

# **Lecture 14**

## **Projection and least square**

# Projection

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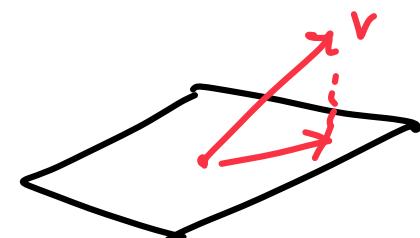
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Q:  $V \subseteq$  subspace, How we write down the orthogonal projection onto  $V$ ?



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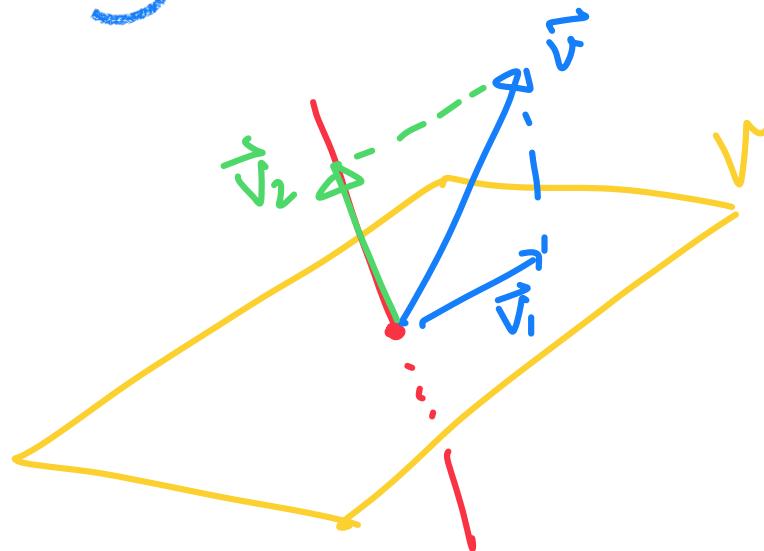
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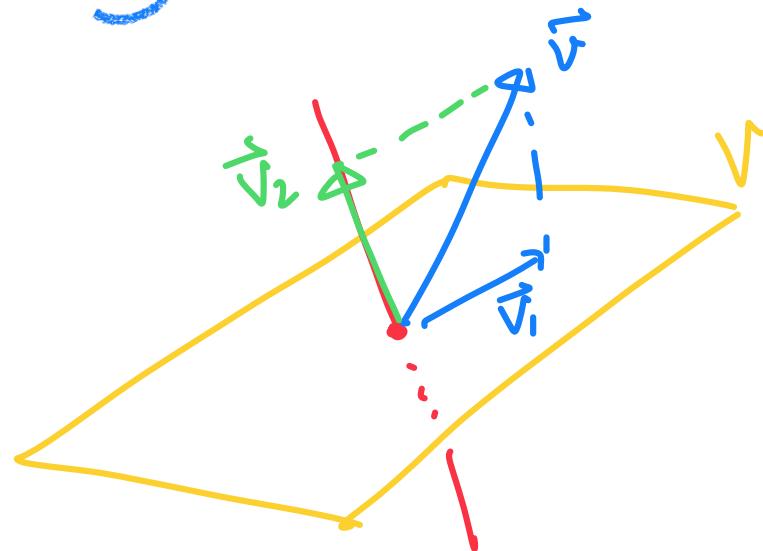
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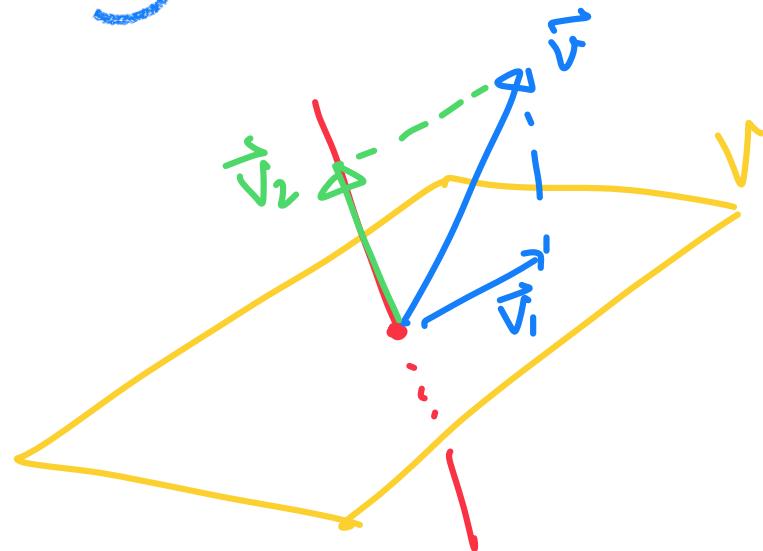
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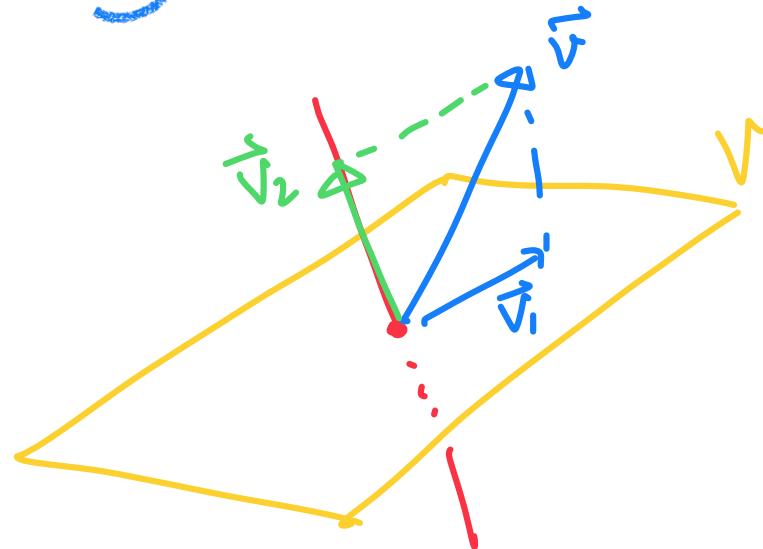
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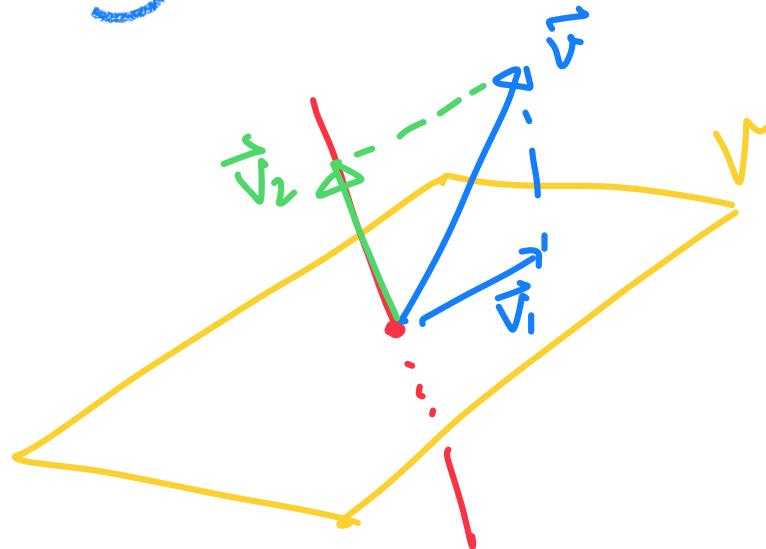
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Step 4: Transition matrix  $e_i[\text{id}]_{v_i}$

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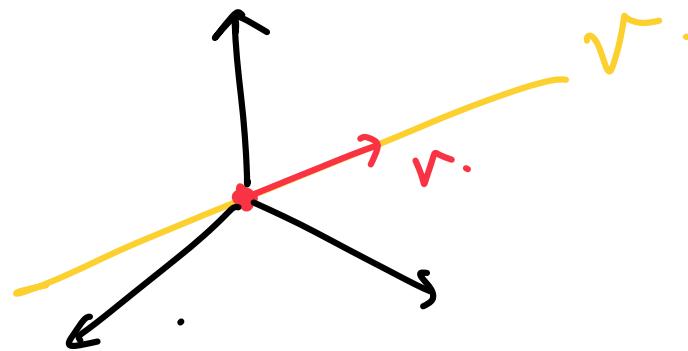
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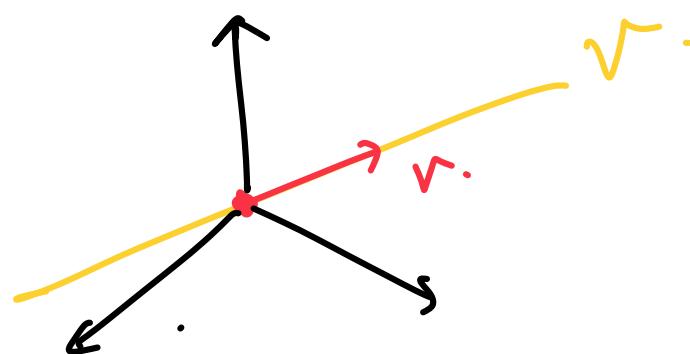


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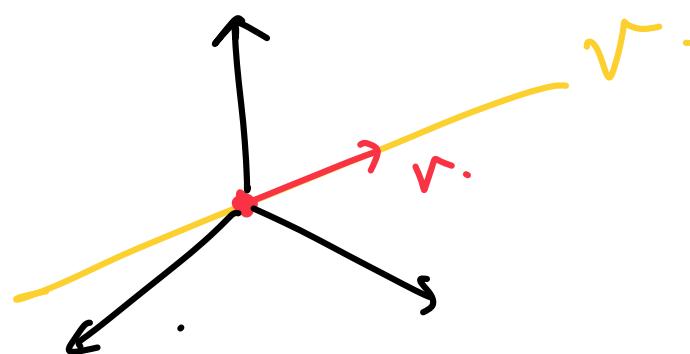
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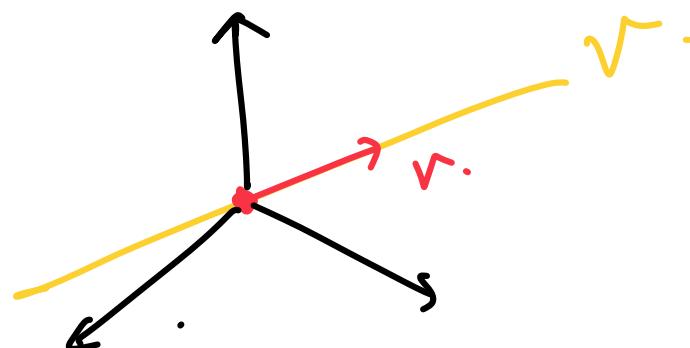
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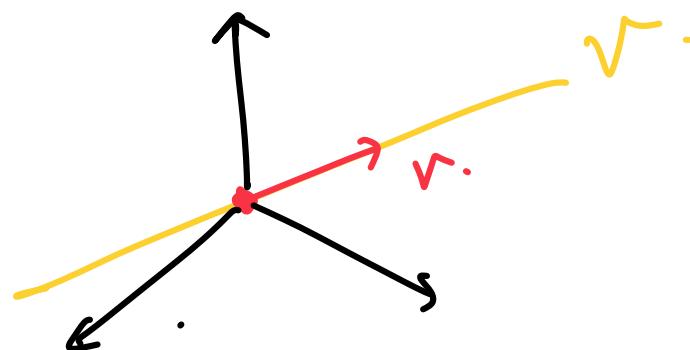
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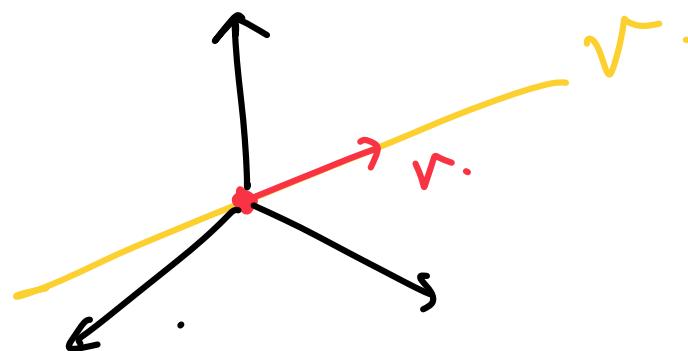
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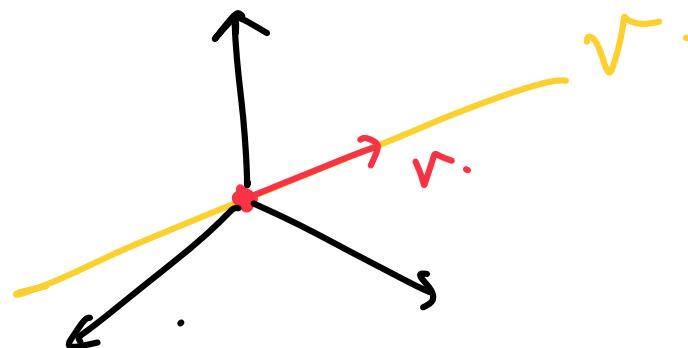
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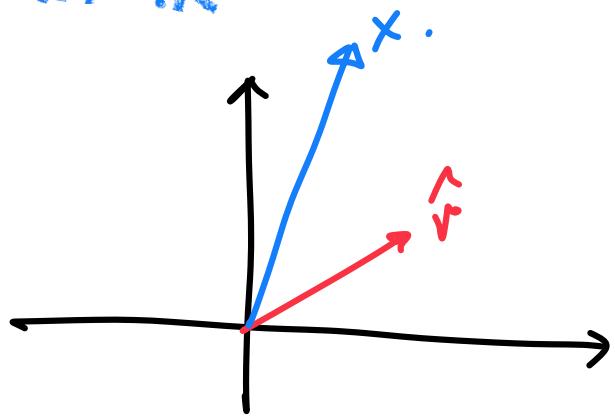
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- Guess a formula for  $c$

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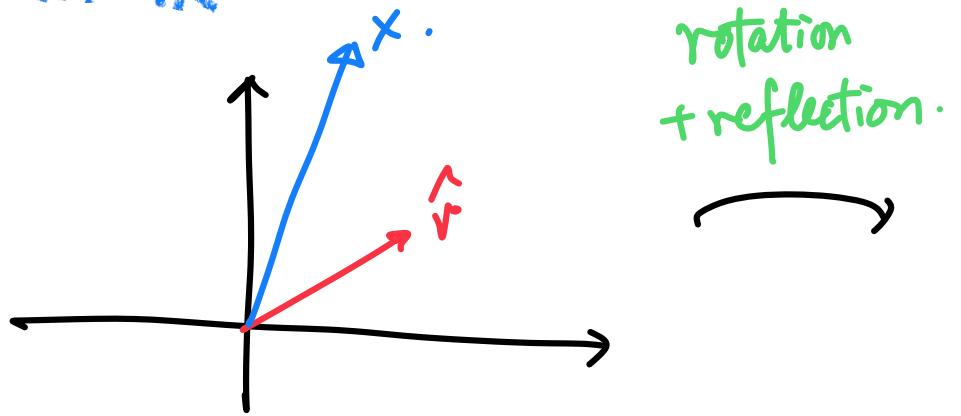
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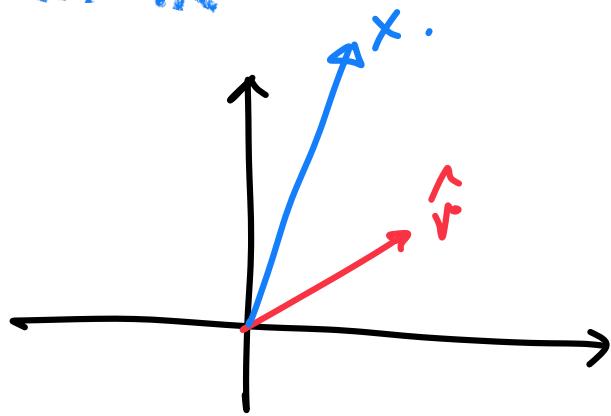
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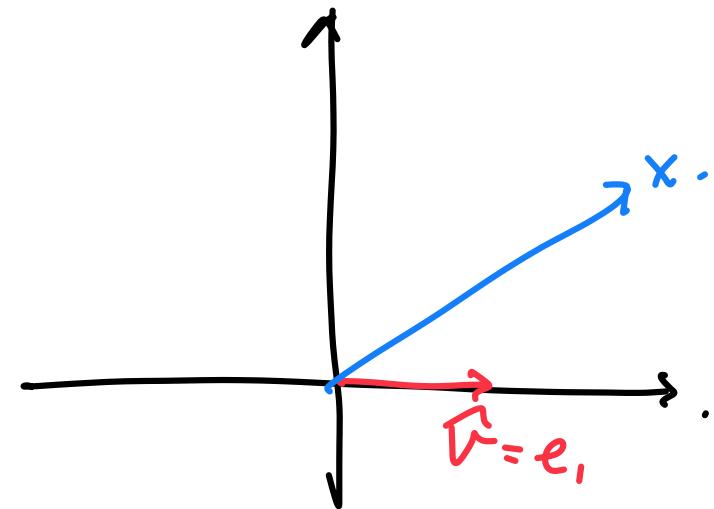
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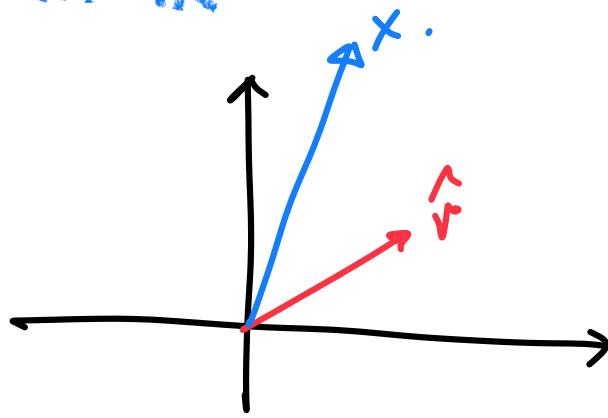


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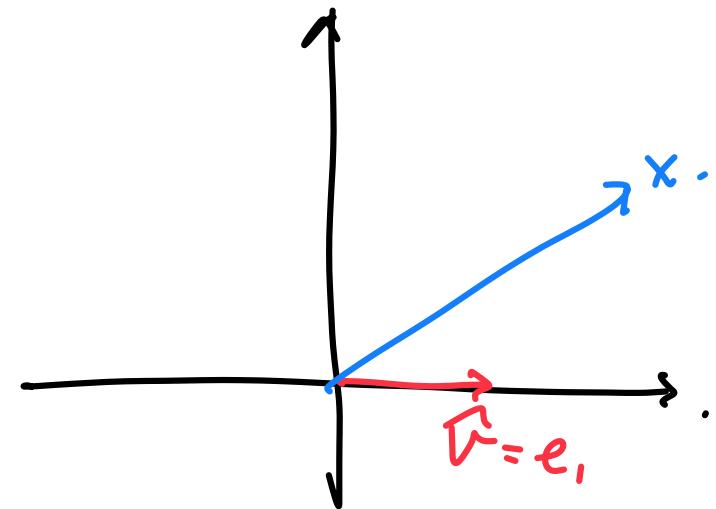


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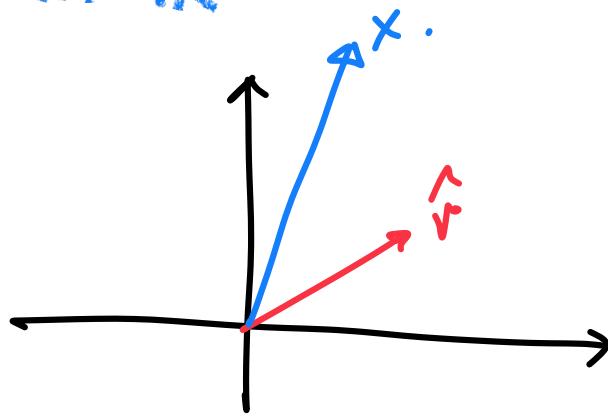
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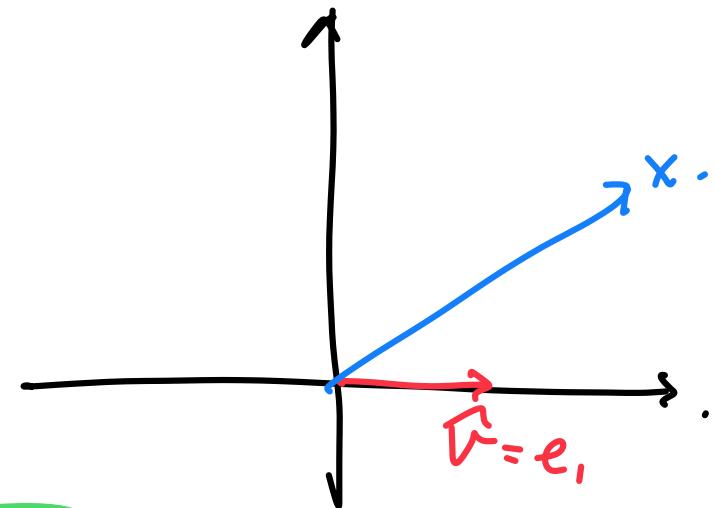
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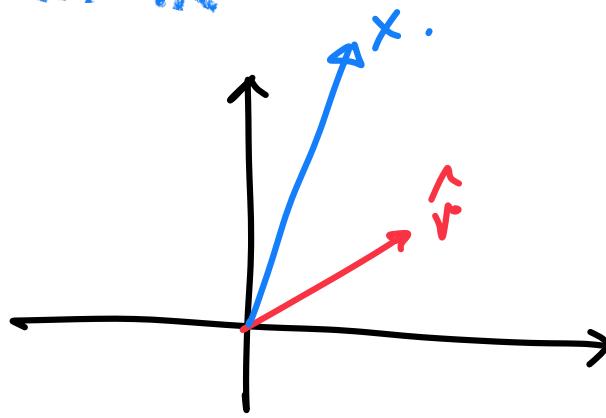
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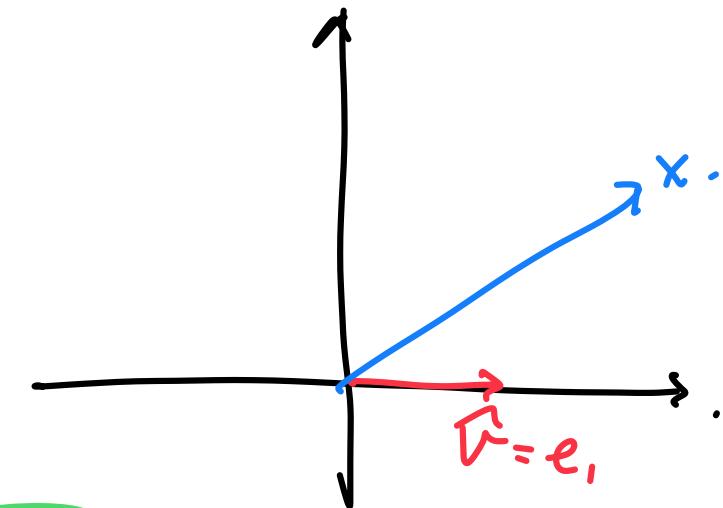
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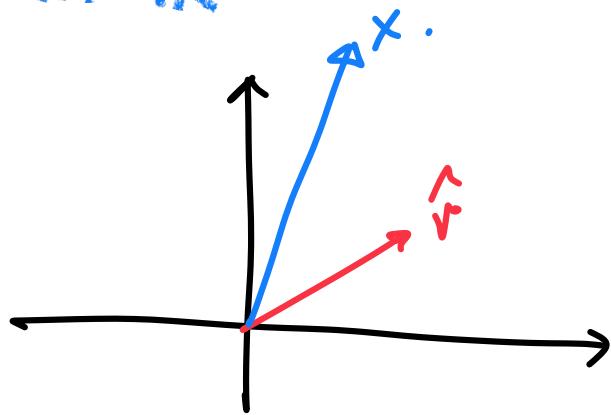


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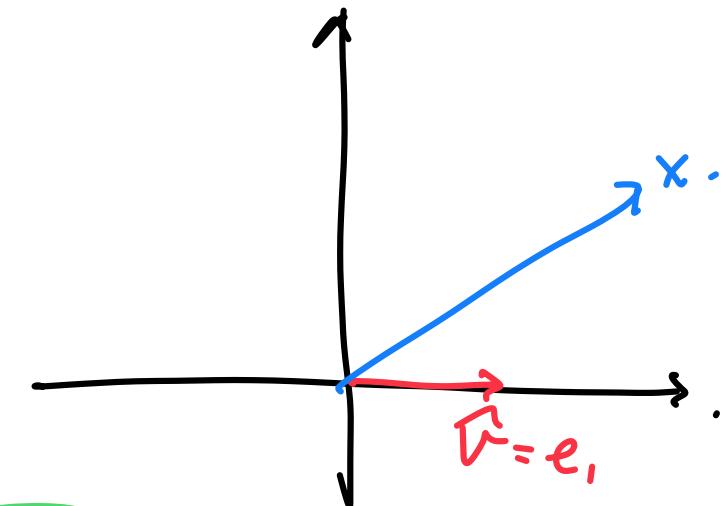
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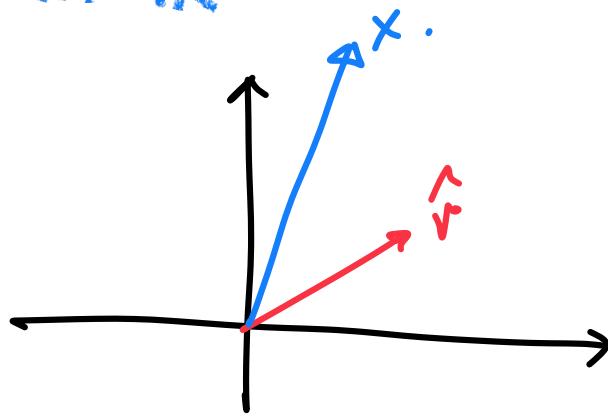
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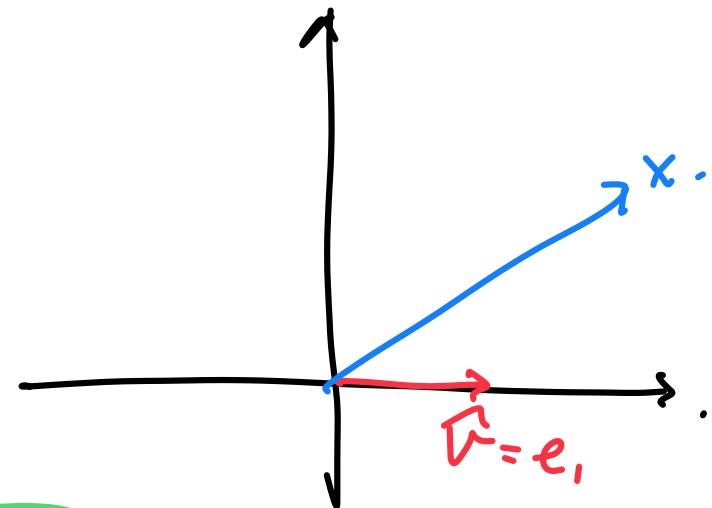
Claim:  $P(x) = \langle x, \hat{v} \rangle \hat{v} = \frac{\langle x, v \rangle}{\|v\|^2} v$  is the required projection!

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In the later picture:  $P(x) = \langle x, \hat{v} \rangle \hat{v} = c$ .

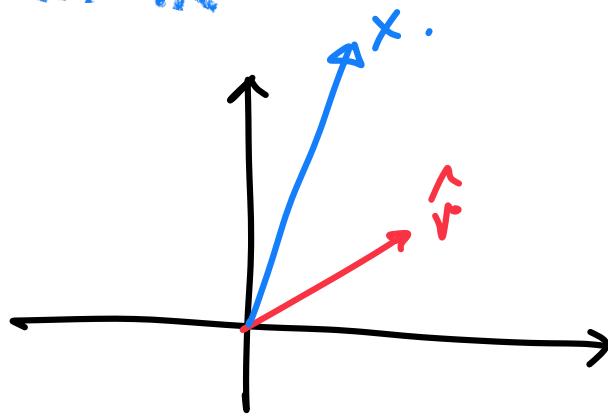
Observation: This formula holds for any dimension.

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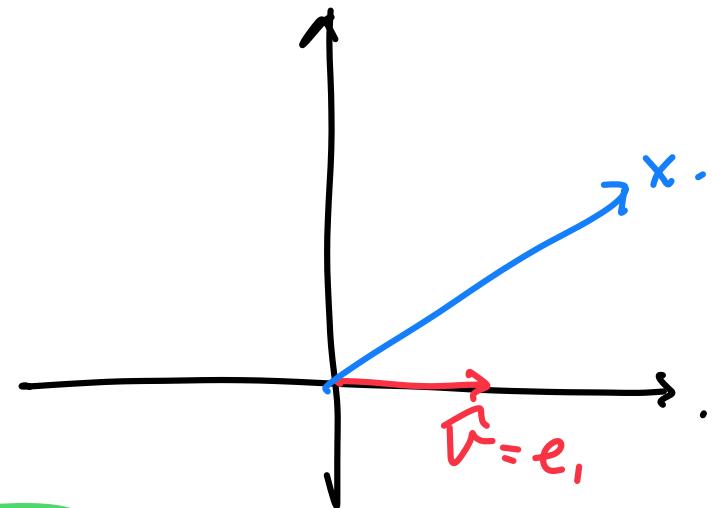
- Let any  $x$ , write  $x = (x - \langle x, \hat{v} \rangle \hat{v}) + \langle x, \hat{v} \rangle \hat{v}$

# Projection

Say in  $\mathbb{R}^2$ :



rotation  
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then  $[P] = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$

# Projection

Observation:

For the projection  $P$  onto a line:

$[P]$  is a symmetric matrix:

$$[P]^T = \left( \frac{1}{\|v\|^2} v \cdot v^T \right)^T = \frac{1}{\|v\|^2} v \cdot v^T = [P].$$

- Indeed: Any projection  $P$  onto  $V$  has its matrix representation under  $e_i$ 's being symmetric (prove later).

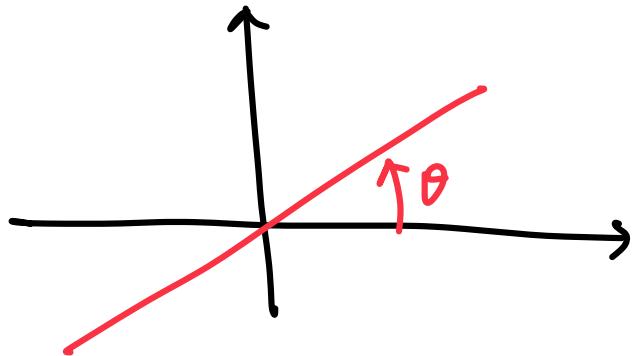
e.g.

We may check the formula for projection onto the  $\theta$ -line in  $\mathbb{R}^2$ .

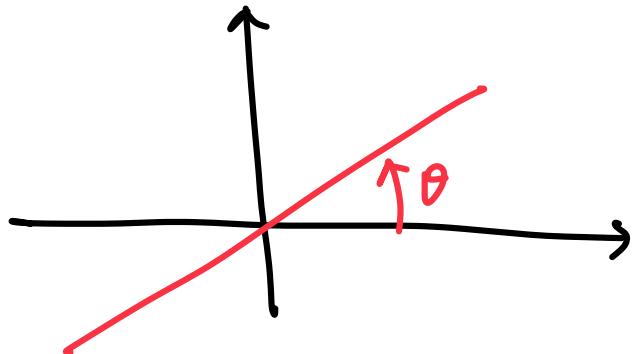
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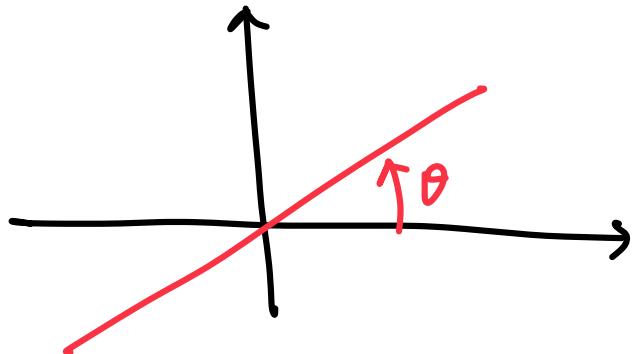


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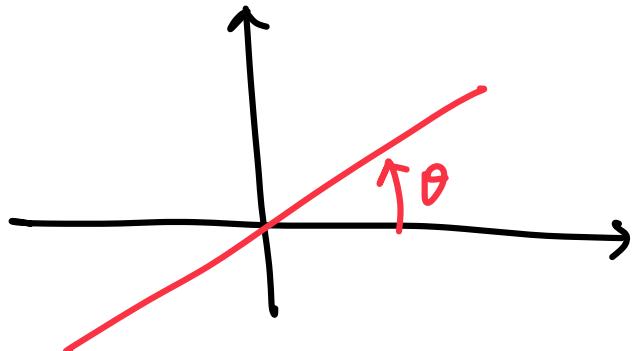
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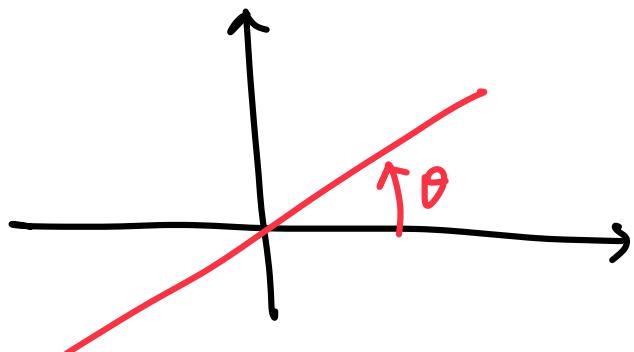
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which agrees with the one we get using transition matrix.

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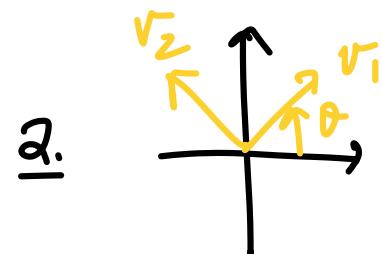
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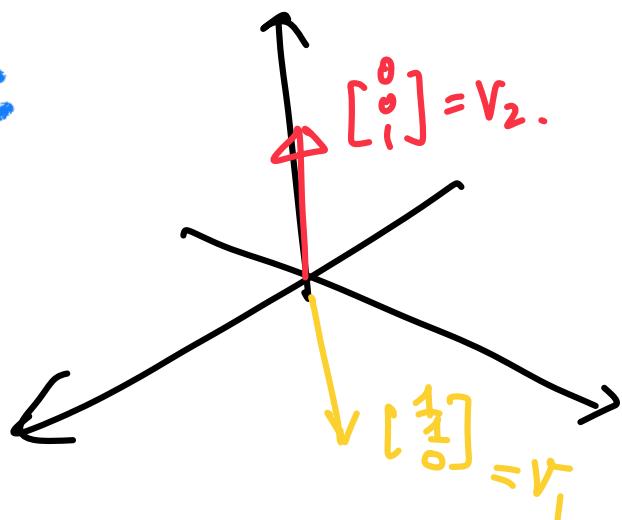
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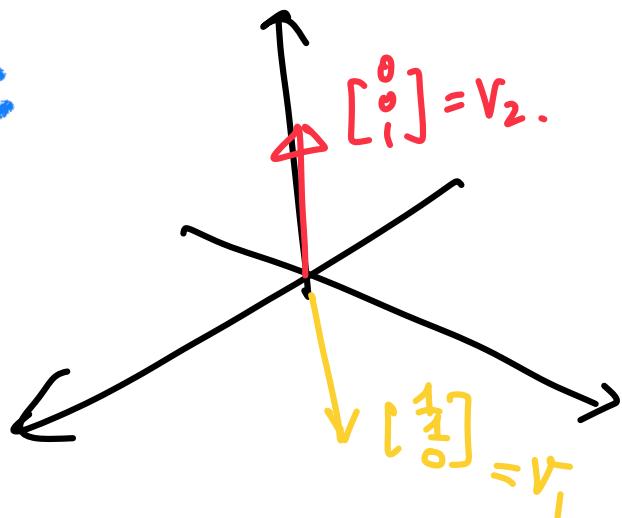


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Observation:  $[P]^T = [P]$ , i.e. it is a symmetric matrix.

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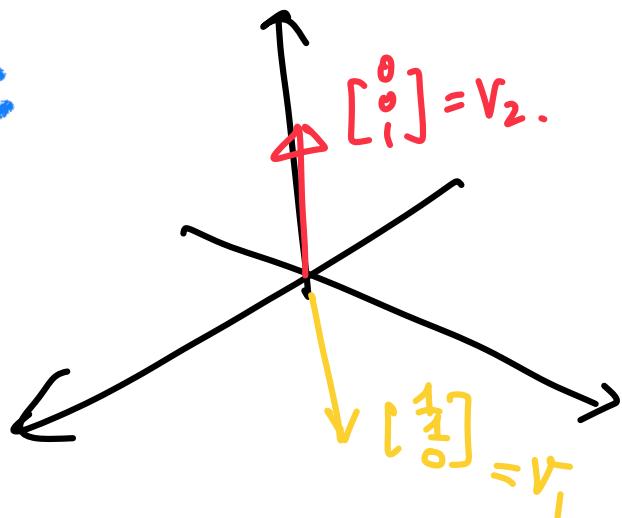
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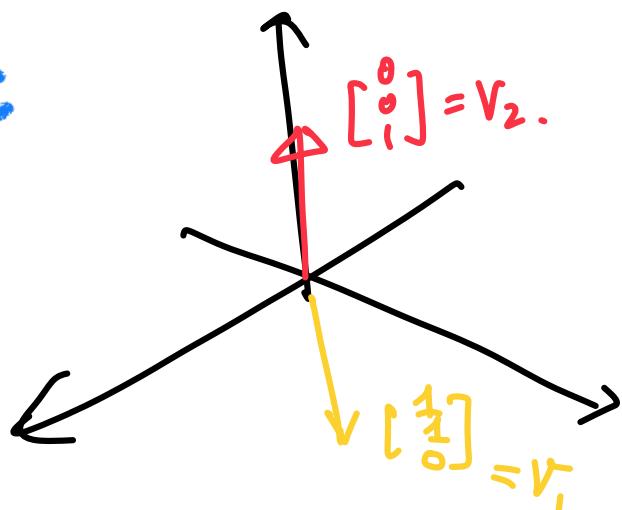
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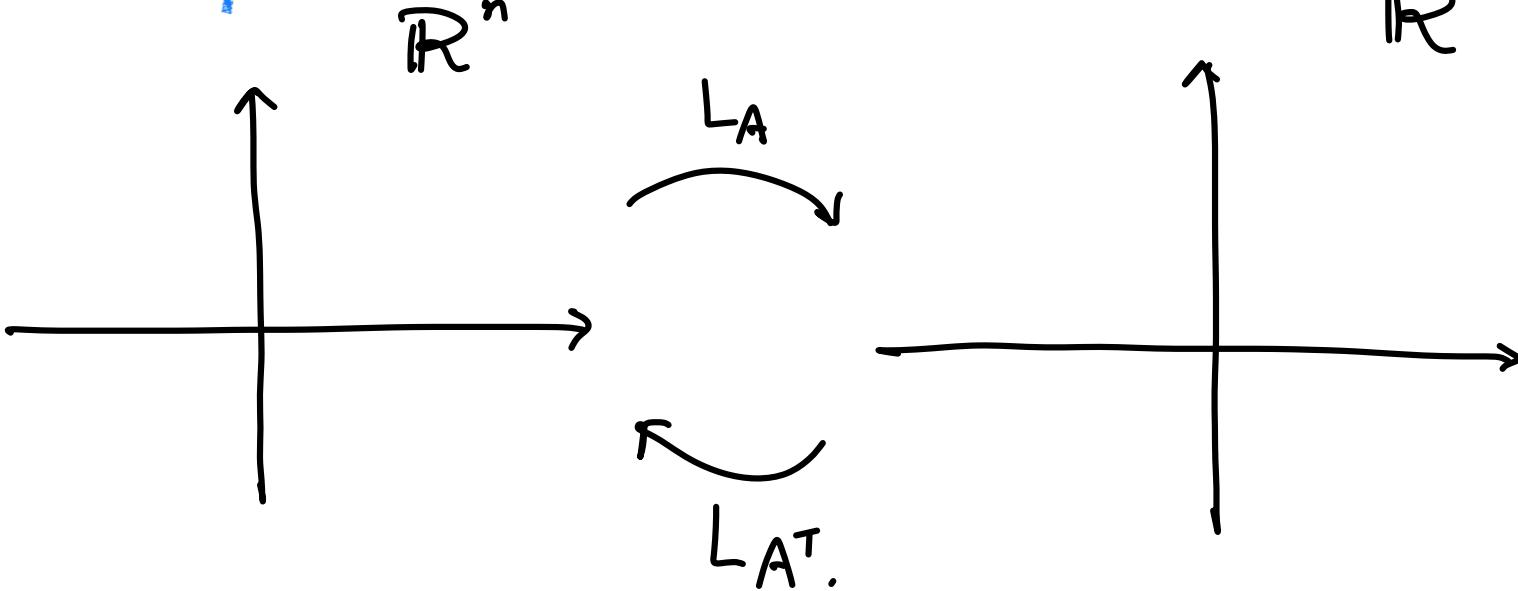
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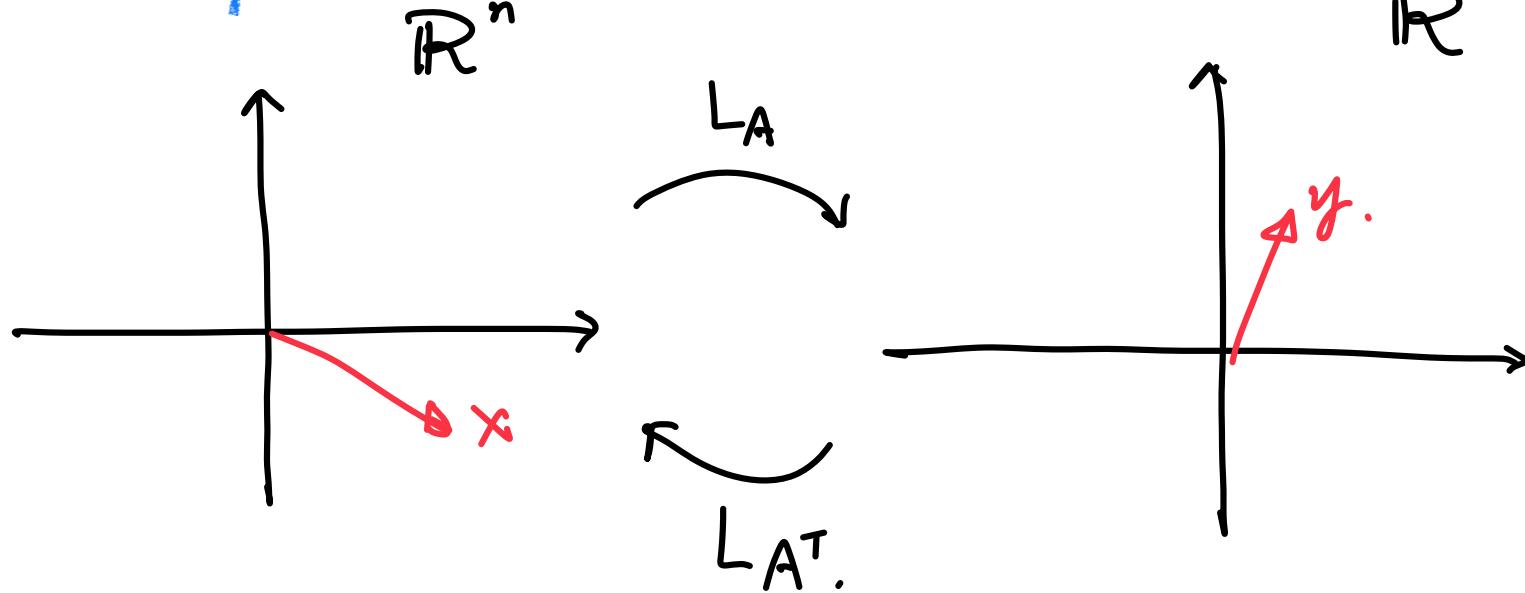


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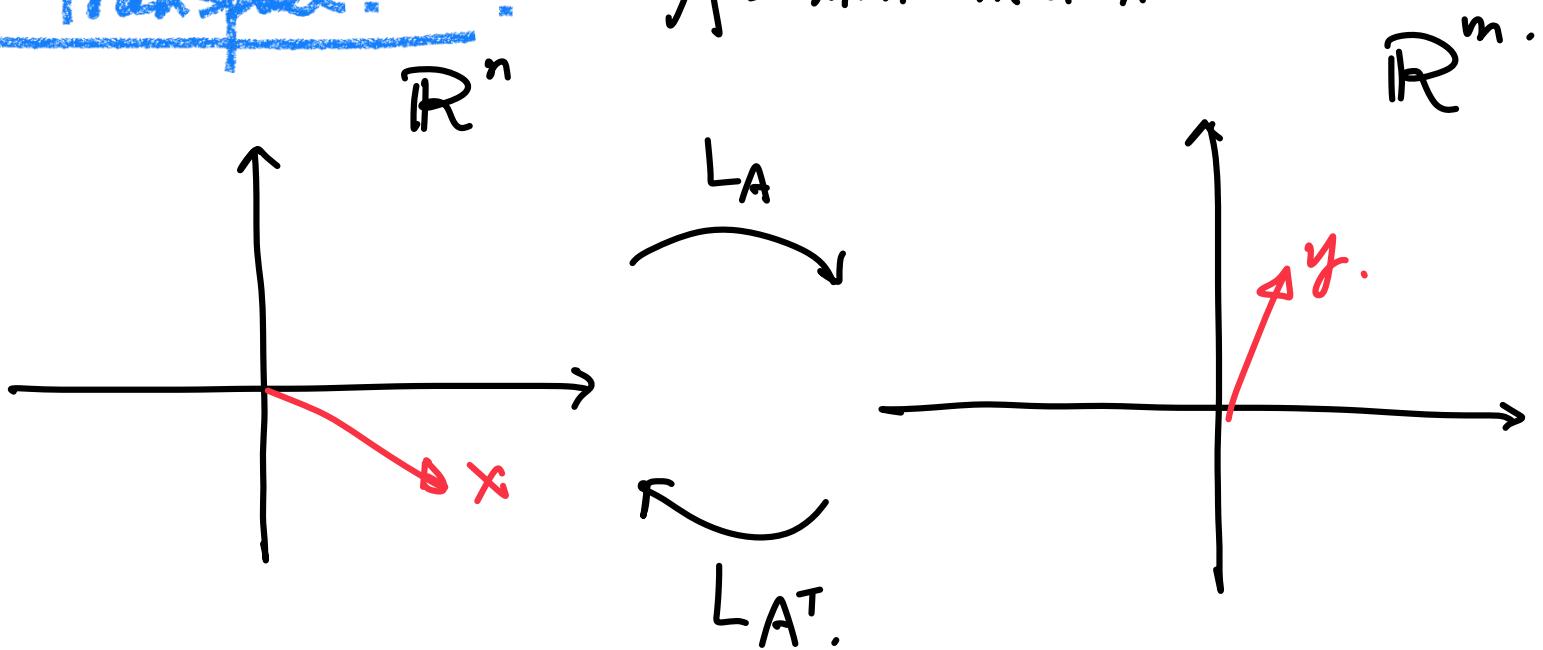
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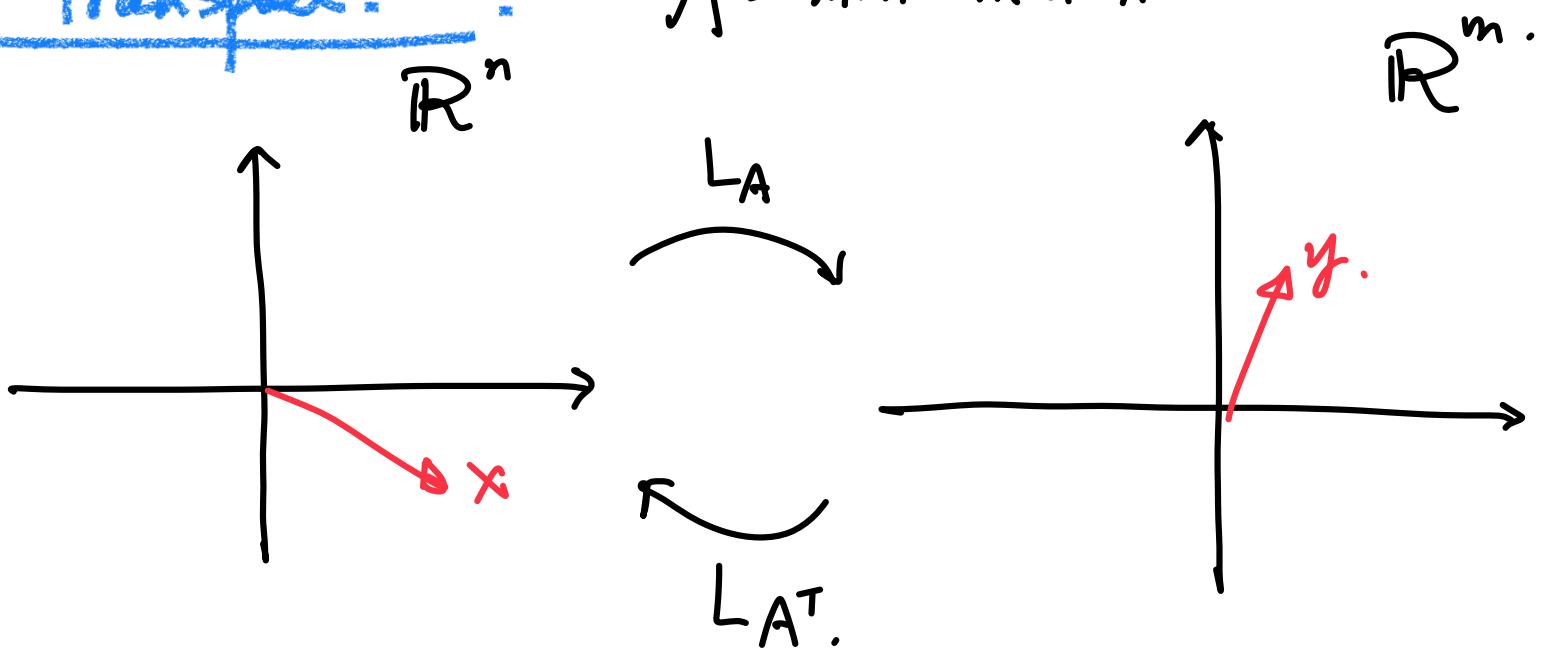
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Why: L.H.S. =  $(Ax)^T y = x^T (A^T y) = \langle x, A^T y \rangle$

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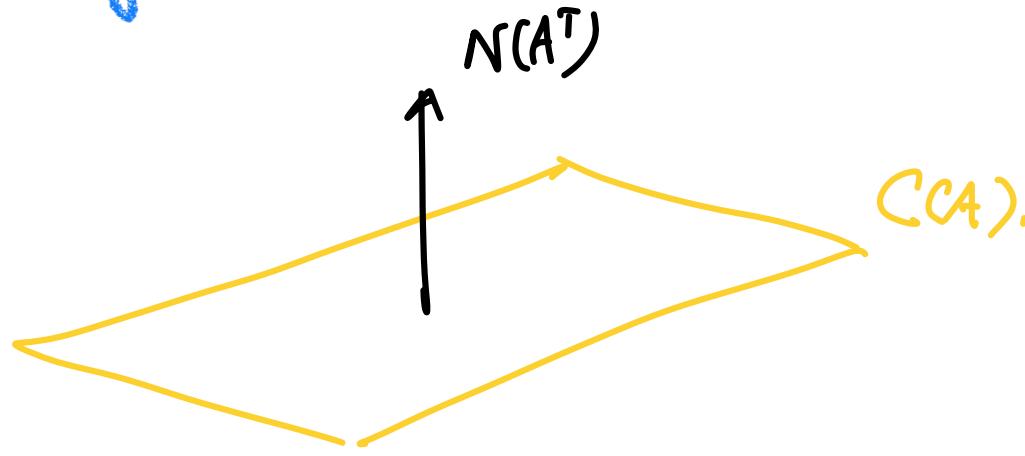
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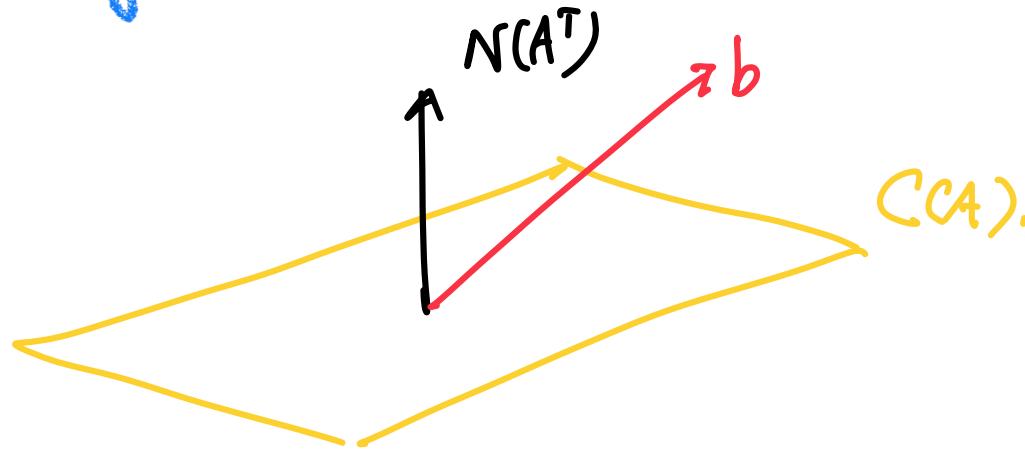


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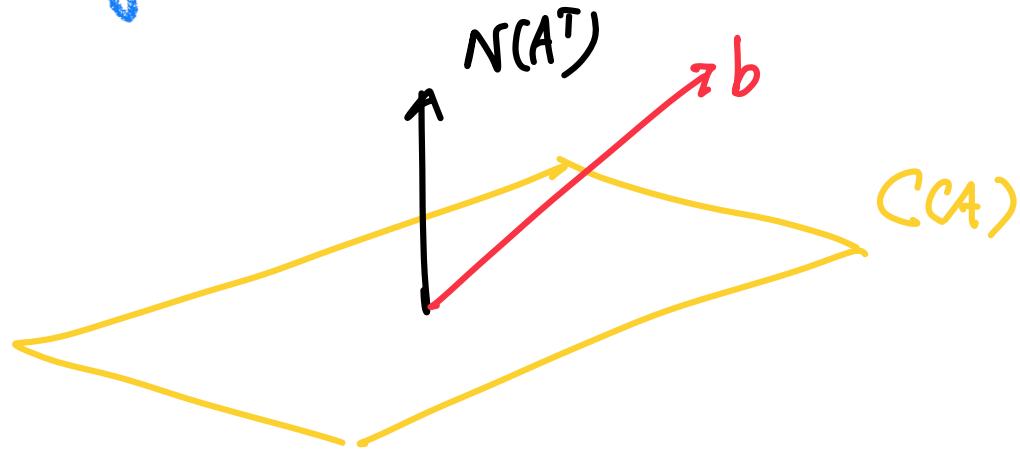


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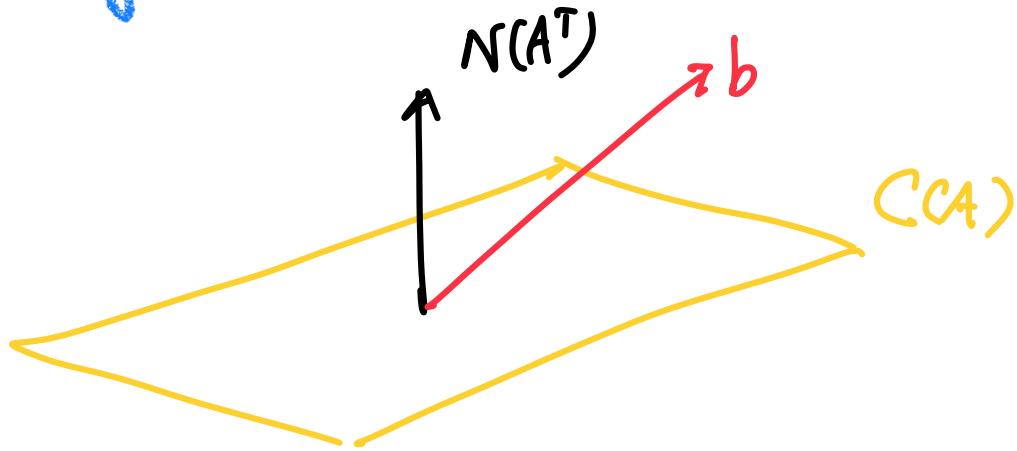
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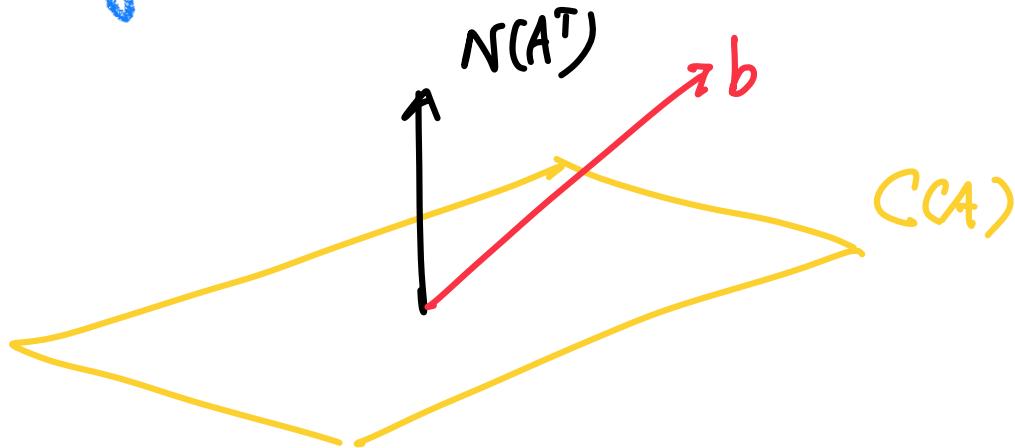
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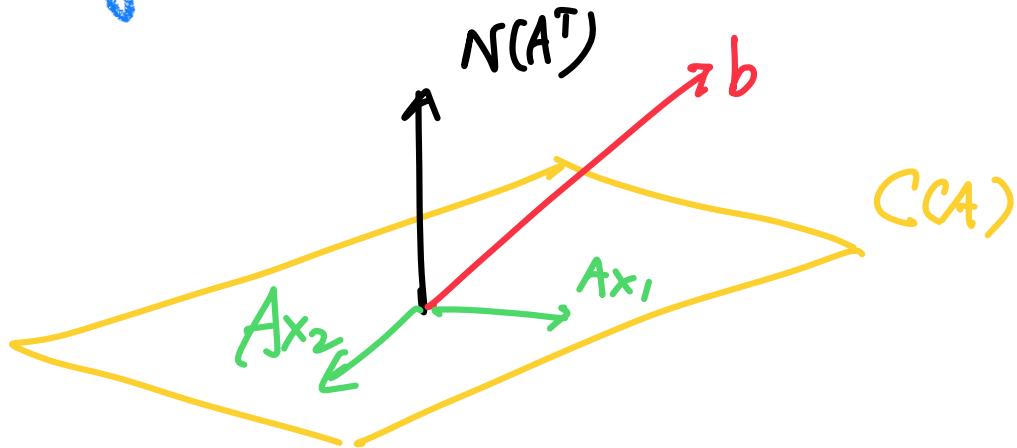
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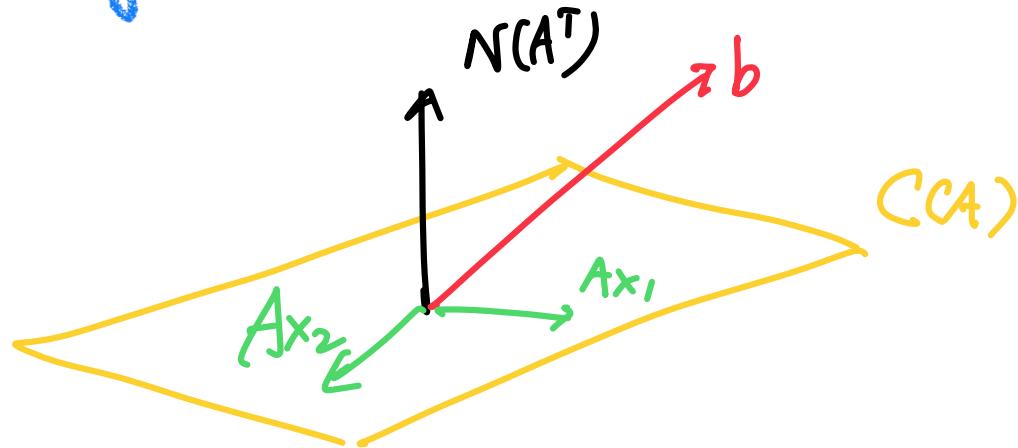
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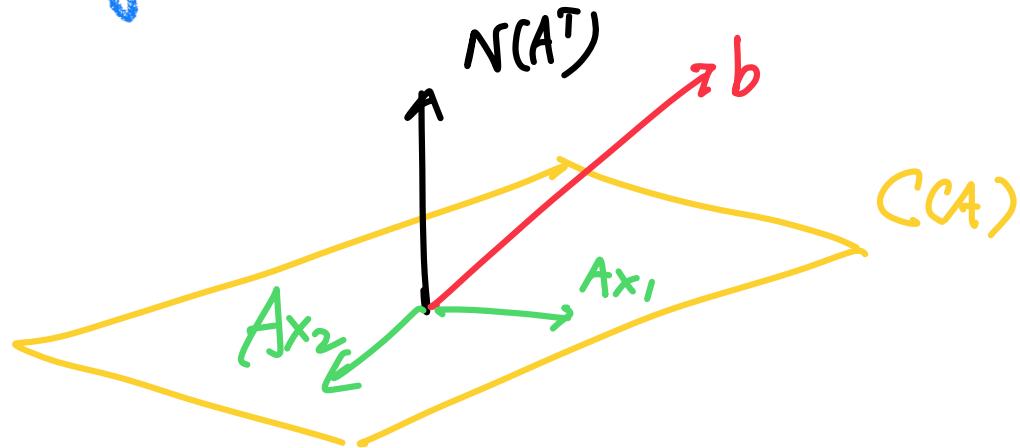
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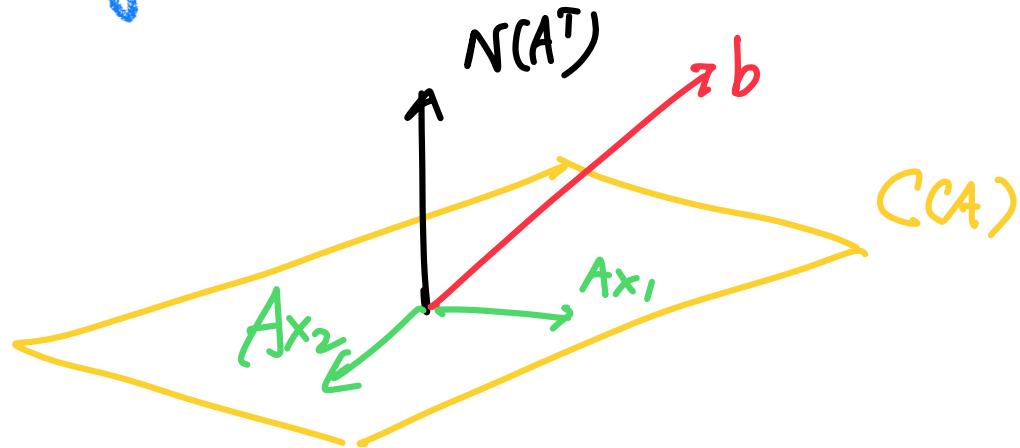
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- Then  $b - A\hat{x}$  is in  $C(A)^\perp = N(A^T)$ .

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Therefore  $P$  is a projection.