

# **Lecture 10**

## **The 4 fundamental subspaces**

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- Given a  $m \times n$  matrix  $A$ , we can consider

1. null space of  $A$  :  $N(A) = \{x \mid x \in \mathbb{R}^n, Ax=0\}$

2. column space of  $A$ :  $C(A) = \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$

3. Row space of  $A := C(A^T)$

4. left nullspace of  $A := N(A^T)$ .

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- $N(A)$ ,  $C(A^T)$  are subspaces of  $\mathbb{R}^n$

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Recall: We have proven

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- Are there other relation between their dimension?

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Claim:  $C(A^T) = \text{Span} \left\{ \begin{bmatrix} 1 \\ 3 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 3 \\ 3 \end{bmatrix} \right\}$  is a basis for  $C(A^T)$

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- $\dim(C(A^T)) = \# \text{ of pivot rows} = \text{rk}(A).$

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$$\begin{bmatrix} 1 & 2 & -1 \\ 3 & 6 & -3 \\ 3 & 9 & 3 \\ 2 & 7 & 4 \end{bmatrix} \begin{bmatrix} e_{11} & e_{21} & e_{31} \\ e_{12} & e_{22} & e_{32} \\ e_{13} & e_{23} & e_{33} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 0 & 0 \\ 3 & 3 & 0 \\ 2 & 3 & 0 \end{bmatrix}$$

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$$\xrightarrow{?} \begin{bmatrix} 1 & 2 & -1 \\ 3 & 6 & -3 \\ 3 & 9 & 3 \\ 2 & 7 & 4 \end{bmatrix} \begin{bmatrix} e_{11} & e_{21} & e_{31} \\ e_{12} & e_{22} & e_{32} \\ e_{13} & e_{23} & e_{33} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 0 & 0 \\ 3 & 3 & 0 \\ 2 & 3 & 0 \end{bmatrix}$$

$\xrightarrow{\parallel} \xrightarrow{\parallel} \xrightarrow{0}$

$$\vec{a}_1 \vec{a}_2 \vec{a}_3 \quad \vec{u}_1 \vec{u}_2 \vec{u}_3$$

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$$\begin{array}{c}
 \text{Given: } \\
 \left[ \begin{array}{ccc} 1 & 2 & -1 \\ 3 & 6 & -3 \\ 3 & 9 & 3 \\ 2 & 7 & 4 \end{array} \right] \left[ \begin{array}{ccc} e_{11} & e_{21} & e_{31} \\ e_{12} & e_{22} & e_{32} \\ e_{13} & e_{23} & e_{33} \end{array} \right] = \left[ \begin{array}{ccc} 1 & 0 & 0 \\ 3 & 0 & 0 \\ 3 & 3 & 0 \\ 2 & 3 & 0 \end{array} \right] \\
 \text{Row operations: } \\
 \begin{matrix} \cancel{1} & \cancel{2} & \cancel{-1} \\ \cancel{3} & \cancel{6} & \cancel{-3} \\ \cancel{3} & \cancel{9} & \cancel{3} \\ \cancel{2} & \cancel{7} & \cancel{4} \end{matrix} \\
 \begin{matrix} \cancel{\overrightarrow{a}_1} & \cancel{\overrightarrow{a}_2} & \cancel{\overrightarrow{a}_3} \\ \overrightarrow{u}_1 & \overrightarrow{u}_2 & \overrightarrow{u}_3 \end{matrix}
 \end{array}$$

$$\begin{aligned}
 & e_{11}\overrightarrow{a}_1 + e_{12}\overrightarrow{a}_2 + e_{13}\overrightarrow{a}_3 = \overrightarrow{u}_1 \\
 \Rightarrow & e_{21}\overrightarrow{a}_1 + e_{22}\overrightarrow{a}_2 + e_{23}\overrightarrow{a}_3 = \overrightarrow{u}_2 \\
 & e_{31}\overrightarrow{a}_1 + e_{32}\overrightarrow{a}_2 + e_{33}\overrightarrow{a}_3 = \overrightarrow{u}_3
 \end{aligned}$$

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$$\begin{array}{c}
 \text{⑦.} \\
 \left[ \begin{array}{ccc} 1 & 2 & -1 \\ 3 & 6 & -3 \\ 3 & 9 & 3 \\ 2 & 7 & 4 \end{array} \right] \left[ \begin{array}{ccc} e_{11} & e_{21} & e_{31} \\ e_{12} & e_{22} & e_{32} \\ e_{13} & e_{23} & e_{33} \end{array} \right] = \left[ \begin{array}{ccc} 1 & 0 & 0 \\ 3 & 0 & 0 \\ 3 & 3 & 0 \\ 2 & 3 & 0 \end{array} \right] \\
 \text{⑧.} \quad \overbrace{\vec{a}_1}^{\parallel} \quad \overbrace{\vec{a}_2}^{\parallel} \quad \overbrace{\vec{a}_3}^{\parallel} \qquad \qquad \qquad \overbrace{\vec{u}_1}^{\parallel} \quad \overbrace{\vec{u}_2}^{\parallel} \quad \overbrace{\vec{u}_3}^{\parallel}
 \end{array}$$

$$\Rightarrow \left. \begin{array}{l} e_{11}\vec{a}_1 + e_{12}\vec{a}_2 + e_{13}\vec{a}_3 = \vec{u}_1 \\ e_{21}\vec{a}_1 + e_{22}\vec{a}_2 + e_{23}\vec{a}_3 = \vec{u}_2 \\ e_{31}\vec{a}_1 + e_{32}\vec{a}_2 + e_{33}\vec{a}_3 = \vec{u}_3 \end{array} \right\} \Rightarrow \begin{array}{l} \text{Span}\{\vec{u}_1, \vec{u}_2, \vec{u}_3\} \\ \subseteq \text{Span}\{\vec{a}_1, \vec{a}_2, \vec{a}_3\} \end{array}$$

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$$A \vec{b}_i = b_{1i} \vec{a}_1 + b_{2i} \vec{a}_2 + \dots + b_{ni} \vec{a}_n \in C(A).$$

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$\Rightarrow$  every column in  $AB$  lies in  $C(A)$ .  $\square$

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- $C(A^T), N(A) \subseteq \mathbb{R}^n$   
 $\dim = r$        $\dim = n-r$

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- $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in N(A)$ ,  $\begin{bmatrix} -a_i- \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$ .

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- $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \in N(A)$ ,  $\begin{bmatrix} -a_1 \\ -a_2 \\ -a_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$ .  
 $\nwarrow \langle a_i^T, \vec{x} \rangle$  inner product

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- Take a basis  $w_1, \dots, w_k$  of  $C(AA^T)$ ,  $v_1, \dots, v_l$  of  $N(A)$
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$$a_1w_1 + \dots + a_kw_k = -b_1v_1 - \dots - b_\ell v_\ell .$$

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$$\underbrace{a_1 w_1 + \dots + a_k w_k}_{\text{in } C(A^T)} = - \underbrace{b_1 v_1 + \dots + b_\ell v_\ell}_{\text{in } N(A)} .$$

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$$\underbrace{a_1 w_1 + \dots + a_k w_k}_{\text{in } C(A^T)} = - \underbrace{b_1 v_1 + \dots + b_\ell v_\ell}_{\text{in } N(A)} .$$

$$\Rightarrow \text{both sides are zero} \Rightarrow a_1 = \dots = a_k = 0 = b_1 = \dots = b_\ell .$$

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- Therefore  $w_1, \dots, w_k, v_1, \dots, v_l$  are l.i.
- We can extend it to a basis by adding more vectors  $\vec{a}_1, \dots, \vec{a}_s$ .
- But  $k+l=n \Rightarrow$  we cannot add more by dimension constraint.

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- Therefore  $w_1, \dots, w_k, v_1, \dots, v_e$  are l.i.
- We can extend it to a basis by adding more vectors  $\vec{a}_1, \dots, \vec{a}_s$ .
- But  $k+l=n \Rightarrow$  we cannot add more by dimension constraint.
- Hence  $w_1, \dots, w_k, v_1, \dots, v_e$  is a basis for  $\mathbb{R}^n$ .

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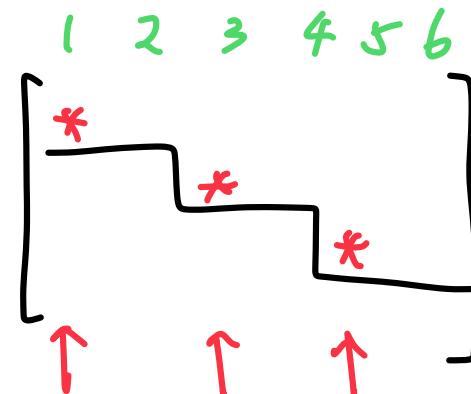
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- In the above example,  $\vec{a}_1, \vec{a}_3, \vec{a}_5$  is a basis for  $C(A)$ .

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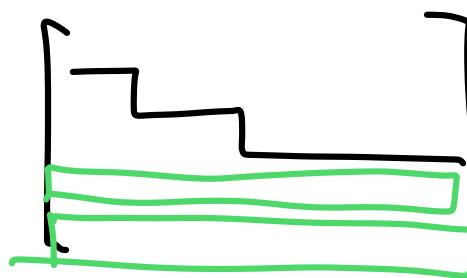
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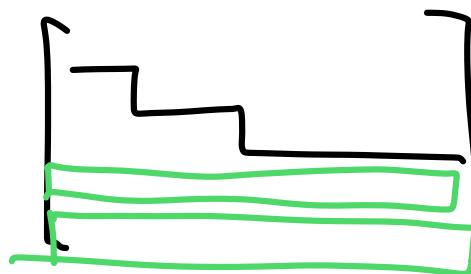
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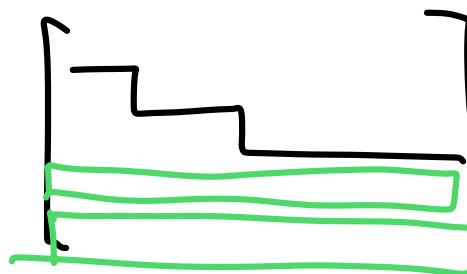
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Row Echelon form

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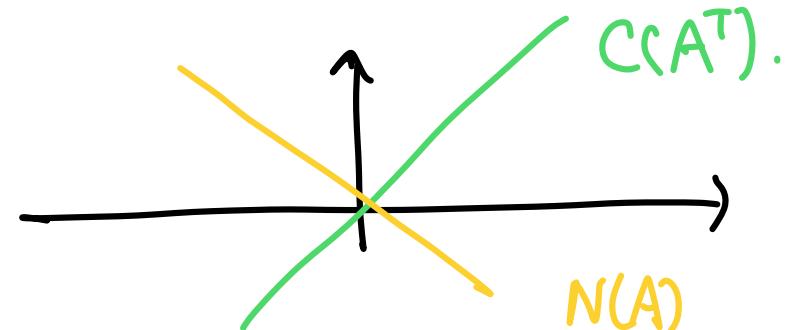
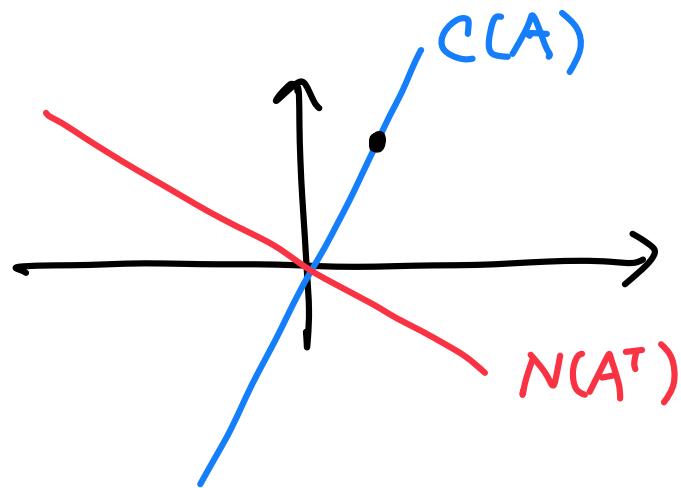
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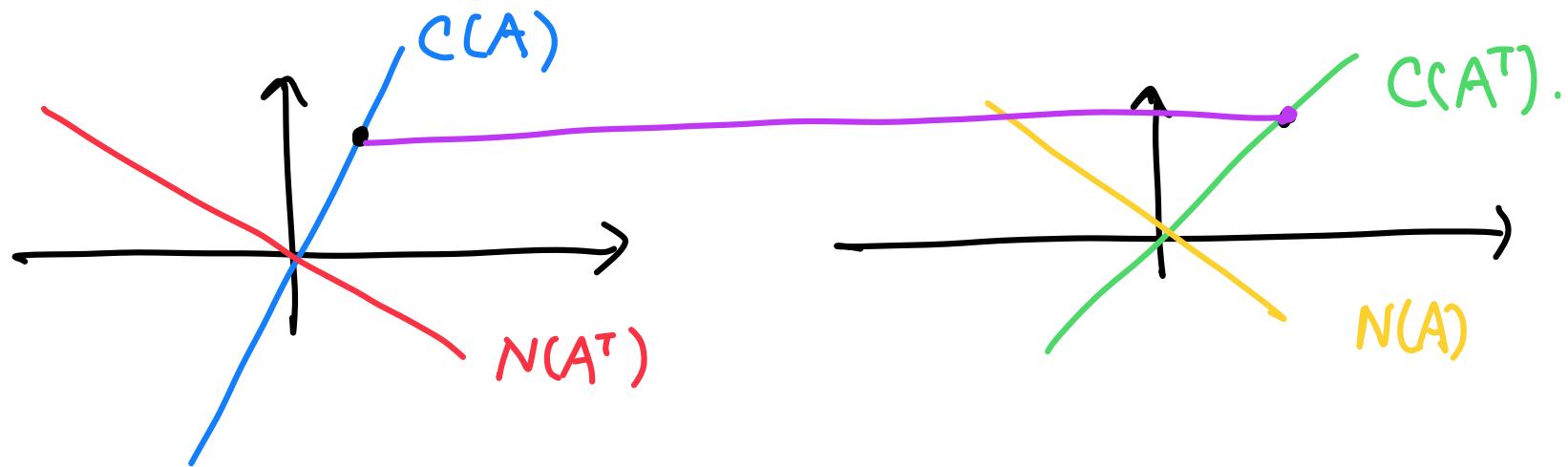


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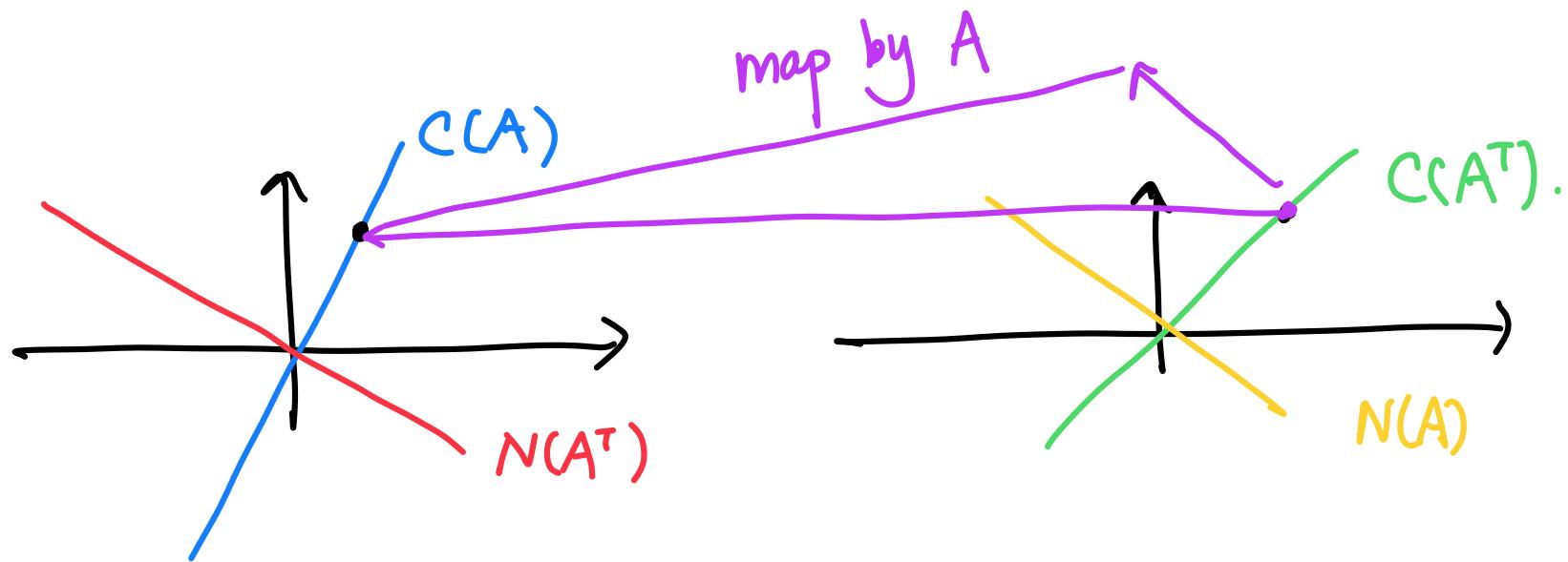


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and we say  $B = A^{-1}$  (because inverse is unique)

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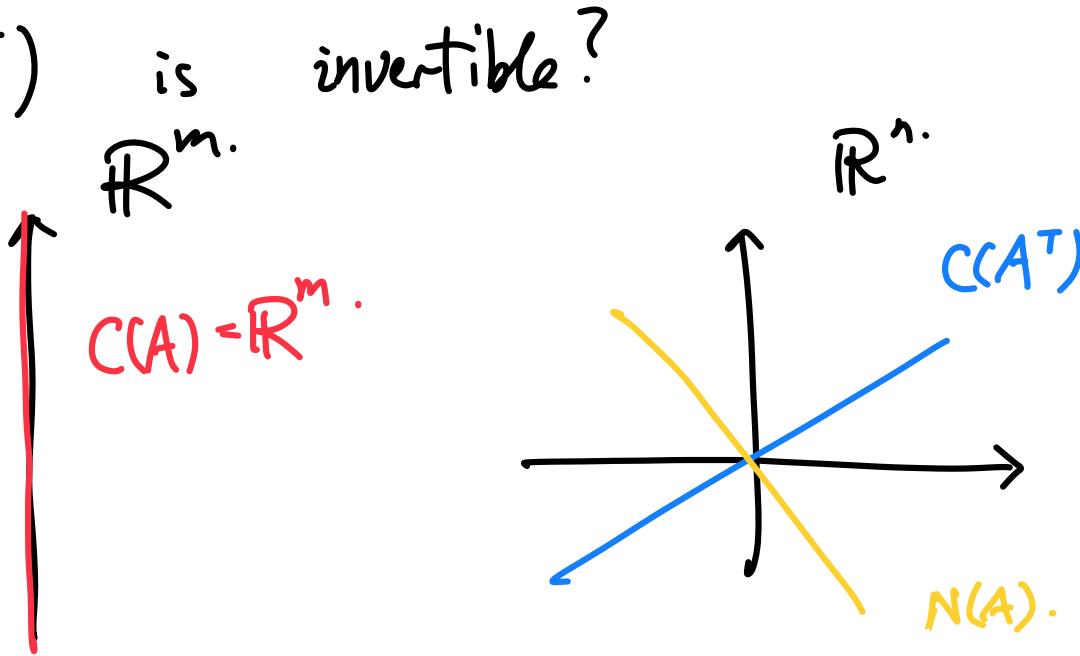
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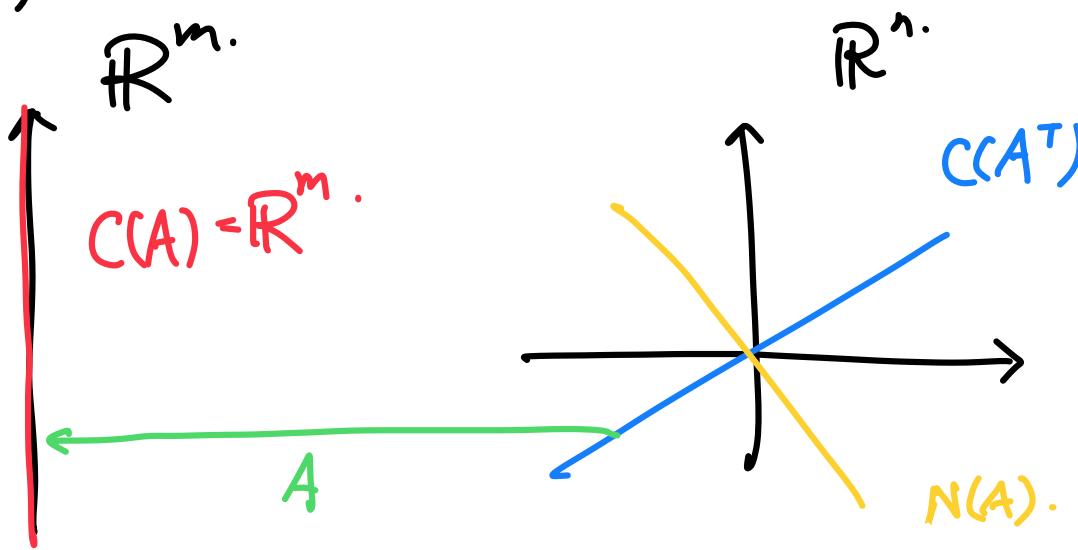


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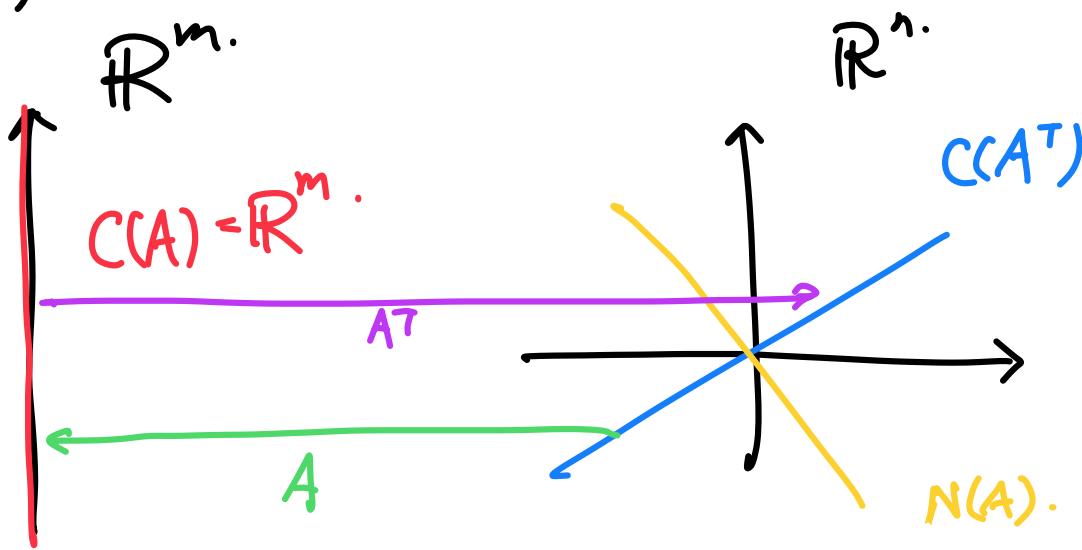


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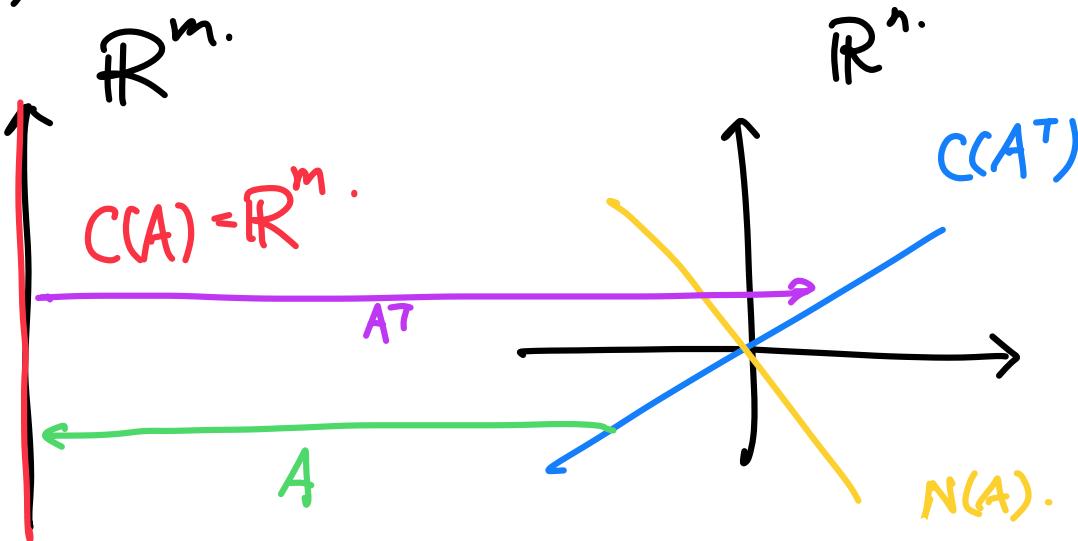


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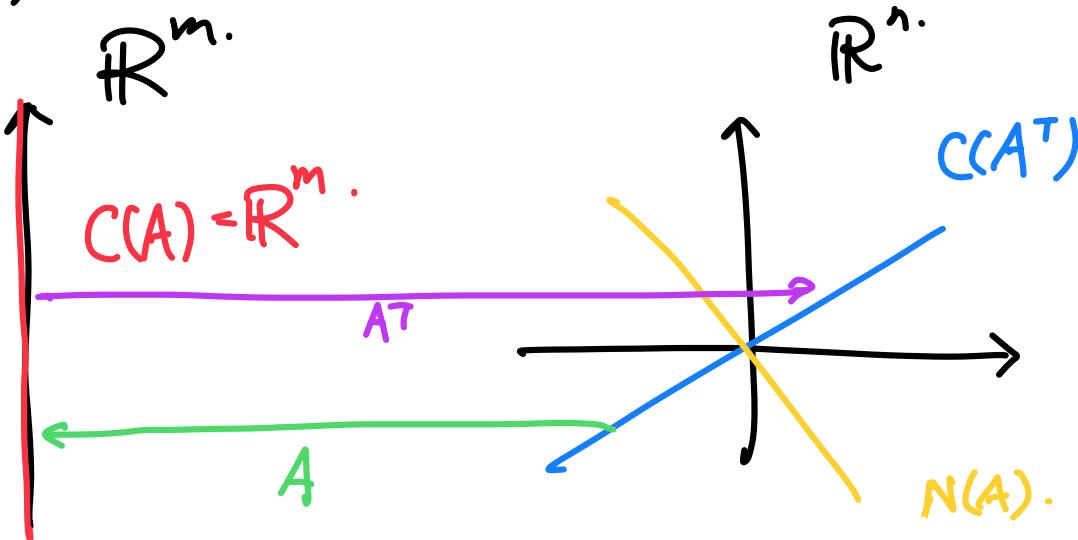
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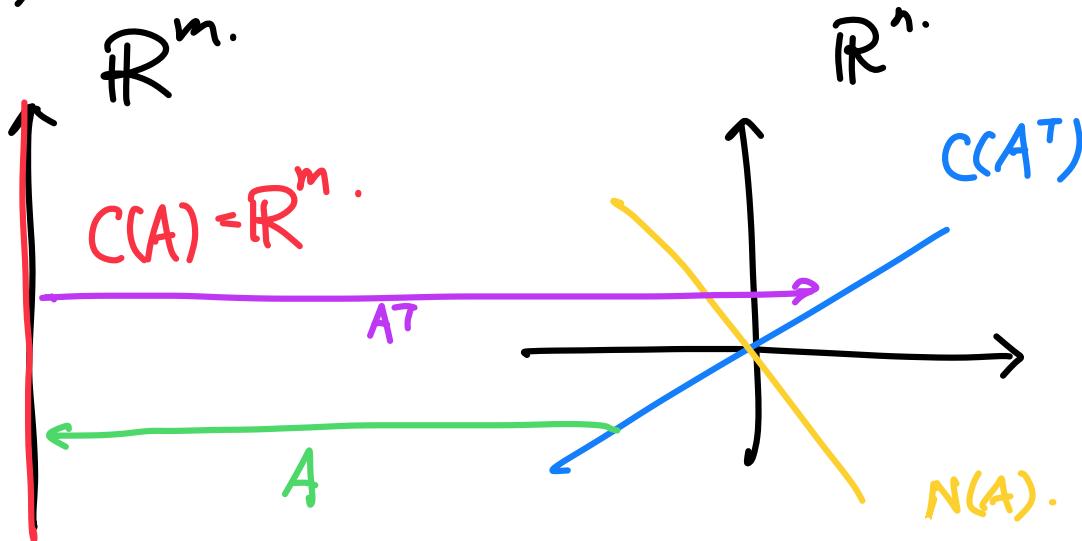
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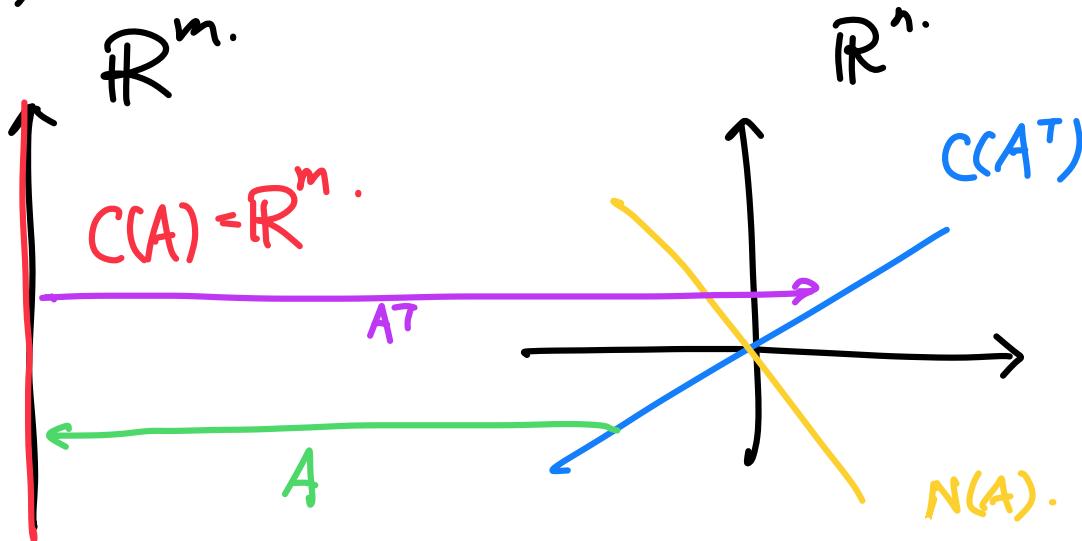
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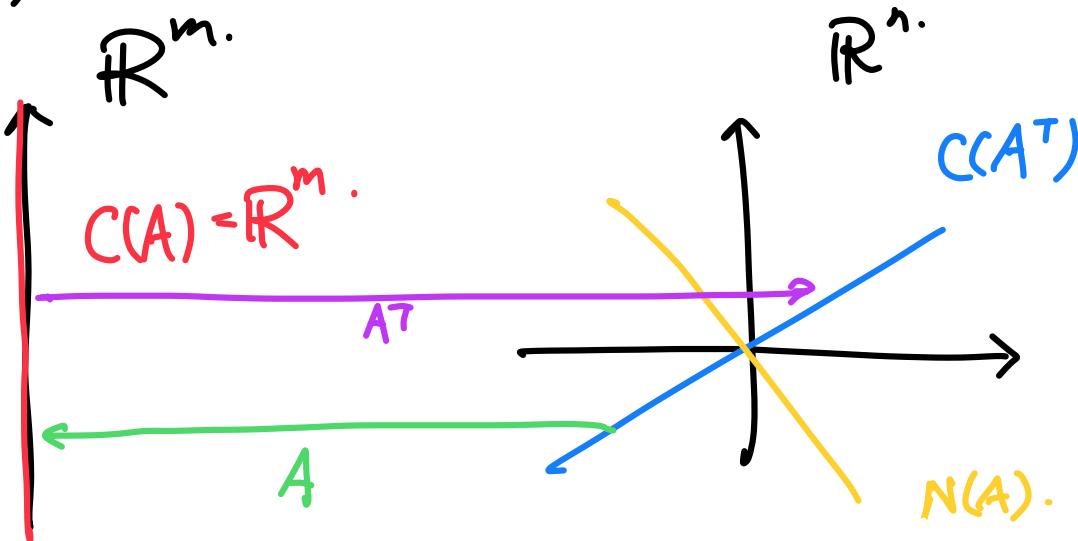
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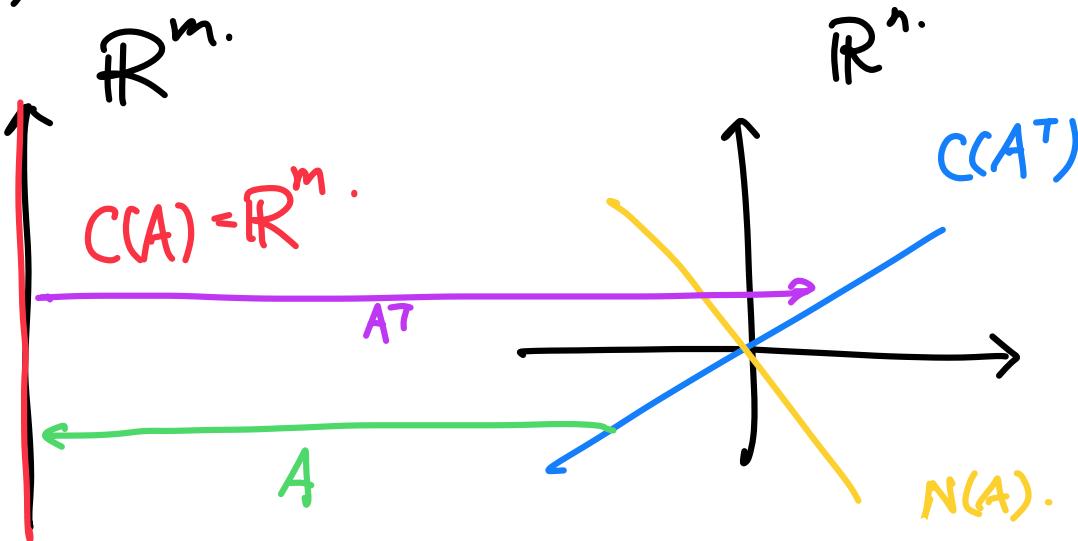
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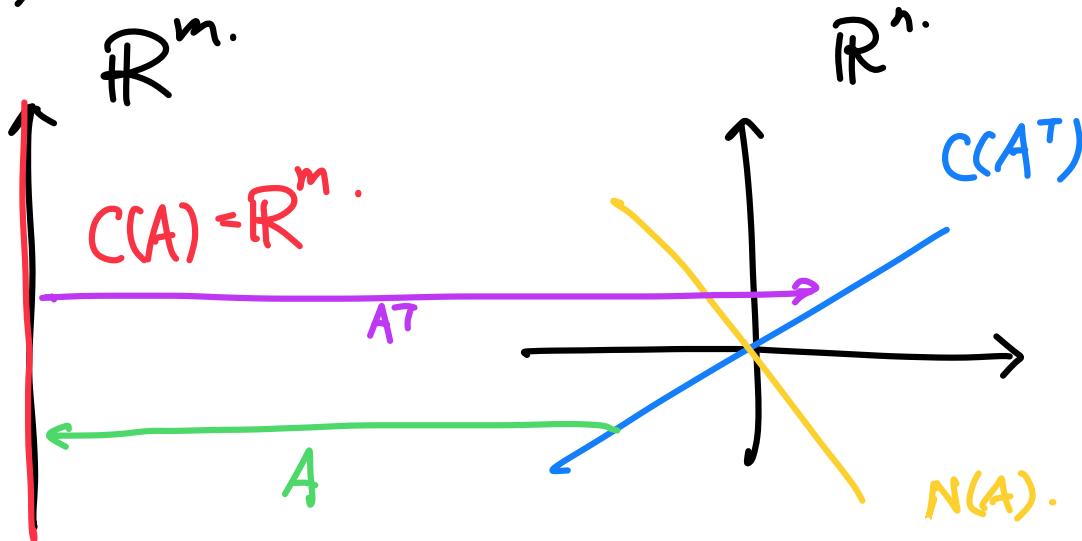
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- $N(AA^T) = 0$  and it is a square matrix  $\Rightarrow$  it is invertible.

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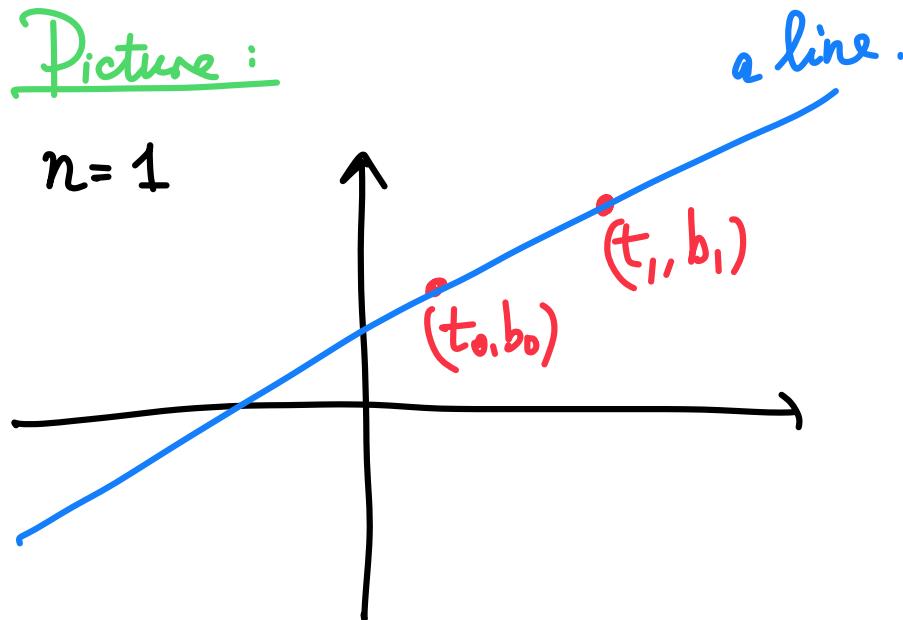
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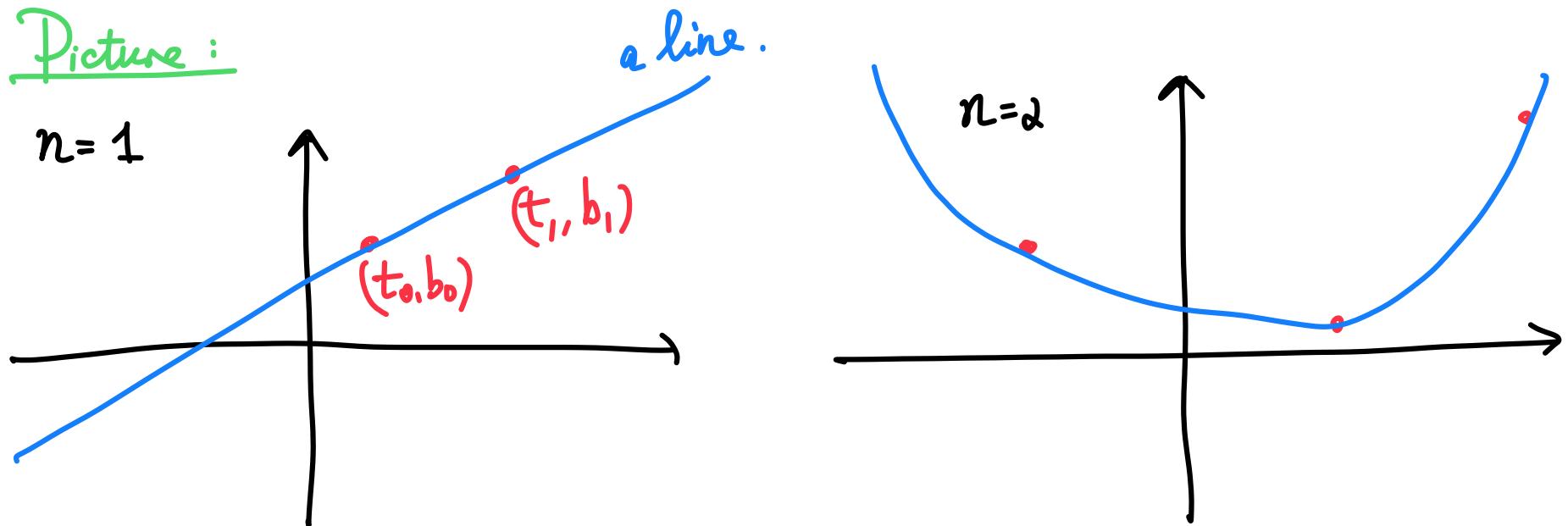
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$$V = \begin{bmatrix} 1 & t_0 & t_0^2 & t_0^3 \\ 1 & t_1 & t_1^2 & t_1^3 \\ 1 & t_2 & t_2^2 & t_2^3 \\ 1 & t_3 & t_3^2 & t_3^3 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix} = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

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Vandermonde matrix : invertible if all  $t_i$  are distinct!

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$\checkmark$

ask whether it is invertible.

$$\tilde{V}_1 = \begin{bmatrix} t_1 - t_0 & 0 & 0 \\ 0 & t_2 - t_0 & 0 \\ 0 & 0 & t_3 - t_0 \end{bmatrix} \quad \boxed{\begin{bmatrix} 1 & t_1 + t_0 & t_1^2 + t_1 t_0 + t_0^2 \\ 1 & t_2 + t_0 & t_2^2 + t_2 t_0 + t_0^2 \\ 1 & t_3 + t_0 & t_3^2 + t_3 t_0 + t_0^2 \end{bmatrix}}$$

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$$\tilde{V}_1 \text{ is invertible} \iff V_1 = \begin{bmatrix} 1 & t_1 & t_1^2 \\ 1 & t_2 & t_2^2 \\ 1 & t_3 & t_3^2 \end{bmatrix} \text{ is invertible}$$

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$$\Rightarrow A = \begin{bmatrix} 1 \\ a_1 \\ 1 \end{bmatrix} [1 \ c_2 \ c_3]$$

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for some non-zero  
 $u \in \mathbb{R}^m, v \in \mathbb{R}^n$ .