AHB-Lite Platform Level Interrupt Controller

Datasheet

1st October, 2017

Contents

1. AHB-Lite PLIC

The Roa Logic AHB-Lite PLIC (Platform Level Interrupt Controller) IP is a fully parameterised soft IP implementing a Interrupt Controller as specified by the *RISC-V Privileged v1.9.1 specification*.

The IP features an AHB-Lite Slave interface, with all signals defined in the *AMBA 3 AHB-Lite v1.0* specifications fully supported. Bus address and data widths as well as the number of Interrupt Sources and Targets supported are specified via parameters.

The controller further supports user defined priority levels and pending events, in addition to interrupt masking via programmable priority thresholds.
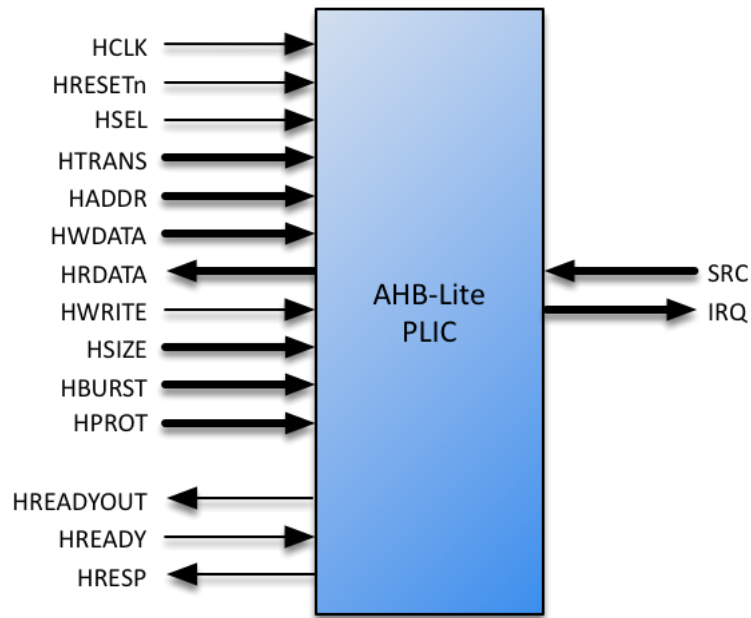

Figure 1.1: PLIC Port Diagram

1.1   Features

- AHB-Lite Interface with parameterised address and data width

- User defined number of Interrupt Sources and Targets

- User defined priority level per Interrupt Source

- Interrupt masking per target via Priority Threshold support

- User defined Interrupt Pending queue depth per source

2. Specifications

2.1 Functional Description

The AHB-Lite PLIC IP core is a fully parameterised Platform-Level Interrupt Controller, featuring a single AHB-Lite Slave interface and interfaces to a user-defined number of both Interrupt Sources and Targets.

The purpose of the PLIC core is to connect multiple interrupt sources to one or more interrupt targets. The core supports a programmable number of simultaneous pending interrupt requests per source and routing of those interrupt requests to individual targets.

Per the RISC-V Privileged Architecture Instruction Set specification (v1.9.1), the core performs full interrupt prioritisation of each interrupt source; each may be assigned a separate priority and enabled per target via a matrix of interrupt enable bits. Further, an optional threshold per target may be defined to mask lower priority interrupts.

To reduce latency, the PLIC core presents all asserted interrupts to the target in priority order, queuing them so that a software interrupt handler can service all interrupts without the need to restore the interrupted context.

An example use of the PLIC core is shown below:
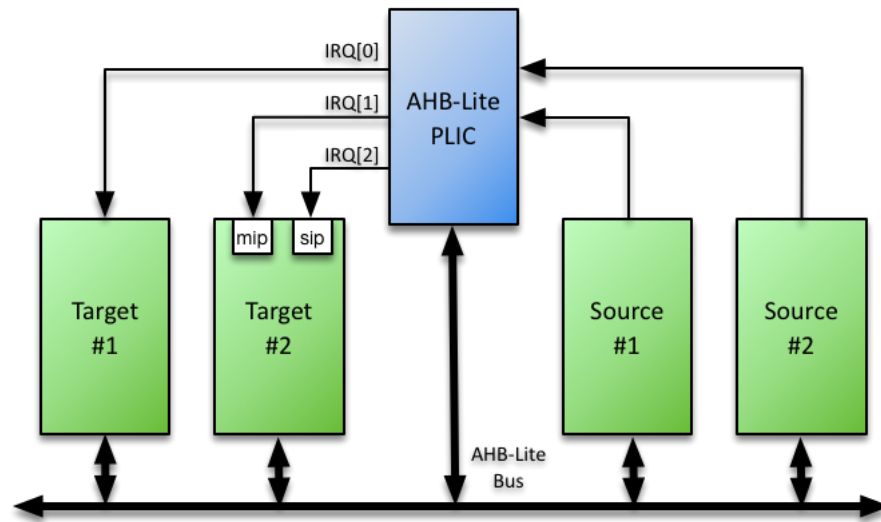
Figure 2.1: PLIC System Diagram

2.2 Interrupt Handling Handshake

The Roa Logic implementation of the handshake between Interrupt source, target and PLIC is illustrated below, and described in further detail in the following sections:
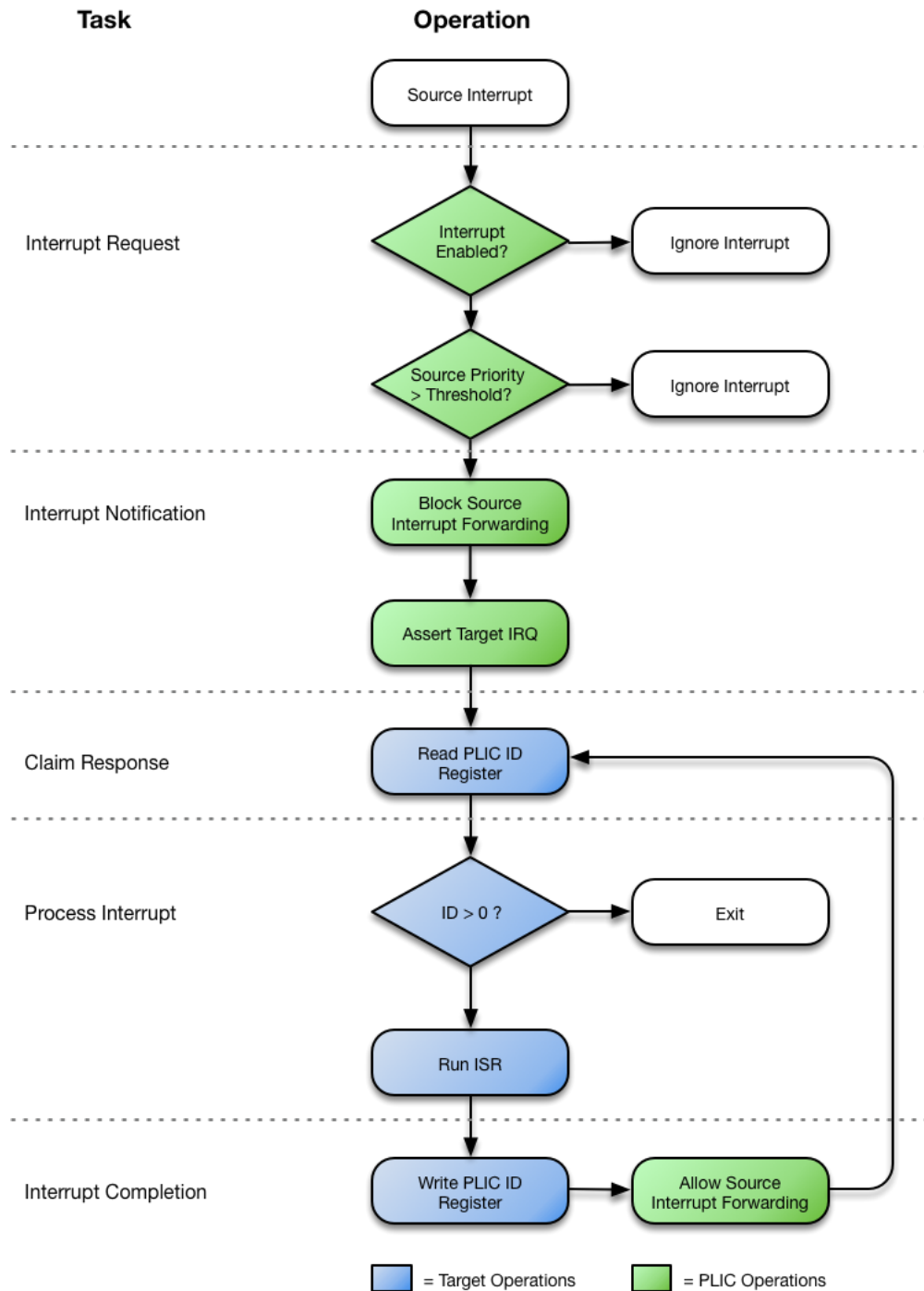
Figure 2.2: Interrupt Handling handshake

2.2.1   PLIC Configuration

A matrix of Interrupt Enable vectors – one IE register per target – determines which target processes the interrupts from which source.

Each Interrupt Source attached to the PLIC is then assigned a Priority Level – an unsigned integer that determines the relative priority of the interrupt source. The greater

the integer, the greater the priority level. A Priority Threshold per target may also be defined to mask lower priority interrupts such that interrupts will only be presented to a target if the assigned Priority Level is greater than the Priority Threshold.

In addition each source is automatically assigned an Interrupt Identifier (`ID`) – an unique unsigned integer. This identifier determines interrupt priority when 2 or more interrupts with the same priority level are asserted. The lower the `ID` assigned to the source, the greater the interrupt priority.

2.2.2   Interrupt Request

A source asserts an interrupt request to the PLIC. The PLIC validates the request by first checking if an interrupt enable bit is set for each target and if the priority of the interrupt source exceeds any defined Interrupt Priority Threshold. If these conditions do not hold, the Interrupt Request is deemed invalid and stalled pending updates to the interrupt enable and/or priority threshold bits.

The PLIC also determines if a previous interrupt request has been made by the same source. If an interrupt is defined as level triggered and has already been asserted but not yet serviced, the request is ignored. If an interrupt is defined as edge triggered and has already been asserted but not yet serviced, the request is queued by incrementing a Interrupt Pending counter by one. The depth of this counter is parameterised.

If the request is deemed valid the request is forwarded to the appropriate target. In the case of queued edge-triggered requests, the interrupt pending counter is decremented by one immediately upon claim of the interrupt by the target.

2.2.3   Interrupt Notification

A target is notified of an interrupt request by the assertion of the IRQ output for the relevant target. The PLIC also blocks the forwarding of any further requests from the interrupt source until the asserted request is serviced.

On each clock cycle the ID register is loaded with the unique identifier of the highest priority interrupt to be processed.

2.2.4   Claim Response

A target makes an interrupt claim response by reading the ID register, which also notifies the target of the interrupt source to service. The PLIC de-asserts the IRQ output for the target in response to the claim. unless another, lower priority, interrupt is still pending.

2.2.5   Interrupt Handler

If the ID read is greater than zero, the target services the identified interrupt source. If the ID read is zero, this indicates no outstanding pending interrupts remain and the handler may terminate.

2.2.6   Interrupt Completion

Once an interrupt has been serviced, completion is signalled to the PLIC by writing to the ID register. The act of writing to the register is the completion notification; the value written is irrelevant.

On receiving the completion notification the PLIC will again allow interrupts to be forwarded from the corresponding source.

The Interrupt Handler may then exit, however it is possible a new interrupt request may have been asserted while the handler was running. To reduce latency the handler may instead determine if a new interrupt has been received and if so again claim the interrupt (See earlier). In this way the interrupt handler can service all interrupts without the need to restore the interrupted context.

3. Configurations

3.1 Core Parameters

The size and implementation style of the PLIC module is defined via HDL parameters as specified below:

Parameter	Type	Default	Description
AHB Interface:			
HADDR_SIZE	Integer	32	Width of AHB Address Bus
HDATA_SIZE	Integer	32	Width of AHB Data Buses
PLIC Configuration:			
SOURCES	Integer	16	Number of Interrupt Sources
TARGETS	Integer	4	Number of Interrupt Targets
PRIORITIES	Integer	8	Number of Priority Levels
MAX_PENDING_COUNT	Integer	8	Max number of pending events
HAS_THRESHOLD	Integer	1	Is Threshold Implemented
HAS_CONFIG_REG	Integer	1	Is Config Reg. Implemented

Table 3.1: Core Parameters

3.1.1 HADDR_SIZE

The HADDR_SIZE parameter specifies the address bus size to connect to the AHB-Lite based host. Valid values are 32 and 64. The default value is 32.

3.1.2 HDATA_SIZE

The HDATA_SIZE parameter specifies the data bus size to connect to the AHB-Lite based host. Valid values are 32 and 64. The default value is 32

3.1.3 SOURCES

The SOURCES parameter defines the number of individual interrupt sources supported by the PLIC IP. The default value is 16. The minimum value is 1.

3.1.4 TARGETS

The TARGETS parameter defines the number of targets supported by the PLIC IP. The default value is 4. The minimum value is 1.

3.1.5   PRIORITIES

The PLIC IP supports prioritisation of individual interrupt sources. The `PRIORITIES` parameter defines the number of priority levels supported by the PLIC IP. The default value is 8. The minimum value is 1.

3.1.6   MAX_PENDING_COUNT

The PLIC module supports multiple concurrently arriving interrupt requests. The maximum number of requests that are supported is defined by the `MAX_PENDING_COUNT` parameter.

Expand MAX_PEND explanation

The default value is 8. The minimum value is 0.

3.1.7   HAS_THRESHOLD

The PLIC module supports interrupt thresholds – the masking of individual interrupt sources based on their priority level. The `HAS_THRESHOLD` parameter defines if this capability is enabled.

The default value is enabled ('1'). To disable, this parameter should be set to '0'.

3.1.8   HAS_CONFIG_REG

The PLIC module supports an optional Configuration Register, which is documented in section 0. The `HAS_CONFIG_REG` parameter defines if this capability is enabled.

The default value is enabled (1'). To disable this parameter should be set to '0'.

4. Interfaces

4.1 AHB-Lite Interface

The AHB-Lite interface is a regular AHB-Lite slave port. All signals are supported. See the *AMBA 3 AHB-Lite Specification* for a complete description of the signals.

Port	Size	Direction	Description
HRESETn	1	Input	Asynchronous active low reset
HCLK	1	Input	Clock Input
HSEL	1	Input	Bus Select
HTRANS	2	Input	Transfer Type
HADDR	HADDR_SIZE	Input	Address Bus
HWDATA	HDATA_SIZE	Input	Write Data Bus
HRDATA	HDATA_SIZE	Output	Read Data Bus
HWRITE	1	Input	Write Select
HSIZE	3	Input	Transfer Size
HBURST	3	Input	Transfer Burst Size
HPROT	4	Input	Transfer Protection Level
HREADYOUT	1	Output	Transfer Ready Output
HREADY	1	Input	Transfer Ready Input
HRESP	1	Output	Transfer Response

Table 4.1: PLIC Interface Signals

4.1.1 HRESETn

When the active low asynchronous HRESETn input is asserted ('0'), the interface is put into its initial reset state.

4.1.2 HCLK

HCLK is the interface system clock. All internal logic for the AHB-Lite interface operates at the rising edge of this system clock and AHB bus timings are related to the rising edge of HCLK.

4.1.3 HSEL

The AHB-Lite interface only responds to other signals on its bus – with the exception of the global asynchronous reset signal HRESETn – when HSEL is asserted ('1'). When HSEL is negated ('0') the interface considers the bus IDLE.

4.1.4 HTRANS

HTRANS indicates the type of the current transfer as shown in Table 4.2

HTRANS	Type	Description
00	IDLE	No transfer required
01	BUSY	Connected master is not ready to accept data, but intents to continue the current burst.
10	NONSEQ	First transfer of a burst or a single transfer
11	SEQ	Remaining transfers of a burst

Table 4.2: HTRANS Signal Types

4.1.5 HADDR

HADDR is the address bus. Its size is determined by the HADDR_SIZE parameter and is driven to the connected peripheral.

4.1.6 HWDATA

HWDATA is the write data bus. Its size is determined by the HDATA_SIZE parameter and is driven to the connected peripheral.

4.1.7 HRDATA

HRDATA is the read data bus. Its size is determined by the HDATA_SIZE parameter and is sourced by the connected peripheral.

4.1.8 HWRITE

HWRITE is the read/write signal. HWRITE asserted ('1') indicates a write transfer.

4.1.9 HSIZE

HSIZE indicates the size of the current transfer as shown in table 4.3:

HSIZE	Size	Description
000	8 bit	Byte
001	16 bit	Half Word
010	32 bit	Word
011	64 bits	Double Word
100	128 bit	
101	256 bit	
110	512 bit	
111	1024 bit	

Table 4.3: HSIZE Values

4.1.10 HBURST

HBURST indicates the transaction burst type – a single transfer or part of a burst.

HBURST	Type	Description
000	SINGLE	Single access**
001	INCR	Continuous incremental burst
010	WRAP4	4-beat wrapping burst
011	INCR4	4-beat incrementing burst
100	WRAP8	8-beat wrapping burst
101	INCR8	8-beat incrementing burst
110	WRAP16	16-beat wrapping burst
111	INCR16	16-beat incrementing burst

Table 4.4: HBURST Types

4.1.11 HPROT

The `HPROT` signals provide additional information about the bus transfer and are intended to implement a level of protection.

Bit#	Value	Description
3	1	Cacheable region addressed
	0	Non-cacheable region addressed
2	1	Bufferable
	0	Non-bufferable
1	1	Privileged Access
	0	User Access
0	1	Data Access
	0	Opcode fetch

Table 4.5: HPROT Indicators

4.1.12 HREADYOUT

`HREADYOUT` indicates that the current transfer has finished. Note, for the AHB-Lite PLIC this signal is constantly asserted as the core is always ready for data access.

4.1.13 HREADY

`HREADY` indicates whether or not the addressed peripheral is ready to transfer data. When `HREADY` is negated ('0') the peripheral is not ready, forcing wait states. When `HREADY` is asserted ('1') the peripheral is ready and the transfer completed.

4.1.14 HRESP

`HRESP` is the instruction transfer response and indicates OKAY ('0') or ERROR ('1').

4.2 PLIC Interface

The PLIC provides a single input bus to which all interrupt sources must connect, one bit of the bus per source. A single output bus similarly connects to all interrupt targets, one bit per target. The width of each of these interface buses is specified as a core parameter.

Port	Size	Direction	Description
SRC	SOURCES	Input	Interrupt Sources
IRQ	TARGETS	Output	Interrupt Requests

Table 4.6: PLIC Interface Signals

4.2.1 SRC

Interrupt sources connect to the SRC[SOURCES-1..0] input of the PLIC module. The width of this interface is defined by the SOURCES parameter.

4.2.2 IRQ

Interrupt targets are sourced by the IRQ[TARGETS-1..0] output of the PLIC module. The width of this interface is defined by the TARGETS parameter.

4.3 Register Interface

The operation and run-time configuration of the PLIC is managed via a memory mapped register interface consisting of the following registers:

Register	Registers	Width (bits)	Mode	Function
CONFIG	1	64	RO	Configuration
EL	1	SOURCES	RW	Edge/Level Trigger
IE	TARGETS	SOURCES	RW	Interrupt Enable
ID	TARGETS	$\text{clog}_2(\text{SOURCES})$	RW	ID of Highest priority IRQ, Int. Claim (R), Int. Complete (W)
PRIORITY	SOURCES	$\text{clog}_2(\text{PRIORITIES})$	RW	Priority Level
THRESHOLD	TARGETS	$\text{clog}_2(\text{PRIORITIES})$	RW	Priority Threshold

Table 4.7: PLIC Register Interface

Note: $\text{clog}_2()$ refers to the System Verilog function by the same name, defined as:

The system function \$clog2 shall return the ceiling of the log base 2 of the argument (the log rounded up to an integer value). The argument can be an integer or an arbitrary sized vector value. The argument shall be treated as an unsigned value, and an argument value of 0 shall produce a result of 0.

4.3.1 Register Descriptions

The purpose and functionality of each register of the interface is documented in the following sections:

CONFIG

The `CONFIG` register is a Read-Only register that enables a software routine to determine the hardware configuration of the PLIC module.

When enabled via the `HAS_CONFIG_REG` hardware parameter, the `CONFIG` register returns a 64 bit value constructed as follows:

Bit Position	63		49	48	47		32	31		16	15		0
Value		0		HAS_THRESHOLD		PRIORITIES			TARGETS			SOURCES	

Figure 4.1: Configuration Register

The values, `HAS_THRESHOLD`, `PRIORITIES`, `TARGETS` and `SOURCES` correspond to the hardware parameters documented in section 3.1 Core Parameters.

The `CONFIG` register is always 64 bits. For 32 bit implementations this means 2 physical registers are required, 1 each for the upper and lower word. For 64 bit implementations a single register will be implemented.

EL

The `EL` Read/Write register defines if an interrupt source is Edge or Level Triggered.

The number of interrupt sources, as defined by the `SOURCES` parameter, determines the width of the `EL` register. One bit within the register corresponds to an interrupt source, where a logic high ('1') defines a rising-edge triggered interrupt and a logic low ('0') defines a level triggered interrupt. These bits will be packed into the minimum number of registers.

The physical number of registers implemented can be calculated as follows:

```
No. of Registers = ROUNDUP(SOURCES/HDATA_SIZE)
```

Example: For a 32 bit system supporting 48 interrupt sources

```
No. of Registers = ROUNDUP(SOURCES/HDATA_SIZE)
                 = ROUNDUP(48/32)
                 = ROUNDUP(1.5)
                 = 2
```

IE[]

A matrix of `IE[]` Read/Write registers define if an interrupt source is enabled or disabled for a specific target. When disabled, any interrupts generated by the source will be ignored by the PLIC.

The number of targets determines the number of `IE[]` registers. The number of interrupt sources, as defined by the `SOURCES` parameter, determines the width of each `IE[]` register.

One bit within the register corresponds to an individual interrupt source, where a logic high ('1') defines an interrupt source as enabled and a logic low ('0') as disabled. These bits will be packed into the fewest registers possible and the resulting number of registers calculated as follows:

```
No. of Registers = ROUNDUP(SOURCES/HDATA SIZE)*TARGETS
```

Example: For a 32 bit system supporting 48 interrupt sources and 4 targets

```
No. of Registers = ROUNDUP(SOURCES/HDATA_SIZE)*TARGETS
                 = ROUNDUP(48/32)*4
                 = ROUNDUP(1.5)*4
                 = 2*4
                 = 8
```

ID[]

The `ID[]` Read/Write register identifies to each target the ID of the highest priority pending interrupt request.

```
No. of Registers = TARGETS
```

This register indicates to the target which of potentially multiple pending interrupts should be serviced rather than relying on this being resolved by the software Interrupt Service Routine.

When a target reads this register, this also indicates the target has claimed the interrupt for the defined source and will service then service the interrupt source.

A target then writes to this register to indicate completion of servicing the interrupt source. It is the action of writing to this register which generates the interrupt completion notification – the value written will not update the register which continues to identify the highest priority interrupt source to be serviced.

PRIORITY[]

The `PRIORITY[]` Read/Write registers define the priority level of each interrupt source. Interrupt priority increases with larger values of `PRIORITY`.

Each interrupt source can be assigned a priority, which is defined as positive integer. The PLIC parameter `PRIORITIES` defines the number of priority levels for a specific implementation, which then allows a source to be assigned a priority between 1 and `PRIORITIES`.

These priority levels are packed into `HDATA SIZE` bit registers, as fields aligned to 4-bit nibble boundaries

```
No. of Registers = ROUNDUP(SOURCES/FPR)
```

where:

```
FPR = FIELDS_PER_REGISTER
    = HDATA_SIZE/(4*NPP)


NPP = NIBBLES_PER_PRIORITY
    = ROUNDUP($clog2(PRIORITIES+1)/4)
```

Example: For a 32 bit system supporting 48 interrupt sources and 8 priority levels

```
NPP = NIBBLES_PER_PRIORITY
    = ROUNDUP($clog2(PRIORITIES+1)/4)
    = ROUNDUP($clog2(8+1)/4)
    = ROUNDUP(4/4)
    = 1


FPR = FIELDS_PER_REGISTER
    = HDATA_SIZE/(4*NPP)
    = 32/(4*1)
    = 8


No. of Registers = ROUNDUP(SOURCES/FPR)
                 = ROUNDUP(48/8)
                 = 6
```

Note: $clog_2()$ refers to the System Verilog function by the same name and calculates the number of binary bits required to represent a given integer.

THRESHOLD[]

Each target may be assigned a priority threshold via the THRESHOLD[] registers and therefore the PLIC implements 1 register per threshold.

```
No. of Registers = TARGETS
```

Only active interrupts that have a priority strictly greater than the threshold will cause an interrupt notification to be sent to the target. A THRESHOLD[] value of 0 means that no interrupts will be masked.

4.3.2   Register Address Map

The PLIC supports a wide variety of options and unlimited user-definable number of both interrupt sources and targets. To configure and control the PLIC requires a memory-mapped register interface that must be defined according to the specific implementation.

To ease the development of PLIC based systems, the Roa Logic PLIC implements a dynamic register interface based on the hardware parameters set during generation of the implementation, packing multiple bit-fields into registers where feasible to minimise the required address space.

The following sections describe the calculations performed during generation of the dynamic register interface so that the user may determine the registers available and the memory mapping of those registers for a given implementation.

A spreadsheet in Microsoft Excel format is available to perform these calculations based on user-defined parameters to show the registers and memory mapping. Further, simulation of the PLIC will also shows the registers and memory mapping.

The order of the registers in the memory map is defined as Table 4.8.

Order	Registers
1	CONFIG Register(s)
2	EL Registers
3	PRIORITY Registers
4	IE Registers
5	THRESHOLD Registers
6	ID Registers

Table 4.8: Register Address Order

Registers are mapped to consecutive addresses based on this order and the number of registers required.

4.3.3 Register Address Map Example

Using the example of a 32 bit system supporting 48 interrupt sources, 4 targets and 8 priority levels as shown in Table 4.9:

Parameter	Number
HDATA_WIDTH	32
SOURCES	48
TARGETS	4
PRIORITIES	8

Table 4.9: Example Parameters

The resulting number of registers is:

Registers	Number
CONFIG	2
EL	2
PRIORITY	6
IE	8
THRESHOLD	4
ID	4
Total	**26**

Table 4.10: No of Registers

These registers will be then mapped as follows according to the order defined in Table 4.8:

Reg	Parameter	Value
0	0x0	CONFIG
1	0x4	CONFIG
2	0x8	EL
3	0xC	EL
4	0x10	PRIORITY
5	0x14	PRIORITY
6	0x18	PRIORITY
7	0x1C	PRIORITY
8	0x20	PRIORITY
9	0x24	PRIORITY
10	0x28	IE
11	0x2C	IE
12	0x30	IE
13	0x34	IE
14	0x38	IE
15	0x3C	IE
16	0x40	IE
17	0x44	IE
18	0x48	THRESHOLD
19	0x4C	THRESHOLD
20	0x50	THRESHOLD
21	0x54	THRESHOLD
22	0x58	ID
23	0x5C	ID
24	0x60	ID
25	0x64	ID

Table 4.11: Example Address Map

Note: When simulating the PLIC, the simulator will print a detailed Register Address Mapping showing explicitly how each interrupt source and target maps to the register fields. A Microsoft Excel worksheet is also available from the Roa Logic web site showing the same Address Map.

Figure 4.2: Register Mapping Worksheet

4.4 Resources

Below are some example implementations for various platforms.

All implementations are push button, no effort has been undertaken to reduce area or improve performance.

Platform	DFF	Logic Cells	Memory	Performance (MHz)

Table 4.12: Resource Utilisation Examples

4.5 References

The PLIC is designed to be compliant with the following specifications, as licensed under the Creative Commons Attribution 4.0 International License:

"The RISC-V Instruction Set Manual, Volume I: User-Level ISA, Document Version 2.2", Editors Andrew Waterman and Krste Asanović,RISC-V Foundation, May 2017.

"The RISC-VInstruction Set Manual, Volume II: Privileged Architecture, Version 1.9.1",Editors Andrew Waterman and Krste Asanović, RISC-V Foundation, November 2016

4.6   Revision History

Date	Rev.	Comments
October, 2017	1.0	Initial Release
** **		
** **		
** **		

Table 4.13: Revision History

Todo list