

# Final project

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**Abstract**—Keep short-the whole paper shall not exceed the four pages plus reference.

## I. INTRODUCTION

1/2 page

## II. ROBOT MODEL

1/2-1 page

## III. MOTION PLANNING

1/2-1 page

## IV. RESULTS

1 page

## V. DISCUSSION

1/2-1 page

## VI. EXAMPLES OF EDITING LATEX

### A. Equations

$$a = b + c \quad (1)$$

### B. Figures



Fig. 1. TUD logo

### C. Algorithm

**Algorithm 1** What function do algorithms achieve

Initialization

```
for do
  if then
    if then
      end
    end
  end
end
return 1
```

### D. table

| Path | Cost           |
|------|----------------|
| 1    | $\sqrt{21.25}$ |
| 2    | $\sqrt{145}$   |
| 3    | $\sqrt{10}$    |
| 4    | $\sqrt{41}$    |
| 5    | $3\sqrt{5}$    |
| 6    | $3\sqrt{10}$   |
| 7    | $5\sqrt{2}$    |

TABLE I

DIJKSTRA ALGORITHM

### E. Citation

This is an example of citation[1].

## REFERENCES

- [1] E. W. Dijkstra, "A note on two problems in connexion with graphs," *Numerische Mathematik*, vol. 1, pp. 269–271, 1959.

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Fig. 2. Figure cross the line.