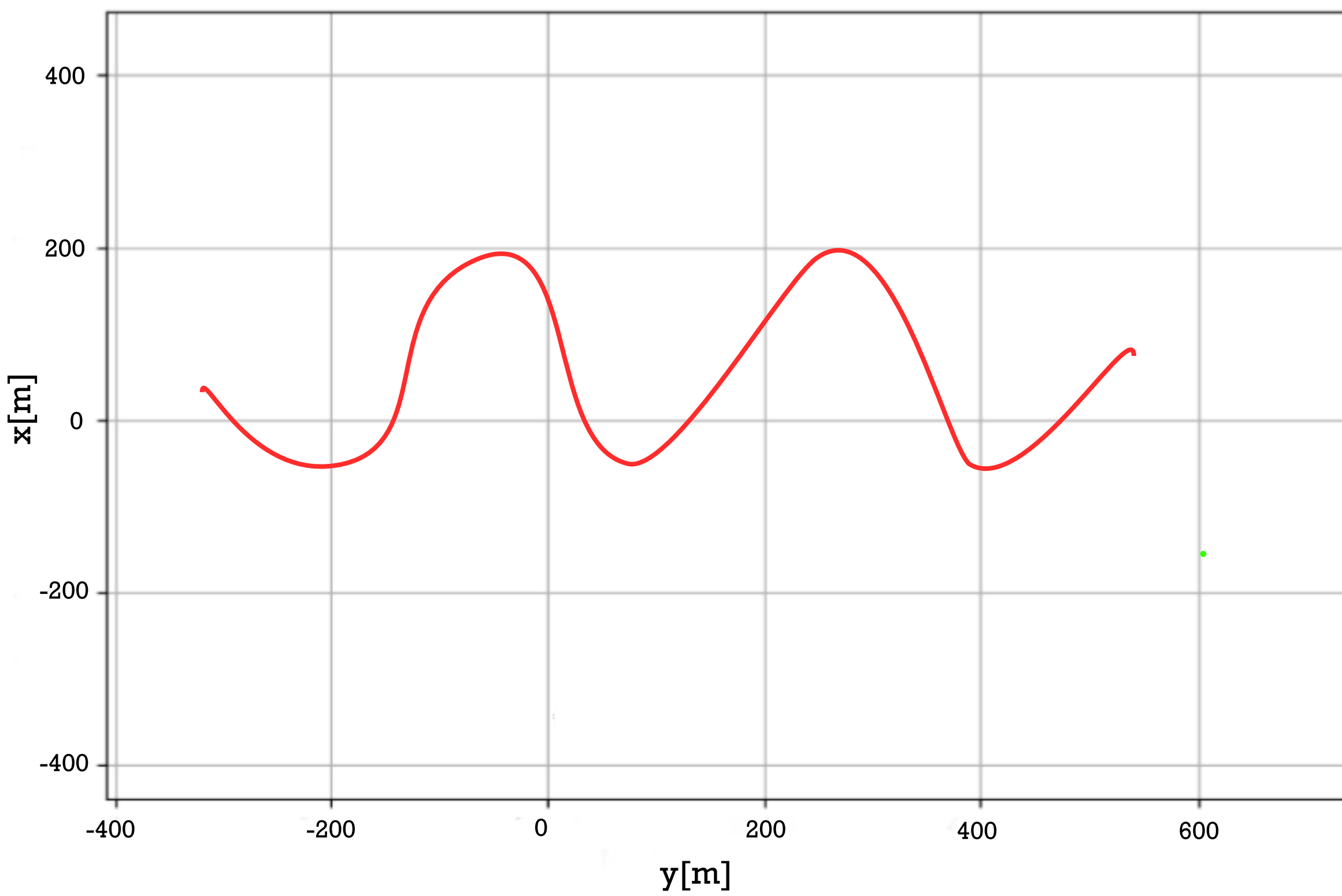
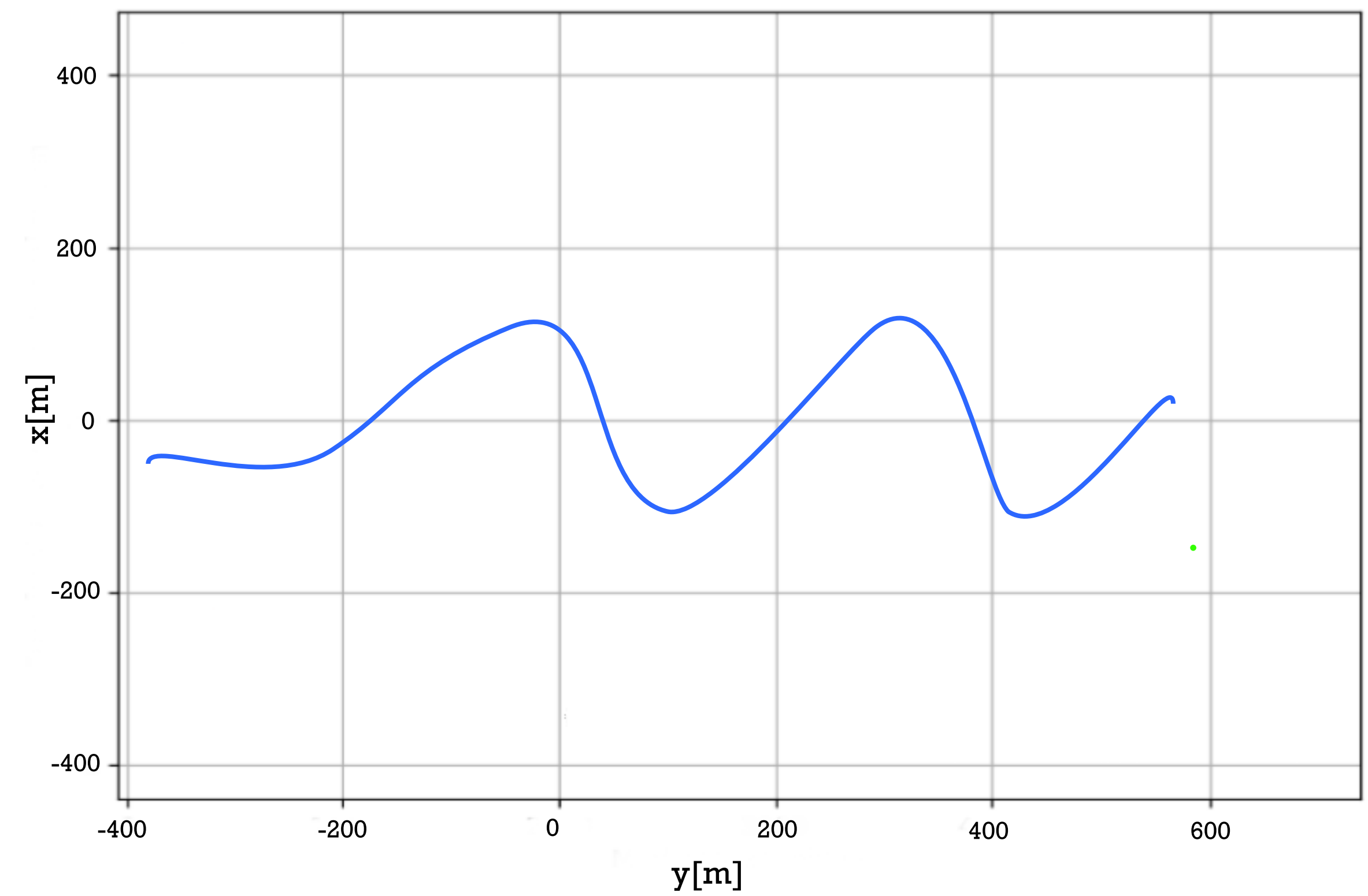


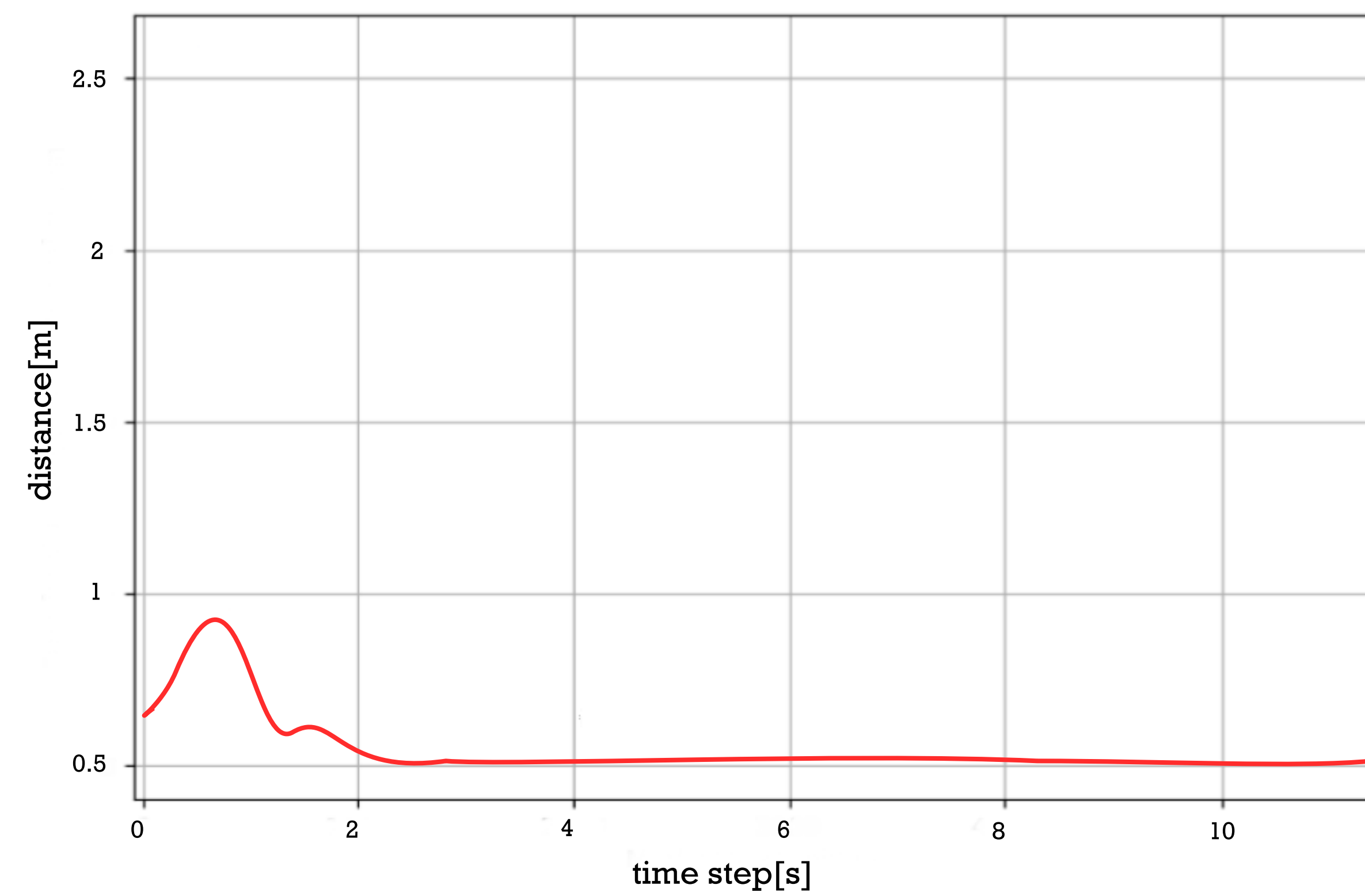
a) The target trajectory



b) The robot tracking trajectory



c) Evolution of the distance

d) Variation of the dynamic of the target ( $\dot{\theta}_T$ )