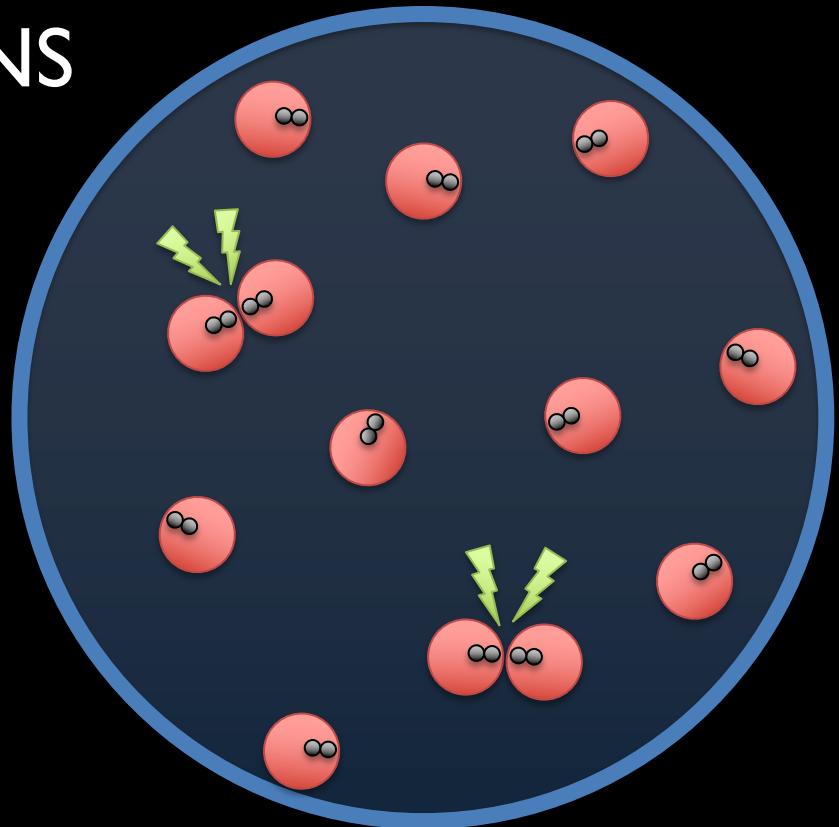


CASA0011:Agent-Based Modelling for Spatial Systems

Dr Thomas OLÉRON EVANS
Dr Sarah WISE

thomas.evans.11@ucl.ac.uk
s.wise@ucl.ac.uk

Centre for Advanced
Spatial Analysis,
90 Tottenham Court Road



The ABM Course

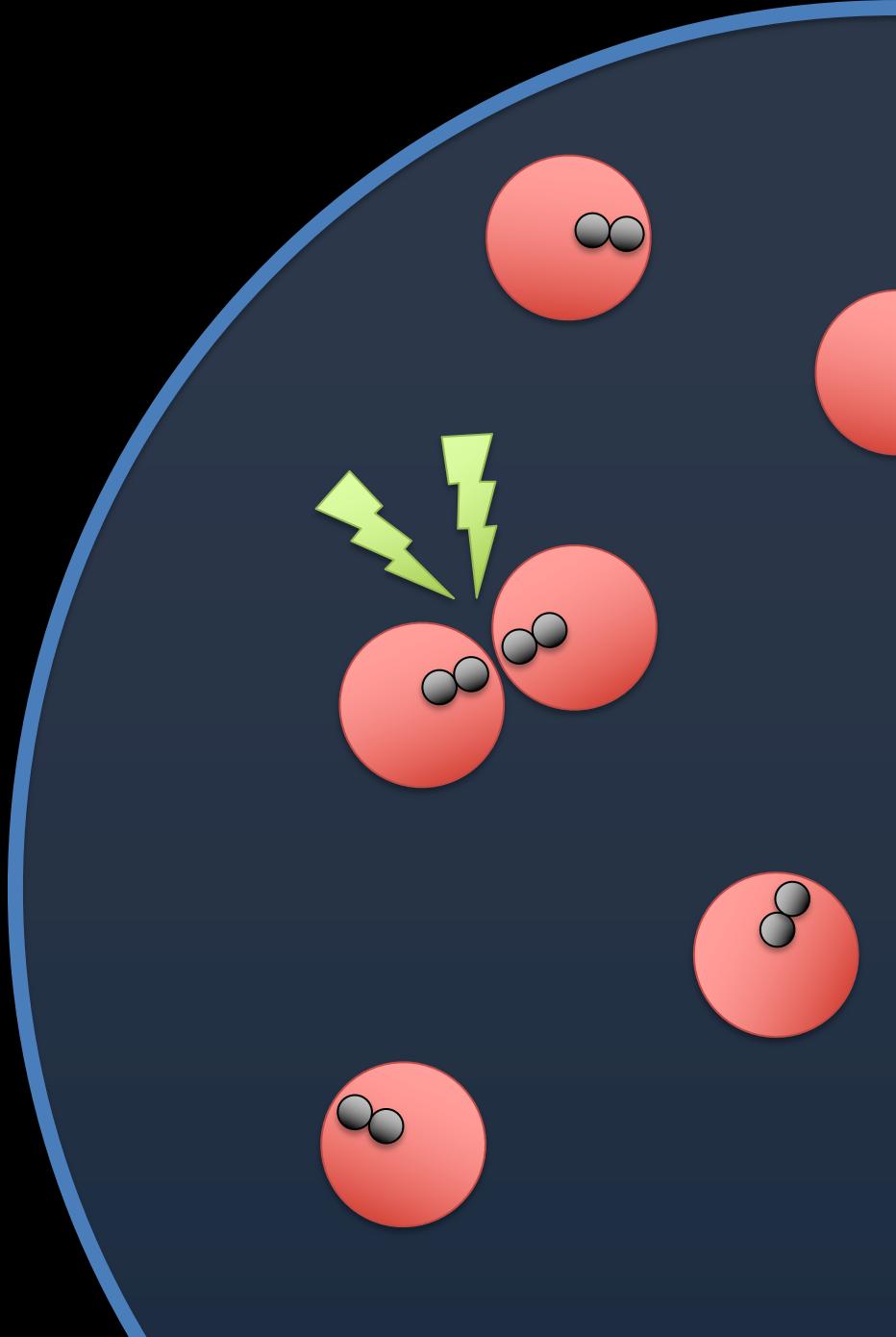
- Week 1:** Introduction to ABMs
- Week 2:** Cellular Automata
- Week 3:** ABM Methodology
- Week 4:** Agent Behaviours
- Week 5:** ABMs as Research Tools

READING WEEK

- Week 6:** Modelling Competitive Agents
- Week 7:** Presenting Results
- Week 8:** Forecasting & Prediction
- Week 9:** Validation & Verification
- Week 10:** Shared!

OBJECTIVES

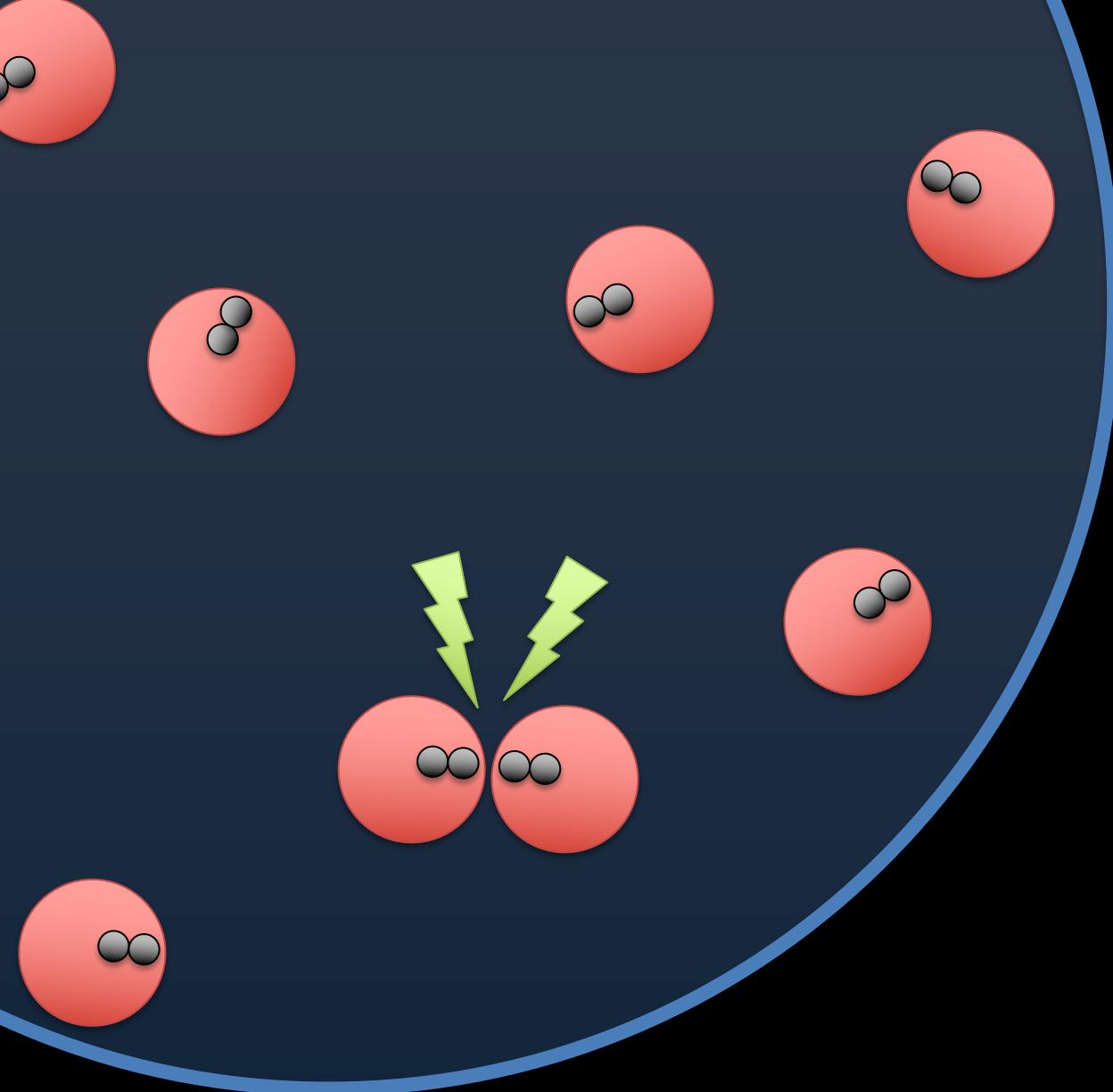
1. Discuss multi-scale modelling.
2. Explore how different kinds of models can be combined.



Course Objectives

You should...

1. understand the principles of agent-based modelling (ABM)
2. be able to describe the type and range of systems to which ABM can be profitably and appropriately applied
3. be able to conceptualise and model urban systems with complex dynamics
4. show evidence of being able to translate these understandings into the practical methodology of modelling



LECTURE 10

Part 1

MULTI-SCALE MODELLING

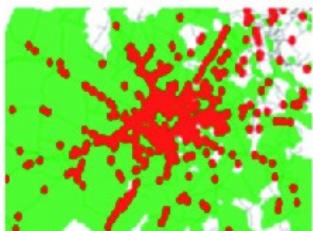
Review: Lecture 8

Modelling at different scales
– in both SPACE and TIME

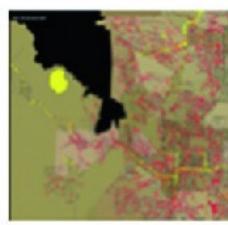
- How do we choose the appropriate scale?
- How do we match the scales of space and time to one another?

Spatial Scale

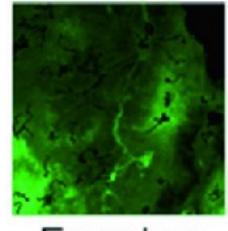
Macro



Traffic



Disasters



Farming



Migration

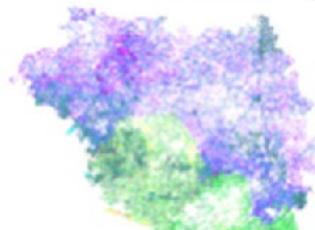
Meso



Pedestrian Dynamics



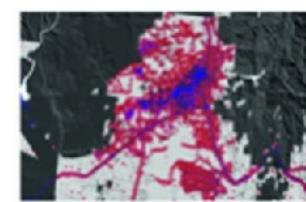
Humanitarian Relief



Disease Spread

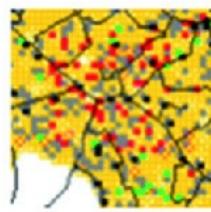


Residential Choice

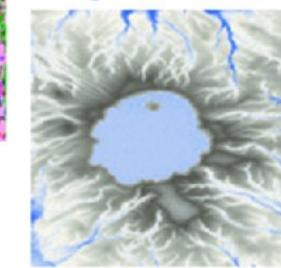


Urban Growth & Land Use Change

Micro



Riots



Rainfall & Erosion

Minutes

Hours

Days

Years

Temporal Scale

Combining MULTIPLE SCALES

The model can encompass multiple **scales** of processes. This is especially important in patterns which occur over different scales.

Here, you can have scale over different:

- Spaces (eg building, streetscape, city).
- Timesteps (eg observation, planning, goal-setting).
- Social units (eg individual, family, community, nation).
- Combinations of these (eg individuals leading organisations, influenced by relationships with one another over time).

Example: virus on a network

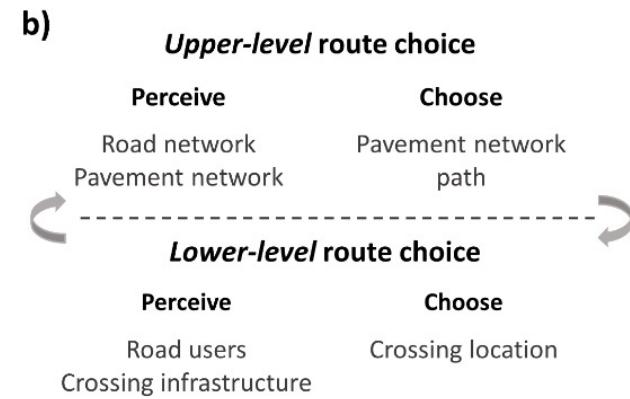
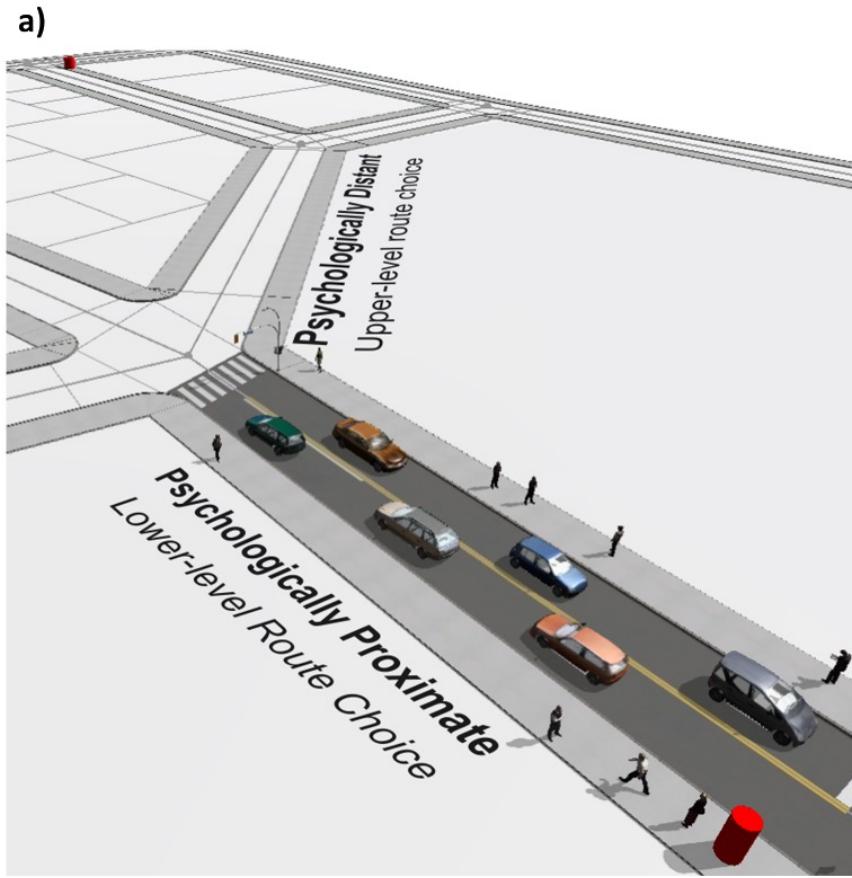
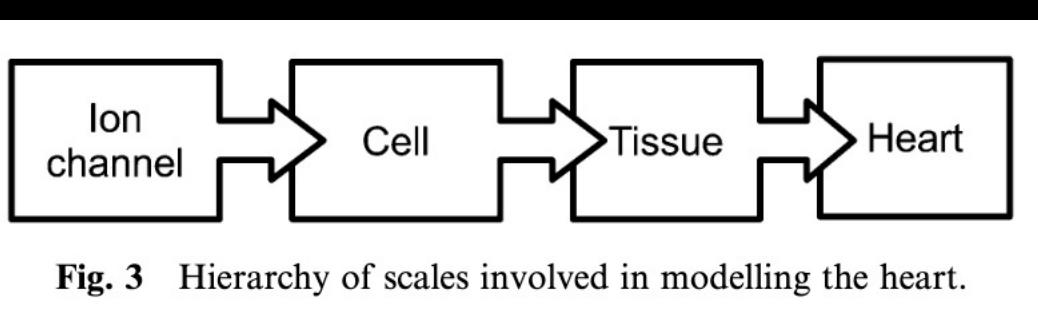
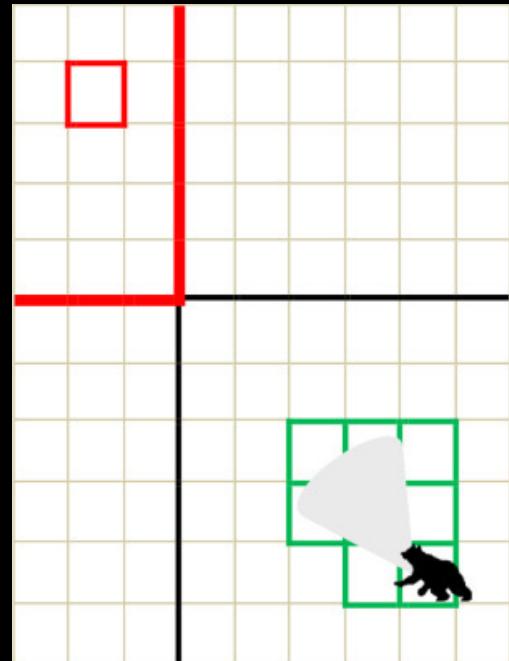


Figure 3.1: a) Diagram illustrating the CLT route choice framework. Red pillars indicate an origin and destination. Within the psychologically proximate environment road users and crossing infrastructure can be perceived. The psychologically distant environment is perceived as more abstract. b) Summary of *upper-level* and *lower-level* route choice. Grey arrows indicate interaction between levels.

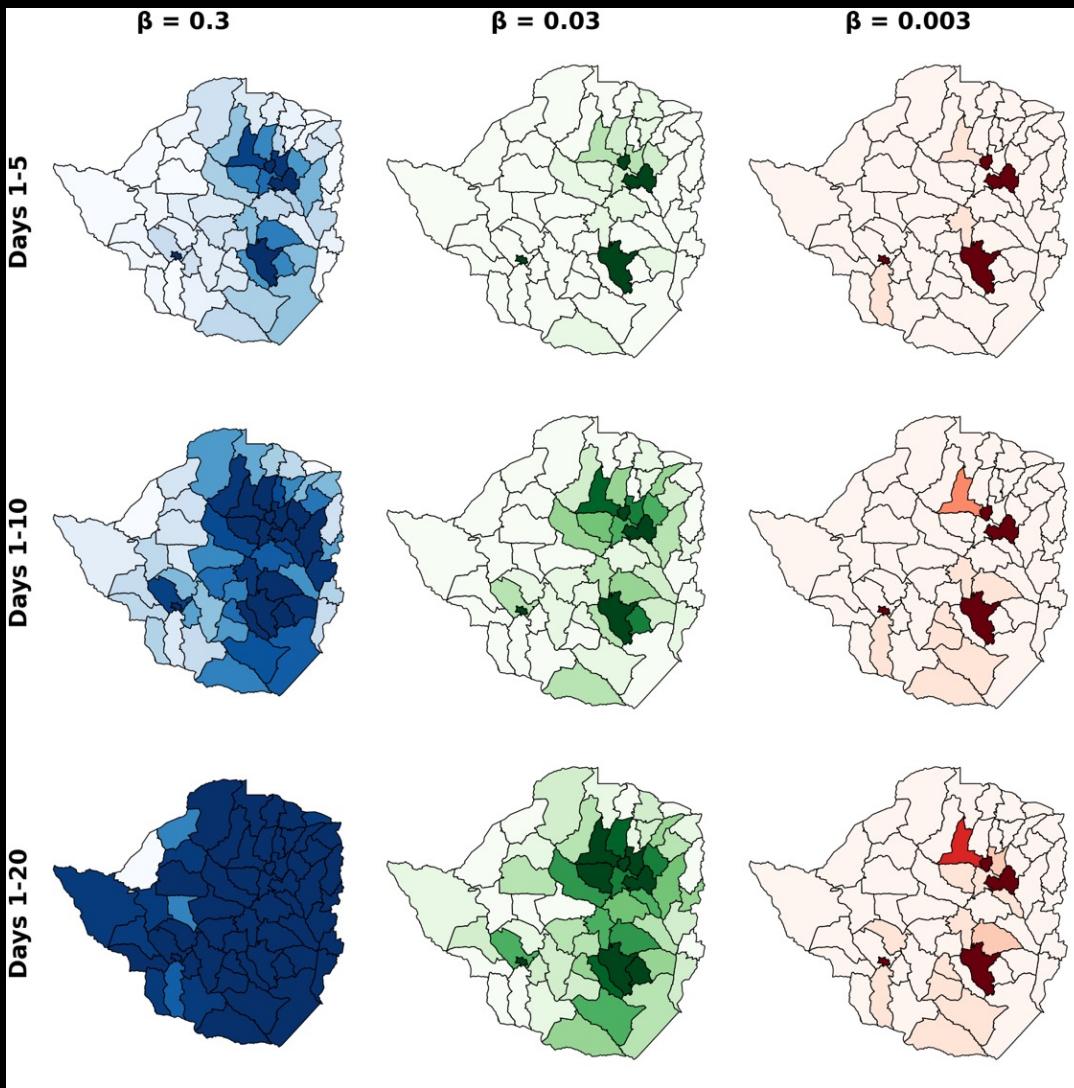
Over a range of scales

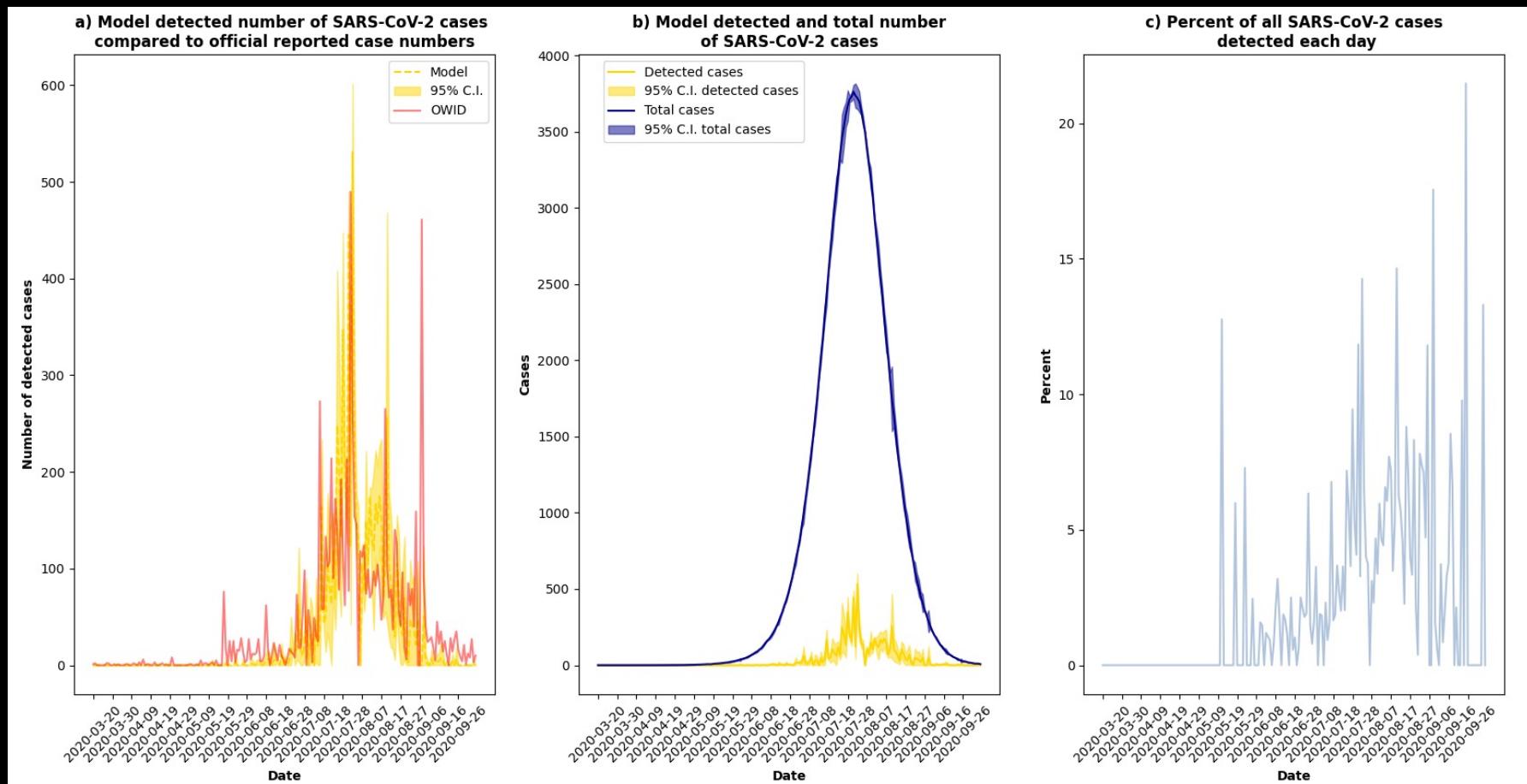
Zubiria Perez, Alejandra, Christopher Bone, and Gordon Stenhouse. 2021. 'Simulating Multi-Scale Movement Decision-Making and Learning in a Large Carnivore Using Agent-Based Modelling'. *Ecological Modelling* 452 (July): 109568.
<https://doi.org/10.1016/j.ecolmodel.2021.109568>.



Dada, Joseph O., and Pedro Mendes. 2011. 'Multi-Scale Modelling and Simulation in Systems Biology'. *Integrative Biology* 3 (2): 86.
<https://doi.org/10.1039/c0ib00075b>.

50% Sample





Want to read more?

Lippe, Melvin, Mike Bithell, Nick Gotts, Davide Natalini, Peter Barbrook-Johnson, Carlo Giupponi, Mareen Hallier, et al. 2019. ‘Using Agent-Based Modelling to Simulate Social-Ecological Systems across Scales’. *GeoInformatica* 23 (2): 269–98.
<https://doi.org/10.1007/s10707-018-00337-8>.

COMBINING MODELS

SLEUTH model

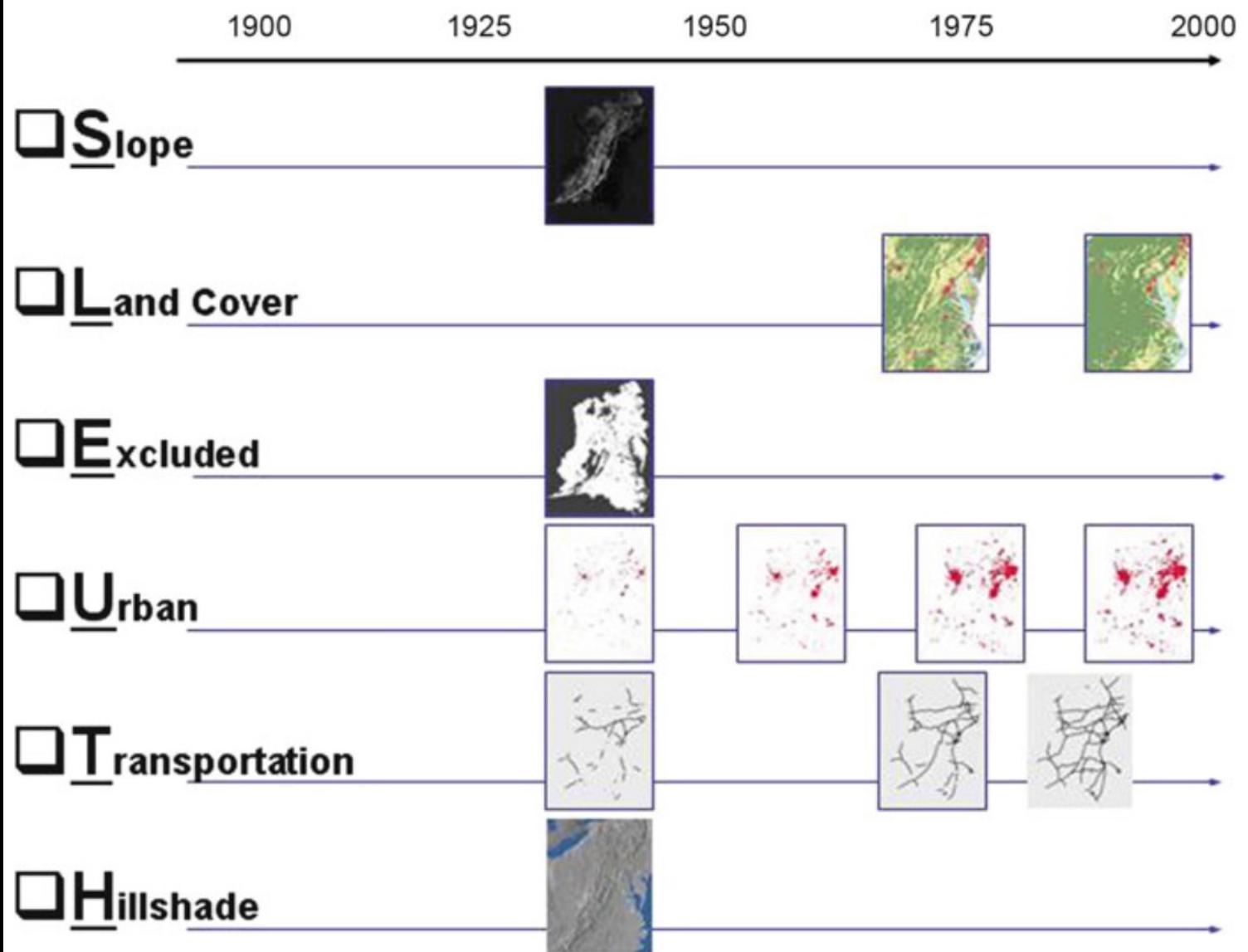


Fig. 62.2 Input data for the SLEUTH model. Minimum layers are topographic slope, two land use maps, one exclusion map, four urban extent maps, two transportation maps, and a hill-shaded background image. Data shown are for the Environmental Protection Agency's Mid Atlantic Regional Assessment study area

Clarke, Keith C.
2014. 'Cellular Automata and Agent-Based Models'. In *Handbook of Regional Science*, Berlin, Heidelberg: Springer.
https://doi.org/10.1007/978-3-642-23430-9_63

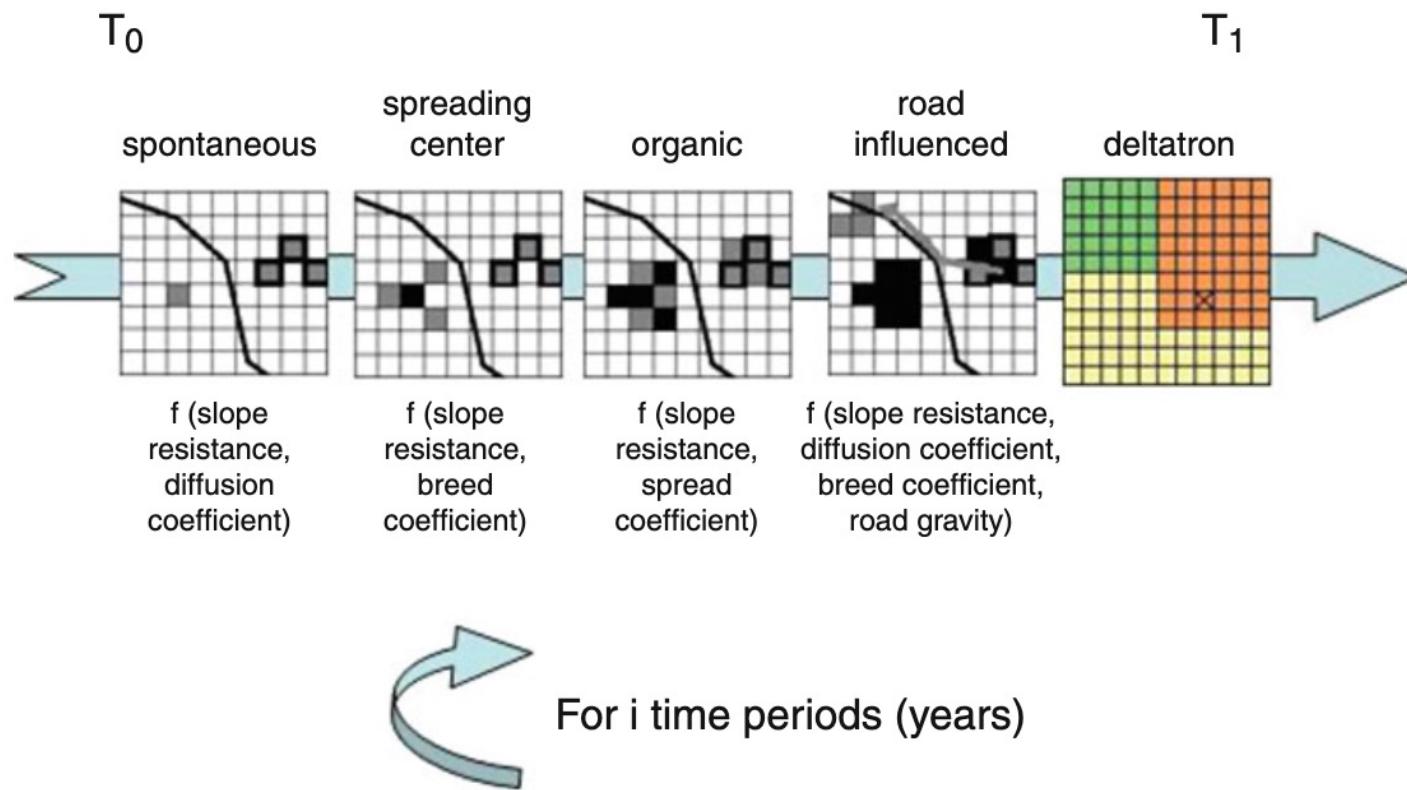


Fig. 62.3 At each cycle in the CA model, five sets of behavior rules are enforced. These are controlled by the factors and parameters shown and are applied in sequence for each one “year” iteration of the model

Clarke, Keith C.
2014. ‘Cellular Automata and Agent-Based Models’. In *Handbook of Regional Science*, Berlin, Heidelberg: Springer.

https://doi.org/10.1007/978-3-642-23430-9_63



<https://github.com/swise5/takamatsu>

THANKS!