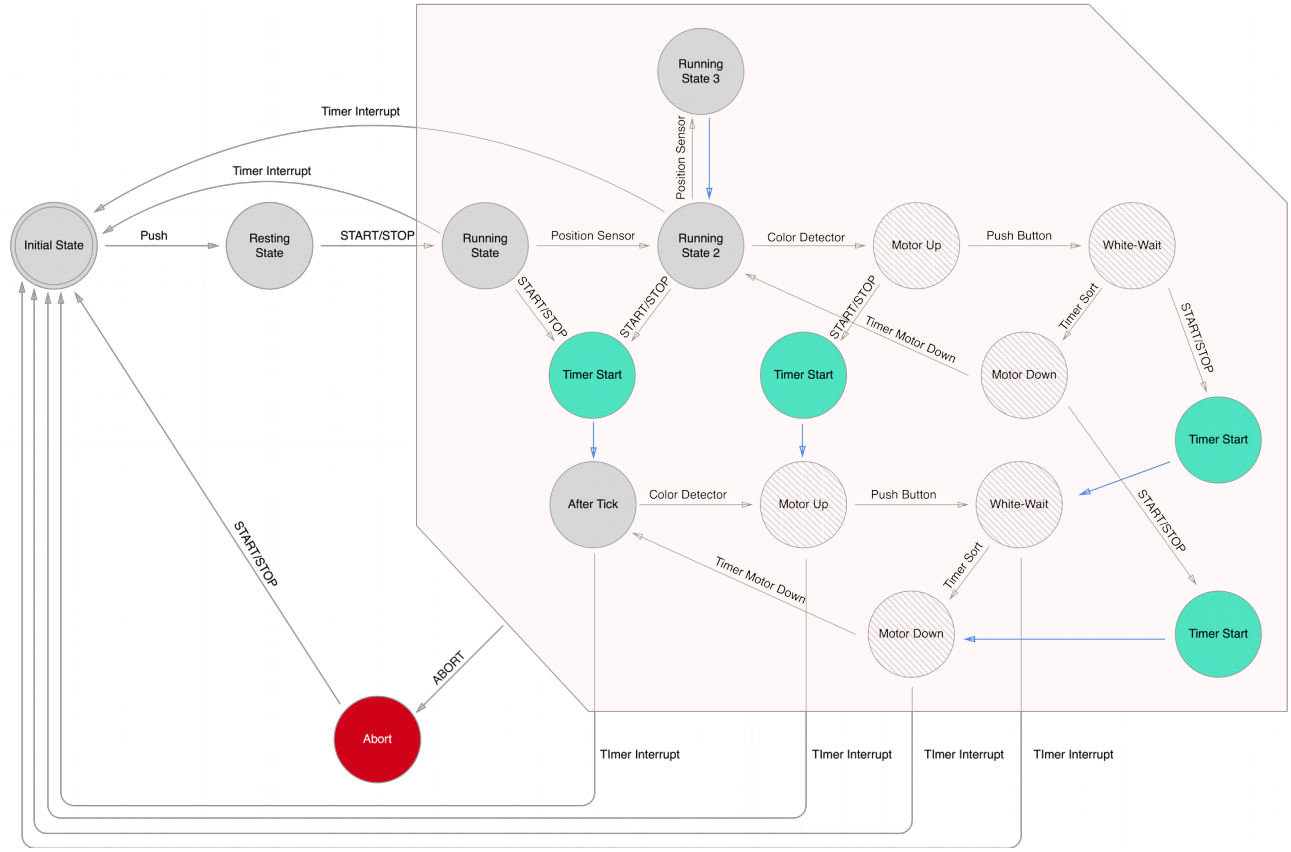
After tick

Outputs	Value for output
Lens lamp position	1
Lens lamp sorter	1
Engine conveyor	1
Engine feeder	1
Engine sorter	0
Display	0
LED state indicator	0
Timer start	Belt

State transitions

Current state	Input	Input value	Next State
Initial	Push	1	Initial2
Initial2	Push	0	Resting
Resting	StartStop	1	Running
Running	Timer	TEnd	Initial
Running	PositionSensor	0	Running2
Running	Abort	1	Aborted
Running	StartStop	1	TimerStart1
Running2	Timer	TEnd	Initial
Running2	PositionSensor	0	Running3
Running2	ColorDetector	1	MotorUp
Running2	StartStop	1	TimerStart1
Running2	Abort	1	Aborted
Running3	Tick	1	Running2
MotorUp	PushButton	1	WhiteWait
MotorUp	StartStop	1	TimerStart2
MotorUp	Abort	1	Aborted
WhiteWait	StartStop	1	TimerStart3
WhiteWait	Abort	1	Aborted
WhiteWait	Timer	SORT	MotorDown
MotorDown	StartStop	1	TimerStart4
MotorDown	Abort	1	Aborted
MotorDown	Timer	Motor Down	Running2
TimerStart	Timer	Tic	After tick
TimerStart2	Timer	Tic	MotorUp2
TimerStart3	Timer	Tic	WhiteWait2
TimerStart4	Timer	Tic	MotorDown2
MotorUp2	PushButton	1	WhiteWait2
MotorUp2	Abort	1	After tick
MotorUp2	Timer	Timer Interrupt	Initial
WhiteWait2	Timer	SORT	MotorDown2
WhiteWait2	Abort	1	Aborted
WhiteWait2	Timer	Timer Interrupt	Initial
MotorDown2	Timer	Motor Down	After tick
MotorDown2	Abort	1	Aborted
MotorDown2	Timer	Timer Interrupt	Initial
After tick	ColorDetector	1	MotorUp2
After tick	Abort	1	Aborted
After tick	Timer	Timer Interrupt	Initial
Aborted	StartStop	1	Initial

Finite state Automaton



- Add state “Inital2” between “Initial” and “Resting”
- The position sensor does not trigger a state change when the input is 1, instead it does when the input is 0
- There are multiple states with the same name

UPPAAL model

[Insert UPPAAL model here]

Validation and Testing

[Insert validation and testing here]