## Inhibitor Petri Nets

- addendum to CDC -

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## 1 Inhibitor Nets. Why?

Two workers (robots)  $P_1$  and  $P_2$  want to produce certain goods in two steps:  $P_1$  completes the first step, then stores the goods, and  $P_2$  takes the goods and completes the second step. Suppose  $P_1$  is allowed to take a break whenever he wants, but  $P_2$  is allowed to do it only when no goods are stored.

The PN in Figure 1 is not a sound model of this problem because  $P_2$  can

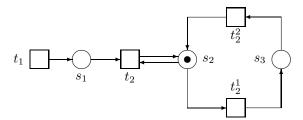


Figure 1

take a break when  $s_1$  still holds goods. The meaning of the elements in the net are:

- $t_1 P_1$ ;
- goods are stored in  $s_1$ ;
- $t_2 P_2$ ;
- $t_2^1 P_2$  takes a break;
- $t_2^2 P_2$  back to work.

**Definition 1** An *Inhibitor Petri Net*, abbreviated IPN, is a pair  $\gamma = (\Sigma, I)$ , where  $\Sigma$  is a PN and  $I \subseteq S \times T$  such that  $F \cap I = \emptyset$ .

Elements of I are represented as in Figure 2.

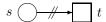


Figure 2

**Definition 2** Let  $\gamma = (\Sigma, I)$  be an inhibitor Petri net, M a marking of  $\gamma$  and  $t \in T$ .

- (1)  $M[t\rangle_{\gamma,i}$  if:
  - (a)  $M[t\rangle_{\Sigma};$
  - (b) M(s) = 0, for all  $s \in S$  such that  $(s, t) \in I$ .
- (2)  $M[t\rangle_{\gamma,i}M'$  if  $M[t\rangle_{\gamma,i}$  and  $M[t\rangle_{\Sigma}M'$ .

The IPN in Figure 3 is a sound model of the problem above.

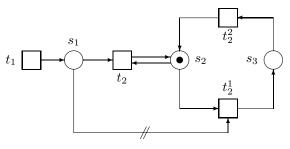


Figure 3

## 2 Inhibitor Nets and 1-inhibitor Nets

**Definition 3** A k-inhibitor Petri net  $(k \ge 0)$ , abbreviated k-IPN, is an inhibitor Petri net  $\gamma = (\Sigma, I)$  such that  $|\{s \in S | (s, t) \in I\}| \le k$ , for all  $t \in T$ .

**Lemma 1** Let  $\gamma = (\Sigma, I, M_0)$  be a marked inhibitor Petri net and  $cod(I) = \{t_1, \ldots, t_r\}, r \geq 1$ . Then, there exists an 1-inhibitor Petri net  $\gamma' = (\Sigma', I', M_0')$  such that:

- (1)  $S' = S \cup \{s_{t_1}, \dots, s_{t_r}\}\ (s_{t_i} \notin S \text{ for any } 1 \le i \le r);$
- (2) T' = T;

- (3)  $I' = \{(s_{t_i}, t_i) | 1 \le i \le r\};$
- (4)  $M'_0 = (\underbrace{M_0}_S, \underbrace{\beta_1}_{s_{t_1}}, \dots, \underbrace{\beta_r}_{s_{t_r}})$ , where,

$$\beta_i = \sum_{s \in S, (s, t_i) \in I} M_0(s),$$

for all  $1 \le i < r$ ;

(5) each reachable marking M' in  $\gamma'$  is of the form

$$M' = (\underbrace{M}_{S}, \underbrace{\alpha_{1}}_{s_{t_{1}}}, \dots, \underbrace{\alpha_{r}}_{s_{t_{r}}}),$$

where M is reachable in  $\gamma$  and

$$\alpha_i = \sum_{s \in S, (s,t_i) \in I} M(s),$$

for all  $1 \le i \le r$ ;

(6) if  $M \in \mathbf{N}^S$  then, for every  $w \in T^*$ ,

$$M_0[w\rangle_{\gamma,i}M \Leftrightarrow M_0'[w\rangle_{\gamma',i}(M,\alpha_1,\ldots,\alpha_r),$$

where  $\alpha_1, \ldots, \alpha_r$  are as in (5);

(7)  $FiringSequences(\gamma) = FiringSequences(\gamma')$ .

**Proof.** Let  $\gamma = (\Sigma, I, M_0)$  be an inhibitor net,  $\Sigma = (S, T, F, W)$ , and

$$cod(I) = \{t_1, \dots, t_r\} \quad (r \ge 1).$$

The basic idea to construct  $\gamma'$  is:

- if transition t tests places  $s_1, \ldots, s_k$   $((s_i, t) \in I)$ , for all  $1 \le i \le k$ , then we consider a new place  $s_t$  such that for every marking M' of  $\gamma'$  the following holds:

$$M'(s_t) = 0 \Leftrightarrow (\forall 1 \le i \le k)(M'(s_i) = 0).$$

Then, it will be enough for t to test only  $s_t$  (in  $\gamma'$ ).

The definition of  $\gamma'$  is:

- $S' = S \cup \{s_{t_1}, \dots, s_{t_r}\}$  (a new place  $s_{t_i}$  is associated to each transition  $t_i \in cod(I)$ , for any  $1 \le i \le r$ );
- T' = T;

- 
$$F' = F \cup \bigcup_{t \in cod(I)} \{ (s_t, t') | \exists s' \in S : (s', t) \in I \land (s', t') \in F \}$$
  
  $\cup \bigcup_{t \in cod(I)} \{ (t', s_t) | \exists s' \in S : (s', t) \in I \land (t', s') \in F \};$ 

$$- W'(x,y) = \left\{ \begin{array}{ll} W(x,y), & \text{if } (x,y) \in F \\ W(s',t'), & \text{if } \exists t \in cod(I), \ \exists t' \in T', \ \exists s' \in S: \\ & (s',t) \in I, \ (s',t') \in F, \ (x,y) = (s_t,t') \\ W(t',s'), & \text{if } \exists t \in cod(I), \ \exists t' \in T', \ \exists s' \in S: \\ & (s',t) \in I, \ (t',s') \in F, \ (x,y) = (t',s_t); \end{array} \right.$$

- $I' = \{(s_t, t) | t \in cod(I)\};$
- $M_0' = (M_0, \beta_1, \dots, \beta_r)$ , where

$$\beta_i = \sum_{s \in S, (s, t_i) \in I} M_0(s),$$

for all  $1 \le i \le r$ .

 $\gamma'$  is an 1-inhibitor net and satisfies (1)-(7).  $\square$ 

## 3 Reachability, Coverability, Boundedness and Liveness for Inhibitor Petri Nets

Let  $A = (Q, q_0, q_f, C, x_0, I)$  be a CM. Define an 1-inhibitor Petri net as follows:

- associate a place  $s_u$  to each  $u \in Q \cup C$ ;
- associate a transition t to each instruction I(q, c, q'), as follows:

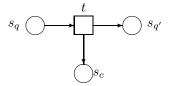


Figure 4

• associate two transitions t' and t'' to each instruction I(q,c,q',q''), as follows:

A configuration  $\sigma = (q, x)$  of A is simulated by the marking M given by:

$$\begin{array}{lcl} M_{\sigma}(s_q) & = & 1, \\ M_{\sigma}(s_{q'}) & = & 0, & \forall q' \in Q - \{q\}, \\ M_{\sigma}(s_c) & = & x(c), & \forall c \in C. \end{array}$$

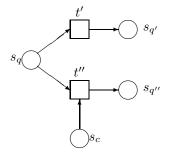


Figure 5 æ

Let  $M_0$  be the marking corresponding to the initial configuration. Let J be the set of pairs  $(s_c, t')$ .

The net  $\gamma = (\Sigma, J, M_0)$  such defined is an 1-inhibitor Petri net. Moreover:

(\*)  $\sigma = (q, x)$  is reachable in A from  $\sigma_0 = (q_0, x_0)$  iff  $M_{\sigma}$  is reachable in  $\gamma$  from  $M_0$ .

Define now 3 new nets obtained from  $\gamma$  as follows.

Let  $\Sigma_1$  be the net in Figure 6, where  $t_1, \ldots, t_r$  are new transitions associated to places  $s \in S - \{q_f\}$  (one transition to each place).

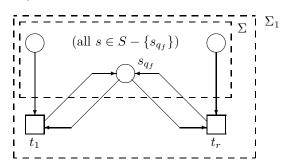


Figure 6

Let  $\Sigma_2$  be the net in Figure 7, where  $s^*$  is a new place. Let  $\Sigma_3$  be the net in Figure 8, where  $t^*$  is a new transition. Let  $\gamma_i = (\Sigma_i, J, M_0^i)$ , where

$$M_0^1 = M_0^3 = M_0$$

and

$$M_0^2(y) = \begin{cases} M_0(y), & y \in S \\ 0, & y = s^* \end{cases}$$

 $\gamma_i$  is an 1-inhibitor net. Moreover:

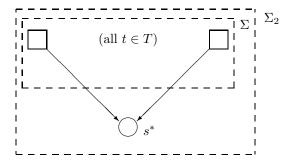


Figure 7

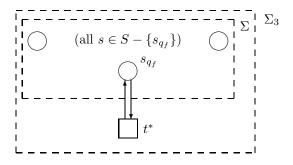


Figure 8

- (1) A marking M such that  $M(s_{q_f})=1$  is reachable in  $\gamma$  iff A halts;
- (2) The marking  $M(y) = \begin{cases} 1, & y = s^* \\ 0, & \text{otherwise} \end{cases}$  is coverable in  $\gamma_1$  iff A halts;
- (3)  $\gamma_2$  is bounded iff A halts;
- (3)  $t^*$  (in  $\gamma_3$ ) is live iff A halts.

 ${\bf Theorem~1~} \ {\bf The~reachable,~coverability,~boundedness~and~liveness~problem~are~all~undecidable~for~inhibitor~Petri~nets.$ 

**Theorem 2** The family of languages generated by (labeled) inhibitor Petri nets equals the family of type 0 Chomsky languages (or, the family of languages accepted by Turing machines).