

# CoUDA: Continual Unsupervised Domain Adaptation for Industrial Fault Diagnosis under Dynamic Working Conditions (Supplementary Material)

## A. Algorithm

The algorithm of the CoUDA framework is summarized in Algorithm 1.

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### Algorithm 1 : CoUDA Framework

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#### Stage 1: Source Domain Pre-training

**Input:** Source data  $\mathcal{D}_S$ , feature extractor  $f_{\theta}$ , classifier  $g_{\theta}$ .

**Hyperparameters:** Total epochs  $E$ , learning rate  $\eta$ , batch size  $b$ , momentum  $m$ , temperature  $\tau$ , balance parameter  $\alpha$ .

```

1: for  $e \leftarrow 0$  to  $E$  do
2:   for every mini-batch  $(x^S, y^S) \in \mathcal{D}_S$  do
3:     Infer.  $\mathcal{L}^S(x^S, y^S; \theta_S) = \mathcal{L}_{\text{IPC}} + \alpha \cdot \mathcal{L}_{\text{IIC}}$ ;
4:     SGD.  $\theta_S \leftarrow \theta_S - \eta \cdot \nabla \mathcal{L}^S(x^S, y^S; \theta_S)$ .
5:   end for
6: end for
```

**Return:** Pre-trained feature extractor  $f_{\theta_S}$ , classifier  $g_{\theta_S}$ .

#### Stage 2: Sequential Target Domain Adaptation

**Input:** Source data  $\mathcal{D}_S$ , pre-trained feature extractor  $f_{\theta_S}$ , classifier  $g_{\theta_S}$ , unlabeled sequential target data  $\{\mathcal{D}_{T_t}\}_{t=1}^T$ .

**Hyperparameters:** Total epochs  $E$ , learning rate  $\eta$ , batch size  $b$ , momentum  $m$ , temperature  $\tau$ , balance parameter  $\alpha$ .

```

1: for  $t \leftarrow 1$  to  $T$  do
2:   Initialize  $f_{\theta_t} \leftarrow f_{\theta_{t-1}}$ ,  $g_{\theta_t} \leftarrow g_{\theta_S}$ ;
3:   for  $e \leftarrow 0$  to  $E$  do
4:     for every mini-batch  $(x^S, y^S) \in \mathcal{D}_S$ ,  $(x^{T_t}) \in \mathcal{D}_{T_t}$  do
5:       Infer.  $\mathcal{L}^{T_t}(x^S, y^S, x^{T_t}; \theta_t, \theta_{t-1}) = \mathcal{L}_{\text{CE}} + \mathcal{L}_{\text{FKD}}$ 
6:          $+ \beta(e) \cdot \mathcal{L}_{\text{IEM}} + (1 - \beta(e)) \cdot \mathcal{L}_{\text{LDA}}$ ;
7:       SGD.  $\theta_t \leftarrow \theta_t - \eta \cdot \nabla \mathcal{L}^{T_t}(x^S, y^S, x^{T_t}; \theta_t)$ .
8:     end for
9:   if  $t > 1$  then
10:    evaluation on previous target domains
11:     $\{\mathcal{D}_{T_1}, \dots, \mathcal{D}_{T_t}\}$ ;
12:   end if
13: end for
```

**Return:** New feature extractor  $f_{\theta_t}$ , global classifier  $g_{\theta_S}$ .

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## B. Prototype Contrastive Learning (PCL)

As shown in Fig. 1, we compare the performance of the source-only model with and without PCL on the target domains. The source-only model with PCL achieves better performance in all unseen target domains, which demonstrates the effectiveness of PCL in improving the generalization ability of the source model. The removal of PCL reduces the generalization ability of the source model, leading to a reduction in its ability of both adaptation and anti-forgetting.

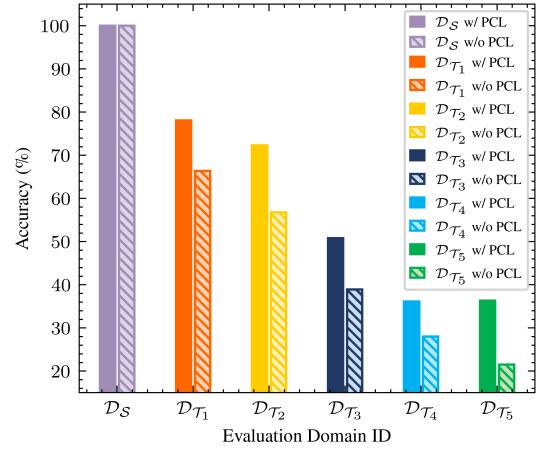


Fig. 1. The performance comparison of source-only model w/ and w/o PCL.

## C. Hyperparameter Sensitivity Analysis

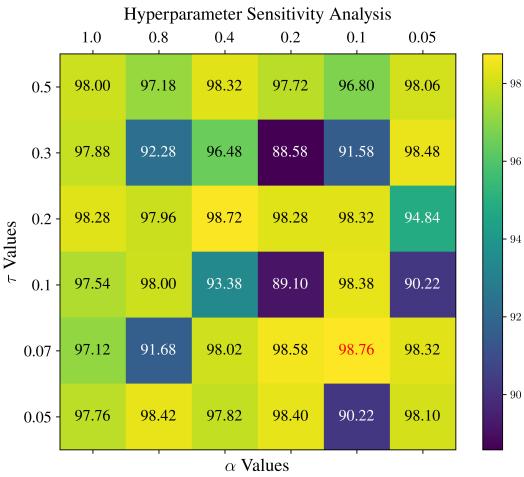


Fig. 2. Hyperparameter sensitivity analysis. The ACC of CoUDA with different hyper-parameters  $\tau$  and  $\alpha$ .

We conducted a grid search of the hyper-parameters  $\tau$  and  $\alpha$ , which are the temperature parameter in the IIC loss and the balance parameter between the IPC and IIC losses, respectively. To evaluate the sensitivity of the hyper-parameters, we varied the values of  $\tau$  and  $\alpha$  from 0.05 to 0.5 and from 1.0 to 0.05, respectively. We plotted the heatmap of the ACC with different hyper-parameters using the domain scenario S1 for the analysis, as shown in Fig. 2. The best performance is achieved when  $\tau = 0.07$  and  $\alpha = 0.1$ .