view\_frames Result Recorded at time: 276.493 footprint odom Broadcaster: /gazebo Average rate: 10000.000 Hz Most recent transform: 0.000 (276.493 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate:  $\overline{36.308}$  Hz Average rate: 36.308 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (276.493 sec old) Most recent transform: 276.480 (0.013 sec old) Most recent transform: 276.480 ( 0.013 sec old) Most recent transform: 0.000 (276.493 sec old) Most recent transform: 0.000 (276.493 sec old) Buffer length: 0.000 sec Buffer length: 3.911 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.911 sec right\_wheel lidar\_base caster\_leg arm\_base left\_wheel Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 42.308 Hz Most recent transform: 276.491 (0.002 sec old) Most recent transform: 0.000 (276.493 sec old) Most recent transform: 0.000 (276.493 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.900 sec caster\_wheel lidar\_link torso Broadcaster: /robot\_state\_publisher Average rate: 42.308 Hz Most recent transform: 276.491 (0.002 sec old) Buffer length: 3.900 sec arm Broadcaster: /robot\_state\_publisher Average rate: 42.308 Hz Most recent transform: 276.491 (0.002 sec old) Buffer length: 3.900 sec elbow Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 42.308 Hz Average rate: 10000.000 Hz Most recent transform: 276.491 (0.002 sec old) Most recent transform: 0.000 (276.493 sec old) Buffer length: 3.900 sec Buffer length: 0.000 sec hand\_base camera\_link Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (276.493 sec old) Buffer length: 0.000 sec hand\_palm Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (276.493 sec old) Buffer length: 0.000 sec hand\_right\_finger Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (276.493 sec old) Buffer length: 0.000 sec hand\_left\_finger