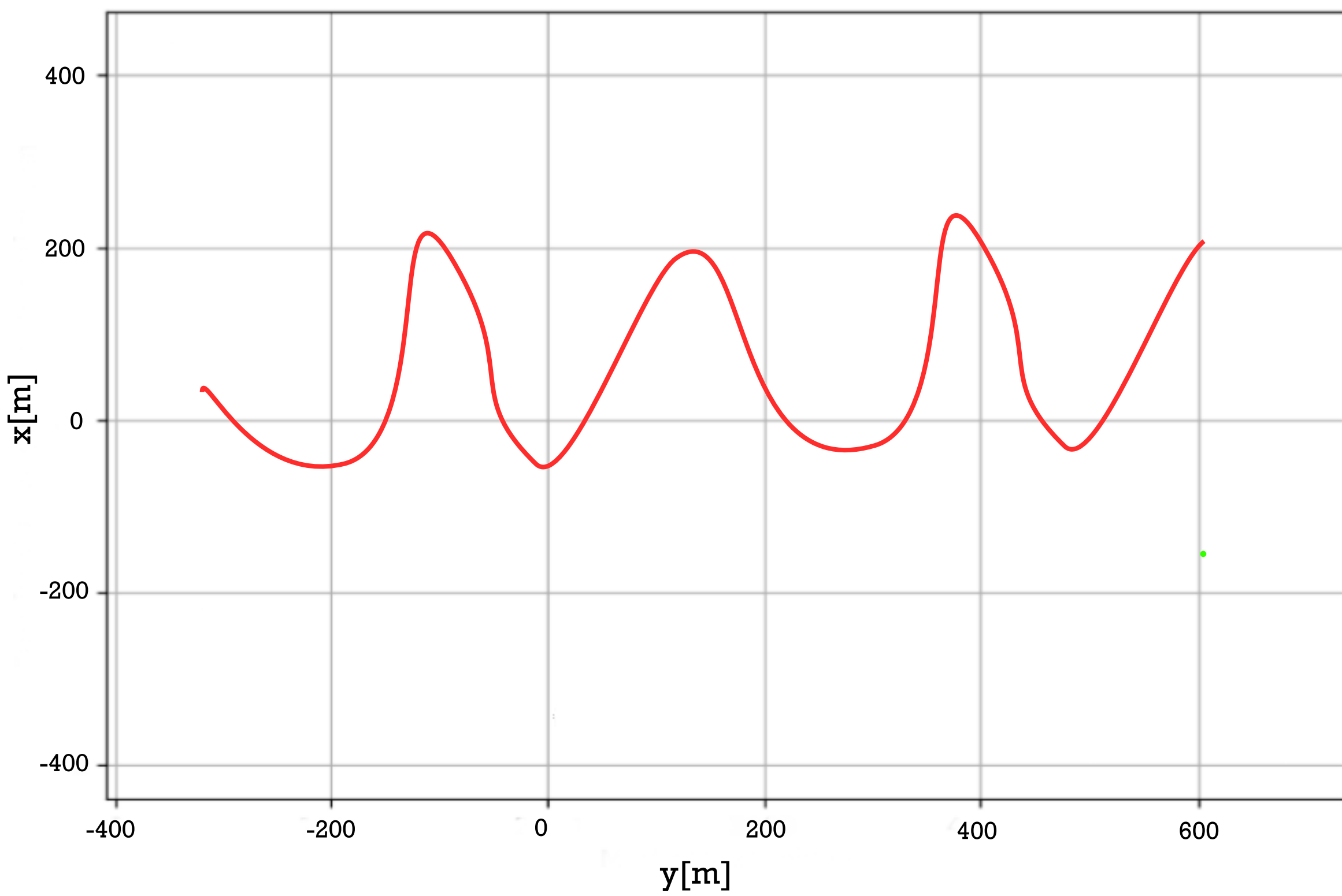
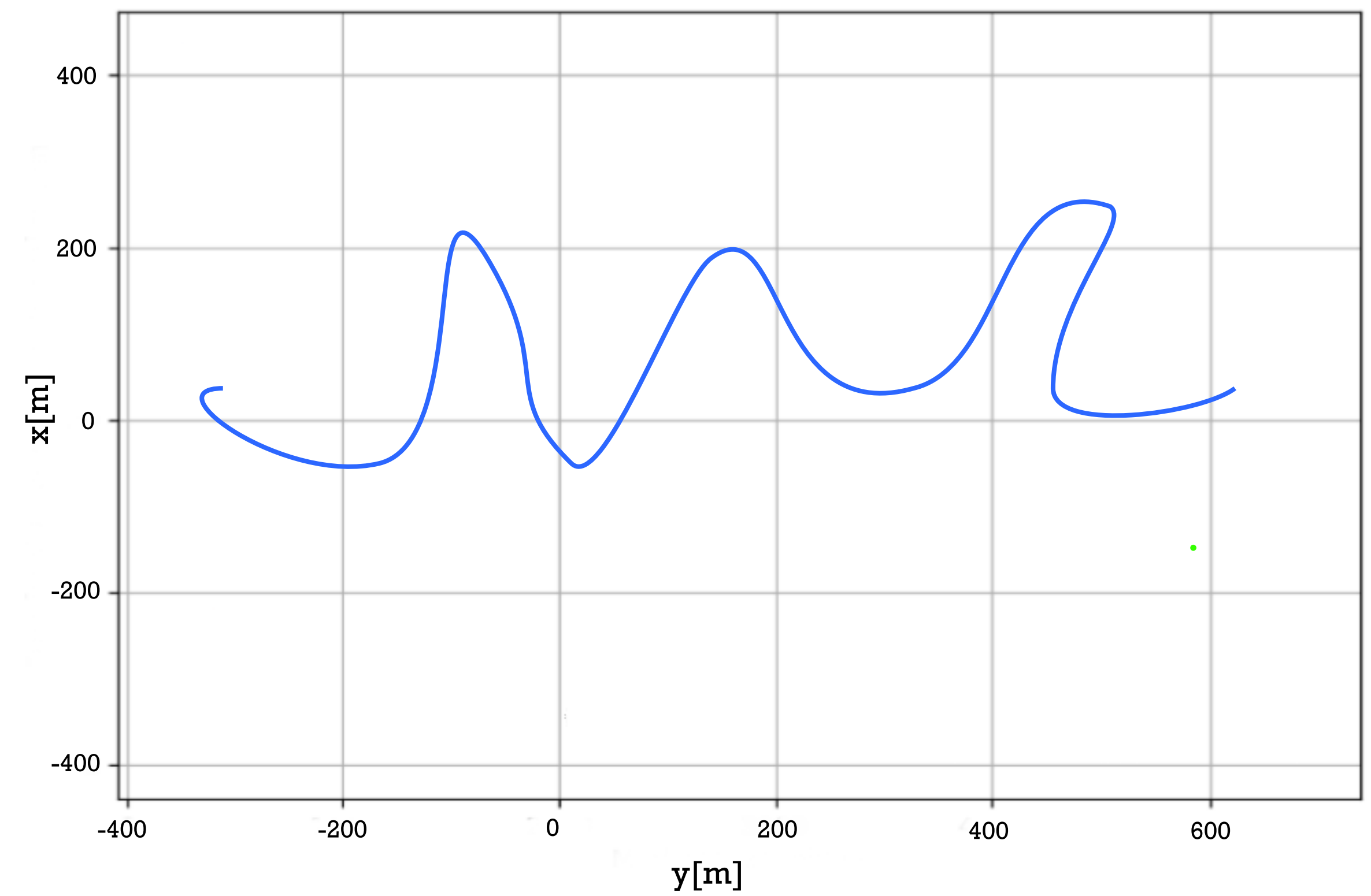
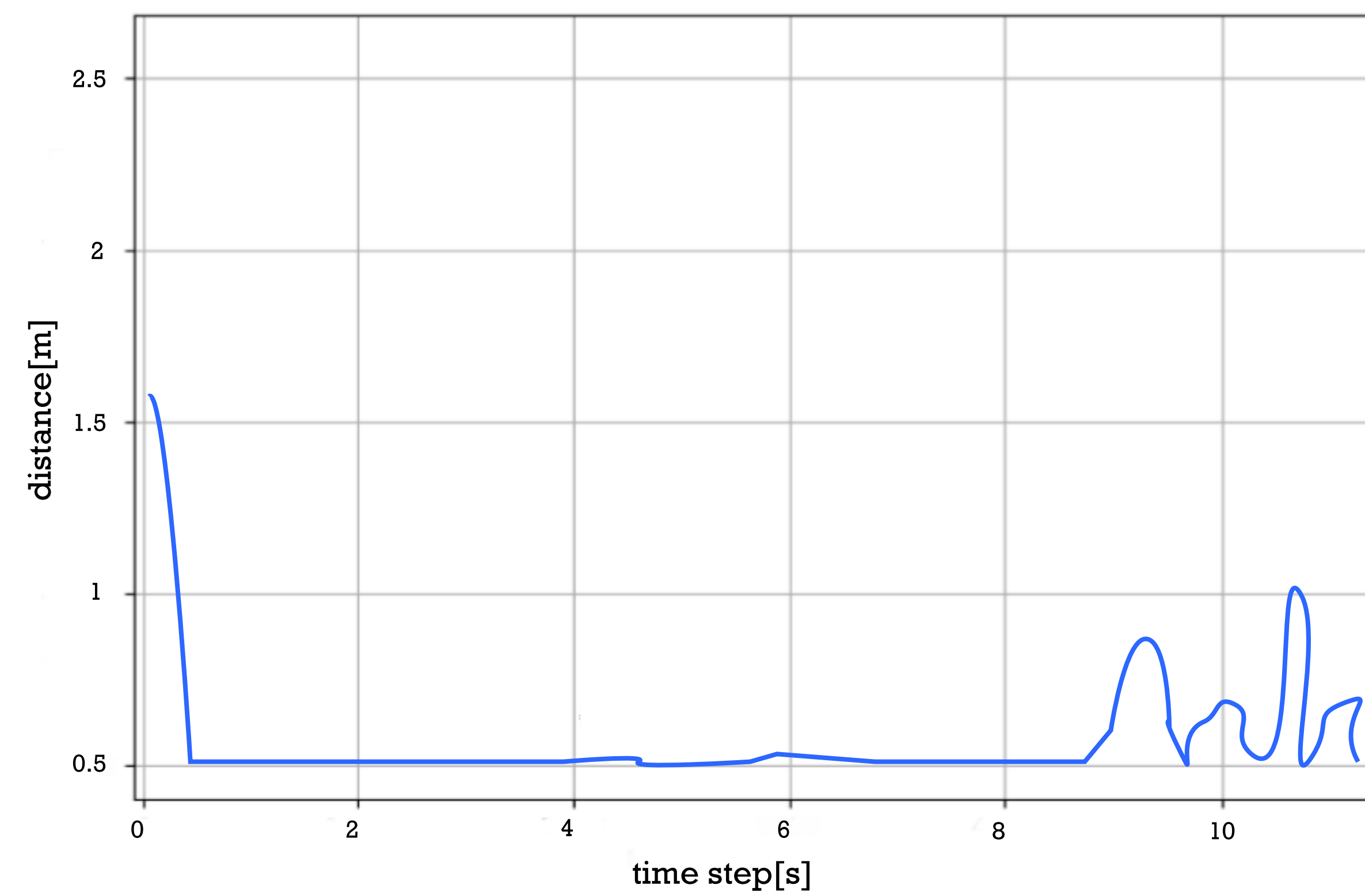


a) The target trajectory



b) The robot tracking trajectory

c) Evolution of the distance d_{Si} d) Variation of the dynamic of the target ($\dot{\theta}_T$)