Remote Procedure Call Implementations

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 - NFS (Network File Service)
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- ▶ DCE (Distributed Computing Environment) RPC. Implements at-most-once semantics by default. At-least-once (idempotent) can also be chosen as an option for some procedures.
 - Distributed file service.
 - Directory service.
 - Security service.
 - Distributed Time Service.

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- ► Can use either TCP/IP or UDP underneath to make remote calls. The selection depends on the application requirements.

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- Program numbers are assigned in blocks of 0x2000000 according to the following table.

0	
0x0-0x1FFFFFFF	defined by Sun
0x20000000-0x3FFFFFF	defined by user
0x40000000-0x5FFFFFF	transient
0×60000000-0×FFFFFFF	reserved

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- Header files are in /usr/include/rpc/ and /usr/include/rpcsvc. The latter one has header files for common services implemented using RPC.

Observing RPC on a server

In the onyx lab, you can try the following commands:

▶ Use the following command to get a summary of rpc services available on a server:

```
rpcinfo -s onyx
```

Use the following command to make a RPC call to procedure 0 (the null procedure) for RPC program number 100003 and report whether a response was received.

```
rpcinfo -T tcp onyx 100003
```

See man page for more options.

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- ▶ Then write the server functions in any language that supports system calling conventions. Compile the server along with the server skeleton generated by rpcgen.
- ► To create an executable program for a remote program, write an ordinary main program that makes local procedure calls to the client skeletons, and link the program with the rpcgen skeletons.

RPC and XDR languages

The XDR language is for describing data and is similar to C declarations.

The RPC language is an extension to the XDR language, with the addition of program and version types.

An RPC file is a series of definitions. The following definition types are recognized.

- ▶ enum-definition
- ▶ typedef-definition
- ▶ const-definition
- ▶ declaration-definition
- ▶ struct-definition
- ▶ union-definition
- ▶ program-definition

▶ XDR enum before compilation.

```
enum colortype {
   RED = 0,
   GREEN = 1,
   BLUE = 2
};
```

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An XDR typedef followed by the compiled C typedef.

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typedef string fname_stype<255>;
typedef char *fname_type;
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► An XDR typedef followed by the compiled C typedef.

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An XDR constant declaration followed by compiled C version.

```
const DOZEN = 12;
#define DOZEN 12
```

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▶ Pointer declarations. Same as in C. Pointers cannot be sent over the network, but we can use XDR pointers to send recursive data types, such as lists and trees. In XDR, this is known as optional-data, instead of a pointer. For example:

```
listitem * next;
```

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- ➤ Voids. In a void declaration, the variable is not named. Declarations of voids occur only in union and program definitions.

XDR Struct's and Union's

An XDR struct is almost like in C. For example.

```
/* XDR version */
struct coord {
   int x;
   int y;
}

/* here is the compiled C version */
struct coord {
   int x;
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}
typedef struct coord coord;
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XDR Struct's and Union's

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  /* XDR version */
  struct coord {
     int x:
     int y;
  /* here is the compiled C version */
  struct coord {
     int x:
     int v;
  typedef struct coord coord;
> XDR Unions are discriminated unions unlike C unions. An example.
  union read_result switch (int errno) {
     case 0:
         opaque data[1024];
     default:
         void;
  }:
  /* the compiled C version */
  struct read_result {
     int errno:
     union {
         char data[1024]:
     } read_result_U;
  }:
  tyepdef struct read_result read_result;
```

Programs

An example program definition.

```
program TIMEPROG {
    version TIMEVERS {
        unsigned int TIMEGET(void) = 1;
        void TIMESET(unsigned) = 2;
    } = 1;
} = 44;
```

► The corresponding C declarations.

```
#define TIMEPROG 44
#define TIMEVERS 1
#define TIMEGET 1
#define TIMESET 2
```

Examples

See the folder rpc in the examples.

- square
- msg
- sort
- userlookup
- ► linked list
- ► thread-safe-square